

# Performance Analysis of P2P Storage Systems

## Data Lifetime Under Constrained Bandwidth and Multiple Failures

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# Research report

This presentation is based on research report:



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Julian MONTEIRO, Stéphane PERENNES**

Analysis of the Repair Time in Distributed Storage Systems  
INRIA Rapport de recherche RR-7538, 2011

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  - System mechanics
  - Related work
- 2 Factor of efficiency**
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# Motivation

- Indefinite backup
  - negligible read rate
  - high reliability:  $10^{-5}$  loss probability/100GB  $\rightsquigarrow$   $10^{-12}$  loss probability/5MB
- Cheap and scalable
  - highly distributed
  - unreliable hardware
  - uses consumer connections
- Better model
  - To be sure how design parameters shape reliability
  - Remove unasserted assumptions
  - Look into often omitted detail
  - Relate everything to costs and probability of failure
  - Thoroughly validated

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# Case study

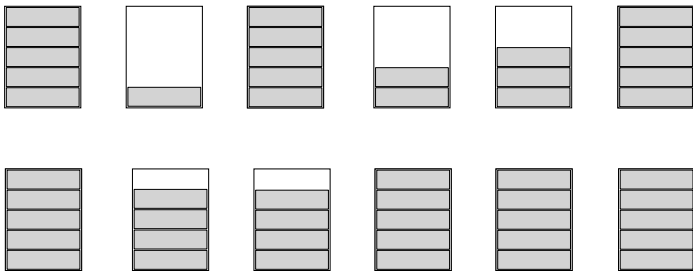
- Users have 1Mbps connections, but allocate 128kbps to repairs
- Users allocate 300GB disk space, insert 100GB data
- Expected lifetime = 1 year, neighbourhood size = 100 peers
- Repair time of 1 disk = 17 hours ( $= 100 \cdot 8 \cdot 10^6 \text{kb} / (100 \cdot 128 \text{kbps})$ )
- Probability of data loss per year (PDLPY) of  $10^{-8}$
- By our model, repair time = 9 days, PDLPY = 0.2

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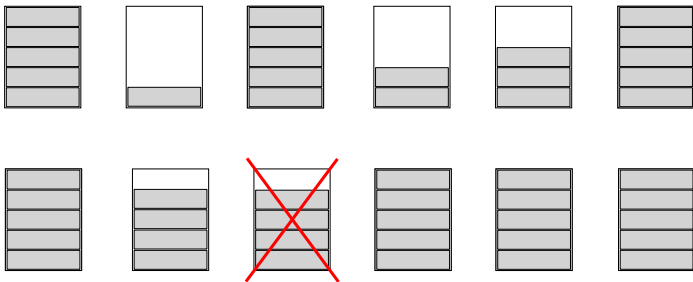


# System mechanics



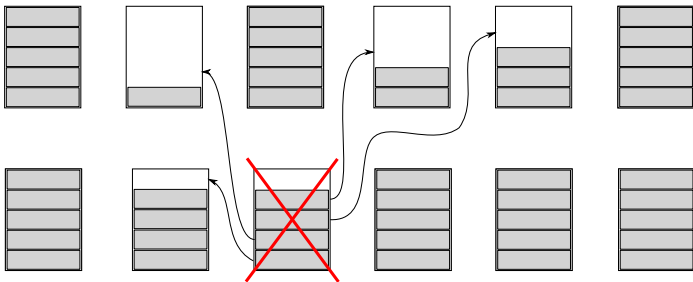
Data redundancy maintained in continuous repair process

# System mechanics



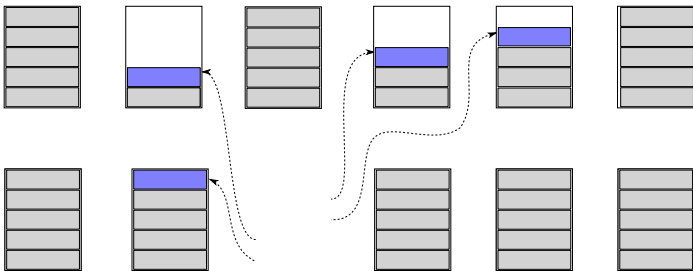
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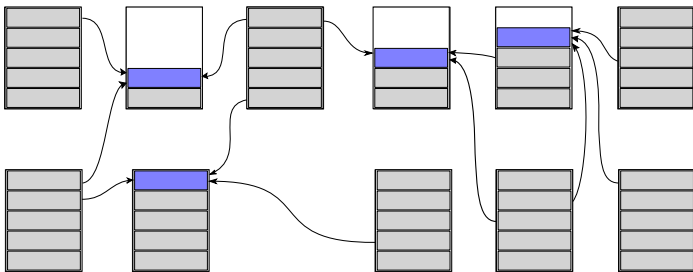
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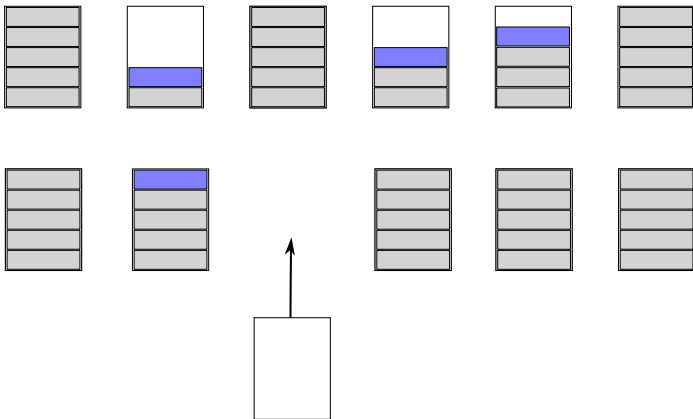
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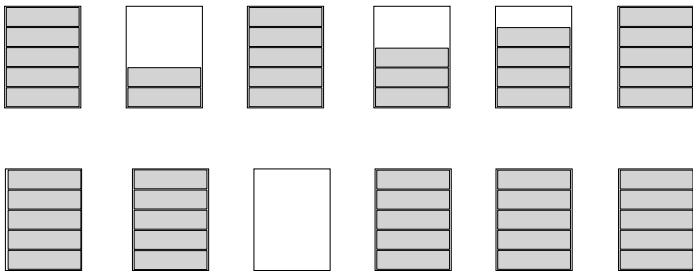
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# Related work

Some of the similar works:

- **Analysis of Failure Correlation Impact on Peer-to-Peer Storage Systems** by Dalle et al. looks into whole disk failures, but assumes exponential reconstruction time; 2009
- **Simulation analysis of download and recovery processes in P2P storage systems** by Dandoush et al. find download/recovery time hypo-exponential, but looks only at single fragment level; 2009
- **Availability in Globally Distributed Storage Systems** by Ford et al. bases on a large body of data tracing Google storage systems; 2010



# Peer imbalance

## Reasons:

- New disks are **empty**, fill up gradually
  - disk load / age — truncated geometric distribution
- Workload depends on disk load
- Repairs typically need fragments from full disks

## Effect:

- Repair time given by wait time for full disks
- Young disks unutilized  $\Rightarrow$  **wasted bandwidth**

# Peer imbalance

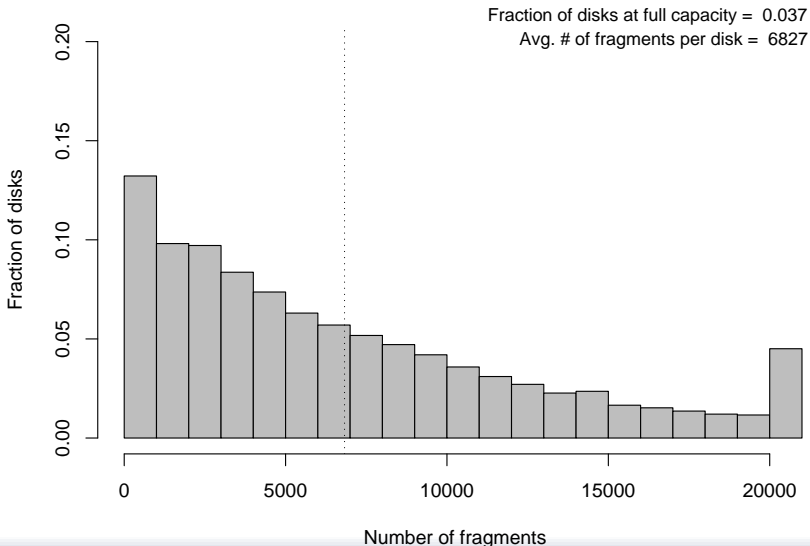
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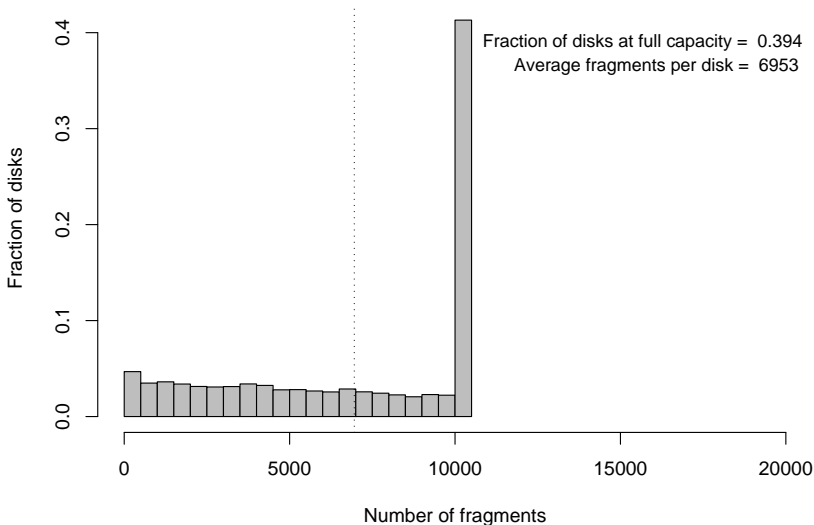
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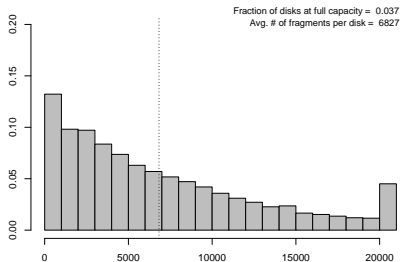
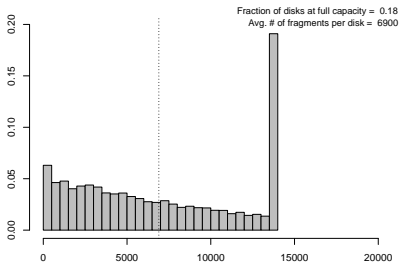
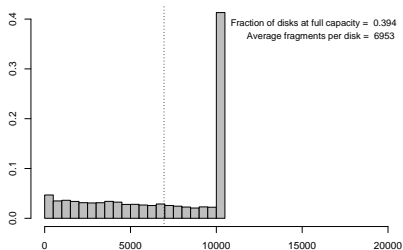
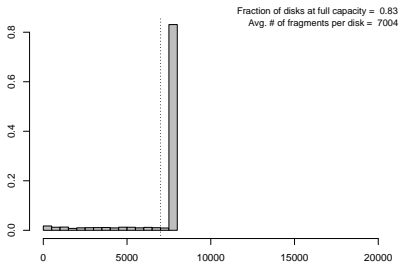
# Disk load imbalance at global 33% ( $x = 3$ )



# Disk load imbalance at global 66% ( $x = 3/2$ )



# Disk load imbalance — comparison



# Factor of efficiency

Let:

- $x$  be the disk **overcapacity** — average capacity / average usage
- $\rho$  be the **factor of efficiency** — total throughput / total bandwidth

We found out that:

$$\rho \approx \frac{1}{x}$$

# Verification

$x$	1.1	1.5	2.0	3.0
$\varphi_{sim}$	0.83	0.39	0.18	0.04
$\varphi_{model}$	0.83	0.42	0.20	0.06
$\varphi x$	0.91	0.63	0.4	0.18
$P_{full}$	$1 - 10^{-14}$	$1 - 10^{-5}$	0.999	0.92
$\rho_{sim}$	0.83	0.63	0.48	0.40
$\rho_{model}$	0.91	0.67	0.5	0.33
$T_{sim}$	1.07	2.69	8.55	21.76
$T_{model}$	1.00	2.61	17.81	54.61

Where:  $\varphi$  - fraction of full disks in network;  $P_{full}$  - probability of a block to have  $\geq 1$  fragment on a full disk;  $T$  - reconstruction time;  $n = 14$  - # fragments for each block

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Even when full disks are rare, most blocks have a fragment on them



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Model closely matches simulations

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$x$  has high impact on reconstruction time

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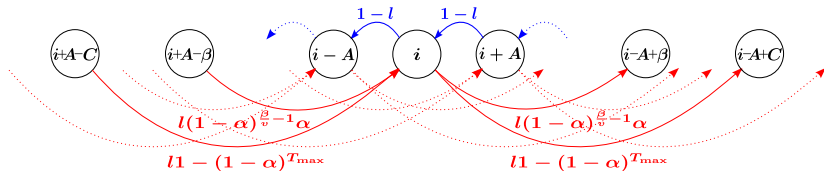
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Model would need extension for big  $x$ ,  
but this represents inefficient resource usage

# Why a queueing model?

- Target system has **many** peers
- We want to know what happens in years of work
- Simulations would consume prohibitive amounts of time
  - some operations done on each block in each time step
  - 100'000 peers
  - 100GB per peer / 5MB blocks = 20'000 blocks per peer
  - 10 years with 1 hour resolution
  - **over 5 years of simulation** assuming  $10^6$  operations / second

# Markovian queuing model



- Global queue of all blocks needing repair
- $M^\beta/D/1$ ,  $\beta$  is the batch size function
- States — number of fragments in queue
- Transitions — reconstructions or failings
- 2 batch sizes — full disk; expected value of non-full disk

# What does it give?

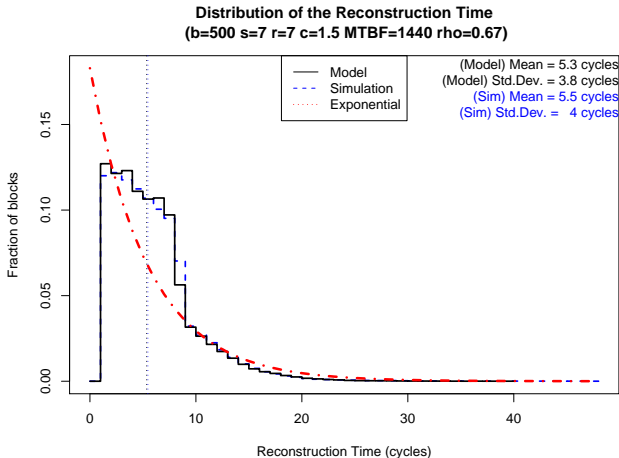
- Waiting time given directly by stationary state of the queue
- Same goes for bandwidth usage
- Expected data loss computed using stationary state
- Stationary state computed semi-analytically or numerically
- Implementation in **R** converges in  $<2s$

# Simulations/Experiments

- Markovian queuing model implemented in R
- Custom simulator implemented in Java
- Experiments based on UbiStorage system deployed on Grid5000



# Reconstruction time: model vs simulation

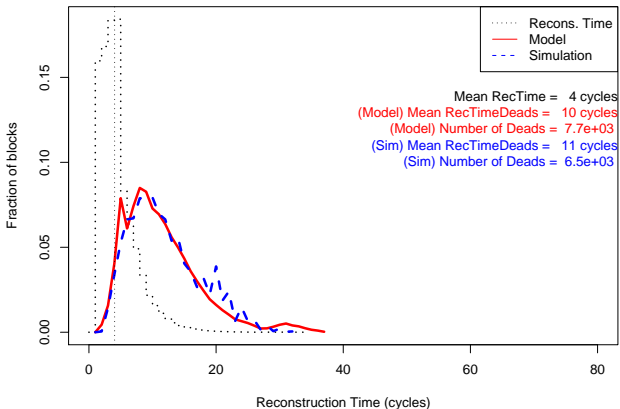


Not always exponential



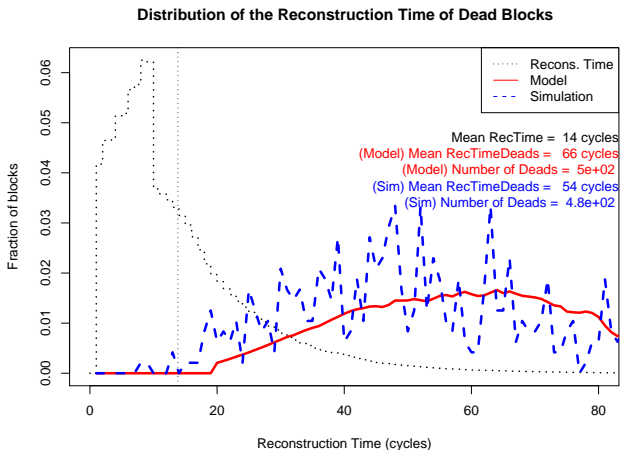
# Lost data: model vs simulation

## Distribution of the Reconstruction Time of Dead Blocks



With too much short repairs; almost perfect fit

# Lost data: model vs simulation

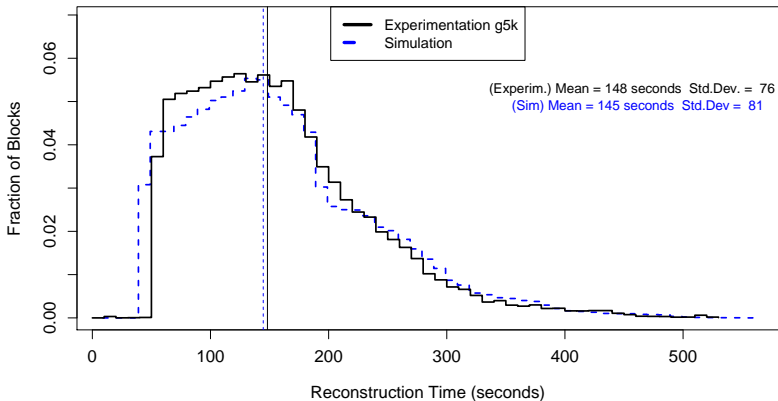


For the long tail; smooth fit

# Experimentation setup

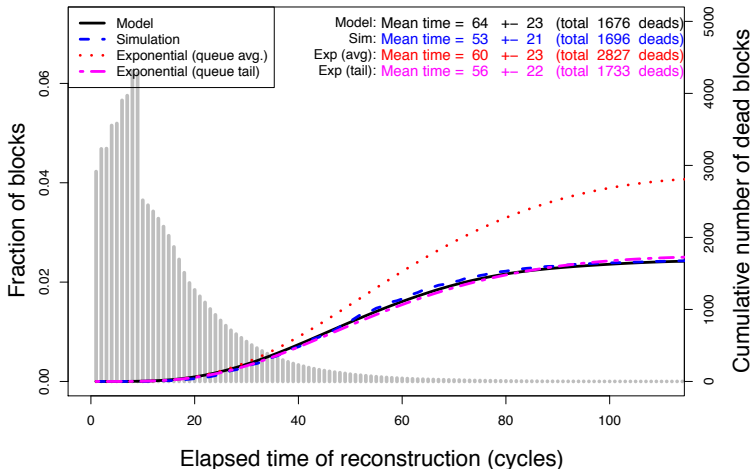
- An overlay of 50–200 peers built on Grid5000 nodes
- Failures according to traces or a random process
- Acceleration factor of 3–350
  - All times compressed
  - Less data
  - Limited bandwidth
- Same parameters fed into simulator and model

# Experimentation results



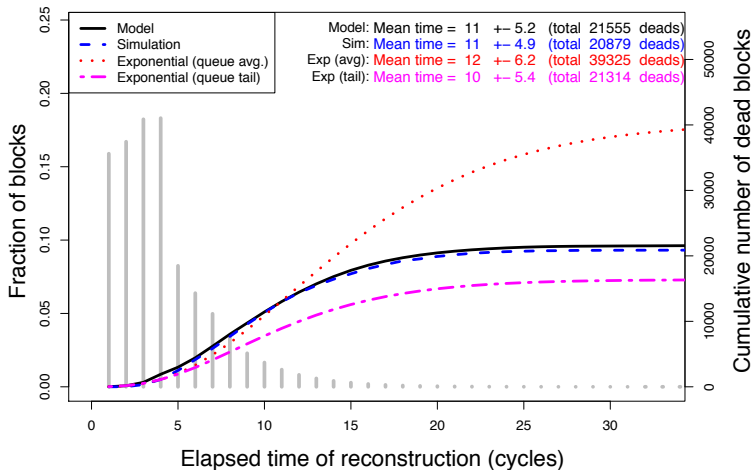
Pretty good fit too

# Exponential, average and tail



Sometimes exponential is good enough if fitting tail

# Exponential, average and tail



Sometimes it is not

# Take-aways

- Intuition is not sufficient
- Simplistic methods fit only some scenarios
- Seemingly irrelevant details do matter
- Simple, accurate and validated model was proposed