

# Point counting in genus 2: towards 128 bits

P. Gaudry	É. Schost	N. Pitcher
Cacao project	ORCCA	MSCS
CNRS-INRIA	UWO	U. of Illinois

# Genus 2 curves and associated objects

- $C$  is the curve defined over  $\mathbb{F}_p$  by

$$y^2 = x^5 + f_4x^4 + f_3x^3 + f_2x^2 + f_1x + f_0,$$

with  $p$  large prime.

- $\mathbf{J}$  is its **Jacobian**
  - projective variety of **dimension 2**;
  - but we will work on an affine part of it.
- $\mathbf{K}$  is the associated **Kummer surface**
  - $\mathbf{K} = \mathbf{J}/\{\pm 1\}$ .
  - a projective variety of **dimension 2** too;
  - we won't work with it too much.

# Why?

Cryptologists like genus 2 Jacobians.

- Dimension 2:
  - there are more rational points than on an elliptic curve,
  - so for a given number of points, smaller base field.
- Scalar multiplication is not too slow
  - Chudnovsky<sup>2</sup>, Gaudry.

So they could be competitive with elliptic curves.

# Our question

**Problem:** finding **one** curve

- whose Jacobian has a **prime** cardinality (for safety reasons);
- over a **prime field**;
- with **small coefficients**
  - to make scalar multiplication fast.

Goal:  $p = 2^{127} - 1$ .

**We are not there yet**, but almost.

- a first 128 bit run;
- the curve was mostly random (but lucky).

## Previous work, large characteristic

**Schoof** (1985): polynomial time algorithm for elliptic curves.

- Pila (1990): algorithm for abelian varieties.
- Kampkötter (1991): genus 2 algorithm.
- Adleman-Huang (1996), Huang-Ierardi (1998): improvements of Pila's work.
- **Gaudry-Harley** (2000): genus 2 algorithm,  $p \simeq 2^{61}$ .
- **Matsuo-Chao-Tsujii** (2002): baby steps / giant steps strategy.
- **Gaudry-S.** (2004): cryptographic size:  $p \simeq 2^{82}$ .
- **Gaudry-S.** (2004): parallel, low-memory version of Matsuo-Chao-Tsujii.

# Schoof's approach

Let

$$\chi = T^4 - s_1T^3 + s_2T^2 - ps_1T + p^2 \in \mathbb{Z}[T]$$

be the **characteristic polynomial** of the Frobenius endomorphism on  $\mathbf{J}$ .

- $\text{card}(\mathbf{J}) = \chi(1)$ ;
- for  $\ell \in \mathbb{N}$ , computing the  **$\ell$ -torsion** (or a subset of it) gives  **$\chi \bmod \ell$**  (up to some indeterminacy, maybe).

**General scheme:**

- for as many coprimes  $\ell_1, \dots, \ell_r$  as possible, compute the  $\ell$ -torsion;
- some collision detection technique is used if we do not have enough precision to conclude by Chinese remaindering:

If  $\ell_1 \cdots \ell_r = m$ , then the cost is about  $p^{0.75}/m$ .

# Concretely

It boils down to solving polynomial systems.

## To keep in mind:

- an element of the Jacobian has **4** coordinates with **2** relations.
- $\ell$ -torsion has cardinality  $\ell^4$ .

**Large primes:** up to  $\ell = 31$  or  $\ell = 37$  ( $\ell = 43$  doable?)

- solving bivariate systems by bivariate resultants.

## Prime powers:

- cool improvements on  $2^k$ -torsion and  $3^k$ -torsion;
- brute-force improvements on  $5^k$ -torsion and  $7^k$ -torsion.

# Concretely

Software environment: [NTL](#)

- Does better than Magma for the routines we need
  - most basic routines on uni (bi, tri) -variate polynomials.
- Convenient
  - `./configure ; make`
- On the other hand, no Gröbner engine
  - anyway, faster workarounds.



# Reduction to bivariate solving

Almost everything is from [Gaudry-Harley](#) and [Gaudry-S.](#):

- Rewrite  $[\ell]D = 0$  as

$$D = P_1(x_1, y_1) + P_2(x_2, y_2), \quad [\ell]P_1 = -[\ell]P_2.$$

- You get equations in  $(x_1, y_1, x_2, y_2)$  with symmetries.
- Rewrite these equations in the elementary symmetric polynomials.  
Saves a factor of 2!
- Solve bivariate equations with bivariate resultants.

What's left to improve:

- Bivariate resultants are sub-optimal.  
Output size  $\simeq \ell^4$ ; cost  $O^\sim(\ell^6)$   
 $O^\sim$  means we neglect logarithmic factors.
- Systems are over-determined.

# Lifting the torsion

While (possible==true) do

- write the equations that say  $[\ell]P_{k+1} = P_k$   $\ell^4$  solutions;
- extend the base field with one solution;
- continue.  $\ell \rightarrow \ell^2 \rightarrow \ell^3 \rightarrow \dots$

Here,  $\ell = 2, 3, 5, 7$ .

- Known complexity estimates ill-adapted: it's all in the big-Oh.
- the systems are **simple enough** that specialized solutions may pay off:
  - $\ell = 2$ : reduction to square-root extraction;
  - $\ell = 3$ : deformation techniques & root-finding;
  - $\ell = 5, 7$ : bivariate resultants, again.

# Division by 2

1. Amounts to compute **square roots**.

- ...or a little bit more (extend the base field when no square root exists)
- complexity as in **Kaltofen-Shoup, 1997**.

2. Main subroutine: modular composition  $A, B, C \mapsto A(B) \bmod C$ .

- most other operations reduce to composition or a dual form of it.
  - irreducibility tests
  - equal-degree factorization
  - finding new primitive elements
- **cost**:  $C(d) = O^{\sim}(d^{1.5})$  (**polynomial operations**) +  $O(d^2)$  (**linear algebra**)
- **Kedlaya-Umans**: not useful yet.

# Division by 3

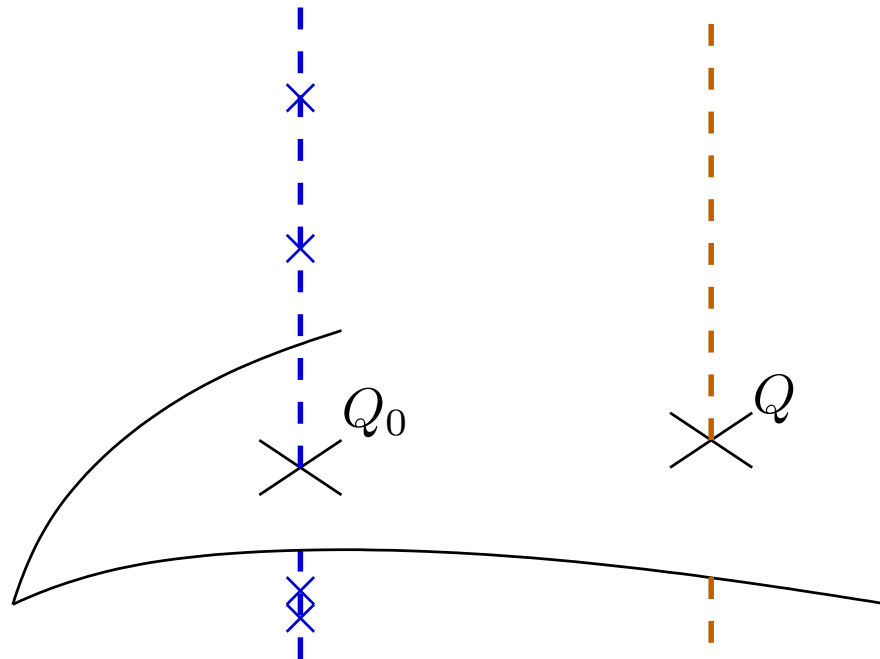
## Basic idea

- The system  $[3]P = Q$  is parametrized by the coordinates of  $Q$ .
- Set up a homotopy between the target  $[3]P = Q$  and an initial system  $[3]P_0 = Q_0$  for which we know the solutions  
basically, we let  $Q_t = (1 - t)Q_0 + tQ$ .
- Compute a description of the solution curve and let  $t = 1$ .

# Division by 3

## Basic idea

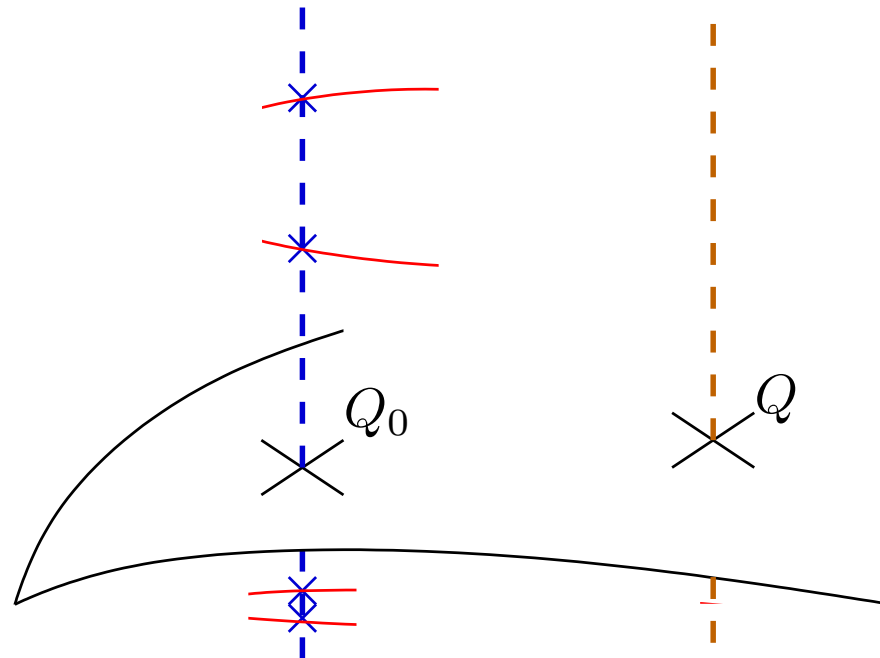
- The system  $[3]P = Q$  is parametrized by the coordinates of  $Q$ .
- Set up a homotopy between the target  $[3]P = Q$  and an initial system  $[3]P_0 = Q_0$  for which we know the solutions  
basically, we let  $Q_t = (1 - t)Q_0 + tQ$ .
- Compute a description of the solution curve and let  $t = 1$ .



# Division by 3

## Basic idea

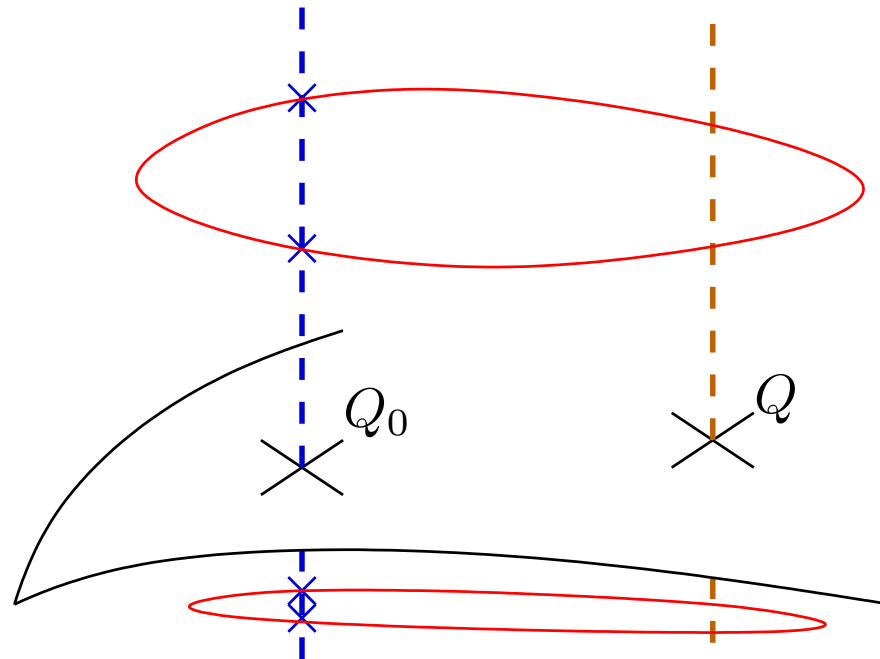
- The system  $[3]P = Q$  is parametrized by the coordinates of  $Q$ .
- Set up a homotopy between the target  $[3]P = Q$  and an initial system  $[3]P_0 = Q_0$  for which we know the solutions  
basically, we let  $Q_t = (1 - t)Q_0 + tQ$ .
- Compute a description of the solution curve and let  $t = 1$ .



# Division by 3

## Basic idea

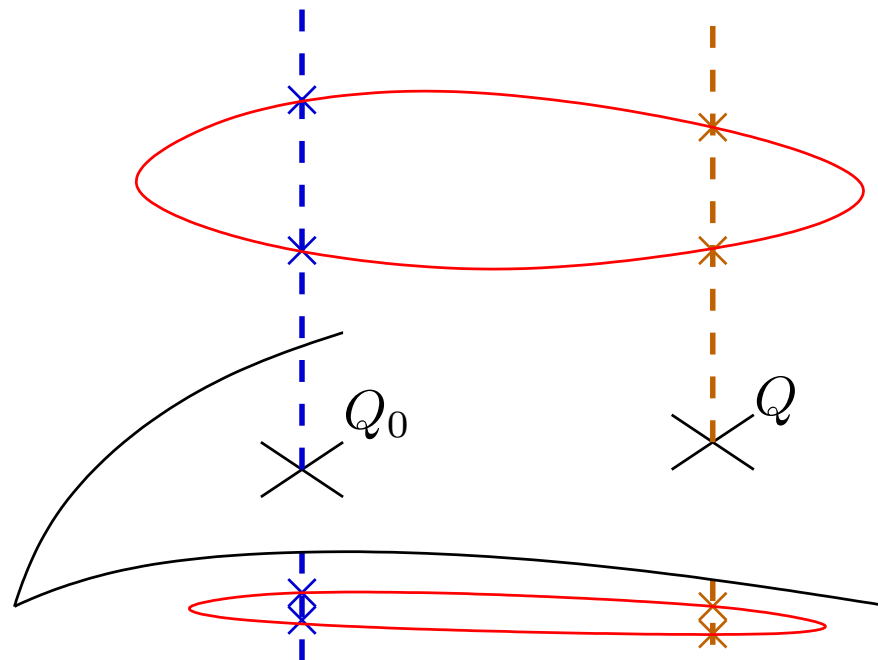
- The system  $[3]P = Q$  is parametrized by the coordinates of  $Q$ .
- Set up a homotopy between the target  $[3]P = Q$  and an initial system  $[3]P_0 = Q_0$  for which we know the solutions  
basically, we let  $Q_t = (1 - t)Q_0 + tQ$ .
- Compute a description of the solution curve and let  $t = 1$ .



# Division by 3

## Basic idea

- The system  $[3]P = Q$  is parametrized by the coordinates of  $Q$ .
- Set up a homotopy between the target  $[3]P = Q$  and an initial system  $[3]P_0 = Q_0$  for which we know the solutions  
basically, we let  $Q_t = (1 - t)Q_0 + tQ$ .
- Compute a description of the solution curve and let  $t = 1$ .

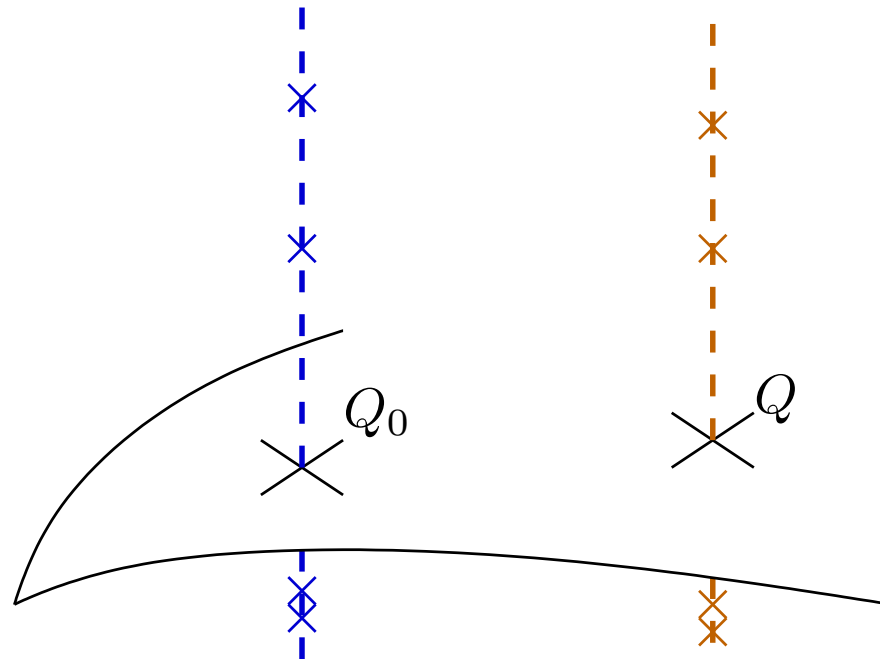




# Division by 3

## Basic idea

- The system  $[3]P = Q$  is parametrized by the coordinates of  $Q$ .
- Set up a homotopy between the target  $[3]P = Q$  and an initial system  $[3]P_0 = Q_0$  for which we know the solutions  
basically, we let  $Q_t = (1 - t)Q_0 + tQ$ .
- Compute a description of the solution curve and let  $t = 1$ .



# Concretely

General idea: as in Pardo-San Martin; Matera et al.

## 1. Evaluation properties

- nice straight-line program for multiplication by 3.

## 2. Action of the 3-torsion

- branches are conjugate: lift only one branch.

## 3. Local $\rightarrow$ global

- rational interpolation.

## 4. Subgroups of the 3-torsion

- easier factorization.

# The nice straight-line program

```
ZZ_pEX DT141=-tmp14c+MulTrunc(tmp14b, DT91+DT101, k)-DT121-DT131;
ZZ_pEX DT142=2*MulTrunc(tmp14b, DT61-1, k)-2*v1-DT132;
ZZ_pEX DT143=MulTrunc(-u1-1, tmp14a, k) -2*MulTrunc(tmp14b, v1, k)+T9-DT133;
ZZ_pEX DT144=tmp14a-T10;
ZZ_pEX T15=(T14-MulTrunc(T12, u1, k))/2;
ZZ_pEX DT151=(DT141-MulTrunc(DT121, u1, k)-T12)/2;
ZZ_pEX DT152=DT142/2-u1v1;
ZZ_pEX DT153=(DT143+MulTrunc(T9, u1, k))/2;
ZZ_pEX T16=(T13-MulTrunc(T12, u0, k))/2;
ZZ_pEX DT161=(DT131-MulTrunc(DT121, u0, k))/2;
ZZ_pEX DT162=(DT132-T12)/2-u0v1;
ZZ_pEX DT163=(DT133+MulTrunc(T9, u0, k))/2;
ZZ_pEX T17=-MulTrunc(DT61, T4, k)-2*MulTrunc(T15, v1, k);
ZZ_pEX DT171=MulTrunc(DT61, T3, k)-2*(T4+MulTrunc(DT151, v1, k));
ZZ_pEX DT172=-MulTrunc(DT61, T1, k)-2*MulTrunc(DT152, v1, k);
ZZ_pEX DT173=-MulTrunc(DT61, DT43, k)-2*(MulTrunc(DT153, v1, k)+T15);
ZZ_pEX DT174=-MulTrunc(DT61, DT44, k)-tmp14c+tmp13a;
ZZ_pEX T18=SqrTrunc(T15, k);
ZZ_pEX DT181=2*MulTrunc(T15, DT151, k);
ZZ_pEX DT182=2*MulTrunc(T15, DT152, k);
ZZ_pEX DT183=2*MulTrunc(T15, DT153, k);
ZZ_pEX DT184=MulTrunc(T15, DT144, k);
ZZ_pEX T19=SqrTrunc(T16, k);
ZZ_pEX DT191=2*MulTrunc(T16, DT161, k);
ZZ_pEX DT192=2*MulTrunc(T16, DT162, k);
ZZ_pEX DT193=2*MulTrunc(T16, DT163, k);
```

```

ZZ_pEX DT194=MulTrunc(T16, T10, k);
ZZ_pEX tmp20a=T15+T16;
ZZ_pEX T20=SqrTrunc(tmp20a, k)-T18-T19;
ZZ_pEX DT201=2*MulTrunc(tmp20a, DT151+DT161, k)-DT181-DT191;
ZZ_pEX DT202=2*MulTrunc(tmp20a, DT152+DT162, k)-DT182-DT192;
ZZ_pEX DT203=2*MulTrunc(tmp20a, DT153+DT163, k)-DT183-DT193;
ZZ_pEX DT204=MulTrunc(tmp20a, DT144+T10, k)-DT184-DT194;
ZZ_pEX T21=T20-SqrTrunc(T4, k);
ZZ_pEX DT211=DT201+2*MulTrunc(T4, T3, k);
ZZ_pEX DT212=DT202-2*MulTrunc(T4, T1, k);
ZZ_pEX DT213=DT203-2*MulTrunc(T4, DT43, k);
ZZ_pEX DT214=DT204-2*MulTrunc(T4, DT44, k);
ZZ_pEX T22=T19-MulTrunc(T17, T4, k);
ZZ_pEX DT221=DT191+MulTrunc(T17, T3, k)-MulTrunc(T4, DT171, k);
ZZ_pEX DT222=DT192-MulTrunc(T17, T1, k)-MulTrunc(T4, DT172, k);
ZZ_pEX DT223=DT193-MulTrunc(T17, DT43, k)-MulTrunc(T4, DT173, k);
ZZ_pEX DT224=DT194-MulTrunc(T17, DT44, k)-MulTrunc(T4, DT174, k);
ZZ_pEX T23=u1*Eu1;
ZZ_pEX T24 =u0 - T23 + Eu1Eu1 - Eu0;
ZZ_pEX tmp25=T24-Eu0;
ZZ_pEX tmp25b=Eu0*u1;
ZZ_pEX T25=MulTrunc(u0, tmp25, k) + Eu0*(SqrTrunc(u1, k)-T23+Eu0);
ZZ_pEX DT251=-u0*Eu1+2*tmp25b-Eu0Eu1;
ZZ_pEX DT252=tmp25+u0;
ZZ_pEX T26=Ev1+v1;
ZZ_pEX T27=Ev0+v0;
ZZ_pEX T28=ff4-u1;

```

## Results

task	time in sec.	bottleneck
$\ell = 2^{17}$	348,008	modular composition
$\ell = 3^7$	126,720	lifting / interpolation
		polynomial too large for FFT
$\ell = 5^4$	235,713	bivariate resultants
$\ell = 7^2$	95,975	bivariate resultants
$\ell = 11, \dots, 31$	2,242,185	bivariate resultants
		memory becomes a problem
kangaroos	7300	
total	3,055,901 $\approx$ 1 month	

We expect to test about **10000** curves before finding a suitable one.

Should take about **100 CPU years**.