

# Title of Your Document

First Author and Second Author

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**Key words:** first keyword, second keyword.

## 1 Introduction

Your text comes here ...



**Fig. 1** A sample figure.

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## 2 Preliminaries

This sentence shows how to refer to Figure 1 in Section 1. Referring to tables is equally simple: Table 1.

**Table 1** This is an example of a table.

Longitude	Latitude	Roll
0	0	0
50	20	-30
110	50	-40

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\bibliographystyle{smpsci}
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```

at the end of your document. As a usage example, we refer to the proceedings of ARK 2012 [2] and to Denavit Hartenberg [1].

## References

1. Denavit, J., Hartenberg, R.S.: A kinematic notation for lower pair mechanisms based on matrices. *ASME Journal of Applied Mechanics* **22**(2), 215–221 (1955)
2. Lenarčič, J., Husty, M.L. (eds.): *Latest Advances in Robot Kinematics*. Springer (2012). DOI 10.1007/978-94-007-4619-0