

Classification of Hyperspectral Data Using Support Vector Machines and Adaptive Neighborhoods

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Outline

1 Introduction

2 Spectral-spatial classification of hyperspectral data

- Segmentation
- Spectral-spatial classification

3 Conclusions and perspectives

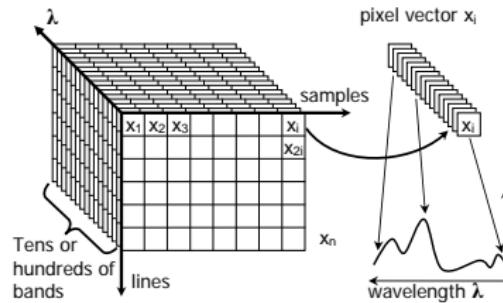
Hyperspectral image

Every pixel contains a detailed spectrum (>100 spectral bands)

- + More information per pixel → increasing capability to distinguish objects
- Dimensionality increases → classification problem becomes more complex



Efficient algorithms for automatic processing are required!

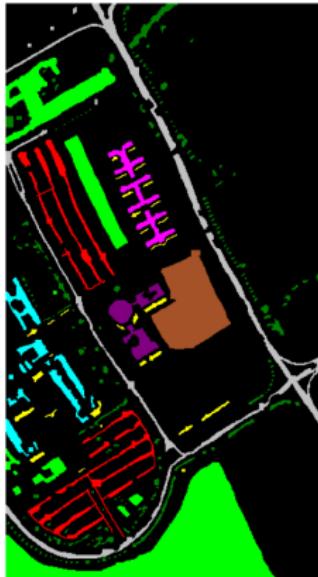


Classification problem

Input ROSIS image
[610 × 340 × 103]



Ground-truth data



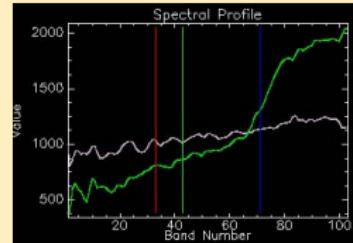
Task

Assign **every** pixel to **one** of the **nine** classes:
alphalt
meadows
gravel
trees
metal sheets
bare soil
bitumen
bricks
shadows

Classification approaches

Only spectral information

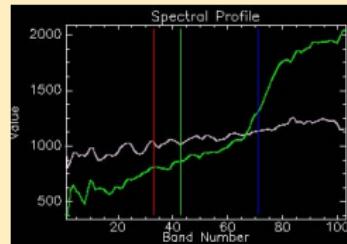
- Spectrum of each pixel is analyzed
- Directly accessible
- Kernel-based methods (e.g. SVM)
→ good classification results



Classification approaches

Only spectral information

- Spectrum of each pixel is analyzed
- Directly accessible
- Kernel-based methods (e.g. SVM)
→ good classification results



Spectral + spatial information

- Info about spatial structures included
- How to define structures?
 - closest neighborhood → not flexible enough
 - adaptive neighborhood (segmentation map)
→ currently investigated



Objective

- **Segment** a hyperspectral image = find an exhaustive partitioning of the image into homogeneous regions
- **Spectral** info + **spatial** info → classify image

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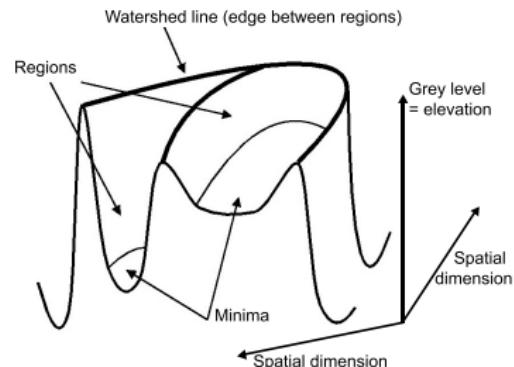
- Segmentation
- Spectral-spatial classification

3 Conclusions and perspectives

1. Watershed segmentation



gradient
⇒



Region growing method:

- **Minimum** of a gradient = core of a homogeneous region
- **1 region** = set of pixels connected to 1 local minimum of the gradient
- **Watershed lines** = edges between adjacent regions

1. Watershed segmentation

Tarabalka, Y., Chanussot, J., Benediktsson, J. A., Angulo, J., Fauvel, M., 2008.

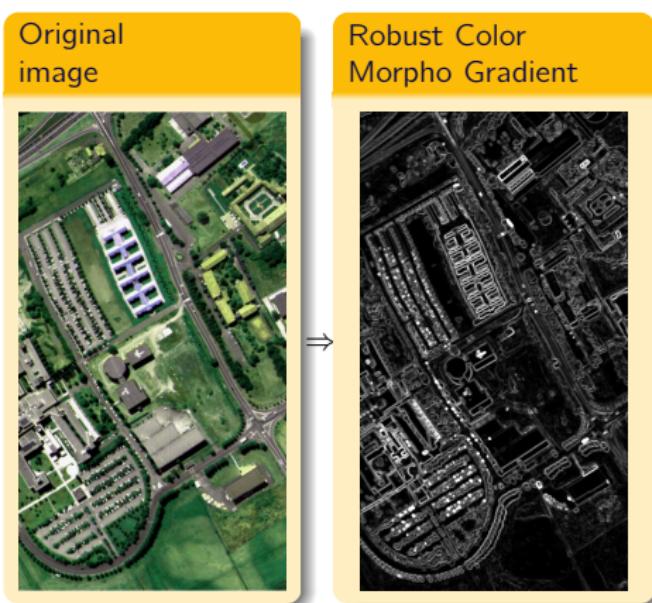
Segmentation and classification of hyperspectral data using watershed. In Proc. of IGARSS '08, Boston, USA.

Original
image



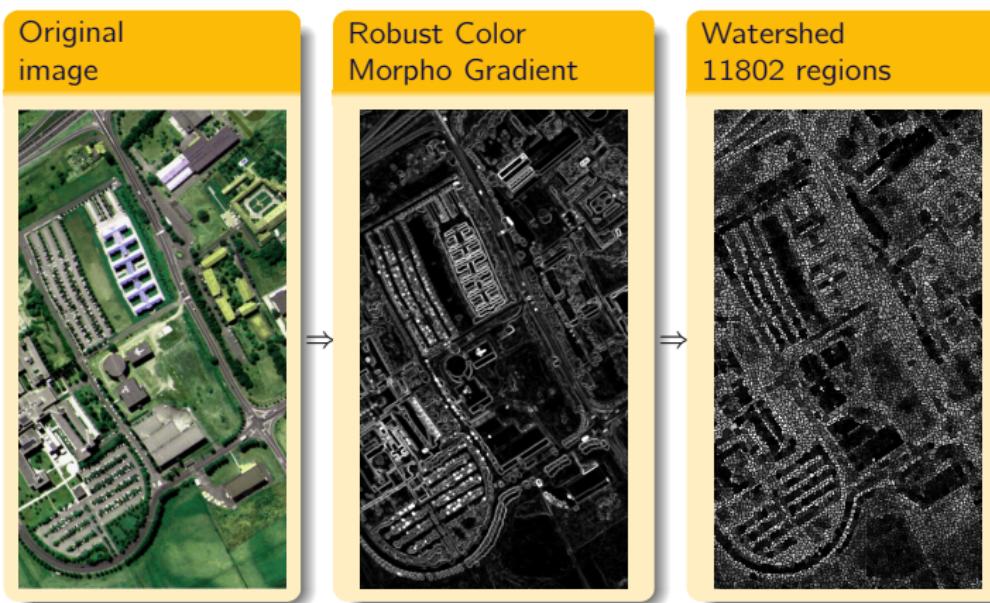
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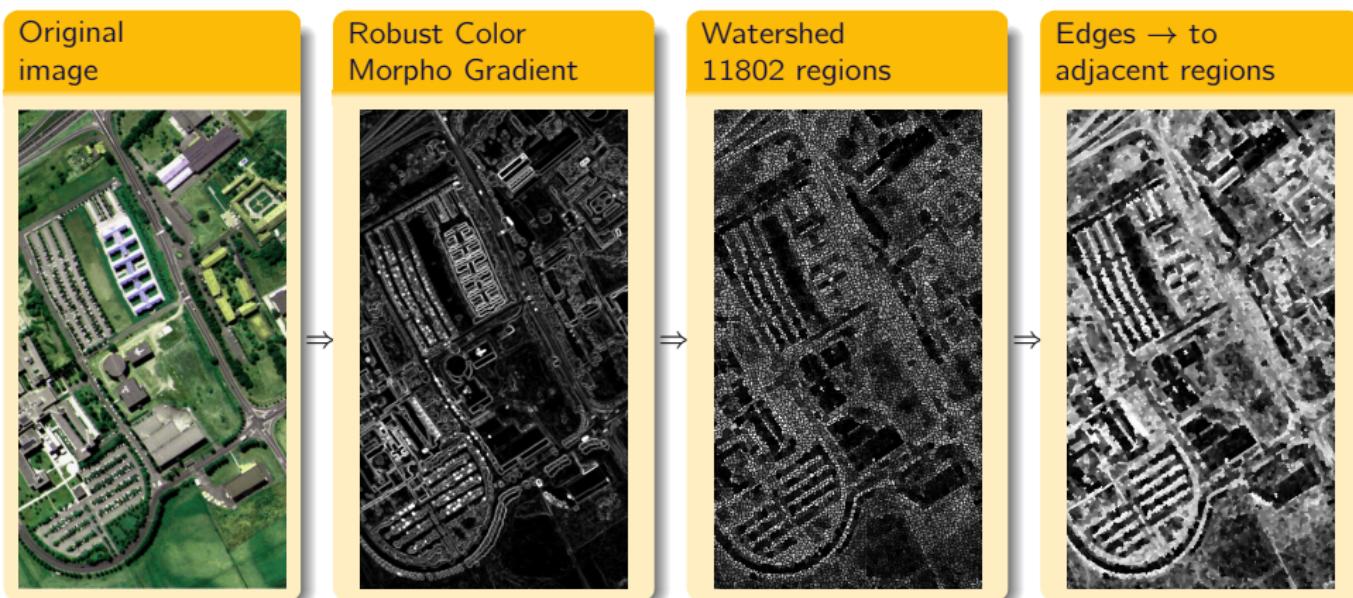
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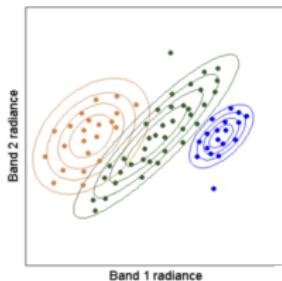


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2. Partitional clustering (EM)



① Clustering

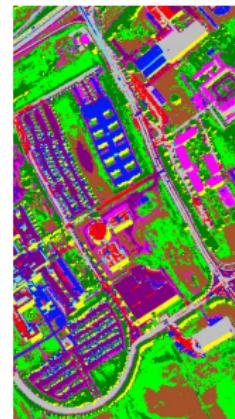
- pixels are grouped into C clusters
- in each cluster \rightarrow pixels drawn from a Gaussian distribution
- distribution parameters \rightarrow EM algorithm

② Labeling of connected components

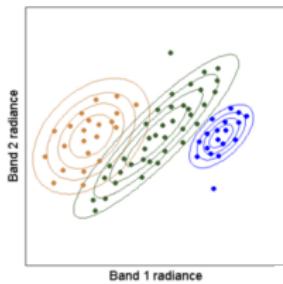


10 clusters

\Rightarrow



2. Partitional clustering (EM)



① Clustering

- pixels are grouped into C clusters
- in each cluster \rightarrow pixels drawn from a Gaussian distribution
- distribution parameters \rightarrow EM algorithm

② Labeling of connected components



10 clusters
 \Rightarrow
21450
regions



same cluster,
but different
regions!

3. Hierarchical image segmentation (HSEG)

- Region growing + Spectral Clustering
- Dissimilarity criterion (*DC*):
Spectral Angle Mapper (SAM)
between the region mean vectors u_i and u_j

$$SAM(u_i, u_j) = \arccos\left(\frac{u_i \cdot u_j}{\|u_i\|_2 \|u_j\|_2}\right)$$

- ➊ Each pixel – one region
- ➋ Find DC_{min} between adjacent regions
- ➌ Merge adjacent regions with $DC = DC_{min}$
- ➍ Merge non-adjacent regions with
 $DC \leq DC_{min} \cdot SpectralClusterWeight$
- ➎ If not converge, go to 2

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1	2	3
4	5	6
7	8	9
10	11	12

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13	13	6
7	8	14
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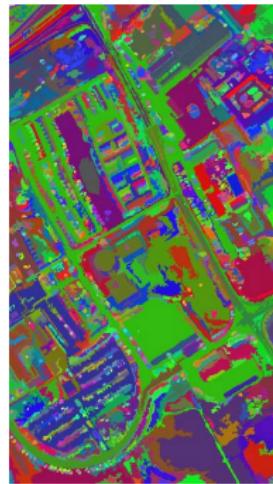
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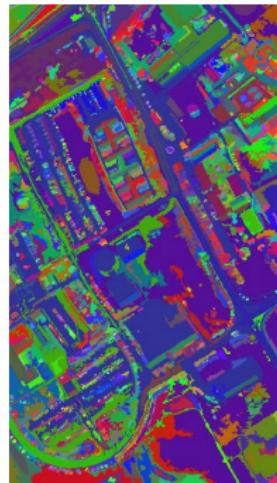
$SCW = 0.0$
7231 regions

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$SCW = 0.1$
7575 regions

Outline

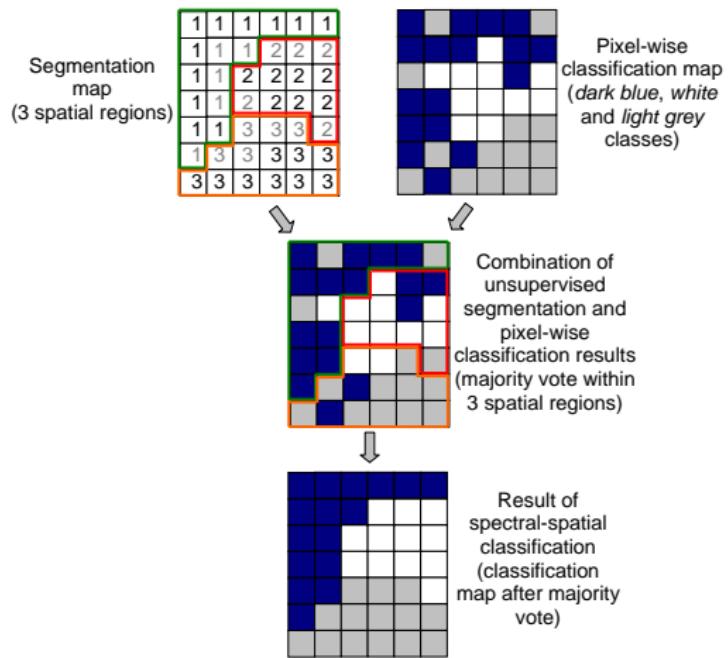
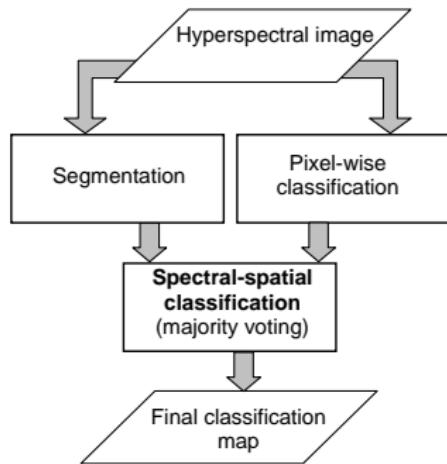
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Spectral-spatial classification scheme



Spectral-spatial classification

Original
image



Spectral-spatial classification

Original
image



SVM
classification



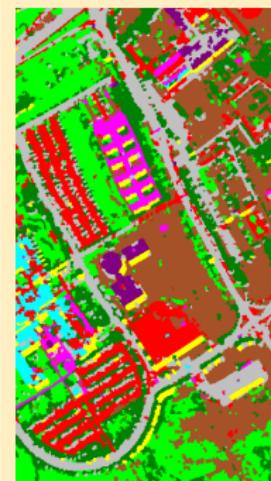
OA = 81.01%
AA = 88.25%

Spectral-spatial classification

SVM
classification



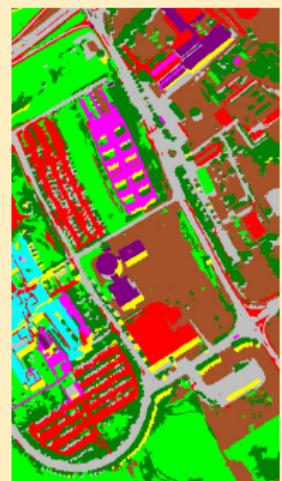
SVM +
Watershed



SVM +
Partit.clustering



SVM + HSEG
(SCW = 0.1)



OA = 81.01%
AA = 88.25%

OA = 85.42%
AA = 91.31%

OA = 93.59%
AA = 94.39%

OA = 93.85%
AA = 97.07%

Classification accuracies (%):

SCW	SVM	+Watersh.	+Part.Clus.	+HSEG		EMP ¹
				0.0	0.1	
OA	81.01	85.42	93.59	90.00	93.85	85.22
AA	88.25	91.31	94.39	94.15	97.07	90.76
κ	75.86	81.30	91.48	86.86	91.89	80.86
asphalt	84.93	93.64	90.72	73.33	94.77	95.36
meadows	70.79	75.09	92.73	88.73	89.32	80.33
gravel	67.16	66.12	82.09	97.47	96.14	87.61
trees	97.77	98.56	99.21	98.45	98.08	98.37
metal sheets	99.46	99.91	100	99.10	99.82	99.48
bare soil	92.83	97.35	96.78	98.43	99.76	63.72
bitumen	90.42	96.23	92.46	95.92	100	98.87
bricks	92.78	97.92	97.80	98.81	99.29	95.41
shadows	98.11	96.98	97.74	97.11	96.48	97.68

¹A. Plaza et al., 2009. Recent advances in techniques for hyperspectral image processing. *Remote Sensing of Environment*, accepted for publication.

Conclusions and perspectives

Conclusions

- ① Scheme for spectral-spatial classification of hyperspectral data is presented
- ② Several segmentation techniques are investigated
- ③ The HSEG segmentation map leads to the best classification
- ④ Obtained classification accuracies > all previous results

Perspectives

- Explore ways to fuse spectral + spatial info

Thank you for your attention!