

Arithmetic-Geometric Means for π

A formal study

Yves Bertot

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Objectives

- ▶ Already studied computations of π through roots of cos, arctan, Archimedes
- ▶ Follow an exam from the French national selection exams for math teachers (5 hour exam, graduate level)
- ▶ Going further into mathematics (calculus, mainly),
- ▶ New aspects: more difficulties around derivatives and integration
- ▶ Use of square roots in computation
- ▶ Test the capabilities of Coq as a programming language

The context

- ▶ The arithmetic geometric mean algorithm
 - ▶ Take arbitrary a and b positive real numbers,
 - ▶ Set $a_0 = a$, $b_0 = b$,
 - ▶ Set $a_{n+1} = \frac{a_n + b_n}{2}$ and $b_{n+1} = \sqrt{a_n b_n}$,
- ▶ Properties:
 - ▶ $0 < n \Rightarrow b_n < a_n$
 - ▶ a_n and b_n converge fast towards a value $M(a, b)$

	a	b
0	1	.5
1	0.75	0.70...
2	0.7285	0.7282
3	0.72839552	0.72839550
4	0.7283955155234534	0.7283955155234533

Derivatives of arithmetic geometric mean

- ▶ Consider the case $a_0 = 1$ $b_0 = x$,
- ▶ Specialize to $f_n(x) = a_n(1, x)$,
- ▶ f_n converges uniformly towards $f(x) = M(1, x)$,
- ▶ the function f is derivable with the property:

$$\pi = 2\sqrt{2} \frac{f^3\left(\frac{1}{\sqrt{2}}\right)}{f'\left(\frac{1}{\sqrt{2}}\right)} = 2\sqrt{2} \lim_{n \rightarrow \infty} \frac{b_n^2\left(1, \frac{1}{\sqrt{2}}\right) a_n\left(1, \frac{1}{\sqrt{2}}\right)}{a_n'\left(1, \frac{1}{\sqrt{2}}\right)}$$

- ▶ This property is established by studying *elliptic curves*

Algorithm for π (one variant)

- ▶ $y_n(x) = \frac{a_n(x)}{b_n(x)} \quad z_n(x) = \frac{b'_n(x)}{a'_n(x)}$
- ▶ $y_{n+1}(x) = \frac{1 + y_n(x)}{2\sqrt{y_n(x)}} \quad z_{n+1}(x) = \frac{1 + y_n(x)z_n(x)}{(1 + z_n(x))\sqrt{y_n(x)}}$
- ▶ $y_0(\frac{1}{\sqrt{2}}) = \sqrt{2} \quad z_1(\frac{1}{\sqrt{2}}) = \sqrt{\sqrt{2}}$
- ▶ $\pi_0 = 2 + \sqrt{2} \quad \pi_{n+1} = \pi_n \frac{1 + y_{n+1}(\frac{1}{\sqrt{2}})}{1 + z_{n+1}(\frac{1}{\sqrt{2}})}$
- ▶ for $1 \leq n$ $0 \leq \pi_{n+1} - \pi \leq \frac{4\pi_0}{500^{2^n}}$

Formalization context

- ▶ Started with Coq's standard library
- ▶ Important tactic: `psatzl` (F. Besson)
 - ▶ Not using the `sos` extension: trouble installing `csdp`
- ▶ Switch to Coquelicot (Boldo, Lelay, Melquiond)
 - ▶ Drawback: unstable library
 - ▶ Drawback: result more complex to distribute
 - ▶ Advantage: using others' work
 - ▶ Advantage: More regular collections of theorems

General purpose contributions

- ▶ A variable change theorem for Riemann integrals
- ▶ Improper integrals in the style of Coq's standard library
 - ▶ A function is `up_infinite_integrable` if $\int_a^b f(x)dx$ has a limit when b grows to ∞
 - ▶ `upInt f a h` is the value (h is the proof)
 - ▶ the same for `down_infinite_integrable` and `infinite_integrable`
 - ▶ General theorems: *Chasles*, linearity, improper integral of x^{-k} , bounds, extensionality
- ▶ A study of `arcsinh`
- ▶ **Dini** : every increasing sequence of continuous functions converging pointwise to a continuous function converges uniformly,

Example lemma: variable change in integrals

```
Lemma RiemannInt_variable_change : (* standard *)  
  forall f g g' a b (ab : a <= b)  
    (h : Riemann_integrable  
      (fun x => g' x * f (g x)) a b)  
    (h' : Riemann_integrable f (g a) (g b)),  
  (forall x, a <= x <= b -> is_derive g x (g' x)) ->  
  (forall x, a <= x <= b -> g a <= g x <= g b) ->  
  (forall x, g a <= x <= g b -> continuity_pt f x) ->  
  (forall x, a <= x <= b -> continuity_pt g' x) ->  
  RiemannInt h = RiemannInt h'.
```

Note that the type of h and h' is used to know what is computed in `RiemannInt`

Definition of arithmetic geometric mean sequence

- ▶ a simple recursive function returning a pair of values

```
Fixpoint ag (a b : R) (n : nat) :=  
  match n with  
  | 0%nat => (a, b)  
  | S p => let (a_p, b_p) := ag a b p in  
            ((a_p + b_p)/2, sqrt(a_p * b_p))  
end.
```

- ▶ Proofs that the two sequences are monotonous and converge are easy.

Link to elliptic integrals

- ▶ Elliptic integrals come in the form of

$$I(a, b) = \int_0^{\infty} \frac{dt}{\sqrt{(t^2 + a^2)(t^2 + b^2)}}$$

- ▶ Proved equality :

$$I(a, b) = I\left(\frac{a+b}{2}, \sqrt{ab}\right)$$

- ▶ and also

$$I(a, b) = \int_0^{\frac{\pi}{2}} \frac{dx}{\sqrt{a^2 \cos^2 x + b^2 \sin^2 x}}$$

- ▶ proofs using ε reasoning: show that the difference is smaller than any positive ε
- ▶ Both proofs rely on variable changes, need 300 and 200 lines of proof.

Commuting derivation and integrals

- ▶ Important contribution from the `coquelicot` library

$$\frac{d \int_u^v f(w, t) dt}{dw}(x) = \int_u^v \frac{df(w, t)}{dw}(x) dt$$

(under the right conditions for f around x)

- ▶ Used to show that $I(a, b) = \frac{\pi}{2M(a, b)}$
- ▶ This is a formula for computing elliptic integrals when π is known (attributed to Gauß)

Behavior for $(1, b)$ and b close to 0

- ▶ Through another variable change we have:

$$\int_0^\infty \frac{dt}{\sqrt{(t^2+1)(t^2+b^2)}} = 2 \int_0^{\sqrt{b}} \frac{dt}{\sqrt{(t^2+1)(t^2+b^2)}}$$

$$\int_0^{\sqrt{b}} \frac{dt}{\sqrt{(t^2+1)(t^2+b^2)}} \sim \operatorname{arcsinh}(\sqrt{b}) \quad \text{for } b \rightarrow 0^+$$

- ▶ by direct reasoning on agm we have:

$$2^n f\left(\frac{\sqrt{a_n(1,x)^2 - b_n(1,x)^2}}{a_n(1,x)}\right) = \frac{f(\sqrt{1-x^2})}{f(x)}$$

Link to derivatives

$$f(x) \sim \frac{-\pi}{2\ln(x)} \quad \text{for } x \rightarrow 0^+$$

- ▶ With equivalences and equalities from the previous slides

$$\lim_{n \rightarrow \infty} 2^{-n} \ln \left(\frac{a_n(1, x)}{\sqrt{a_n(1, x)^2 - b_n(1, x)^2}} \right) = \frac{\pi}{2} \frac{f(x)}{f(\sqrt{1-x^2})}$$

- ▶ Studying separately the derivatives of the left hand side and deriving directly the right-hand-side

$$\frac{f^2(x)}{x(1-x^2)} = \frac{\pi}{2} \frac{f'(x)f(\sqrt{1-x^2}) - \frac{-x}{\sqrt{1-x^2}}f(x)f'(\sqrt{1-x^2}))}{f^2(\sqrt{1-x^2})}$$

Main derivative formula

- ▶ at $x = \frac{1}{\sqrt{2}}$ the last formula simplifies greatly into:

$$\pi = 2\sqrt{2} \frac{f^3(\frac{1}{\sqrt{2}})}{f'(\frac{1}{\sqrt{2}})}$$

- ▶ To compute the ratio, we can compute approximations of f and f' as approximated by $a_n(1, x)$ and $b_n(1, x)$ and their derivatives
- ▶ More efficient to work with $y_n = \frac{a_n}{b_n}$ and $z_n = \frac{b'_n}{a'_n}$
- ▶ Use the Dini theorem to express that a_n converges uniformly towards f .

Abstract description

```
Fixpoint agmpi n :=  
  match n with  
    0%nat => (2 + sqrt 2)  
  | S p => agmpi p * (1 + y_ n (/sqrt 2))  
          / (1 + z_ n (/sqrt 2))  
  end.
```

Concretely computing a large number of decimals

- ▶ Computing with large integers
 - ▶ To compute at precision $\frac{1}{p}$, multiply all values by p
- ▶ Théry et al. provide numbers as binary trees whose leaves are 31bit words,
 - ▶ Still not comparable to GMP : no arrays, more memory consumption
- ▶ Fast square roots re-implemented by Théry from previous work by Zimmermann, Magaud, & B.
- ▶ Fast execution provided by Dénès' native computation.
 - ▶ just-in-time compilation and execution directly inside Coq
- ▶ Work yet to be completed: formal proofs about error composition

Fixed precision computation

Definition hp1 :=

 (*some large integer*) (2 ^ precision)%bigZ.

Definition invhp x := (hp1 * hp1 / x)%bigZ.

Definition sqrthp x := BigZ.sqrt (x * hp1).

Definition mulhp x y := ((x * y) / hp1)%bigZ.

Definition addhp x y := (x + y)%bigZ.

Notation "x + y" := (addhp x y) : hp_scope.

Notation "x * y" := (mulhp x y) : hp_scope.

Notation "x / y" := (mulhp x (invhp y)) : hp_scope.

Delimit Scope hp_scope with H.

Concrete implementation of algorithm

```
Fixpoint agmpi n :=
  match n with
  | 0%nat => ((hp2 + (sqrthp hp2))%H, y1, z1)
  | S p =>
    let '(pip, yn, zn) := agmpi p in
    let sy := sqrthp yn in
    let zn1 := (hp1 + zn)%H in
    ((pip * ((hp1 + yn)%H / zn1)%H)%H,
     ((hp1 + yn)%H / (hp2 * sy)%H)%H,
     ((hp1 + (yn * zn)%H)%H / (zn1 * sy)%H)%H)
  end.
```

Error analysis



$$0 \leq \pi_n - \pi \leq \frac{4\pi_0}{500^{2^n}}$$

- ▶ Square root and division computations on integers
 - ▶ rounding by default (towards 0)

$$\sqrt{x} - e < \boxed{\text{sqrt}(x)} \leq \sqrt{x}$$

$$\frac{x}{y} - e < \boxed{\frac{x}{y}} \leq \frac{x}{y}$$

- ▶ A theorem to control error propagation

$$e < \frac{e'}{3} \quad \wedge \quad |\boxed{y_n} - y_n| < e' \quad \Rightarrow \quad \left| \frac{1 + \boxed{y_n}}{2 \boxed{\text{sqrt}(\boxed{y_n})}} - \frac{1 + y_n}{2\sqrt{y_n}} \right| < e'$$

Several attempt for error estimation in y_n

- ▶ First attempts looking like naive interval arithmetics
 - ▶ with bisection
- ▶ Last attempt using derivative and *mean value theorem*
 - ▶ error cancellation improves as y_n gets closer to 1
 - ▶ derivative of $\frac{1+y}{2\sqrt{y}}$ is $\frac{y-1}{4y\sqrt{y}}$
- ▶ So if error on y_n is within a few ulp, the error on y_{n+1} will stay the same

To be continued

- ▶ Need the same kind of error control for z_n
- ▶ Need to propagate the errors through the repeated multiplications
- ▶ Maybe replace square root with one rounding up

Running the program

- ▶ Write (in Coq) a program enumerating the digits
- ▶ Write (in Ocaml) the printing of the digits

Packaging the function call

```
Inductive bin := L (x : Z) | N (t1 t2 : bin).
```

```
Fixpoint ntb (x:bigZ) (n : nat) (b : bigZ) :=  
match n with  
  0 => L (BigZ.to_Z x)  
| S p => let (y, z) := BigZ.div_eucl x (10 ^ b) in  
  N (ntb y p (BigZ.div b 2)) (ntb z p (BigZ.div b 2))  
end.
```

```
Definition digits rank :=  
let hp1 := (10 ^ (2 ^ bigZ_of_nat rank))%bigZ in  
let hp2 := (hp1 + hp1)%bigZ in  
ntb (pi hp1 hp2 rank) rank  
  (2 ^ bigZ_of_nat (pred rank))%bigZ.
```

```
Extraction "pi.ml" digits.
```

Lessons learned

- ▶ Corpus of known facts is really growing
- ▶ Navigating libraries, `ssrflect`, Coq standard library, `coquelicot`, *Need for streamlining*
- ▶ Reflexions on more advanced tactics
 - ▶ Automatic proofs of positivity for simple expressions
 - ▶ Automatic proofs of derivability, continuity
- ▶ Extracted code may be less efficient than code inside Coq
- ▶ Hope to continue the efforts towards an imperative implementation