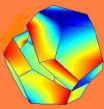


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Hessians in INTLAB, the Matlab toolbox for verified computations

Siegfried M. Rump, Hamburg





new book:

- F. Bornemann, D. Laurie, S. Wagon, J. Waldvogel:

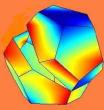
The SIAM 100-Digit Challenge,
A Study in High-Accuracy Numerical Computing,
SIAM, Philadelphia 2004.

In 5 out of 10 chapters solutions are presented using INTLAB (our interval Matlab toolbox).



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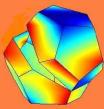
... Various ingredients needed ...

[Matlab operator concept, Interval library,
self-validating methods, gradients/Hessians,
validated standard functions, input/output ...]



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Matlab V5+ Operator concept

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```
polynom p'  
[list1 list2]  
q\stack  
R * intval(A)  
y = f(hessianinit(x));  
x = x - y.hx \ y.dx'
```

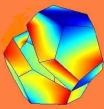
directory @hessian

operators plus, mtimes, transpose, display, ...



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Objectives for Interval library

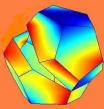
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- portability - from PC to supercomputer
and parallel computer
- only 1 code - no special versions
- suitable for compilation and interpretation
- no special hardware
- fast



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Computation with sets - Intervals (Sunaga '58)

$$A = [\underline{a}, \bar{a}] := \{x \in \mathbb{R} : \underline{a} \leq x \leq \bar{a}\} \in \text{IIR}$$

$$A \circ B := \bigcap \{C \in \text{IIR} : \forall a \in A \ \forall b \in B : a \circ b \in C\}$$

for $\circ \in \{+, -, \cdot, /\}$

well known rules

$$[\underline{a}, \bar{a}] + [\underline{b}, \bar{b}] = [\underline{a} + \underline{b}, \bar{a} + \bar{b}]$$

...

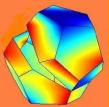
Inclusion isotonicity

$$\forall a \in A \quad \forall b \in B : \quad a \circ b \in A \circ B$$



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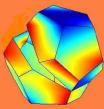
$\begin{pmatrix} [\underline{x_1}, \overline{x_1}] \\ \vdots \\ [\underline{x_n}, \overline{x_n}] \end{pmatrix} \in (\mathbb{IIR})^n \cong \mathbb{IIR}^n$, similarly $\mathbb{IIR}^{n \times n}$

$(A \cdot B)_{ij} := \sum_k A_{ik} \cdot B_{kj}$ with interval $+, \cdot$



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Arithmetical issues (IEEE 754, 1984)

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\mathbb{F} Floating point numbers including $\pm\infty$

- rounding to nearest
- rounding downwards
- rounding upwards

$$\forall a, b \in \mathbb{F} \quad \forall \circ \in \{+, -, \cdot, /\}$$

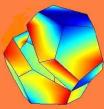
$$\nabla(a \circ b) = \max\{x \in \mathbb{F} : x \leq a \circ b\}$$

$$\Delta(a \circ b) = \min\{x \in \mathbb{F} : a \circ b \leq x\}$$



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Intervals using floating point numbers

$A = [\underline{a}, \bar{a}] := \{x \in \mathbb{R} : \underline{a} \leq x \leq \bar{a}\} \in \text{IIF}$ for $\underline{a}, \bar{a} \in \text{IF}$

$A \circ B := \bigcap\{C \in \text{IIF} : \forall a \in A \quad \forall b \in B : a \circ b \in C\}$
for $\circ \in \{+, -, \cdot, /\}$

well known rules

$$[\underline{a}, \bar{a}] + [\underline{b}, \bar{b}] = [\nabla(\underline{a} + \underline{b}), \Delta(\bar{a} + \bar{b})]$$

...

...

...

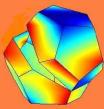
Inclusion isotonicity

$$\forall a \in A \quad \forall b \in B : a \circ b \in A \circ B$$



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$$\begin{pmatrix} [\underline{x}_1, \overline{x}_1] \\ \vdots \\ [\underline{x}_n, \overline{x}_n] \end{pmatrix} \in (\mathbb{IF})^n \cong \mathbb{IF}^n, \text{ similarly } \mathbb{IF}^{n \times n}$$

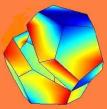
$$(A \cdot B)_{ij} := \sum_k A_{ik} \cdot B_{kj} \text{ with interval } +, \cdot$$

Valid bounds for the range of n -dimensional functions over a real box using only floating point operations



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Bounds for the range of a function

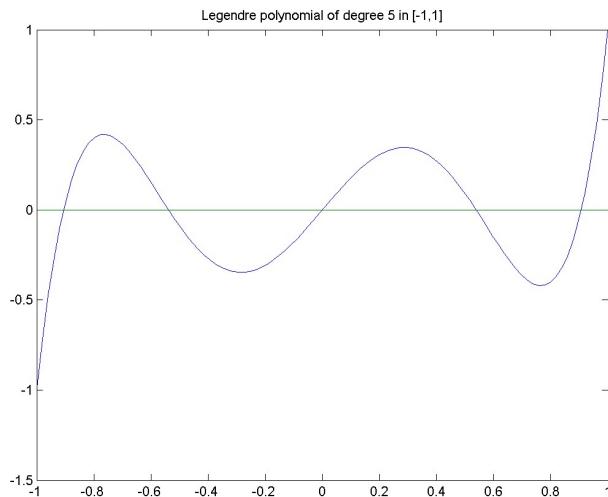
Legendre polynomial

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```
n = 5, P = legendre(n)
```

over $-1 \leq x \leq 1$

```
polynom P[x] =  
    7.8750 x^5  
   -8.7500 x^3  
    1.8750 x
```

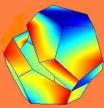


```
>> X = infsup(-1,1); P{X}  
  
intval ans =  
[ -18.5001, 18.5001]
```



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Bounds for the range of a function

Griewank function

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```
G = inline(' (x^2+y^2)/4000+cos(x)*cos(y)/sqrt(2)+1')
```

over $-60 \leq x, y \leq 60$

2000 meshpoints in each coordinate:

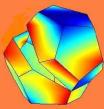
upper bound for minimum $\min(G(x,y)) \leq 0.2957$

```
>> X = infsup(-60,60); Y = X; G(X,Y)  
intval ans =  
[ 0.2928, 3.5072]
```



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A simple self-validating method

$f : \mathbb{IR}^n \rightarrow R^n \in C^1$, $\tilde{x} \in \mathbb{IR}^n$ with $f(\tilde{x}) \approx 0$

Compute bounds for $\hat{x} \approx \tilde{x}$ with $f(\hat{x}) = 0$.

$$f(x) = 0 \Leftrightarrow g(x) = x,$$

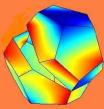
where $g(x) := x - R \cdot f(x)$, $\det R \neq 0$.

$$\begin{aligned} X \in \mathbb{IR}^n, g(X) \subseteq X &\xrightarrow{\text{Brouwer}} \exists \hat{x} \in X : g(\hat{x}) = \hat{x} \\ &\Rightarrow f(\hat{x}) = 0 \end{aligned}$$

Check $g(X) \subseteq X$ and prove $\det R \neq 0$.

Naive approach:

$$g(X) \subseteq X - R \cdot f(X) \not\subseteq X$$



Bounds for the solution of nonlinear systems

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Prove $g(X) = \{x - R \cdot f(x) : x \in X\} \subseteq X$

$$\begin{aligned} g(x) &= g(\tilde{x}) + M \cdot (x - \tilde{x}) \\ &\quad \text{where } M_i = \frac{\partial g}{\partial x}(\zeta_i), \quad \zeta_i \in x \cup \tilde{x} \\ &= \tilde{x} - R \cdot f(\tilde{x}) + \{I - R \cdot M\}(x - \tilde{x}) \\ &\subseteq \tilde{x} - R \cdot f(\tilde{x}) + \{I - R \cdot M\}(X - \tilde{x}) \\ &=: K_f(\tilde{x}, X) \quad \text{Krawczyk operator} \end{aligned}$$

Theorem. $\tilde{x} \in X$ and $K_f(\tilde{x}, X) \subseteq \text{int}(X)$

$\Rightarrow \exists! \hat{x} \in X : f(\hat{x}) = 0.$

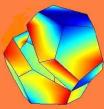
Computation of M by automatic differentiation

Fast matrix operations



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Gradients

- Standard forward mode
- Sparse storage scheme

```
>> G = inline(' (x^2+y^2)/4000+cos(x)*cos(y)/sqrt(2)+1')
```

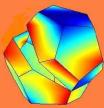
```
>> X = gradientinit([2;3]); G(X(1),X(2))
gradient value ans.x =
1.29456543963867
gradient derivative(s) ans.dx =
0.63753584839404    0.04302600886466
```

```
>> X = gradientinit(midrad([2;3],1e-10)); G(X(1),X(2))
intval gradient value ans.x =
1.294565440_____
intval gradient derivative(s) ans.dx =
0.6375358484____ 0.0430260089_____
```



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Hessian

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- Standard forward mode
- Sparse storage scheme

Model Problem 61 (Conn, Gould, Lescrenier, Toint), Princeton:

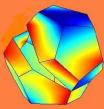
```
N = length(x); % model problem: N = 1000, initial x=ones(N,1);
I = 1:N-4;
y = sum( (-4*x(I)+3.0).^2 ) + sum( ( x(I).^2 + 2*x(I+1).^2 + ...
3*x(I+2).^2 + 4*x(I+3).^2 + 5*x(N).^2 ).^2 );
```

size (x.x) N elements
size (x.dx) N^2 elements
size (x.hx) N^3 elements



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Hessian storage scheme

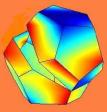
one possibility: symmetric

but not supported by Matlab

INTLAB: $a.hx$ stored $\Rightarrow a.hx + a.hx^T$ is Hessian

Example:

$$(a * b).hx = a.hx * b.x + a.dx * b.dx + a.x * b.hx$$

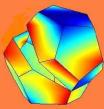


Matrix multiplication $C=R*A$

top-down approach (inner loop: single operations)

```
for i=1:n
    for j=1:n
        for k=1:n
            if R(i,k)>=0
                SetRoundDown
                Cinf(i,j)=Cinf(i,j)+R(i,k)*Ainf(i,k);
                SetRoundUp
                Csup(i,j)=Csup(i,j)+R(i,k)*Asup(i,k);
            else
                SetRoundDown
                Cinf(i,j)=Cinf(i,j)+R(i,k)*Asup(i,k);
                SetRoundUp
                Csup(i,j)=Csup(i,j)+R(i,k)*Ainf(i,k);
            end
        end
    end
end
```

Problem: inner loop not at all optimizable



Midpoint-radius arithmetic Timing - Convex SPP 200

Compiled C-code [sec]

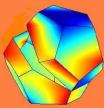
R*[A]	n=200	n=500	n=1000
top-down	2.48	71.4	570.4
new	0.07	1.7	12.3

[A]*[B]	n=200	n=500	n=1000
top-down	2.40	72.3	613.6
new	0.17	3.3	20.2



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Matrix multiplication $C=R*[A]$

Matlab Timing (interpreted code):
 $n=50$, 120 Mhz Pentium

top-down 126 sec

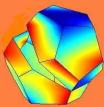
new 0.06 sec

Details in S.M. Rump: Fast and parallel interval arithmetic. BIT, 39(3):539–560, 1999



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Verified solution of linear systems: INTLAB timing

Solution of $Ax=b$, full matrix, randomly generated

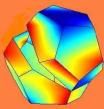
n	INTLAB		
	built-in Matlab	point data	interval data
1000	2.8 s	20.2 s	22.3 s

Coconut example for $n=1000$,
one Newton step, x_s approximate minimum

```
>> tic,y.hx\y.dx';toc                                approximate solution  
Elapsed time is 0.451000 seconds.
```

```
>> tic,verifylss(y.hx,y.dx');toc      verified inclusion  
Elapsed time is 0.471000 seconds.
```





Rigorous standard functions: properties

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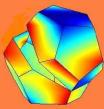
- portability (pure Matlab code)
- $\lesssim 3$ ulp accuracy over entire floating point range
- absolutely rigorous

Details in S.M. Rump: Rigorous and portable standard functions. BIT, 41(3):540–562, 2001



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```
>> intvalinit('displayinfsup')
f=inline('x^2-2'), x=infsup(1,2) for i=1:4
    y=f(gradientinit(x)); x=intersect(x,x.mid-f(x.mid)/y.dx)
end
```

====> Default display of intervals by infimum/supremum
(e.g. [3.14 , 3.15])

```
f =
    Inline function:
```

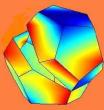
```
    f(x) = x^2-2
```

```
intval x = [ 1.000000000000000, 2.00000000000000]
intval x = [ 1.374999999999999, 1.437500000000001]
intval x = [ 1.414062499999999, 1.41441761363637]
intval x = [ 1.41421355929452, 1.41421356594718]
intval x = [ 1.41421356237309, 1.41421356237310]
```



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```
>> intvalinit('display_')
f=inline('x^2-2'), x=infsup(1,2) for i=1:4
    y=f(gradientinit(x)); x=intersect(x,x.mid-f(x.mid)/y.dx)
end
```

====> Default display of intervals with uncertainty (e.g. 3.14_)

```
f =
```

 Inline function:

```
    f(x) = x^2-2
```

```
intval x =
```

```
    2.-----
```

```
intval x =
```

```
    1.4-----
```

```
intval x =
```

```
    1.414-----
```

```
intval x =
```

```
    1.41421356-----
```

```
intval x =
```

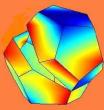
```
    1.41421356237309
```

```
>>
```



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Why self-validating methods:

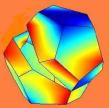
Correct answer or error message

What are the eigenvalues of the following 7×7 matrix?

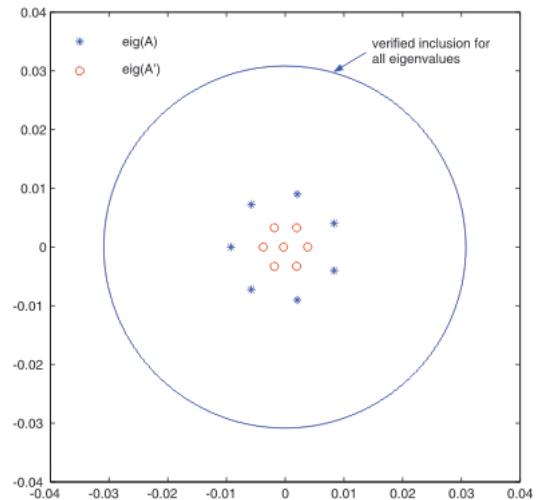
A =

3.2704	4.2268	-2.9925	2.5902	-0.1306	1.3495	0.4708
2.7041	0.9369	-0.7639	2.9434	1.1338	-0.5135	-1.2424
2.6288	2.7926	-1.1863	2.4664	-0.4605	0.9760	-1.1777
-5.3920	-3.9846	3.7885	-5.2513	-2.7607	0.2610	0.0214
3.3226	0.8233	-1.1560	3.3884	2.0575	-0.3869	-1.1942
-0.4403	-0.9826	0.4109	-0.3525	0.2232	-1.0126	-0.2296
-1.3145	1.8579	-0.4431	-1.6898	-1.9447	1.6597	1.1853





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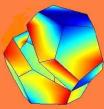


no warning!



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Programming robustness

- Construct problem with integer entries and known solution, e.g. π
- A programming error may produce

[3.141592653589792, 3.141592653589793]

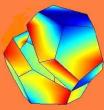
Floating point approximations of superb quality.

The bounds coincide to 16 decimal places
but are **WRONG!**



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INTLAB Highlights

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- all basic real and complex interval operations
- fast and rigorous real and complex standard functions
- gradient toolbox
- hessian toolbox
- slope toolbox
- polynomial toolbox
- multiple precision toolbox (slow)

25 KLOC (pure Matlab), > 600 routines

some 3500 users in more than 40 countries

free from <http://www.ti3.tu-harburg.de>



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