

Grid programming with components:
an advanced **COMP**onent platform for an
effective invisible grid

GridCOMP
Effective Components for the Grids



Autonomic QoS Control with Behavioral Skeleton

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GridCOMP WP3

21 Oct 2008 - Sophia Antipolis - France

GridCOMP conference ProActive/GCM user group

● Motivation

- why adaptive and autonomic management
- why skeletons

● Behavioural Skeletons in GCM

- parametric composite component with management
- functional and non-functional description
- families of behavioural skeletons
- distributed overlay of management

● GCM implementation

- preliminary experiments and performances

Why Autonomic Computing



- Scientific and industrial applications **do require** QoS control
 - QoS figures of a distributed application **can hardly be** predicted in static way
 - unstable platforms, irregular applications, dynamically changing requirements ...
 - QoS is often **contractually** specified; infringement of it may be fined
 - industry need to **dynamically size** application QoS to expand market share while keeping design and tuning cost limited
 - design application once in a scalable way, sell it to many clients of different size
 - QoS is a first-class concept** of the emerging services/utility business
 - cloud, SaaS, PaaS, etc.
 - business/price may greatly depend by QoS, and vice-versa

Why Autonomic Computing (User-defined QoS requirements for Apps)



- Performance
 - the app should sustain x transactions per second
 - the app should complete each transaction in t seconds
- Security
 - the link between $P1$ and $P2$ should be secured with k -strong encryption
 - the *DB* service is exposed by platform $P3$
- Fault-tolerance
 - the parallel server should survive to the failure of y platforms

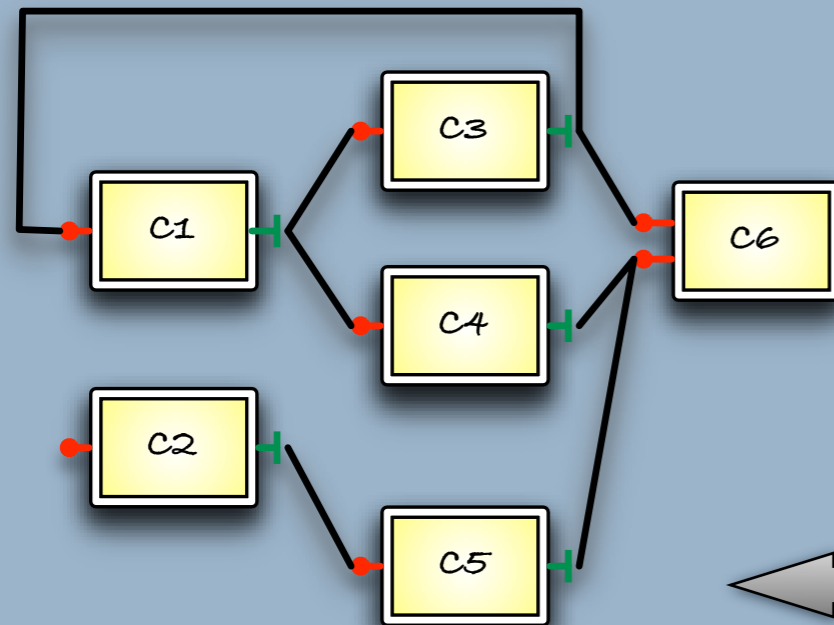
... then consider that x , t , $P1$, $P2$, $P3$, k , y can dynamically change as may dynamically change the performance and the state of the running environment ...

Autonomic Computing paradigm



managed components

manager



QoS data

Analyse

broken contract

Monitor

Plan

Execute

next configuration

- monitor: collect execution stats: machine load, service time, input/output queues lengths, ...
- analyse: instantiate performance models with monitored data, detect broken contract, in and in the case try to detect the cause of the problem
- plan: select a (predefined or user defined) strategy to re-convey the contract to validity. The strategy is actually a “program” using execute API
- execute: leverage on mechanism to apply the plan

Why skeletons

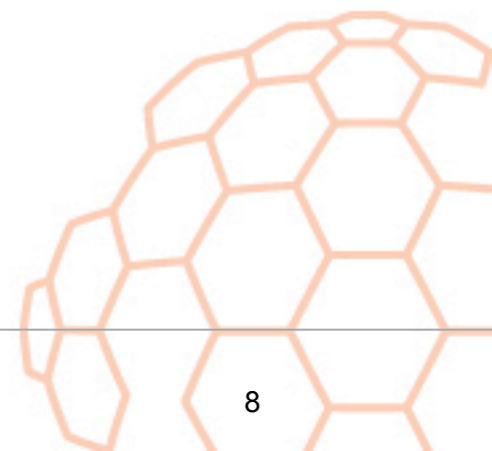


- Management is difficult
 - application change along time (ADL not enough)
 - how “describe” functional, non-functional features?
 - the low-level programming of component and its management is simply too complex
- Component development is already too difficult
 - how much of your time do you spend in run-time debugging and performance tuning?
- Component reuse is already a problem
 - specialising component yet more with management strategy would just worsen the problem
 - especially if the component should be reverse engineered to be used (its behaviour may change along the run)

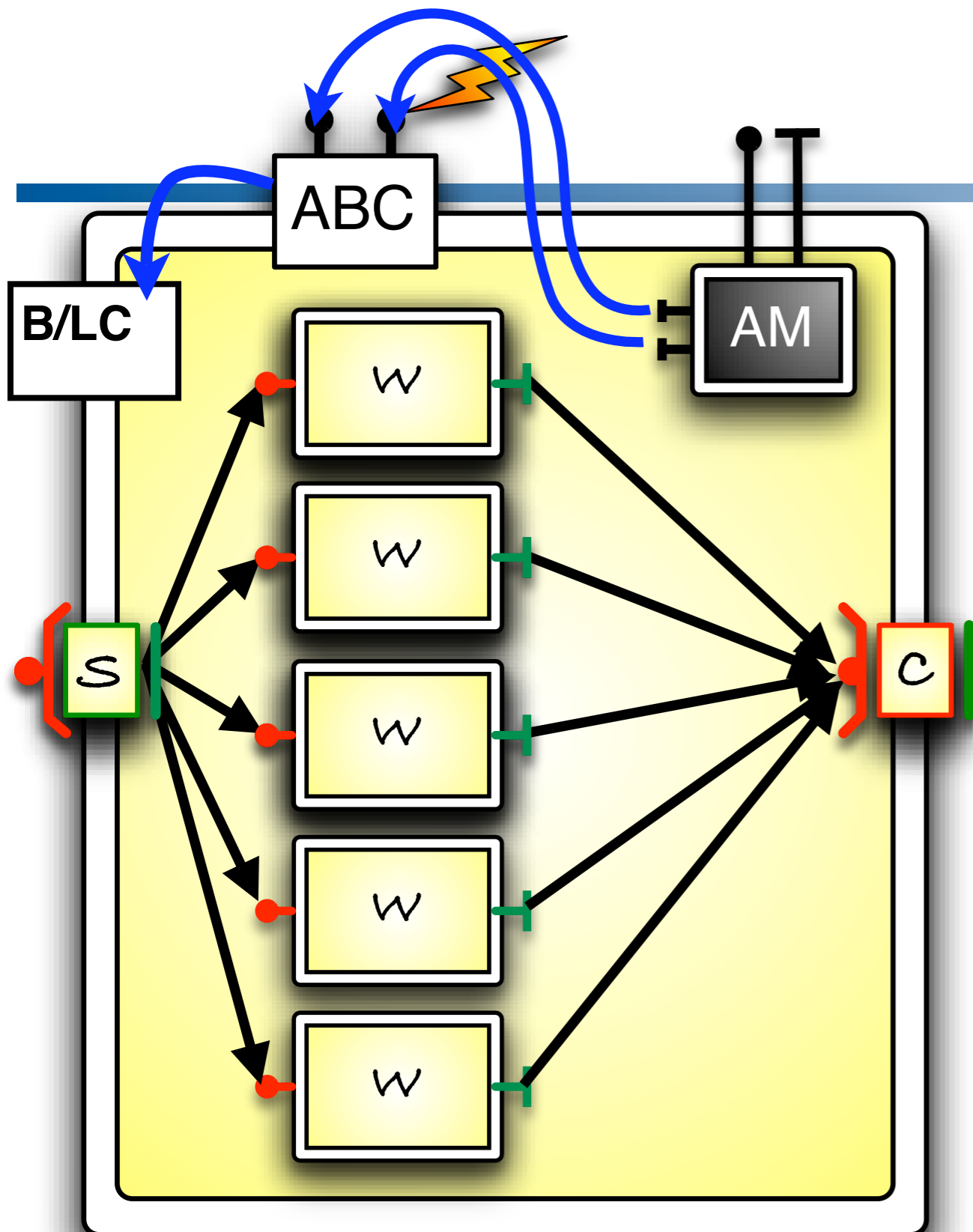


- Represent an evolution of the algorithmic skeleton concept for component management
 - abstract parametric paradigms of component assembly
 - specialised to solve one or more management goals
 - self-configuration/optimization/healing/protection.
 - carry a semi-formal/formal description and an implementation
 - they are higher-order components (or factories), actually
- Are higher-order components
- Are not exclusive
 - can be composed with non-skeletal assemblies via standard components connectors
 - overcome a classic limitation of skeletal systems

- Functional Replication
 - **Farm/parameter sweep (self-optimization)**
 - **Stateless Data-Parallel (self-configuring map-reduce)**
 - e.g. one server port (n of server ports is a parameter)
 - **Stateful Data-Parallel (self-configuring stateful map-reduce)**
 - e.g. two server ports: set_state and execute
 - Active/Passive Replication (self-healing)
- Proxy
 - Pipeline (coupled self-protecting proxies)
- Wrappers



Functional replication



1. Choose a schema

*e.g. functional replication
ABC API is chosen accordingly*

2. Choose an inner component

compliant to BeSke constraints

3. Choose behaviour of ports

e.g. unicast/from_any, scatter/gather

4. Run your application

then trigger adaptations

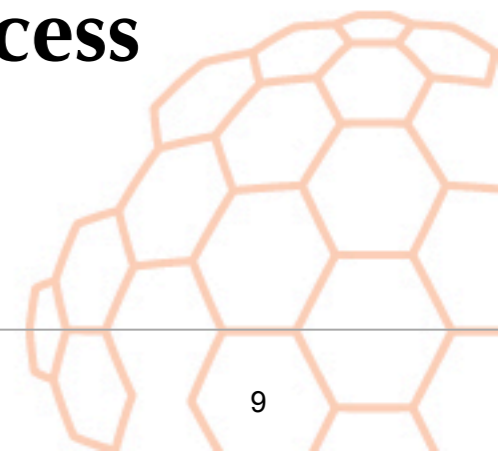
5. Automatisate the process

with a Manager

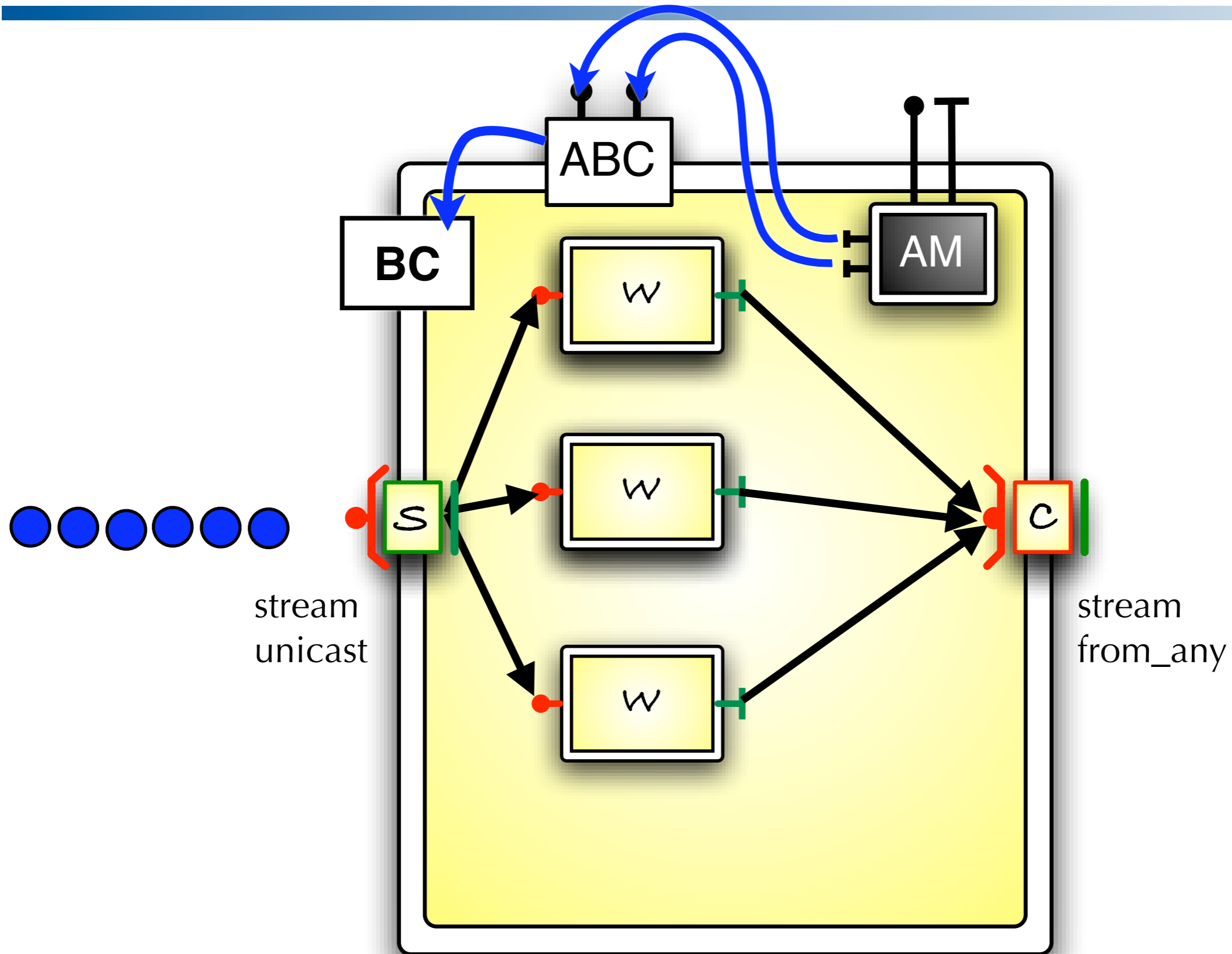
ABC = Autonomic Behaviour Controller (implements mechanisms)

AM = Autonomic Manager (implements policies)

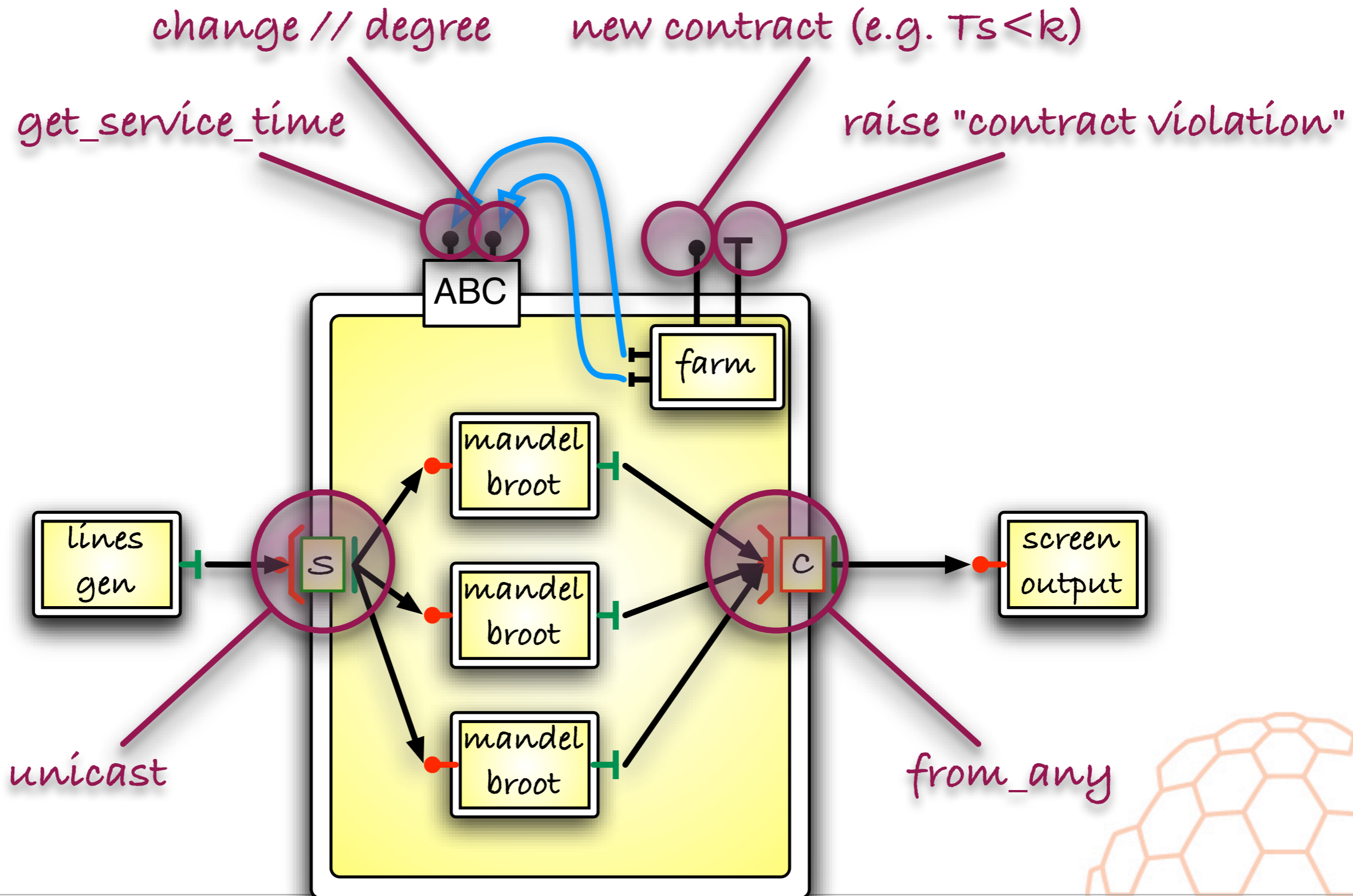
B/LC = Binding + Lifecycle Controller



Farm BeSke



Farm BeSke (e.g. Mandelbrot)

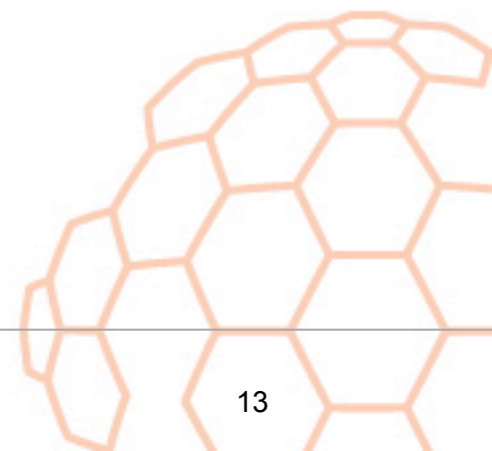
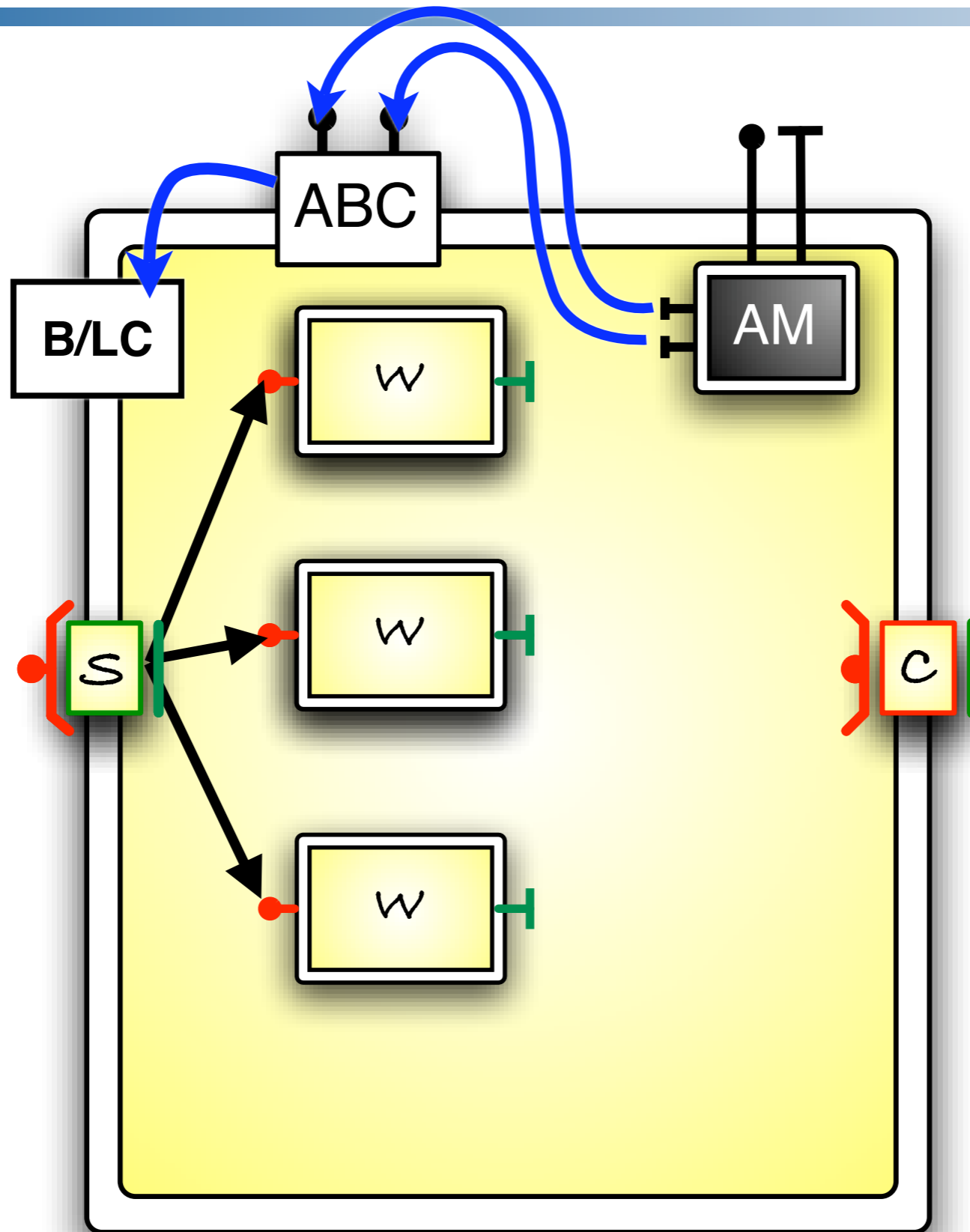
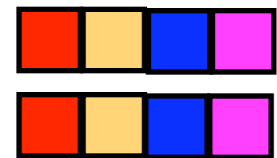


Farm BeSke contract (e.g. Mandelbrot)

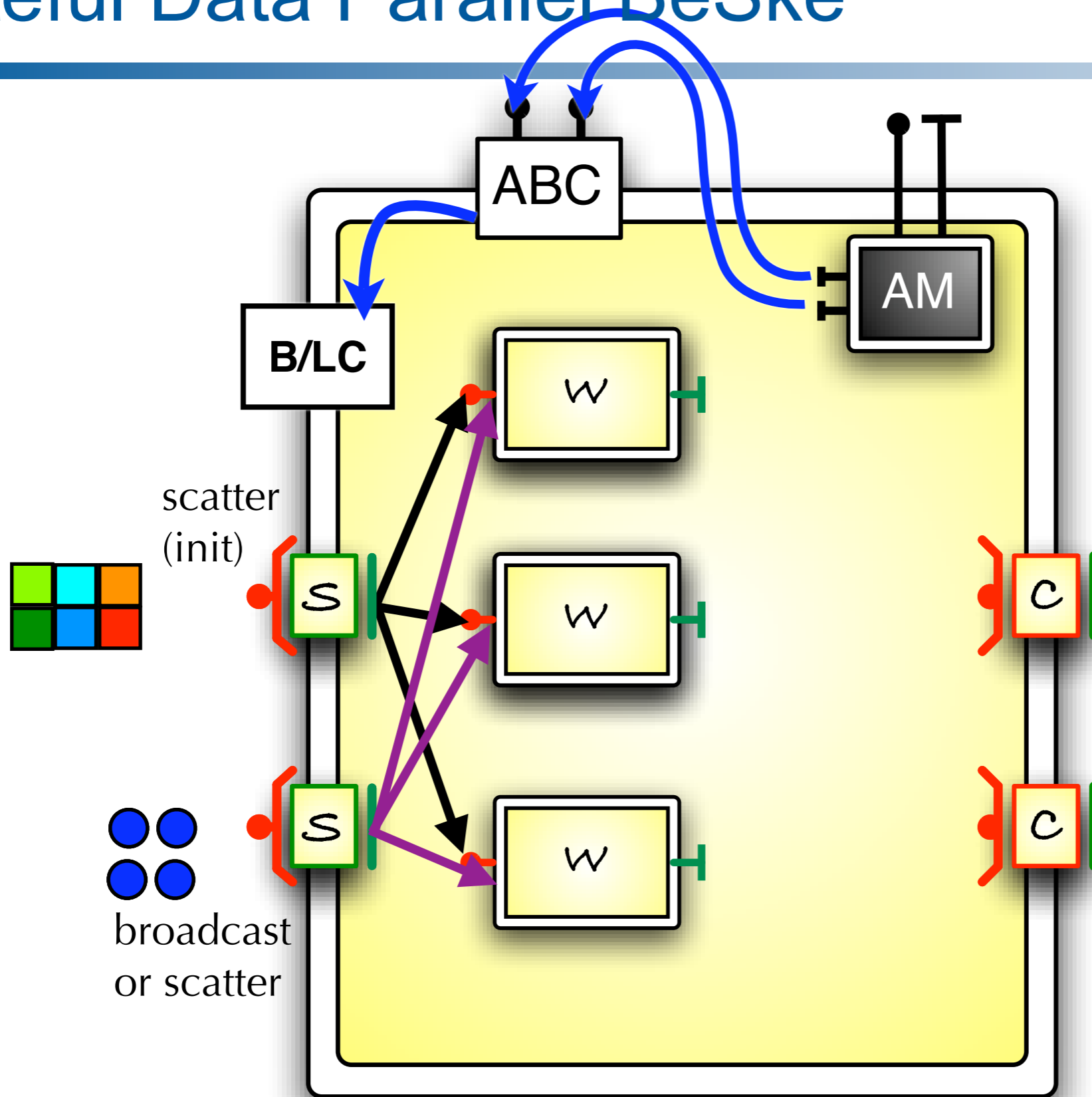
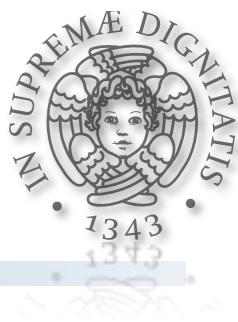


```
rule "CheckInterArrivalRate"
  salience 5
  when
    $arrivalBean : ArrivalRateBean( value < ManagersConstants.LOW_PERF_LEVEL)
  then
    $arrivalBean.setData(ManagersConstants.notEnoughTasks_VIOL);
    $arrivalBean.fireOperation(ManagerOperation.RAISE_VIOLATION);
    System.out.println( "InterArrivalTime not enough - Raising a violation");
  end
rule "CheckRateLow"
  when
    $departureBean : DepartureRateBean( value < ManagersConstants.LOW_PERF_LEVEL )
    $parDegree: NumWorkerBean(value <= ManagersConstants.MAX_NUM_WORKERS)
  then
    $departureBean.fireOperation(ManagerOperation.ADD_WORKER);
    $departureBean.fireOperation(ManagerOperation.BALANCE_LOAD);
    System.out.println( "Adding "+ManagersConstants.ADD_WORKERS+ "workers");
  end
rule "CheckRateHigh"
  when
    $departureBean : DepartureRateBean( value > ManagersConstants.HIGH_PERF_LEVEL )
    $parDegree: NumWorkerBean(value > ManagersConstants.MIN_NUM_WORKERS)
  then
    $departureBean.fireOperation(ManagerOperation.DEL_WORKER);
    $departureBean.fireOperation(ManagerOperation.BALANCE_LOAD);
    System.out.println( "Rate "+$departureBean.getValue()+" (Removing 1 workers)");
  end
end
```

Stateless Data Parallel BeSke



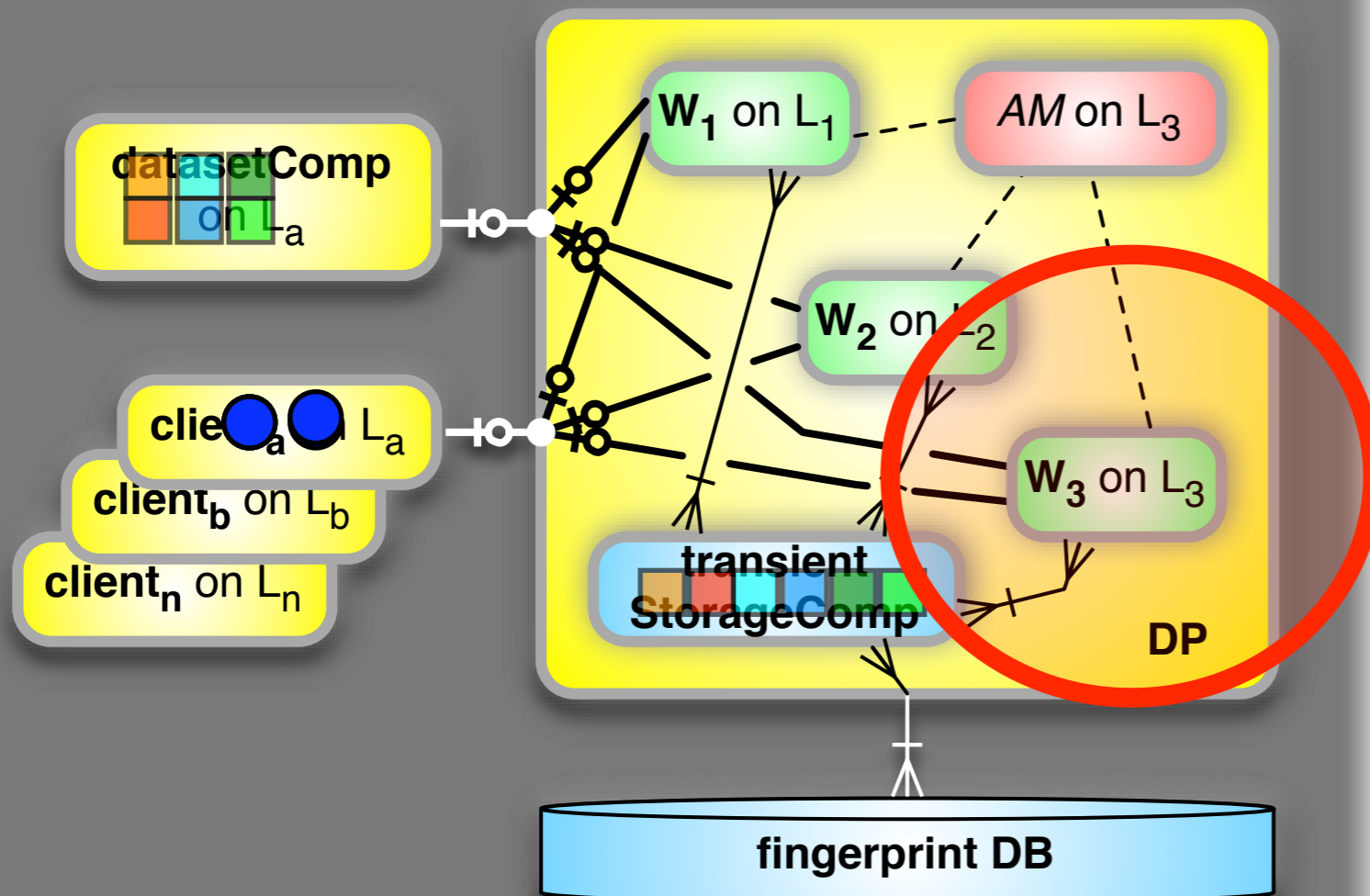
Stateful Data Parallel BeSke



Notes

- any number of server and client ports (either RPC or stream, in theory)
- the model cannot (structurally) enforce init happens before requests on other ports
- port reconfiguration and data redistribution should be atomic (no tasks should be distributed in the middle).
- data can be reconfigured in a distributed way (provided a suitable data port abstraction is defined)

Stateful Data Parallel BeSke (e.g. IBM mockup)



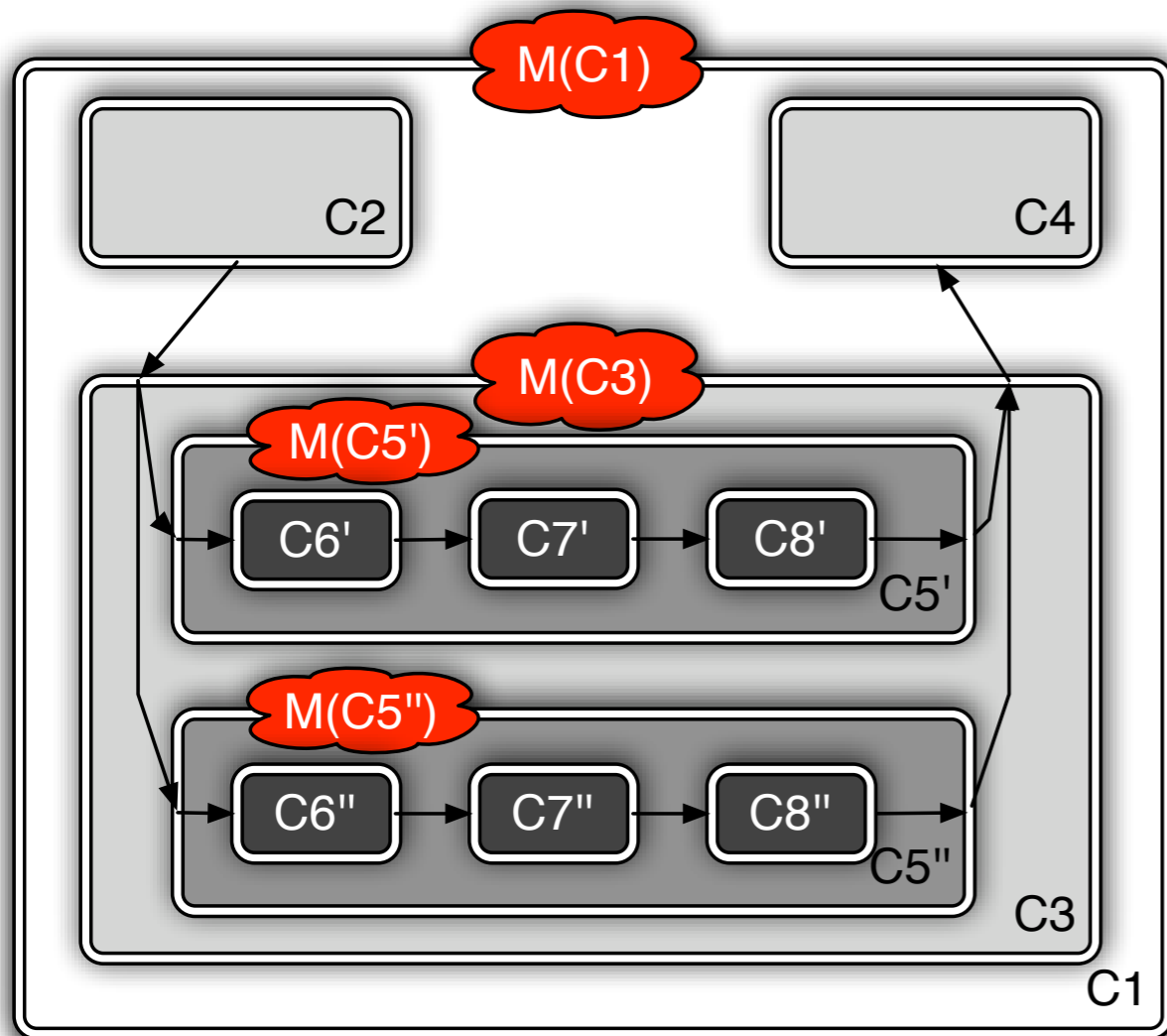
- 7) AM reacts (e.g. increasing // degree):
 copying $W1$;
 bindings (external, AM, StorageComp) should be preserved;
 DB partitions (Wx state) should be redistributed via StorageComp
- 6) AM may sense a changed answer time (e.g. increased), due to a dataset size/kind and/or platform status change
- 5) **repeat 2-3-4 ... 2-3-4 ...**
- 4) clients get the answer $OR(W1, W2, \dots)$
- 3) each worker matches the fingerprint against its DB partition
- 2) clients broadcast requests to all workers
- 1) references to DB slices are scattered

⊕ RPC or dataflow bindings

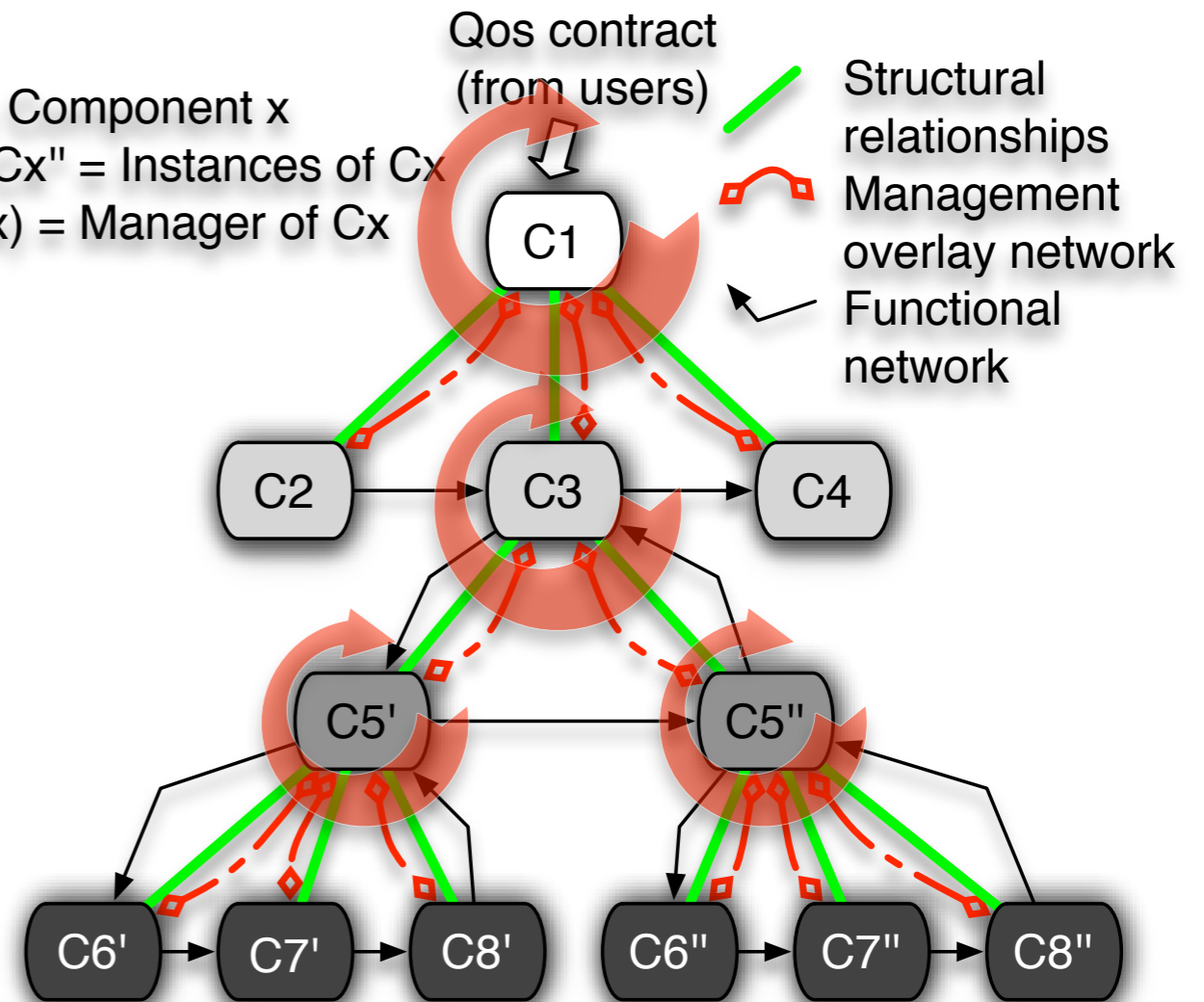
⋯ management bindings

⊕⊖ data sharing port bindings

Overlay of Management



C_x = Component x
 C_x', C_x'' = Instances of C_x
 $M(C_x)$ = Manager of C_x



Overlay of management: motivation



$T_s > \text{low}$
 $T_s < \text{high}$

1) push a QoS contract, e.g. $\text{low} < T_s < \text{high}$

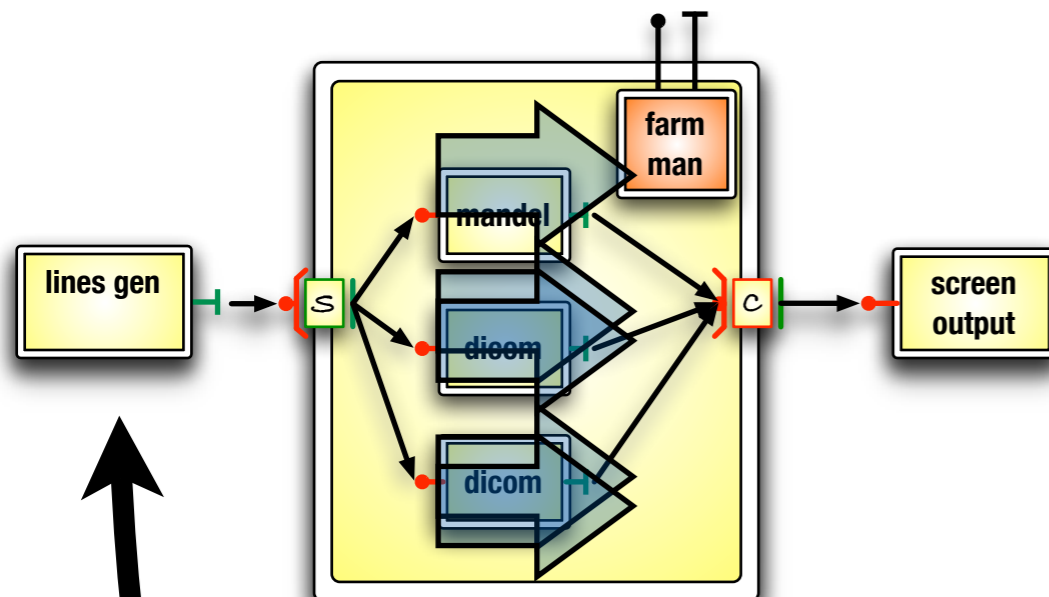
2) run the application

3) suppose $\text{low} > T_s$

4) farm man react adding one or more workers to increase farm **potential** power

5) that is ok in many case, not always ...

6) if the farm is not receiving enough tasks the **reaction is simply wrong**



Overlay of management: example



$T_s > \text{low}$
 $T_s < \text{high}$

1) push a QoS contract, e.g. $\text{low} < T_s < \text{high}$

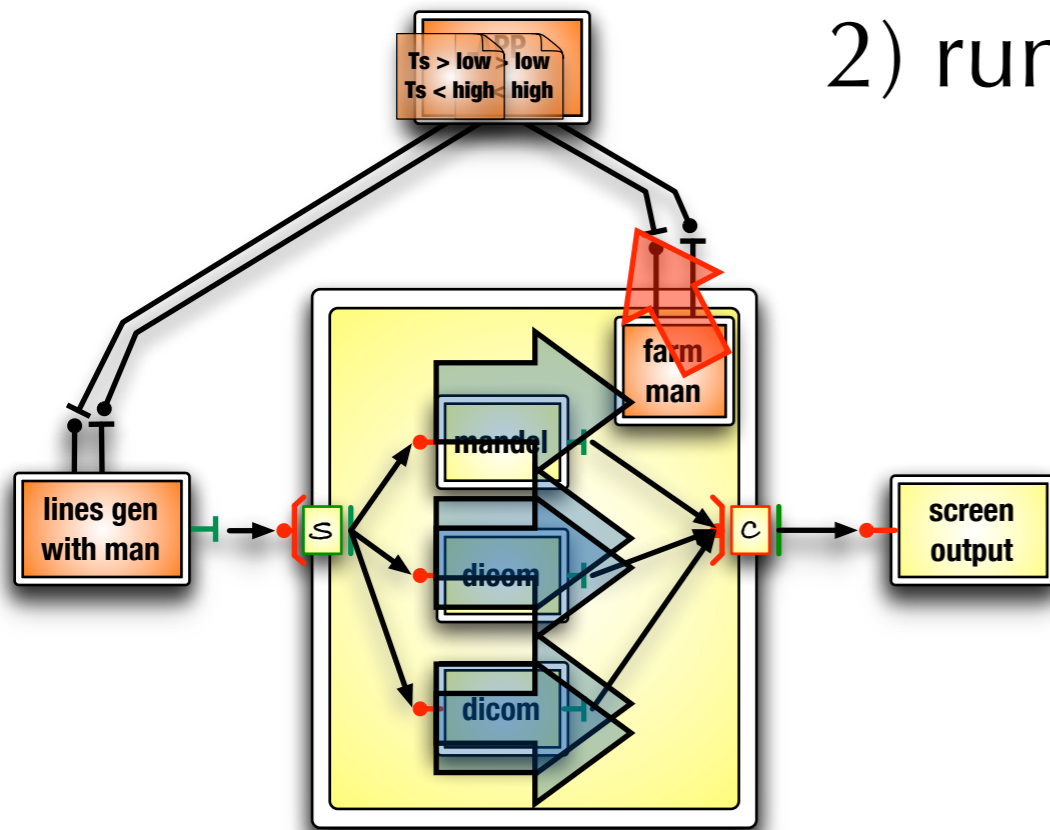
2) run the application

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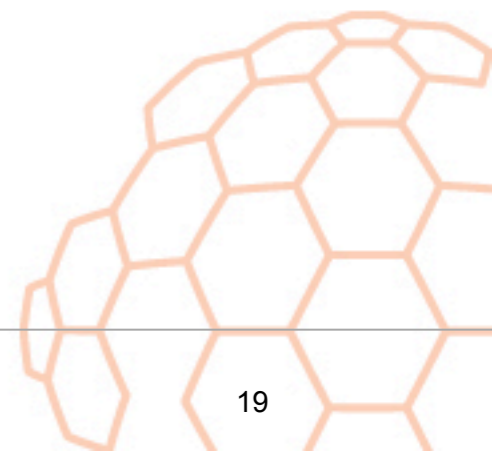
4) farm man react as follows:
if $T_{\text{arrival}} > \text{low}$ **then** add_w
else $\text{raiseup}(\text{not_enough_tasks})$

5) man. now involve a global decision

6) as an example APP manager manager may ask lines gen manager to increase the task rate



Two tiers management demo (Mandelbrot)



● Behavioural Skeletons in GCM

- templates with built-in management for the App designer
- methodology for the skeleton designer
 - management can be changed/refined
 - just prove your own management is correct against skeleton functional description
- can be freely mixed with standard GCM components
 - because once instanced, they are standard

● Overlay of management

- relying on JBoss drools for manager policy
- now supporting distributed overlay of management
 - e.g. hierarchical management

