

# Toward Validated Composition in Component-based Adaptive Middleware

Annie Ressouche<sup>1</sup> and Jean-Yves Tigli<sup>2</sup> and Oscar Carrillo<sup>1</sup>

<sup>1</sup>Inria Sophia-Antipolis Méditerranée (Pulsar team)

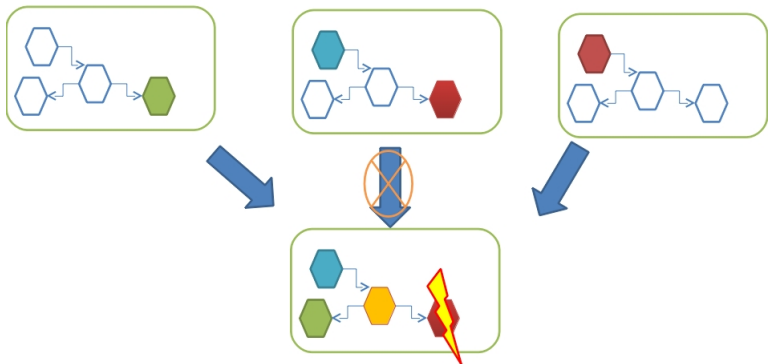
<sup>2</sup>Nice Sophia Antipolis University and CNRS (Rainbow team)

SC 2011




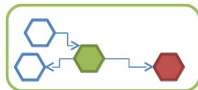
## Motivation

- Challenge in **adaptive** middleware : How to manage interaction and sometimes conflicts between multiple ambient applications ?




## Our Approach

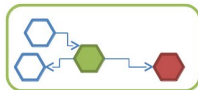
- 1 Need for validation on the critical component 
  - Introduction of a **synchronous monitor** to manage such a component



- 2 Need for formal and sound **composition** operation


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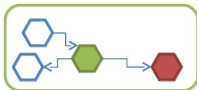
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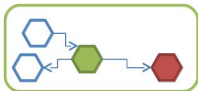


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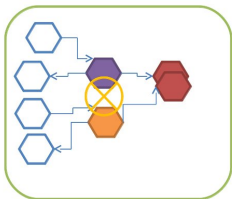


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- 2 Need for formal and sound **composition** operation
  - Synchronous composition of monitors

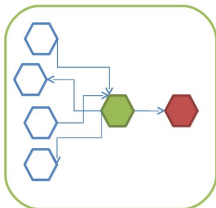


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# Outline

- 1 Introduction
- 2 Use case Introduction
- 3 Components with Validated Behaviors
  - Component Behavior as Synchronous Model
  - Synchronous Monitors
  - Component Behavior Validation
- 4 Synchronous Monitor Composition
  - Multiple Access to Critical Components
  - Synchronous Monitor Composition
  - Composition and Validation
- 5 Practical Issues
  - WComp Middleware
  - WComp Synchronous Monitor Specification
  - Use Case Specification
  - Use Case Monitor Composition
  - Use Case Validation
  - Use case Implementation in WComp
- 6 Future Work



- Monitor old adults in an instrumented home
- **Use case** : observe kitchen usage with :
  - ① a **camera** sensor ( to locate the person)
  - ② a **fridge** sensor (contact sensor on the door)
  - ③ a **timer** sensor
  - ④ a **posture** sensor ( accelerometers)
- **Goal** : send the appropriate alarm (warning, weak\_alarm, strong\_alarm)



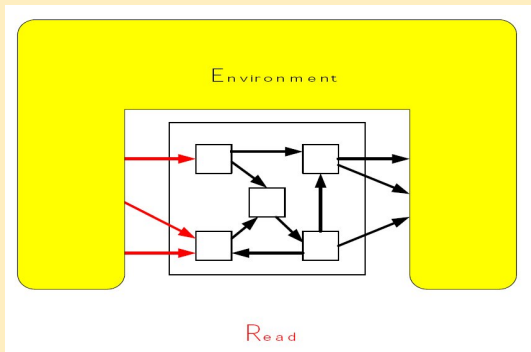
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## Synchronous Modeling

- **time model** : monitors listen to events and provide output events in reaction They could be response time sensitive and should support formal validation( $\Rightarrow$  **determinism**)
- component behavior models = synchronous models
- Synchronous models can be expressed as **Mealy Machine**

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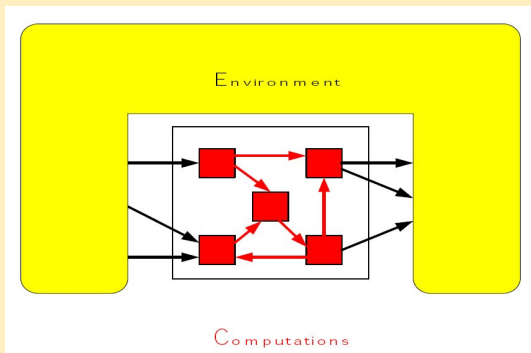
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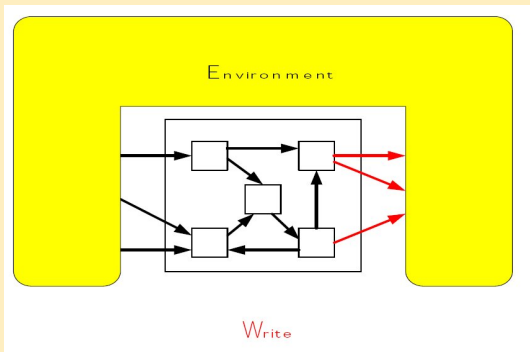
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Synchronous models respect the *synchronous hypothesis*
  - Succession of reactions  $\Rightarrow$  **logical time**
  - **Broadcasting** of events (non blocking communication)
  - Reactions are **atomic** : input and resulting output events are **simultaneous**
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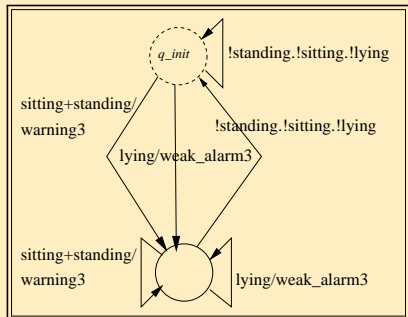


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## Mealy machines

- both finite automata and synchronous models
- model-checking techniques apply



$\langle Q, q^{init}, I, O, \mathcal{T}, \lambda \rangle :$

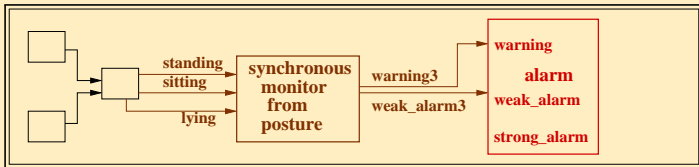
- $Q$  : finite set of states
- $q^{init} \in Q$  : initial state
- $\mathcal{T} \subseteq Q \times Q$  : transition relation
- $\lambda : \mathcal{T} \times I^B \mapsto 2^{O_\epsilon}$  : labeling function

## Synchronous Monitors

- Critical components ( $C$ ) will provide a synchronous model of their behaviors as a Mealy machine ( $M$ )
- If  $M = \langle Q, q^{init}, I, O, \mathcal{T}, \lambda \rangle$  and  $I_C$  is the input event set of  $C$ , there is an injective mapping :  $in : O \mapsto I_C$

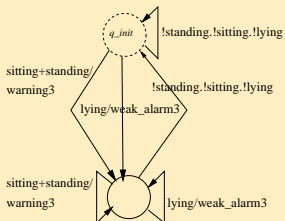
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## Component Behavior Validation

- **model-checking** techniques apply in our approach
- properties =  $\forall CTL^*$  formulas
- formulas interpreted over **Kripke structure**
  - detail
- $M \mapsto \mathcal{K}(M)$ .

### Definition

$M \models \psi$  iff  $\mathcal{K}(M) \models \psi$  and iff each initial state of  $\mathcal{K}(M)$  satisfies  $\psi$

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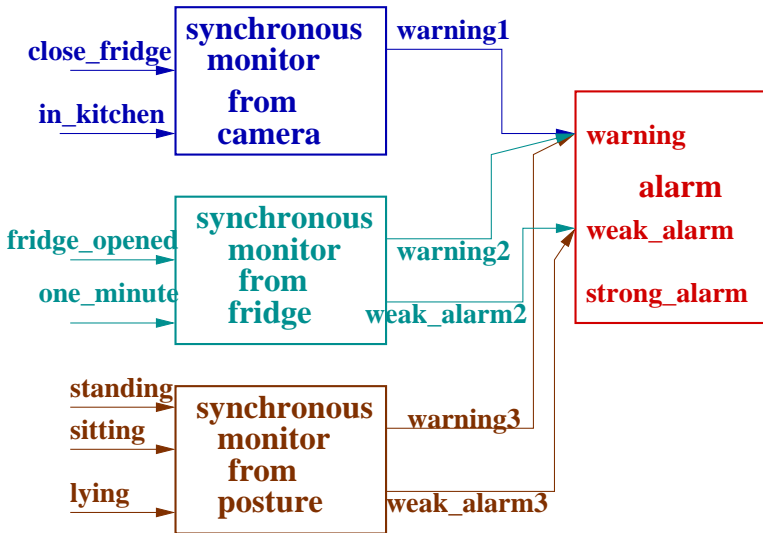
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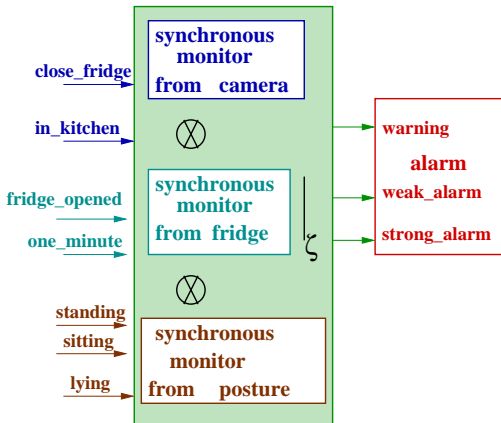
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A critical component may have multiple synchronous monitors :





## Composition under constraints



## Composition with constraints

- synchronous product ( $\otimes$ )
- constraint function ( $\zeta$ )

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$$M_1 = \langle Q_1, q_1^{init}, l_1, O_1, \mathcal{T}_1, \lambda_1 \rangle$$

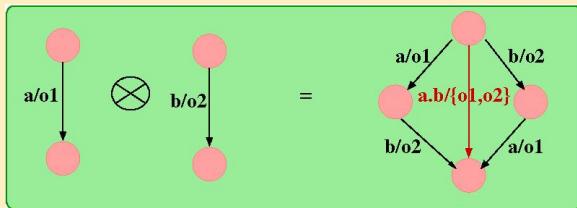
$$M_2 = \langle Q_2, q_2^{init}, l_2, O_2, \mathcal{T}_2, \lambda_2 \rangle$$

$$M_1 \otimes M_2 = \langle Q_1 \times Q_2, (q_1^{init}, q_2^{init}), l_1 \cup l_2, O_1 \cup O_2, \mathcal{T}, \lambda \rangle :$$

- $\mathcal{T} = \{((q_1, q_2), (q'_1, q'_2)) \mid (q_1, q'_1) \in \mathcal{T}_1, (q_2, q'_2) \in \mathcal{T}_2\}$ ;
- $\lambda(((q_1, q_2), (q'_1, q'_2)), i_1 \cdot i_2) = o_1 \cup o_2$  if there is  
 $(q_1, q'_1) \in \mathcal{T}_1 \mid \lambda_1((q_1, q'_1), i_1) = o_1$  and  
 $(q_2, q'_2) \in \mathcal{T}_2 \mid \lambda_2((q_2, q'_2), i_2) = o_2$

## Composition with constraints

- **synchronous product** ( $\otimes$ )
- **constraint function** ( $\zeta$ )



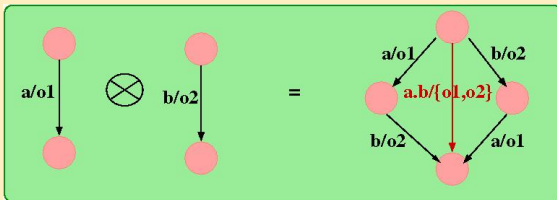
## Composition with constraints

- synchronous product ( $\otimes$ )
- constraint function ( $\zeta$ )

- 1 Define the **output set**  $O$  of the composition monitor such that there is an injection  $in : O \mapsto I_C$
- 2 Define a **surjective function**  $\gamma : O_1 \cup O_2 \cup O_1 \times O_2 \mapsto O_\epsilon$  according to the respective injection from monitor output events and  $I_C$  :
  - $\forall o_1 \in O_1, \gamma(o_1) = o$  and  $in(o) = in_1(o_1)$
  - $\forall o_2 \in O_2, \gamma(o_2) = o$  and  $in(o) = in_2(o_2)$
- 3 Deduce the **constraint function**  $\zeta : 2^{O_1 \cup O_2} \mapsto 2^O$  :  
 $\forall o \in 2^{O_1 \cup O_2}$ , if  $\exists o_1, o_2 \in o$  such that  $\gamma(o_1, o_2) \neq \epsilon$  then  $\gamma(o_1, o_2) \in \zeta(o)$ ; else  $\gamma(o_1) \in \zeta(o)$  and  $\gamma(o_2) \in \zeta(o)$

## Composition with constraints

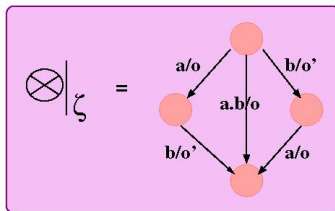
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$$O = \{o, o'\}$$

$$\zeta: o1 \rightarrow o$$

$$o2 \rightarrow o'$$

$$\{o1, o2\} \rightarrow o$$


## $\forall CTL^*$ formula preservation

- Goal : ensure that  $\forall CTL^*$  properties are preserved through composition under constraints ;
- Means :
  - Show that  $\mathcal{K}(M_1 \otimes |_{\zeta} M_2)$  ( $K_{\zeta}$ ) approximates  $\mathcal{K}(M_1)$  ( $K_1$ ) ;
  - Define a translation  $\tau_{\zeta}$  to map  $\forall CTL^*$  properties related to  $M_1$  to properties related to  $(M_1 \otimes |_{\zeta} M_2)$  ;
  - Prove that  $K_1 \models \phi \Rightarrow K_{\zeta} \models \tau_{\zeta}(\phi)$  ;
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## Lemma

$K_\zeta$  approximates  $K_1$

## Approximation

- 1 there is a surjective mapping  $h_a : A_\zeta \mapsto A_1$
- 2 there is a surjective mapping  $h : \mathcal{K}Q_\zeta \mapsto \mathcal{K}Q_1$  such that  $h(q_\zeta) = q_1 \Rightarrow \forall a_1 \in L_1(q_1), \exists a_\zeta \in L_\zeta(q_\zeta)$  and  $h_a(a_\zeta) = a_1$ .
- 3  $q_\zeta \longrightarrow q'_\zeta$  is a transition of  $K_\zeta$  then  $h(q_\zeta) \longrightarrow h(q'_\zeta)$  is a transition in  $K_1$

## Definition

$\tau_\zeta$  :

- $\tau_\zeta(\text{true}) = \text{true}$  ;  $\tau_\zeta(\text{false}) = \text{false}$
- $\forall a_1 \in A_1, \tau_\zeta(a_1) = \bigvee_{a_\zeta \in A_\zeta} a_\zeta \mid h_a(a_1) = a_\zeta$
- extended to formulas according to logic syntax

## Theorem

*Let  $M_1$  and  $M_2$  be two Mealy machines and  $\phi$  a  $\forall CTL^*$  formula related to  $M_1$ , then  $M_1 \models \phi \Rightarrow M_1 \otimes |_\zeta M_2 \models \tau_\zeta(\phi)$*

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## WComp : our experimental middleware



- WComp, middleware for ubiquitous and ambient computing
- Based on services for devices software infrastructure
- Manage interactions between devices at runtime using a component-based architecture and event flows



## WComp Synchronous Monitor Specification

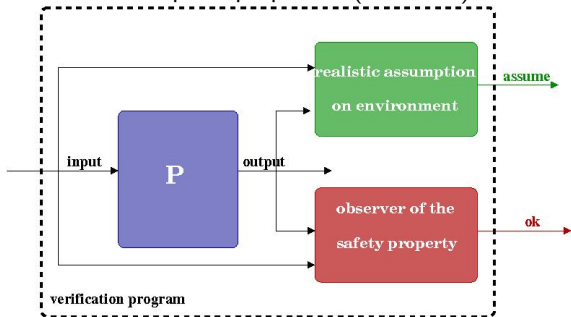
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  - respect of synchrony hypothesis
  - compilation generates mealy machines
  - synchronous product natural
  - constraint functions expressed as equations
  - well adapted to formal verification
- 2 **Lesar** model-checker to verify properties :
  - Bdd based model-checker
  - **observers** to express properties (in Lustre)

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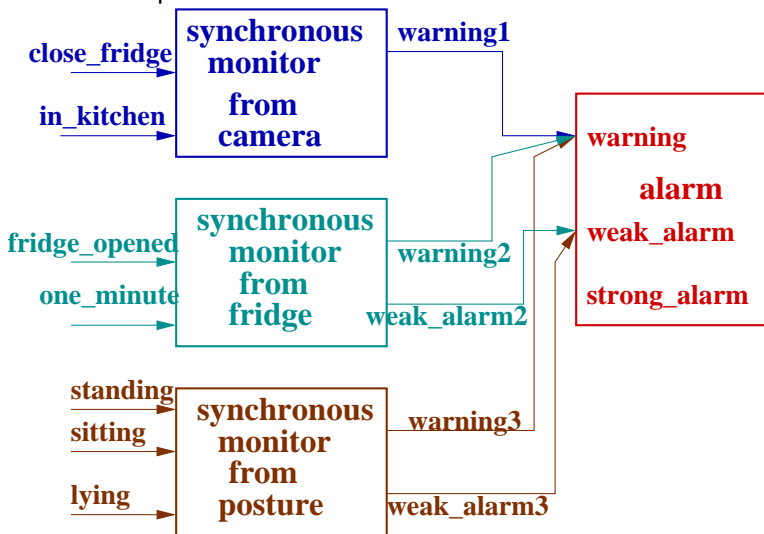
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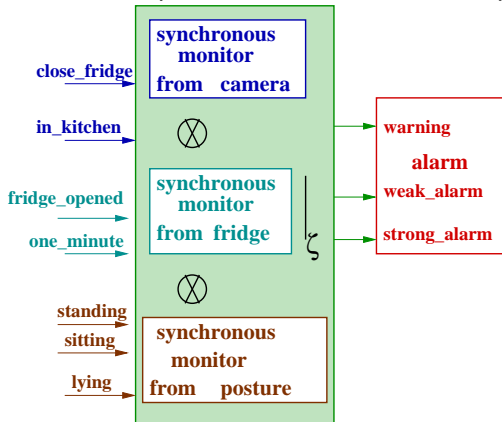


## Use Case Implementation



```
node camera(in_kitchen,close_fridge:bool) returns(warning1:bool)
let warning1 = in_kitchen and close_fridge;
tel
node fridge(fridge_opened, one_minute: bool)
  returns (warning2, weak_alarm2: bool);
let warning2= fridge_opened and not one_minute;
  weak_alarm2= fridge_opened and one_minute;
tel
node posture(sitting, standing,lying:bool)
  returns(warning3,weak_alarm3:bool)
let warning3 = (standing or sitting) and not lying;
  weak_alarm3 = not standing and not sitting and lying;
tel
```

## Use Case Implementation : monitor composition



```
node alarm_comp (close_fridge, fridge_opened, one_minute, standing,
                 sitting, lying, in_kitchen : bool)
  returns (warning, weak_alarm, strong_alarm : bool)

var warning1, warning2, warning3, weak_alarm2, weak_alarm3 : bool;
let  warning1 = camera(in_kitchen, close_fridge);
     (warning2, weak_alarm2) = fridge(fridge_opened, one_minute);
     (warning3, weak_alarm3) = posture(standing, sitting, lying);

warning = warning1 or warning2 or warning3 and not weak_alarm2
         and not weak_alarm3;
weak_alarm = weak_alarm2 xor weak_alarm3;
strong_alarm = weak_alarm2 and weak_alarm3;
tel
```

```
node verif (close_fridge, fridge_opened, one_minute, standing,
           sitting, lying, in_kitchen : bool) returns (prop: bool)
var warning, weak_alarm, strong_alarm : bool;
let (warning, weak_alarm, strong_alarm) =
    alarm_comp(close_fridge, fridge_opened, one_minute,
              standing, sitting, lying, in_kitchen);
    assert (not ((standing and lying) or (standing and sitting) or
                (lying and sitting)));
    prop = if (fridge_opened and one_minute and lying)
            then strong_alarm else true;
tel
```



```

node verif (close_fridge, fridge_opened, one_minute, standing,
           sitting, lying, in_kitchen : bool) returns (prop: bool)
var warning, weak_alarm, strong_alarm : bool;
let (warning, weak_alarm, strong_alarm) =
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    prop = if (fridge_opened and one_minute and lying)
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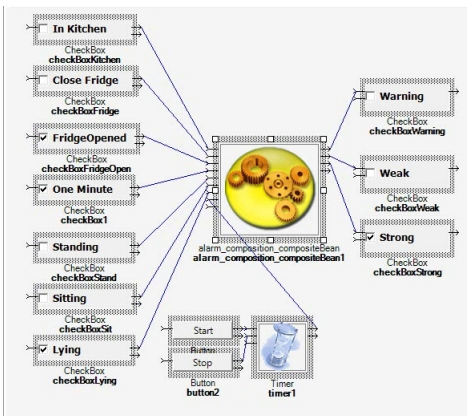
```

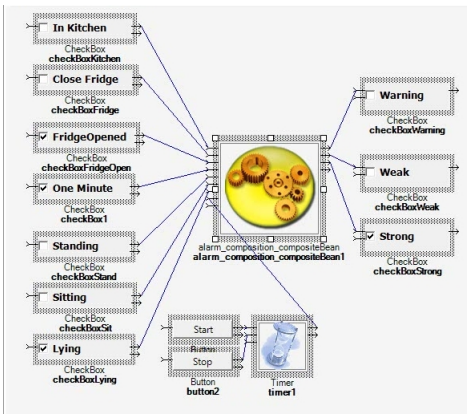
### Property Preservation

In **fridge** synchronous monitor :  $fridge\_opened \Rightarrow warning_2$

$\tau_c(warning_2) = warning$

In **alarm\_comp** monitor :  $fridge\_opened \Rightarrow warning$





SynComp tool offering :

- facilities to design synchronous monitor and observers
- automatic generation of WComp components for synchronous monitors

## Future Work

- 1 Improve constraint function expression (default rules) to get efficient adaptation
- 2 A dedicated language versus Lustre
- 3 Apply **Abstract Interpretation** methodology
  - To perform validation on complex value events
  - To strengthen runtime composition
- 4 Study how global properties can be decomposed into local ones (**assume-guarantee** paradigm)

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## Kripke Structure

A *Kripke structure*  $K$  is a tuple :  $K = \langle Q, Q_0, A, R, L \rangle$  where :

- $Q$  is a finite set of states ;
- $Q_0 \subseteq Q$  is the set of initial states ;
- $A$  is a finite set of atomic propositions ;
- $R \subseteq Q \times Q$  is a transition relation that must be total : for every state  $q \in Q$ , there is a state  $q'$  such that  $R(q, q')$  ;
- $L : S \mapsto 2^A$  is a labeling function that labels each state by the set of atomic propositions true in that state.

▶ return



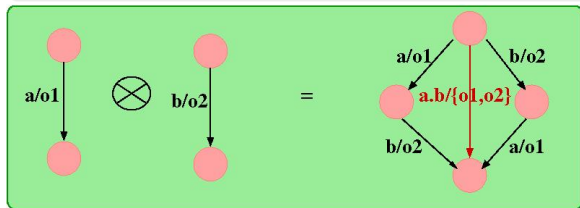
## Definition

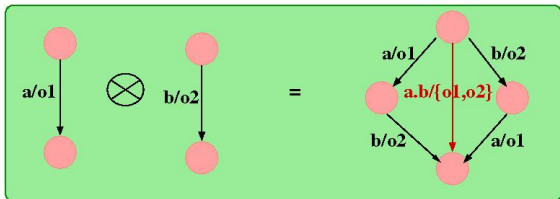
$$M_1 = \langle Q_1, q_1^{init}, l_1, O_1, \mathcal{T}_1, \lambda_1 \rangle$$

$$M_2 = \langle Q_2, q_2^{init}, l_2, O_2, \mathcal{T}_2, \lambda_2 \rangle$$

$$M_1 \otimes M_2 = \langle Q_1 \times Q_2, (q_1^{init}, q_2^{init}), l_1 \cup l_2, O_1 \cup O_2, \mathcal{T}, \lambda \rangle :$$

- $\mathcal{T} = \{((q_1, q_2), (q'_1, q'_2)) \mid (q_1, q'_1) \in \mathcal{T}_1, (q_2, q'_2) \in \mathcal{T}_2\}$ ;
- $\lambda(((q_1, q_2), (q'_1, q'_2)), i_1 \cdot i_2) = o_1 \cup o_2$  if there is  
 $(q_1, q'_1) \in \mathcal{T}_1 \mid \lambda_1((q_1, q'_1), i_1) = o_1$  and  
 $(q_2, q'_2) \in \mathcal{T}_2 \mid \lambda_2((q_2, q'_2), i_2) = o_2$



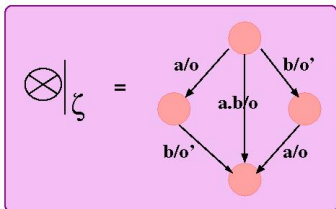


$O = \{o, o'\}$

$\zeta: o1 \rightarrow o$

$o2 \rightarrow o'$

$\{o1, o2\} \rightarrow o$



return