

Deformation techniques for sparse systems

Gabriela Jeronimo^{a,b}, Guillermo Matera^{b,c}, Pablo Solernó^{a,b}, and Ariel Waissbein^d

^aDepartamento de Matemática, Facultad Cs. Exactas y Naturales, Universidad de Buenos Aires, Ciudad Universitaria, Pabellón I (1428) Buenos Aires, Argentina

^bNational Council of Science and Technology (CONICET), Argentina

^bInstituto de Desarrollo Humano, Universidad Nacional de General Sarmiento, J.M. Gutiérrez 1150 (1613) Los Polvorines, Buenos Aires, Argentina

^cCoreLabs, CORE Security Technologies, Humboldt 1967 (C1414CTU) Buenos Aires, Argentina
ITBA, Av. E. Madero 399 (C1106ACD) Buenos Aires, Argentina

In this talk we present a probabilistic symbolic algorithm for solving zero-dimensional *sparse* systems, namely, systems defined by polynomials with nonzero coefficients only at a prescribed set of monomials. Our algorithm combines a symbolic homotopy procedure, based on a flat deformation of a certain morphism of affine varieties, with the polyhedral deformation of Huber and Sturmfels. The complexity of our algorithm is cubic in the size of the combinatorial structure of the input system. This size is mainly represented by the cardinality and mixed volume of Newton polytopes of the input polynomials and an arithmetic analogue of the mixed volume associated to the deformations under consideration.