Reconstruction de courbes en super-résolution sans-grille

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30th August 2023

Morpheme research team Inria, CNRS, Université Côte d'Azur 1. Introduction

- 2. Off-the-grid spikes
- 3. A new divergence regularisation
- 4. Off-the-grid numerical reconstruction

5. Conclusion

Introduction

Objective

To image **live** biological structures at **small scales**.

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Source to estimate



Introducing a grid



Reconstruction \hat{S} on a grid



Reconstruction \hat{S} on a finer grid



Reconstruction \hat{S} is now **off-the-grid**

Off-the-grid spikes

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- Banach endowed with TV-norm : $m\in\mathcal{M}\left(\mathcal{X}
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If $m = \sum_{i=1}^{N} a_i \delta_{x_i}$ a discrete measure, then $|m|(\mathcal{X}) = \sum_{i=1}^{N} |a_i|$.

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[de Castro and Gamboa, 2012, Bredies and Pikkarainen, 2012] for $\lambda >$ 0 :

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Difficult numerical problem: infinite dimensional, non-reflexive. Tackled by greedy algorithm like *Frank-Wolfe* [Frank and Wolfe, 1956], *etc*.

Some results for spikes reconstruction

Reconstruction by fluorescence microscopy SMLM: acquisition stack with few lit fluorophores per image.





Figure 1: Two excerpts from a SMLM stack



Stack mean



Stack mean

Off-the-grid [Laville et al., 2021]



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Off-the-grid [Laville et al., 2021] Deep-STORM [Nehme et al., 2018]



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SMLM drawback: a lot of images, no live-cell imaging.

A new divergence regularisation

Geometry encoded in off-the-grid

	0D		
Geometry	Spikes		
Space	$\mathcal{M}\left(\mathcal{X} ight)$		
Regulariser	$\left\ \cdot\right\ _{\mathrm{TV}}$		



Geometry encoded in off-the-grid

	0D	$2D^1$
Geometry	Spikes	Sets
Space	$\mathcal{M}(\mathcal{X})$	$\mathrm{BV}(\mathcal{X})$
Regulariser	$\left\ \cdot\right\ _{\mathrm{TV}}$	$\left\ \cdot\right\ _{1}+\left\ \mathrm{D}\cdot\right\ _{\mathrm{TV}}$



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- let $\gamma : [0, 1] \to \mathbb{R}^d$ a 1-rectifiable parametrised Lipschitz curve, we say that $\mu_{\gamma} \in \mathscr{V}$ is a measure **supported on a curve** γ if:

$$\forall \boldsymbol{g} \in \boldsymbol{C_0}(\boldsymbol{\mathcal{X}})^{\boldsymbol{2}}, \quad \langle \boldsymbol{\mu_{\gamma}}, \boldsymbol{g} \rangle_{\boldsymbol{\mathcal{M}}^{\boldsymbol{2}}} \stackrel{\text{def.}}{=} \int_0^1 \boldsymbol{g}(\boldsymbol{\gamma}(t)) \cdot \dot{\boldsymbol{\gamma}}(t) \, \mathrm{d}t.$$

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CROC energy

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- $\left\|\operatorname{div} \boldsymbol{m}\right\|_{\mathrm{TV}}$ is the (open) curve counting term.

Consider the variational problem we coined *Curves Represented On Charges*:

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Do curve measures minimise (CROC)?

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Ext K is the set of extreme points of K.



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Theorem (from [Boyer et al., 2019, Bredies and Carioni, 2019])

There exists a minimiser of F which is a linear sum of extreme points of $\operatorname{Ext} \mathcal{B}_F^1$

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Characterise Ext \mathcal{B}^1_E of the regulariser \iff outline the structure of a *minimum* of *F*.

• If $E = \mathcal{M}(\mathcal{X})$ and $R = \|\cdot\|_{\mathrm{TV}}$, then:

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• If $E = \mathscr{V}$ and $R = \|\cdot\|_{\mathscr{V}}$, then:

 $\mathsf{Ext}(\mathcal{B}_{\mathscr{V}}) = ?$

Main result

Let the (non-complete) set of curve measures endowed with weak-* topology:

$$\mathfrak{G} \stackrel{\mathrm{def.}}{=} \left\{ rac{\mu_{\boldsymbol{\gamma}}}{\|\mu_{\boldsymbol{\gamma}}\|_{\mathscr{V}}}, \, \boldsymbol{\gamma} \, \mathsf{Lipschitz} \, \mathsf{1} ext{-rectifiable simple curve}
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$$\operatorname{Ext}(\mathcal{B}^1_{\mathscr{V}}) = \mathfrak{G}.$$

Off-the-grid numerical reconstruction

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We present the Charge Sliding Frank-Wolfe algorithm.





Figure 2: The source and its noisy acquired image I
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$$\eta = \Phi^* (\Phi m - \underbrace{y}_{=\nabla t}) \simeq \Delta u$$



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Final results



Reconstruction [Laville et al., 2023a].



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- Bézier curves holds nice regularity properties, encodes a curve with few control points
- Pro: always smooth curves. Cons: prone to shortening.



Conclusion

Recap

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Still, there is room for improvements:

- define a *scalar* operator, further enabling curve reconstruction in fluctuation microscopy;
- improve the support estimation step;
- tackle the curve crossing issue.

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Figure 4: First step of first iteration: certificate and support of new curve estimated



Figure 4: First step of first iteration: certificate and support of new curve estimated



Amplitude optimisation

Figure 4: First iteration: second and third steps



Amplitude optimisation

Both amplitude and position optimisation

Figure 4: First iteration: second and third steps



Figure 4: Second iteration: another curve is found



Figure 4: Second iteration: another curve is found