

## Developments in the MAD package

Shaun Forth

Cranfield University (Shrivenham Campus)  
S.A.Forth@cranfield.ac.uk

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# Outline

- 1 MAD's Forward Mode [For04]
- 2 Differentiating Object-Oriented Code
- 3 Integration into TOMLAB
- 4 Sparse Matrices
- 5 Roadmap & Conclusions
- 6 References

## Present MAD Release Contains

- `fmad` class - forward mode AD by operator overloading
- `derivvec` class - for storage and combination of multiple directional derivatives.
- `madutil` - directory of utility functions
- `madrecode` - directory of recoded MATLAB functions
- `usefulbits` - directory with sample `startup.m` initialisation file

## fmad class constructor

- e.g. `x=fmad([1.1 2 3],[4 5 6]);`
- Defines fmad object with
  - value component - row vector [1.1 2 3]
  - deriv component - single directional derivative [4 5 6]
- Perform overloaded operations, e.g., element-wise multiplication via `times`

```
z=x.*x
```

```
value =
```

```
    1.2100    4.0000    9.0000
```

```
derivatives =
```

```
    8.8000   20.0000   36.0000
```

## fmad class times function for $z=x.*y$

```
function z=times(x,y)
% FUNCTION: TIMES
% SYNOPSIS: elemental multiplication z=x.*y of one or more
if isa(x,'fmad')&isa(y,'fmad')
    z.value=x.value.*y.value;
    z.deriv=y.value.*x.deriv+x.value.*y.deriv;
elseif isa(x,'fmad')
    z.value=x.value.*y;
    z.deriv=y.*x.deriv;
else
    z.value=x.*y.value;
    z.deriv=x.*y.deriv;
end
z=class(z,'fmad');
```

## Working with multiple directional derivatives

- What if we want the Jacobian?
- Seed derivatives with identity  $\mathbf{I}_3$   
`x=fmad([1.1 2 3],eye(3));`
- Overloaded operation with **same times** function gives

value =

1.2100      4.0000      9.0000

Derivatives

Size = 1 3

No. of derivs = 3

derivs(:, :, 1) = 2.2000                      0                      0

derivs(:, :, 2) =            0            4            0

derivs(:, :, 3) =            0            0            6

## The fmad and derivvec classes

```
function xad=fmad(x,dx)
% FUNCTION: FMAD
% SYNOPSIS: Class constructor for forward Matlab AD objects
xad.value=x;
sx=size(xad.value);
sd=size(dx);
    if prod(sx)==prod(sd)
        xad.deriv=reshape(dx,sx);
    else
        xad.deriv=derivvec(dx,size(xad.value));
    end
```

If number of elements of supplied derivatives and value don't match then pass derivatives and value's size to derivvec

## The derivvec class

- Store derivatives as a matrix with each directional derivative "unrolled" into a column.
- e.g. `derivvec(eye(3), [1 3])` derivatives stored as,

$$\begin{bmatrix} \text{direc 1} & \text{direc 2} & \text{direc 3} \\ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} & \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} & \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



## The times operation of the derivvec class

- e.g. Need to calculate,

$$\begin{bmatrix} 1.1 & 2 & 3 \end{bmatrix} .* \begin{bmatrix} \text{direc 1} & \text{direc 2} & \text{direc 3} \\ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} & \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} & \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{bmatrix}$$

with multiplication of each of the 3 directional derivatives.

- Convert value to column matrix and replicate 3 times

$$\begin{bmatrix} 1.1 & 1.1 & 1.1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{bmatrix} .* \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1.1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

columns give required directional derivatives.

## Accessor Functions

- Getting the value

```
getvalue(z)
```

```
ans =
```

```
    1.2100    4.0000    9.0000
```

- Getting "external representation" of derivatives

```
getderivs(z)
```

```
ans(:, :, 1) =
```

```
    2.2000    0    0
```

```
ans(:, :, 2) =
```

```
    0    4    0
```

```
ans(:, :, 3) =
```

```
    0    0    6
```

## Accessor Functions (ctd)

- Getting unrolled internal representation

```
>> getinternalderivs(z)
```

```
ans =
```

```
2.2000    0    0  
0    4.0000    0  
0    0    6.0000
```

## madutil functions

e.g.

- `getvalue`, `getderivs`, `getinternalderivs` for objects of class `double`.
- High-level interface functions for use in stiff ODE and optimisation solvers [FK04].
- `MADcolor`, `MADgetseed` and `MADgetcompressedJac` for colouring (row compression) a sparse Jacobian, generating the seed matrix and "uncompressing" the compressed Jacobian.

# madrecode functions

Used for 2 reasons

- 1: Builtin MATLAB function is too complicated to manipulate its value and derivative components e.g. `filter` function
  - Code as MATLAB to let `fmad` differentiate it directly
  - Place in `madrecode` directory e.g. `madrecode/filter_mad`
  - Create `fmad` class function `filter` to call `filter_mad`
- 2: MATLAB supplied function not differentiable by `fmad`
  - Usually due to assignment of `fmad` object to part of double array e.g. `splncore`
  - Place copy of MATLAB function in `madrecode` directory e.g. `madrecode/splncore_mad`
  - Edit to ensure `fmad` can differentiate it
  - Create `fmad` class function `splncore` to call `splncore_mad`

## Differentiating Object-Oriented Code

- User's code with classes, objects, overloaded operations?
- e.g., polynomials  $p_1 = x^3 + 2x^2 + 3x + 4$  and  $p_2 = 3x + 4$  and  $p_3 = a_1 * p_1 + a_2 * p_2$  via polynom objects

```
a1=1; a2=2; x=1;
```

```
p1=polynom([1 2 3 4]); % class constructor call
```

```
p2=polynom([3 4]); % class constructor call
```

```
p3=a1*p1+a2*p2 % overloaded arithmetic
```

```
y=polyval(p3,x) % accessor function
```

- and gives

```
p3 = x^3 + 2*x^2 + 9*x + 12
```

```
y = 24
```

## Jacobian w.r.t. $a_1, a_2$

- Set derivatives of  $a_1, a_2$  to be rows of  $I_2$

```
a1=fmad(1,[1 0]); a2=fmad(2,[0 1]);
```

```
...
```

```
p3=a1*p1+a2*p2;
```

- Gives error

```
??? Function 'times' is not defined for values of class
```

```
Error in ==> times at 18
```

```
    [varargout{1:nargout}] = builtin('times', varargin{:})
```

```
Error in ==> fmad.mtimes at 38
```

```
    z.value=xval.*y;
```

- In  $a_1*p_1$  since first object is `fmad` then uses `fmad mtimes` operation.

## Setting object precedence

- Must use polynom class operations ahead of fmad ones.
- Modify polynom class constructor

```
function p = polynom(a)
% some coding removed
    p.c = a(:).';
    p = class(p, 'polynom');
    superiorto('fmad') % added this line
```

- Now we get

```
p3=a1*p1+a2*p2; y=polyval(p3,x)
value = 24
Derivatives
Size = 1  1 No. of derivs = 2
derivs(:, :, 1) = 10
derivs(:, :, 2) = 7
```



## Object-oriented code

- Technique of overloading user's objects or AD library objects used by other AD tools e.g. C++ templating in FADBAD [BS96].
- Success with `fmad` in differentiating one industrial application from chemical industry involving 6 classes.
- Need graceful exception handling.

# TOMLAB

- TOMLAB [HE04, HGE04] is general purpose development environment in MATLAB for solution of optimisation problems.
- TOMLAB supplies:
  - MATLAB-coded solver algorithms
  - State-of-the-art optimisation software e.g., SNOPT [GMS05]
  - External solvers are distributed as compiled MEX files.
- MAD distributed as package [FE04] - single user academic license \$110 + \$22 / year support/upgrade

# Integration into TOMLAB

- Integration performed by Kenneth Holmström and Marcus Edvall of TOMLAB
- Always uses `fmad`'s forward mode with sparse storage of derivatives
  - No need for sparsity pattern to be supplied or calculated.
  - Good performance over a wide range of problem sizes
- If user supplies gradient code then `fmad` can calculate the Hessian.
- For the user everything is **automatic** (provided it works!)

## The Brown Problem

$$\text{minimise } f(\mathbf{x}) = \sum_{i=1}^{n-1} \left[ (x_i^2)^{x_{i+1}^2+1} + (x_{i+1}^2)^{x_i^2+1} \right],$$

with  $n = 1000$  and  $x_0 = [-1, 1, -1, 1, \dots, 1]$  and supplied Hessian sparsity pattern.

## Coding

```
load brownhstr; % Hessian sparsity pattern
n=1000; x_0=-ones(n,1); x_0(2:2:n,1)=1;
% set up TOMLAB Problem specification for FD
Prob = conAssign('brownf', [], [], Hstr, [], [], ...
                'Brown Problem', x_0);
disp('Using FD gradient')
ResultFD=tomRun('ucsolve', Prob, [], 2);
% now use AD
Prob.ADObj=1; % turns on AD for 1st derivatives
disp('Using AD gradient')
ResultAD=tomRun('ucsolve', Prob, [], 2);
```

## Results

Using BFGS algorithm with default convergence conditions on Pentium IV laptop

Derivative Technique	Nonlinear Iterations	CPU time (s)
FD	7	26.1
fmad(sparse)	7	4.0

## Sparse Matrices

- Sparse matrices are intrinsic to MATLAB
- Created by sparse function,

```
S = sparse([3 2 3 4 1],[1 2 2 3 4],[1 2 3 4 5],4,4)
```

```
S =
```

```
(3,1)      1
```

```
(2,2)      2
```

```
(3,2)      3
```

```
(4,3)      4
```

```
(1,4)      5
```

- fmad uses sparse objects to store derivatives.
- Only recently enabled fmad to possess sparse values.

## Dropping Problem

```
>> x=[3;4]; % create values
>> s=sparse([1;2],[1;2],x,2,2) % diagonal matrix
s = (1,1)      3
     (2,2)      4
>> s(1,1)=s(1,1)-3 % subtract 3 from element 1,1
s =
     (2,2)      4 % element is dropped
>> [i,j,val]=find(s) % find nonzero elements
i = 2    j = 2    val = 4
```

The zero value is **dropped**



## Differentiating the dropping problem

```
>> x=fmad([3;4],speye(2));  
>> s=sparse([1;2],[1;2],x,2,2);  
>> s(1,1)=s(1,1)-3;  
>> [i,j,val]=find(s);
```

Warning: value and derivatives have different sparsity

> In fmad.find at 54

```
>> getvalue(i) = [1 2]'  
>> getvalue(j) = [1 2]'  
>> getvalue(val) = [0 4]'  
>> getinternalderivs(val) =  
    (1,1)      1  
    (2,2)      1
```

Return zero values where we have nonzero derivatives.

- Similar to **branching problem** defining  $y = f(x) = x$  by

```
if x==0
    y=0
else
    y=x
end
```

for which AD gives  $dy/dx = 0$  for  $x = 0$ .

- **Dropping problem**: for each element  $x_{ij}$  of the sparse matrix

```
if x(i,j)==0
    storage for x(i,j) is removed
end
```

- But fmad does not remove corresponding  $\nabla x_{ij}$  (unless zero).
- Ramifications for reverse mode!

# Roadmap

## MAD

- Improve documentation.
- Complex valued functions w.r.t real dependents [PBC95]-engineering analysis.
- Reverse mode

## MSAD

- Source transformation extension of MAD
- Uses optimised derivative operations of `fmad/derivvec`
- But with further efficiency advantages of source-transformation
- See Rahul Kharche's talk

# Conclusions

- `fmad/derivvec` classes provide easy to use, efficient implementation of forward mode AD for first derivatives.
- Can handle coding of some complexity e.g. response surface fitting [RF04], racing car trajectory optimisation [Bra04], nonlinear control [CAS03].
- It appears users' object oriented code can be easily differentiated
- Robust enough to be commercially distributed

# The 2<sup>nd</sup> European AD Workshop

- Thursday November 17<sup>th</sup> – Friday November 18<sup>th</sup>
- Whitworth Conference Centre  
Royal Military College of Science  
Cranfield's Shrivenham Campus  
Shrivenham, Swindon  
Oxfordshire, UK
- 20 miles south of Oxford, 40 miles west of Heathrow
- Special sessions: AD in computational engineering, + ?
- Enquiries:
  - Admin [amor@rmcs.cranfield.ac.uk](mailto:amor@rmcs.cranfield.ac.uk)
  - Programme [S.A.Forth@cranfield.ac.uk](mailto:S.A.Forth@cranfield.ac.uk)



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