### Uniqueness for the wave equation (1d)

Wave eq.

$$(\partial_{tt}^2 - c^2 \partial_{xx}^2) u = 0 \tag{1}$$

endowed with Cauchy data

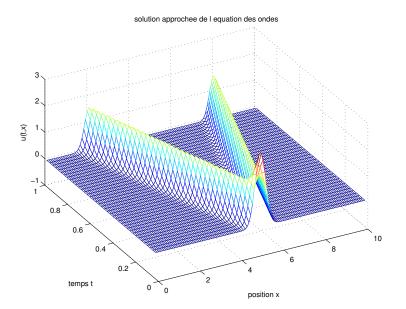
$$u(0,x) = g(x), \qquad \partial_t u(0,x) = h(x).$$

D'Alembert's formula

$$u(t,x) = \frac{1}{2} \Big( g(x-ct) + g(x+ct) + \frac{1}{c} \int_{x-ct}^{x+ct} h(y) \, \mathrm{d}y \Big).$$
 (2)

With  $h \in C^0$ ,  $g \in C^1$  it provides a <u>weak</u>  $C^1$  sol. of (1) Crucial observation: **Finite speed of propagation** The sol. at time *t* and position *x* only depends on the data in the domain [x - c|t|, x + c|t|]. If the data is supported in [-R, +R], the sol. is supported in [R - c|t|, R + c|t].

# Finite speed of propagation



#### Uniqueness

We suppose v sol. with data g = 0, h = 0. We wish to show that

v = 0 a.e.

Reasoning by duality: we are going to show that

$$\int_{\mathbb{R}} v(T, y) \zeta(y) \, \mathrm{d} y = 0$$

for any time T and any trial function  $\zeta \in C_c^{\infty}(\mathbb{R})$ . Let

$$\psi(t,x) = \frac{1}{2c} \int_{x-c(t-T)}^{x+c(t-T)} \zeta(y) \,\mathrm{d}y.$$

This is a solution of  $(\partial_{tt}^2 - c^2 \partial_{xx}^2)\psi = 0$ , with

$$\psi(T, x) = 0, \qquad \partial_t \psi(T, x) = \zeta(x).$$

## Uniqueness, II

Let

$$I(t) = \int_{\mathbb{R}} \partial_t v(t, x) \psi(t, x) \, \mathrm{d}x - \int_{\mathbb{R}} v(t, x) \partial_t \psi(t, x) \, \mathrm{d}x.$$

It is well defined since  $\zeta$  is at least  $C^2$  and assuming  $\operatorname{supp}(\zeta) \subset [-R, +R]$ , for any t fixed,  $x \mapsto \psi(t, x)$  is supported in [-R - c|t - T|, R + c|t - T|]. Therefore  $I \in C^0(\mathbb{R})$  with

$$I(0) = 0,$$
  $I(T) = -\int v(T, x)\zeta(x) \, \mathrm{d}x.$ 

Goal: show that I(t) = 0 for any t.

# Uniqueness, III

*I* is only continuous: we cannot take  $\frac{d}{dt}$ . Let  $\theta \in C^{\infty}_{c}(\mathbb{R})$ . With integration by parts:  $\int_{\mathbb{D}} I(t)\theta'(t) \, \mathrm{d}t = \iint_{\mathbb{D}\times\mathbb{D}} \partial_t v(t,x)\psi(t,x)\theta'(t) \, \mathrm{d}x \, \mathrm{d}t - \iint_{\mathbb{D}\times\mathbb{D}} v(t,x)\partial_t \psi(t,x)\theta'(t) \, \mathrm{d}x \, \mathrm{d}t$  $= \iint_{\mathbb{R} \times \mathbb{R}} \partial_t v(t, x) \partial_t (\psi(t, x) \theta(t)) \, \mathrm{d}x \, \mathrm{d}t - \iint_{\mathbb{R} \times \mathbb{R}} \partial_t v(t, x) \partial_t \psi(t, x) \theta(t) \, \mathrm{d}x \, \mathrm{d}t$  $-\iint_{\mathbb{T}_{u,w}} v(t,x)\partial_t \psi(t,x)\theta'(t)\,\mathrm{d}x\,\mathrm{d}t$  $= \iint_{\mathbb{R}\times\mathbb{R}} \partial_t v(t,x) \partial_t \big( \psi(t,x)\theta(t) \big) \, \mathrm{d}x \, \mathrm{d}t + \iint_{\mathbb{R}\times\mathbb{D}} v(t,x) \partial_t \big( \partial_t \psi(t,x)\theta(t) \big) \, \mathrm{d}x \, \mathrm{d}t$  $-\iint_{\mathbb{T}} v(t,x)\partial_t \psi(t,x)\theta'(t)\,\mathrm{d}x\,\mathrm{d}t$  $= \iint_{\mathbb{D}\times\mathbb{D}} \partial_t v(t,x) \partial_t \big( \psi(t,x)\theta(t) \big) \, \mathrm{d}x \, \mathrm{d}t + \iint_{\mathbb{D}\times\mathbb{D}} v(t,x) \partial_{tt}^2 \psi(t,x)\theta(t) \, \mathrm{d}x \, \mathrm{d}t$  $= \iint_{\mathbb{R} \to \mathbb{R}} \partial_t v(t, x) \partial_t \big( \psi(t, x) \theta(t) \big) \, \mathrm{d}x \, \mathrm{d}t + \iint_{\mathbb{R} \to \mathbb{R}} v(t, x) c^2 \partial_{xx}^2 \psi(t, x) \theta(t) \, \mathrm{d}x \, \mathrm{d}t$  $= \iint_{\mathbb{D} \to \mathbb{D}^n} (\partial_t - c \partial_x) v(t, x) (\partial_t + c \partial_x) (\psi(t, x) \theta(t)) \, \mathrm{d}x \, \mathrm{d}t = 0.$ ・ 《母 》 《 母 》 《 母 》 《 母 》 《

#### Uniqueness, IV

Work with

$$\theta(t) = \int_0^t \left( h(\tau) - \kappa(\tau) \int_0^T h(s) \, \mathrm{d}s \right) \mathrm{d}\tau$$

with *h* and  $\kappa$  continuous, supported in [0, T], with  $\int_0^T \kappa(s) ds = 1$ . Thus  $\theta$  is  $C^1$  on [0, T] with  $\theta(0) = 0$  and  $\theta(T) = 0$ . Since  $\theta'(t) = h(t) - \kappa(t) \int_0^T h(s) ds$ , we get

$$\int_{\mathbb{R}} I(t)\theta'(t)\,\mathrm{d}t = \int_0^T I(t)\theta'(t)\,\mathrm{d}t = 0 = \int_0^T \left(I(t) - \int_0^T I(s)\kappa(s)\,\mathrm{d}s\right)h(t)\,\mathrm{d}t.$$

It holds for arbitrary trial function h, thus I(t) is constant on [0, T]. Since I(0) = 0, we have I(t) = 0 on [0, T], and finally v(t, x) = 0 a.e.