

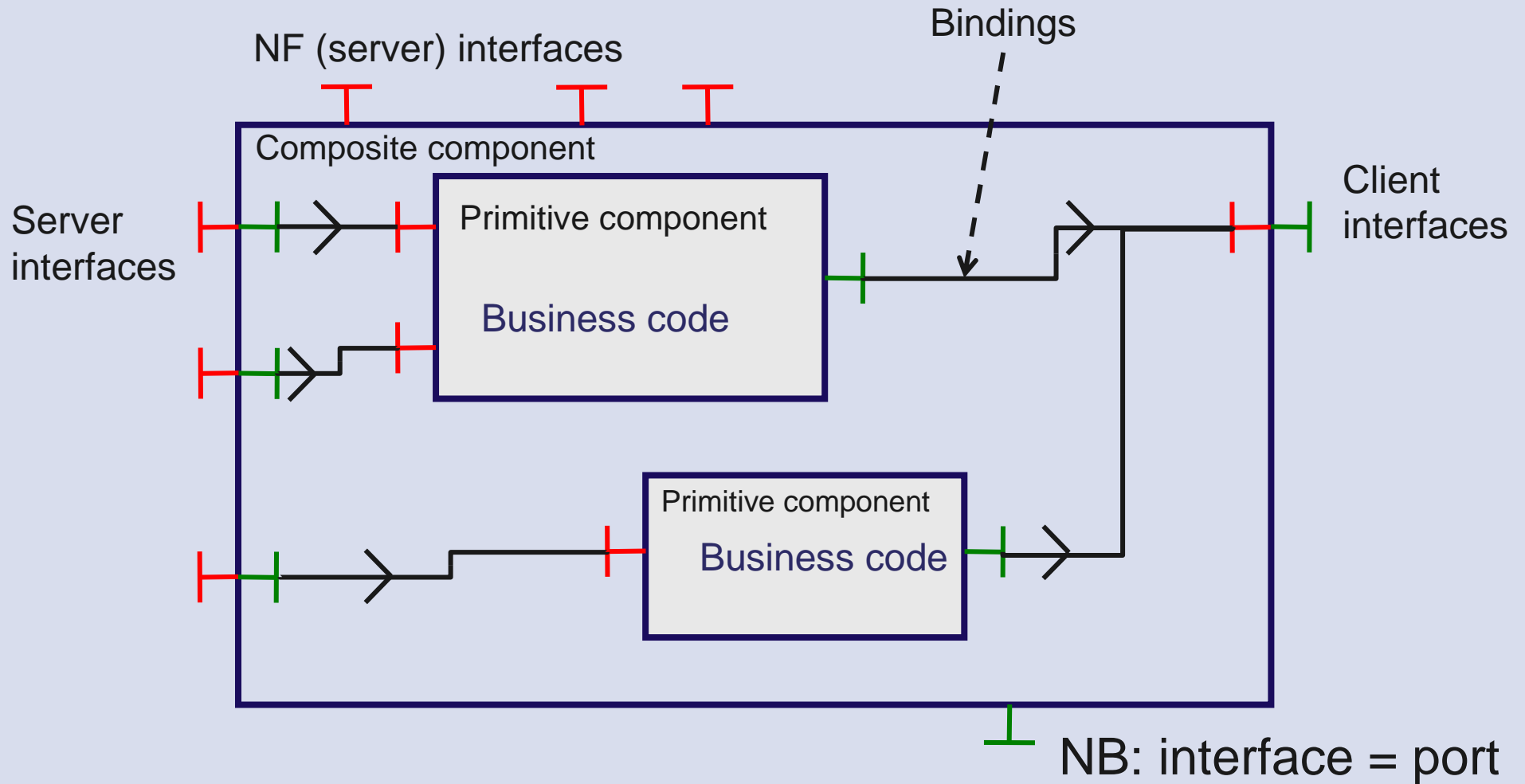
Formalism and Platform for Autonomous Distributed Components

OASIS team - Ludovic Henrio

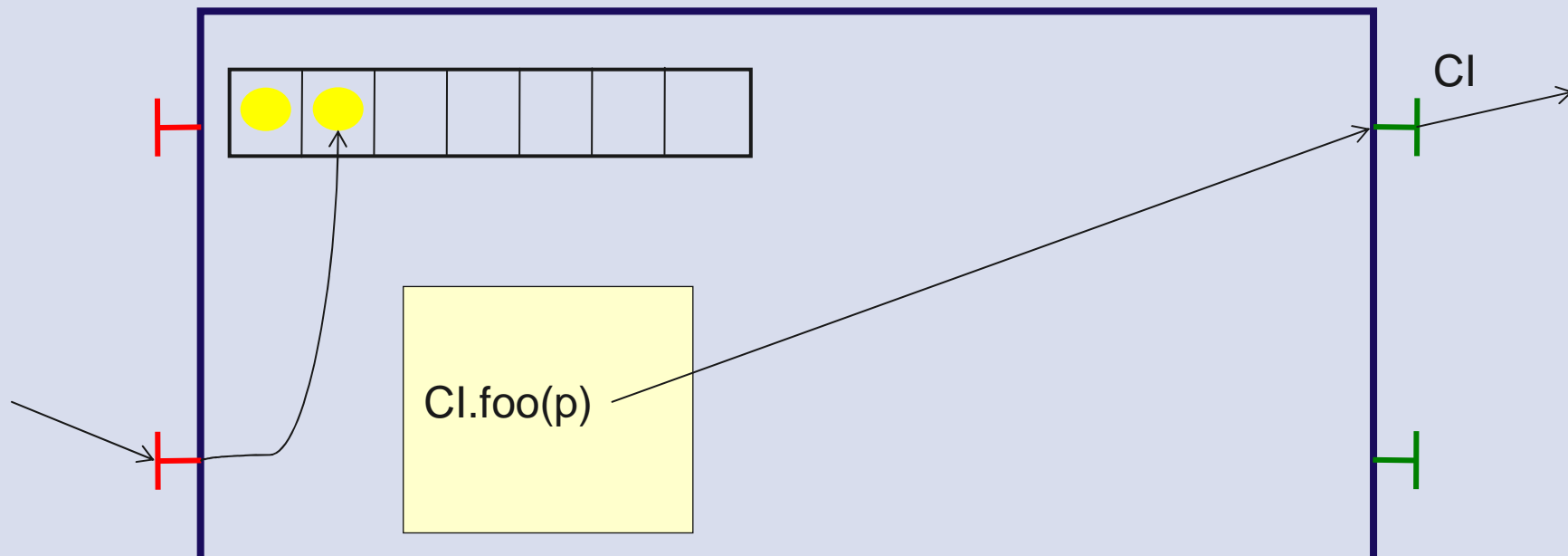
- A Distributed Component Model
- Formalisation in Isabelle
- Autonomous components:
Componentise component management and distributed reconfiguration

A DISTRIBUTED COMPONENT MODEL

What are (GCM) Components?



A Primitive GCM Component



Primitive components communicating by *asynchronous* remote method invocations on interfaces (*requests*)

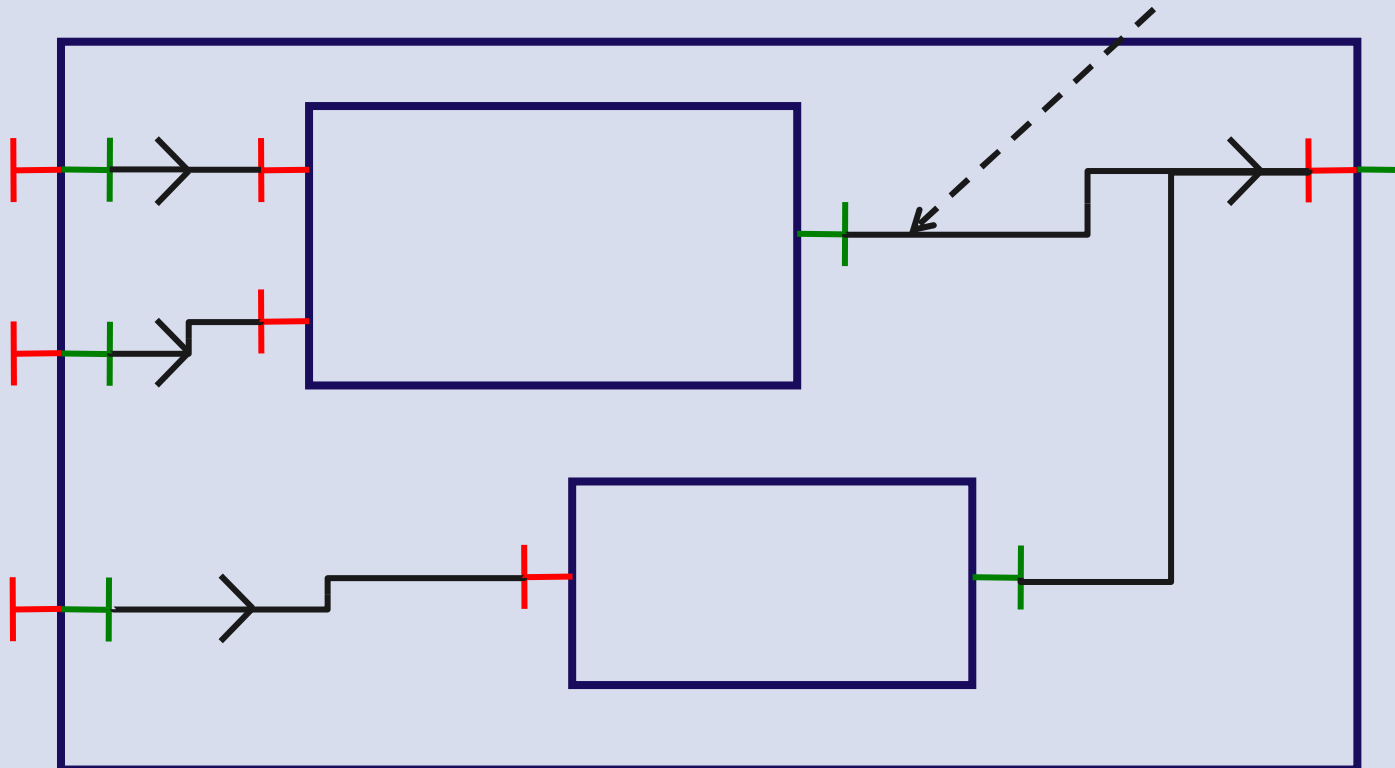
→ Components abstract away distribution and *concurrency*

in ProActive (reference implementation) components are mono-threaded

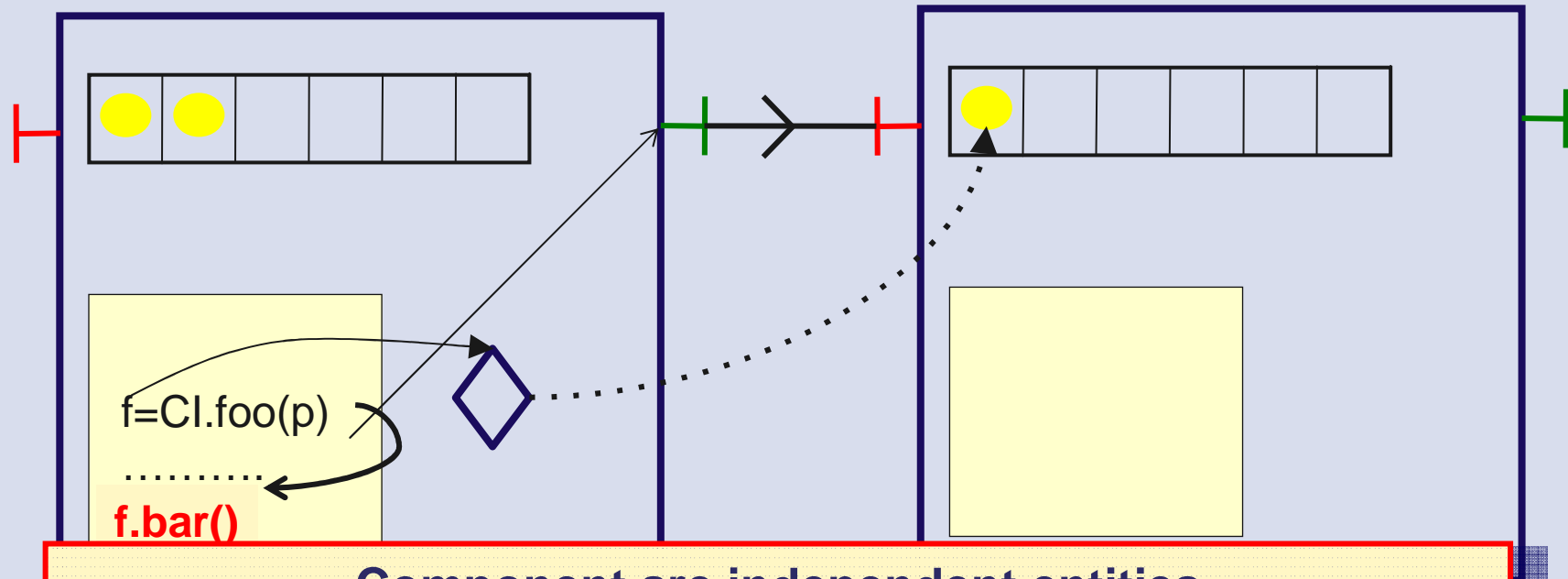
→ **simplifies concurrency** but can create **deadlocks**

Composition in GCM

Bindings:
Requests = Asynchronous method invocations



Futures for Components



**Component are independent entities
(threads are isolated in a component)**

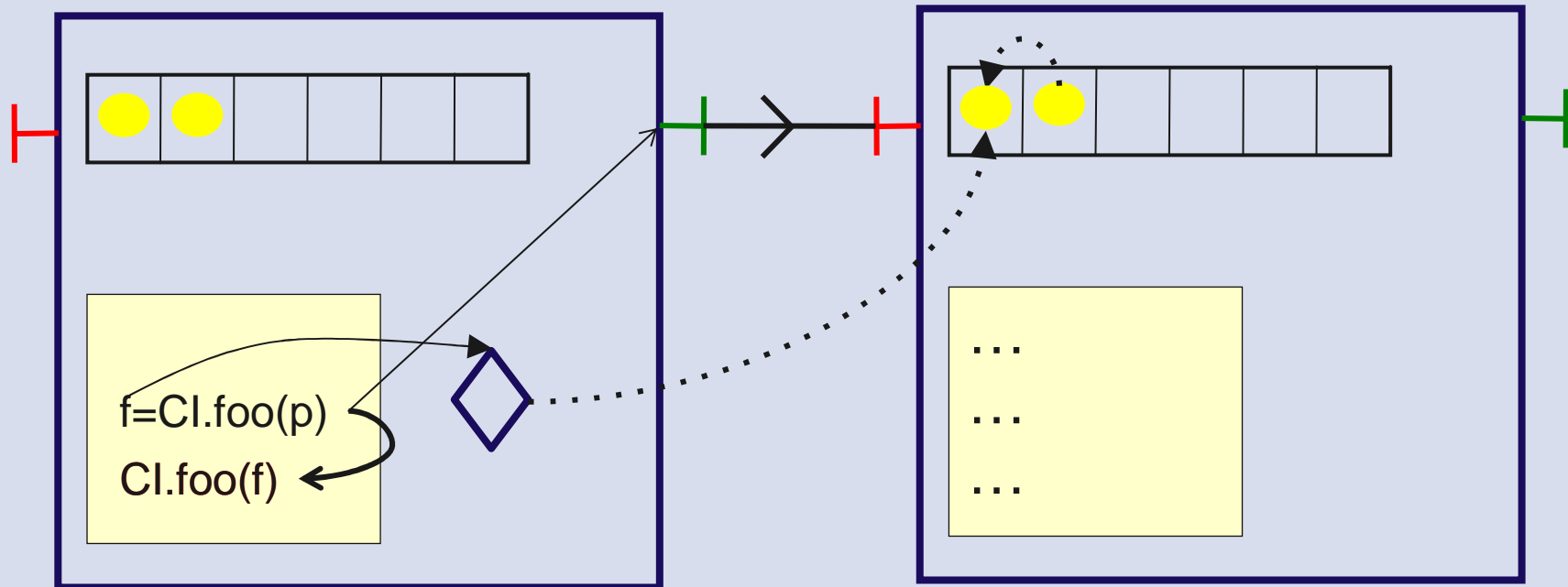
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Asynchronous method invocations with results



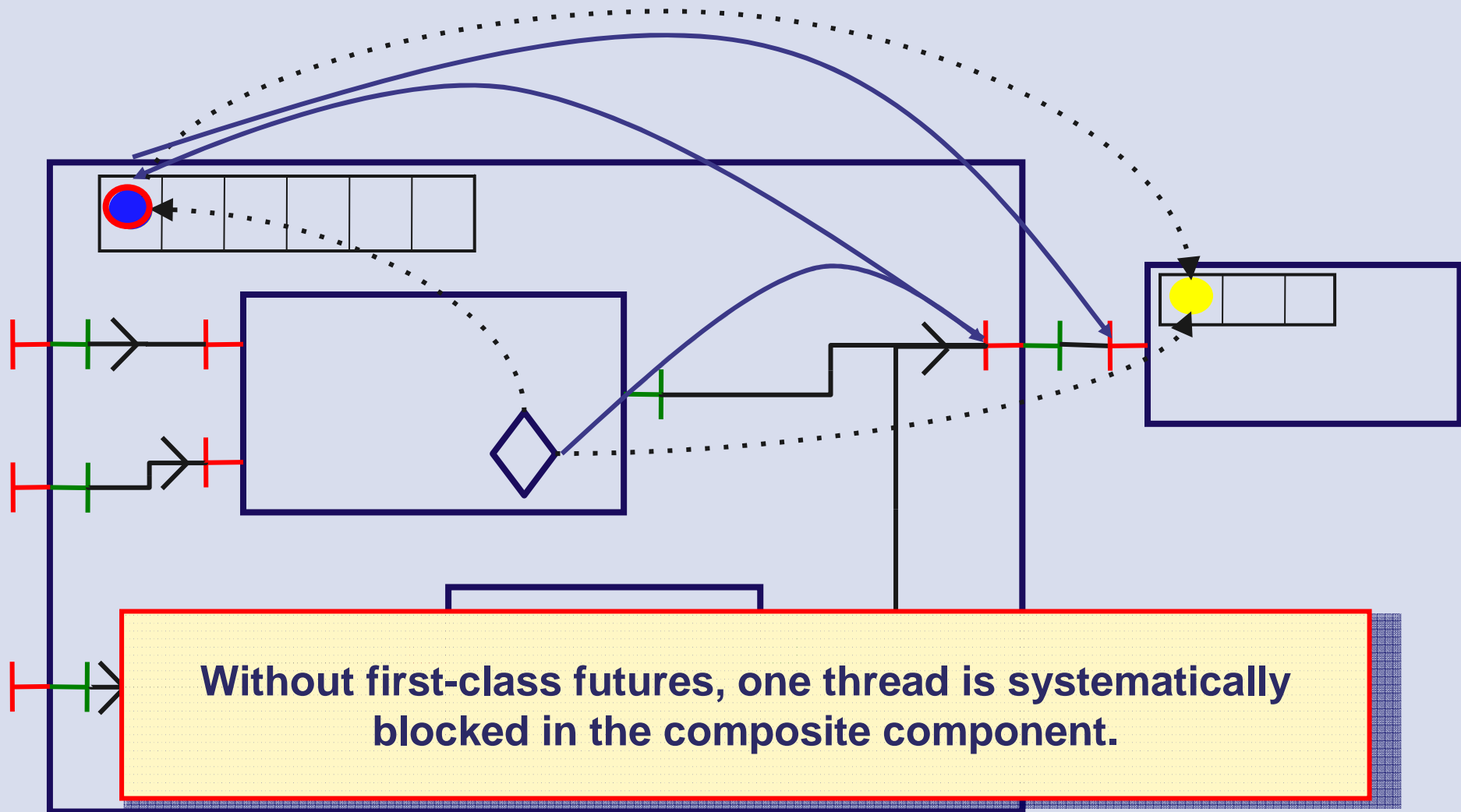
Futures are necessary

First-class Futures



- Only strict operations are blocking (access to a future)
- Communicating a future is not a strict operation

First-class Futures and Hierarchy



Approach: a refined GCM model

- A model:
 - more precise than GCM, give a semantics to the model:
 - future / requests
 - request queues
 - no shared memory between components
 - notion of request service
 - less precise than ProActive/GCM
 - can be multithreaded
 - no “active object” model

FORMALISATION

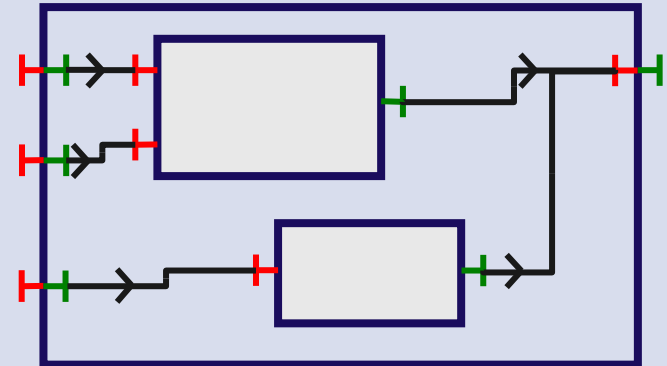
Objectives

- A model general enough to study GCM, but also other component models interacting by requests
- In a theorem prover (Isabelle)
- To study
 - the GCM component model,
 - its implementation(s),
 - interaction between futures and components,
 - component reconfiguration and management

Principles

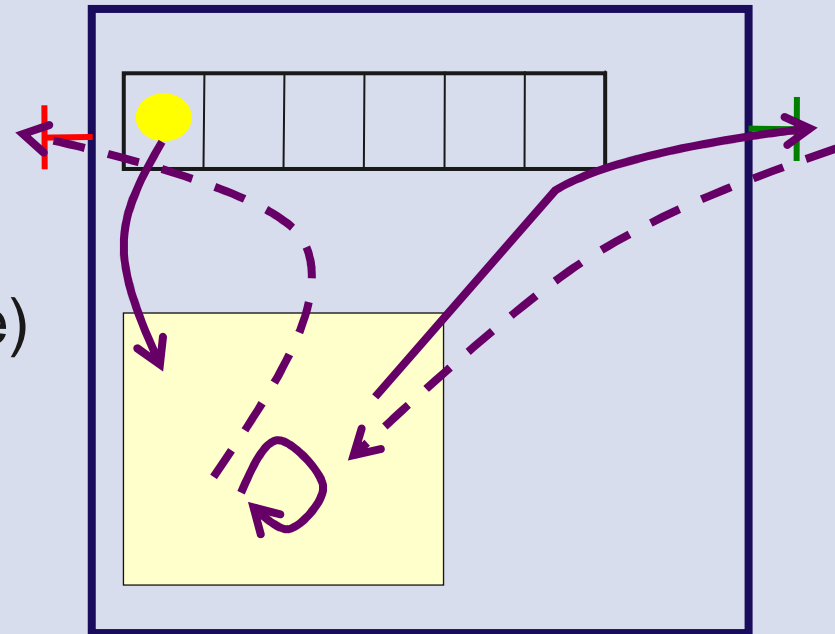
- component architecture:
 - bindings
 - interfaces (only functional)
 - component composition
- communications by requests and futures
 - request queues
 - future references
- abstraction of the business code by a behaviour (~LTS)
- values abstracted away: we just keep track of future references

```
types Value = "natx(Fid list)"
```



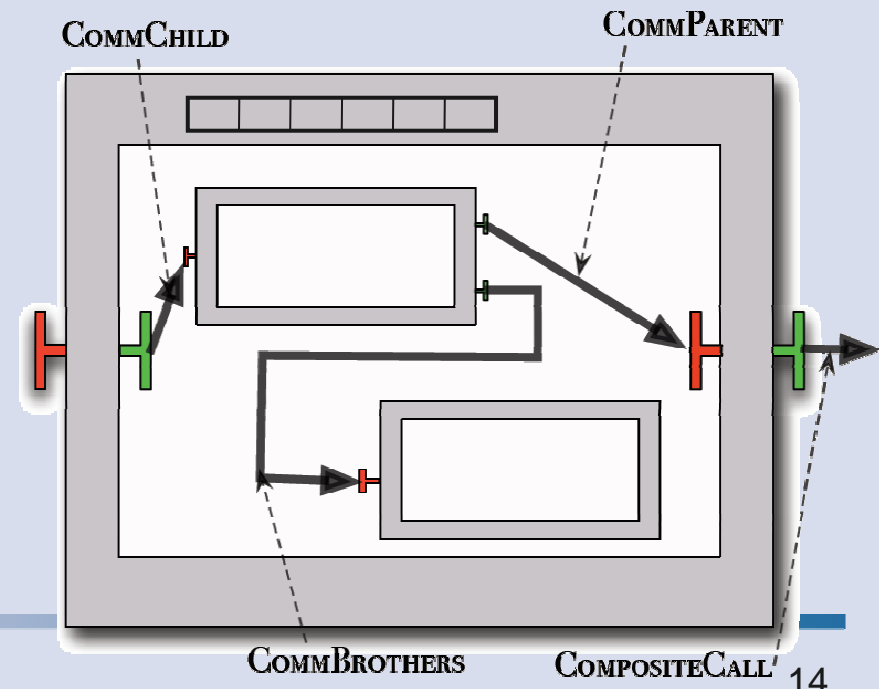
Primitive Components

- Primitive components are defined by interfaces plus an internal behaviour, they can:
 - emit requests
 - serve requests
 - send results
 - receive results (at any time)
 - do internal actionssome rules define a correct behaviour,
e.g. one can only send result for a served request
- We define the behaviour of the whole components as small-step operational semantics



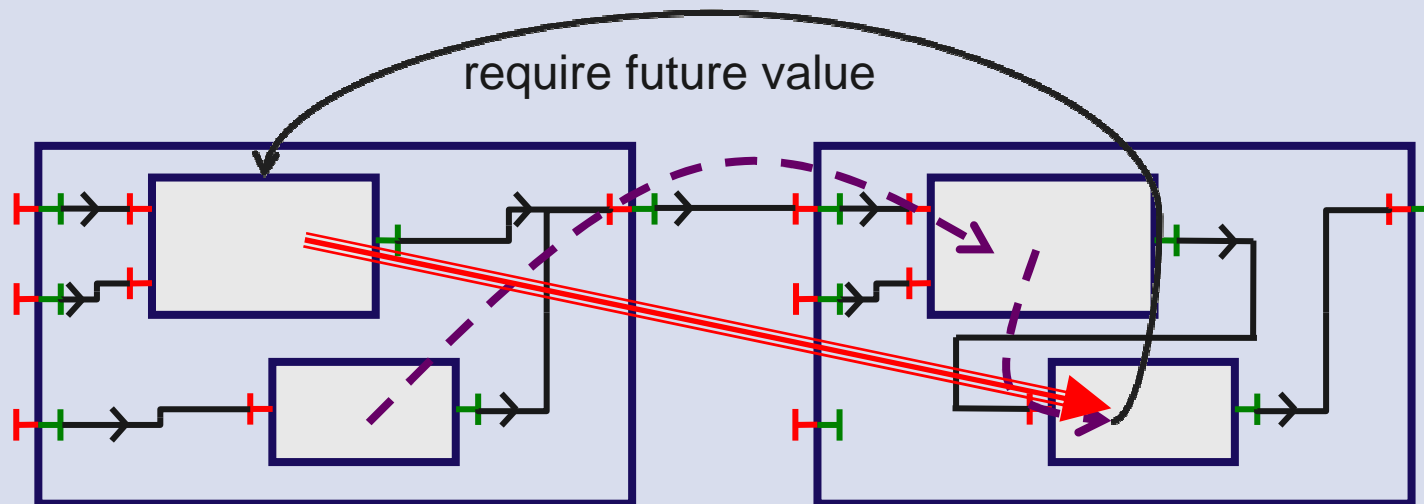
Composite Components

- Composite components are defined by their interfaces + content + bindings
- Semantics
 - Composites also have request queues (futures)
 - Only delegate calls to inner or outer components
 - Use the bindings to know where to transmit requests
 - Plus receive futures (like primitives)



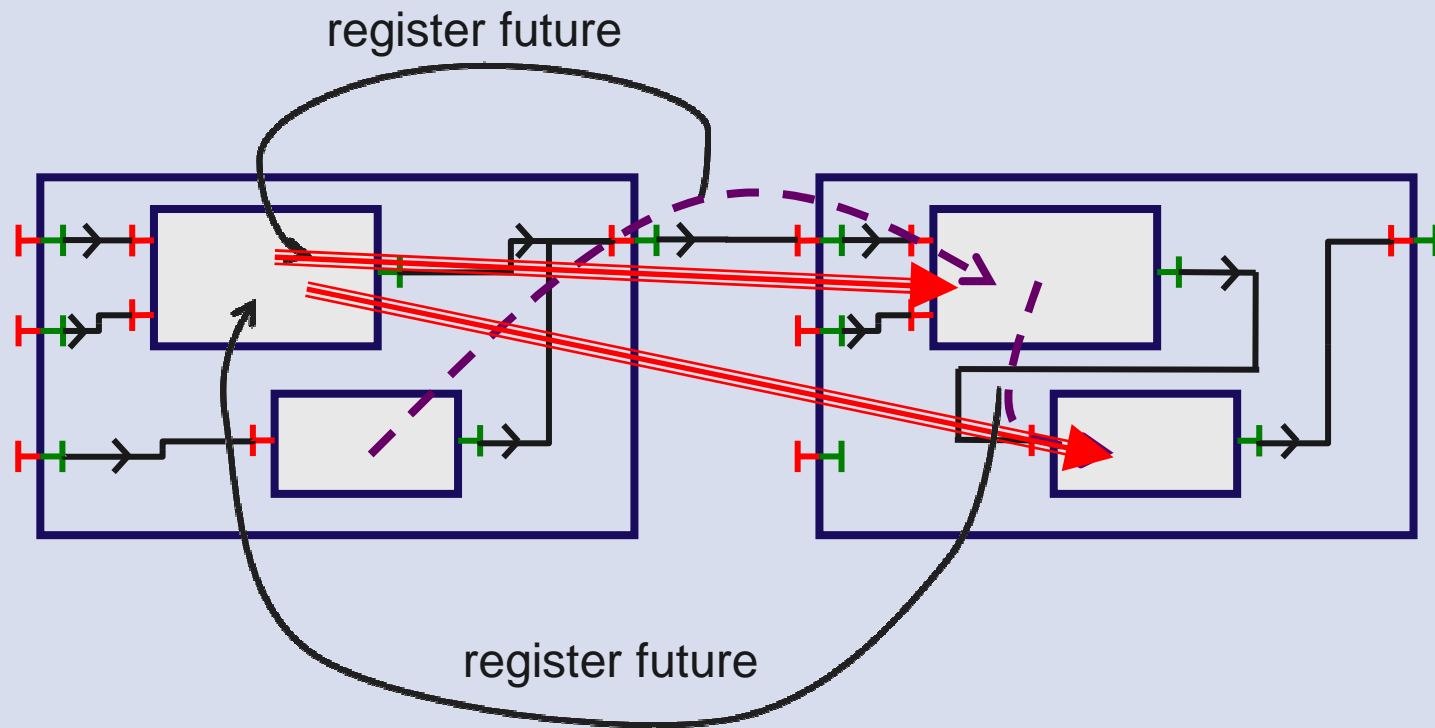
Future Update Strategies

- How to bring future values to components that need them
- Different strategies can be envisioned
- A “naive” approach: Any component can receive a value for a future reference it holds. Not much operational.
- More operational is the lazy approach:



Eager home future update

- A strategy avoiding to store future values indefinitely
- Relies on future registration and sends the value as soon as it is calculated



First Proofs (ongoing)

- Future update remove all references to a given future

lemma UpdFutRed_futdisappear:

```
"S -[f, v, N]→f S2 ,RL ⇒ CorrectComponentWeak S →  
(S2^^N = Some C → f ∉ set (snd v) → f ∉ LocalReferencedRqs C)"
```

- All Future references are registered during reduction

theorem registeredFutures: "⊢ C1 ↦ C2 ⇒

```
(GlobalRegisteredFuturesComp C1 → GlobalRegisteredFuturesComp C2)"
```

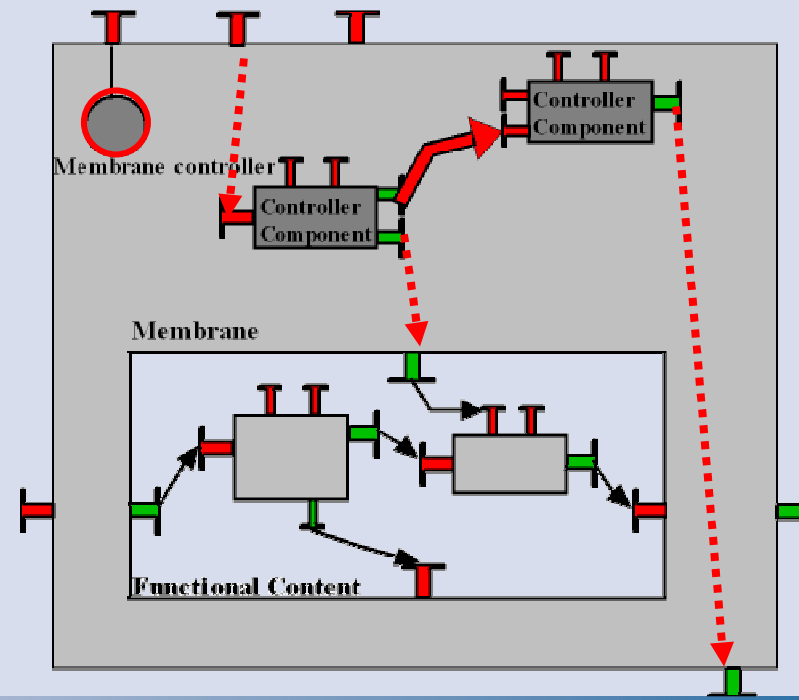
**A formalisation in Isabelle of Component structure +
request / futures**

Middle-term goal: correctness of various strategies

A PLATFORM FOR AUTONOMOUS COMPONENTS

Non-functional Component Structure

- Non-functional aspects as a composition of components (inside a membrane)
 - A component structure for the membrane
 - New kind of interfaces and bindings
 - An API for reconfiguring the membrane
 - Non-functional code is
 - components or objects
 - distributed or not



Adaptation in the GCM

- **Functional adaptation:** adapt the architecture + behaviour of the application to new requirements/objectives
 - add a new functionality
- **Non-functional adaptation:** adapt the architecture of the container+middleware to changing environment/NF requirements (QoS ...)
 - Change communication protocol
 - Update security policy

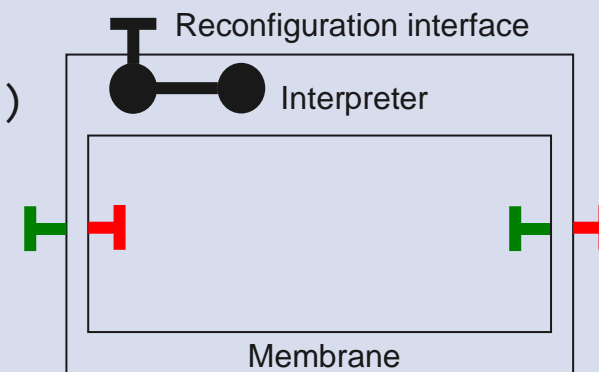
Both functional and non-functional adaptation are expressed as reconfigurations

How to express reconfigurations?

- Fractal / GCM defines an API for reconfiguring components
- We start from FScript:
 - A Scripting reconfiguration language
 - Dedicated to Fractal components
 - FPath expressions: navigate and select elements in the components architecture
 - Centralized execution

A Controller for Reconfigurations

- Manages and allows the invocation of the script interpreter
- Is collocated with the component
- Exposes methods for reconfiguration
 - `setInterpreter(interpreterClassName)`
 - `loadScript(scriptFileName)`
 - `executeAction(actionName, arguments...)`

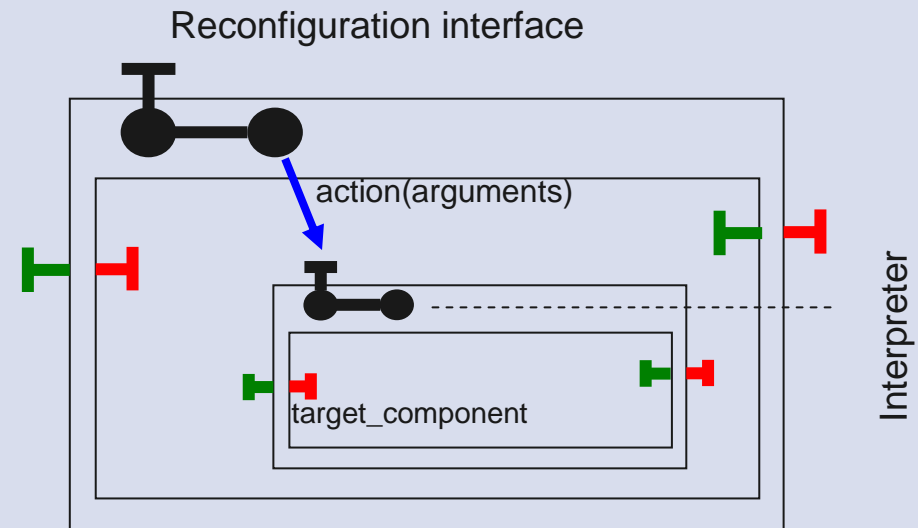


Triggering Distributed Reconfigurations in the Scripting Language

A primitive for the distributed script interpretation

```
remote_call(target_component, action_name, parameters, ...);
```

- Triggers the action `action_name` by the interpreter located in `target_component`
- Receives action arguments as parameter

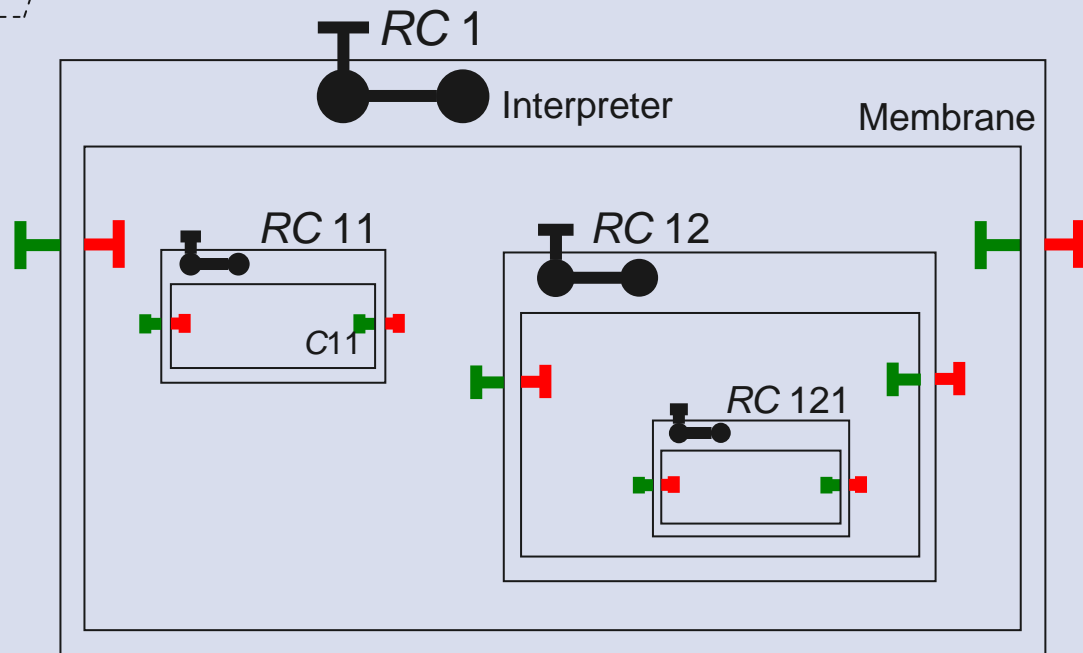
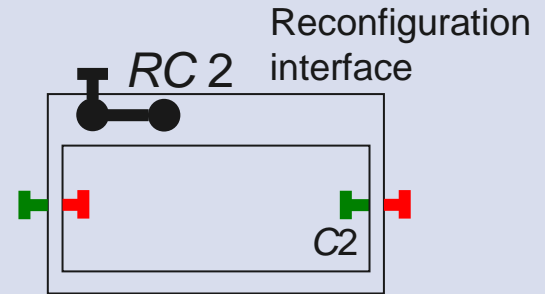


Example

```
definition action1
  ...
  remote_call(C2,'action2')
  remote_call(C11,'action11')
  remote_call(C12,'action12')
  ...
```

```
definition action12
  ...
  remote_call(C121,'action121')
  ...
```

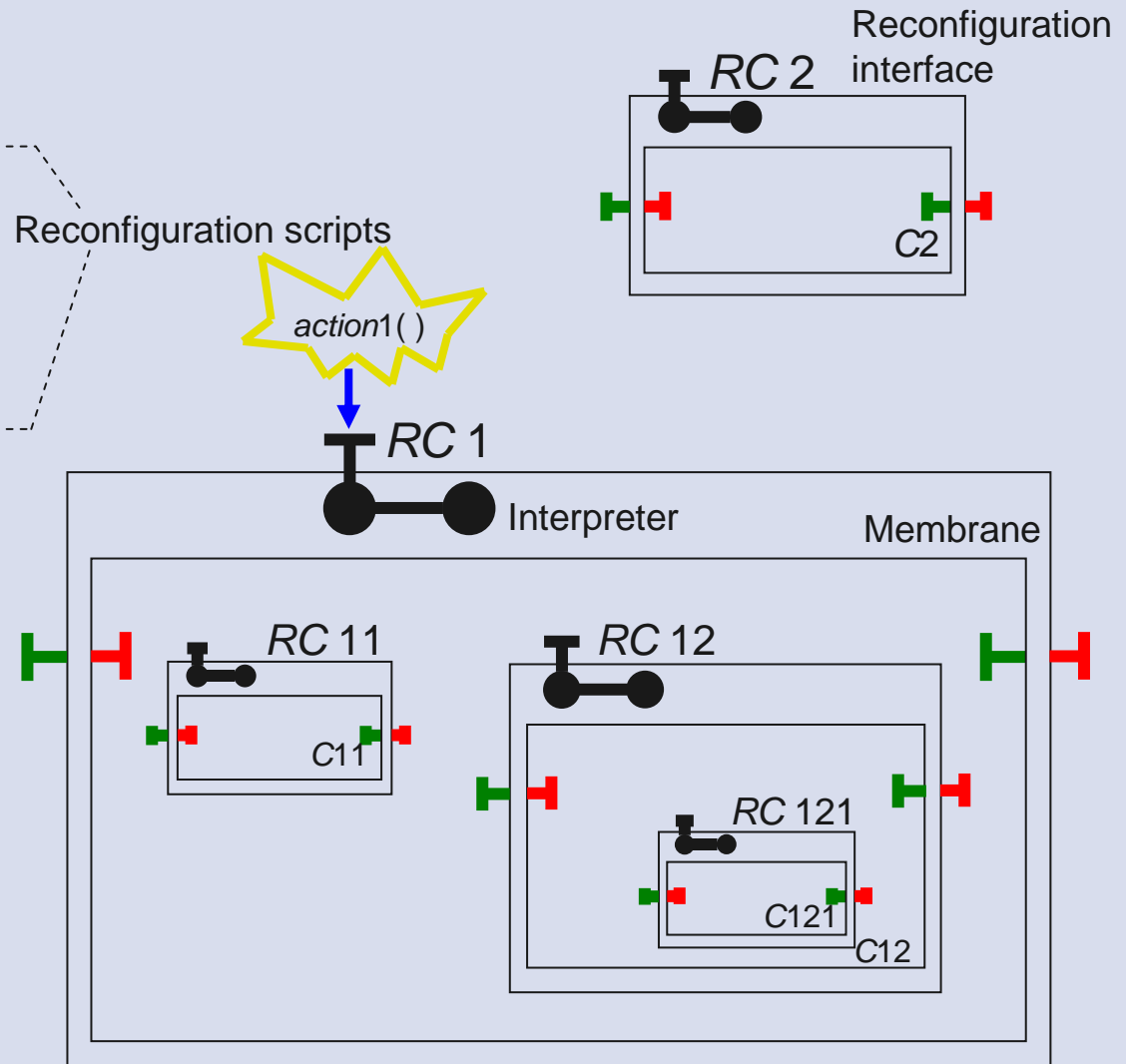
Reconfiguration scripts



Example

```
definition action1
  ...
  remote_call(C2,'action2')
  remote_call(C11,'action11')
  remote_call(C12,'action12')
  ...
```

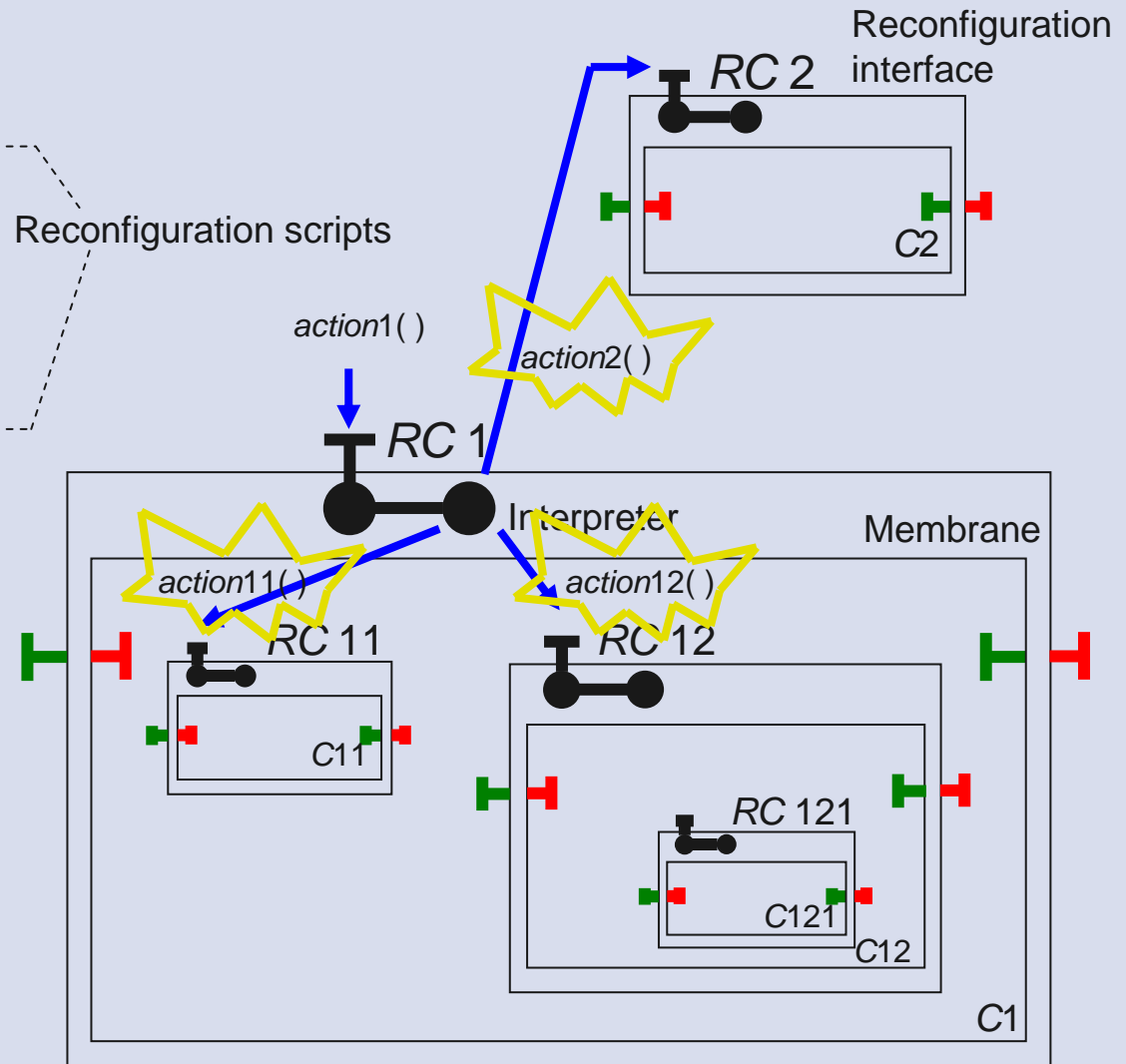
```
definition action12
  ...
  remote_call(C121,'action121')
  ...
```



Example

```
definition action1
  ...
  remote_call(C2,'action2')
  remote_call(C11,'action11')
  remote_call(C12,'action12')
  ...
```

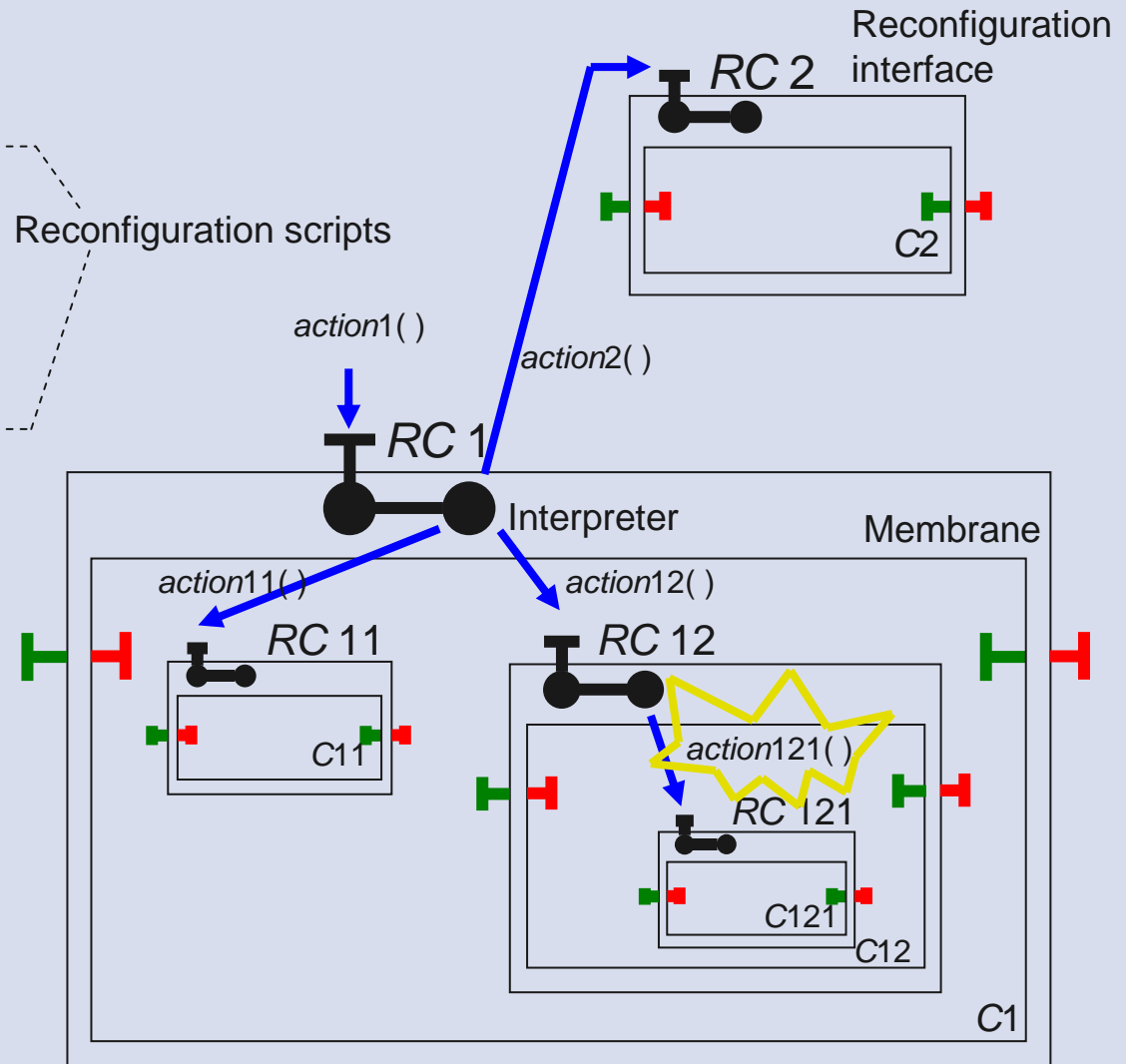
```
definition action12
  ...
  remote_call(C121,'action121')
  ...
```



Example

```
definition action1
  ...
  remote_call(C2,'action2')
  remote_call(C11,'action11')
  remote_call(C12,'action12')
  ...
```

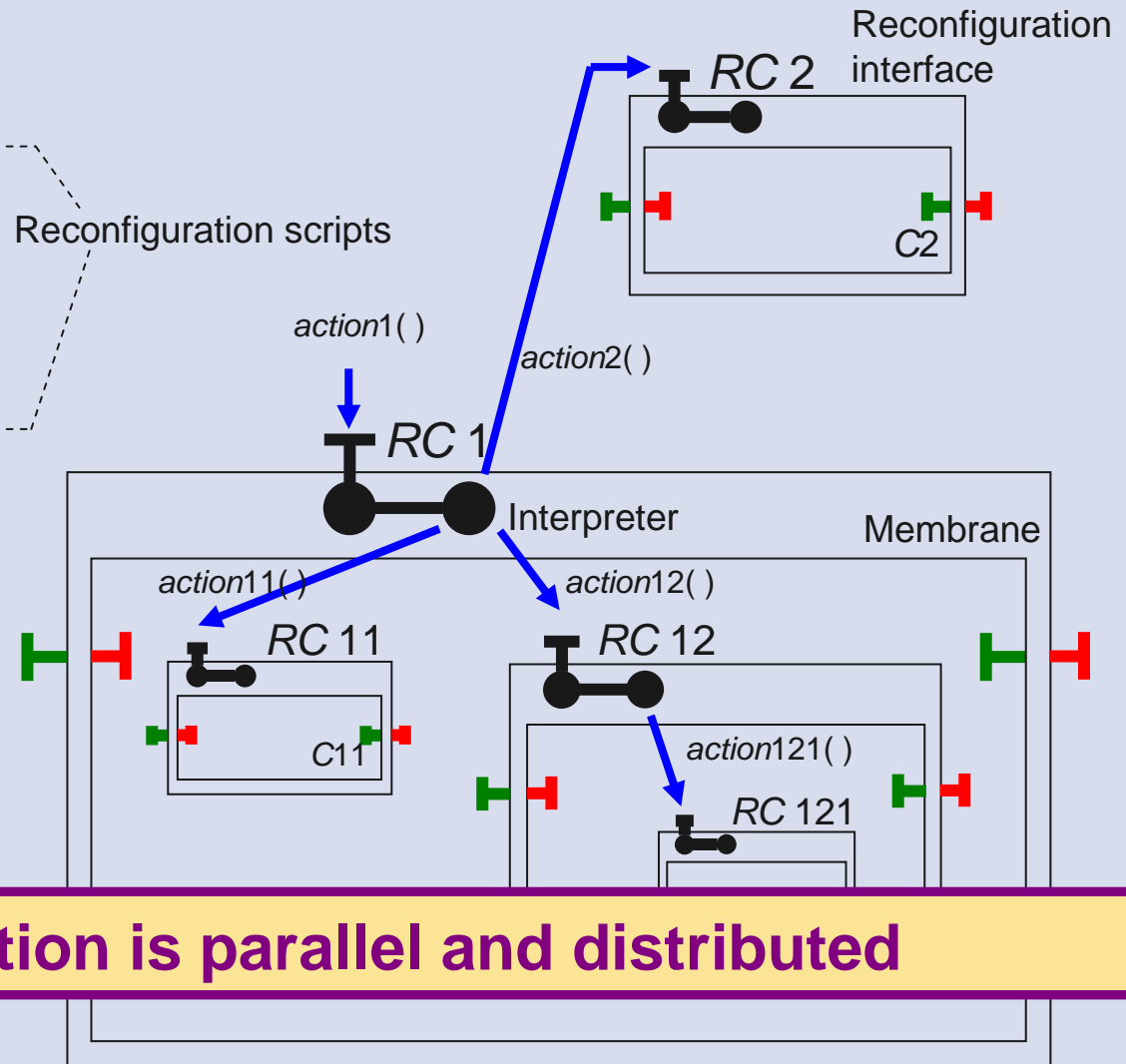
```
definition action12
  ...
  remote_call(C121,'action121')
  ...
```



Example

```
definition action1
  ...
  remote_call(C2,'action2')
  remote_call(C11,'action11')
  remote_call(C12,'action12')
  ...
```

```
definition action12
  ...
  remote_call(C121,'action121')
  ...
```



The interpretation is parallel and distributed

Conclusion

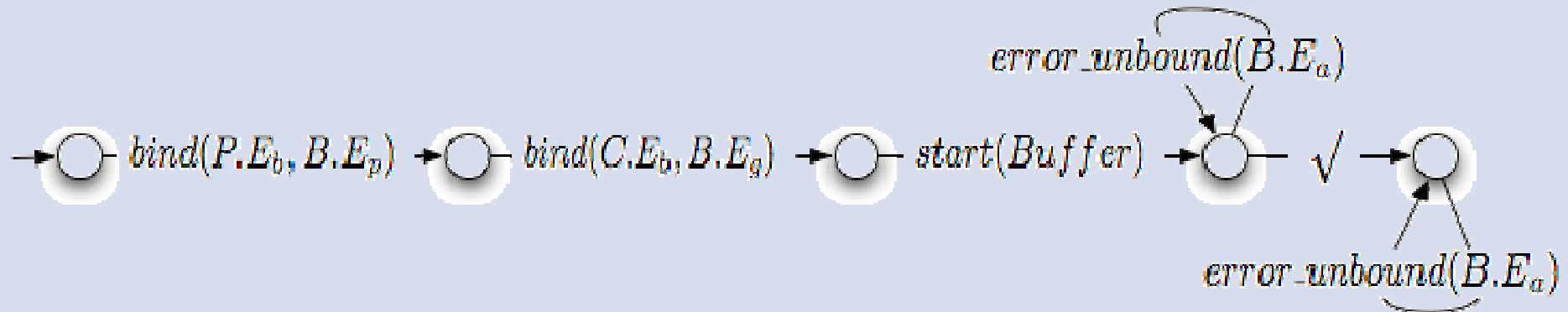
- A component model for adaptive autonomous components
 - structured membrane
 - distributed reconfiguration
- A platform supporting adaptation and distribution
 - based on ProActive (active objects, distribution)
 - ADL (membrane and business code composition)
- A formalisation to study the component model and its implementation
 - toward verification of component management procedures

Ongoing and Future Works

- Formalisation is a long process:
 - For the moment, more a formal specification + a few proofs than a complete verification environment
- Verification of (re)configuration procedures by model checking
 - Complementary with Theorem proving approach application specific vs. model properties
 - Already model generation relies on ASP properties

Verification of Properties: Deployment

start Buffer without linking the alarm interface



- The deployment is always successful

$$[(not \checkmark)^*] \langle true^* . \checkmark \rangle \quad true$$

- But Error during deployment

$$[(not \checkmark)^* . O_E] \quad false$$

Verification of Properties

regular μ -calculus (Mateescu'2004)

- Deployment
- (on the Static Automaton with successful synchronisation visible)

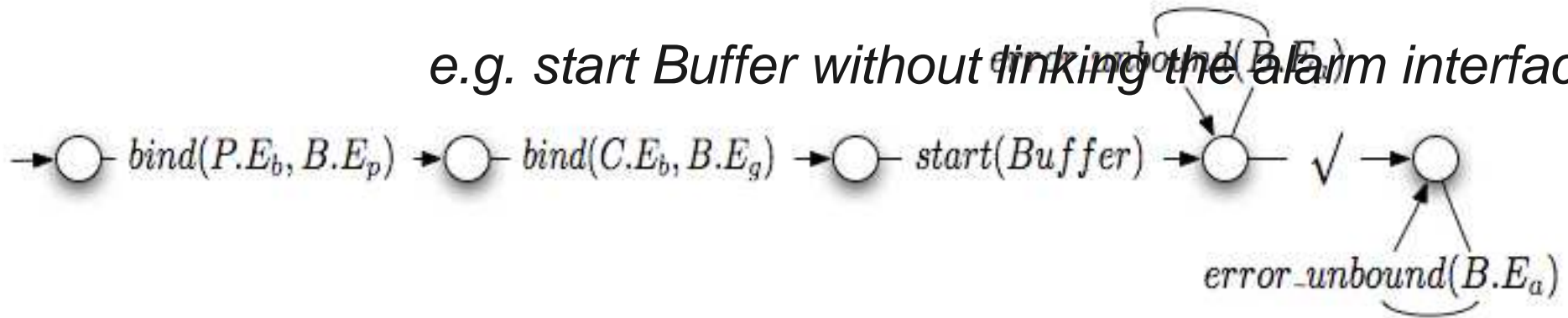
- The deployment is always successful

$$[(\text{not } \checkmark)^*] \langle \text{true}^* . \checkmark \rangle \text{true}$$

- No Error during deployment

$$[(\text{not } \checkmark)^* . O_E] \text{false}$$

e.g. start Buffer without linking the alarm interface

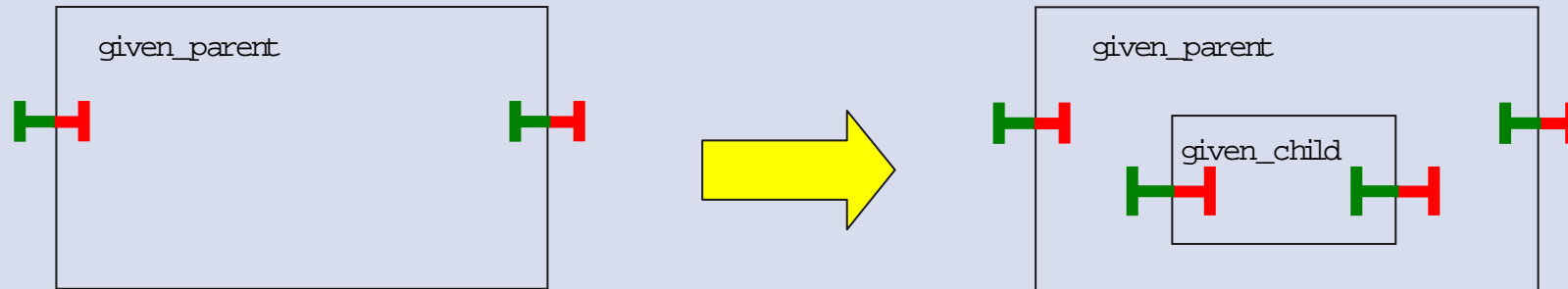


Verification of Properties

- Functional properties under reconfiguration (respecting the topology)
 - Future update (asynchronous result messages) independent of life-cycle or binding reconfigurations
 - Build a model including life-cycle controllers, with the reconfiguration actions visible:
 $?unbind(C.E_b, B.E_g) \quad ?stop(C)$
 - Then we can prove:
 $[true^*.Req_Get()] \mu X. (< true > true \wedge [\neg Resp_Get()] X)$

Example

- Add the component `given_child` to the composite `given_parent`



```
remote_call($given_parent, 'add', '$given_parent', 'given_child');
```

GCM API for Reconfiguration

- Life-cycle controller

```
string getFcState ();  
void startFc () throws IllegalLifecycleException;  
void stopFc () throws IllegalLifecycleException;
```

- Binding controller

```
string[] listFc ();  
any lookupFc (string clientIfName )  
             throws NoSuchInterfaceException;  
void bindFc (string clientIfName, any serverIf) throws ...  
void unbindFc (string clientIfName) throws ...
```

- Content Controller

```
any[] getFcInternalInterfaces ();  
any getFcInternalInterface (string ifName) throws ... Component[] getFcSubComponents  
();  
void addFcSubComponent (Component c) throws ...  
void removeFcSubComponent (Component c) throws ...
```