

# **AN INTRODUCTION TO REASONING WITH EXISTENTIAL RULES**

DAVID CARRAL

LIRMM, INRIA, UNIVERSITY OF MONTPELLIER, CNRS

NOVEMBER 17, 2021

# ABOUT TO THE SEMINAR

# PROGRAM

1. Morning Session from 9:30 to 12:00 (more general/introductory):
  - ▶ “Introduction to  $\exists$ -Rules” by D. Carral
  - ▶ “Reasoning with Guarded  $\exists$ -Rules” by M. Thomazo
  - ▶ [Coffee Break \(outside of the seminar room\)](#)
  - ▶ “Compressing Rule-based Reasoning” by J. Urbani
2. [Lunch Break from 12:00 to 13:30 in Building 5 \(did you register?\)](#)
3. Afternoon Session from 13:30 to 17:00 (more specific/technical):
  - ▶ “Capturing Homomorphism-Closed Decidable Queries with  $\exists$ -Rules” by S. Rudolph (winner of the Ray Reiter Best Paper Prize 2021)
  - ▶ “Answering Counting Queries over Lightweight Ontologies” by M. Thomazo
  - ▶ [Coffee Break \(outside of the seminar room\)](#)
  - ▶ “Derivation Graphs, Greediness, and Bounded-treewidth in the Context of  $\exists$ Rules” by T. Lyon
  - ▶ “ $\exists$ -rules: Intersecting FO-Rewritability and Core Termination” by P. Ostropolski-Nalewaja

# PROGRAM

1. Morning Session from 9:30 to 12:00
2. Lunch Break from 12:00 to 13:30
3. Afternoon Session from 13:30 to 17:00

# PROGRAM

1. Morning Session from 9:30 to 12:00
2. Lunch Break from 12:00 to 13:30
3. Afternoon Session from 13:30 to 17:00

## Remark

Complete schedule available at:

<https://www-sop.inria.fr/members/David.Carral/events/2021-montpellier-existential-rules-seminar.html>

I will also upload the slides by the end of the week!

Google “David Carral Sophia Inria” to find my personal webpage, then look under the “Events” tab.

# ACKNOWLEDGEMENTS

**Organisators:** Virginie Fèche, Mégane Miquel, and Christian Retoré

# ACKNOWLEDGEMENTS

**Organisators:** Virginie Fèche, Mégane Miquel, and Christian Retoré  
(also, Marie-Laure Mugnier and Federico Ulliana)

# ACKNOWLEDGEMENTS

**Organisators:** Virginie Fèche, Mégane Miquel, and Christian Retoré  
(also, Marie-Laure Mugnier and Federico Ulliana)

**Speakers:** Timothy Stephen Lyon, Piotr Ostropolski-Nalewaja,  
Sebastian Rudolph, Michaël Thomazo x 2, and Jacopo Urbani



# ACKNOWLEDGEMENTS

**Organisators:** Virginie Fèche, Mégane Miquel, and Christian Retoré (also, Marie-Laure Mugnier and Federico Ulliana)

**Speakers:** Timothy Stephen Lyon, Piotr Ostropolski-Nalewaja, Sebastian Rudolph, Michaël Thomazo x 2, and Jacopo Urbani

**Funding provided by:**

- The LIRMM through the “Action Transverse Logique”
- The GraphIK team
- The Chair of Computational Logic at TU Dresden (that is, Sebastian’s research group)

# INTRO TO EXISTENTIAL RULES

# GOALS OF THIS PRESENTATION

What this talk is about:

- General intro to  $\exists$ -rules
- Provide context for the other talks
- Research goals in this field

# GOALS OF THIS PRESENTATION

What this talk is about:

- General intro to  $\exists$ -rules
- Provide context for the other talks
- Research goals in this field

What is not:

- Motivation for the research of  $\exists$ -rules
- Deep technical content

# GOALS OF THIS PRESENTATION

What this talk is about:

- General intro to  $\exists$ -rules
- Provide context for the other talks
- Research goals in this field

What is not:

- Motivation for the research of  $\exists$ -rules
- Deep technical content

**Remark: Contact me for more info!**

- Email: [david.carral@inria.fr](mailto:david.carral@inria.fr)
- Office 3.129 at Building 5

# SYNTAX: EXISTENTIAL RULES

## Definition: Existential Rules

An (*existential*) rule is a first-order logic formula  $\forall \vec{x}, \vec{z}. \beta[\vec{x}, \vec{z}] \rightarrow \exists \vec{y}. \eta[\vec{x}, \vec{y}]$  where  $\beta$  and  $\eta$  are conjunctions of atoms without function symbols.

In a nutshell:  $\exists$ -rules = Datalog rules +  $\exists$ -quantifiers in the head

# SYNTAX: EXISTENTIAL RULES

## Definition: Existential Rules

An (*existential*) rule is a first-order logic formula  $\forall \vec{x}, \vec{z}. \beta[\vec{x}, \vec{z}] \rightarrow \exists \vec{y}. \eta[\vec{x}, \vec{y}]$  where  $\beta$  and  $\eta$  are conjunctions of atoms without function symbols.

In a nutshell:  $\exists$ -rules = Datalog rules +  $\exists$ -quantifiers in the head

## Example: Existential Rules

$$\forall x. \text{PhDStudent}(x) \rightarrow \exists y. \text{MainSupervisor}(x, y) \wedge \text{Professor}(y)$$

$$\forall x, y, z. \text{MainSupervisor}(x, y) \wedge \text{EmployedAt}(y, z) \rightarrow \text{StudiesAt}(x, z)$$

$$\forall x, y, z. \text{MainSupervisor}(x, y) \wedge \text{MainSupervisor}(x, z) \rightarrow y \approx z$$

$$\forall x. \text{Professor}(x) \wedge \text{PhDStudent}(x) \rightarrow \perp$$

# SYNTAX: EXISTENTIAL RULES

## Definition: Existential Rules

An (*existential*) rule is a first-order logic formula  $\forall \vec{x}, \vec{z}. \beta[\vec{x}, \vec{z}] \rightarrow \exists \vec{y}. \eta[\vec{x}, \vec{y}]$  where  $\beta$  and  $\eta$  are conjunctions of atoms without function symbols.

In a nutshell:  $\exists$ -rules = Datalog rules +  $\exists$ -quantifiers in the head

## Example: Existential Rules

$$\begin{aligned} & PhDStudent(x) \rightarrow \exists y. MainSupervisor(x, y) \wedge Professor(y) \\ & MainSupervisor(x, y) \wedge EmployedAt(y, z) \rightarrow StudiesAt(x, z) \\ & MainSupervisor(x, y) \wedge MainSupervisor(x, z) \rightarrow y \approx z \\ & Professor(x) \wedge PhDStudent(x) \rightarrow \perp \end{aligned}$$

We often omit universal quantifiers



# SYNTAX: EXISTENTIAL RULES

## Definition: Existential Rules

An (*existential*) rule is a first-order logic formula  $\forall \vec{x}, \vec{z}. \beta[\vec{x}, \vec{z}] \rightarrow \exists \vec{y}. \eta[\vec{x}, \vec{y}]$  where  $\beta$  and  $\eta$  are conjunctions of atoms without function symbols.

In a nutshell:  $\exists$ -rules = Datalog rules +  $\exists$ -quantifiers in the head

## Example: Existential Rules

$$\begin{aligned} & PhDStudent(x) \rightarrow \exists y. MainSupervisor(x, y) \wedge Professor(y) \\ & MainSupervisor(x, y) \wedge EmployedAt(y, z) \rightarrow StudiesAt(x, z) \\ & MainSupervisor(x, y) \wedge MainSupervisor(x, z) \rightarrow y \approx z \\ & Professor(x) \wedge PhDStudent(x) \rightarrow \perp \end{aligned}$$

We often omit universal quantifiers

## Remark: Database Theory

Diff. notation: tuple/equality generating dependencies and constraints.

## Definition

- A *fact* is an atomic formula  $P(\vec{c})$  where  $\vec{c}$  are constants.

## Definition

- A *fact* is an atomic formula  $P(\vec{c})$  where  $\vec{c}$  are constants.
- A *Boolean conjunctive query (BCQ)* is a (closed) formula  $\exists \vec{y}. \beta[\vec{y}]$  where  $\beta$  is a conjunction of atoms without function symbols.

## Definition

- A *fact* is an atomic formula  $P(\vec{c})$  where  $\vec{c}$  are constants.
- A *Boolean conjunctive query (BCQ)* is a (closed) formula  $\exists \vec{y}. \beta[\vec{y}]$  where  $\beta$  is a conjunction of atoms without function symbols.
- A *knowledge base (KB)* is a tuple  $\langle \mathcal{R}, \mathcal{F} \rangle$  where  $\mathcal{R}$  is a rule set and  $\mathcal{F}$  is a fact set.

## Definition

- A *fact* is an atomic formula  $P(\vec{c})$  where  $\vec{c}$  are constants.
- A *Boolean conjunctive query (BCQ)* is a (closed) formula  $\exists \vec{y}. \beta[\vec{y}]$  where  $\beta$  is a conjunction of atoms without function symbols.
- A *knowledge base (KB)* is a tuple  $\langle \mathcal{R}, \mathcal{F} \rangle$  where  $\mathcal{R}$  is a rule set and  $\mathcal{F}$  is a fact set.

All of the above: first-order logic formulas without function symbols!

## Definition

- A *fact* is an atomic formula  $P(\vec{c})$  where  $\vec{c}$  are constants.
- A *Boolean conjunctive query (BCQ)* is a (closed) formula  $\exists \vec{y}. \beta[\vec{y}]$  where  $\beta$  is a conjunction of atoms without function symbols.
- A *knowledge base (KB)* is a tuple  $\langle \mathcal{R}, \mathcal{F} \rangle$  where  $\mathcal{R}$  is a rule set and  $\mathcal{F}$  is a fact set.

All of the above: first-order logic formulas without function symbols!

## Definition: BCQ Entailment

A KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  *entails* a BCQ  $\gamma$ , written  $\mathcal{K} \models \gamma$ , if  $\gamma$  is a logical consequence of  $\mathcal{R} \cup \mathcal{F}$  under standard first-order logic semantics.

## Definition

- A *fact* is an atomic formula  $P(\vec{c})$  where  $\vec{c}$  are constants.
- A *Boolean conjunctive query (BCQ)* is a (closed) formula  $\exists \vec{y}. \beta[\vec{y}]$  where  $\beta$  is a conjunction of atoms without function symbols.
- A *knowledge base (KB)* is a tuple  $\langle \mathcal{R}, \mathcal{F} \rangle$  where  $\mathcal{R}$  is a rule set and  $\mathcal{F}$  is a fact set.

All of the above: first-order logic formulas without function symbols!

## Definition: BCQ Entailment

A KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  *entails* a BCQ  $\gamma$ , written  $\mathcal{K} \models \gamma$ , if  $\gamma$  is a logical consequence of  $\mathcal{R} \cup \mathcal{F}$  under standard first-order logic semantics.

## Remark

Can we decide BCQ entailment?

# SOLVING BCQ ENTAILMENT: UNIVERSAL MODELS

Determine if  $\mathcal{K}$  entails  $\gamma$ : determine if infinitely many models (which may be infinite!) satisfy  $\gamma$



# SOLVING BCQ ENTAILMENT: UNIVERSAL MODELS

Determine if  $\mathcal{K}$  entails  $\gamma$ : determine if infinitely many models (which may be infinite!) satisfy  $\gamma$   
 $\rightsquigarrow$  2 dimensions of infinity!

# SOLVING BCQ ENTAILMENT: UNIVERSAL MODELS

Determine if  $\mathcal{K}$  entails  $\gamma$ : determine if infinitely many models (which may be infinite!) satisfy  $\gamma$   
 $\rightsquigarrow$  2 dimensions of infinity!

## Definition

A *universal model* of a KB  $\mathcal{K}$  is a model that can be homomorphically embedded into every other model of  $\mathcal{K}$ .

# SOLVING BCQ ENTAILMENT: UNIVERSAL MODELS

Determine if  $\mathcal{K}$  entails  $\gamma$ : determine if infinitely many models (which may be infinite!) satisfy  $\gamma$   
 $\rightsquigarrow$  2 dimensions of infinity!

## Definition

A *universal model* of a KB  $\mathcal{K}$  is a model that can be homomorphically embedded into every other model of  $\mathcal{K}$ .

## Theorem

A KB  $\mathcal{K}$  entails a BCQ iff it is satisfied by some universal model of  $\mathcal{K}$ .

# SOLVING BCQ ENTAILMENT: UNIVERSAL MODELS

Determine if  $\mathcal{K}$  entails  $\gamma$ : determine if infinitely many models (which may be infinite!) satisfy  $\gamma$   
 $\rightsquigarrow$  2 dimensions of infinity!

## Definition

A *universal model* of a KB  $\mathcal{K}$  is a model that can be homomorphically embedded into every other model of  $\mathcal{K}$ .

## Theorem

A KB  $\mathcal{K}$  entails a BCQ iff it is satisfied by some universal model of  $\mathcal{K}$ .

Proof Intuition: universal models are the *logically weakest* models

# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z.R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

$$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x) \text{ and } q' = \exists x, y, z. R(x, y) \wedge R(y, z);$$

and the following models of  $\mathcal{K}$ :

$$\mathcal{M} = \{R(a, b), R(b, u), R(u, v), R(v, b)\}$$

$$\mathcal{U} = \{R(a, b), R(b, u_1), R(u_1, u_2), R(u_2, u_3), \dots\}$$

# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z.R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

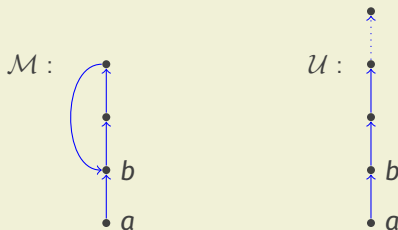
$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x)$  and  $q' = \exists x, y, z. R(x, y) \wedge R(y, z)$ ;

and the following models of  $\mathcal{K}$ :

$$\mathcal{M} = \{R(a, b), R(b, u), R(u, v), R(v, b)\}$$

$$\mathcal{U} = \{R(a, b), R(b, u_1), R(u_1, u_2), R(u_2, u_3), \dots\}$$

Graphical representation:



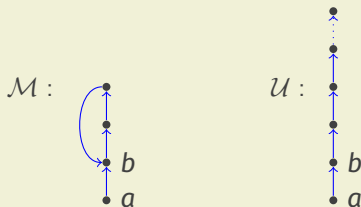
# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z.R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x)$  and  $q' = \exists x, y, z. R(x, y) \wedge R(y, z)$ ;

and the following models of  $\mathcal{K}$ :



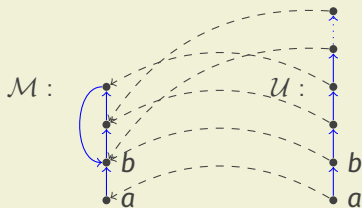
# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z.R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x)$  and  $q' = \exists x, y, z. R(x, y) \wedge R(y, z)$ ;

and the following models of  $\mathcal{K}$ :





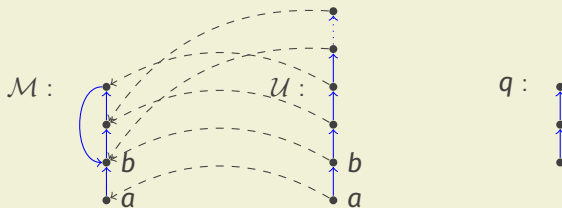
# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z.R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x)$  and  $q' = \exists x, y, z. R(x, y) \wedge R(y, z)$ ;

and the following models of  $\mathcal{K}$ :



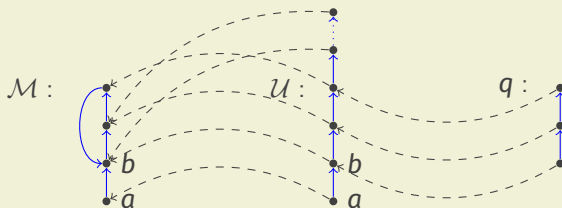
# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z.R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x)$  and  $q' = \exists x, y, z. R(x, y) \wedge R(y, z)$ ;

and the following models of  $\mathcal{K}$ :



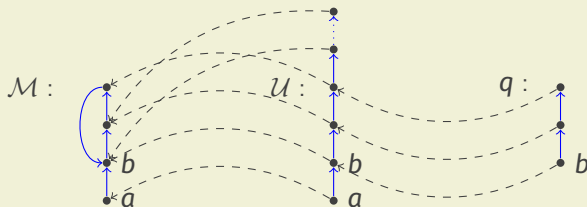
# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z.R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x)$  and  $q' = \exists x, y, z. R(x, y) \wedge R(y, z)$ ;

and the following models of  $\mathcal{K}$ :



## Theorem

A KB  $\mathcal{K}$  entails a BCQ iff it is satisfied by some universal model of  $\mathcal{K}$ .

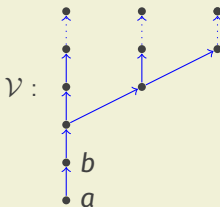
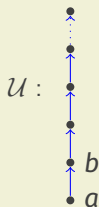
# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z. R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x)$  and  $q' = \exists x, y, z. R(x, y) \wedge R(y, z)$ ;

and the following models of  $\mathcal{K}$ :



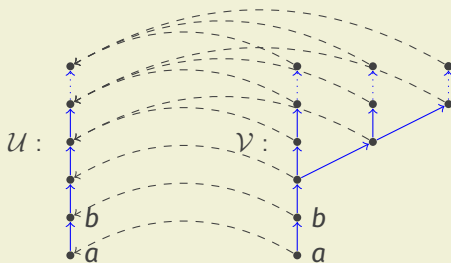
# SOLVING BCQ ENTAILMENT WITH UNIVERSAL MODELS

## Example

Consider the KB  $\mathcal{K} = \langle \{R(x, y) \rightarrow \exists z.R(y, z)\}, \{R(a, b)\} \rangle$ ; the BCQs

$q = \exists x, y, z. R(x, y) \wedge R(y, z) \wedge R(z, x)$  and  $q' = \exists x, y, z. R(x, y) \wedge R(y, z)$ ;

and the following models of  $\mathcal{K}$ :



# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \longrightarrow \text{Actor}(y)$

$\text{ActsIn}(x, y) \longrightarrow \text{Features}(y, x)$

$\text{DirectedBy}(x, y) \longrightarrow \text{Directs}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \longrightarrow \text{DirectsActor}(x, z)$

$\text{Director}(\text{spielberg})$

$\text{ActsIn}(\text{judeLaw}, \text{ai})$

$\text{DirectedBy}(\text{ai}, \text{spielberg})$

# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$

judeLaw



spielberg



$\text{Director}(\text{spielberg})$

$\text{ActsIn}(\text{judeLaw}, \text{ai})$



ai

$\text{DirectedBy}(\text{ai}, \text{spielberg})$

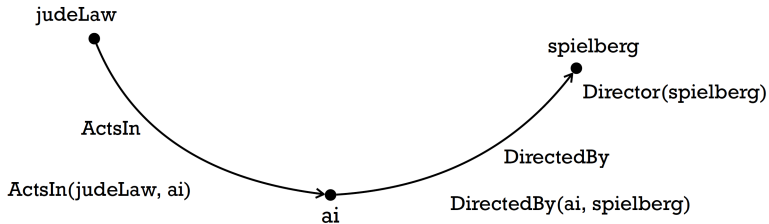
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$





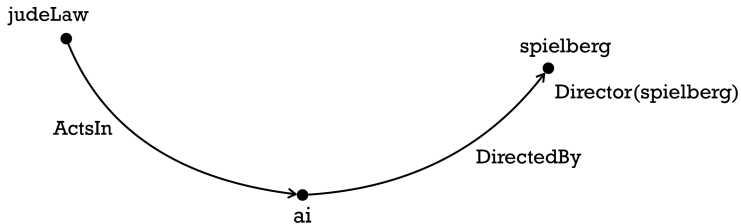
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$



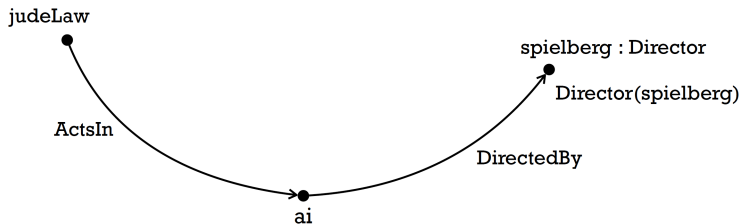
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$



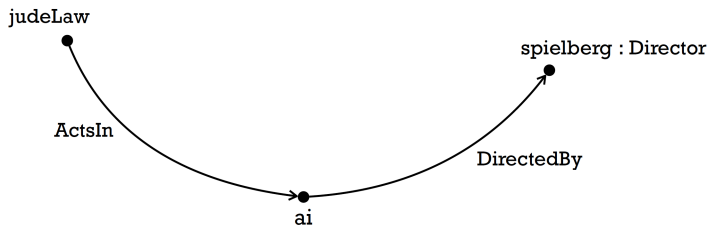
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$



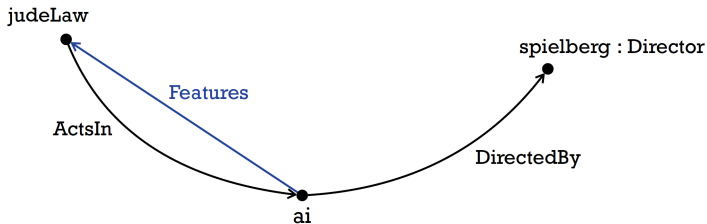
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$



# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

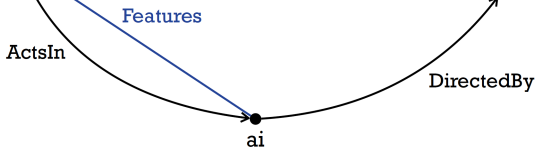
$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$

judeLaw : Actor

spielberg : Director



# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

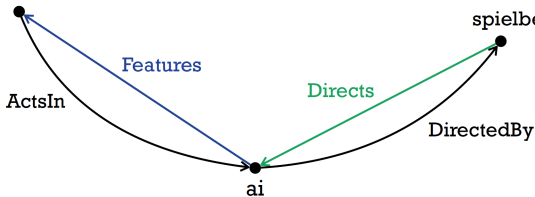
$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$

judeLaw : Actor

spielberg : Director



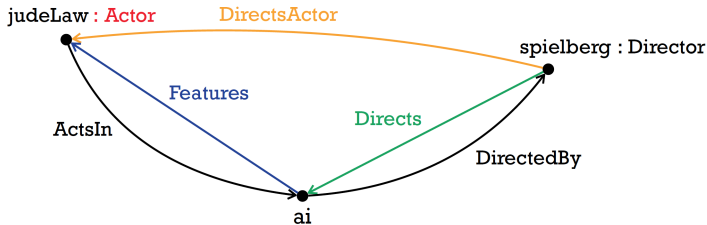
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Features}(x, y) \rightarrow \text{Actor}(y)$

$\text{DirectedBy}(x, y) \rightarrow \text{Directs}(y, x)$

$\text{ActsIn}(x, y) \rightarrow \text{Features}(y, x)$

$\text{Directs}(x, y) \wedge \text{Features}(y, z) \rightarrow \text{DirectsActor}(x, z)$



# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \exists v . \text{HasPart}(x, v) \wedge \text{Wheel}(v)$

$\text{Wheel}(x) \longrightarrow \exists w . \text{IsPartOf}(x, w) \wedge \text{Bicycle}(w)$

$\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$

$\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$

$b : \text{Bicycle}$





# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, f_v(x)) \wedge \text{Wheel}(f_v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, f_w(x)) \wedge \text{Bicycle}(f_w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$

$b : \text{Bicycle}$



# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$	$\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$
$\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$	$\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$

$b : \text{Bicycle}$



# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$

$\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$

$\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$

$\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$

$b : \text{Bicycle}$



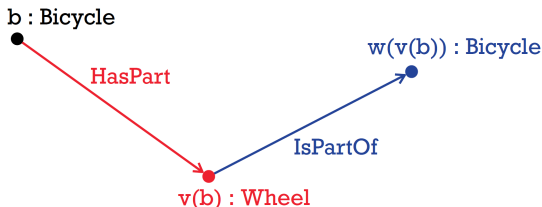
$\text{HasPart}$



$v(b) : \text{Wheel}$

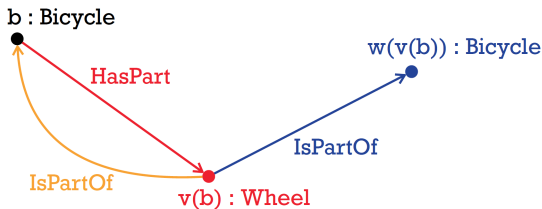
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



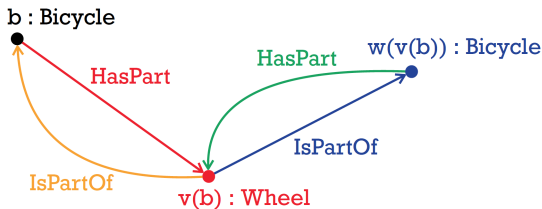
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



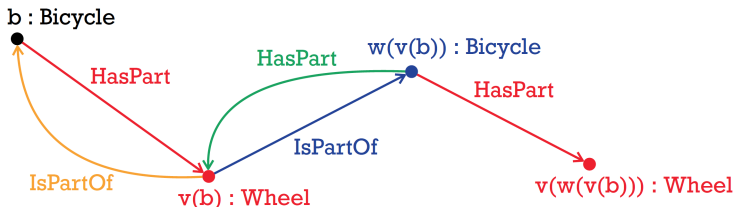
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



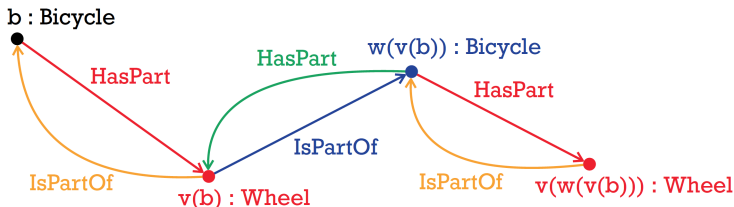
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



# UNIVERSAL MODELS: SKOLEM CHASE

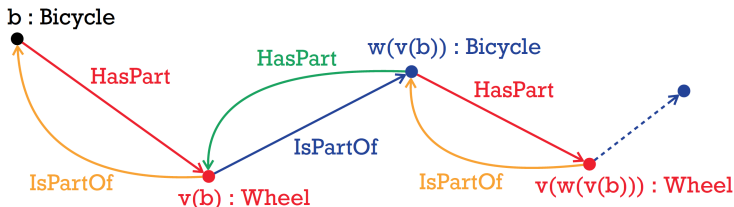
$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$





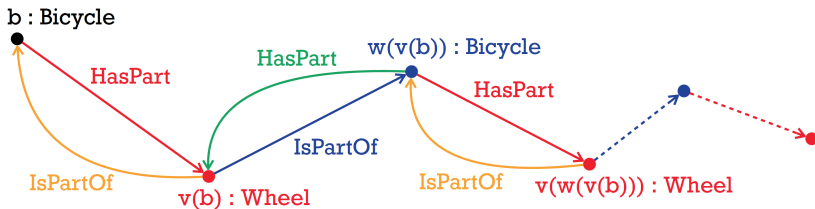
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



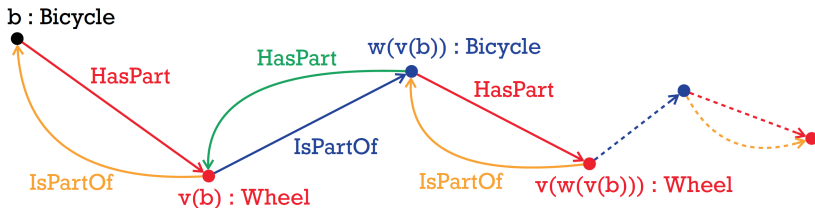
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



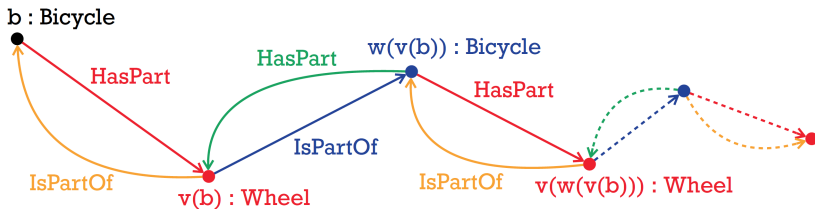
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



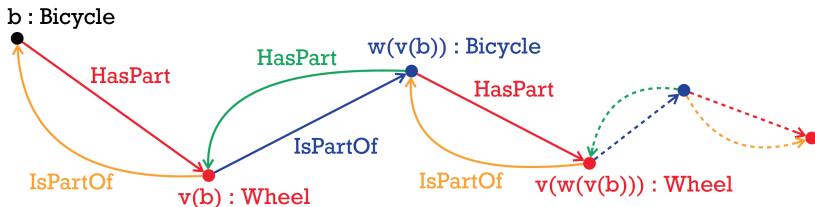
# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



# UNIVERSAL MODELS: SKOLEM CHASE

$\text{Bicycle}(x) \longrightarrow \text{HasPart}(x, v(x)) \wedge \text{Wheel}(v(x))$      $\text{HasPart}(x, y) \longrightarrow \text{IsPartOf}(y, x)$   
 $\text{Wheel}(x) \longrightarrow \text{IsPartOf}(x, w(x)) \wedge \text{Bicycle}(w(x))$      $\text{IsPartOf}(x, y) \longrightarrow \text{HasPart}(y, x)$



## Seminar Talk

Jacopo will discuss an implementation of the chase algorithm that uses compression to improve performance.

Also, see [Mar09] for a formal definition!

# IS BCQ ENTAILMENT DECIDABLE?

Universal models and the chase: we only need one model!

# IS BCQ ENTAILMENT DECIDABLE?

Universal models and the chase: we only need one model!

~→ However, the problem is still undecidable...

# IS BCQ ENTAILMENT DECIDABLE?

Universal models and the chase: we only need one model!

↪ However, the problem is still undecidable...

Reduction from:

## Theorem

Consider two context-free grammars  $G_1$  and  $G_2$ . The problem of checking if  $\mathcal{L}(G_1) \cap \mathcal{L}(G_2) = \emptyset$  is undecidable.



# IS BCQ ENTAILMENT DECIDABLE?

Universal models and the chase: we only need one model!

↪ However, the problem is still undecidable...

Reduction from:

## Theorem

Consider two context-free grammars  $G_1$  and  $G_2$ . The problem of checking if  $\mathcal{L}(G_1) \cap \mathcal{L}(G_2) = \emptyset$  is undecidable.

## Definition

A *context-free grammar* (CFG)  $G$  consists of a start non-terminal  $S$  and a set of production rules of the form

$$A \rightarrow B_1 \cdot \dots \cdot B_n \quad A \rightarrow \epsilon$$

where  $A$  is a non-terminal and each  $B_i$  is a terminal or a non-terminal. Moreover, there is some production rule of the form  $S \rightarrow B_1 \cdot \dots \cdot B_n$  in  $G$ .

Wlog assumptions: all CFGs are defined over the binary alphabet  $\{0, 1\}$ ; non-terminals do not reoccur across different grammars

# BCQ ENTAILMENT IS UNDECIDABLE (1)

How to encode a CFG with an existential rule KB:

## Definition

For a CFG  $G$ , let  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$  where  $\mathcal{R}_G$  is the rule set that contains:

$$V(x) \rightarrow \exists y. R_0(x, y) \wedge V(y)$$

$$V(x) \rightarrow \exists y. R_1(x, y) \wedge V(y)$$

$$\begin{array}{ll} R_{B_1}(x_0, x_1) \wedge \dots \wedge R_{B_n}(x_{n-1}, x_n) \rightarrow R_A(x_0, x_n) & \text{for all } A \rightarrow B_1 \cdot \dots \cdot B_n \in G \\ \rightarrow R_A(x, x) & \text{for all } A \rightarrow \epsilon \in G \end{array}$$

In the above, each  $R_s$  is a fresh binary predicate unique for the non-terminal/terminal symbol  $s$ .

# BCQ ENTAILMENT IS UNDECIDABLE (2)

## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} S \rightarrow oS1 & V(x) \rightarrow \exists y. \textcolor{blue}{R}_o(x, y) \wedge V(y) \quad V(x) \rightarrow \exists y. \textcolor{red}{R}_1(x, z) \wedge V(z) \\ S \rightarrow \epsilon & \textcolor{blue}{R}_o(x, y) \wedge R_S(y, z) \wedge \textcolor{red}{R}_1(z, w) \rightarrow R_S(x, w) \\ & \quad \quad \quad \rightarrow R_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

# BCQ ENTAILMENT IS UNDECIDABLE (2)

## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} V(x) \rightarrow \exists y. \textcolor{blue}{R}_0(x, y) \wedge V(y) & V(x) \rightarrow \exists y. \textcolor{red}{R}_1(x, z) \wedge V(z) \\ S \rightarrow oS1 & \textcolor{blue}{R}_0(x, y) \wedge R_S(y, z) \wedge \textcolor{red}{R}_1(z, w) \rightarrow R_S(x, w) \\ S \rightarrow \epsilon & \rightarrow R_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :

$$\bullet \quad c : V$$

# BCQ ENTAILMENT IS UNDECIDABLE (2)

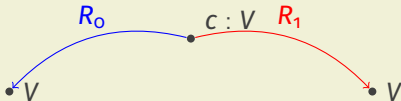
## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} S \rightarrow oS1 & V(x) \rightarrow \exists y. R_o(x, y) \wedge V(y) \quad V(x) \rightarrow \exists y. R_1(x, z) \wedge V(z) \\ S \rightarrow \epsilon & R_o(x, y) \wedge R_S(y, z) \wedge R_1(z, w) \rightarrow R_S(x, w) \\ & \rightarrow R_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



# BCQ ENTAILMENT IS UNDECIDABLE (2)

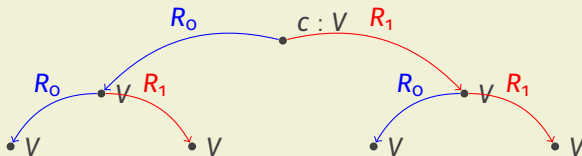
## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} V(x) \rightarrow \exists y. R_0(x, y) \wedge V(y) & V(x) \rightarrow \exists y. R_1(x, z) \wedge V(z) \\ S \rightarrow oS1 & R_0(x, y) \wedge R_S(y, z) \wedge R_1(z, w) \rightarrow R_S(x, w) \\ S \rightarrow \epsilon & \rightarrow R_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



# BCQ ENTAILMENT IS UNDECIDABLE (2)

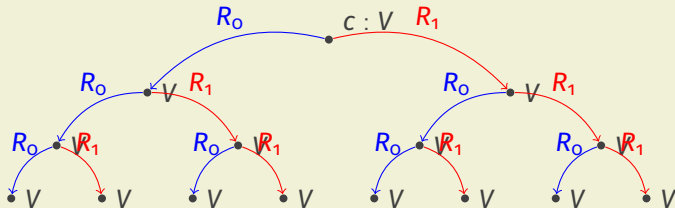
## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} V(x) \rightarrow \exists y. R_0(x, y) \wedge V(y) & V(x) \rightarrow \exists y. R_1(x, z) \wedge V(z) \\ S \rightarrow oS1 & R_0(x, y) \wedge R_S(y, z) \wedge R_1(z, w) \rightarrow R_S(x, w) \\ S \rightarrow \epsilon & \rightarrow R_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



## BCQ ENTAILMENT IS UNDECIDABLE (2)

## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$V(x) \rightarrow \exists y. R_0(x, y) \wedge V(y) \qquad V(x) \rightarrow \exists y. R_1(x, z) \wedge V(z)$$

$$S \rightarrow OS1$$

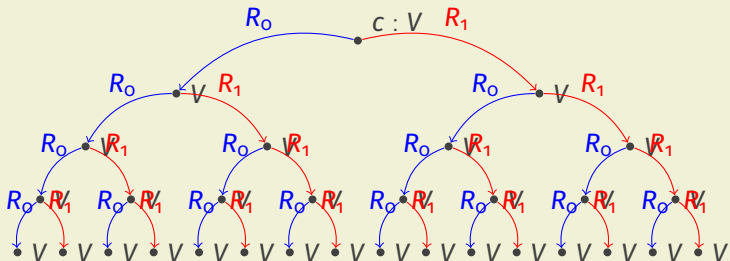
$$R_0(x, y) \wedge R_S(y, z) \wedge R_1(z, w) \rightarrow R_S(x, w)$$

$$S \rightarrow \epsilon$$

$$\rightarrow R_S(x, x)$$

Note that  $\mathcal{L}(G) = 0^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :





# BCQ ENTAILMENT IS UNDECIDABLE (2)

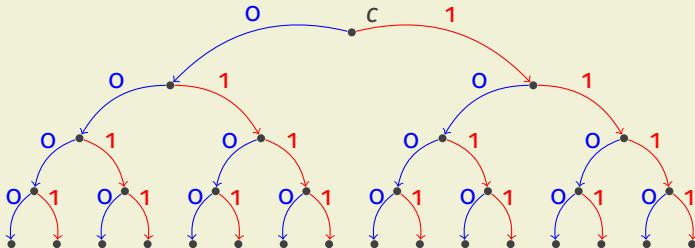
## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} V(x) \rightarrow \exists y. R_0(x, y) \wedge V(y) & V(x) \rightarrow \exists y. R_1(x, z) \wedge V(z) \\ S \rightarrow oS1 & R_0(x, y) \wedge R_S(y, z) \wedge R_1(z, w) \rightarrow R_S(x, w) \\ S \rightarrow \epsilon & \rightarrow R_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



# BCQ ENTAILMENT IS UNDECIDABLE (2)

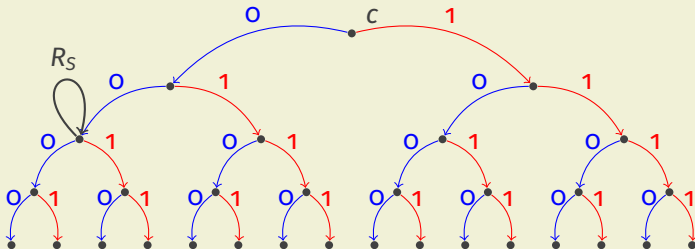
## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} V(x) \rightarrow \exists y. R_o(x, y) \wedge V(y) & V(x) \rightarrow \exists y. R_1(x, z) \wedge V(z) \\ S \rightarrow oS1 & R_o(x, y) \wedge R_S(y, z) \wedge R_1(z, w) \rightarrow R_S(x, w) \\ S \rightarrow \epsilon & \rightarrow R_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



## BCQ ENTAILMENT IS UNDECIDABLE (2)

## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$V(x) \rightarrow \exists y. R_0(x, y) \wedge V(y) \qquad V(x) \rightarrow \exists y. R_1(x, z) \wedge V(z)$$

$$S \rightarrow OS1$$

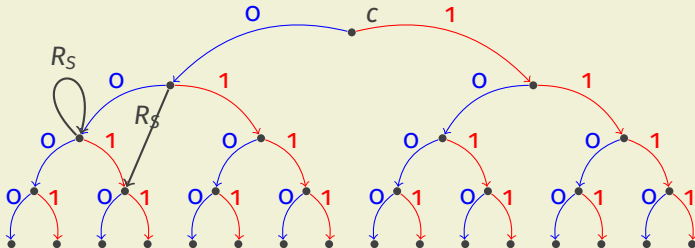
$$R_o(x, y) \wedge R_S(y, z) \wedge R_1(z, w) \rightarrow R_S(x, w)$$

$$S \rightarrow \epsilon$$

$$\rightarrow R_S(x, x)$$

Note that  $\mathcal{L}(G) = 0^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



# BCQ ENTAILMENT IS UNDECIDABLE (2)

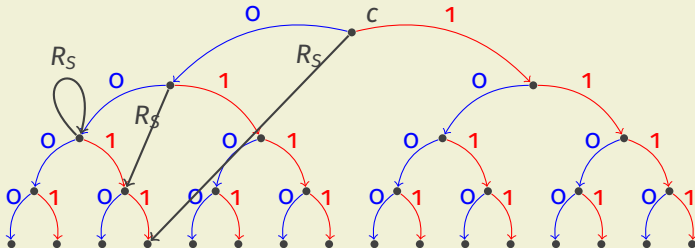
## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} V(x) \rightarrow \exists y. \mathbf{R}_0(x, y) \wedge V(y) & V(x) \rightarrow \exists y. \mathbf{R}_1(x, z) \wedge V(z) \\ S \rightarrow \text{oS1} & \mathbf{R}_0(x, y) \wedge \mathbf{R}_S(y, z) \wedge \mathbf{R}_1(z, w) \rightarrow \mathbf{R}_S(x, w) \\ S \rightarrow \epsilon & \rightarrow \mathbf{R}_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = \text{o}^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



# BCQ ENTAILMENT IS UNDECIDABLE (2)

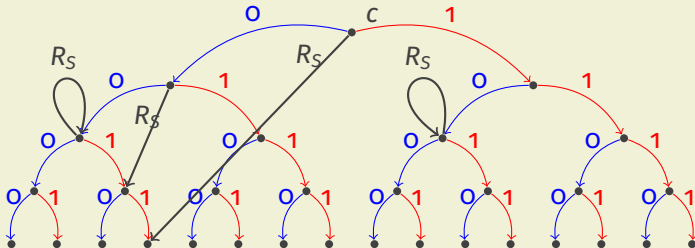
## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} V(x) \rightarrow \exists y. \mathbf{R}_0(x, y) \wedge V(y) & V(x) \rightarrow \exists y. \mathbf{R}_1(x, z) \wedge V(z) \\ S \rightarrow oS1 & \mathbf{R}_0(x, y) \wedge \mathbf{R}_S(y, z) \wedge \mathbf{R}_1(z, w) \rightarrow \mathbf{R}_S(x, w) \\ S \rightarrow \epsilon & \rightarrow \mathbf{R}_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



# BCQ ENTAILMENT IS UNDECIDABLE (2)

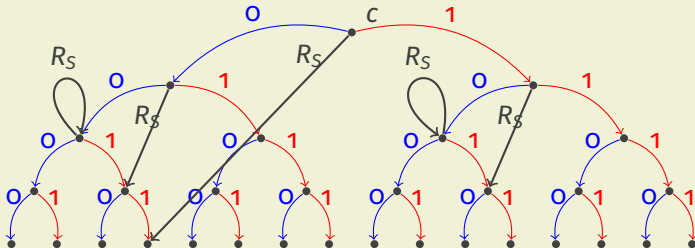
## Example

Consider the CFG  $G$  with start symbol  $S$  (left) and the rule set  $\mathcal{R}_G$  (right):

$$\begin{array}{ll} V(x) \rightarrow \exists y. \mathbf{R}_0(x, y) \wedge V(y) & V(x) \rightarrow \exists y. \mathbf{R}_1(x, z) \wedge V(z) \\ S \rightarrow oS1 & \mathbf{R}_0(x, y) \wedge \mathbf{R}_S(y, z) \wedge \mathbf{R}_1(z, w) \rightarrow \mathbf{R}_S(x, w) \\ S \rightarrow \epsilon & \rightarrow \mathbf{R}_S(x, x) \end{array}$$

Note that  $\mathcal{L}(G) = o^n 1^n$ .

Output of the Skolem chase on input  $\mathcal{K}_G = \langle \mathcal{R}_G, \{V(c)\} \rangle$ :



# BCQ ENTAILMENT IS UNDECIDABLE (3)

## Definition: Reduction

Consider some CFGs  $G_1$  and  $G_2$  with start symbols  $S_1$  and  $S_2$ , respectively. Then, let  $\mathcal{K}_{G_1}^{G_2}$  be the KB:

$$\langle \mathcal{R}_{G_1} \cup \mathcal{R}_{G_2} \cup \{R_{S_1}(x, y) \wedge R_{S_2}(x, y) \rightarrow \text{Int}\}, \{V(c)\} \rangle$$

# BCQ ENTAILMENT IS UNDECIDABLE (3)

## Definition: Reduction

Consider some CFGs  $G_1$  and  $G_2$  with start symbols  $S_1$  and  $S_2$ , respectively. Then, let  $\mathcal{K}_{G_1}^{G_2}$  be the KB:

$$\langle \mathcal{R}_{G_1} \cup \mathcal{R}_{G_2} \cup \{R_{S_1}(x, y) \wedge R_{S_2}(x, y) \rightarrow Int\}, \{V(c)\} \rangle$$

## Lemma

Given some CFGs  $G_1$  and  $G_2$ ,

$$\mathcal{L}(G_1) \cap \mathcal{L}(G_2) = \emptyset \iff \mathcal{K}_{G_1}^{G_2} \not\models Int$$



# BCQ ENTAILMENT IS UNDECIDABLE (3)

## Definition: Reduction

Consider some CFGs  $G_1$  and  $G_2$  with start symbols  $S_1$  and  $S_2$ , respectively. Then, let  $\mathcal{K}_{G_1}^{G_2}$  be the KB:

$$\langle \mathcal{R}_{G_1} \cup \mathcal{R}_{G_2} \cup \{R_{S_1}(x, y) \wedge R_{S_2}(x, y) \rightarrow Int\}, \{V(c)\} \rangle$$

## Lemma

Given some CFGs  $G_1$  and  $G_2$ ,

$$\mathcal{L}(G_1) \cap \mathcal{L}(G_2) = \emptyset \iff \mathcal{K}_{G_1}^{G_2} \not\models Int$$

## Theorem

The problem of checking if a KB entails a BCQ is undecidable.

# BCQ ENTAILMENT IS UNDECIDABLE (3)

## Definition: Reduction

Consider some CFGs  $G_1$  and  $G_2$  with start symbols  $S_1$  and  $S_2$ , respectively. Then, let  $\mathcal{K}_{G_1}^{G_2}$  be the KB:

$$\langle \mathcal{R}_{G_1} \cup \mathcal{R}_{G_2} \cup \{R_{S_1}(x, y) \wedge R_{S_2}(x, y) \rightarrow \text{Int}\}, \{V(c)\} \rangle$$

## Lemma

Given some CFGs  $G_1$  and  $G_2$ ,

$$\mathcal{L}(G_1) \cap \mathcal{L}(G_2) = \emptyset \iff \mathcal{K}_{G_1}^{G_2} \not\models \text{Int}$$

## Theorem

The problem of checking if a KB entails a BCQ is undecidable.

See [BV81] for an alternative proof of the above result.

# RETRIEVING DECIDABILITY (IN SOME CASES)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :

# RETRIEVING DECIDABILITY (IN SOME CASES)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :

1. Check if the Skolem chase terminates on  $\mathcal{R}$

# RETRIEVING DECIDABILITY (IN SOME CASES)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :

1. Check if the Skolem chase terminates on  $\mathcal{R}$
2. Apply this algorithm to  $\mathcal{K}$  and check if its result entails  $\gamma$

# RETRIEVING DECIDABILITY (IN SOME CASES)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :

1. Check if the Skolem chase terminates on  $\mathcal{R}$
2. Apply this algorithm to  $\mathcal{K}$  and check if its result entails  $\gamma$

## Theorem from [GM14]

The problem of checking if the Skolem chase terminates for a rule set or knowledge base is undecidable.

# RETRIEVING DECIDABILITY (IN SOME CASES)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :

1. Check if the Skolem chase terminates on  $\mathcal{R}$
2. Apply this algorithm to  $\mathcal{K}$  and check if its result entails  $\gamma$

## Theorem from [GM14]

The problem of checking if the Skolem chase terminates for a rule set or knowledge base is undecidable.

## Remark: Universal Termination

Note that we consider a check that verifies if the chase of  $\mathcal{R}$  terminates with respect to any fact set.

## RETRIEVING DECIDABILITY (IN SOME CASES) (2)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :



## RETRIEVING DECIDABILITY (IN SOME CASES) (2)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :

1. Check if  $\mathcal{R}$  is *weakly acyclic* (~~the Skolem chase terminates on  $\mathcal{R}$~~ )

## RETRIEVING DECIDABILITY (IN SOME CASES) (2)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :

1. Check if  $\mathcal{R}$  is *weakly acyclic* (~~the Skolem chase terminates on  $\mathcal{R}$~~ )
2. Compute the Skolem chase of  $\mathcal{K}$  and check if its result entails  $\gamma$

## RETRIEVING DECIDABILITY (IN SOME CASES) (2)

In order to decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a BCQ  $\gamma$ :

1. Check if  $\mathcal{R}$  is *weakly acyclic* (~~the Skolem chase terminates on  $\mathcal{R}$~~ )
2. Compute the Skolem chase of  $\mathcal{K}$  and check if its result entails  $\gamma$

### Remark

Weak acyclicity [FKMP05] is a sufficient condition that guarantees universal Skolem chase termination.

# WEAK ACYCLICITY (1)

## Example

Consider the rule set  $\mathcal{R}$

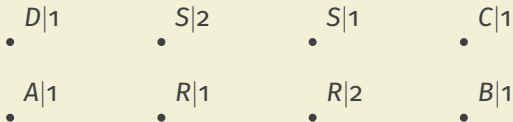
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$B(x) \rightarrow C(x)$$

$$D(x) \rightarrow A(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (1)

## Example

Consider the rule set  $\mathcal{R}$

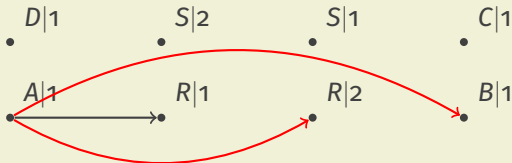
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow A(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (1)

## Example

Consider the rule set  $\mathcal{R}$

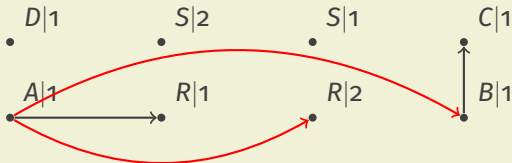
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow A(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (1)

## Example

Consider the rule set  $\mathcal{R}$

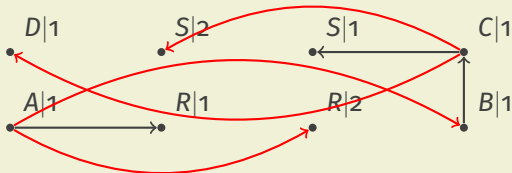
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow A(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (1)

## Example

Consider the rule set  $\mathcal{R}$

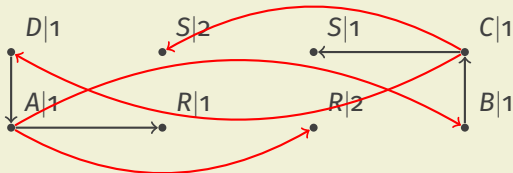
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow A(x)$$

and its weakly acyclic graph





# WEAK ACYCLICITY (1)

## Example

Consider the rule set  $\mathcal{R}$

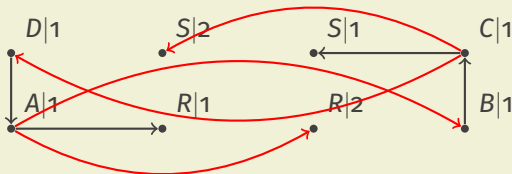
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow A(x)$$

and its weakly acyclic graph



Fails the test: true negative!

# WEAK ACYCLICITY (2)

## Example

Consider the rule set  $\mathcal{R}$

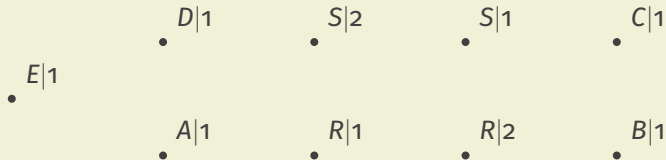
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$B(x) \rightarrow C(x)$$

$$D(x) \rightarrow E(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (2)

## Example

Consider the rule set  $\mathcal{R}$

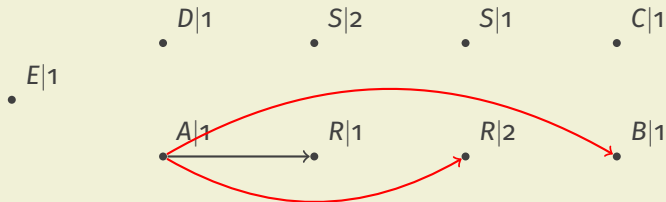
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow E(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (2)

## Example

Consider the rule set  $\mathcal{R}$

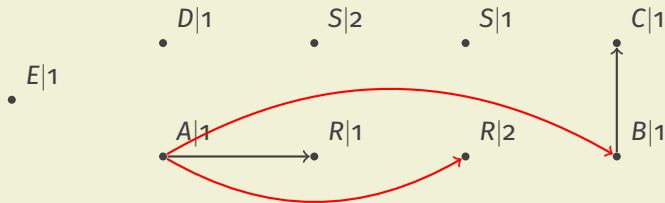
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow E(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (2)

## Example

Consider the rule set  $\mathcal{R}$

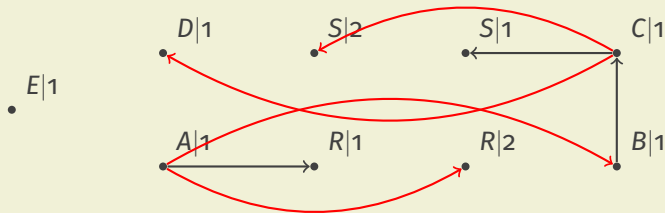
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow E(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (2)

## Example

Consider the rule set  $\mathcal{R}$

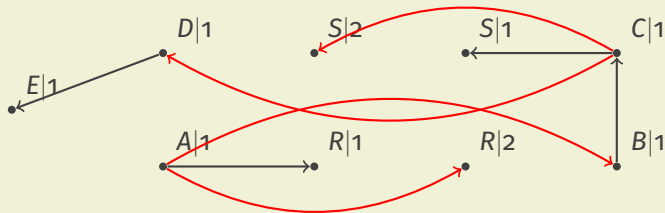
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$B(x) \rightarrow C(x)$$

$$D(x) \rightarrow E(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (2)

## Example

Consider the rule set  $\mathcal{R}$

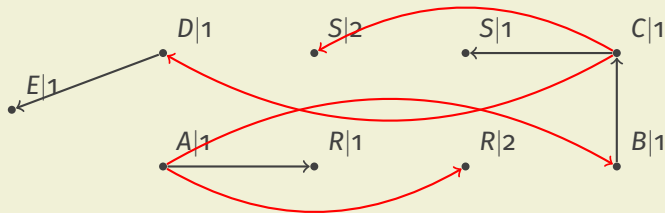
$$A(x) \rightarrow \exists y. R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \rightarrow \exists y. S(x, y) \wedge D(y)$$

$$D(x) \rightarrow E(x)$$

and its weakly acyclic graph



Passes the test: (true) positive!

# WEAK ACYCLICITY (3)

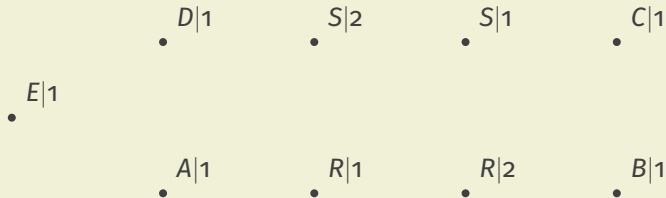
## Example

Consider the rule set  $\mathcal{R}$

$$\begin{aligned} A(x) &\rightarrow \exists y. R(x, y) \wedge B(y) \\ C(x) \wedge E(x) &\rightarrow \exists y. S(x, y) \wedge D(y) \end{aligned}$$

$$\begin{aligned} B(x) &\rightarrow C(x) \\ D(x) &\rightarrow A(x) \end{aligned}$$

and its weakly acyclic graph





# WEAK ACYCLICITY (3)

## Example

Consider the rule set  $\mathcal{R}$

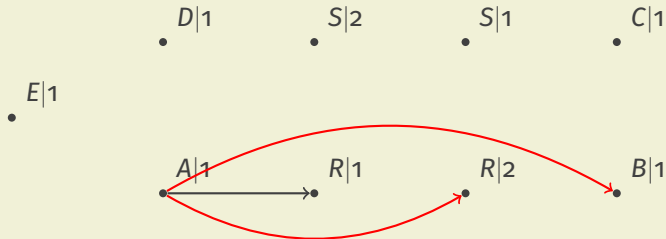
$$A(x) \rightarrow \exists y.R(x, y) \wedge B(y)$$

$$B(x) \rightarrow C(x)$$

$$C(x) \wedge E(x) \rightarrow \exists y.S(x, y) \wedge D(y)$$

$$D(x) \rightarrow A(x)$$

and its weakly acyclic graph



# WEAK ACYCLICITY (3)

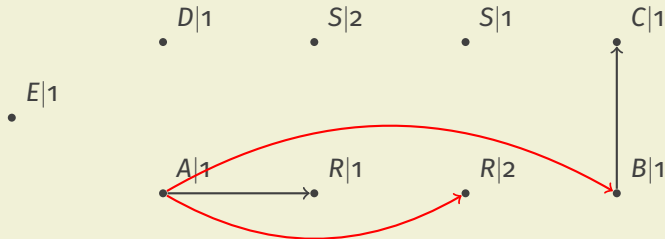
## Example

Consider the rule set  $\mathcal{R}$

$$\begin{aligned} A(x) &\rightarrow \exists y. R(x, y) \wedge B(y) \\ C(x) \wedge E(x) &\rightarrow \exists y. S(x, y) \wedge D(y) \end{aligned}$$

$$\begin{aligned} B(x) &\rightarrow C(x) \\ D(x) &\rightarrow A(x) \end{aligned}$$

and its weakly acyclic graph



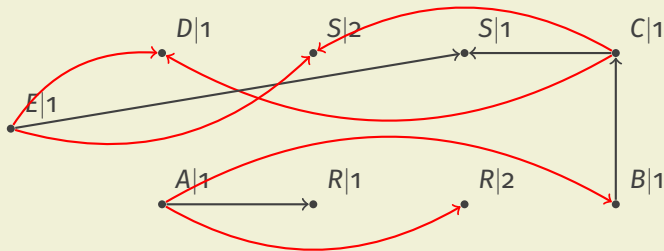
# WEAK ACYCLICITY (3)

## Example

Consider the rule set  $\mathcal{R}$

$$\begin{array}{ll} A(x) \rightarrow \exists y. R(x, y) \wedge B(y) & B(x) \rightarrow C(x) \\ C(x) \wedge E(x) \rightarrow \exists y. S(x, y) \wedge D(y) & D(x) \rightarrow A(x) \end{array}$$

and its weakly acyclic graph



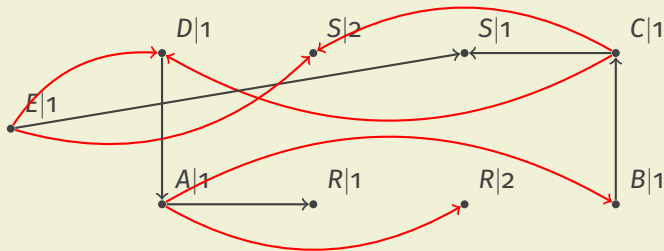
# WEAK ACYCLICITY (3)

## Example

Consider the rule set  $\mathcal{R}$

$$\begin{array}{ll} A(x) \rightarrow \exists y.R(x, y) \wedge B(y) & B(x) \rightarrow C(x) \\ C(x) \wedge E(x) \rightarrow \exists y.S(x, y) \wedge D(y) & D(x) \rightarrow A(x) \end{array}$$

and its weakly acyclic graph



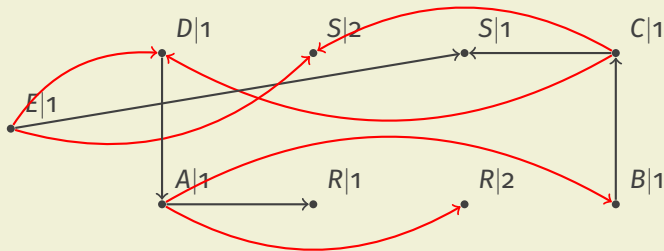
# WEAK ACYCLICITY (3)

## Example

Consider the rule set  $\mathcal{R}$

$$\begin{array}{ll} A(x) \rightarrow \exists y.R(x, y) \wedge B(y) & B(x) \rightarrow C(x) \\ C(x) \wedge E(x) \rightarrow \exists y.S(x, y) \wedge D(y) & D(x) \rightarrow A(x) \end{array}$$

and its weakly acyclic graph



Fails the test: false negative!

# A RECIPE FOR DECIDABILITY

To decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a query  $\gamma$ :

1. *Decidability property*: the Skolem chase terminates on  $\mathcal{R}$
2. *Sufficient condition*: check if  $\mathcal{R}$  is weakly acyclicity
3. *Algorithm*: compute the chase of  $\mathcal{K}$  and check if it entails  $\gamma$

# A RECIPE FOR DECIDABILITY

To decide if a KB  $\mathcal{K} = \langle \mathcal{R}, \mathcal{F} \rangle$  entails a query  $\gamma$ :

1. *Decidability property*: the Skolem chase terminates on  $\mathcal{R}$
2. *Sufficient condition*: check if  $\mathcal{R}$  is weakly acyclicity
3. *Algorithm*: compute the chase of  $\mathcal{K}$  and check if it entails  $\gamma$

## Seminar Talk: Michaël Thomazo (morning)

1. *Decidability property*: bounded tree-width model property
2. *Decidable language*: guarded existential rules
3. *Algorithm*: compute a finite rep. of a (possibly) infinite model

# RESEARCH GOALS

The recipe:

1. Choose a property that guarantees decidability
2. Choose a (decidable) sufficient condition for or a language that has this property
3. Apply the algorithm if the input satisfies the sufficient condition



# RESEARCH GOALS

The recipe:

1. Choose a property that guarantees decidability
2. Choose a (decidable) sufficient condition for or a language that has this property
3. Apply the algorithm if the input satisfies the sufficient condition

Research goals:

- Develop general sufficient conditions and languages that guarantee decidability (Tim's talk).

# RESEARCH GOALS

The recipe:

1. Choose a property that guarantees decidability
2. Choose a (decidable) sufficient condition for or a language that has this property
3. Apply the algorithm if the input satisfies the sufficient condition

Research goals:

- Develop general sufficient conditions and languages that guarantee decidability (Tim's talk).
- Study the complexity of reasoning for theories that satisfy some decidability property or some sufficient condition (Piotr's talk; Michaël's afternoon talk).

# RESEARCH GOALS

The recipe:

1. Choose a property that guarantees decidability
2. Choose a (decidable) sufficient condition for or a language that has this property
3. Apply the algorithm if the input satisfies the sufficient condition

Research goals:

- Develop general sufficient conditions and languages that guarantee decidability (Tim's talk).
- Study the complexity of reasoning for theories that satisfy some decidability property or some sufficient condition (Piotr's talk; Michaël's afternoon talk).
- Efficient algorithm implementation (Jacopo's talk).

# RESEARCH GOALS

The recipe:




1. Choose a property that guarantees decidability
2. Choose a (decidable) sufficient condition for or a language that has this property
3. Apply the algorithm if the input satisfies the sufficient condition


Research goals:

- Develop general sufficient conditions and languages that guarantee decidability (Tim's talk).
- Study the complexity of reasoning for theories that satisfy some decidability property or some sufficient condition (Piotr's talk; Michaël's afternoon talk).
- Efficient algorithm implementation (Jacopo's talk).
- Study the expressivity of decidable classes of rule sets (Sebastian's talk).

**THANKS FOR YOUR ATTENTION!**

# REFERENCES I

-  CATRIEL BEERI AND MOSHE Y. VARDI, *THE IMPLICATION PROBLEM FOR DATA DEPENDENCIES*, AUTOMATA, LANGUAGES AND PROGRAMMING, 8TH COLLOQUIUM, PROCEEDINGS (SHIMON EVEN AND ODED KARIV, EDS.), LECTURE NOTES IN COMPUTER SCIENCE, VOL. 115, SPRINGER, 1981, PP. 73–85.
-  RONALD FAGIN, PHOKION G. KOLAITIS, RENÉE J. MILLER, AND LUCIAN POPA, *DATA EXCHANGE: SEMANTICS AND QUERY ANSWERING*, THEOR. COMPUT. SCI. **336** (2005), NO. 1, 89–124.
-  TOMASZ GOGACZ AND JERZY MARCINKOWSKI, *ALL-INSTANCES TERMINATION OF CHASE IS UNDECIDABLE*, AUTOMATA, LANGUAGES, AND PROGRAMMING - 41ST INTERNATIONAL COLLOQUIUM, ICALP 2014, PROCEEDINGS, PART II (JAVIER ESPARZA, PIERRE FRAIGNIAUD, THORE HUSFELDT, AND ELIAS KOUTSOUPIS, EDS.), LECTURE NOTES IN COMPUTER SCIENCE, VOL. 8573, SPRINGER, 2014, PP. 293–304.

-  BRUNO MARNETTE, *GENERALIZED SCHEMA-MAPPINGS: FROM TERMINATION TO TRACTABILITY*, PROCEEDINGS OF THE TWENTY-EIGHTH ACM SIGMOD-SIGACT-SIGART SYMPOSIUM ON PRINCIPLES OF DATABASE SYSTEMS, PODS 2009 (JAN PAREDAENS AND JIANWEN SU, EDS.), ACM, 2009, PP. 13–22.