

# Ghost Fluid Method for Interfaces flow computations

M. Lutz, B. Nkonga, P. Jack, J. Claudel.

Scallaplix INRIA Futurs  
Institut de Mathématiques de Bordeaux,  
CEA-CESTA Le Barp

Porquerolles 2007

# Interfaces flow

## Interfaces Flow

For interfaces flow, it is assumed that a characteristic volume is always occupied by a pure phase fluid.

## Numerical strategies

- “Explicit” interface tracking (Front tracking)
- “Implicit” interface tracking (Level Set)
- Interface reconstruction (VOF)
- Diffusive Interface

# Outline

- 1 Interfaces flow Model**
  - Level Set for Interface tracking
  - Governing equations
- 2 Ghost Fluid Methods**
  - Finite volume
  - Applications: 1D Cases
- 3 Extension to unstructured meshes**
  - Finite Volume
  - 2D Applications
- 4 Conclusions, Coming and Future work**
  - DG approach for the level set equation
  - Finite Element

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# Interfaces flow model

## Interface Model: bi-fluid case

The interface  $\mathcal{S}$  is the zero of a single level set function  $\phi$ .

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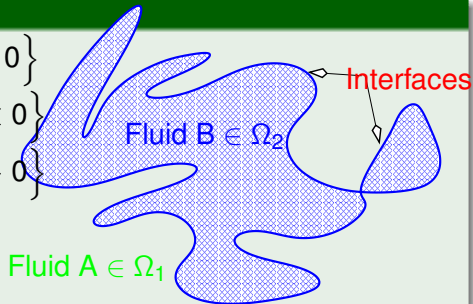
The interface  $\mathcal{S}$  is the zero of a single level set function  $\phi$ .

### Example

$$\mathcal{S}(t) = \{x \text{ such that } \phi(t, x) = 0\}$$

$$\Omega_1(t) = \{x \text{ such that } \phi(t, x) < 0\}$$

$$\Omega_2(t) = \{x \text{ such that } \phi(t, x) > 0\}$$



# Dynamic of the Level set function

## Transport Equation formulation

$$\partial_t \phi + \mathbf{u}(\phi) \cdot \nabla \phi = 0$$

where  $\phi$  is any regular function such that  $\phi(t, x) = 0$  for  $x \in \mathcal{S}(t)$

$\mathbf{u}(\phi)$ , the velocity field, function of the interface motion.

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## Hamilton-Jacobi formulation

$$\partial_t \phi + F(\nabla \phi) |\nabla \phi| = 0, \quad \text{where} \quad F(\nabla \phi) = \frac{\mathbf{u}(\phi) \cdot \nabla \phi}{|\nabla \phi|}$$

In this context,  $\phi$  is usually a signed distance function.

**General Case :**  $\Omega = \Omega_1(t) \cup \Omega_2(t) \cup \mathcal{S}(t)$ .

### Mathematical Model

$$\mathcal{L}_1 \omega_1 = 0 \quad \text{for } \phi(t, x) < 0 \quad (1)$$

$$\mathcal{L}_2 \omega_2 = 0 \quad \text{for } \phi(t, x) > 0 \quad (2)$$

$$\mathcal{G}_1 \omega_1 - \mathcal{G}_2 \omega_2 = \Sigma(\phi, \omega_1, \omega_2) \quad \text{for } \phi(t, x) = 0 \quad (3)$$

$$\partial_t \phi + \mathbf{u}(\phi, \omega_1, \omega_2) \cdot \nabla \phi = 0 \quad \text{for } (t, x) \in [0, T] \times \Omega \quad (4)$$

Definitions : ( )

- ①  $\mathcal{L}_k$  and  $\omega_k$  are differential operator and the set of the unknown, relevant for the flow description in the region  $\Omega_k$ .
- ②  $\mathcal{G}_k$ ,  $\mathbf{u}(\phi, \omega_1, \omega_2)$  and  $\Sigma(\phi, \omega_1, \omega_2)$  are associated to jump conditions and waves transmission at interfaces.

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# Compressible/Compressible Interfaces

## Assumptions

We assume that pure fluids are inviscid, compressible and flow described anywhere by the conservative Euler Equations.

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$$\omega_k \equiv \omega = (\rho, \rho U, p_e)^T$$

$$\mathcal{L}_k \omega_k = \partial_t \omega + \nabla \cdot f(\omega, p_k);$$

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- $\mathcal{G}_k(\phi) \omega_k = (\mathbf{u}|_S \cdot \nabla \phi) \boldsymbol{\omega} + \nabla \phi \cdot \mathbf{f}(\boldsymbol{\omega}, p|_S)$

- $\Sigma(\phi, \omega_1, \omega_2) \equiv 0$  *in absence of tension forces, chemical reaction and phase transition.*

- How are defined  $\mathbf{u}|_S$  and  $p|_S$ ? Shock or CD?*

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# Equation of State (EOS)

## Mie-Gruneisen family of equation of state

$$\Gamma_k(\rho)p_k + \pi_k(\rho) = \rho\varepsilon \quad \text{with} \quad \varepsilon = e - \mathbf{u} \cdot \mathbf{u}/2,$$

where  $\Gamma(\rho)$  and  $\pi_k(\rho, \varepsilon)$  are given functions.

## Example (Perfect Gas EOS)

$$\Gamma(\rho) = \frac{1}{\gamma - 1}, \quad \pi(\rho) = 0, \quad c^2 = \frac{\gamma p}{\rho}$$

## Example (Modified Tait's EOS)

$$\Gamma(\rho) = \frac{1}{m - 1}, \quad \pi(\rho) = \frac{m(\pi_* - \pi_0)}{m - 1},$$

Water :  $m = 7.15$ ,  $\pi_* = 3.3110^8 Pa$ ,  $\pi_0 = 10^5 Pa$

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# Finite volume formulation

## Explicit scheme

- $a_i \omega_i^{n+1} = a_i \omega_i^n - \sum_{j \in \nu(i)} \Phi(\mathbf{n}_{ij}, \omega_i^n, \omega_j^n) - \sum_{j \in \kappa(i)} \Phi_S(\mathbf{n}_{ij}, \omega_i^n, \omega_j^n)$
- $a_i \phi_i^{n+1} = a_i \phi_i^n - \mathcal{R}_i(\phi^n, \omega^{n+1})$

- 1  $j \in \nu(i)$  is a neighbor cell of  $i$  such that  $\phi_i^n \phi_j^n > 0$ .  
The flux  $\Phi$  is a classical one (Roe, HLL, HLLC).
- 2  $j \in \kappa(i)$  is a neighbor cell of  $i$  such that  $\phi_i^n \phi_j^n < 0$ .  
The flux  $\Phi_S$  have to be consistent with jump conditions and wave transmission at the interface.

# Ghost Fluid Method Principle

## Use a classical Flux with ghost states

$$\Phi_S \left( \mathbf{n}_{ij}, \omega_i^n, \omega_j^n \right) \simeq \Phi \left( \mathbf{n}_{ij}, \tilde{\omega}_i^n, \tilde{\omega}_{ij}^n \right) \text{ where } \tilde{\omega} = \tilde{\omega}(\tilde{\rho}, \tilde{\mathbf{u}}, \tilde{p})$$

## Properties of ghost states

The ghost states should be such as the flux  $\Phi \left( \mathbf{n}_{ij}, \tilde{\omega}_i^n, \tilde{\omega}_{ij}^n \right)$  be consistent with

- the jump conditions (static constraint),
- the wave transmission (dynamic constraint).



# Original Ghost Fluid Method (Fedkiw et al. 99)

## Strategy based on static constraint: jump conditions

$$\tilde{\omega}_i = \omega_i, \quad \text{and} \quad \tilde{\omega}_{ij} = \tilde{\omega}_{ij}(\rho_{ij}, \mathbf{u}_j, p_j)$$

where  $\rho_{ij}$  is given by  $s(\rho_i, p_i) = s'(\rho_{ij}, p_j)$

$\rho_{ij}$  is an evaluation of the density close to the interface.

## Implicit assumptions

- Equation with entropy functions  $s$  and  $s'$ , is invertible.  
OK for perfect gas and some Mie-Grunieson EOS.
- Entropy can be extrapolated “near” the interface.

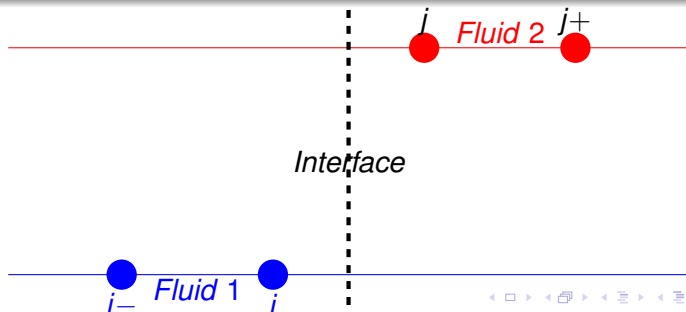
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## Isobaric fix (Fedkiw et al. JCP, 1999)

In order to prevent overheating errors in the GFM method

$$\tilde{\omega}_i = \tilde{\omega}_i(\rho_{i-}, \mathbf{u}_i, p_i), \quad \tilde{\omega}_{ij} = \tilde{\omega}_{ij}(\rho_{ij}, \mathbf{u}_j, p_j), \quad s(\rho_{i-}, p_i) = s'(\rho_{ij}, p_j)$$

Neighbor cells in **1D Case** :  $i- = i - 1, j = i + 1, j+ = j + 1$ .



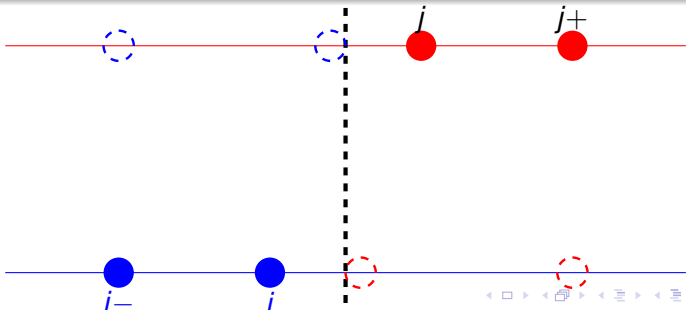
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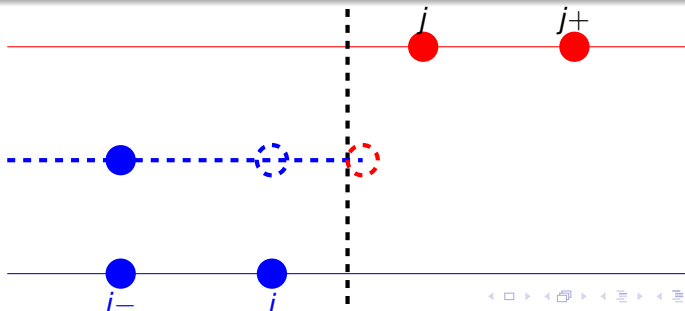
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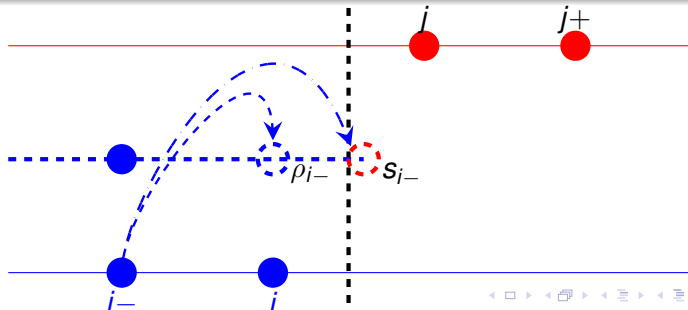
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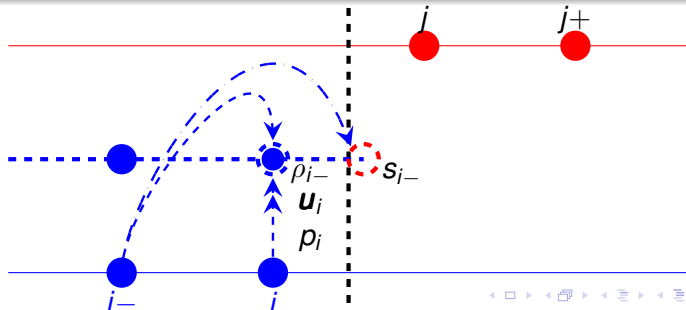
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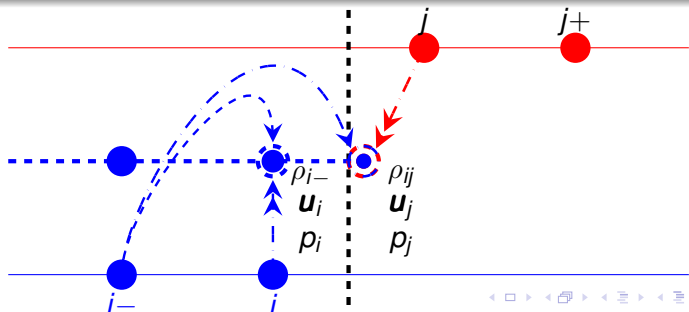
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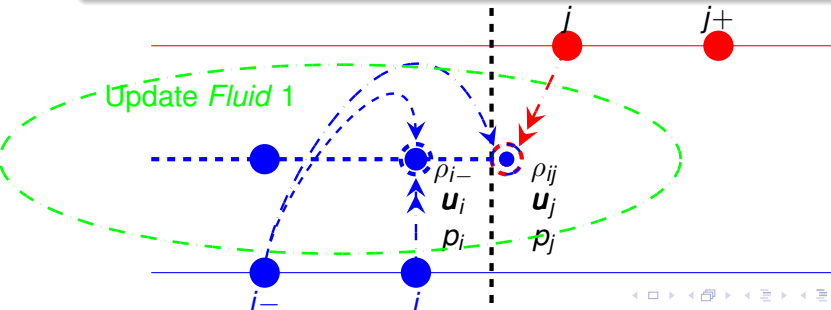
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Neighbor cells in 1D Case :  $i- = i - 1, j = i + 1, j+ = j + 1$ .



# Modified Ghost Fluid Method (Liu et al. 03)

Strategy mixing static and dynamic constraints.

## Wave transmission: two-shock bi-fluid solver

$$dp + \tilde{\rho}_+ \tilde{c}_+ du = 0 \quad \text{along} \quad \frac{dx}{dt} = \tilde{u} + \tilde{c}_+ \quad (5)$$

$$dp - \tilde{\rho}_- \tilde{c}_- du = 0 \quad \text{along} \quad \frac{dx}{dt} = \tilde{u} - \tilde{c}_- \quad (6)$$

$u = \mathbf{u} \cdot \nabla\phi/|\nabla\phi|$ , is the normal velocity.

## Jump conditions on material interfaces

$$p_{ij} = p_{ji} = \tilde{p}, \quad u_{ij} = u_{ji} = \tilde{u}$$

# Modified Ghost Fluid Method (Liu et al. 03)

Jump conditions in a pure fluid gives  $\tilde{\rho}$  as a function of  $\tilde{p}$

$$\left[ \frac{(1 + \Gamma_k(\rho)) p_k + \pi_k(\rho)}{\rho} + p_k \right] = 0 \longrightarrow \begin{cases} \tilde{\rho}_i(\tilde{p}, \omega_{i-}), \\ \tilde{\rho}_j(\tilde{p}, \omega_{j+}) \end{cases}$$

Nonlinear system defining  $\tilde{p}$  and  $\tilde{u}$

$$\tilde{u} - u_{i-} = \int_{p_{i-}}^{\tilde{p}} \frac{dp}{\tilde{a}_-(p)} \quad \text{and} \quad \tilde{u} - u_{j+} = - \int_{p_{j+}}^{\tilde{p}} \frac{dp}{\tilde{a}_+(p)}.$$

$\tilde{a}_-$  and  $\tilde{a}_+$  are approximated acoustic impedances.

# Modified Ghost Fluid Method (Liu et al. 03)

## M-GFM

$$\omega_i \equiv \tilde{\omega}_i = \tilde{\omega}_i(\tilde{\rho}_i, \tilde{\mathbf{u}}_i, \tilde{p})$$

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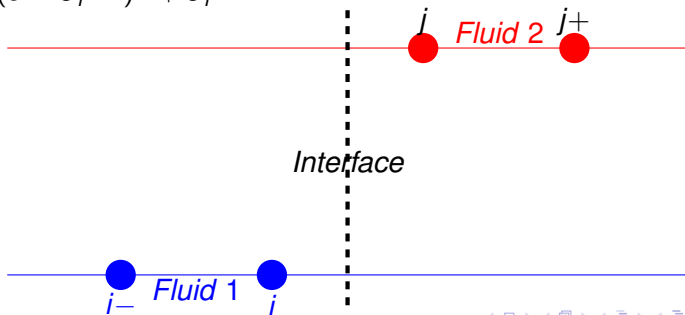
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## H-GFM

$$\tilde{\omega}_i = \tilde{\omega}_i(\bar{\rho}_i, \tilde{\mathbf{u}}_i, \tilde{p})$$

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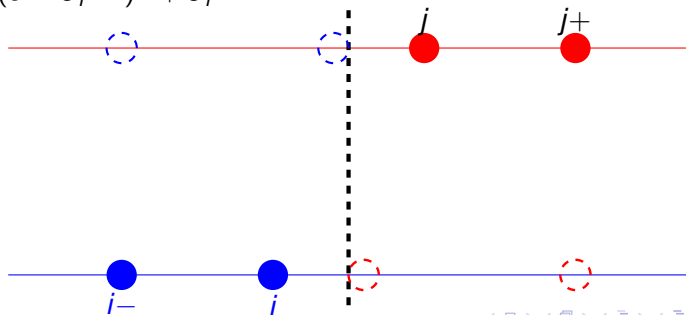
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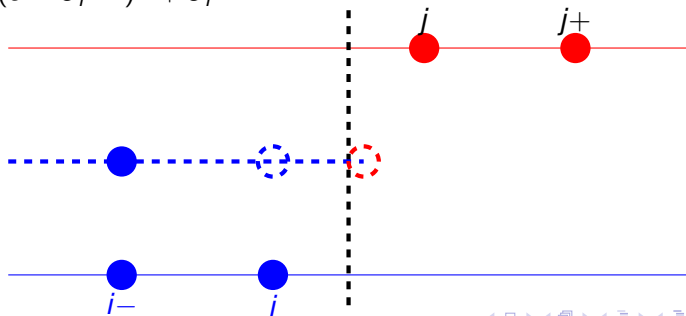
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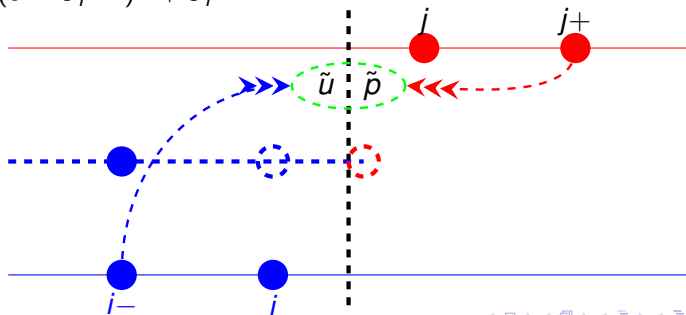
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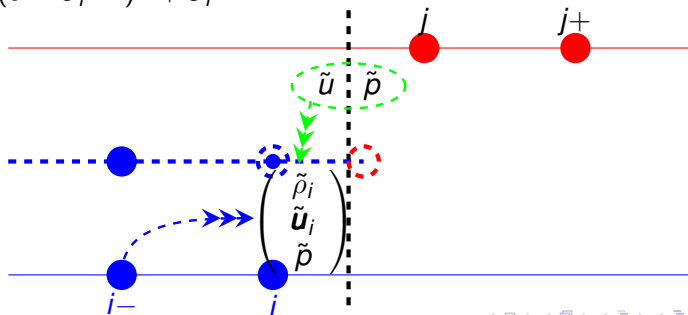
$$\tilde{\mathbf{u}}_i = (\tilde{u} - \mathbf{u}_i \cdot \mathbf{n})\mathbf{n} + \mathbf{u}_i$$

## H-GFM

$$\tilde{\omega}_i = \tilde{\omega}_i(\bar{\rho}_i, \tilde{\mathbf{u}}_i, \tilde{p})$$

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# Modified Ghost Fluid Method (Liu et al. 03)

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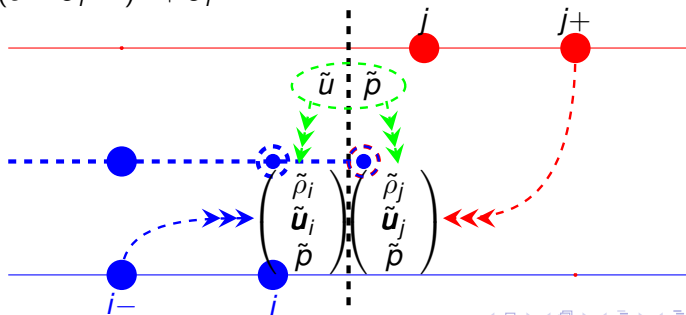
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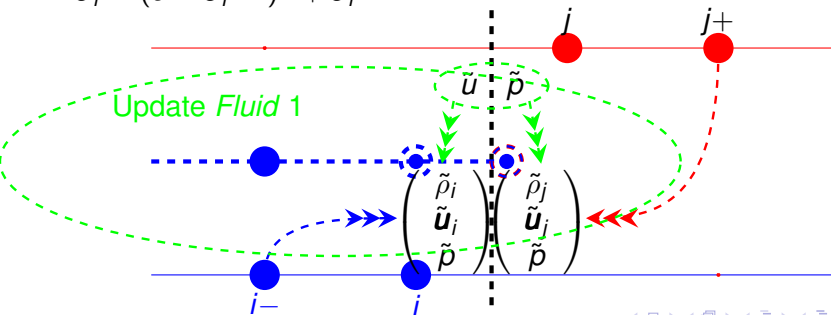
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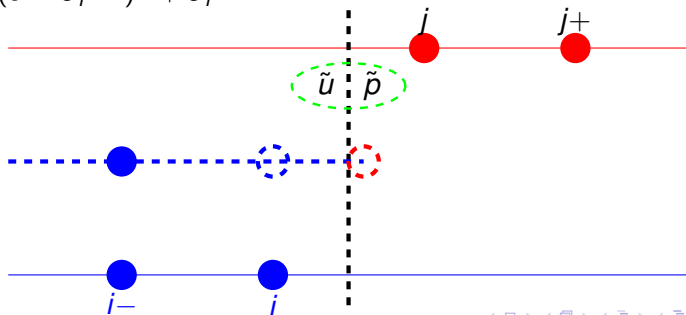
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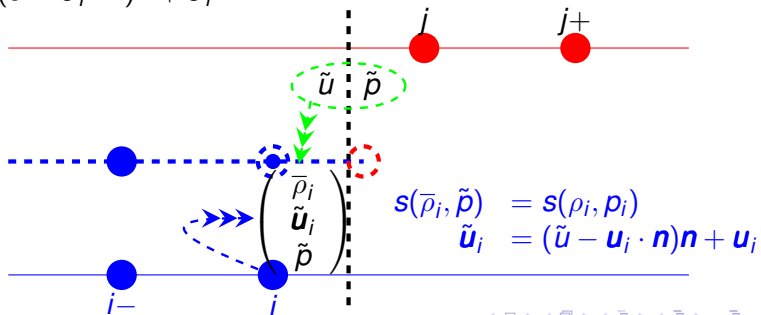
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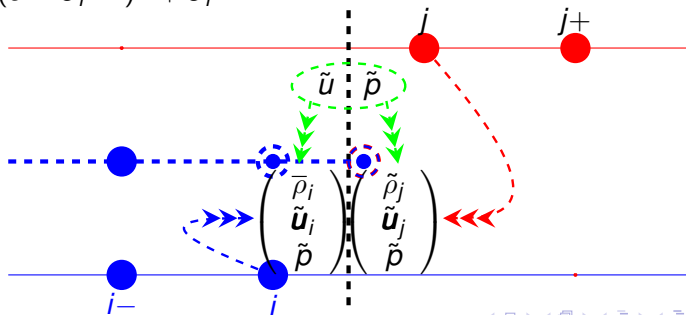
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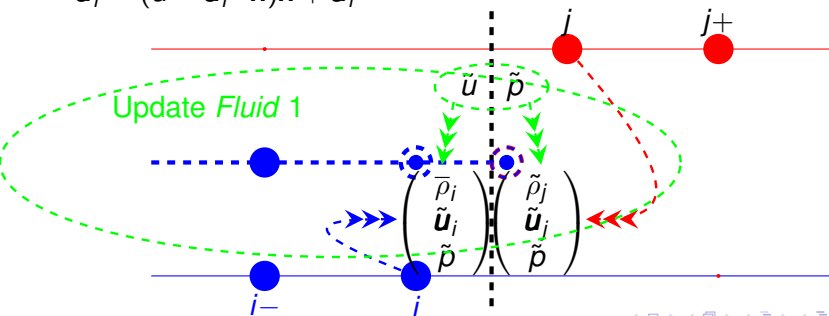
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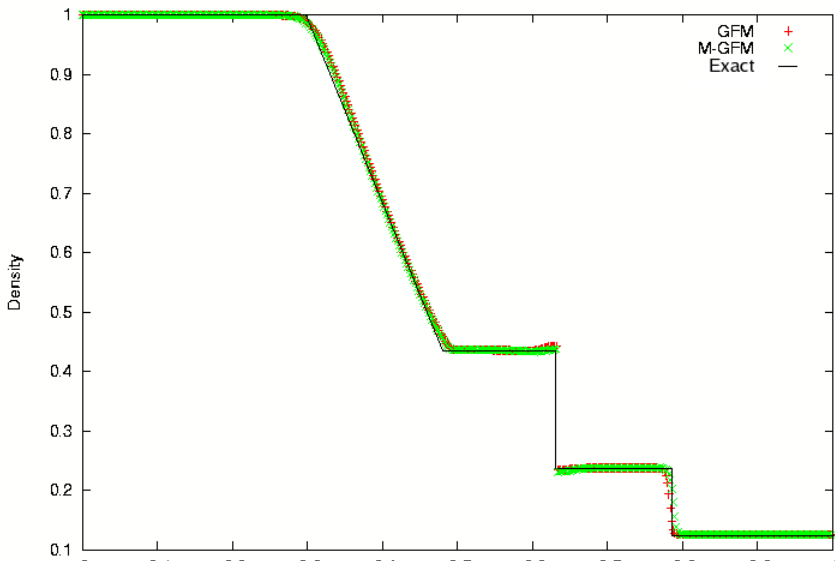
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Applications: 1D Cases

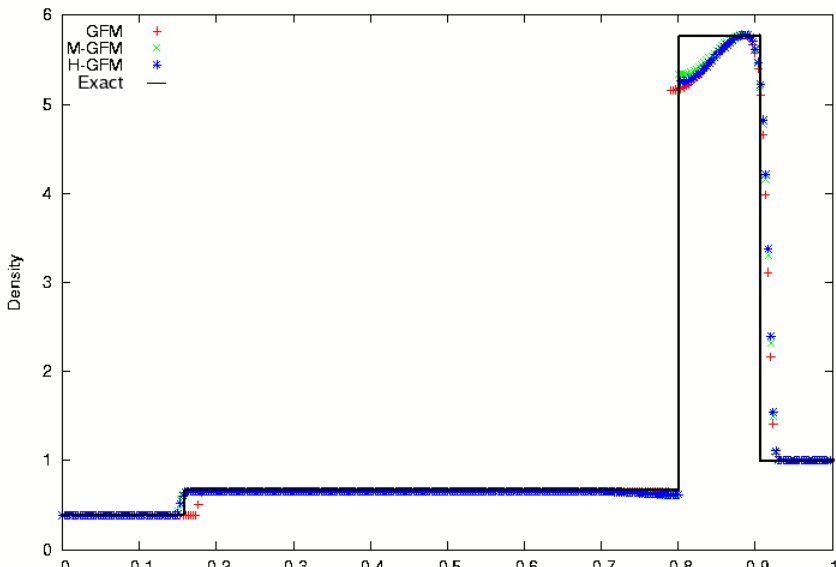
# Sod shock tube





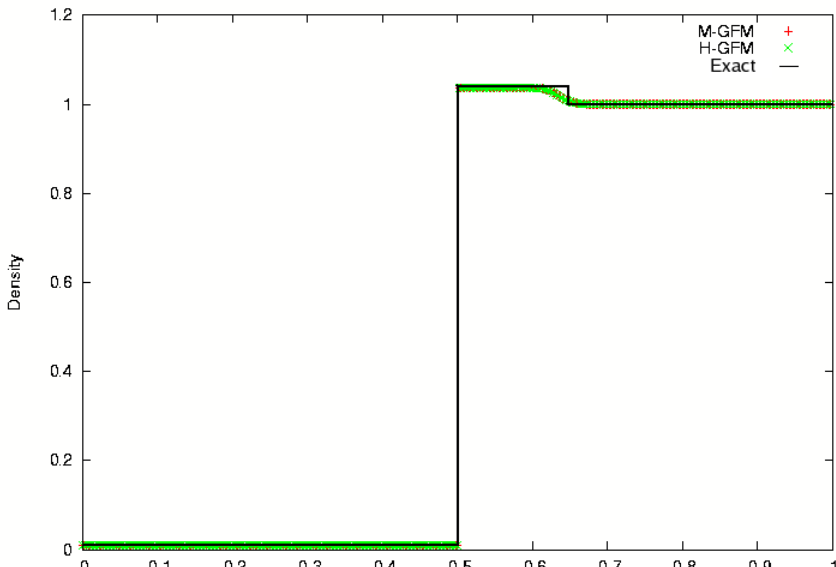
Applications: 1D Cases

# Helium-Air shock tube



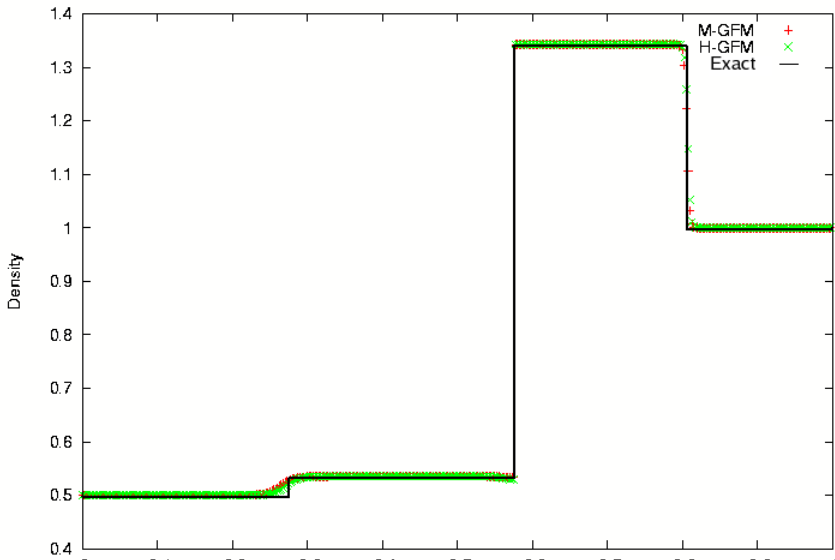
Applications: 1D Cases

# Shock interaction with Water-Air interface



Applications: 1D Cases

# Stronger shock interaction with Water-Air interface



# Outline

- 1 Interfaces flow Model
  - Level Set for Interface tracking
  - Governing equations
- 2 Ghost Fluid Methods
  - Finite volume
  - Applications: 1D Cases
- 3 Extension to unstructured meshes**
  - Finite Volume
  - 2D Applications
- 4 Conclusions, Coming and Future work
  - DG approach for the level set equation
  - Finite Element

# Multi-D Finite volume schemes

## Directions Based Schemes

$$a_i \omega_i^{n+1} = a_i \omega_i^n - \sum_{j \in \nu(i)} \Phi(\mathbf{n}_{ij}, \omega_i^n, \omega_j^n) - \sum_{j \in \kappa(i)} \Phi_S(\mathbf{n}_{ij}, \omega_i^n, \omega_j^n)$$

$$\Phi_S(\mathbf{n}_{ij}, \omega_i^n, \omega_j^n) = \Phi(\mathbf{n}_{ij}, \tilde{\omega}_i^n, \tilde{\omega}_j^n)$$

$$\tilde{\omega}_i^n = \tilde{\omega}(\omega_i, \omega_j, \nabla \phi|_{ij}, \omega_{i-}, \omega_{j+})$$

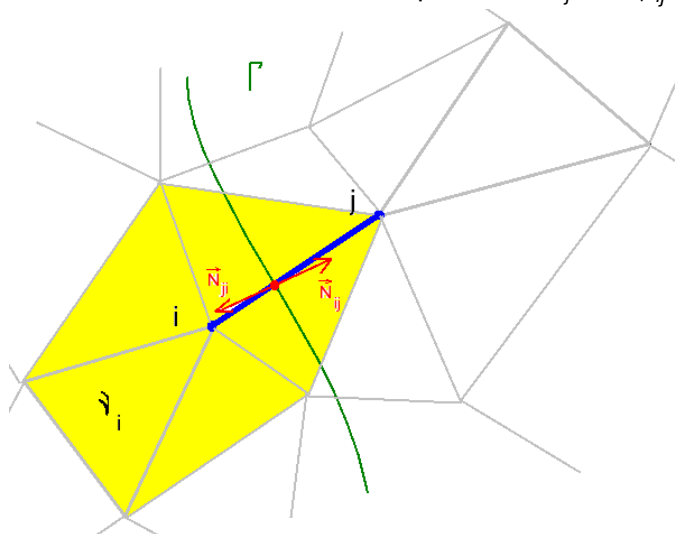
$$\tilde{\omega}_j^n = \tilde{\omega}(\omega_i, \omega_j, \nabla \phi|_{ij}, \omega_{i-}, \omega_{j+})$$

## Need to be defined

- The interface normal  $\nabla \phi|_{ij}$
- The states  $\omega_{i-}$  and  $\omega_{j+}$

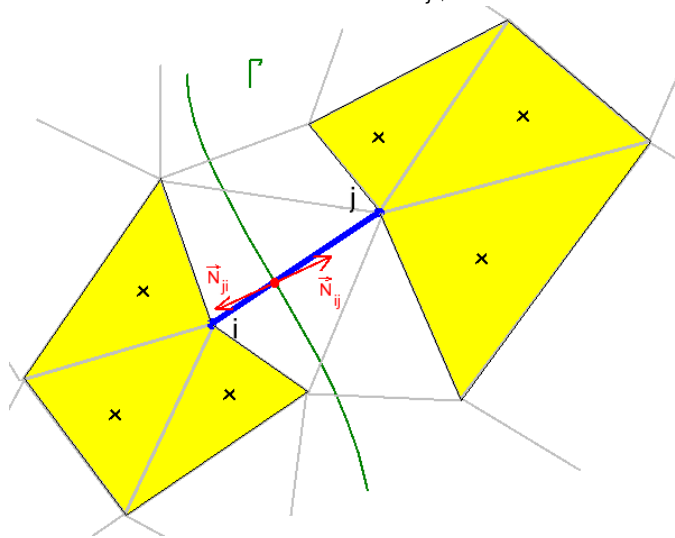
# Interfaces parameters for GFM

Stencil for interface normal computation:  $N_{ij} = \vec{\nabla} \varphi_{ij}$



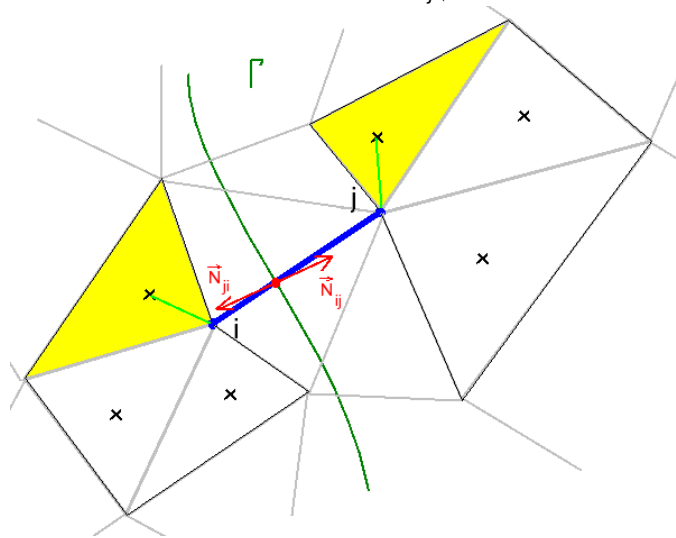
# Interfaces parameters for GFM

Stencil for “isobaric 1”  $\omega_{i-}$  and  $\omega_{j+}$



# Interfaces parameters for GFM

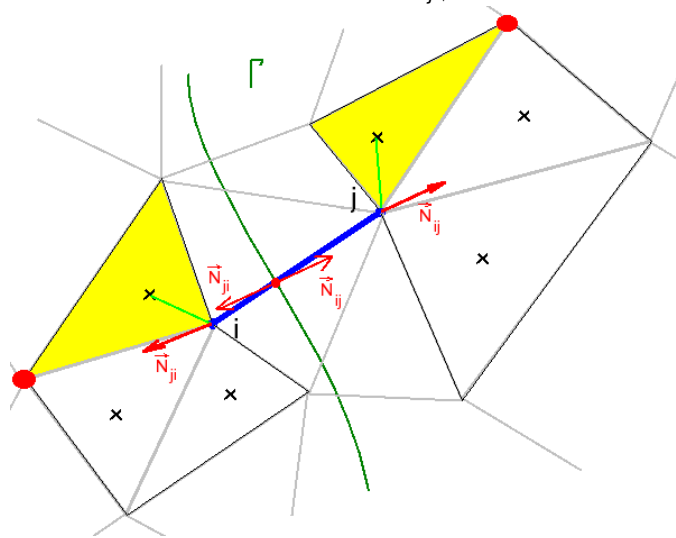
Stencil for “isobaric 2”  $\omega_{i-}$  and  $\omega_{j+}$





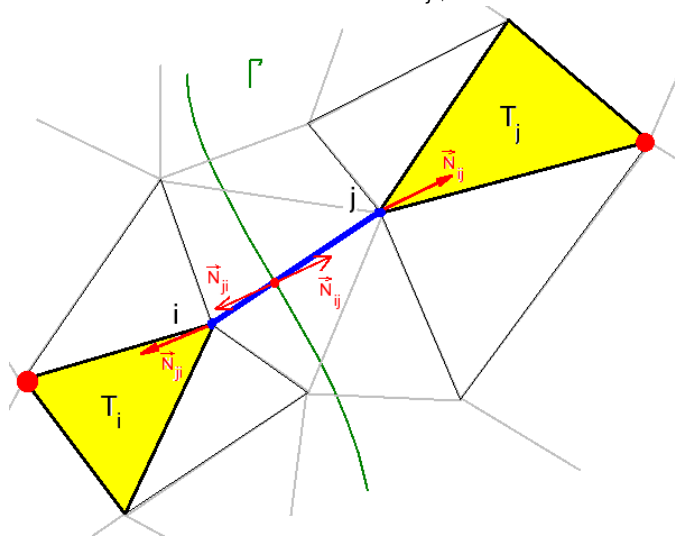
# Interfaces parameters for GFM

Stencil for “isobaric 3”  $\omega_{i-}$  and  $\omega_{j+}$



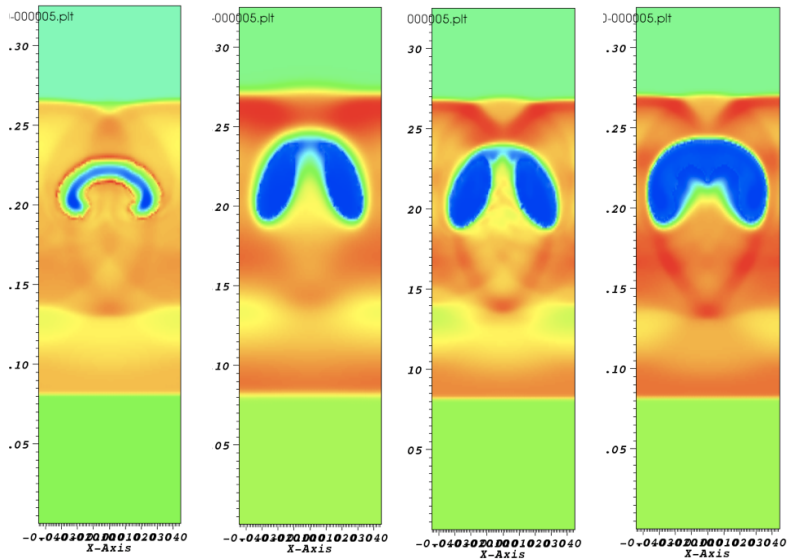
# Interfaces parameters for GFM

Stencil for “isobaric 4”  $\omega_{i-}$  and  $\omega_{j+}$



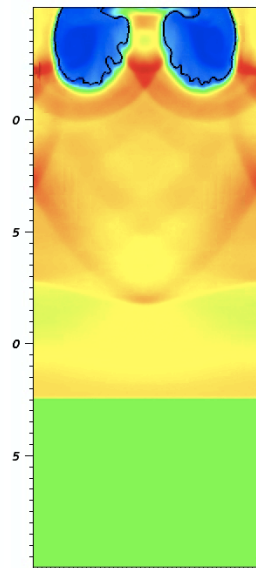
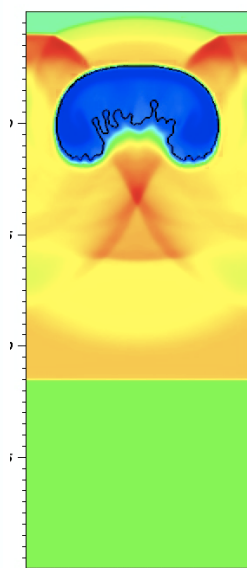
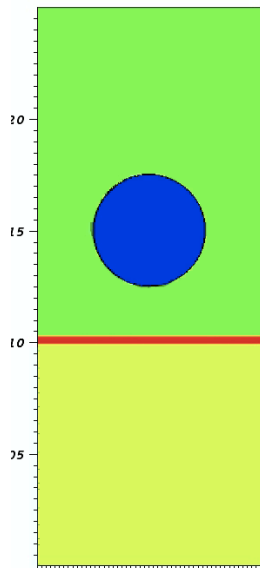
## 2D Applications

## Shock/bubble interaction: Air-Helium



## 2D Applications

## Shock/bubble interaction: Air-water



## 2D Applications

# Shock/bubble interaction: Air-Helium

(blabla)

2D Applications

# Shock/bubble interaction: Air-water

2D Applications

# Shock/bubble interaction: Air-water

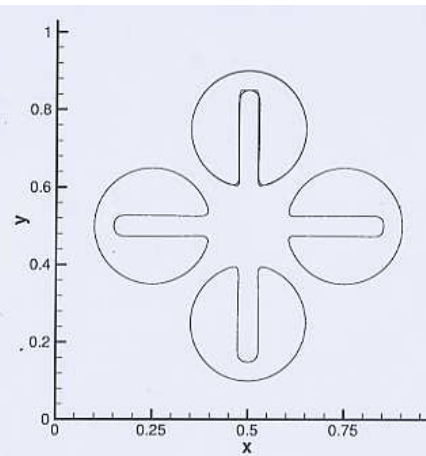
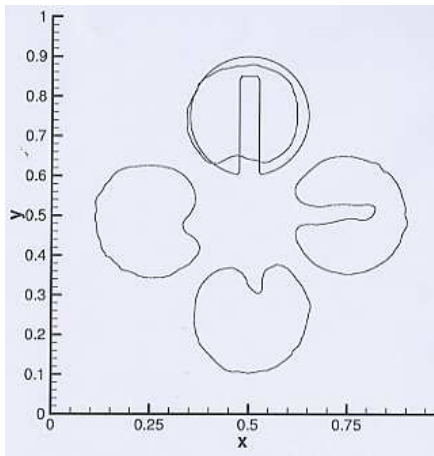
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  - Finite Element



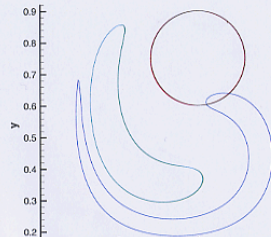
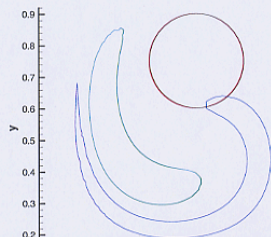
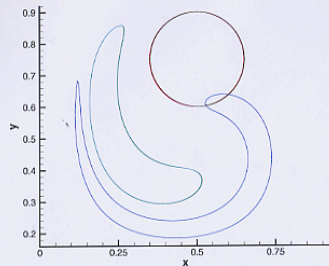
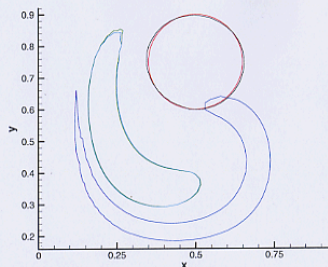
DG approach for the level set equation

# DG for the transport of the level set



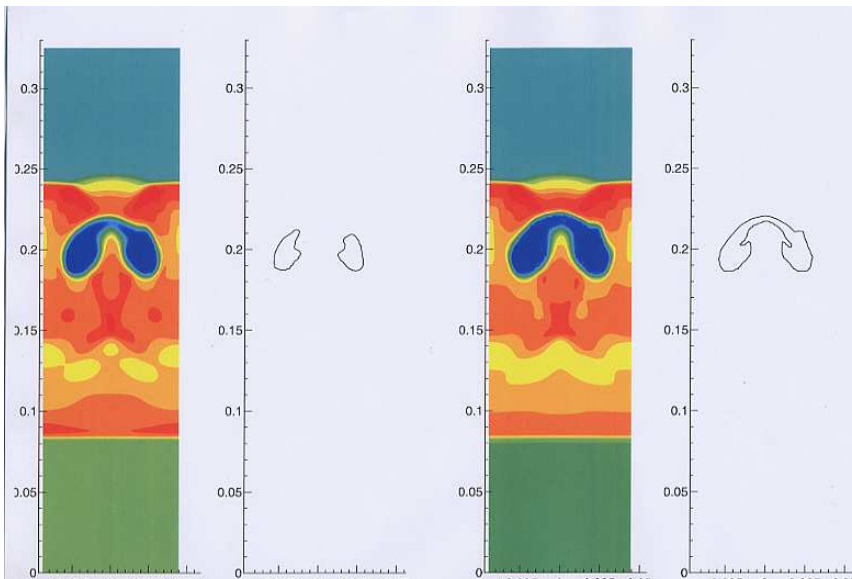
DG approach for the level set equation

# DG for the transport of the level set



DG approach for the level set equation

# Shock/bubble interaction: Barth vs. DG (P1)



# Compressible/Incompressible Interfaces

**Compressible Model:**  $\omega_1 = (\rho, \rho \mathbf{u}, \rho e)^T$  Hyperbolic system.

Compressible component is defined as previously.

**Incompressible Model:**  $\omega_2 = (\pi, \mathbf{u})^T$

- 1  $\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \frac{1}{\rho} \nabla \pi = 0$
- 2  $\nabla \cdot \mathbf{u} = 0$

# Finite element formulation

## Stabilized Galerkin method (with mass lumping)

- $a_i \omega_i^{n+1} = a_i \omega_i^n - \sum_{\tau \in T(i)} \Phi(\omega_\tau^n) - \sum_{\tau \in K(i)} \Phi_S(\omega_\tau^n)$
- $a_i \phi_i^{n+1} = a_i \phi_i^n - \mathcal{R}_i(\phi^n, \omega^{n+1})$

## Stabilizations techniques

- SUPG for convection
- PSPG to handle LBB condition
- Grad-Div to enforce the incompressible constraint.

## Ghost Fluid

$$\Phi_S(\omega_\tau^n) = \Phi(\tilde{\omega}_\tau^n)$$

# Other Issues

## Example

- Deflagration Detonation (Fedkiw 1999)
- Eulerian Fluid/Lagrangian Solid (Fedkiw 2002, Cirak 2004)
- Thin flame and LES premixed combustion (Moureau et al. 2005)
- Phase transition (Gibou et al. 2006)
- Surface tension

## Main points to deal with

- 1 Define the equation for the level set function.
- 2 Set out appropriate jump conditions at the interfaces.

Les bonnes choses ont une fin !!!!!!!!!!! merci aux organisateurs !!!!!!!!!!!

# Thanks

and farewell!