



# Solving Distance CSP with Uncertainties



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Supervisor: Bertrand Neveu

Sophia Antipolis, October 25<sup>th</sup>, 2005

## Outline



- Problem statement (Distance CSP and uncertainties)
- Some applications
- Classic approach for solving Distance CSP
  - Some disadvantage
- A new methodology
  - Space Separation Algorithm and Feasibility Checker
  - Special Quantifier Elimination and Generalized Intervals
  - A new conditions for inner boxes
- Conclusions and future works

## Problem Statement

- Solving CSP (Constraint Satisfaction Problem)
- What is a CSP?
  - Variables (set of decision objects)
  - Domains (set of values for variables)
  - Constraints (relations on the variables)
- Example
 
$$P = (V, D, C)$$

$$V = \{x, y\} \quad D = \{\{1,2\}, \{2,5\}\} \quad C = \{x = y\}$$
- What means “to solve a CSP”?  $x = 2, y = 2$

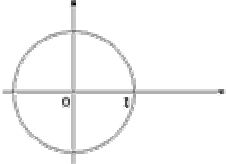


## Problem Statement

- Distance CSP
  - Continuous domains
  - Specific constraints
  - Geometric representation
- Example
 
$$P = (V, D, C)$$

$$V = \{x, y\}$$

$$D = \{[-10,10], [-10,10]\}$$

$$C = \{x^2 + y^2 = 1^2\}$$

$$c: \sum_{k=1}^n (x_k - y_k)^2 = d_i^2$$




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  - Specific constraints
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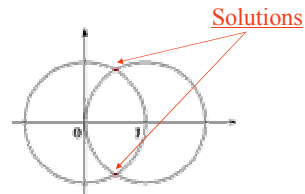
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$$V = \{x, y\}$$

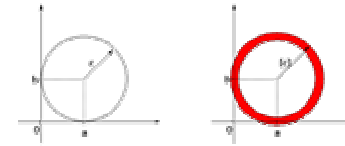
$$D = \{[-10, 10], [-10, 10]\}$$

$$C = \{x^2 + y^2 = 1^2, (x-1)^2 + y^2 = 1^2\}$$



## Problem Statement

- Uncertainties?
  - Parameters
    - Interval values
  - Distance (easy) or Centre (difficult)



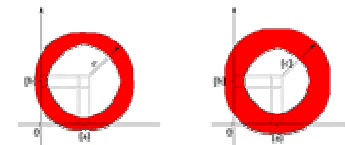
- Examples

$$(x-a)^2 + (y-b)^2 = c^2$$

$$(x-a)^2 + (y-b)^2 = [c]^2$$

$$(x-[a])^2 + (y-[b])^2 = c^2$$

$$(x-[a])^2 + (y-[b])^2 = [c]^2$$



## Problem Statement

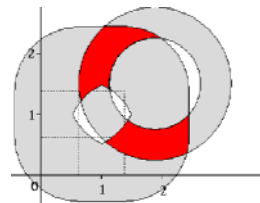
- Solving a Distance CSP
  - Find a description of solutions set as precise as possible

$$CSP \ P = (V, D, C)$$

$$V = \{\vec{P}_1, \dots, \vec{P}_k\}$$

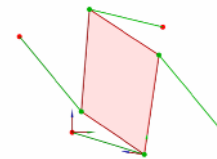
$$D = \{I_1^a, \dots, I_k^a\}$$

$$C = \{d(\vec{P}_i, \vec{P}_j) = d_{ij}, \dots\}$$

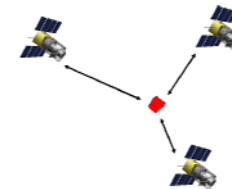


## Applications

### Robotics



### Positioning



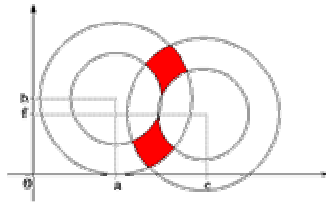
## A Classic Approach

- Applying a Branch and Prune Algorithm

- Filtering phase
- Bisection phase
- Calculating a paving with a given precision

- Problems

- A set of boxes without additional information
- Inefficient computation bisecting inner boxes



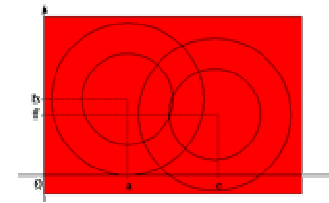
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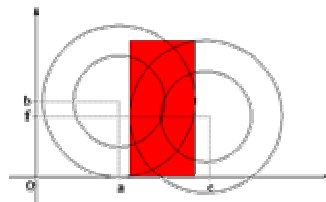
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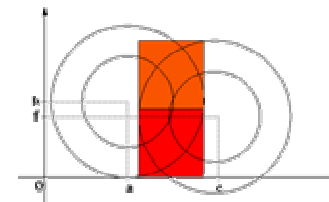
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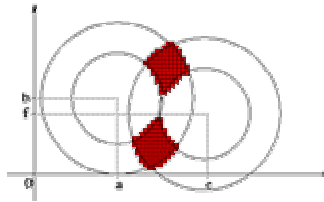
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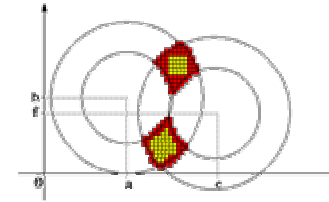
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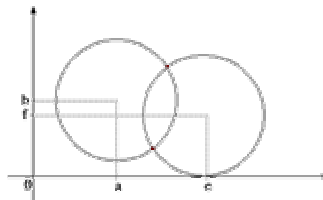
## A New Methodology (CP 2005)

- Initial space separation (isolate)

- Solving the problem without considering the uncertainties
- Applying a Space Separation Algorithm
- Solving a set of CSPs with uncertainties

- Feasibility Checker

- Using a feasibility checker each time the filtering phase does not reduce the domains in order to detect inner boxes.



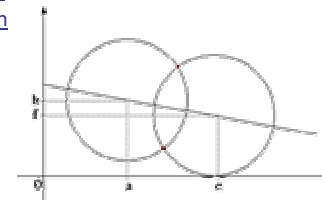
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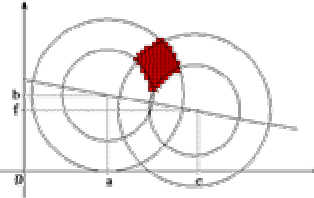
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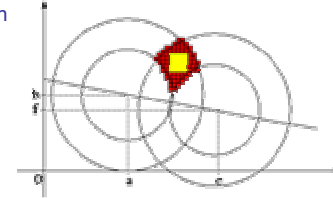
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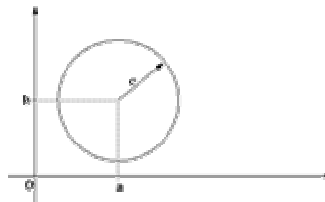
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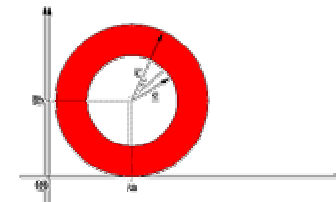
## Feasibility Checker (FC)

$$(x-a)^2 + (y-b)^2 = c^2$$



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$$(x-a)^2 + (y-b)^2 = [c, \bar{c}]^2$$



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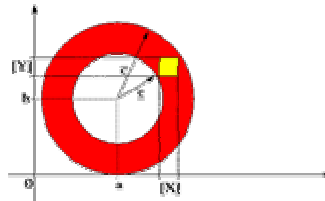
$$(x-a)^2 + (y-b)^2 = [\underline{c}, \bar{c}]^2$$

$$F(X, Y) = ([X]-a)^2 + ([Y]-b)^2$$

$$F(X, Y) \subseteq [\underline{c}, \bar{c}]^2$$

$$\forall x \in [X], \forall y \in [Y] \exists c \in [C]$$

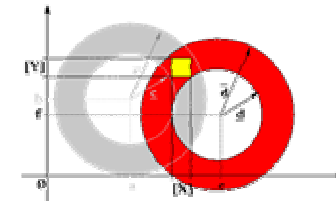
$$((x-a)^2 + (y-b)^2 = c^2)$$



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$$(x-a)^2 + (y-b)^2 = [\underline{c}, \bar{c}]^2$$

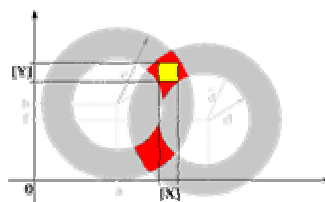
$$(x-e)^2 + (y-f)^2 = [\underline{d}, \bar{d}]^2$$



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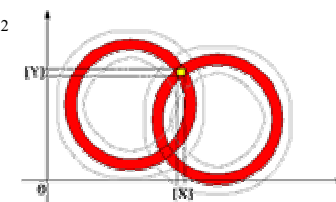
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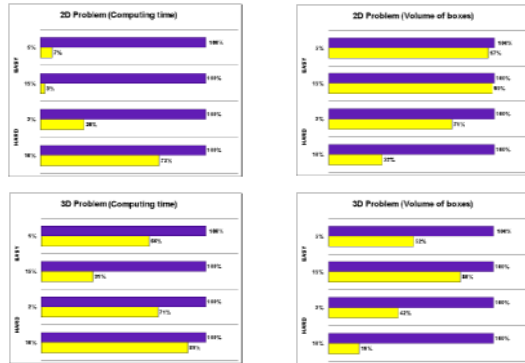
$$\downarrow$$

$$([X]-\hat{a})^2 + ([Y]-\hat{b})^2 \subseteq [c]^2$$

(sufficient condition)

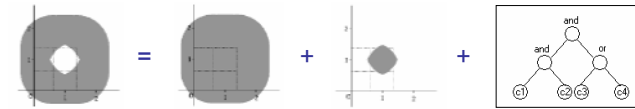


## Preliminary Results



## Inner Boxes Checkers (SAC 2006)

- A Specific Quantifier Elimination (QE)



- Generalized Interval Evaluation (GI)

- Classic

$$x + a : [1,3] + [4,8] = [5,11]$$

$$x + a : [1,3] + [4,5] = [5,8]$$

- Generalized

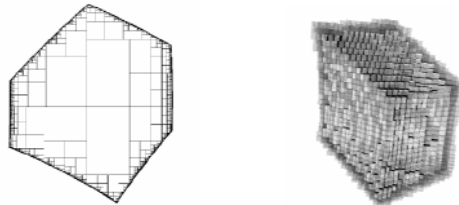
$$x + a : [1,3] + [8,4] = [9,7]$$

$$x + a : [1,3] + [5,4] = [6,7]$$



## Inner Boxes Checkers

- Some Results



- Sufficient Conditions (necessary in some cases)



## A New Inner Boxes Checker (?)

- Proposition

if  $(\vec{P}_x \cap \vec{P}_a = \emptyset) \Rightarrow GI$  is a necessary condition

- Example

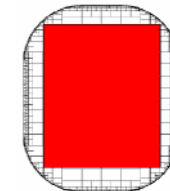
$$([x]-[a])^2 + ([y]-[b])^2 \subseteq [c]^2$$

- New checker

$$Z_1 = ([x]-[a])^2$$

$$Z_2 = ([y]-[b])^2$$

$$Z_1 + Z_2 - [c] \subseteq [0,0]$$



- Sufficient and Necessary condition



## Conclusions

- A new approach for solving Distance CSP with uncertainties was proposed
  - Improving information in the solver results
  - Improving computing time by using a feasibility checker
- Different inner boxes checkers were analysed
  - Classic IA, Quantified Elimination, Generalized Interval
  - A new necessary a sufficient condition was found
- Future Works
  - Studying a Generalization of the new condition
  - Combining with a decomposition algorithm



Questions...

