No-Regret Caching via Online Mirror Descent

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We can place a local cache with finite capacity to satisfy some of the requests.

- Least recently used (LRU)
- Least frequently used (LFU)
- $\bullet \ \ldots \ many$ more variants based on LRU and LFU

System

- Catalog of files $\mathcal{N} = \{1, 2, \dots, N\}$
- $w_i \in \mathbb{R}_+$ cost to serve file *i* from the remote server
- $k \in \mathbb{N}$ is the cache capacity
- The cache can store fractions of files. The set of valid cache configurations is $\mathcal{X} = \left\{ x \in [0, 1]^N : \sum_{i=1}^N x_i = k \right\}$
- In a followup work we also consider integral caches.¹



¹T. Si Salem et al., arXiv preprint arXiv:2101.12588 2021.

Requests

• We consider that requests may arrive in batches of size *R*, where a given file is requested at most *h* times



• $\frac{R}{h}$ represented the diversity of the requests in a batch

When a request batch r_t arrives, the cache incurs the following cost:

$$f_{r_t}(x_t) = \sum_{i=1}^N w_i r_{t,i} (1 - x_{t,i}).$$

Uncertain Environment pprox Adversary

- Files popularity can change over time in an unpredictable manner.
- We target robust performance: the users can behave as adversaries selecting the request process to harm the system.



 $Regret = Total \ cost \ of \ the \ policy - Total \ cost \ of \ the \ static \ optimum$

$$= \sum_{t=1}^{T} f_{r_t}(x_t) - \sum_{t=1}^{T} f_{r_t}(x_*)$$

where x_* is the optimal static cache configuration.

- If the average regret (Regret/T) tends to 0 when T is large, then the policy experiences on average the same costs as the best static optimum!
- This happens when the regret is sublinear in *T*. Such policy is called a no-regret policy.

• One could get inspired from offline optimization and select a new state trying to minimize the aggregate cost. This can fail catastrophically, because of the adversarial nature of the requests!

Paschos et al.² proposed OGD for online caching, that updates the cache state as follows:

- When a request is received r_t the system incurs a cost $f_{r_t}(x_t)$
- Take a gradient update step $\tilde{x}_{t+1} = x_t \eta \nabla f_{r_t}(x_t)$
- Project \tilde{x}_{t+1} to the set of valid cache configurations \mathcal{X}
- Obtain the new state $x_{t+1} = \Pi_{\mathcal{X}}(\tilde{x}_{t+1})$

²G. S. Paschos et al. in IEEE INFOCOM 2019 - IEEE Conference on Computer Communications, **2019**, pp. 235–243.

- It is a no-regret policy!
- This result is proved in Paschos et al.³ only for R = h = 1

³G. S. Paschos et al. in IEEE INFOCOM 2019 - IEEE Conference on Computer Communications, **2019**, pp. 235–243.

Contributions

- First to apply the more general online mirror descent (OMD), a family of gradient methods that includes OGD as a special case
- Analyse OGD in the case R ≠ h ≠ 1. We also improve on the Paschos et al.'s bound (valid only for R = h = 1) by a factor at least √2
- Show that another policy in the OMD family has lower regret for diverse adversarial requests or small cache sizes (difficult scenarios), and enjoys lower computational cost
- Prove that the optimal OMD strategy depends on the diversity of the request batches
- Evaluate the policies on synthetic traces and a real CDN trace

Online Mirror Descent (OMD)



Figure 2: OMD update rule⁴.

Different mirror maps Φ give different algorithms.

⁴S. Bubeck, Found. Trends Mach. Learn. 2015, 8, 231–357.

Negative Entropy Mirror Map

• We propose to use OMD with the negative entropy mirror map

$$\Phi(\mathbf{x}) = \sum_{i=1}^{N} x_i \log(x_i)$$

• OMD under the neg-entropy mirror map $\rm (OMD_{NE})$ adapts the cache state via a multiplicative rule, as opposed to the additive rule of OGD

$$\tilde{x}_{t+1,i} = x_{t,i} e^{-\eta \frac{\partial f_{r_t}(x_t)}{\partial x_i}}.$$

- The mirror map is more suitable to the geometry of $\ensuremath{\mathcal{X}}$
- The projection is less costly than in OGD

 $\mathcal{O}(k)$ vs. $\mathcal{O}(N)$ for R = h = 1.

 $\mathcal{O}(N + k \log k)$ vs. $\mathcal{O}(N^2)$ for general values of R, h.

Fixed Popularity



 (a) Normalized Time
 (b) Normalized Time
 (c) Time-Averaged

 Averaged Cost of OGD
 Averaged Cost of
 Regret

 OMD_{NE}
 OMD
 OMD

The learning rate denoted by η^* is the learning rate that gives the tightest worst-case regrets for OGD and OMD_{NE} . While this learning rate is selected to protect against any (adversarial) request sequence, it is not too pessimistic.

Effect of Diversity



Zipf(α) popularity distribution:

- Low α gives batches with high diversity
- High α gives batches with low diversity

 $OMD_{\rm NE}$ outperforms OGD in the high-diversity regime and small cache sizes.

Robustness to Transient Requests



We observe that $\mathrm{OMD}_{\mathrm{NE}}$ is consistently more robust to popularity changes than OGD.

Akamai Trace



Normalized moving average cost of the different caching policies evaluated on the Akamai Trace. $\rm OMD_{NE}$ and OGD provide consistently the best performance compared to W-LFU, LRU and LFU. OGD performs slightly better than OMD in some parts of the trace.

Thank you for your attention!