

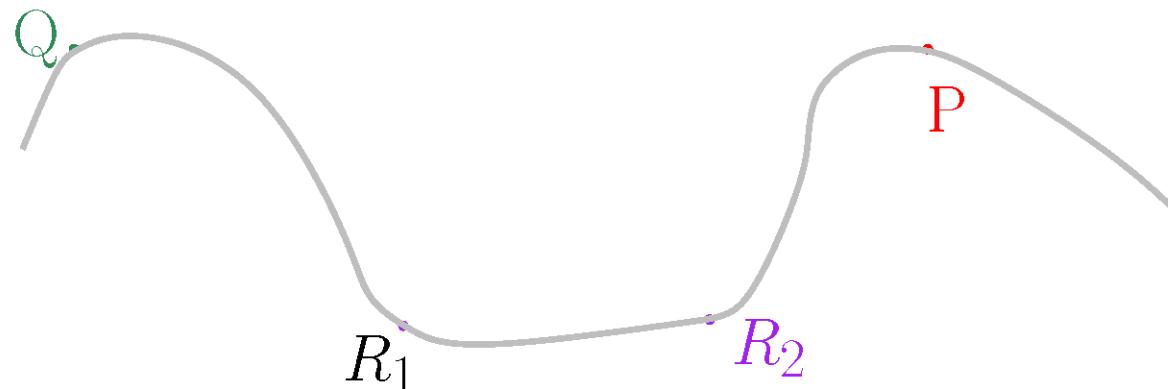
# TANGENTIAL DELAUNAY COMPLEXES IN PRACTICE

Clément Jamin  
Marc Glisse  
Jean-Daniel Boissonnat

# THE TANGENTIAL DELAUNAY COMPLEX

## ❖ Reconstructing manifolds from point clouds

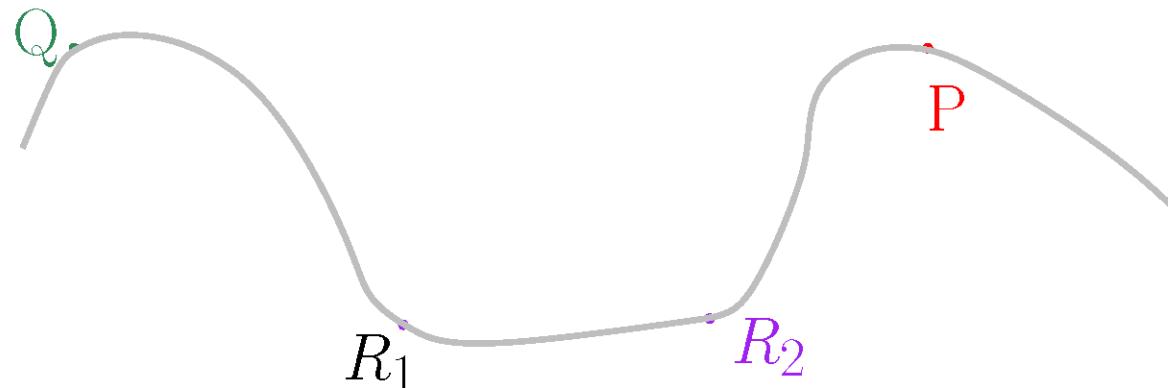
- Geometrization : Data = points + distances between points
- Hypothesis : Data lie close to a structure of “small” intrinsic dimension
- Problem : Infer the structure from the data



# THE TANGENTIAL DELAUNAY COMPLEX

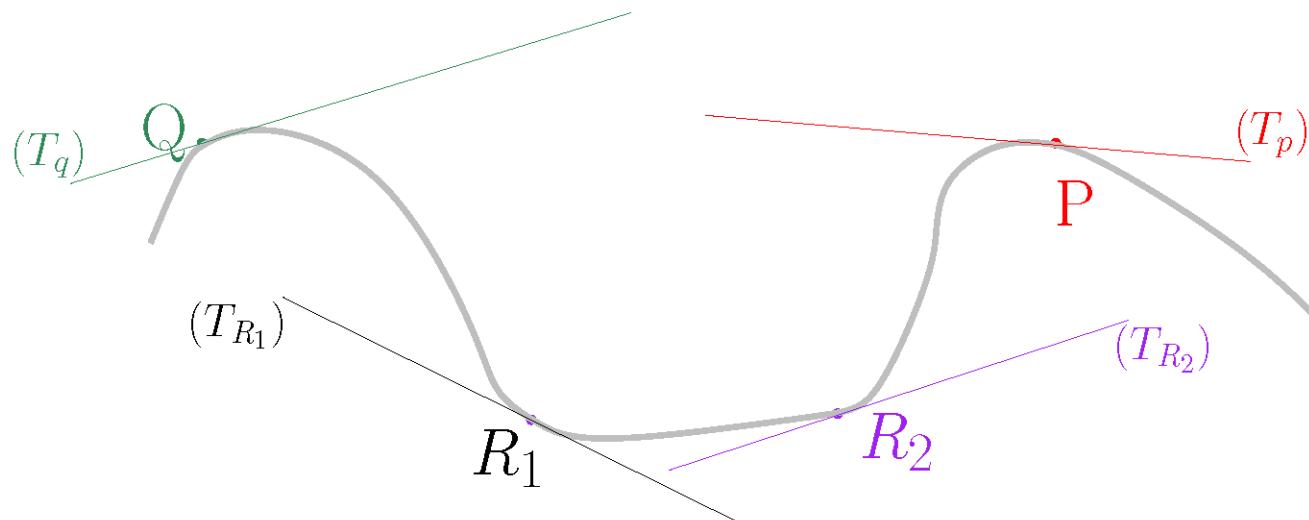
## ❖ Reconstructing manifolds from point clouds

- Input: point samples coming from an unknown manifold
- Goal: reconstruct a  $k$ -dimensional smooth manifold embedded in  $d$ -dimensional Euclidian space



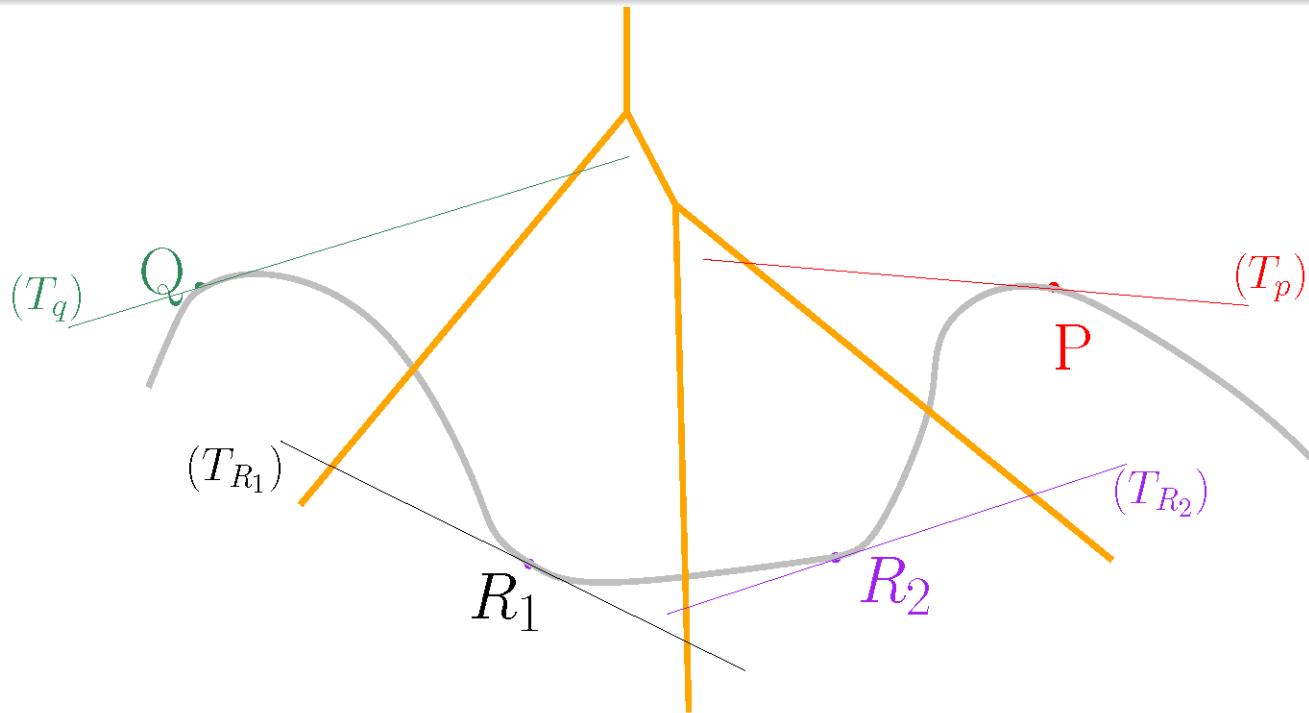
# THE TANGENTIAL DELAUNAY COMPLEX

- ① Construct the star of  $p \in \mathcal{P}$  in the Delaunay triangulation  $\text{Del}_{T_p}(\mathcal{P})$  of  $\mathcal{P}$  restricted to  $T_p$
- ②  $\text{Del}_{TM}(\mathcal{P}) = \bigcup_{p \in \mathcal{P}} \text{star}(p)$



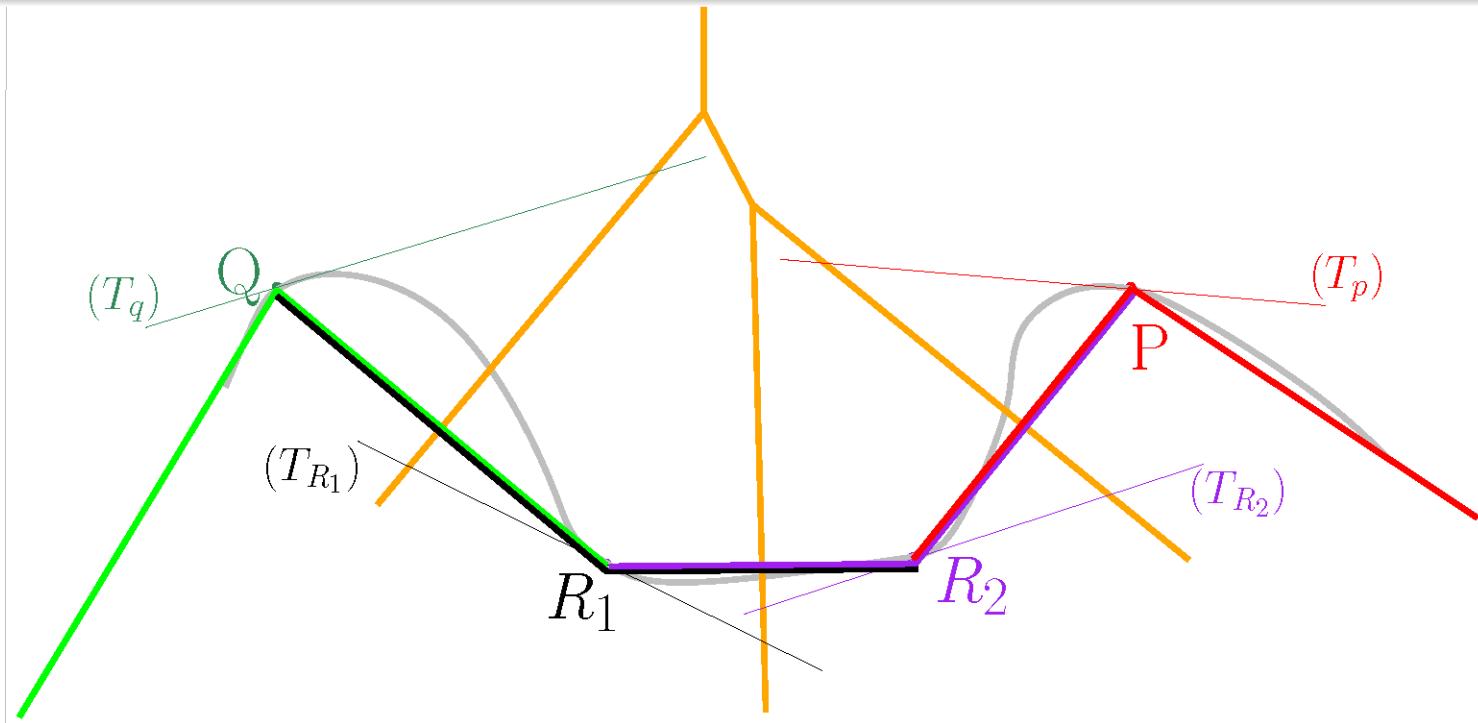
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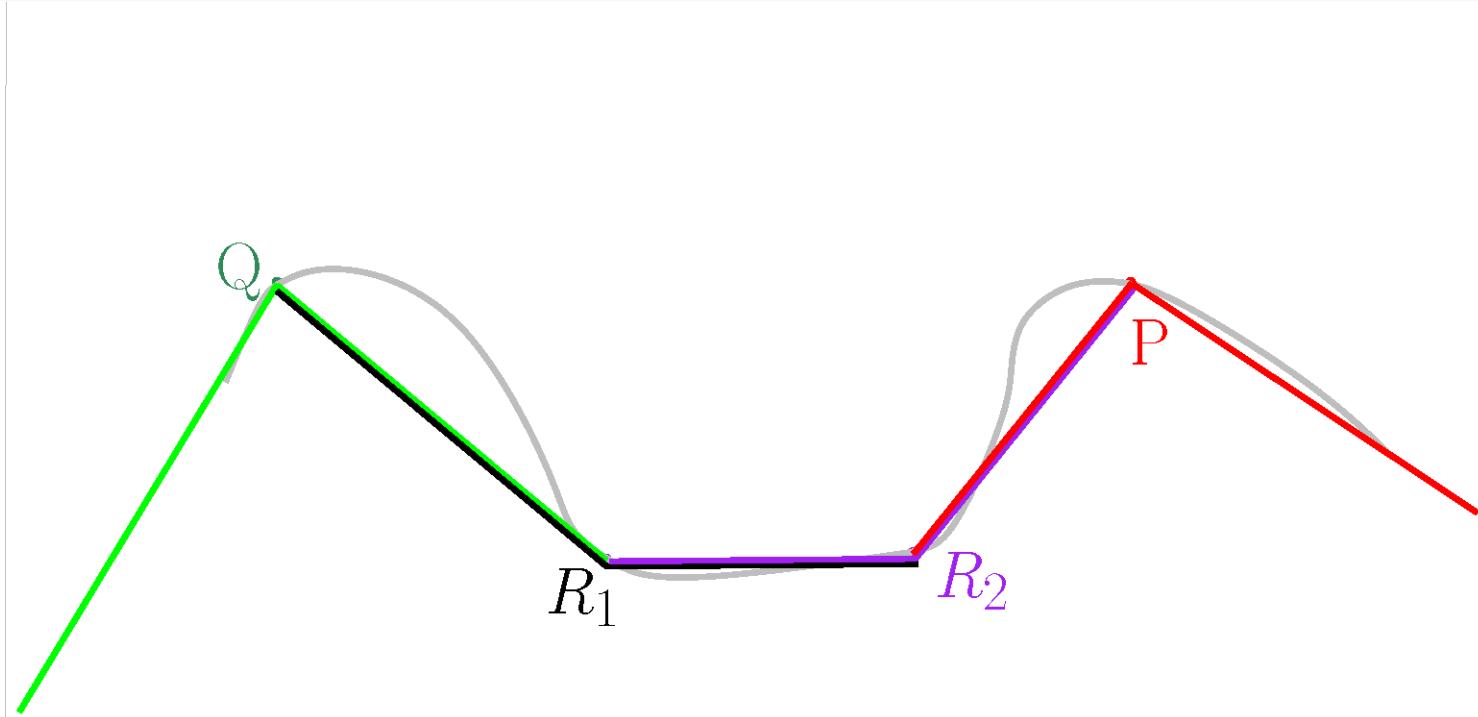
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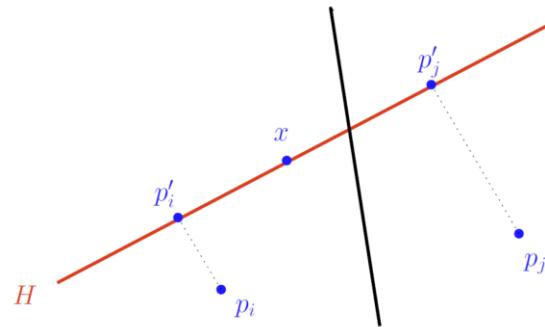
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- ②  $\text{Del}_{TM}(\mathcal{P}) = \bigcup_{p \in \mathcal{P}} \text{star}(p)$



# CONSTRUCTION OF $\text{Del}_{T_p}(\mathcal{P})$

Given a  $d$ -flat  $H \subset \mathbb{R}$ ,  $\text{Vor}(\mathcal{P}) \cap H$  is a weighted Voronoi diagram in  $H$

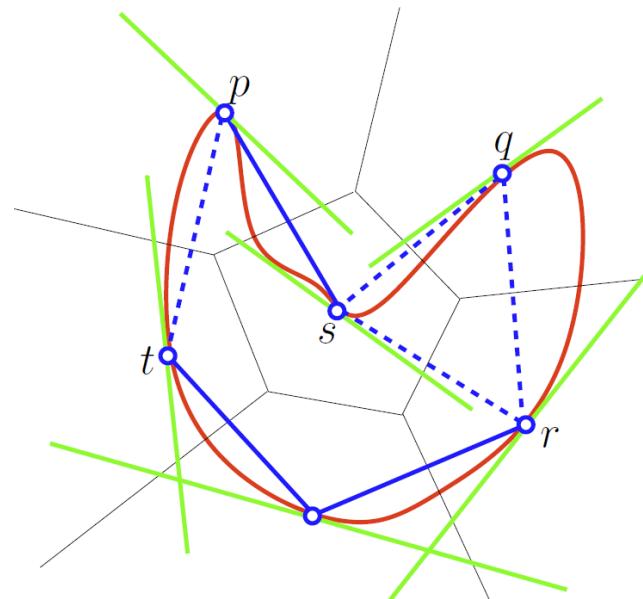
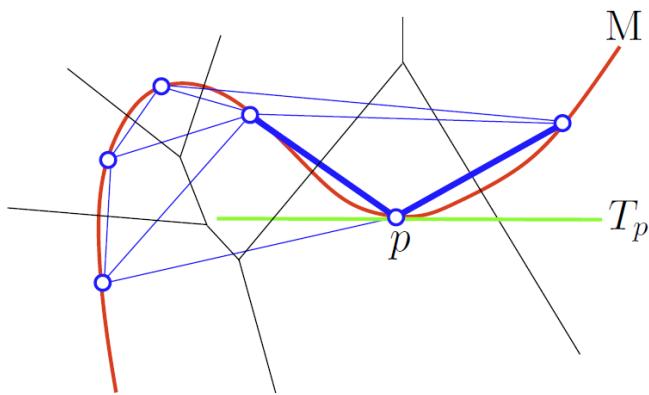


Corollary: construction of  $\text{Del}_{T_p}$

$$\psi_p(p_i) = (p'_i, -\|p_i - p'_i\|^2) \quad (\text{weighted point})$$

- ① project  $\mathcal{P}$  onto  $T_p$  which requires  $O(Dn)$  time
- ② construct  $\text{star}(\psi_p(p_i))$  in  $\text{Del}(\psi_p(p_i)) \subset T_{p_i}$
- ③  $\text{star}(p_i) \approx \text{star}(\psi_p(p_i))$  (isomorphic )

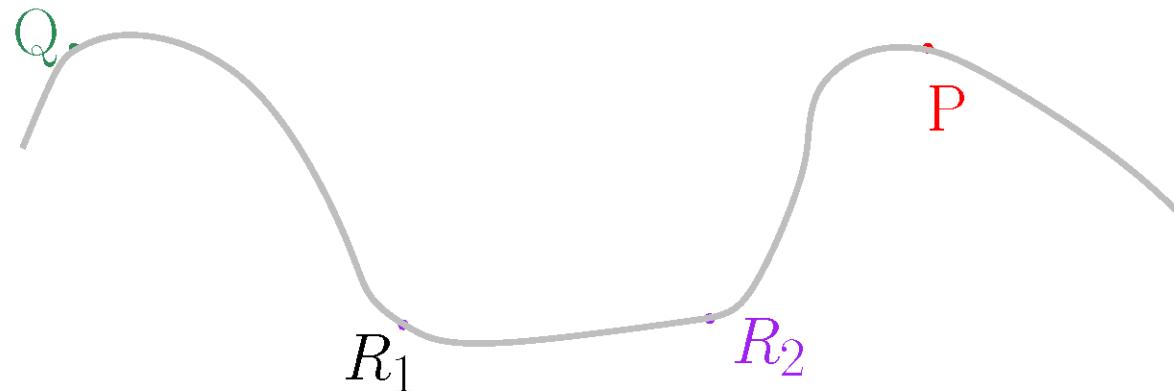
# THE TANGENTIAL DELAUNAY COMPLEX



- +  $\text{Del}_{T\mathbb{M}}(\mathcal{P}) \subset \text{Del}(\mathcal{P})$
- +  $\text{star}(p)$ ,  $\text{Del}_{T_p}(\mathcal{P})$  and therefore  $\text{Del}_{T\mathbb{M}}(\mathcal{P})$  can be computed without computing  $\text{Del}(\mathcal{P})$
- $\text{Del}_{T\mathbb{M}}(\mathcal{P})$  is **not** necessarily a triangulated manifold

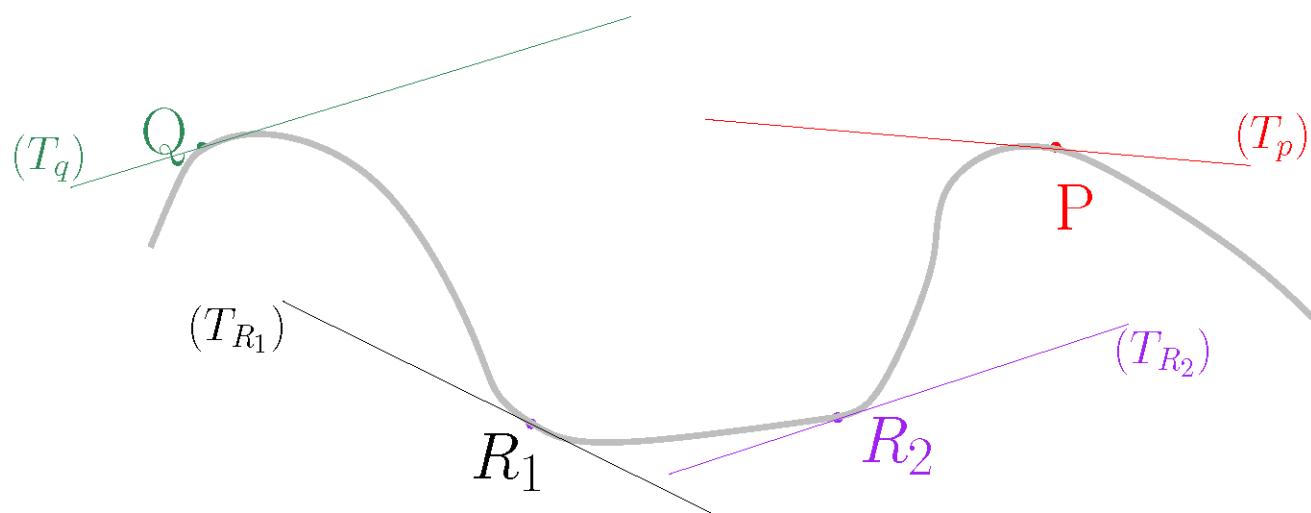
# INCONSISTENCIES IN THE TANGENTIAL COMPLEX

Sometimes, things are not so smooth...



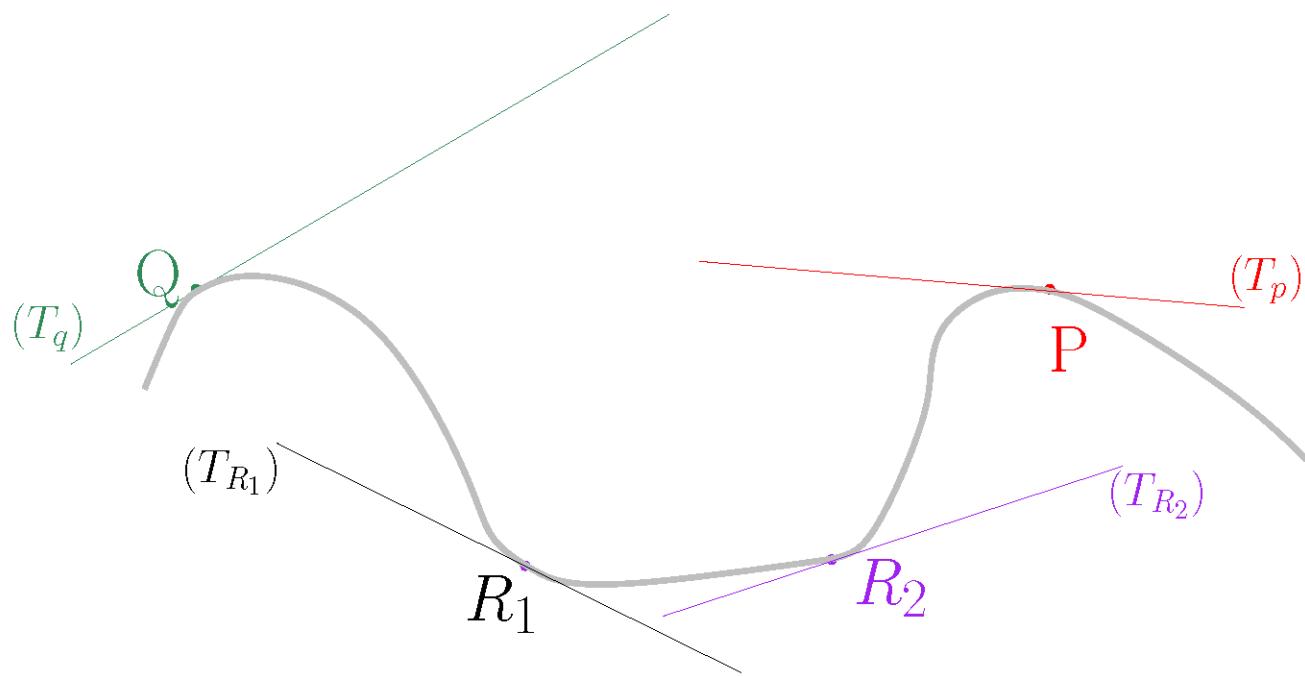
# INCONSISTENCIES IN THE TANGENTIAL COMPLEX

Before...

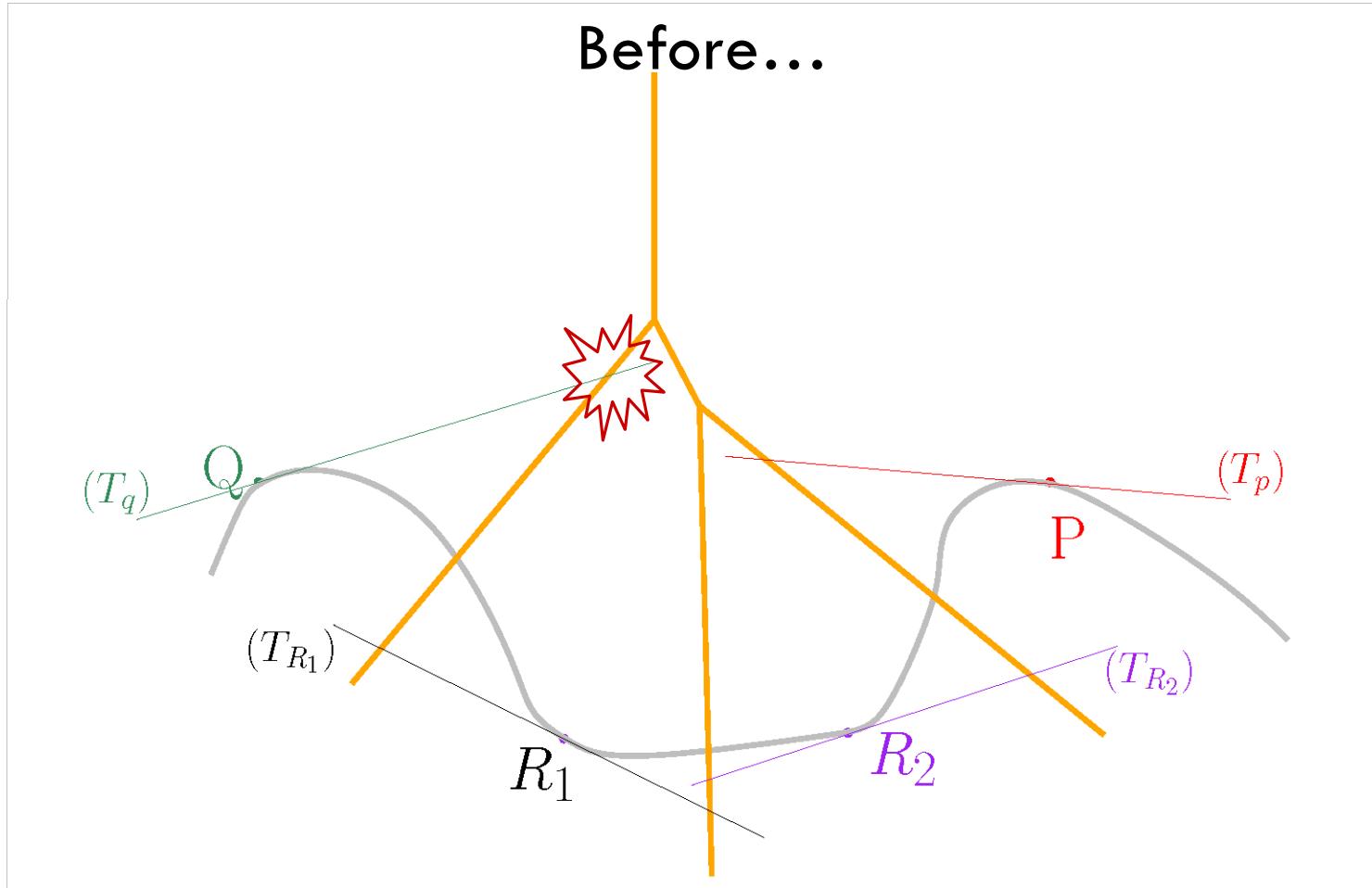


# INCONSISTENCIES IN THE TANGENTIAL COMPLEX

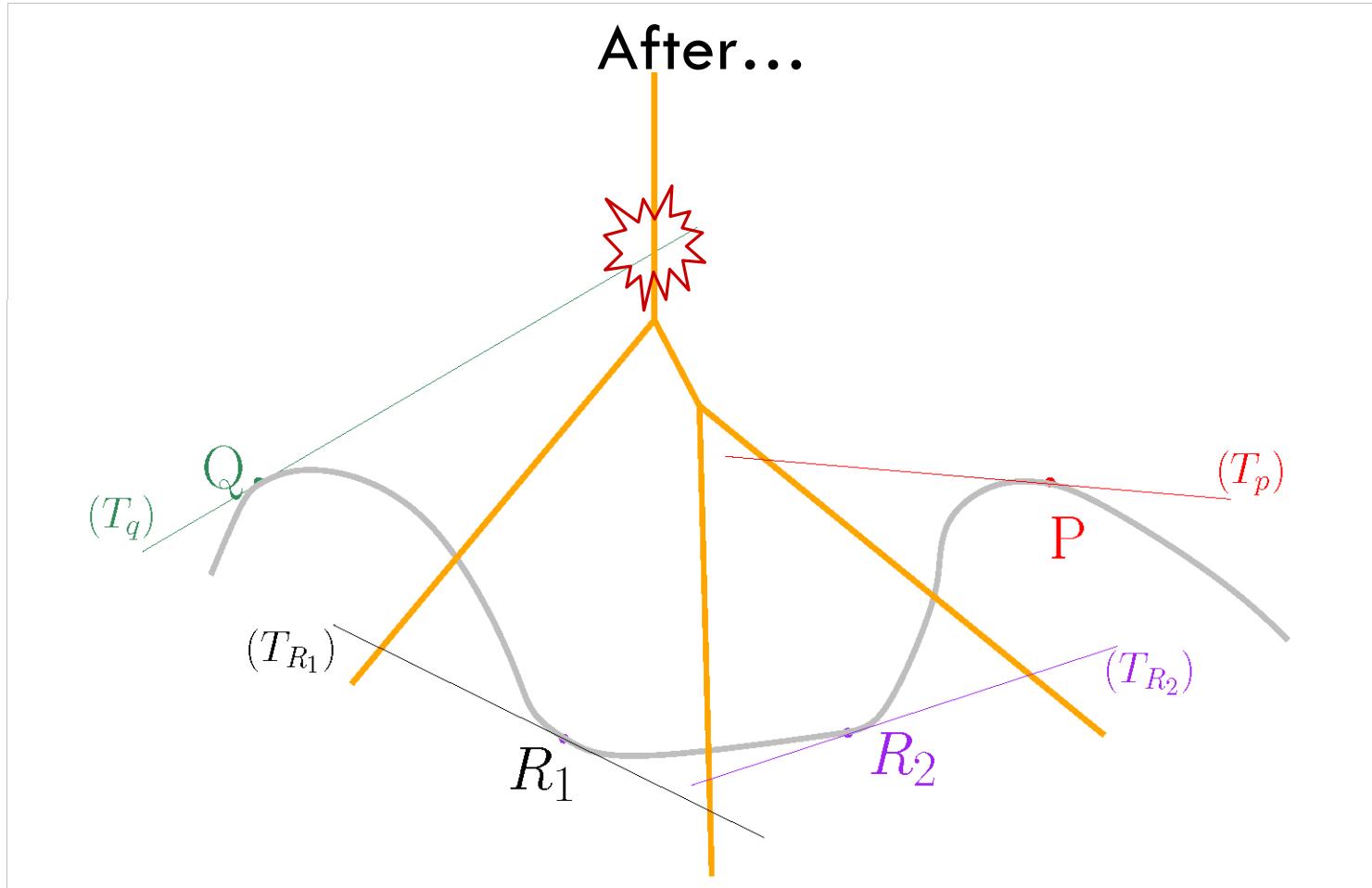
After...



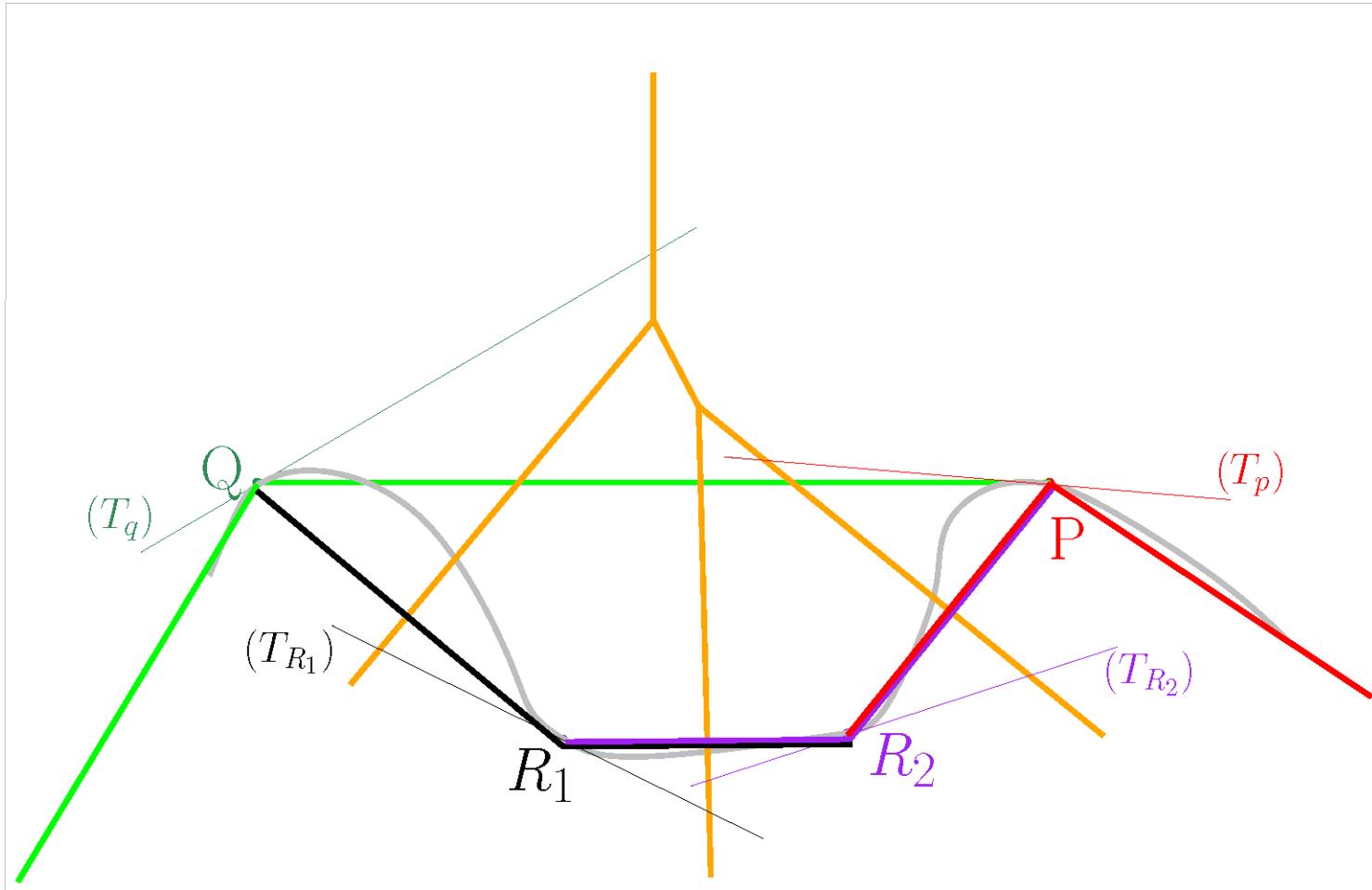
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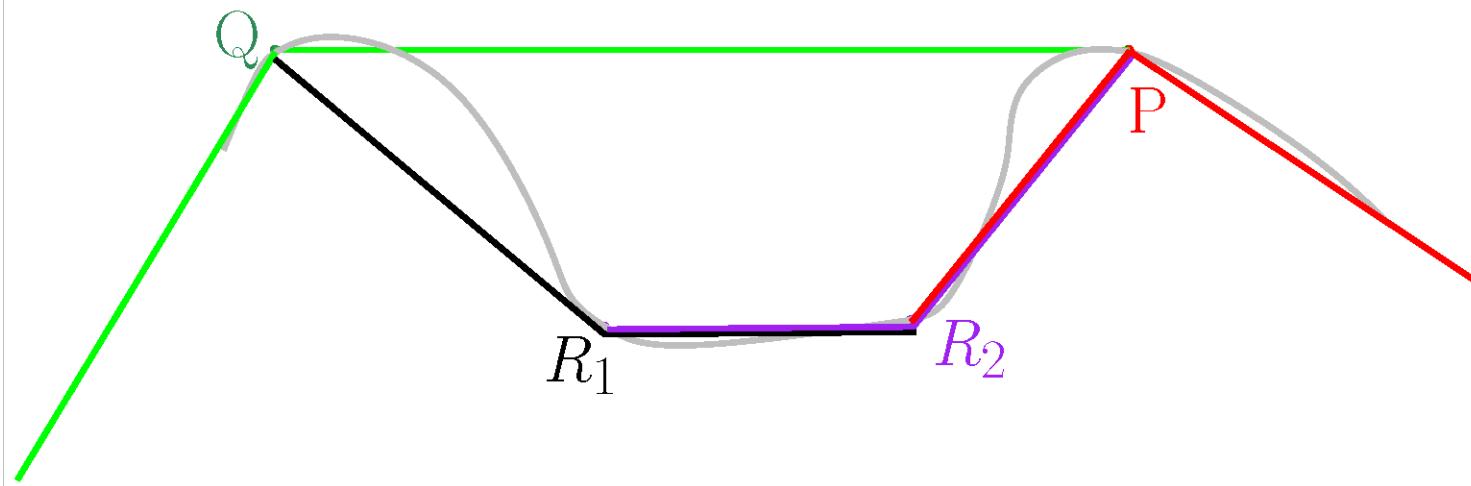


# INCONSISTENCIES IN THE TANGENTIAL COMPLEX



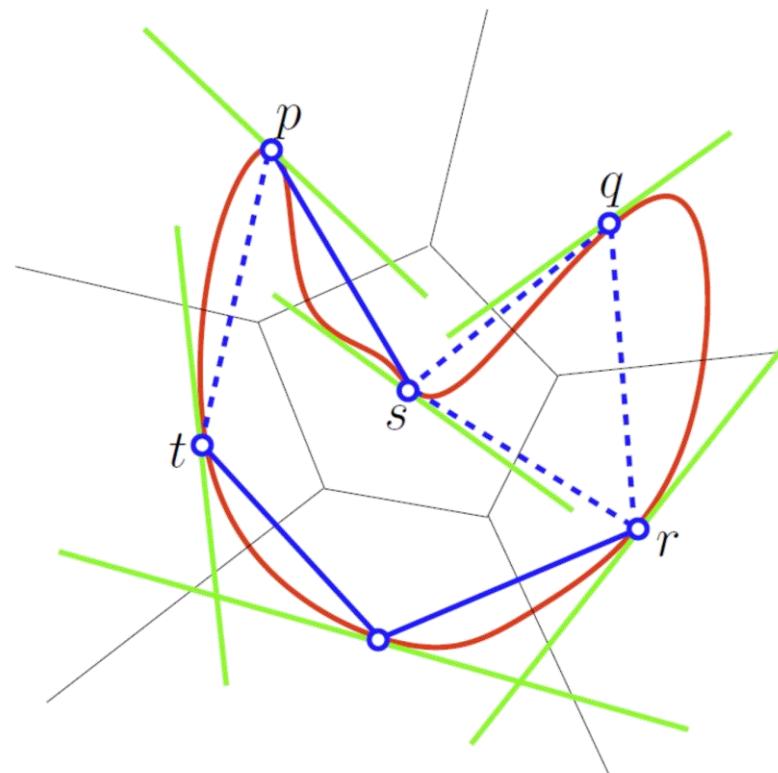
# INCONSISTENCIES IN THE TANGENTIAL COMPLEX

Inconsistency: when a simplex is **not** in the star of all its vertices



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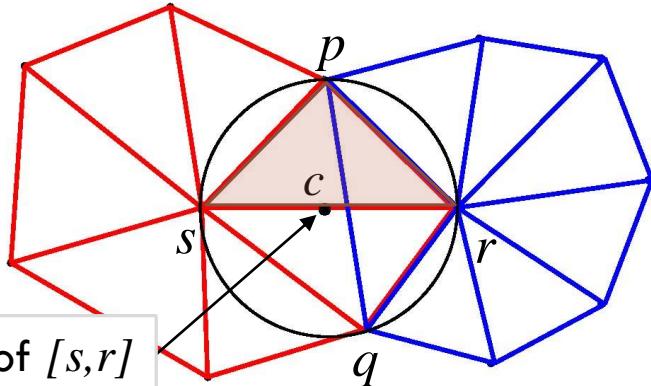


# SOLVING INCONSISTENCIES

- ❖ Perturb the points...
  1. by weighting the points of P
  2. by moving points in their tangent space
- ❖ Option 2 is a bit more effective  
(more degrees of freedom)

# SOLVING INCONSISTENCIES

Power center of  $[s,r]$



$r$  is in the star of  $s$ ,  
but  $s$  is not the star of  $r$   
→ Simplex  $[s,p,r]$  is inconsistent

## ❖ Which points?

1. Center point only:  $s$
2. One random point of the simplex:  $s$  or  $p$  or  $r$
3. Simplex points only:  $s, p, r$
4.  $k+2$  closest points to  $c$ :  $s, p, r, q$
5. Points of the 1-star of  $s$ :  $s, p, r, q, \text{etc.}$

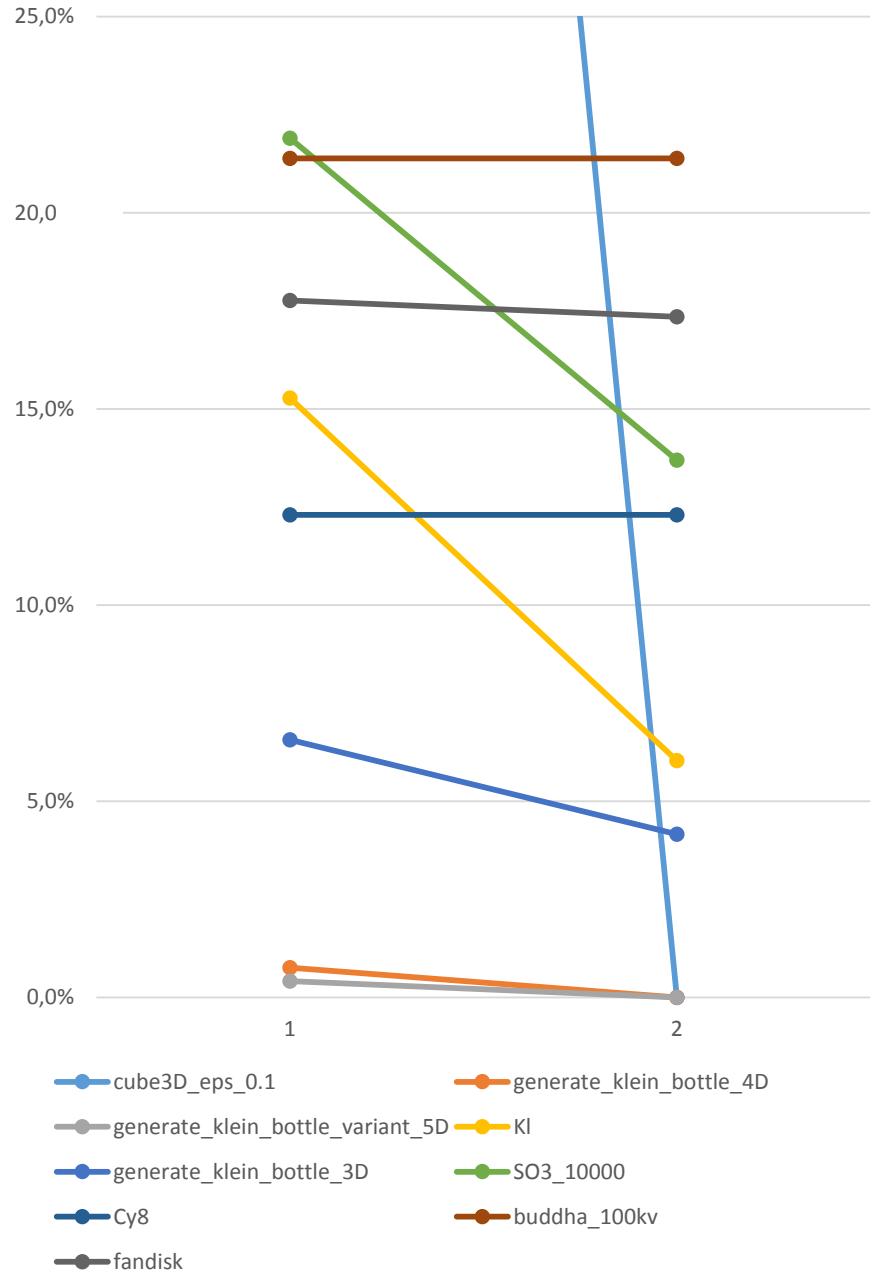
# K+2 CLOSEST POINTS

Input	Intrinsic_dim	Ambient_dim	Sparsity	Num_points_in_input	Num_points	Initial_num_inconsistent_local_tr	%	Best_num_inconsistent_local_tr	%	Final_num_inconsistent_local_tr	%	Init_time	Comput_time	Fix_time	Fix_steps
S3	3	4	0.05	2000	2000	0	0.0%	0	0.0%	0	0.0%	0.04	0.42	N/A	N/A
generate_sphere_d	1	2	0.005	30000	2678	0	0.0%	0	0.0%	0	0.0%	0.06	0.01	N/A	N/A
generate_sphere_d	2	3	0.005	30000	29678	0	0.0%	0	0.0%	0	0.0%	0.20	1.06	N/A	N/A
generate_sphere_d	3	4	0.05	30000	29588	0	0.0%	0	0.0%	0	0.0%	0.32	12.85	N/A	N/A
generate_plane	2	3	0.005	30000	28632	0	0.0%	0	0.0%	0	0.0%	0.16	17.95	N/A	N/A
generate_moment_curve	1	6	0.005	30000	405	0	0.0%	0	0.0%	0	0.0%	0.07	0.01	N/A	N/A
cube3D_eps_0.1	2	3	0.05	1350	1350	1348	99.9%	0	0.0%	0	0.0%	0.02	0.09	2.40	19
generate_klein_bottle_4D	2	4	0.05	10000	9014	68	0.8%	0	0.0%	0	0.0%	0.07	0.32	2.67	3
generate_klein_bottle_variant_5D	2	5	0.05	30000	24989	103	0.4%	0	0.0%	0	0.0%	0.25	0.87	10.24	4
KI	2	5	0.05	4900	4792	732	15.3%	289	6.0%	463	9.7%	0.05	0.13	3000.35	7628
generate_klein_bottle_3D	2	3	0.05	30000	24179	1588	6.6%	1005	4.2%	1121	4.6%	0.17	0.85	3002.44	1213
SO3_10000	3	9	0.05	10000	10000	2190	21.9%	1369	13.7%	1707	17.1%	0.17	2.74	3007.64	214
Cy8	2	24	0.1	6040	6040	743	12.3%	743	12.3%	1260	20.9%	0.14	0.29	3000.10	4495
buddha_100kv	2	3	0.005	99678	40921	8749	21.4%	8749	21.4%	16754	40.9%	0.39	1.11	3002.36	958
fandisk	2	3	0.01	6475	6417	1140	17.8%	1113	17.3%	1610	25.1%	0.05	0.19	3000.36	6000

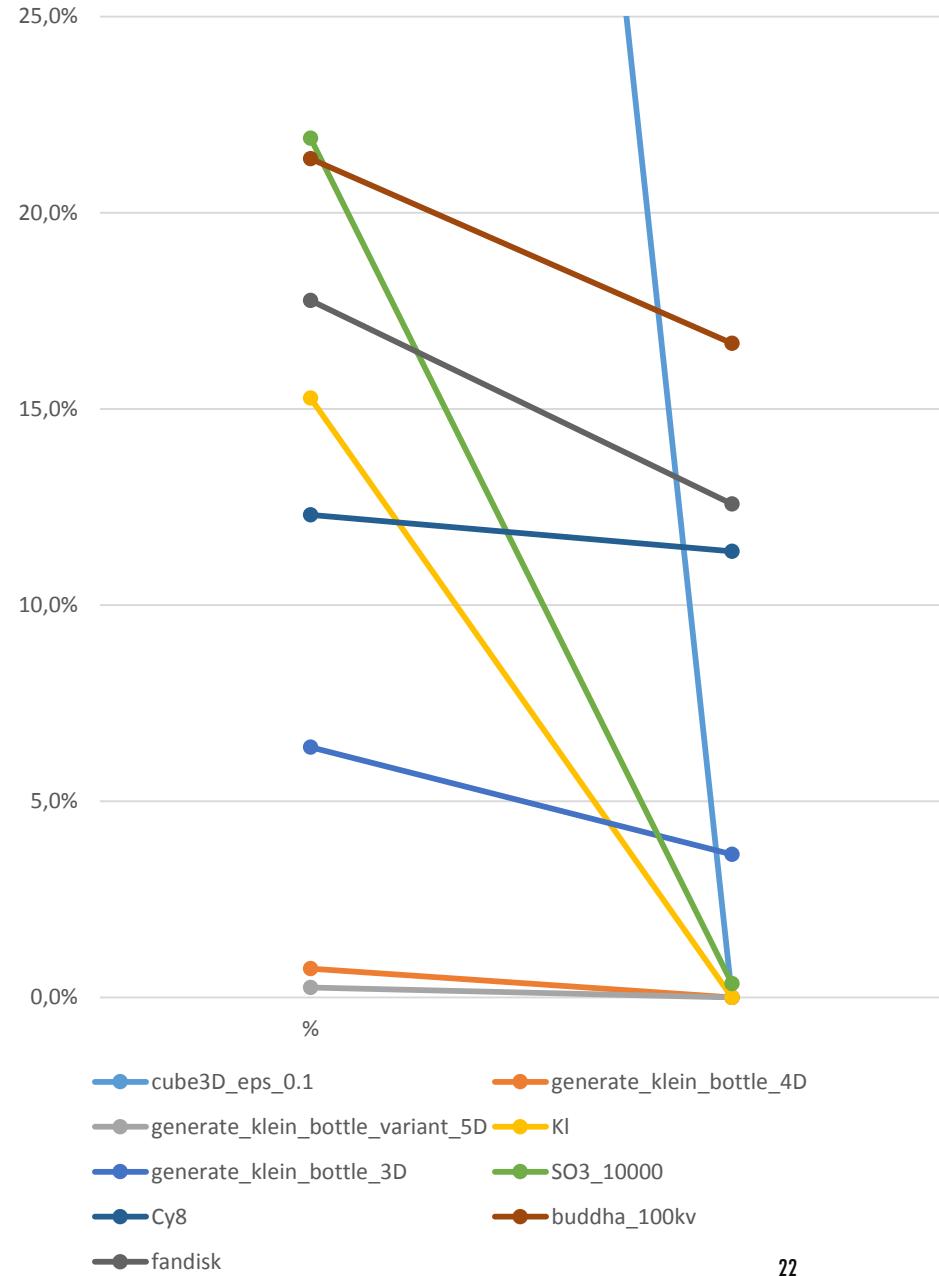
# ONE RANDOM POINT OF THE SIMPLEX

Input	Intrinsic_dim	Ambient_dim	Sparsity	Num_points_in_input	Num_points	Initial_num_inconsistent_local_tr	%	Best_num_inconsistent_local_tr	%	Final_num_inconsistent_local_tr	%	Init_time	Comput_time	Fix_time	Fix_steps
S3	3	4	0.05	2000	2000	0	0.0%	0	0.0%	0	0.0%	0.04	0.43	N/A	N/A
generate_sphere_d	1	2	0.005	30000	2655	0	0.0%	0	0.0%	0	0.0%	0.06	0.01	N/A	N/A
generate_sphere_d	2	3	0.005	30000	29691	0	0.0%	0	0.0%	0	0.0%	0.21	1.05	N/A	N/A
generate_sphere_d	3	4	0.05	30000	29590	0	0.0%	0	0.0%	0	0.0%	0.34	12.80	N/A	N/A
generate_plane	2	3	0.005	30000	28644	0	0.0%	0	0.0%	0	0.0%	0.17	17.33	N/A	N/A
generate_moment_curve	1	6	0.005	30000	409	0	0.0%	0	0.0%	0	0.0%	0.08	0.00	N/A	N/A
cube3D_eps_0.1	2	3	0.05	1350	1350	1348	99.9%	0	0.0%	0	0.0%	0.02	0.09	1.26	9
generate_klein_bottle_4D	2	4	0.05	10000	9029	66	0.7%	0	0.0%	0	0.0%	0.08	0.33	2.89	3
generate_klein_bottle_variant_5D	2	5	0.05	30000	25057	64	0.3%	0	0.0%	0	0.0%	0.28	0.87	5.26	2
KI	2	5	0.05	4900	4792	732	15.3%	0	0.0%	0	0.0%	0.06	0.13	376.49	895
generate_klein_bottle_3D	2	3	0.05	30000	24194	1544	6.4%	882	3.6%	968	4.0%	0.19	0.87	3001.06	1140
SO3_10000	3	9	0.05	10000	10000	2190	21.9%	35	0.4%	250	2.5%	0.19	2.77	3007.12	189
Cy8	2	24	0.1	6040	6040	743	12.3%	687	11.4%	878	14.5%	0.16	0.29	3000.13	4342
buddha_100kv	2	3	0.005	99678	40921	8749	21.4%	6824	16.7%	8602	21.0%	0.44	1.12	3002.86	892
fandisk	2	3	0.01	6475	6417	1140	17.8%	807	12.6%	1054	16.4%	0.05	0.20	3000.22	5617

*k+2* closest points



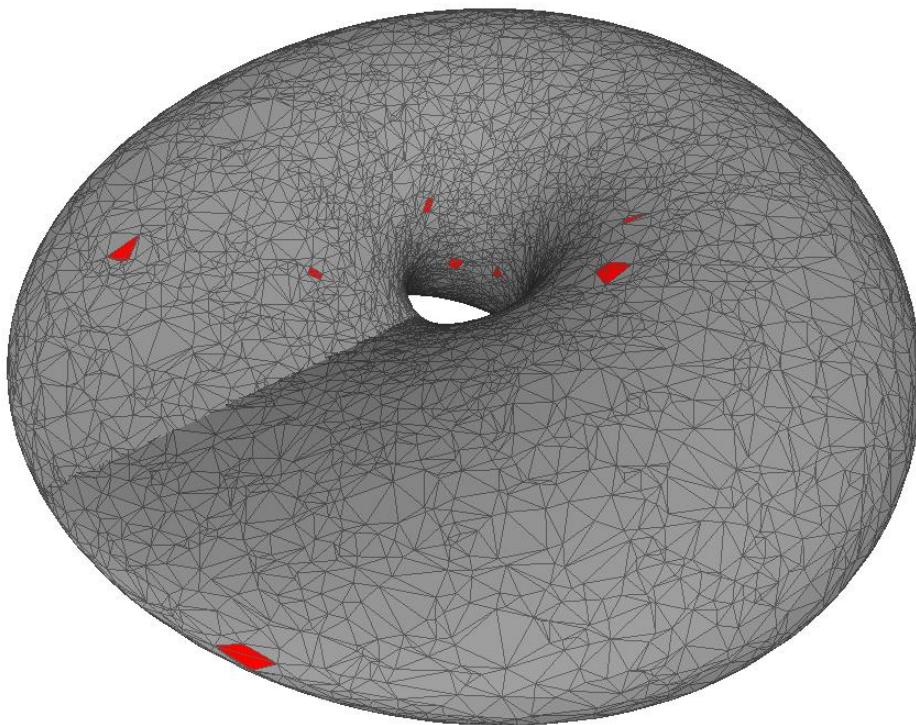
One random point of the simplex



# SNAPSHOTS: GENERATED 4D KLEIN BOTTLE

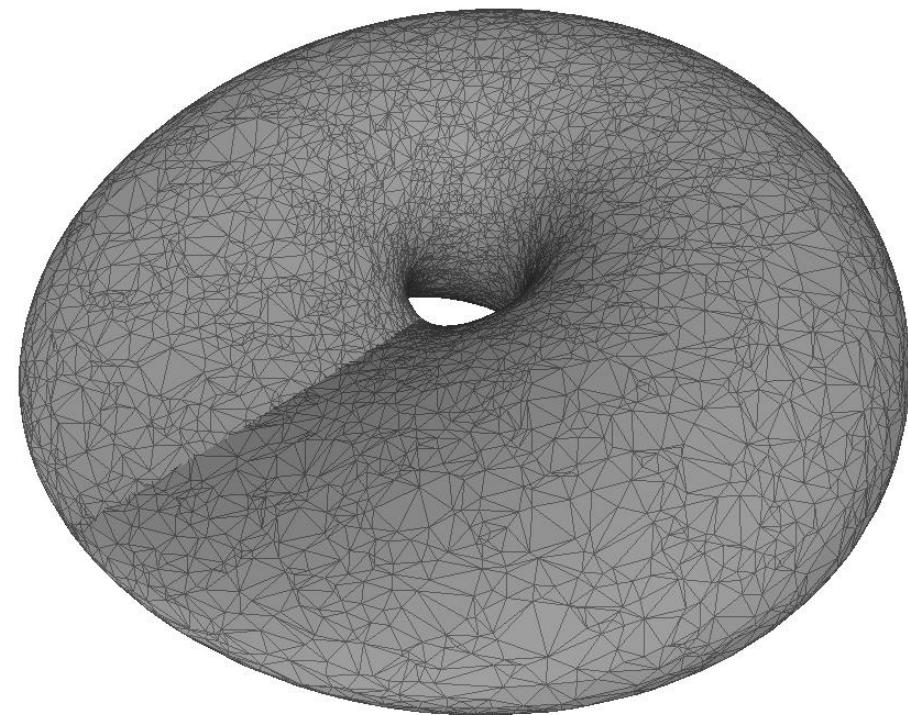
BEFORE

9k points – Dim 2 in  $\mathbb{R}^4$



0.7 %

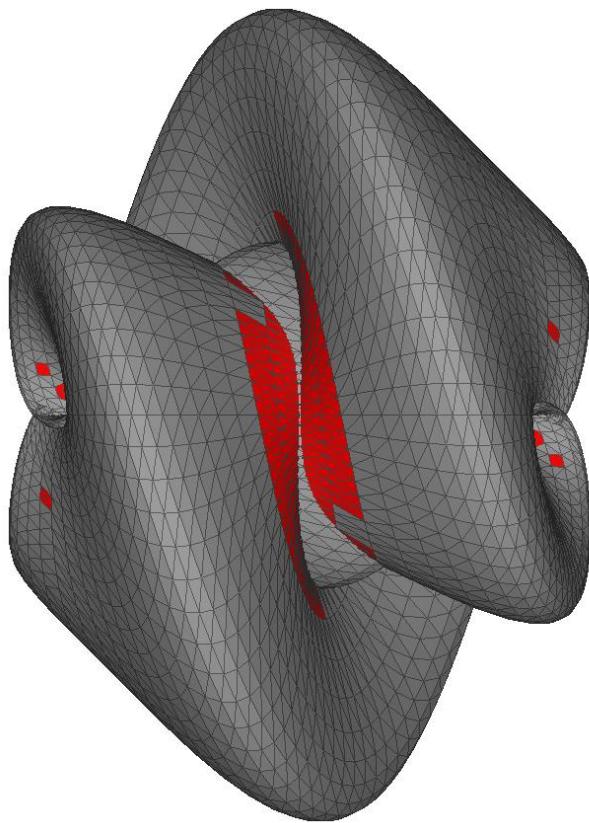
AFTER



0 %

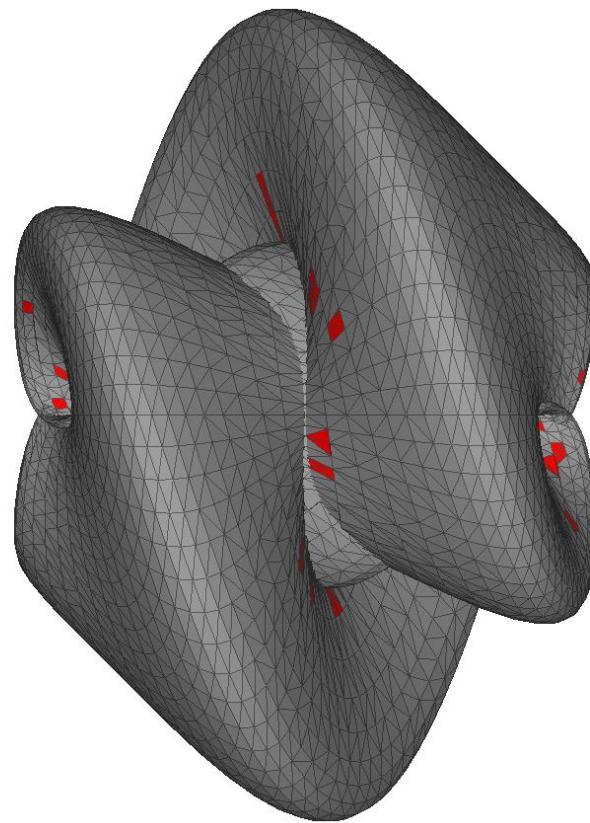
# SNAPSHOTS: 5D KLEIN BOTTLE

5k points – Dim 2 in  $\mathbb{R}^5$



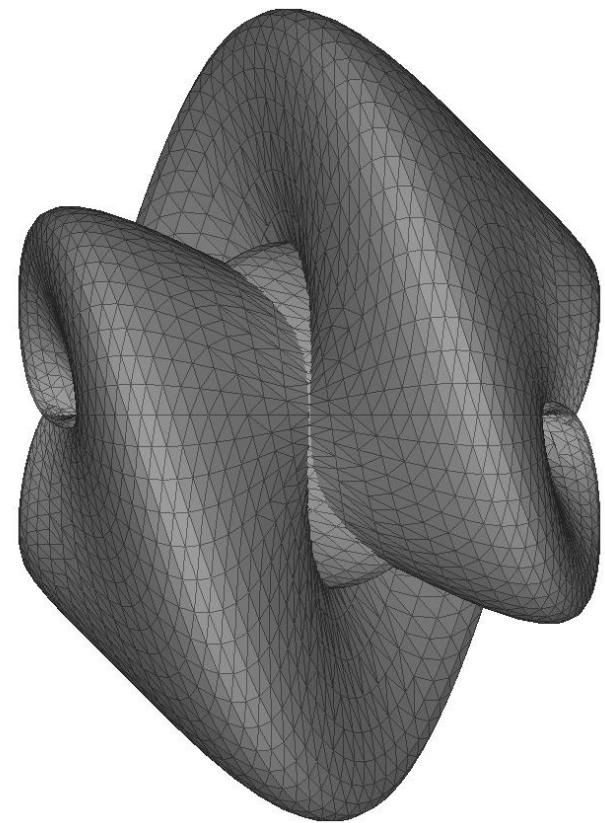
15.3 %

$k+2$  closest points



9.7 %

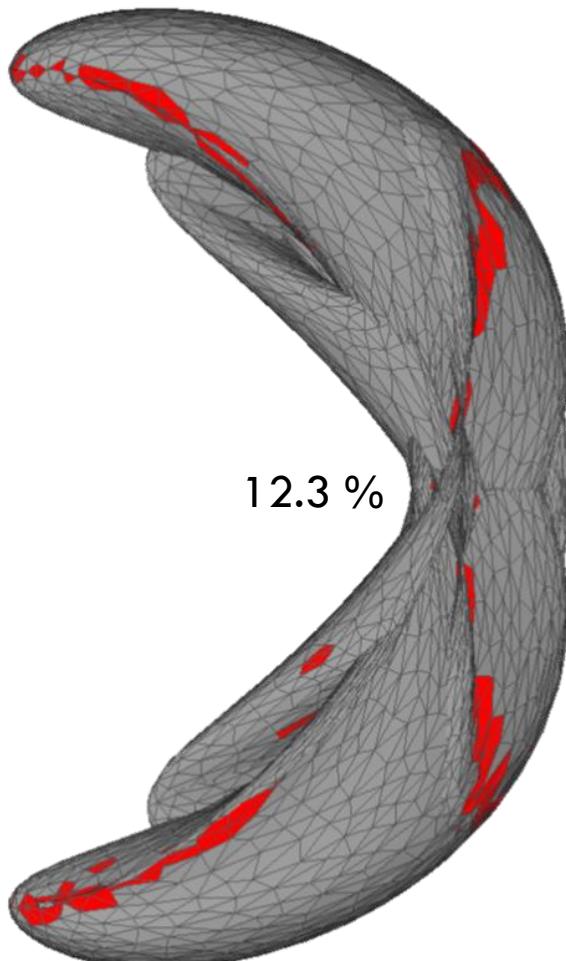
One random point  
of the simplex



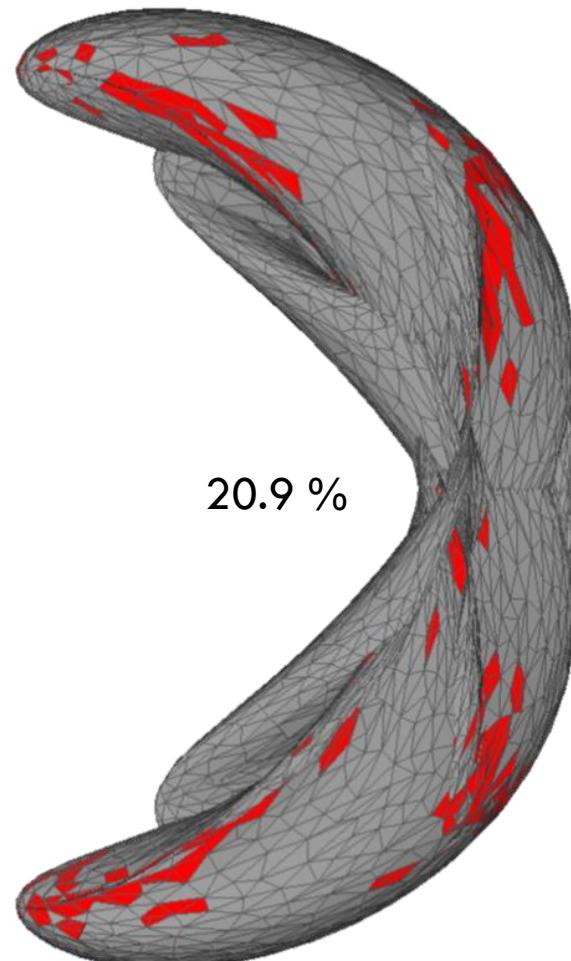
0 %

# SNAPSHOTS: CYCLO-OCTANE

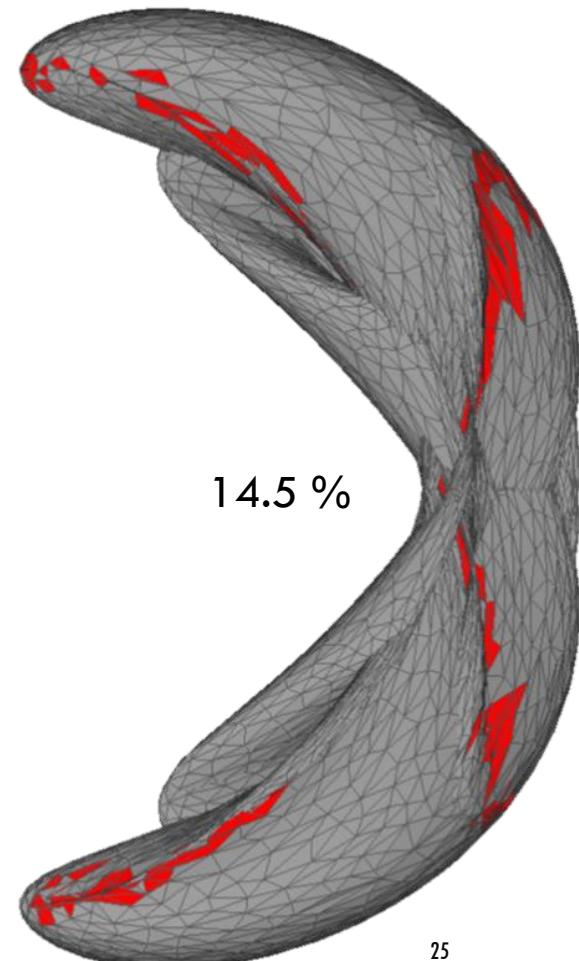
6k points – Dim 2 in  $\mathbb{R}^{24}$



$k+2$  closest points

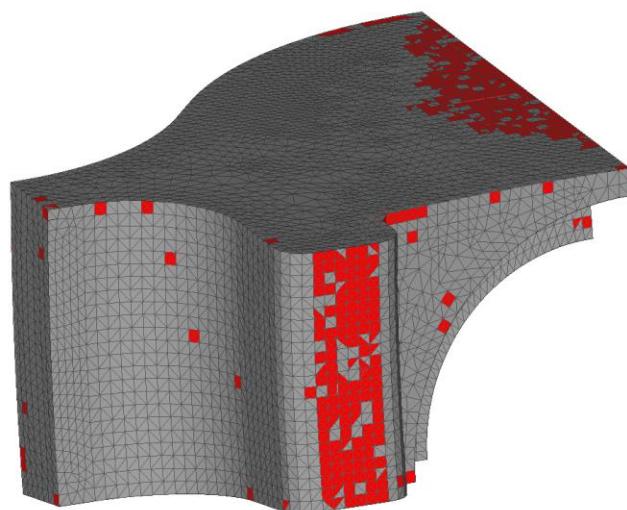


One random point  
of the simplex



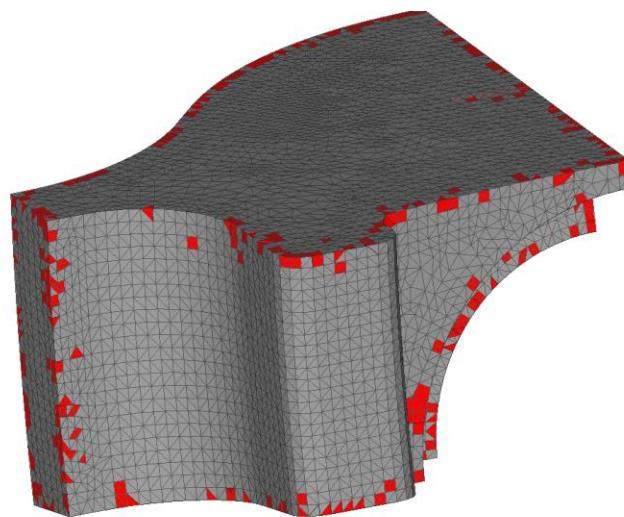
# SNAPSHOTS: FANDISK

6k points – Dim 2 in  $\mathbb{R}^3$



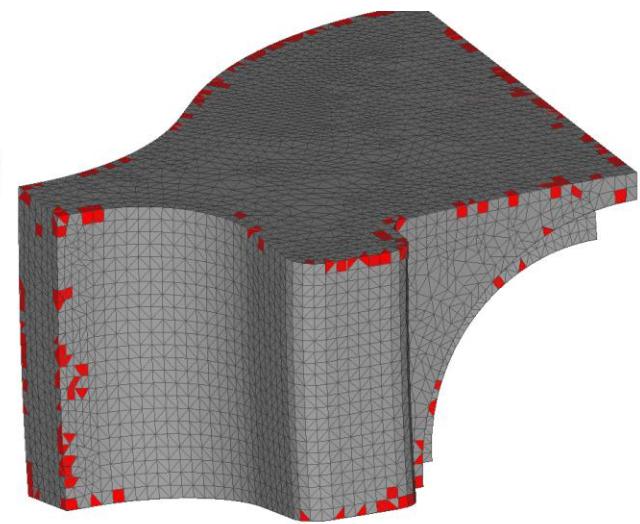
17.8 %

$k+2$  closest points



25.1 %

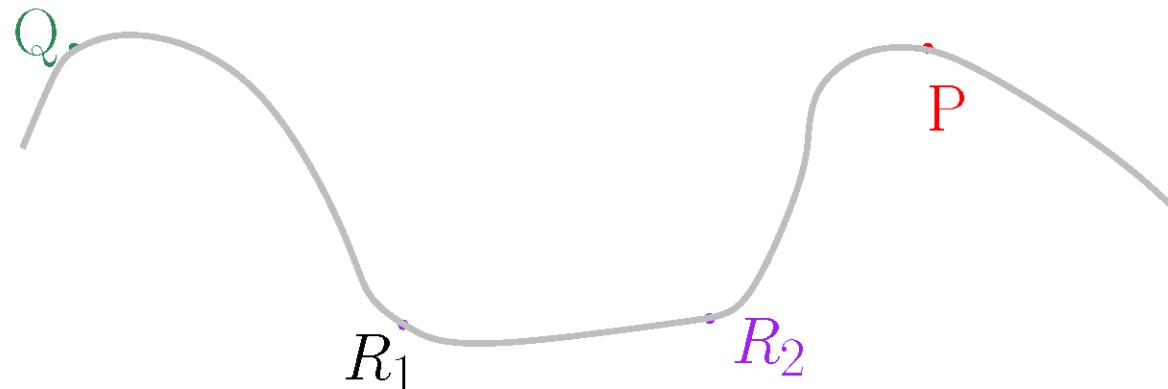
One random point  
of the simplex



16.4 %

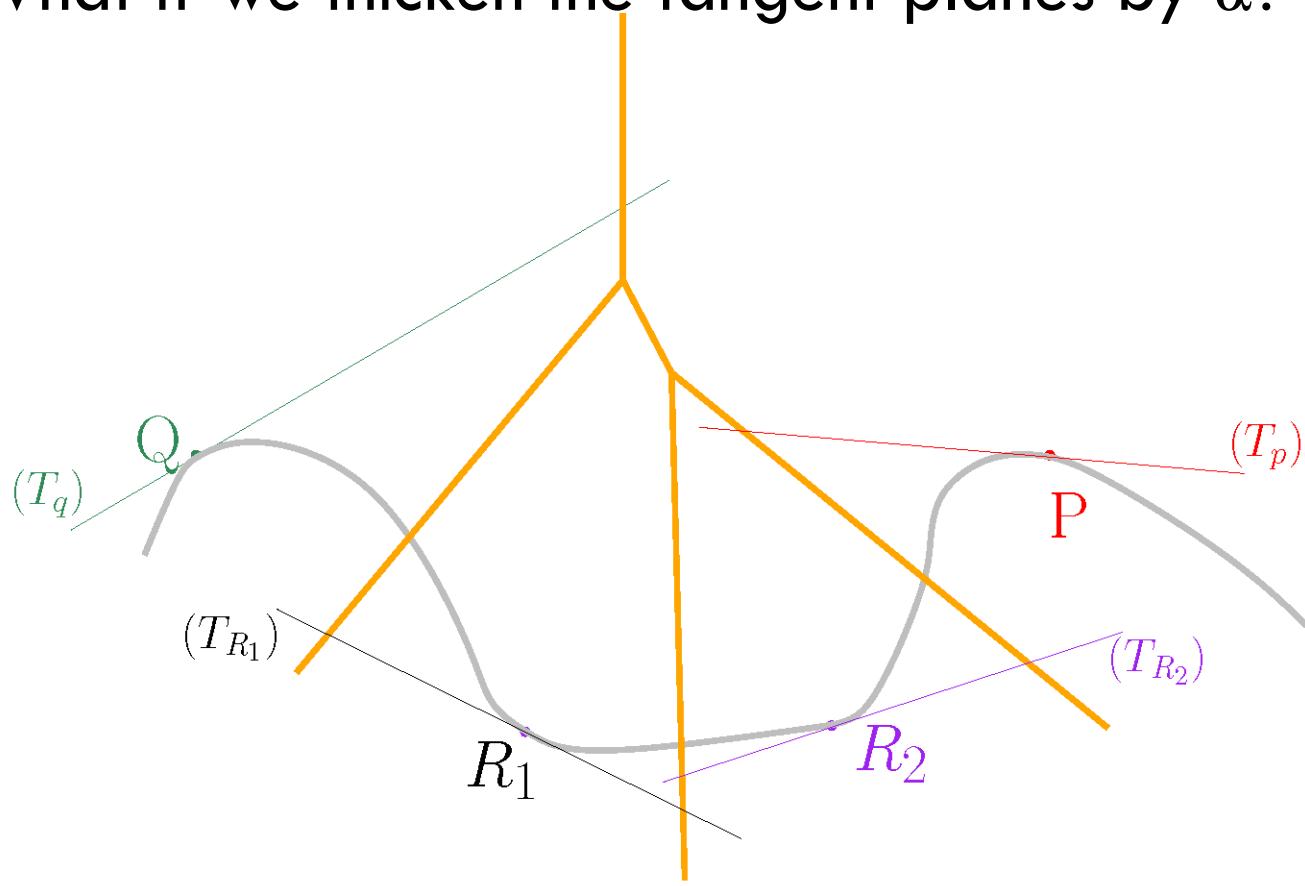
# WIP: ALPHA TANGENTIAL COMPLEX

What if we thicken the tangent planes by  $\alpha$ ?



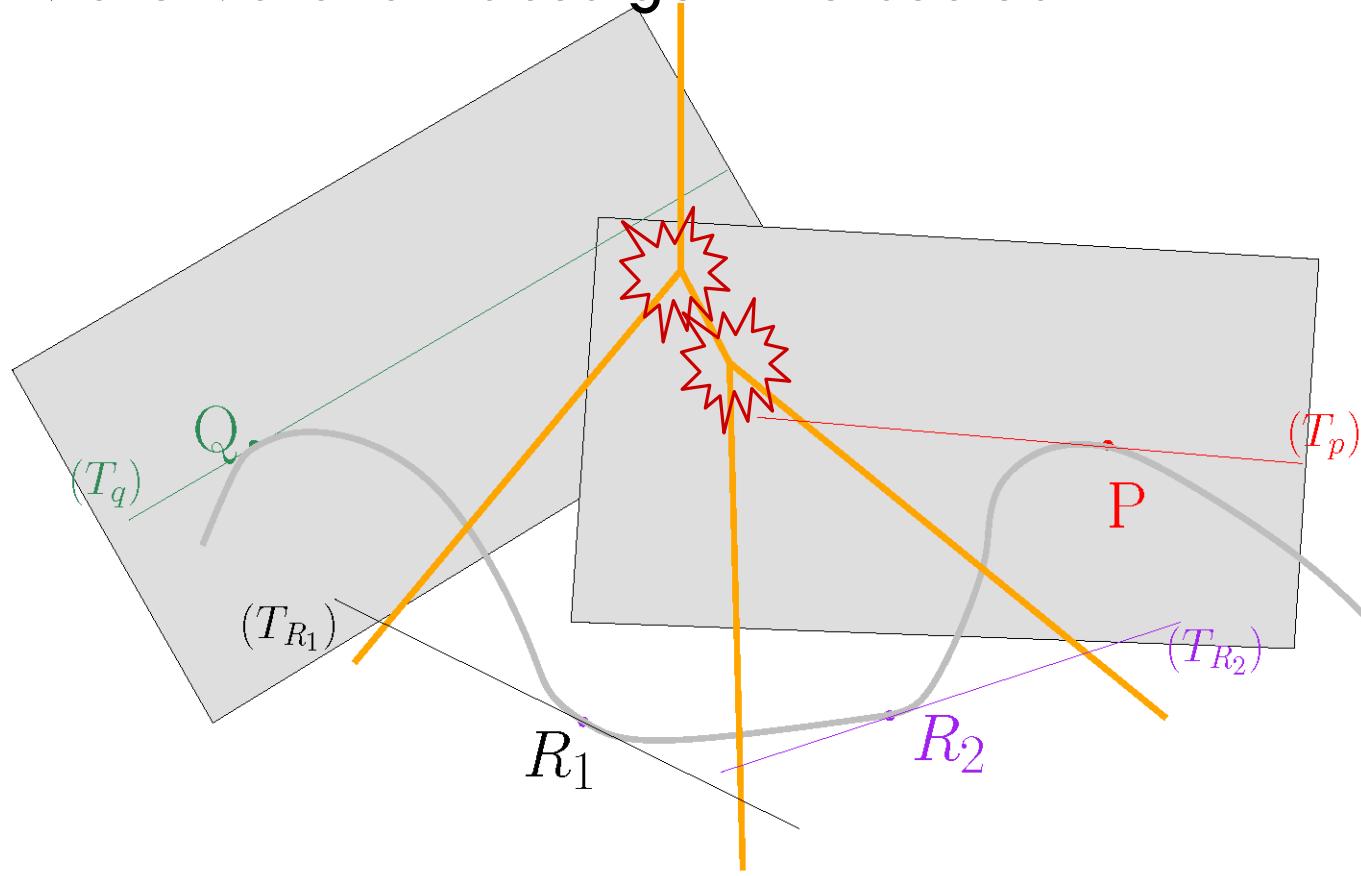
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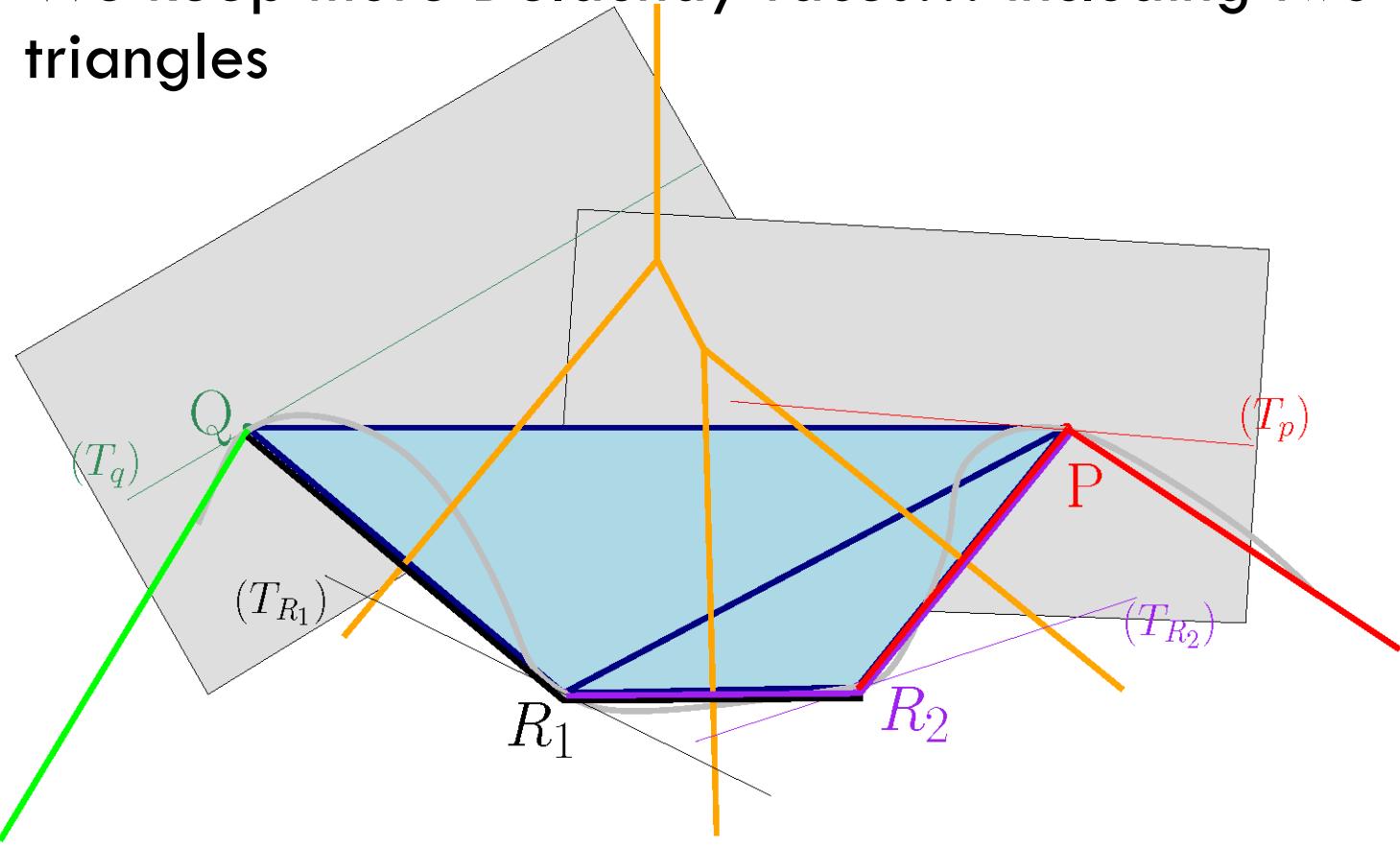
# WIP: ALPHA TANGENTIAL COMPLEX

More Voronoi faces get intersected



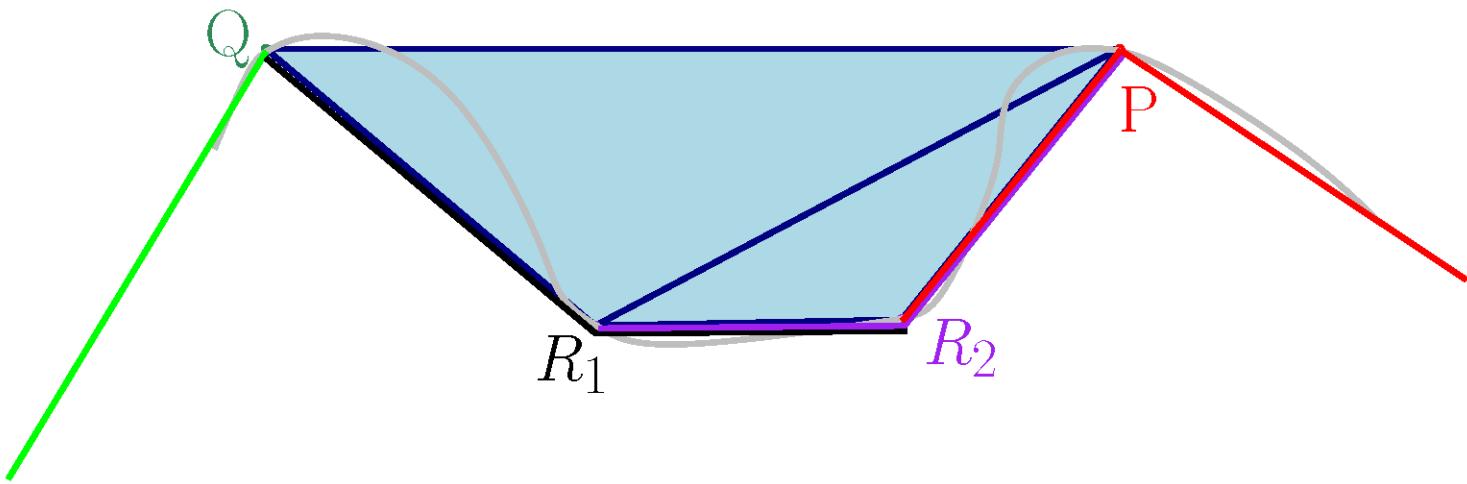
# WIP: ALPHA TANGENTIAL COMPLEX

We keep more Delaunay faces... including two triangles



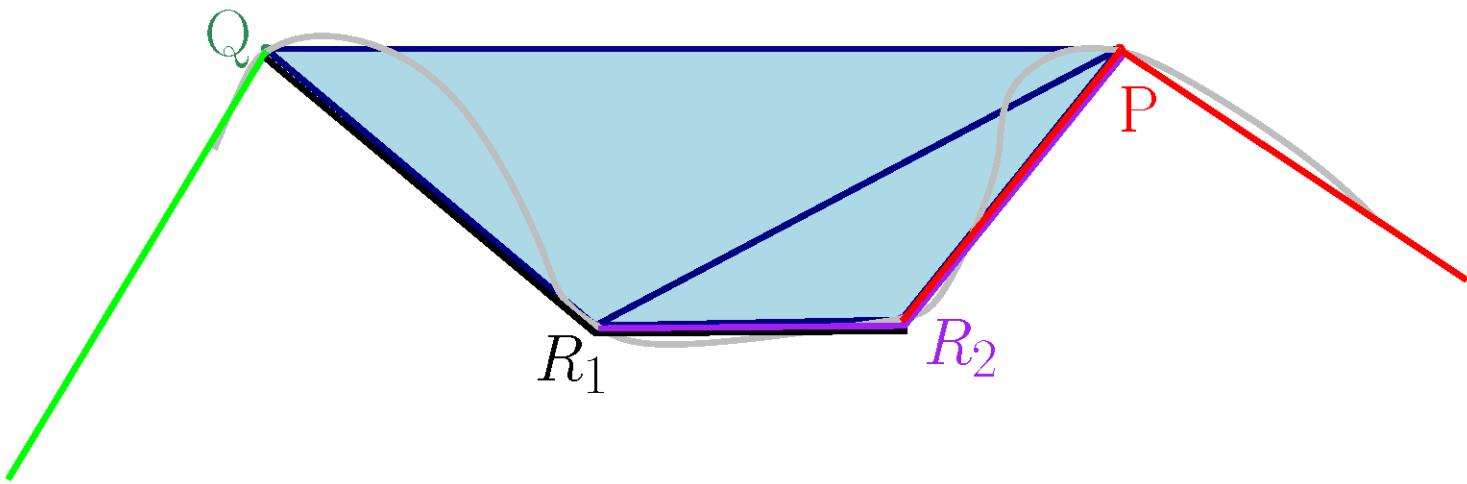
# WIP: ALPHA TANGENTIAL COMPLEX

We end up with simplices of different dimensions



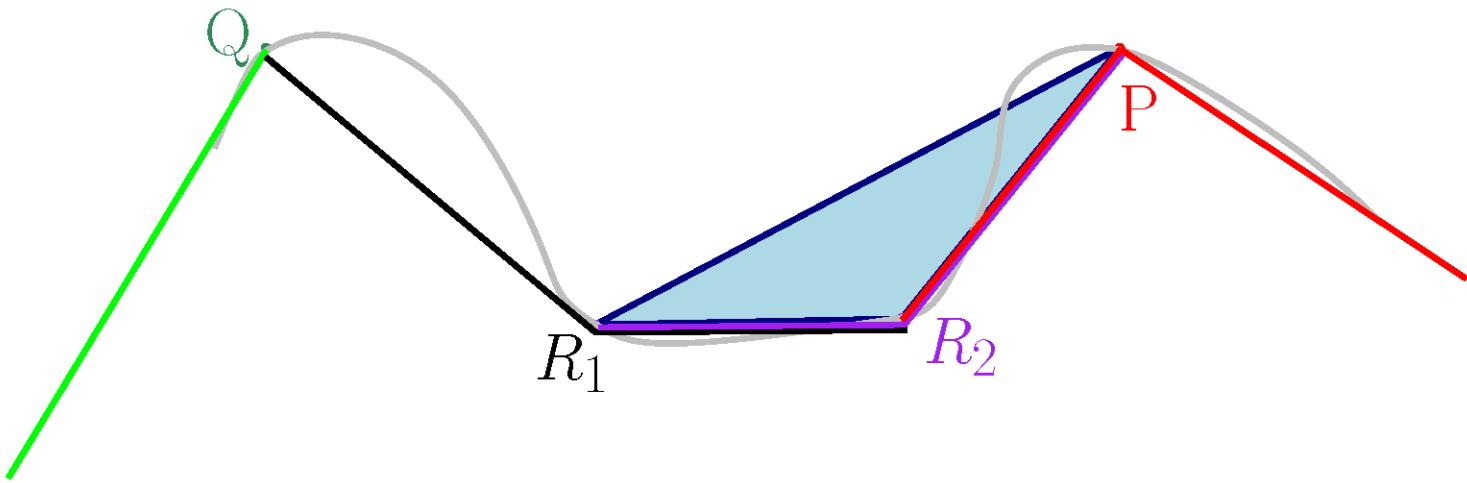
# WIP: ALPHA TANGENTIAL COMPLEX

**Collapse:** when a simplex  $S$  has only one co-face  $C$ , we can remove  $S$  and  $C$  without changing the topology.



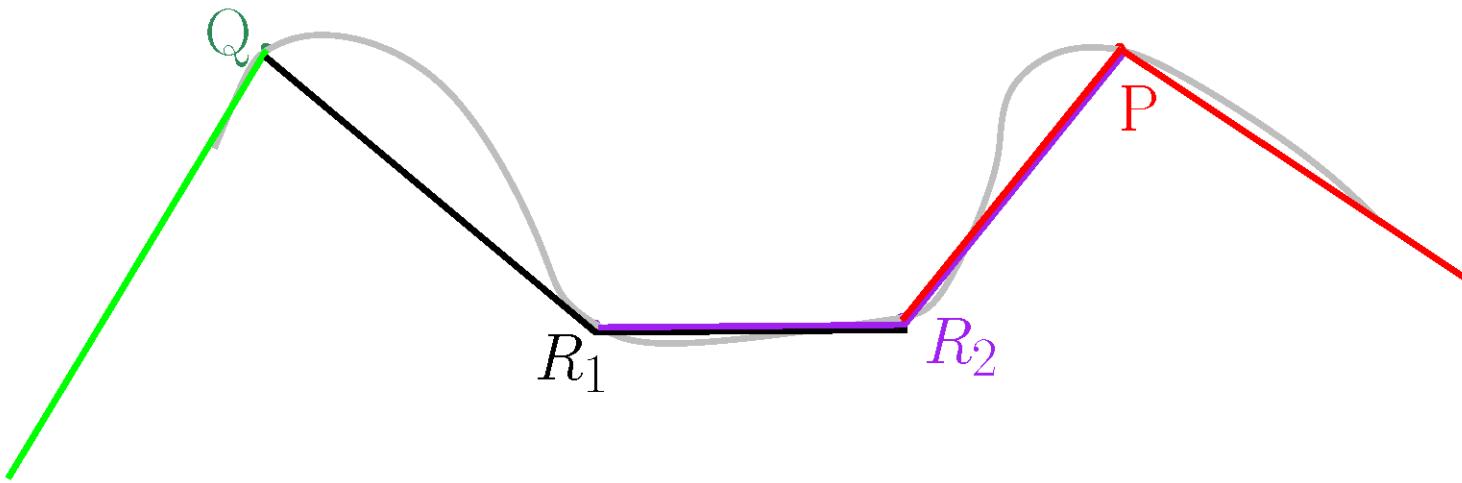
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**Collapse:** when a simplex  $S$  has only one co-face  $C$ , we can remove  $S$  and  $C$  without changing the topology.



# CONCLUSION

- ❖ Tangential Complex: reconstructing a manifold from a point cloud with a complexity depending on the intrinsic dimension.
- ❖ Solving inconsistencies by perturbing the points or the weights
  - Sometimes it works...
    - Dense sampling
    - Low intrinsic dimension
    - Best technique so far: perturb position of one random point of the simplex
  - Sometimes it doesn't
    - Sparse sampling
    - High dimensions (e.g. PCA and very high ambient dimension)
- ❖ Work in progress: alpha tangential complex