

Automated Complexity Analysis of Term Rewrite Systems

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Today's Lecture

From Theory to Automation

1. complexity pairs and relative rewriting
2. dependency pairs for complexity analysis
3. case study: TCT , its complexity framework

Applications to Program Analysis

4. case study: higher-order functional programs

Experimental Evaluation

Input	#rules	orders	TCT
appendAll	12	$O(n^2)$	$O(n)$
bfs	57	?	$O(n)$
bft mmult	59	?	$O(n^3)$
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Figure: Analysis of translated resource aware ML programs.

Towards a Modular Analysis

- ★ complexity pairs and relative rewriting
- ★ weak dependency pairs/dependency tuples
- ★ safe reduction pairs

Complexity Analysis via Relative Rewriting

Definition (relative reduction relation)

★ for two ARSs \rightarrow and \rightsquigarrow over carrier A , define

$$\rightarrow / \rightsquigarrow \triangleq \rightsquigarrow^* \cdot \rightarrow \cdot \rightsquigarrow^* .$$

★ for two TRSs \mathcal{R} and \mathcal{S} ,

$$\rightarrow_{\mathcal{R}/\mathcal{S}} \triangleq \rightarrow_{\mathcal{R}} / \rightarrow_{\mathcal{S}} \qquad \xrightarrow{i}_{\mathcal{R}/\mathcal{S}} \triangleq \xrightarrow{\mathcal{R} \cup \mathcal{S}}_{\mathcal{R}} / \xrightarrow{\mathcal{R} \cup \mathcal{S}}_{\mathcal{S}}$$

– $C[f(l_1\sigma, \dots, l_k\sigma)] \xrightarrow{Q}_{\mathcal{R}} C[r\sigma]$ if $f(l_1, \dots, l_k) \rightarrow r \in \mathcal{R}$ and $l_i\sigma \in \text{NF}(\rightarrow_Q)$.

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Theorem

$$\text{dc}_{\rightarrow \cup \rightsquigarrow, \mathcal{S}} \leq \text{dc}_{\rightarrow / \rightsquigarrow, \mathcal{S}} + \text{dc}_{\rightsquigarrow / \rightarrow, \mathcal{S}} .$$

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Example

For $a \rightarrow b$ and $a \rightsquigarrow c$, $\text{dh}_{\rightarrow \cup \rightsquigarrow}(a) = 1 < 2 = \text{dh}_{\rightarrow / \rightsquigarrow}(a) + \text{dh}_{\rightsquigarrow / \rightarrow}(a)$.

Complexity Pairs

Definition (Zankl & Korp, LMCS'14)

- ★ **Complexity pair (CP)** is pair (\succ, \succsim) of rewrite orders s.t. $\succsim \cdot \succ \cdot \succsim \subseteq \succ$.
- ★ **Compatibility** with **relative TRS** \mathcal{R}/\mathcal{S} if $\mathcal{R} \subseteq \succ$ and $\mathcal{S} \subseteq \succsim$.

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If CP (\succ, \succeq) compatible with \mathcal{R}/\mathcal{S} then

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Theorem (Iterative Complexity Analysis)

If CP (\succ, \succeq) compatible with $\mathcal{R}_1/\mathcal{R}_2 \cup \mathcal{S}$ then

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Note: remains valid for rewriting under strategies

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Dependency Pairs and RC

Theorem

TRS \mathcal{R} is *terminating* iff there is no infinite and minimal chain

$$f^\#(s_1, \dots, s_m) \rightarrow_{\text{DP}(\mathcal{R})/\mathcal{R}} g^\#(t_1, \dots, t_n) \rightarrow_{\text{DP}(\mathcal{R})/\mathcal{R}} \dots$$

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Corollary

TRS \mathcal{R} is *terminating* on \mathcal{B} iff

$$\forall n \in \mathbb{N}. \text{rc}_{\text{DP}(\mathcal{R})/\mathcal{R}}^\#(n) \triangleq \text{dc}_{\text{DP}(\mathcal{R})/\mathcal{R}, \mathcal{B}^\#}(n) \in \mathbb{N}.$$

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Questions:

1. is there a “small” $f: \mathbb{N} \rightarrow \mathbb{N}$ s.t. $\text{rc}_{\mathcal{R}}(n) \leq f(\text{rc}_{\text{DP}(\mathcal{R})/\mathcal{R}}^\#(n))$?
2. what about techniques from the DP framework?

Dependency Pairs and RC (II)

Example

Consider \mathcal{R}

$$f(s(x)) \rightarrow s(f(f(x)))$$

$$f(x) \rightarrow \text{dup}(x, x) ,$$

with $\text{DP}(\mathcal{R})$

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Then $\text{rc}_{\text{DP}(\mathcal{R})/\mathcal{R}}^\#$ is linear whereas $\text{rc}_{\mathcal{R}}(n)$ grows double-exponential.

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Question: Reasons that cause this blow-up?

1. DPs track single path in “calls graph”
2. DPs do not account for duplication

Weak Dependency Pairs and Dependency Tuples

★ **Weak Dependency Pairs WDP(\mathcal{R})** [Hirokawa & Moser, IJCAR'08]

1. bundle **outermost function calls** in weak dependency pair

$$f^\#(l_1, \dots, l_k) \rightarrow c_n(r_1^\#, \dots, r_n^\#) \quad \text{for each } f(l_1, \dots, l_k) \rightarrow C[r_1, \dots, r_n] \in \mathcal{R}$$

where C maximal constructor-context

2. impose **non-duplication & weight-gap** condition



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★ Dependency Pair Tuples $DT(\mathcal{R})$ [Noschinski et al., CADE'11]

1. bundle **all function calls** in dependency tuple
2. restricted to **innermost rewriting**



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Dependency Tuples

Definition (dependency tuples, Noschinski et. al, CADE'11)

★ **dependency tuple** of $f(l_1, \dots, l_m) \rightarrow r$ is

$$f^\#(l_1, \dots, l_m) \rightarrow c_k(g_1^\#(\vec{t}_1), \dots, g_k^\#(\vec{t}_k)) ,$$

where $g_1(\vec{t}_1), \dots, g_k(\vec{t}_k)$ are all subterms of r with defined root;

★ **DT(\mathcal{R})** collects DTs of rules in \mathcal{R}



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Example \mathcal{R}

DT(\mathcal{R})

$$[] \text{ ++ } ys \rightarrow ys$$

$$[] \text{ ++}^\# \rightarrow c_0$$

$$(x :: xs) \text{ ++ } ys \rightarrow x :: (xs \text{ ++ } ys) \quad (x :: xs) \text{ ++}^\# ys \rightarrow c_1(xs \text{ ++}^\# ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}^\#([]) \rightarrow c_0$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \text{ ++ } [x] \quad \text{rev}^\#(x :: xs) \rightarrow c_2(\text{rev}(xs) \text{ ++}^\# [x], \text{rev}^\#(xs))$$

Dependency Tuples (II)

Lemma

Reduction sequence

$$f(v_1, \dots, v_k) \xrightarrow{i}_{\mathcal{R}} t_1 \xrightarrow{i}_{\mathcal{R}} t_2 \xrightarrow{i}_{\mathcal{R}} \dots,$$

simulated step-wise by reduction

$$f^\#(v_1, \dots, v_k) \xrightarrow{i}_{DT(\mathcal{R})/\mathcal{R}} C_1[\vec{s}_1] \xrightarrow{i}_{DT(\mathcal{R})/\mathcal{R}} C_2[\vec{s}_2] \xrightarrow{i}_{DT(\mathcal{R})/\mathcal{R}} \dots,$$

with \vec{s}_i marked innermost redexes in t_i .

Dependency Triples (III)

Example

Sequence

$$\text{rev}([1, 2]) \xrightarrow{i}_{\mathcal{R}_{\text{rev}}} \underline{\text{rev}([3])} \dot{+} [1] \xrightarrow{i}_{\mathcal{R}_{\text{rev}}} (\text{rev}([]) \dot{+} [2]) \dot{+} [1] \xrightarrow{i}_{\mathcal{R}_{\text{rev}}} \dots,$$

translates to

$$\begin{aligned} \text{rev}^{\#}([1, 2]) &\xrightarrow{i}_{\text{DT}(\mathcal{R}_{\text{rev}})/\mathcal{R}_{\text{rev}}} C_1[\underline{\text{rev}([3])} \dot{+}^{\#} [1], \underline{\text{rev}^{\#}([3])}] \\ &\xrightarrow{i}_{\text{DT}(\mathcal{R}_{\text{rev}})/\mathcal{R}_{\text{rev}}} C_2[(\text{rev}([]) \dot{+} [2]) \dot{+}^{\#} [1], \text{rev}([]) \dot{+}^{\#} [2], \text{rev}^{\#}([])] \\ &\xrightarrow{i}_{\text{DT}(\mathcal{R}_{\text{rev}})/\mathcal{R}_{\text{rev}}} \dots \end{aligned}$$

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Theorem (Soundness of DTs (Noschinski et. al, CADE'11))

$$\text{rc}_{\mathcal{R}}(n) \leq \text{rc}_{\text{DT}(\mathcal{R})/\mathcal{R}}^{\#}(n) .$$

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Question: What about inverse, i.e., completeness?

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★ $\text{rc}_{\mathcal{R}}(n) = \text{rc}_{\text{DT}(\mathcal{R})/\mathcal{R}}^{\#}(n)$ if \mathcal{R} is **confluent**

Safe Reduction Pairs

Definition (Hirokawa & Moser, IJCAR'08)

- ★ **Safe reduction pair** is pair $(>, \gtrsim)$ of orders on terms s.t.
 - $>$ is closed under substitutions and monotone on compound symbols c_i introduced by WDPs/DTs
 - \gtrsim is a rewrite order
 - $\gtrsim \cdot > \cdot \gtrsim \subseteq >$
- ★ **compatible** with \mathcal{P}/\mathcal{R} if $\mathcal{P} \subseteq >$ and $\mathcal{R} \subseteq \gtrsim$.

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- ★ **compatible** with \mathcal{P}/\mathcal{R} if $\mathcal{P} \subseteq \succ$ and $\mathcal{R} \subseteq \succsim$.

Theorem

If (\succ, \succsim) compatible with \mathcal{P}/\mathcal{R} then

$$\text{rc}_{\mathcal{P}/\mathcal{R}}^{\#}(n) \leq \text{dc}_{\succ, \mathcal{B}^{\#}}.$$

Note: As for complexity pairs, can be applied in iterative way

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Figure: Analysis of translated resource aware ML programs.

Case Study: TCT

- ★ complexity problems and processors
- ★ complexity processors
 - dependency graph decomposition
 - usable rules
 - complexity pairs & relative rewriting

Tyrolean Complexity Tool

History

2008 version 1.0 *extension to termination prover $T\overline{T}_2$*

- ★ 4 dedicated complexity techniques (POP*, WDPs, safe reduction pairs, usable rules)

2009 version 1.5 *first dedicated implementation*

- ★ 9 methods implemented

2013 version 2.0 *Gödel award at FLOC Olympic Games*

- ★ 23 methods implemented
- ★ modular complexity framework

2015 version 3.3 *current version*

- ★ certification support through CeTA
- ★ frontends for functional and imperative programs

Complexity Framework Underlying TCT

1. **complexity problem** is tuple $\mathcal{P} = \langle S, W, Q, \mathcal{T} \rangle$
 - S, W and Q define rewrite relation $\xrightarrow{Q}_{S \cup W}$ of \mathcal{P}
 - \mathcal{T} is set of starting terms

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$$\text{cp}_{\mathcal{P}}(n) \triangleq \text{dc}_{\xrightarrow{\mathcal{Q}}_{\mathcal{S}/\mathcal{W}, \mathcal{T}}}(n),$$

3. **complexity processor** is inference rule

$$\frac{\vdash \mathcal{P}_1 : f_1 \quad \dots \quad \vdash \mathcal{P}_n : f_n}{\vdash \mathcal{P} : f}$$

- **judgement** $\vdash \mathcal{P} : f$ valid if $\text{cp}_{\mathcal{P}}(n) \in O(f(n))$
- processor **sound** if validity of judgements preserved

Complexity Framework Underlying TCT

1. **complexity problem** is tuple $\mathcal{P} = \langle \mathcal{S}, \mathcal{W}, \mathcal{Q}, \mathcal{T} \rangle$
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$$\text{cp}_{\mathcal{P}}(n) \triangleq \text{dc}_{\xrightarrow{\mathcal{Q}}_{\mathcal{S}/\mathcal{W}, \mathcal{T}}}(n),$$

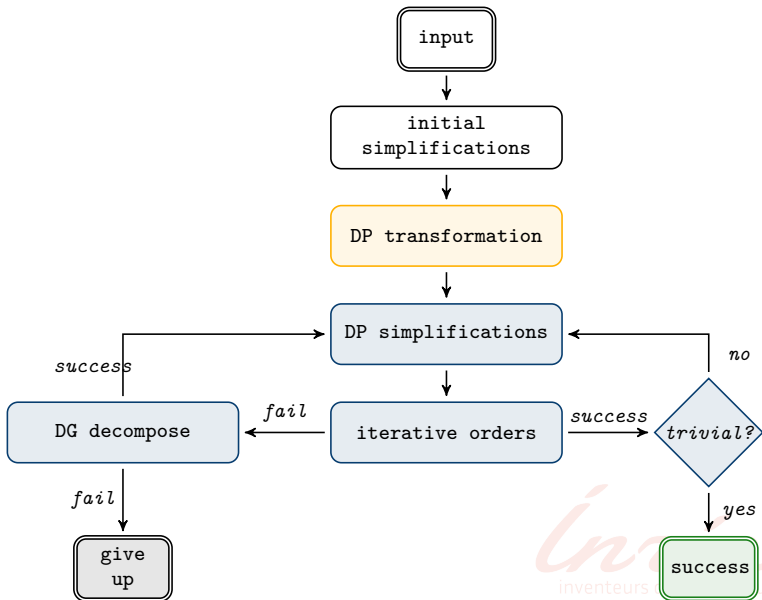
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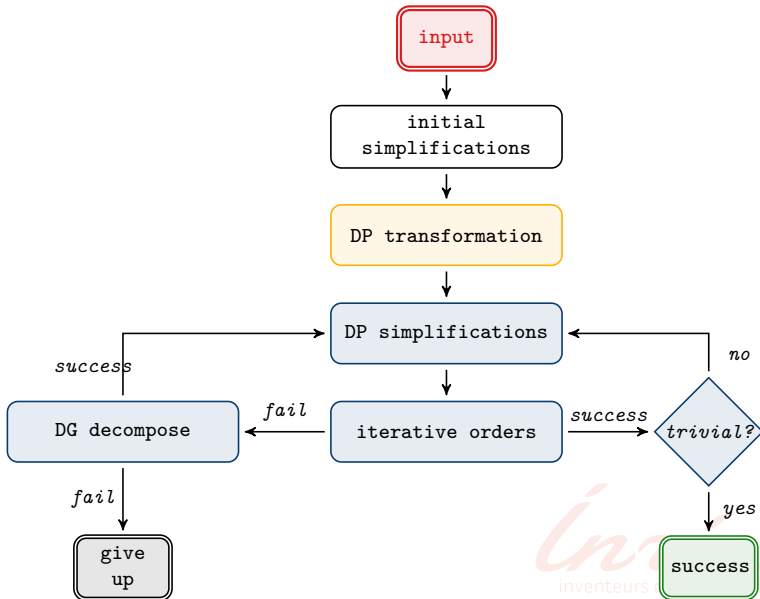
- **judgement** $\vdash \mathcal{P} : f$ valid if $\text{cp}_{\mathcal{P}}(n) \in O(f(n))$
 - processor **sound** if validity of judgements preserved
4. **complexity proof** is deduction using sound processors and axiom

$$\vdash \langle \emptyset, \mathcal{W}, \mathcal{Q}, \mathcal{T} \rangle : f$$

Runtime Complexity Proof Search in TCT



Runtime Complexity Proof Search in TCT



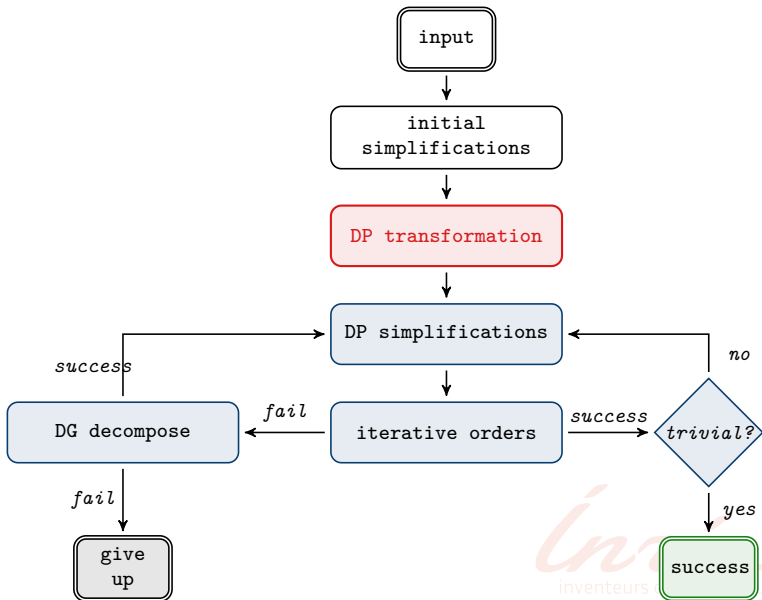
Canonical Complexity Problems

Definition (canonical complexity problem)

Let \mathcal{R} be a TRS over terms \mathcal{T} and basic terms \mathcal{B}

	full	innermost
derivational	$\langle \mathcal{R}, \emptyset, \emptyset, \mathcal{T} \rangle$	$\langle \mathcal{R}, \emptyset, \mathcal{R}, \mathcal{T} \rangle$
runtime	$\langle \mathcal{R}, \emptyset, \emptyset, \mathcal{B} \rangle$	$\langle \mathcal{R}, \emptyset, \mathcal{R}, \mathcal{B} \rangle$

Runtime Complexity Proof Search in TCT



Dependency Tuples in TCT

Theorem (Dependency Tuple Transformation)

The following processor is sound

$$\frac{\vdash \langle \text{DT}(\mathcal{S}), \text{DT}(\mathcal{W}) \cup \mathcal{S} \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f \quad \text{NF}(\mathcal{Q}) \subseteq \text{NF}(\mathcal{S} \cup \mathcal{W})}{\vdash \langle \mathcal{S}, \mathcal{W}, \mathcal{Q}, \mathcal{B} \rangle : f} \text{DT}$$

Example: Initial IRC Problem

current: $\langle S, W, Q, B \rangle$

$$\begin{array}{ll} S & \begin{array}{l} [] \vdash ys \rightarrow ys \\ (x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys) \end{array} \end{array} \qquad \begin{array}{l} \text{rev}([]) \rightarrow [] \\ \text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x] \end{array}$$

$$W \qquad \emptyset$$

$$\begin{array}{ll} Q & \begin{array}{l} [] \vdash ys \rightarrow ys \\ (x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys) \end{array} \end{array} \qquad \begin{array}{l} \text{rev}([]) \rightarrow [] \\ \text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x] \end{array}$$

Example: DT Transformation

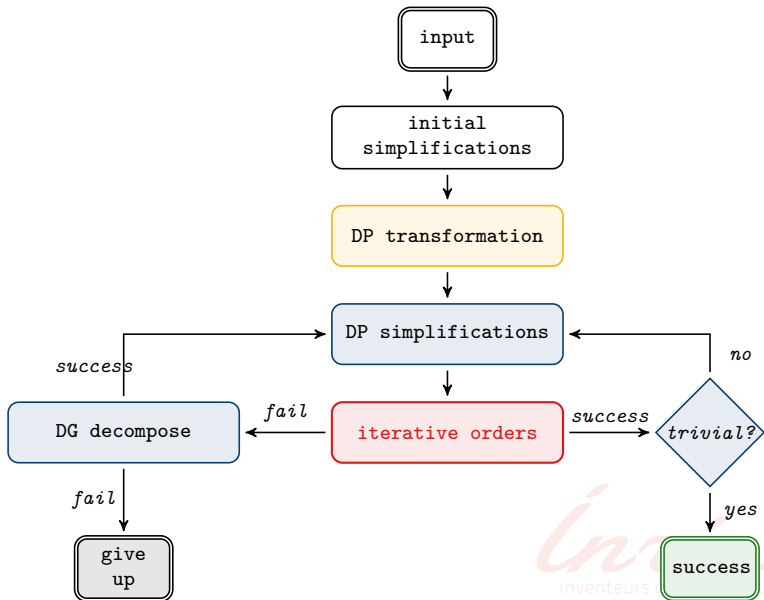
current: $\langle S, W, Q, B^\# \rangle$

$$\begin{array}{ll} S & [] \mathbin{++}^\# ys \rightarrow c_0 \qquad \text{rev}^\#([]) \rightarrow c_0 \\ & (x :: xs) \mathbin{++}^\# ys \rightarrow c_1(xs \mathbin{++}^\# ys) \quad \text{rev}^\#(x :: xs) \rightarrow c_2(\text{rev}(xs) \mathbin{++}^\# [x], \text{rev}^\#(xs)) \end{array}$$

$$\begin{array}{ll} W & [] \mathbin{++} ys \rightarrow ys \qquad \text{rev}([]) \rightarrow [] \\ & (x :: xs) \mathbin{++} ys \rightarrow x :: (xs \mathbin{++} ys) \qquad \text{rev}(x :: xs) \rightarrow \text{rev}(xs) \mathbin{++} [x] \end{array}$$

$$\begin{array}{ll} Q & [] \mathbin{++} ys \rightarrow ys \qquad \text{rev}([]) \rightarrow [] \\ & (x :: xs) \mathbin{++} ys \rightarrow x :: (xs \mathbin{++} ys) \qquad \text{rev}(x :: xs) \rightarrow \text{rev}(xs) \mathbin{++} [x] \end{array}$$

Runtime Complexity Proof Search in TCT



Complexity Pairs & Relative Rewriting

Theorem (Relative Decomposition Processor)

The following processor is sound:

$$\frac{\vdash \langle \mathbf{S}_1, \mathbf{S}_2 \cup \mathbf{W}, \mathbf{Q}, \mathbf{T} \rangle : f \quad \vdash \langle \mathbf{S}_2, \mathbf{S}_1 \cup \mathbf{W}, \mathbf{Q}, \mathbf{T} \rangle : g}{\vdash \langle \mathbf{S}_1 \cup \mathbf{S}_2, \mathbf{W}, \mathbf{Q}, \mathbf{T} \rangle : f + g} \text{ RD}$$

Theorem (Complexity Pair Processor)

The following processor is sound:

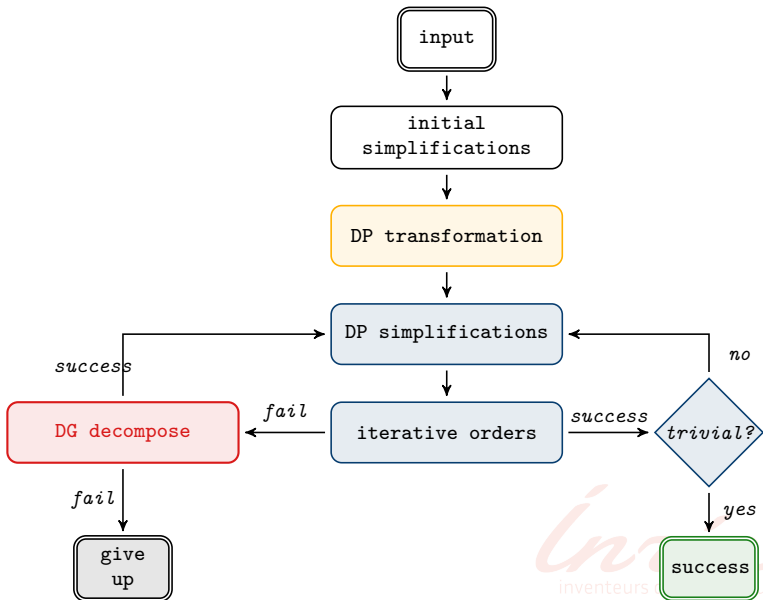
$$\frac{\mathbf{W} \subseteq \succeq \quad \mathbf{S} \subseteq \succ}{\vdash \langle \mathbf{S}, \mathbf{W}, \mathbf{Q}, \mathbf{T} \rangle : \text{dc}_{\succ, \mathbf{T}}} \text{ CP}$$

where (\succeq, \succ) is (ν, μ) -monotone complexity pair with

$$\xrightarrow{\mathbf{Q}}^*_{\mathbf{S} \cup \mathbf{W}}(\mathbf{T}) \subseteq \mathcal{T}_\nu(\xrightarrow{\mathbf{Q}}_{\mathbf{W}}) \quad \xrightarrow{\mathbf{Q}}^*_{\mathbf{S} \cup \mathbf{W}}(\mathbf{T}) \subseteq \mathcal{T}_\mu(\xrightarrow{\mathbf{Q}}_{\mathbf{S}}).$$

★ CP-processor encompasses safe reduction pairs Question: why?

Runtime Complexity Proof Search in TCT



Dependency Graphs

Definition (dependency graph (DG))

dependency graph of (DP) problem $\mathcal{P} = \langle \mathcal{S}, \mathcal{W}, \mathcal{Q}, \mathcal{T} \rangle$ is graph where

- ★ nodes are dependency pairs of \mathcal{P}
- ★ there is an edge labeled i from $s \rightarrow c_k(t_1, \dots, t_k)$ to $u \rightarrow c_l(v_1, \dots, v_l)$ if $t_i\sigma \xrightarrow{\mathcal{Q}}_{\mathcal{S} \cup \mathcal{W}}^* u\tau$ holds for some substitutions σ, τ

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- ★ DG reflects order of dependency pair application
- ★ not computable in general \Rightarrow over-approximations exist



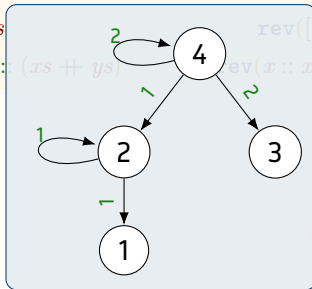
Example: Dependency Graph

current: $\langle S, W, Q, B^\# \rangle$

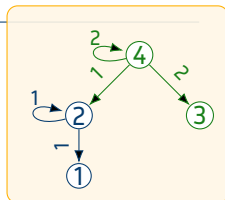
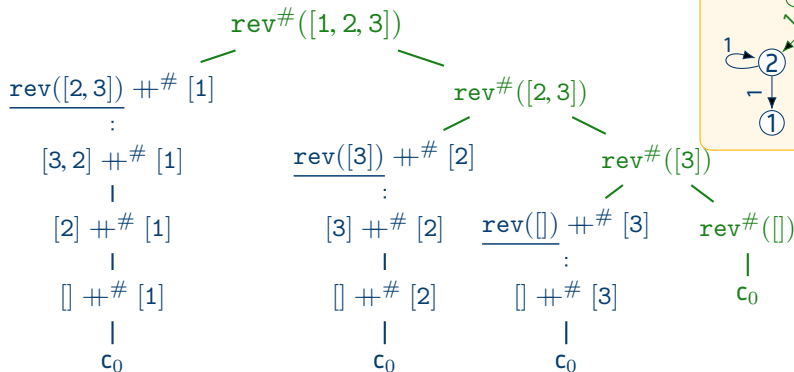
S (1) $[] \dashv\# ys \rightarrow c_0$ (3) $\text{rev}^\#([]) \rightarrow c_0$
(2) $(x :: xs) \dashv\# ys \rightarrow c_1(xs \dashv\# ys)$ (4) $\text{rev}^\#(x :: xs) \rightarrow c_2(\text{rev}(xs) \dashv\# [x], \text{rev}^\#(xs))$

W $[] \dashv ys \rightarrow ys$ $\text{rev}([]) \rightarrow []$
 $(x :: xs) \dashv ys \rightarrow x :: (xs \dashv ys)$ $\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \dashv [x]$

Q $[] \dashv ys \rightarrow ys$ $\text{rev}([]) \rightarrow []$
 $(x :: xs) \dashv ys \rightarrow x :: (xs \dashv ys)$ $\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \dashv [x]$

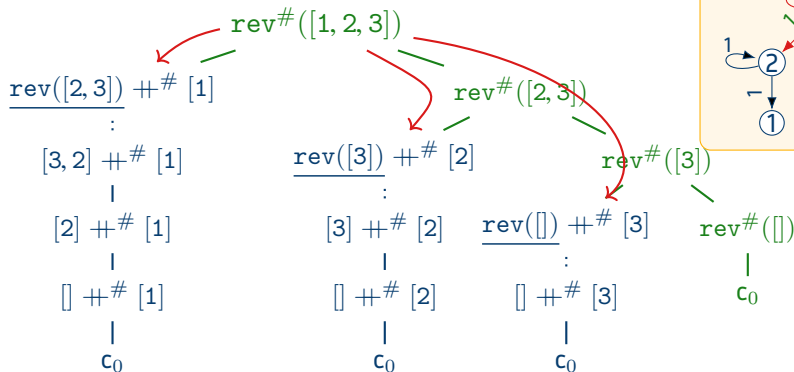


DG Decomposition: Intuitions



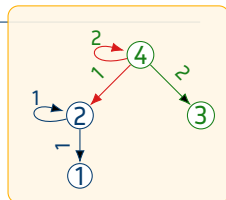
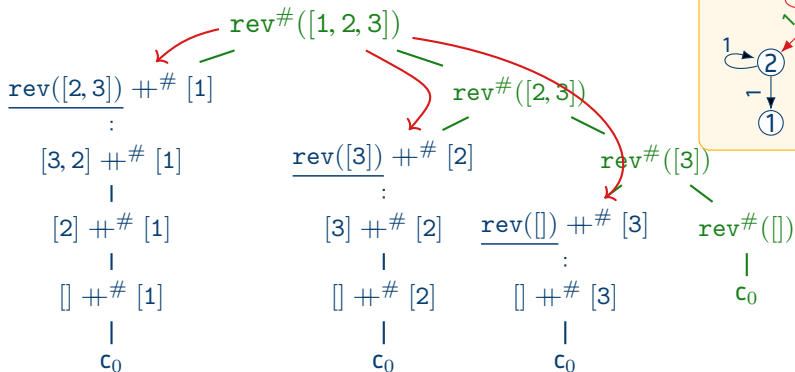
$$\frac{\vdash \langle \{\textcircled{1}, \textcircled{2}\}, \{\textcircled{3}, \textcircled{4}\} \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f \quad \vdash \langle \{\textcircled{3}, \textcircled{4}\}, \{\textcircled{1}, \textcircled{2}\} \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : g}{\vdash \langle \{\textcircled{3}, \textcircled{4}\} \cup \{\textcircled{1}, \textcircled{2}\}, \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f + g} \text{RD}$$

DG Decomposition: Intuitions



$$\frac{\vdash \langle \{\textcircled{1}, \textcircled{2}\}, \textcolor{red}{C} \cup \textcolor{teal}{W}, \textcolor{brown}{Q}, \mathcal{B}^\# \rangle : f \quad \vdash \langle \{\textcircled{3}, \textcircled{4}\}, \textcolor{teal}{W}, \textcolor{brown}{Q}, \mathcal{B}^\# \rangle : g}{\vdash \langle \{\textcircled{3}, \textcircled{4}\} \cup \{\textcircled{1}, \textcircled{2}\}, \textcolor{teal}{W}, \textcolor{brown}{Q}, \mathcal{B}^\# \rangle : f \times g} \text{DGD}$$

DG Decomposition: Intuitions

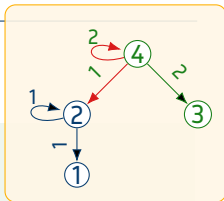


$$\frac{\vdash \langle \{\textcircled{1}, \textcircled{2}\}, \mathcal{C} \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f \quad \vdash \langle \{\textcircled{3}, \textcircled{4}\}, \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : g}{\vdash \langle \{\textcircled{3}, \textcircled{4}\} \cup \{\textcircled{1}, \textcircled{2}\}, \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f \times g} \text{ DGD}$$

$$\mathcal{C} \quad (4 \xrightarrow{1} 2) \quad \text{rev}^\#(x :: xs) \rightarrow \text{rev}(xs) ++^\# [x] \quad (4 \xrightarrow{2} 4) \quad \text{rev}^\#(x :: xs) \rightarrow \text{rev}^\#(xs)$$

Example: DG Decomposition

current: $\langle S_{\downarrow}, C \cup W, Q, B^{\#} \rangle$ and $\langle S_{\uparrow}, W, Q, B^{\#} \rangle$



S_{\downarrow}

$$(1) [] \vdash^{\#} ys \rightarrow c_0$$

$$(2) (x :: xs) \vdash^{\#} ys \rightarrow c_1(xs \vdash^{\#} ys)$$

S_{\uparrow}

$$(3) \text{rev}^{\#}([]) \rightarrow c_0$$

$$(4) \underline{\text{rev}^{\#}(x :: xs)} \rightarrow c_2(\underline{\text{rev}(xs) \vdash^{\#} [x]}, \underline{\text{rev}^{\#}(xs)})$$

C

$$\text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \vdash^{\#} [x] \leftarrow$$

$$\text{rev}^{\#}(x :: xs) \rightarrow \text{rev}^{\#}(xs) \leftarrow$$

W

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

Q

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

DG Decomposition

Theorem (DG Decomposition)

The following processor is sound:

$$\frac{\vdash \langle \mathcal{S}_{\downarrow}, \text{sep}(\mathcal{S}_{\uparrow} \cup \mathcal{W}_{\uparrow}) \cup \mathcal{W}_{\downarrow} \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle : f \quad \vdash \langle \mathcal{S}_{\uparrow}, \mathcal{W}_{\uparrow} \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle : g}{\vdash \langle \mathcal{S}_{\downarrow} \cup \mathcal{S}_{\uparrow}, \mathcal{W}_{\downarrow} \uplus \mathcal{W}_{\uparrow} \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle : f \times g}$$

where

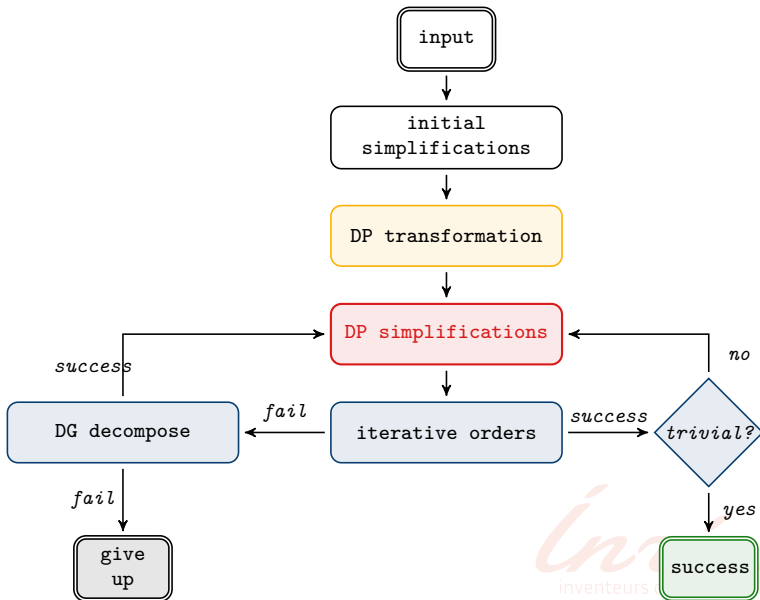
★ $\mathcal{S}_{\downarrow}, \mathcal{S}_{\uparrow}, \mathcal{W}_{\downarrow}, \mathcal{W}_{\uparrow}$ are DPs:

1. $\mathcal{S}_{\downarrow} \cup \mathcal{W}_{\downarrow}$ is forward closed set of DPs in the DG
2. DG-predecessors of $\mathcal{S}_{\downarrow} \cup \mathcal{W}_{\downarrow}$ are in \mathcal{S}_{\uparrow}

★ $\text{sep}(\mathcal{R}) \triangleq \{l \rightarrow r_i \mid l \rightarrow c_k(r_1, \dots, r_k) \in \mathcal{R}\}$



Runtime Complexity Proof Search in TCT



Simplifications: Guided by DG

Theorem (simplify RHSs, remove weak suffix, predecessor estimation)

The following processors are sound:

★ *Simplify RHSs:*

$$\frac{\vdash \langle \text{simp}(\mathcal{S}), \text{simp}(\mathcal{W}), \mathcal{Q}, \mathcal{B}^\# \rangle : f}{\vdash \langle \mathcal{S}, \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f} \text{SIMP-RHS}$$

where **simp** drops r_i if $DP\ l \rightarrow c_k(r_1, \dots, r_i, \dots, r_k)$ has no outgoing edge labeled by i

★ *Remove weak suffix:*

$$\frac{\mathcal{W}_\downarrow \text{ forward-closed DPs} \quad \vdash \langle \mathcal{S}, \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f}{\vdash \langle \mathcal{S}, \mathcal{W} \uplus \mathcal{W}_\downarrow, \mathcal{Q}, \mathcal{B}^\# \rangle : f} \text{RWS}$$

★ *Predecessor estimation:*

$$\frac{DG\text{-predecessors of } \mathcal{S}_1 \subseteq \mathcal{S}_2 \quad \vdash \langle \mathcal{S}_2, \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f}{\vdash \langle \mathcal{S}_1 \cup \mathcal{S}_2, \mathcal{W}, \mathcal{Q}, \mathcal{B}^\# \rangle : f} \text{PE}$$

Simplifications: Usable Rules

Theorem (Usable Rules Processor, Semantic Version)

Usable rules $\mathcal{U}_{\mathcal{P}}(\mathcal{R}) \subseteq \mathcal{R}$ of TRS \mathcal{R} wrt. $\mathcal{P} = \langle \mathcal{S}, \mathcal{W}, \mathcal{Q}, \mathcal{T} \rangle$ are those that can be applied in \mathcal{P} -derivation from \mathcal{T} .

The following processor is sound:

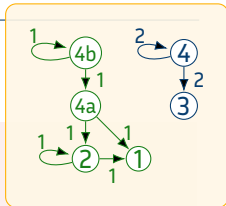
$$\frac{\vdash \langle \mathcal{U}_{\mathcal{P}}(\mathcal{S}), \mathcal{U}_{\mathcal{P}}(\mathcal{W}), \mathcal{Q}, \mathcal{T} \rangle : f}{\vdash \langle \mathcal{S}, \mathcal{W}, \mathcal{Q}, \mathcal{T} \rangle : f} \text{ UR}$$

Notes:

- ★ non-usable rules \approx dead code
- ★ usable rules not computable in general
- ★ over-approximated, e.g. using **tree automata** or via **usable symbols**
 - $f \triangleright g$ iff $f(\vec{l}) \rightarrow r \in \mathcal{P}$ and $g \in \mathcal{D}(r)$
 - usable symbols of terms \mathcal{T} are $\mathcal{US}_{\mathcal{P}}(\mathcal{T}) \triangleq \{g \mid \exists f \in \mathcal{D}(\mathcal{T}). f \triangleright^* g\}$
 - approximated usable rules are $\mathcal{U}_{\mathcal{P}}(\mathcal{R}) \triangleq \{f(\vec{l}) \rightarrow r \in \mathcal{R} \mid f \in \mathcal{US}_{\mathcal{P}}(\mathcal{T})\}$

Example: Simplifications

current: $\langle S_{\downarrow}, C \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle$ and $\langle S_{\uparrow}, \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle$



S_{\downarrow}

$$(1) [] \vdash^{\#} ys \rightarrow c_0$$

$$(2) (x :: xs) \vdash^{\#} ys \rightarrow c_1(xs \vdash^{\#} ys)$$

S_{\uparrow}

$$(3) \text{rev}^{\#}([]) \rightarrow c_0$$

$$(4) \text{rev}^{\#}(x :: xs) \rightarrow c_1(\text{rev}(xs) \vdash^{\#} [x], \text{rev}^{\#}(xs))$$

C

$$(4a) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \vdash^{\#} [x]$$

$$(4b) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}^{\#}(xs)$$

\mathcal{W}

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

\mathcal{Q}

$$[] \vdash ys \rightarrow ys$$

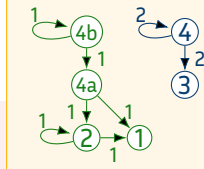
$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

Example: Simplifications

current: $\langle S_{\downarrow}, C \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle$ and $\langle S_{\uparrow}, \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle$



S_{\downarrow}

$$(1) [] \vdash^{\#} ys \rightarrow c_0$$

$$(2) (x :: xs) \vdash^{\#} ys \rightarrow c_1(xs \vdash^{\#} ys)$$

S_{\uparrow}

$$(3) \text{rev}^{\#}([]) \rightarrow c_0$$

$$(4) \text{rev}^{\#}(x :: xs) \rightarrow c_1(\text{rev}(xs) \vdash^{\#} [x], \text{rev}^{\#}(xs))$$

C

$$(4a) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \vdash^{\#} [x]$$

$$(4b) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}^{\#}(xs)$$

\mathcal{W}

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

\mathcal{Q}

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

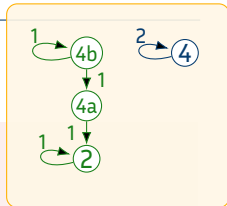
$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

predecessor estimation

Example: Simplifications

current: $\langle S_{\downarrow}, C \cup \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle$ and $\langle S_{\uparrow}, \mathcal{W}, \mathcal{Q}, \mathcal{B}^{\#} \rangle$



S_{\downarrow}

$$(2) (x :: xs) \vdash^{\#} ys \rightarrow c_1(xs \vdash^{\#} ys)$$

S_{\uparrow}

$$(4) \text{rev}^{\#}(x :: xs) \rightarrow c_2(\text{rev}(xs) \vdash^{\#} [x], \text{rev}^{\#}(xs))$$

C

$$(4a) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \vdash^{\#} [x]$$

$$(4b) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}^{\#}(xs)$$

\mathcal{W}

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

\mathcal{Q}

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash y$$

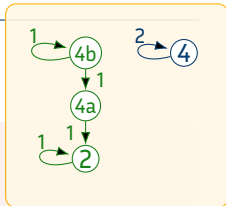
$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(xs) \vdash [x]$$

simplify RHSs

Example: Simplifications

current: $\langle S_{\downarrow}, C \cup W, Q, B^{\#} \rangle$ and $\langle S_{\uparrow}, W, Q, B^{\#} \rangle$



S_{\downarrow}

$$(2) (x :: xs) \vdash^{\#} ys \rightarrow c_1(xs \vdash^{\#} ys)$$

S_{\uparrow}

$$(4) \text{rev}^{\#}(x :: xs) \rightarrow c_1(\text{rev}^{\#}(xs))$$

C

$$(4a) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \vdash^{\#} [x]$$

$$(4b) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}^{\#}(xs)$$

W

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

Q

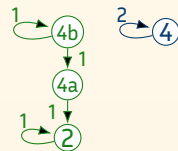
$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash y :: xs \rightarrow \text{rev}(xs) \vdash [x]$$

usable rules

Example: Simplifications

current: $\langle S_{\Downarrow}, C \cup W, Q, B^{\#} \rangle$ and $\langle S_{\Uparrow}, \emptyset, Q, B^{\#} \rangle$



S_{\Downarrow}

$$(2) (x :: xs) \vdash^{\#} ys \rightarrow c_1(xs \vdash^{\#} ys)$$

S_{\Uparrow}

$$(4) \text{rev}^{\#}(x :: xs) \rightarrow c_1(\text{rev}^{\#}(xs))$$

C

$$(4a) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \vdash^{\#} [x]$$

$$(4b) \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}^{\#}(xs)$$

W

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

Q

$$[] \vdash ys \rightarrow ys$$

$$(x :: xs) \vdash ys \rightarrow x :: (xs \vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \vdash [x]$$

Example: Finishing the Proof

$$\begin{array}{c}
 \frac{\vdash \langle (2), C \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : ?}{\vdash \langle \mathcal{S}_{\downarrow}, C \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : ?} \text{ SIMPS} \quad \frac{\vdash \langle (4), \emptyset, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : ?}{\vdash \langle \mathcal{S}_{\uparrow}, \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : ?} \text{ SIMPS} \\
 \hline
 \frac{\vdash \langle \mathcal{S}_{\downarrow}, C \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : ? \quad \vdash \langle \mathcal{S}_{\uparrow}, \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : ?}{\vdash \langle \text{DT}(\mathcal{R}_{\text{rev}}), \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : ?} \text{ DGD} \\
 \hline
 \frac{\vdash \langle \text{DT}(\mathcal{R}_{\text{rev}}), \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : ?}{\vdash \langle \mathcal{R}_{\text{rev}}, \emptyset, \mathcal{R}_{\text{rev}}, \mathcal{B} \rangle : ?} \text{ DT}
 \end{array}$$

$$(2) \ (x :: xs) \# ys \rightarrow c_1(xs \# ys)$$

$$(4) \ \text{rev}^{\#}(x :: xs) \rightarrow c_1(\text{rev}^{\#}(xs))$$

C

$$(4a) \ \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \# [x]$$

$$(4b) \ \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}^{\#}(xs)$$

\mathcal{R}_{rev}

$$[] \# ys \rightarrow ys$$

$$(x :: xs) \# ys \rightarrow x :: (xs \# ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \# [x]$$

Example: Finishing the Proof

$$\begin{array}{c}
 (2) \subseteq >_{\mathcal{A}} \quad \mathcal{R}_{\text{rev}} \subseteq \geq_{\mathcal{A}} \\
 \hline
 \vdash \langle (2), \mathcal{C} \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n \\
 \hline
 \vdash \langle \mathcal{S}_{\downarrow}, \mathcal{C} \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n \\
 \hline
 \vdash \langle \text{DT}(\mathcal{R}_{\text{rev}}), \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B} \rangle : \\
 \hline
 \vdash \langle \mathcal{R}_{\text{rev}}, \emptyset, \mathcal{R}_{\text{rev}}, \mathcal{B} \rangle :
 \end{array}$$

PI

SIMPS

$$(2) \ (x :: xs) \dashv\!\!\!\vdash^{\#} ys \rightarrow c_1(xs \dashv\!\!\!\vdash^{\#} ys)$$

$$(4) \ \text{rev}^{\#}(x :: xs) \rightarrow c_1(\text{rev}^{\#}(xs))$$

C

$$(4a) \ \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \dashv\!\!\!\vdash^{\#} [x]$$

$$(4b) \ \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}^{\#}(xs)$$

\mathcal{R}_{rev}

$$[] \dashv\!\!\!\vdash ys \rightarrow ys$$

$$(x :: xs) \dashv\!\!\!\vdash ys \rightarrow x :: (xs \dashv\!\!\!\vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \dashv\!\!\!\vdash [x]$$

$$[]_{\mathcal{A}} \triangleq 0$$

$$x ::_{\mathcal{A}} xs \triangleq 1 + xs$$

$$\text{rev}_{\mathcal{A}}(xs) \triangleq xs$$

$$xs \dashv\!\!\!\vdash_{\mathcal{A}} ys \triangleq xs + ys$$

$$\text{rev}^{\#}_{\mathcal{A}}(xs) \triangleq xs$$

$$xs \dashv\!\!\!\vdash^{\#}_{\mathcal{A}} ys \triangleq xs$$

$$c_1(t) \triangleq t$$

S

Example: Finishing the Proof

★ $\text{normal}(\text{rev}^\#) \triangleq \{1\}$

★ $\text{rev}^\# > c_1$

★ recursion depth 1

$$\begin{array}{c}
 \text{SIMPS} \quad \frac{\frac{(4) \subseteq >_{\text{spop}^*}}{\vdash \langle (4), \emptyset, \mathcal{R}_{\text{rev}}, \mathcal{B}^\# \rangle : n} \text{SPOP}^*}{\vdash \langle \mathcal{S}_{\uparrow}, \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^\# \rangle : n} \text{SIMPS} \\
 \text{DGD} \quad \frac{\vdash \langle \mathcal{S}_{\uparrow}, \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^\# \rangle : n}{\vdash \langle \text{DT}(\mathcal{R}_{\text{rev}}), \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^\# \rangle : ?} \text{DT} \\
 \frac{\vdash \langle \text{DT}(\mathcal{R}_{\text{rev}}), \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^\# \rangle : ?}{\vdash \langle \mathcal{R}_{\text{rev}}, \emptyset, \mathcal{R}_{\text{rev}}, \mathcal{B} \rangle : ?} \text{DT}
 \end{array}$$

$$(2) \quad (x :: xs) \text{++}^\# ys \rightarrow c_1(xs \text{++}^\# ys)$$

$$(4) \quad \text{rev}^\#(x :: xs) \rightarrow c_1(\text{rev}^\#(xs))$$

\mathcal{C}

$$(4a) \quad \text{rev}^\#(x :: xs) \rightarrow \text{rev}(xs) \text{++}^\# [x]$$

$$(4b) \quad \text{rev}^\#(x :: xs) \rightarrow \text{rev}^\#(xs)$$

\mathcal{R}_{rev}

$$[] \text{++} ys \rightarrow ys$$

$$(x :: xs) \text{++} ys \rightarrow x :: (xs \text{++} ys)$$

$$\text{rev}([]) \rightarrow []$$

$$\text{rev}(x :: xs) \rightarrow \text{rev}(xs) \text{++} [x]$$

Example: Finishing the Proof

$$\begin{array}{c}
 \frac{(2) \subseteq >_{\mathcal{A}} \quad \mathcal{R}_{\text{rev}} \subseteq \geq_{\mathcal{A}}}{\vdash \langle (2), C \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n} \text{PI} \\
 \frac{\vdash \langle (2), C \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n}{\vdash \langle \mathcal{S}_{\downarrow}, C \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n} \text{SIMPS} \\
 \frac{\vdash \langle \mathcal{S}_{\downarrow}, C \cup \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n}{\vdash \langle \text{DT}(\mathcal{R}_{\text{rev}}), \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n^2} \text{DT} \\
 \frac{\vdash \langle \text{DT}(\mathcal{R}_{\text{rev}}), \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n^2}{\vdash \langle \mathcal{R}_{\text{rev}}, \emptyset, \mathcal{R}_{\text{rev}}, \mathcal{B} \rangle : n^2} \text{DT}
 \end{array}
 \quad
 \begin{array}{c}
 \frac{(4) \subseteq >_{\text{spop}^*}}{\vdash \langle (4), \emptyset, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n} \text{SPOP}^* \\
 \frac{\vdash \langle (4), \emptyset, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n}{\vdash \langle \mathcal{S}_{\uparrow}, \mathcal{R}_{\text{rev}}, \mathcal{R}_{\text{rev}}, \mathcal{B}^{\#} \rangle : n} \text{SIMPS} \\
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 \end{array}$$

$$(2) \ (x :: xs) \dashv\!\!\!\vdash^{\#} ys \rightarrow c_1(xs \dashv\!\!\!\vdash^{\#} ys)$$

$$(4) \ \text{rev}^{\#}(x :: xs) \rightarrow c_1(\text{rev}^{\#}(xs))$$

\mathcal{C}

$$(4a) \ \text{rev}^{\#}(x :: xs) \rightarrow \text{rev}(xs) \dashv\!\!\!\vdash^{\#} [x]$$

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$$[] \dashv\!\!\!\vdash ys \rightarrow ys$$

$$(x :: xs) \dashv\!\!\!\vdash ys \rightarrow x :: (xs \dashv\!\!\!\vdash ys)$$

$$\text{rev}([]) \rightarrow []$$

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Implementation notes

- ★ implementing complexity pairs

Complexity Pairs in TCT

- ★ polynomial, matrix, arctic interpretations and (small) polynomial path orders (modulo argument filtering) implemented in TCT

Complexity Pairs in TCT

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- ★ RD-processor, CP-processor and UR-processor combined in one

$$\frac{\mathcal{U}_{\mathcal{P},>}(\mathcal{S}_1) \subseteq > \quad \mathcal{U}_{\mathcal{P},>}(\mathcal{S}_2 \cup \mathcal{W}) \subseteq \gtrsim}{\vdash \langle \mathcal{S}_2, \mathcal{S}_1 \cup \mathcal{W}, \mathcal{Q}, \mathcal{T} \rangle : g} \\ \vdash \langle \mathcal{S}_1 \cup \mathcal{S}_2, \mathcal{W}, \mathcal{Q}, \mathcal{T} \rangle : \text{dc}_{>,\mathcal{T}} + g$$

- usable rules $\mathcal{U}_{\mathcal{P},>}$ take problem \mathcal{P} and order $>$ into account
- “function usable” only if occurs in right-hand-side “inspected by” ($>$, \gtrsim)
- specific definition depends on kind of order

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- usable rules $\mathcal{U}_{\mathcal{P},>}$ take problem \mathcal{P} and order $>$ into account
 - “function usable” only if occurs in right-hand-side “inspected by” ($>$, \gtrsim)
 - specific definition depends on kind of order
- ★ search via encoding to SAT modulo theories (SMT)

Example: Synthesis PI

★ fix **abstract** shape of interpretations...

$$f_{\mathcal{A}}(x) = c_f^x \cdot x + c_f \quad g_{\mathcal{A}}(x, y) = c_g^{xy} \cdot x \cdot y + c_g^x \cdot x + c_g^y \cdot y + c_g$$

...and lift algebraic operations and interpretation of terms:

$$\llbracket f(g(x, y)) \rrbracket = c_f^x \cdot c_g^{xy} \cdot x \cdot y + c_f^x \cdot c_g^x \cdot x + c_f^x \cdot c_g^y \cdot y + c_f^x \cdot c_g + c_f$$

$$\llbracket f(g(x, y)) \rrbracket - \llbracket f(x) \rrbracket = c_f^x \cdot c_g^{xy} \cdot x \cdot y + c_f^x \cdot (c_g^x - 1) \cdot x + c_f^x \cdot c_g^y \cdot y + c_f^x \cdot c_g$$

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- ★ (weak) **orientation** of rule $f(l_1, \dots, l_k) \rightarrow r$ expressible as

$$f(l_1, \dots, l_k) \bowtie_{\mathcal{A}} r \triangleq \llbracket f(l_1, \dots, l_k) \rrbracket_{\mathcal{A}} - \llbracket r \rrbracket_{\mathcal{A}} \bowtie 0$$

where $(\bowtie \in \{>_{\mathbb{N}}, \geq_{\mathbb{N}}\})$

- approximated via **absolute positiveness condition** on coefficients

$$\begin{aligned} \llbracket f(g(x, y)) \rrbracket >_{\mathcal{A}} \llbracket f(x) \rrbracket &= c_f^x \cdot c_g^{xy} \geq_{\mathbb{N}} 0 \wedge c_f^x \cdot (c_g^x - 1) \geq_{\mathbb{N}} 0 \wedge c_f^x \cdot c_g^y \geq_{\mathbb{N}} 0 \\ &\wedge c_f^x \cdot c_g \geq_{\mathbb{N}} 1 \end{aligned}$$

Example: Synthesis PI (II)

★ μ -monotonicity of $f_{\mathcal{A}}$ encoded via

$$\text{mono}(f_{\mathcal{A}}, \mu) \triangleq \bigwedge_{\bar{c}_{\mathbf{f}}^{\bar{x}} \in \text{coeff}(\mathbf{f})} \bar{c}_{\mathbf{f}}^{\bar{x}} \geq_{\mathbb{N}} 0 \wedge \bigwedge_{i \in \mu(\mathbf{f})} \bar{c}_{\mathbf{f}}^{x_i} \geq_{\mathbb{N}} 1$$

where $f_{\mathcal{A}}(x_1, \dots, x_k) = \sum_{\bar{x} \subseteq \{x_1, \dots, x_k\}} \bar{c}_{\mathbf{f}}^{\bar{x}} \cdot \bar{x}$

Example: Synthesis PI (II)

★ μ -monotonicity of $\mathbf{f}_{\mathcal{A}}$ encoded via

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★ usable rules of \mathcal{R} wrt. start terms \mathcal{T} encoded with atoms $\mathbf{u}_{l \rightarrow r}$ via

$$\text{URs}(\mathcal{R}, \mathcal{T}) \triangleq \bigwedge_{\substack{l \rightarrow r \in \mathcal{R} \\ \text{rt}(l) \in \text{Fun}(\mathcal{T})}} \mathbf{u}_{l \rightarrow r} \wedge \bigwedge_{l \rightarrow r \in \mathcal{R}} (\mathbf{u}_{l \rightarrow r} \rightarrow \phi(r))$$

where

$$\phi(x) \triangleq \top$$

$$\phi(\mathbf{f}(t_1, \dots, t_k)) \triangleq \bigwedge_{l \rightarrow r \in \mathcal{R}, \text{rt}(l) = \mathbf{f}} \mathbf{u}_{l \rightarrow r} \wedge \bigwedge_{1 \leq i \leq k} (\pi(\mathbf{f}, i) \rightarrow \phi(t_i)) \quad \pi(\mathbf{f}, i) \triangleq \bigvee_{\substack{\mathbf{c}_{\mathbf{f}}^{\bar{x}} \geq_{\mathbb{N}} 1 \\ \mathbf{c}_{\mathbf{f}}^{\bar{x}} \in \text{coeff}(\mathbf{f}), x_i \in \bar{x}}} \mathbf{c}_{\mathbf{f}}^{\bar{x}}$$

Example: Synthesis PI (III)

★ weak orientation of TRS \mathcal{R} via

$$\text{orient}(\mathcal{R}) \triangleq \bigwedge_{l \rightarrow r \in \mathcal{R}} u_{l \rightarrow r} \rightarrow \llbracket l \rrbracket_{\mathcal{A}} - \llbracket r \rrbracket_{\mathcal{A}} \geq_{\mathbb{N}} m_{l \rightarrow r}$$

with fresh integer variables $m_{l \rightarrow r} \geq 0$ for each $l \rightarrow r \in \mathcal{R}$

Example: Synthesis PI (III)

- ★ weak orientation of TRS \mathcal{R} via

$$\text{orient}(\mathcal{R}) \triangleq \bigwedge_{l \rightarrow r \in \mathcal{R}} u_{l \rightarrow r} \rightarrow \llbracket l \rrbracket_{\mathcal{A}} - \llbracket r \rrbracket_{\mathcal{A}} \geq_{\mathbb{N}} m_{l \rightarrow r}$$

with fresh integer variables $m_{l \rightarrow r} \geq 0$ for each $l \rightarrow r \in \mathcal{R}$

- ★ extended RP processor for $\langle \mathcal{S}, \mathcal{W}, \mathcal{Q}, \mathcal{T} \rangle$ implementable as

$$\bigwedge_{f \in \mathcal{F}} \text{mono}(f_{\mathcal{A}}, \mu \cup \nu) \wedge \text{URs}(\mathcal{S} \cup \mathcal{W}, \mathcal{T}) \wedge \text{orient}(\mathcal{S} \cup \mathcal{W}) \wedge \Phi$$

- formula Φ enforces which rules in $\mathcal{R} \subseteq \mathcal{S}$ should be oriented strictly, e.g.,

$$\Phi \triangleq \bigwedge_{l \rightarrow r \in \mathcal{S}} m_{l \rightarrow r} \geq_{\mathbb{N}} 1 \quad \text{or} \quad \Phi \triangleq \bigvee_{l \rightarrow r \in \mathcal{S}} m_{l \rightarrow r} \geq_{\mathbb{N}} 1$$

- open sub-problem: $\langle \mathcal{S} \setminus \mathcal{R}, \mathcal{W} \cup \mathcal{R}, \mathcal{Q}, \mathcal{T} \rangle$ where \mathcal{R} determined from assignment of variables $m_{l \rightarrow r}$

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Summary

- ★ TCT build on top of a modular framework for complexity analysis
- ★ decomposition techniques such as DG decomposition key to strength of analysis
- ★ ultimately, analysis boils down to synthesising a “ranking function” (reduction orders) via SMT
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Summary

- ★ TcT build on top of a modular framework for complexity analysis
- ★ decomposition techniques such as DG decomposition key to strength of analysis
- ★ ultimately, analysis boils down to synthesising a “ranking function” (reduction orders) via SMT
- ★ currently, tools give asymptotic bounds, but more precise bounds could be extracted
- ★ automated tools can treat non-trivial examples, fully automatically
- ★ proofs requiring semantic arguments are beyond reach for fully automated analysis

Applications to Program Analysis

- ★ Case study: higher-order functional programs

Motivation

```
1 let (o) f g = fun z → f (g z) ;;
2 let rec walk = function
3   | [] → id
4   | x::xs → walk xs o (fun ys → x::ys) ;;
5 let rev l = walk l [] ;;
```


Goal: Runtime Complexity Analysis of Higher-Order Programs

Main Challenge: applied functions not statically known

Direct Approaches: Rewriting Techniques

★ Higher-Order Polynomial Interpretations



$$\llbracket \text{map} \rrbracket = \lambda \phi. \lambda n. n \times (\phi \ n) : (\mathbb{N} \rightarrow \mathbb{N}) \rightarrow \mathbb{N} \rightarrow \mathbb{N}$$

-  P. Baillot and U. Dal Lago. “Higher-Order Interpretations and Program Complexity”. In *Proc. of 26th CSL*, pp. 62–76, 2012.

Direct Approaches: Type Systems


★ Amortized Resource Analysis

$$\Gamma \vdash^k \text{map} : (\mathbb{N}^p \xrightarrow{1} \mathbb{N}^q) \xrightarrow{0} \mathbb{L}^s \xrightarrow{c} \mathbb{L}^t$$

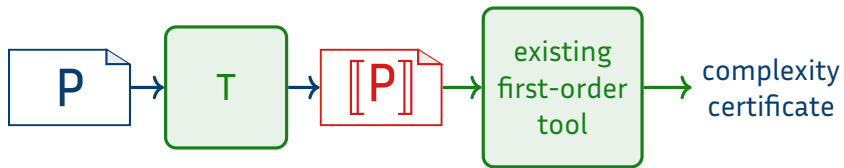
-  S. Jost et al. "Static Determination of Quantitative Resource Usage for Higher-order Programs". In *Proc. of 37th POPL*, pp. 223–236, 2010.
-  J. Hoffmann, A. Das, and S-C. Weng. "Towards Automatic Resource Bound Analysis for OCaml". In *Proc. of 44th POPL*, pp. 359–373, 2017.

★ Sized types and instrumentation with clock

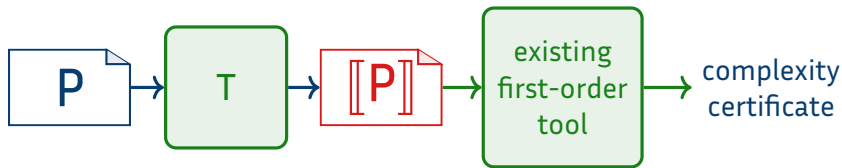
$$\Gamma \vdash \text{map} : \forall l k. (\forall i. \mathbb{N}_i \xrightarrow{f(i)} \mathbb{N}_{g(i)}) \xrightarrow{0} \mathbb{L}_l(\mathbb{N}_k) \xrightarrow{(f(k)+1) \cdot l} \mathbb{L}_g(\mathbb{N}_{f(k)})$$

-  M. Avanzini and U. Dal Lago. "Automating Sized-Type Inference for Complexity Analysis". In *Proc. of 22nd ICFP*, 2017.

Program Transformations for Complexity Analysis



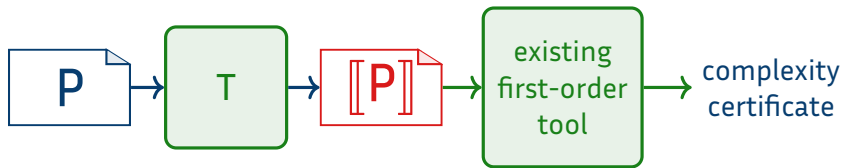
Program Transformations for Complexity Analysis



Constraints on Transformation T :

1. certificate can be relayed back to input program P
 - complexity reflecting: runtime of $P \leq$ runtime of $T(P)$
 - ideally, complexity preserving: runtime of $T(P) \leq$ runtime of P

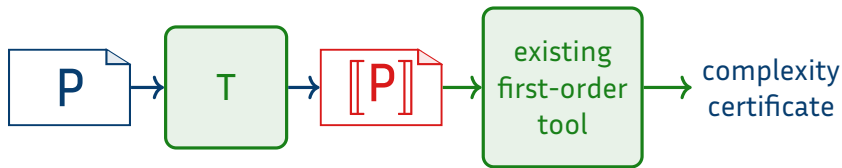
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2. transformed program $[[P]]$ suitable for analysis by existing tools

Program Transformations for Complexity Analysis



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 - complexity reflecting: runtime of $P \leq$ runtime of $T(P)$
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Natural Candidate: Reynold's defunctionalization

From Programs to Rewrite Systems

Input:

★ “PCF + constructors”

$$M, N ::= x \mid M N \mid \lambda x. M \mid \text{fix}(x. M) \mid C(M_1, \dots, M_k) \\ \mid \text{match } M \text{ with } \{C_1(\vec{x}_1) \mapsto M_1 \mid \dots \mid C_n(\vec{x}_n) \mapsto M_n\}$$

★ usual call-by-value reduction semantics

Output: applicative term rewrite system (ATRS)

From Programs to Rewrite Systems

Definition (defunctionalization to ATRS)

- ★ $\langle x \rangle \triangleq x$
- ★ $\langle M N \rangle \triangleq \langle M \rangle @ \langle N \rangle$
- ★ $\langle C(M_1, \dots, M_k) \rangle \triangleq C(\langle M_1 \rangle, \dots, \langle M_k \rangle)$
- ★ $\langle \lambda x. M \rangle \triangleq \text{Lam}_{x.M}(\vec{y})$ where $\vec{y} = \text{FVar}(\lambda x. M)$
 $\text{Lam}_{x.M}(\vec{y}) @ x \rightarrow \langle M \rangle$



U. Dal Lago and S. Martini. "On Constructor Rewrite Systems and the Lambda-Calculus". In *Proc. of 36th ICALP*, pp. 163–174, 2009.

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 $\text{Lam}_{x.M}(\vec{y}) @ x \rightarrow \langle M \rangle$
- ★ $\langle \text{fix}(x.M) \rangle \triangleq \text{Fix}_{x.M}(\vec{y})$ where $\vec{y} = \text{FVar}(\text{fix}(x.M))$
 $\text{Fix}_{x.M}(\vec{y}) @ z \rightarrow \langle M \rangle \{ \text{Fix}_{x.M}(\vec{y}) / x \} @ z$

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- ★ $\langle \lambda x. M \rangle \triangleq \text{Lam}_{x.M}(\vec{y})$ where $\vec{y} = \text{FVar}(\lambda x. M)$
 $\text{Lam}_{x.M}(\vec{y}) @ x \rightarrow \langle M \rangle$
- ★ $\langle \text{fix}(x. M) \rangle \triangleq \text{Fix}_{x.M}(\vec{y})$ where $\vec{y} = \text{FVar}(\text{fix}(x. M))$
 $\text{Fix}_{x.M}(\vec{y}) @ z \rightarrow \langle M \rangle \{ \text{Fix}_{x.M}(\vec{y}) / x \} @ z$
- ★ $\langle \text{match } M \text{ with } cs \rangle = \text{Match}_{cs}(\vec{y}) @ \langle M \rangle$ where $\vec{y} = \text{FVar}(cs)$
 $\text{Match}_{cs}(\vec{y}) @ C_i(\vec{x}_i) \rightarrow \langle M_i \rangle \quad (1 \leq i \leq n, cs = \{ \dots \mid C_i(\vec{x}_i) \mapsto M_i \mid \dots \})$

From Programs to Rewrite Systems (II)

Theorem

Let \mathcal{A}_{PCF} collect all rules defined synchronous to $\langle \cdot \rangle$.

1. \mathcal{A}_{PCF} implements PCF in a step-by-step manner (call-by-value)
2. on first-order inputs, finite restriction $\mathcal{A}_P \subseteq \mathcal{A}_{PCF}$ sufficient to implement $P = \lambda \vec{x}. M$.

```

1 let (o) f g = fun z → f (g z) ;;
2 let rec walk = function
3   | [] → id
4   | x::xs → walk xs o (fun ys → x::ys) ;;
5 let rev l = walk l [] ;;

```

⇓ **desugar + defunctionalize**

- | | |
|--|--|
| (1) $\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$ | (6) $(o) @ f \rightarrow (o)_1(f)$ |
| (2) $\text{Fix}_w @ l \rightarrow \text{Lam}_1 @ l$ | (7) $(o)_1(f) @ g \rightarrow \text{Lam}_3(f, g)$ |
| (3) $\text{Lam}_1 @ l \rightarrow \text{Match}_w @ l$ | (8) $\text{Lam}_3(f, g) @ z \rightarrow f @ (g @ z)$ |
| (4) $\text{Match}_w @ [] \rightarrow \text{Id}$ | (9) $\text{Id} @ ys \rightarrow ys$ |
| (5) $\text{Match}_w @ (x::xs) \rightarrow (o) @ (\text{Fix}_w @ xs) @ \text{Lam}_2(x)$ | (10) $\text{Lam}_2(x) @ ys \rightarrow x::ys$ |

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in suitable format for analysis by first-order tools

Experimental Evaluation

- ★ **Implementation:** <http://cbr.uibk.ac.at/tools/hoca/>
- ★ **FOP:** T_{CTV2} for complexity, T_{TT2} for termination (SN)
- ★ **Testbed:** 25 higher-order functions from literature on FP
 - higher-order sorting functions, list & tree traversals (maps, folds, ...), Okasaki's parser combinators, ...

		constant	linear	quadratic	poly	SN
RaML	# systems	2	4	8	—	—
	avg. ET (secs)	2.79	0.32	1.55	—	—
Defunctionalize	# systems	2	5	5	5	8
	FOP avg. ET (secs)	1.71	4.82	4.82	4.82	1.38

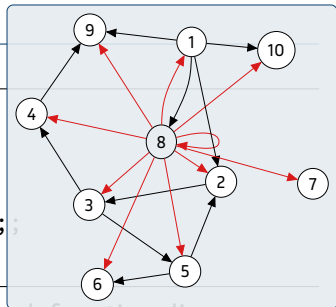
Table: Experimental evaluation on 25 higher-order examples. **Defunctionalize:** Amortized, type-based analysis with RaML prototype (<http://raml.co/>).
Simplify: FOP on defunctionalized ATRS.

ATRS \mathcal{A}_{rev}

```

1 let (o) f g = fun z → f (g z) ;;
2 let rec walk = function
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↓ desugar + defunctionalize

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★ recursive structure of translated ATRSs apparently too complicated

1. defines one global function $@$
2. computation entirely driving by data

Governing the Chaos

program transformations can remedy the situations

1. inlining

- remove unnecessary indirections introduced by rigid transformation

2. dead code elimination

- eliminate inlined functions

3. instantiation

- specialize “higher-order variables” via control/data flow analysis

4. uncurrying

- effectively replaces global apply function with specialized ones

Inlining & Dead Code Elimination

- ★ **inlining** is optimization that replaces function calls by bodies
- ★ **dead code elimination** removes non-reachable code

(2) $\text{Fix}_w @ l \rightarrow \text{Lam}_1 @ l$

(3) $\text{Lam}_1 @ l \rightarrow \text{Match}_w @ l$

(4) $\text{Match}_w @ [] \rightarrow \text{Id}$

(5) $\text{Match}_w @ (x :: xs) \rightarrow (\circ) @ (\text{Fix}_w @ xs) @ \text{Lam}_2(x)$

⇓ inline Lam_1

(2) $\text{Fix}_w @ l \rightarrow \text{Match}_w @ l$

(4) $\text{Match}_w @ [] \rightarrow \text{Id}$

(5) $\text{Match}_w @ (x :: xs) \rightarrow (\circ) @ (\text{Fix}_w @ xs) @ \text{Lam}_2(x)$

⇓ inline Match_w

(2a) $\text{Fix}_w @ [] \rightarrow \text{Id}$

(2b) $\text{Fix}_w @ (x :: xs) \rightarrow (\circ) @ (\text{Fix}_w @ xs) @ \text{Lam}_2(x)$

Inlining

Definition (inlining + narrowing)

replaces a rule $l \rightarrow C[f(t_1, \dots, t_k)] \in \mathcal{A}$ by

$$\{(l \rightarrow C[r])_{\mu} \mid \exists f(l_1, \dots, l_k) \rightarrow r \in \mathcal{A}, f(t_1, \dots, t_k) \approx_{\mu} f(l_1, \dots, l_k)\}.$$

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Traps

1. mixes evaluation-order
2. not cost-neutral in general, even asymptotically
 - inline $f(n) \rightarrow 0$ in $g(m) \rightarrow f(g(m))$
3. narrowing cause subtle issue when inlined function partially defined
 - inline $f(n, 0) \rightarrow n$ in $g(S(m)) \rightarrow f(g(m), m)$

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Theorem

For non-ambiguous \mathcal{A} , redex-preserving inlining of sufficiently defined function f is asymptotic complexity-reflecting.

Overall...

- | | |
|--|---|
| (1) $\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$ | (6) $(\circ) @ f \rightarrow (\circ)_1(f)$ |
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★ runtime of **Rev** coincide, up to constant speed-up

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- ★ runtime of **Rev** coincide, up to constant speed-up
- ★ **Implementation Trap**: inlining blows up program size/diverge
 - inline conservatively (calls to Lam_* , Match_* , and constants)

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- ★ runtime of **Rev** coincide, up to constant speed-up
- ★ **Implementation Trap**: inlining blows up program size/diverge
 - inline conservatively (calls to Lam_* , Match_* , and constants)
- ★ **troublesome rule (8) still present**

Instantiation of Higher-Order Variables

$$(1) \quad \text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$$

$$(2a) \quad \text{Fix}_w @ [] \rightarrow \text{Id}$$

$$(2b) \quad \text{Fix}_w @ (x :: xs) \rightarrow \text{Lam}_3(\text{Fix}_w @ xs, \text{Lam}_2(x))$$

$$(8) \quad \text{Lam}_3(f, g) @ z \rightarrow f @ (g @ z)$$

$$(9) \quad \text{Id} @ ys \rightarrow ys$$

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Central Observation:


- ★ seen in isolation, variables f and g can be instantiated arbitrarily
- ★ not so when considering only calls to Rev


Instantiation of Higher-Order Variables

(1) $\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$	(8) $\text{Lam}_3(f, g) @ z \rightarrow f @ (g @ z)$
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Central Observation:

- ★ seen in isolation, variables f and g can be instantiated arbitrarily
- ★ not so when considering only calls to Rev
- ★ determining precise set of instances undecidable
- ★ but can be efficiently approximated, e.g., with tree automata techniques

 N. D. Jones. "Flow Analysis of Lazy Higher-order Functional Programs". *TCS*, Vol. 375, pp. 120–136, 2007.

 J. Kochems and L. Ong. "Improved Functional Flow and Reachability Analyses Using Indexed Linear Tree Grammars". In *Proc. of 22nd RTA*, pp. 187–202, 2011.

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$S \rightarrow \text{Rev} @ \star$	$\star \rightarrow [] \mid \star::\star$
(1) $R_1 \rightarrow R_8 \mid R_9$	$L_1 \rightarrow \star$
(2a) $R_{2a} \rightarrow \text{Id}$	
(2b) $R_{2b} \rightarrow \text{Lam}_3(R_{2a}, \text{Lam}_2(X_{2b}))$ $\mid \text{Lam}_3(R_{2b}, \text{Lam}_2(X_{2b}))$	$X_{2b} \rightarrow \star$ $XS_{2b} \rightarrow \star$
(8) $R_8 \rightarrow R_8 \mid R_{10}$	$F_8 \rightarrow R_{2a} \mid R_{2b}$ $G_8 \rightarrow \text{Lam}_2(X_{2b})$ $Z_8 \rightarrow [] \mid R_{10}$
(9) $R_9 \rightarrow [] \mid X_{10} \mid YS_{10}$	$YS_9 \rightarrow [] \mid R_{10}$
(10) $R_{10} \rightarrow [] \mid X_{10} \mid YS_{10}$	$X_{10} \rightarrow X_{2b}$ $YS_{10} \rightarrow [] \mid R_{10}$

Tree automaton over-approximating collecting semantics.

Instantiation of Higher-Order Variables

(1) $\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$	(8) $\text{Lam}_3(f, g) @ z \rightarrow f @ (g @ z)$
(2a) $\text{Fix}_w @ [] \rightarrow \text{Id}$	(9) $\text{Id} @ ys \rightarrow ys$
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$S \rightarrow \text{Rev} @ \star$	$\star \rightarrow [] \mid \star::\star$
(1) $R_1 \rightarrow R_8 \mid R_9$	$L_1 \rightarrow \star$
(2a) $R_{2a} \rightarrow \text{Id}$	
(2b) $R_{2b} \rightarrow \text{Lam}_3(R_{2a}, \text{Lam}_2(X_{2b}))$	$X_{2b} \rightarrow \star$
$\mid \text{Lam}_3(R_{2b}, \text{Lam}_2(X_{2b}))$	$XS_{2b} \rightarrow \star$
(8) $R_8 \rightarrow R_8 \mid R_{10}$	$F_8 \rightarrow R_{2a} \mid R_{2b}$
(9) $R_9 \rightarrow [] \mid X_{10} \mid YS_{10}$	$G_8 \rightarrow \text{Lam}_2(X_{2b})$
(10) $R_{10} \rightarrow [] \mid X_{10} \mid YS_{10}$	$Z_8 \rightarrow [] \mid R_{10}$
	$YS_9 \rightarrow [] \mid R_{10}$
	$X_{10} \rightarrow X_{2b}$
	$YS_{10} \rightarrow [] \mid R_{10}$

Tree automaton over-approximating collecting semantics.

$$f \mapsto \text{Id} \mid \text{Lam}_3(f, g)$$

$$g \mapsto \text{Lam}_2(x)$$

Variable bindings extracted from tree automaton.

Instantiation of Higher-Order Variables (II)

(1) $\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$	(8) $\text{Lam}_3(f, g) @ z \rightarrow f @ (g @ z)$
(2a) $\text{Fix}_w @ [] \rightarrow \text{Id}$	(9) $\text{Id} @ ys \rightarrow ys$
(2b) $\text{Fix}_w @ (x::xs) \rightarrow \text{Lam}_3(\text{Fix}_w @ xs, \text{Lam}_2(x))$	(10) $\text{Lam}_2(x) @ ys \rightarrow x::ys$

+

$$f \mapsto \text{Id} \mid \text{Lam}_3(f, g)$$

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↓ instantiate (8)

(1)	$\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$
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(8a)	$\text{Lam}_3(\text{Id}, \text{Lam}_2(x)) @ z \rightarrow \text{Id} @ (\text{Lam}_2(x) @ z)$
(8b)	$\text{Lam}_3(\text{Lam}_3(f, g), \text{Lam}_2(x)) @ z \rightarrow \text{Lam}_3(f, g) @ (\text{Lam}_2(x) @ z)$
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Instantiation of Higher-Order Variables (II)

(1) $\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$	(8) $\text{Lam}_3(f, g) @ z \rightarrow f @ (g @ z)$
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+

$$f \mapsto \text{Id} \mid \text{Lam}_3(f, g)$$

$$g \mapsto \text{Lam}_2(x)$$

↓ instantiate (8), simplify

(1)	$\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$
(2a)	$\text{Fix}_w @ [] \rightarrow \text{Id}$
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(9)	$\text{Id} @ ys \rightarrow ys$

★ resulting ATRS **head-variable** free; applied functions statically known

Uncurrying

$$C(\vec{s}) @ t_1 @ \dots @ t_n \implies C_n(\vec{s}, t_1, \dots, t_n)$$

Uncurrying

$$C(\vec{s}) @ t_1 @ \dots @ t_n \quad \Rightarrow \quad C_n(\vec{s}, t_1, \dots, t_n)$$

(1) $\text{Rev} @ l \rightarrow \text{Fix}_w @ l @ []$
(2a) $\text{Fix}_w @ [] \rightarrow \text{Id}$
(2b) $\text{Fix}_w @ (x :: xs) \rightarrow \text{Lam}_3(\dots)$
 \vdots

\Rightarrow

(1) $\text{Rev}_1(l) \rightarrow \text{Fix}_w^2(l, [])$
(2a) $\text{Fix}_w^1([]) \rightarrow \text{Id}$
(2b) $\text{Fix}_w^1(x :: xs) \rightarrow \text{Lam}_3(\dots)$
 \vdots

Uncurrying

$$C(\vec{s}) @ t_1 @ \dots @ t_n \Rightarrow C_n(\vec{s}, t_1, \dots, t_n)$$

$$\begin{array}{l} (1) \quad \text{Rev} @ l \rightarrow \text{Fix}_w @ l @ [] \\ (2a) \quad \text{Fix}_w @ [] \rightarrow \text{Id} \\ (2b) \quad \text{Fix}_w @ (x :: xs) \rightarrow \text{Lam}_3(\dots) \\ \quad \quad \quad \vdots \end{array}$$

+ η -saturate

$$\begin{array}{l} (2a') \quad \text{Fix}_w @ [] @ z \rightarrow \text{Id} @ z \\ (2b') \quad \text{Fix}_w @ (x :: xs) @ z \rightarrow \text{Lam}_3(\dots) @ z \end{array}$$

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N. Hirokawa, A. Middeldorp, and H. Zankl. "Uncurrying for Termination". In *Proc. of 15th LPAR*, 2008.

Uncurrying (II)

Definition (η -saturation)

- ★ application arity $aa(\mathbf{C})$ is maximal number of arguments applied to \mathbf{C}
- ★ ATRS \mathcal{A} is η -saturated if

$$\mathbf{C}(\vec{s}) @ t_1 @ \dots @ t_n \rightarrow r \in \mathcal{A} \implies \mathbf{C}(\vec{s}) @ t_1 @ \dots @ t_n @ \mathbf{z} \rightarrow r @ \mathbf{z} \in \mathcal{A}$$

whenever $n < aa(\mathbf{C})$, with \mathbf{z} fresh variable

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Theorem (η -Saturation & Uncurrying)

1. η -saturation finite if \mathcal{A} “well-typed”
2. η -saturation is complexity preserving & reflecting
3. uncurrying head-variable free, η -saturated ATRS is complexity preserving & reflecting

Uncurry (III)

$$(1) \quad \text{Rev}_1(l) \rightarrow \text{Fix}_w^2(l, [])$$

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$$(8b) \quad \text{Lam}_3^1(\text{Lam}_3(f, g), \text{Lam}_2(x), z) \rightarrow \text{Lam}_3^1(f, g, \text{Lam}_2^1(x, z))$$

$$(9) \quad \text{Id}_1(ys) \rightarrow ys$$

↓ simplify & rename

$$(1a) \quad \text{rev}([]) \rightarrow []$$

$$(1b) \quad \text{rev}(x :: xs) \rightarrow \text{eval}(\text{walk}(xs), \text{Cons}(x), [])$$

$$(2a) \quad \text{walk}([]) \rightarrow \text{Id}$$

$$(2b) \quad \text{walk}(x :: xs) \rightarrow \text{Comp}(\text{walk}(xs), \text{Cons}(x))$$

$$(8a) \quad \text{eval}(\text{Id}, \text{Cons}(x), z) \rightarrow x :: z$$

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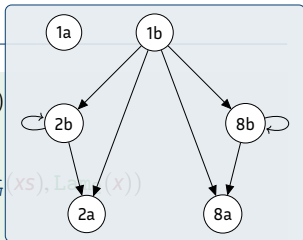
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Tyrolean Complexity Tool

Web Interface



CBR Home TcT Home Download Experiments **TCT Web**

Input (in *xml* or *trs* format)

select example ...

or upload file

Browse...

No file selected.

```
1 (VAR x xs z f g)
2
3 (RULES
4   rev([]) -> []
5   rev(::(x,xs)) -> build(walk(xs),Cons(x),[])
6   walk([]) -> Id
7   walk(::(x,xs)) -> Comp(walk(xs),Cons(x))
8   build(Id,Cons(x),z) -> ::(x,z)
9   build(Comp(f,g),Cons(x),z) -> build(f,g,::(x,z))
10 )
```

Category

Complexity Measure:



Runtime Complexity



Derivational Complexity

Rewriting Strategy:



Full Rewriting



Innermost Rewriting

Search Strategy



Automatic



Certify



Customised by user

check

with timeout of

30

seconds.

WORST_CASE(? , 0(n^1))

Applied Processor: Bounds {initialAutomaton = minimal, enrichment = match}

Proof:

The problem is match-bounded by 2.

The enriched problem is compatible with following automaton.

:: 0(2,2) -> 2

:: 1(2,1) -> 1

:: 1(2,2) -> 1

:: 1(2,2) -> 3

Experimental Evaluation

- ★ **Implementation:** <http://cbr.uibk.ac.at/tools/hoca/>
- ★ **FOP:** T_{CTV2} for complexity, T_{TT2} for termination (SN)
- ★ **Testbed:** 25 higher-order functions from literature on FP
 - higher-order sorting functions, list & tree traversals (maps, folds, ...), Okasaki's parser combinators, ...

		constant	linear	quadratic	poly	SN
RaML	# systems	2	4	8	—	—
	avg. ET (secs)	2.79	0.32	1.55	—	—
Defunctionalize	# systems	2	5	5	5	8
	FOP avg. ET (secs)	1.71	4.82	4.82	4.82	1.38
Simplify	# systems	2	14	18	20	25
	HoCA avg. ET (secs)	2.28	0.54	0.43	0.42	0.87
	FOP avg. ET (secs)	0.51	2.53	6.30	10.94	1.43

Table: Experimental evaluation on 25 higher-order examples. **Defunctionalize:** Amortized, type-based analysis with RaML prototype (<http://raml.co/>).

Simplify: FOP on defunctionalized ATRS. **RaML:** FOP on defunctionalized &

Some Relevant Cases

- ★ standard examples from literature on functional programming
 - the presented `reverse` function
 - `insert sort` defined by `fold`; comparison passed as argument
 - `DFS tree flattening` via difference lists
 - `maximum sequence sum` defined via `scanr`
 - ...
- ⇒ optimal asymptotic bound could be inferred for all examples

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- `maximum sequence sum` defined via `scanr`
- ...

⇒ optimal asymptotic bound could be inferred for all examples

★ examples where we can only show termination

- `merge sort`
 - instantiation of higher-order divide and conquer combinator [Bird'89]
- `Okasaki's parsing combinators` [Okasaki'98]
 - combinators reach `order 7`
- `lazy/memoized` computation of Fibonacci numbers

Conclusion

higher-order functional programs can be effectively analysed
with first order tools

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Pros:

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 - nowadays, no problem even for compilers (e.g., MLton)
 - modularity within the back-end
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- ★ same applies to other approaches (e.g. for JBC or Prolog)

Thank You!

★ HoCA

<http://cbr.uibk.ac.at/tools/hoca>

★ TcT

<http://cl-informatik.uibk.ac.at/software/tct>