

Empirical Risk Minimization and Zero-Sum Games with Noisy Observations

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Join work with **Ke Sun** and **Alain Jean-Marie**.

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Samir M. Perlaza, Iñaki Esnaola, and H. Vincent Poor. “**Sensitivity of the Gibbs Algorithm to Data Aggregation in Supervised Machine Learning**”. Research Report, INRIA, No. RR-9474, Sophia Antipolis, France, Jun., 2022.



Samir M. Perlaza, Gaetan Bisson, Iñaki Esnaola, Alain Jean-Marie, Stefano Rini, “**Empirical Risk Minimization with Relative Entropy Regularizations**”. Research Report, INRIA, No. RR-9454, Sophia Antipolis, France, Feb., 2022.



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The Problem of Supervised Learning

Notation and Definitions

Consider the following **supervised learning** scenario:

- three sets \mathcal{X} (patterns), \mathcal{Y} (labels) and $\mathcal{M} \subset \mathbb{R}^d$ (models), with $d \in \mathbb{N}$.
- a function $f : \mathcal{M} \times \mathcal{X} \rightarrow \mathcal{Y}$ (explicit expression **is known**)

Statistical Assumptions

Two random variables X and Y satisfy

$$Y = f(\theta^*, X), \quad (1)$$

for some specific model θ^* (optimal model or hypothesis).

- model θ^* is **unknown**
- a dataset $\mathbf{z} = ((x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)) \in (\mathcal{X} \times \mathcal{Y})^n$ **is available**



The Problem of Supervised Learning

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Consider the following **supervised learning** scenario:

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Statistical Assumptions

Two random variables X and Y satisfy

$$Y = f(\theta^*, X), \quad (1)$$

for some specific model θ^* (optimal model or hypothesis).

Objective: Model Selection

Given a dataset $z \in (\mathcal{X} \times \mathcal{Y})^n$, find the model θ^* in (1)

Empirical Risk Minimization: The Problem of Supervised Learning

Problem Formulation

- Let $\ell : \mathcal{Y} \times \mathcal{Y} \rightarrow [0, +\infty)$ be a **risk (or loss or cost)** function.

Risk

Given a data point $(x, y) \in \mathcal{X} \times \mathcal{Y}$, the model $\theta \in \mathcal{M}$ induces the **risk** $\ell(f(\theta, x), y)$.

Empirical Risk

Given a dataset $z = ((x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)) \in (\mathcal{X} \times \mathcal{Y})^n$, the *empirical risk* induced by the model $\theta \in \mathcal{M}$ is

$$L_z(\theta) = \frac{1}{n} \sum_{i=1}^n \ell(f(\theta, x_i), y_i). \quad (2)$$

Empirical Risk Minimization: The Problem of Supervised Learning

Problem Formulation

- Let $\ell : \mathcal{Y} \times \mathcal{Y} \rightarrow [0, +\infty)$ be a **risk (or loss or cost)** function.

Risk

Given a data point $(x, y) \in \mathcal{X} \times \mathcal{Y}$, the model $\theta \in \mathcal{M}$ induces the **risk** $\ell(f(\theta, x), y)$.

Empirical Risk

Given a dataset $z = ((x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)) \in (\mathcal{X} \times \mathcal{Y})^n$, the *empirical risk* induced by the model $\theta \in \mathcal{M}$ is

$$L_z(\theta) = \frac{1}{n} \sum_{i=1}^n \ell(f(\theta, x_i), y_i). \quad (2)$$

Problem Formulation: Empirical Risk Minimization (ERM)

Given the dataset z , solve $\min_{\theta \in \mathcal{M}} L_z(\theta)$.

The Problem of Supervised Learning: Empirical Risk Minimization

Problem Formulation: Empirical Risk Minimization (ERM)

Given a **noisy** dataset \tilde{z} , $\min_{\theta \in \mathcal{M}} L_{\tilde{z}}(\theta)$.

Strong connection with other problems:

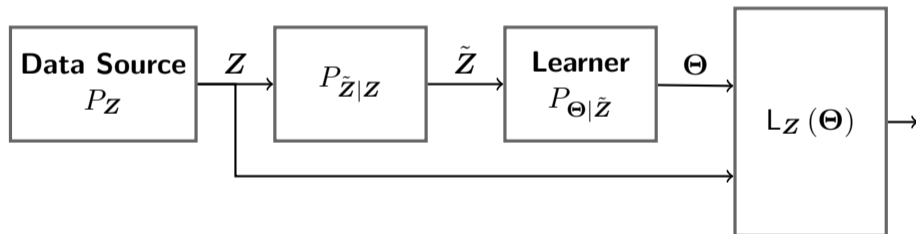
- M -Estimation
- minimum contrast estimation
- sample average approximation

Appears in: machine learning, statistical physics, statistics, operations research, decision making, game theory, information theory, stochastic optimization, ...

The Problem of Supervised Learning: Empirical Risk Minimization

Problem Formulation: Empirical Risk Minimization (ERM)

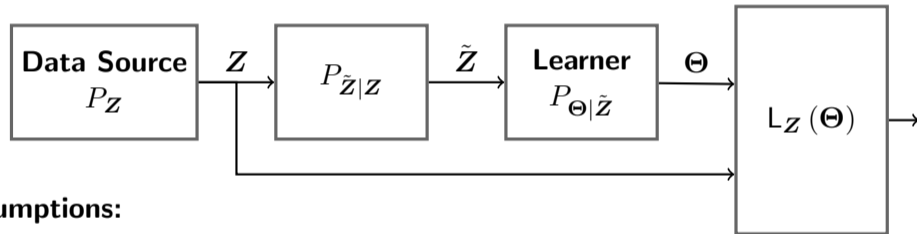
Given a **noisy** dataset \tilde{z} , $\min_{\theta \in \mathcal{M}} L_{\tilde{z}}(\theta)$.



The Problem of Supervised Learning: Empirical Risk Minimization

Problem Formulation: Empirical Risk Minimization (ERM)

Given a **noisy** dataset \tilde{z} , $\min_{\theta \in \mathcal{M}} L_{\tilde{z}}(\theta)$.

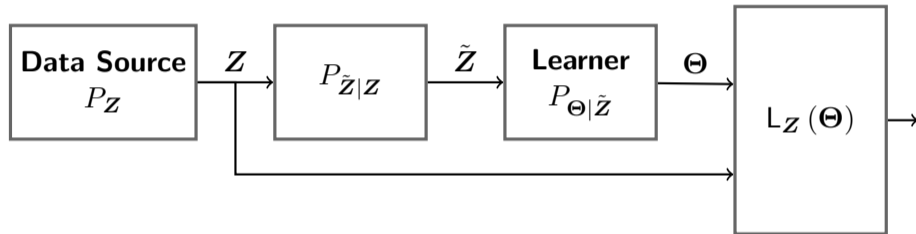


Assumptions:

- The probability measure P_Z is **unknown**.
- A **channel estimation** can be obtained with **arbitrary precision** by the Learner.
- A **prior** Q_Z on the data might be available:
 - Perfect prior: $D(P_Z \| Q_Z) = 0$ (ideal case)
 - **Mismatch**: $D(P_Z \| Q_Z) > 0$ (practical case)
- Consider P_Z is the measure that **maximizes the expected empirical risk**

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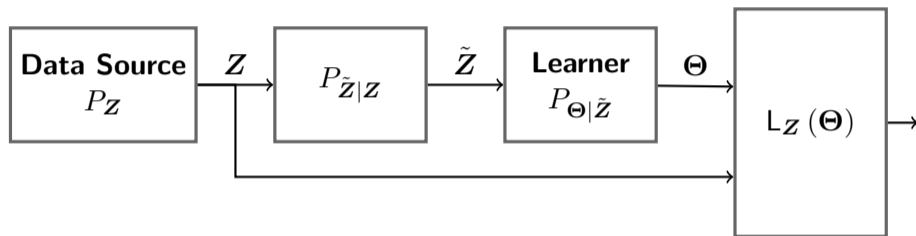
The Problem of Supervised Learning: Empirical Risk Minimization



Key Question:

How to **model** this interaction ?

The Problem of Supervised Learning: Empirical Risk Minimization



Key Question:

How to **model** this interaction ?

is this a **Zero-Sum Game**?

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Zero-Sum Games

Notation and Definitions

Consider a 2×2 ZSG in normal form, denoted by $\mathcal{G}(\underline{u})$, with payoff matrix

$$\underline{u} = \begin{pmatrix} u_{1,1} & u_{1,2} \\ u_{2,1} & u_{2,2} \end{pmatrix}.$$

- **Two actions** for Player 1: $\mathcal{A}_1 \triangleq \{a_1, a_2\}$; and for Player 2: $\mathcal{A}_2 \triangleq \{b_1, b_2\}$.
- $\forall (i, j) \in \{1, 2\}$, when Player 1 plays a_i and Player 2 plays b_j , the **payoff** is $u_{i,j}$

Player 1 chooses lines and Player 2 chooses columns

- $\forall k \in \{1, 2\}$, a **strategy** for Player k is a probability measure $P_{A_k} \in \Delta(\mathcal{A}_k)$.
- **Expected Payoff** determined by the function $u : \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$:

$$u(P_{A_1}, P_{A_2}) = \sum_{(i,j) \in \{1,2\}^2} P_{A_1}(a_i) P_{A_2}(b_j) u_{i,j}, \quad (3)$$

Player 1 **maximizes**, while Player 2 **minimizes** the payoff.



Zero-Sum Games

Nash Equilibria

Relevant solution concept when **actions are chosen simultaneously**: Nash Equilibrium.

Nash Equilibrium

The strategies $P_{A_1}^* \in \Delta(\mathcal{A}_1)$ and $P_{A_2}^* \in \Delta(\mathcal{A}_2)$ form an NE of the game $\mathcal{G}(\underline{u})$ if:

- For all $Q \in \Delta(\mathcal{A}_1)$,

$$u(P_{A_1}^*, P_{A_2}^*) \geq u(Q, P_{A_2}^*); \text{ and} \quad (4)$$

- For all $Q \in \Delta(\mathcal{A}_2)$,

$$u(P_{A_1}^*, P_{A_2}^*) \leq u(P_{A_1}^*, Q). \quad (5)$$

Zero-Sum Games

Nash Equilibria

Lemma (Nash Equilibria)

Let $P_{A_1}^* \in \Delta(A_1)$ and $P_{A_2}^* \in \Delta(A_2)$ form one NE of the game $\mathcal{G}(\underline{u})$. If the matrix \underline{u} satisfies

$$(u_{1,1} - u_{1,2})(u_{2,2} - u_{2,1}) > 0 \text{ and } (u_{1,1} - u_{2,1})(u_{2,2} - u_{1,2}) > 0, \quad (6)$$

then, the NE is unique and

$$P_{A_1}^*(a_1) = \frac{u_{2,2} - u_{2,1}}{u_{1,1} - u_{1,2} - u_{2,1} + u_{2,2}} \in (0, 1) \quad (7)$$

$$P_{A_2}^*(a_1) = \frac{u_{2,2} - u_{1,2}}{u_{1,1} - u_{1,2} - u_{2,1} + u_{2,2}} \in (0, 1), \text{ and} \quad (8)$$

$$u(P_{A_1}^*, P_{A_2}^*) = \frac{u_{1,1}u_{2,2} - u_{1,2}u_{2,1}}{u_{1,1} - u_{1,2} - u_{2,1} + u_{2,2}}. \quad (9)$$

If the matrix \underline{u} satisfies

$$(u_{1,1} - u_{1,2})(u_{2,2} - u_{2,1}) \leq 0 \text{ or } (u_{1,1} - u_{2,1})(u_{2,2} - u_{1,2}) \leq 0. \quad (10)$$

then, there exist either a unique NE or infinitely many NEs. Moreover,

$$u(P_{A_1}^*, P_{A_2}^*) = \min_{i \in \{1,2\}} \max_{j \in \{1,2\}} u_{i,j} = \max_{j \in \{1,2\}} \min_{i \in \{1,2\}} u_{i,j}. \quad (11)$$

Zero-Sum Games

Stackelberg Equilibrium

Solution concept with **irrevocable and public commitments**: Stackelberg Equilibrium.

- Player 2 (the leader) commits to choose its action by sampling a strategy $P_{A_2} \in \Delta(\mathcal{A}_2)$.
- Player 1 (the follower) observes P_{A_2} **but not the action chosen by Player 2**.
- Player 1 (the follower) chooses its strategy $P_{A_1} \in \Delta(\mathcal{A}_1)$ as a best response to P_{A_2} .

Definition (Stackelberg Equilibrium)

The strategies $P_{A_1}^\bullet \in \Delta(\mathcal{A}_1)$ and $P_{A_2}^\bullet \in \Delta(\mathcal{A}_2)$ form an SE of the game $\mathcal{G}(\underline{u})$ if:

$$P_{A_2}^\bullet \in \arg \min_{Q \in \Delta(\mathcal{A}_2)} \max_{P \in \Delta(\mathcal{A}_1)} u(P, Q); \text{ and} \quad (12)$$

$$P_{A_1}^\bullet \in \arg \max_{P \in \Delta(\mathcal{A}_1)} u(P, P_{A_2}^\bullet). \quad (13)$$



Zero-Sum Games

Stackelberg Equilibrium

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- Player 1 (the follower) chooses its strategy $P_{A_1} \in \Delta(\mathcal{A}_1)$ as a best response to P_{A_2} .

Lemma

Let $P_{A_1}^* \in \Delta(\mathcal{A}_1)$ and $P_{A_2}^* \in \Delta(\mathcal{A}_2)$ form one NE of the game $\mathcal{G}(\underline{u})$. Let also $P_{A_1}^\bullet \in \Delta(\mathcal{A}_1)$ and $P_{A_2}^\bullet \in \Delta(\mathcal{A}_2)$ form one Stackelberg equilibrium of the game $\mathcal{G}(\underline{u})$. Then,

$$u(P_{A_1}^\bullet, P_{A_2}^\bullet) = u(P_{A_1}^*, P_{A_2}^*). \quad (12)$$



Zero-Sum Games

Stackelberg Equilibrium - **Special Case:** Commitments in Pure Strategies

Solution concept with **irrevocable and public commitments in pure strategies**

- Player 2 (the leader) **constrained** to commit to a strategy $P_{A_2} \in \Delta(\mathcal{A}_2)$ such that

$$P_{A_2}(b_1) \in \{0, 1\}. \quad (13)$$

- The follower observes P_{A_2} , which is equivalent to **observing the action** w.p. one.
- The follower chooses its strategy knowing the action played by Player 2.

Lemma

If the matrix \underline{u} satisfies

$$(u_{1,1} - u_{1,2})(u_{2,2} - u_{2,1}) > 0 \text{ and } (u_{1,1} - u_{2,1})(u_{2,2} - u_{1,2}) > 0, \quad (14)$$

then,

$$\max_{j \in \{1,2\}} \min_{i \in \{1,2\}} u_{i,j} \leq \frac{u_{1,1}u_{2,2} - u_{1,2}u_{2,1}}{u_{1,1} - u_{1,2} - u_{2,1} + u_{2,2}} \leq \min_{i \in \{1,2\}} \max_{j \in \{1,2\}} u_{i,j}. \quad (15)$$

Zero-Sum Games

Summary

- Two popular solution concepts: Nash and Stackelberg equilibria
- Commitments are immaterial as long as **the follower observes the actions**
- Commitments in pure strategies are **equivalent to perfect observation of the actions**
- No solution concept for **noisy observation of the actions**

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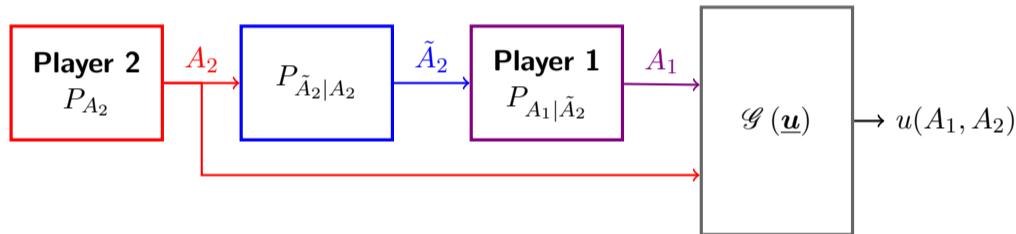
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Zero-Sum Games with **Noisy Observations**

Game Formulation

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



● Assumptions:

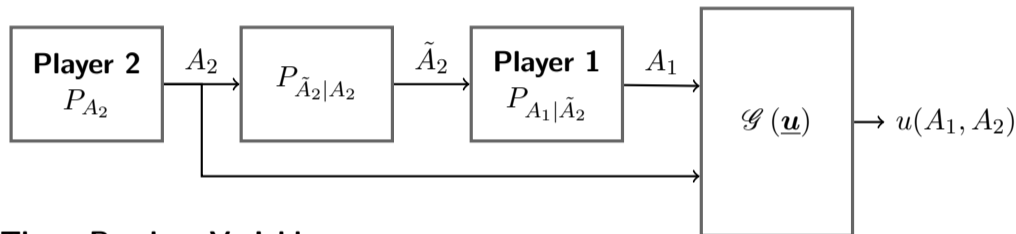
- Player 2 **publicly and irrevocably** commits to use a strategy;
- Player 2 plays an action, which is observed by the Player 1 through a **binary channel**;
- Player 1 chooses its strategy knowing the strategy and the leader's action **up to some noise**.

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Zero-Sum Games with Noisy Observations

Game Formulation

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



• Three Random Variables:

- Action of Player 1: A_1
- Action of Player 2: A_2
- Noisy Observation of the Action of Player 2: \tilde{A}_2 .
- Joint Probability Distribution: For all $(a, \tilde{b}, b) \in \mathcal{A}_1 \times \mathcal{A}_2 \times \mathcal{A}_2$,

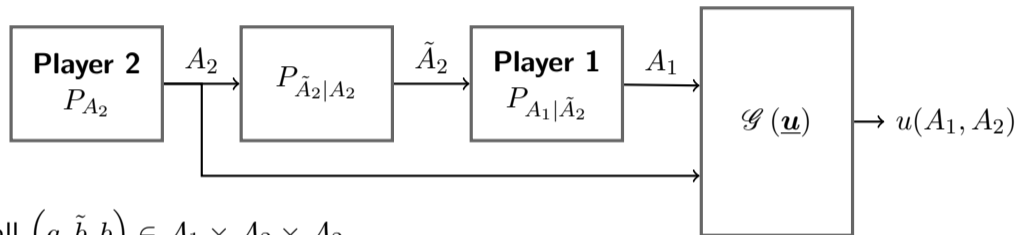
$$P_{A_1 \tilde{A}_2 A_2}(a, \tilde{b}, b) = P_{A_2}(b) P_{\tilde{A}_2|A_2=b}(\tilde{b}) P_{A_1|\tilde{A}_2=\tilde{b}}(a).$$

Inria (16)

Zero-Sum Games with Noisy Observations

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Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



For all $(a, \tilde{b}, b) \in \mathcal{A}_1 \times \mathcal{A}_2 \times \mathcal{A}_2$,

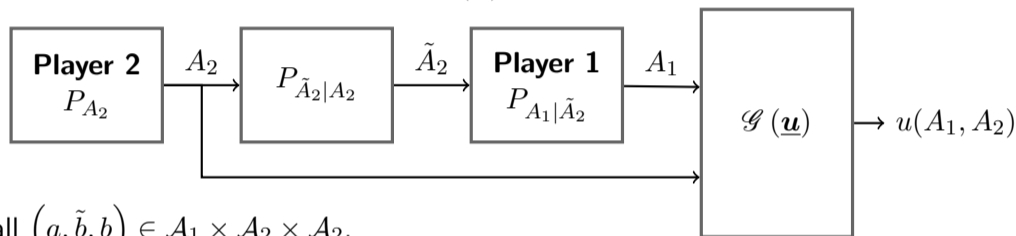
$$P_{A_1 \tilde{A}_2 A_2}(a, \tilde{b}, b) = P_{A_2}(b) P_{\tilde{A}_2|A_2=b}(\tilde{b}) P_{A_1|\tilde{A}_2=\tilde{b}}(a). \quad (16)$$

- **Strategy of Player 1:** $\forall b \in \mathcal{A}_2: P_{A_1|\tilde{A}_2=b} \in \Delta(\mathcal{A}_1)$
- **Strategy of Player 2:** $P_{A_2} \in \Delta(\mathcal{A}_2)$
- **Binary Channel:** $\forall b \in \mathcal{A}_2: P_{\tilde{A}_2|A_2=b} \in \Delta(\mathcal{A}_2)$

Zero-Sum Games with Noisy Observations

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For all $(a, \tilde{b}, b) \in \mathcal{A}_1 \times \mathcal{A}_2 \times \mathcal{A}_2$,

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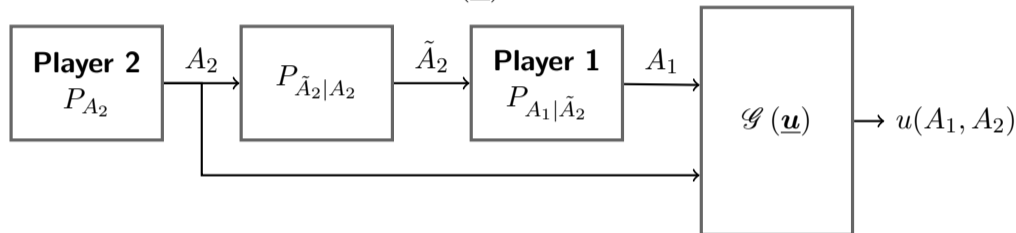
The **expected payoff** is determined by $v : \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$,

$$v\left(P_{A_1|\tilde{A}_2=b_1}, P_{A_1|\tilde{A}_2=b_2}, P_{A_2}\right) = \sum_{(i,j) \in \{1,2\}^2} u_{i,j} P_{A_1 A_2}(a_i, a_j). \quad (17)$$

Zero-Sum Games with Noisy Observations

Game Formulation

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



Definition (Equilibrium)

The tuple $(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger, P_{A_2}^\dagger) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ forms an equilibrium if

$$P_{A_2}^\dagger \in \arg \min_{P \in \Delta(\mathcal{A}_2)} \left(\max_{(Q_1, Q_2) \in \Delta(\mathcal{A}_1)^2} v(Q_1, Q_2, P) \right) \text{ and} \quad (16)$$

$$(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger) \in \max_{(Q_1, Q_2) \in \Delta(\mathcal{A}_1)^2} v(Q_1, Q_2, P). \quad (17)$$

Zero-Sum Games with **Noisy Observations**

Notation

- Alternative representation of the **channel**: $\underline{w} \triangleq \begin{pmatrix} P_{\tilde{A}_2|A_2=a_1}(a_1) & P_{\tilde{A}_2|A_2=a_2}(a_1) \\ P_{\tilde{A}_2|A_2=a_1}(a_2) & P_{\tilde{A}_2|A_2=a_2}(a_2) \end{pmatrix}$.
- For all $i \in \{1, 2\}$, let $\underline{u}^{(i)}$ be a 2×2 matrix $\underline{u}^{(i)} \triangleq \underline{u} \begin{pmatrix} P_{\tilde{A}_2|A_2=a_1}(a_i) & 0 \\ 0 & P_{\tilde{A}_2|A_2=a_2}(a_i) \end{pmatrix}$.
- Let the function $\hat{v} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be

$$\hat{v}(P) = \max_{(Q_1, Q_2) \in \text{BR}_1(P)} v(Q_1, Q_2, P). \quad (18)$$

- Let the function $\hat{u} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be

$$\hat{u}(P) = \max_{Q \in \Delta(\mathcal{A}_1)} u(Q, P). \quad (19)$$



Zero-Sum Games with Noisy Observations

Best Response of the Follower

The set of best responses of Player 1 is determined by $BR_1 : \Delta(\mathcal{A}_2) \rightarrow 2^{\Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1)}$,

$$BR_1(P_{A_2}) = \arg \max_{(Q_1, Q_2) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1)} v(Q_1, Q_2, P_{A_2}). \quad (20)$$

Lemma

For all $(Q_1, Q_2) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1)$ and for all $P \in \Delta(\mathcal{A}_2)$,

$$v(Q_1, Q_2, P) = \begin{pmatrix} Q_1(a_1) \\ Q_1(a_2) \end{pmatrix}^T \underline{\mathbf{u}}^{(1)} \begin{pmatrix} P(a_1) \\ P(a_2) \end{pmatrix} + \begin{pmatrix} Q_2(a_1) \\ Q_2(a_2) \end{pmatrix}^T \underline{\mathbf{u}}^{(2)} \begin{pmatrix} P(a_1) \\ P(a_2) \end{pmatrix}. \quad (21)$$

Zero-Sum Games with **Noisy Observations**

Best Response of the Follower

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Corollary

For all $Q \in \Delta(\mathcal{A}_1)$ and for all $P \in \Delta(\mathcal{A}_2)$,

$$v(Q, Q, P) = u(Q, P). \quad (21)$$

Zero-Sum Games with **Noisy Observations**

Best Response of the Follower

The set of best responses of Player 1 is determined by $BR_1 : \Delta(\mathcal{A}_2) \rightarrow 2^{\Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1)}$,

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Corollary

For all $P \in \Delta(\mathcal{A}_2)$,

$$BR_1(P) = BR_{1,1}(P) \times BR_{1,2}(P), \quad (21)$$

where for all $i \in \{1, 2\}$, the correspondence $BR_{1,i} : \Delta(\mathcal{A}_2) \rightarrow 2^{\Delta(\mathcal{A}_1)}$ is such that

$$BR_{1,i}(P) = \arg \max_{Q \in \Delta(\mathcal{A}_1)} \begin{pmatrix} Q(a_1) \\ Q(a_2) \end{pmatrix}^T \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P(a_1) \\ P(a_2) \end{pmatrix}. \quad (22)$$

Zero-Sum Games with Noisy Observations

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$$BR_1(P_{A_2}) = BR_{1,1}(P) \times BR_{1,2}(P). \quad (20)$$

Lemma

For all $P \in \Delta(\mathcal{A}_2)$ and for all $i \in \{1, 2\}$,

$$BR_{1,i}(P) = \begin{cases} \{Q \in \Delta(\mathcal{A}_1) : Q(a_1) = 1\}, & \text{if } s_i > 0, \\ \{Q \in \Delta(\mathcal{A}_1) : Q(a_1) = 0\}, & \text{if } s_i < 0, \\ \Delta(\mathcal{A}_1), & \text{if } s_i = 0, \end{cases} \quad (21)$$

where $s_i \in \mathbb{R}$ is given by

$$s_i \triangleq (u_{1,1} - u_{2,1}) P(a_1) P_{\tilde{A}_2|A_2=a_1}(a_i) + (u_{1,2} - u_{2,2}) P(a_2) P_{\tilde{A}_2|A_2=a_2}(a_i). \quad (22)$$



Zero-Sum Games with **Noisy Observations**

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Lemma

For all $P \in \Delta(\mathcal{A}_2)$ and for all $i \in \{1, 2\}$,

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where $s_i \in \mathbb{R}$ is given by

$$s_i \triangleq (u_{1,1} - u_{2,1}) P(a_1) P_{\tilde{A}_2|A_2=a_1}(a_i) + (u_{1,2} - u_{2,2}) P(a_2) P_{\tilde{A}_2|A_2=a_2}(a_i) \quad (22)$$

Zero-Sum Games with **Noisy Observations**

Constituent Games

- Consider the ZSGs in normal form $\mathcal{G}(\underline{\mathbf{u}}^{(1)})$ and $\mathcal{G}(\underline{\mathbf{u}}^{(2)})$ (a.k.a **constituent games**).
- For all $i \in \{1, 2\}$, let $P^{(i)} \in \mathbb{R}$ satisfy

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix}. \quad (23)$$

Zero-Sum Games with Noisy Observations

Constituent Games

- For all $i \in \{1, 2\}$, let $P^{(i)} \in \mathbb{R}$ satisfy

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix}. \quad (23)$$

Lemma

If $P_{A_1}^*(a_1) \in (0, 1)$ and $P_{A_2}^*(a_1) \in (0, 1)$ form the unique NE of the game $\mathcal{G}(\underline{\mathbf{u}})$, then

- (a) For all $i \in \{1, 2\}$,

$$P^{(i)} = \frac{P_{A_2}^*(a_1) P_{\tilde{A}_2|A_2=a_2}(a_i)}{P_{A_2}^*(a_2) P_{\tilde{A}_2|A_2=a_1}(a_i) + P_{A_2}^*(a_1) P_{\tilde{A}_2|A_2=a_2}(a_i)} \in [0, 1]; \text{ and} \quad (24)$$

- (b) $P^{(i)} \in \{0, 1\}$ if and only if $|\det \underline{\mathbf{w}}| = 1$

Zero-Sum Games with **Noisy Observations**

Constituent Games

- For all $i \in \{1, 2\}$, let $P^{(i)} \in \mathbb{R}$ satisfy

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix}. \quad (23)$$

Lemma

If $P_{A_1}^*(a_1) \in (0, 1)$ and $P_{A_2}^*(a_1) \in (0, 1)$ form the unique NE of the game $\mathcal{G}(\underline{\mathbf{u}})$, then

$$0 \leq \min \{P^{(1)}, P^{(2)}\} \leq P_{A_2}^*(a_1) \leq \max \{P^{(1)}, P^{(2)}\} \leq 1. \quad (24)$$

The equality $P^{(1)} = P_{A_2}^*(a_1) = P^{(2)}$ holds if and only if $\det \underline{\mathbf{w}} = 0$.



Zero-Sum Games with **Noisy Observations**

Constituent Games

- For all $i \in \{1, 2\}$, let $P^{(i)} \in \mathbb{R}$ satisfy

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix}. \quad (23)$$

Lemma

If $P_{A_1}^*(a_1) \in (0, 1)$ and $P_{A_2}^*(a_1) \in (0, 1)$ form the unique NE of the game $\mathcal{G}(\underline{\mathbf{u}})$, then

$$\min \{P^{(1)}, P^{(2)}\} = \begin{cases} P^{(1)} & \text{if } \det \underline{\mathbf{w}} > 0 \\ P^{(2)} & \text{if } \det \underline{\mathbf{w}} < 0 \\ P^{(1)} = P^{(2)} = P_{A_2}^*(a_1) & \text{if } \det \underline{\mathbf{w}} = 0, \end{cases} \quad (24)$$



Zero-Sum Games with Noisy Observations

Constituent Games

- For all $i \in \{1, 2\}$, let $P^{(i)} \in \mathbb{R}$ satisfy

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}^\top \underline{\mathbf{u}}^{(i)} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix}. \quad (23)$$

Lemma

Assume that $P_{A_1}^*(a_1) \in (0, 1)$ and $P_{A_2}^*(a_1) \in (0, 1)$ form the unique NE of the game $\mathcal{G}(\underline{\mathbf{u}})$. If $u_{1,1} - u_{1,2} - u_{2,1} + u_{2,2} > 0$, then it holds that for all $i \in \{1, 2\}$ and for all $P \in \Delta(\mathcal{A}_2)$,

$$\text{BR}_{1i}(P) = \begin{cases} \{Q \in \Delta(\mathcal{A}_1) : Q(a_1) = 1\}, & \text{if } P(a_1) > P^{(i)}, \\ \{Q \in \Delta(\mathcal{A}_1) : Q(a_1) = 0\}, & \text{if } P(a_1) < P^{(i)}, \\ \{Q \in \Delta(\mathcal{A}_1) : Q(a_1) = \beta, \beta \in [0, 1]\}, & \text{if } P(a_1) = P^{(i)}. \end{cases} \quad (24)$$

If $u_{1,1} - u_{1,2} - u_{2,1} + u_{2,2} \leq 0$, then it holds that for all $i \in \{1, 2\}$ and for all $P \in \Delta(\mathcal{A}_2)$,

$$\text{BR}_{1i}(P) = \begin{cases} \{Q \in \Delta(\mathcal{A}_1) : Q(a_1) = 1\}, & \text{if } P(a_1) < P^{(i)}, \\ \{Q \in \Delta(\mathcal{A}_1) : Q(a_1) = 0\}, & \text{if } P(a_1) > P^{(i)}, \\ \{Q \in \Delta(\mathcal{A}_1) : Q(a_1) = \beta, \beta \in [0, 1]\}, & \text{if } P(a_1) = P^{(i)}. \end{cases} \quad (25)$$

Zero-Sum Games with **Noisy Observations**

Best Commitments

- Let the function $\hat{v} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be

$$\hat{v}(P) = \max_{(Q_1, Q_2) \in \text{BR}_1(P)} v(Q_1, Q_2, P). \quad (26)$$

- Let the function $\hat{u} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be

$$\hat{u}(P) = \max_{Q \in \Delta(\mathcal{A}_1)} u(Q, P). \quad (27)$$

Zero-Sum Games with Noisy Observations

Best Commitments

- Let the function $\hat{v} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be

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- Let the function $\hat{u} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be

$$\hat{u}(P) = \max_{Q \in \Delta(\mathcal{A}_1)} u(Q, P). \quad (27)$$

Lemma

Let $P_{A_1}^* \in \Delta(\mathcal{A}_1)$ and $P_{A_2}^* \in \Delta(\mathcal{A}_2)$ form an NE in the game $\mathcal{G}(\underline{u})$. For all $P \in \Delta(\mathcal{A}_2)$,

$$u(P_{A_1}^*, P_{A_2}^*) \leq \hat{u}(P) \leq \hat{v}(P) \leq \sum_{k \in \{1,2\}} P(a_k) \left(\max_{i \in \{1,2\}} u_{i,k} \right). \quad (28)$$

Zero-Sum Games with Noisy Observations

Best Commitments

- Let the function $\hat{v} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be

$$\hat{v}(P) = \max_{(Q_1, Q_2) \in \text{BR}_1(P)} v(Q_1, Q_2, P). \quad (26)$$

Lemma

Assume that $P_{A_1}^*(a_1) \in (0, 1)$ and $P_{A_2}^*(a_1) \in (0, 1)$ form the unique NE of the game $\mathcal{G}(\underline{u})$ and $u_{1,1} - u_{1,2} - u_{2,1} + u_{2,2} > 0$.

- For all $P \in \Delta(\mathcal{A}_2)$ such that $P(a_1) \geq \max\{P^{(1)}, P^{(2)}\}$, $\hat{v}(P) = u_{1,1}P(a_1) + u_{1,2}P(a_2)$.
- If $\det \underline{u} > 0$, then for all $P \in \Delta(\mathcal{A}_2)$ such that $P^{(1)} < P(a_1) < P^{(2)}$,

$$\hat{v}(P) = \left(u_{1,1}P_{\tilde{A}_2|A_2=a_1}(a_1) + u_{2,1}P_{\tilde{A}_2|A_2=a_1}(a_2) \right) P(a_1) + \left(u_{1,2}P_{\tilde{A}_2|A_2=a_2}(a_1) + u_{2,2}P_{\tilde{A}_2|A_2=a_2}(a_2) \right) P(a_2).$$

- If $\det \underline{u} \leq 0$, then for all $P \in \Delta(\mathcal{A}_2)$ such that $P^{(2)} < P(a_1) < P^{(1)}$,

$$\hat{v}(P) = \left(u_{1,1}P_{\tilde{A}_2|A_2=a_1}(a_2) + u_{2,1}P_{\tilde{A}_2|A_2=a_1}(a_1) \right) P(a_1) + \left(u_{1,2}P_{\tilde{A}_2|A_2=a_2}(a_2) + u_{2,2}P_{\tilde{A}_2|A_2=a_2}(a_1) \right) P(a_2).$$

- For all $P \in \Delta(\mathcal{A}_2)$ such that $P(a_1) \leq \min\{P^{(1)}, P^{(2)}\}$, $\hat{v}(P) = u_{2,1}P(a_1) + u_{2,2}P(a_2)$.

Zero-Sum Games with **Noisy Observations**

Best Commitments

- Let the function $\hat{v} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be

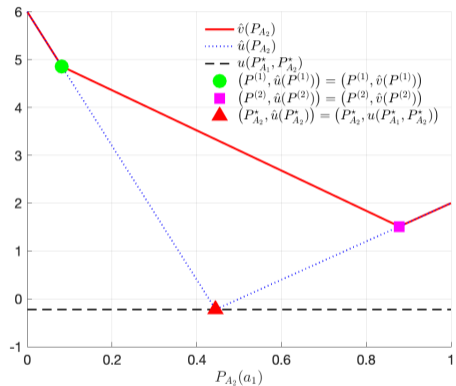
$$\hat{v}(P) = \max_{(Q_1, Q_2) \in \text{BR}_1(P)} v(Q_1, Q_2, P). \quad (26)$$

Corollary

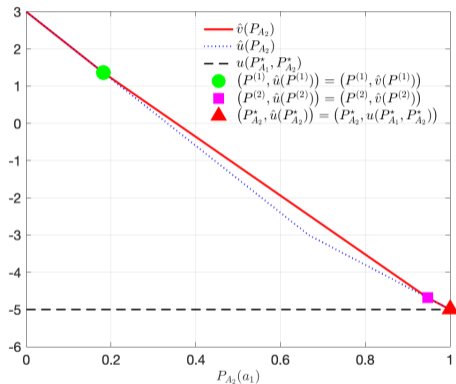
The function $f : [0, 1] \rightarrow \mathbb{R}$ such that $f(x) = \hat{v}(P)$, with $P(a_1) = x$, is piece-wise linear.

Zero-Sum Games with Noisy Observations

Best Commitments



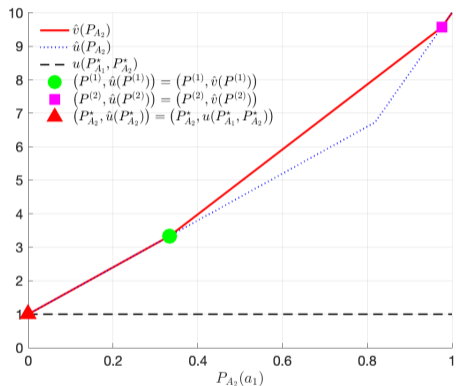
(a) Payoff matrix $\underline{u} = (-8, 6; 2, -2)$ and channel matrix $\underline{w} = (0.9, 0.1; 0.1, 0.9)$.



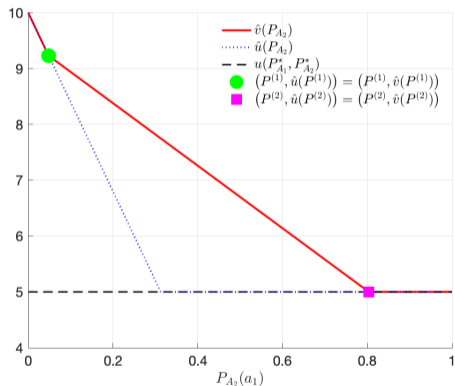
(b) Payoff matrix $\underline{u} = (-5, 1; -6, 3)$ and channel matrix $\underline{w} = (0.9, 0.1; 0.1, 0.9)$.

Zero-Sum Games with Noisy Observations

Best Commitments



(a) Payoff matrix $\underline{u} = (2, 9; -9, 5)$ and channel matrix $\underline{w} = (0.9, 0.1; 0.1, 0.9)$.



(b) Payoff matrix $\underline{u} = (5, 5; -6, 10)$ and channel matrix $\underline{w} = (0.9, 0.1; 0.1, 0.9)$.

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Zero-Sum Games with **Noisy Observations**

Equilibrium with Noisy Observations

Definition (Equilibrium)

The tuple $(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger, P_{A_2}^\dagger) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ forms an equilibrium if

$$P_{A_2}^\dagger \in \arg \min_{P \in \Delta(\mathcal{A}_2)} \left(\max_{(Q_1, Q_2) \in \Delta(\mathcal{A}_1)^2} v(Q_1, Q_2, P) \right) \text{ and} \quad (27)$$

$$(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger) \in \max_{(Q_1, Q_2) \in \Delta(\mathcal{A}_1)^2} v(Q_1, Q_2, P). \quad (28)$$

Zero-Sum Games with Noisy Observations

Equilibrium with Noisy Observations

Definition (Equilibrium)

The tuple $(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger, P_{A_2}^\dagger) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ forms an equilibrium if

$$P_{A_2}^\dagger \in \arg \min_{P \in \Delta(\mathcal{A}_2)} \left(\max_{(Q_1, Q_2) \in \Delta(\mathcal{A}_1)^2} v(Q_1, Q_2, P) \right) \text{ and} \quad (27)$$

$$\left(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger \right) \in \max_{(Q_1, Q_2) \in \Delta(\mathcal{A}_1)^2} v(Q_1, Q_2, P). \quad (28)$$

Theorem (Existence)

The game $\mathcal{G}(\underline{u}, \underline{w})$ always possesses an equilibrium.



Zero-Sum Games with Noisy Observations

Equilibrium with Noisy Observations

Theorem (Equilibrium Payoff)

Let the tuple $(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger, P_{A_2}^\dagger) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ be an equilibrium of the game $\mathcal{G}(\underline{u}, \underline{w})$. Let $P_{A_1}^*(a_1)$ and $P_{A_2}^*(a_1)$ be an NE of the game $\mathcal{G}(\underline{u})$.

- If $P_{A_1}^*(a_1) \in (0, 1)$, $P_{A_2}^*(a_1) \in (0, 1)$, and $(P_{A_1}^*, P_{A_2}^*)$ forms the unique NE, then

$$\hat{v}(P_{A_2}^\dagger) = \min\{\hat{v}(P_1), \hat{v}(P_2)\}, \quad (27)$$

where, for all $i \in \{1, 2\}$, $P_i(a_1) = P^{(i)}$.

- Otherwise,

$$\hat{v}(P_{A_2}^\dagger) = \min\{\max\{u_{1,1}, u_{2,1}\}, \max\{u_{1,2}, u_{2,2}\}\}. \quad (28)$$



Zero-Sum Games with Noisy Observations

Equilibrium with Noisy Observations

Lemma

Let $\mathcal{S} \subseteq \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ be the set of equilibria of the game $\mathcal{G}(\underline{u}, \underline{w})$ and let $P_{A_1}^* \in \Delta(\mathcal{A}_1)$ and $P_{A_2}^* \in \Delta(\mathcal{A}_2)$ be an NE of the game $\mathcal{G}(\underline{u})$. If $P_{A_1}^*(a_1) \in (0, 1)$, $P_{A_2}^*(a_1) \in (0, 1)$, and $(P_{A_1}^*, P_{A_2}^*)$ forms the unique NE, then, there exists a tuple $(Q_1, Q_2, P) \in \mathcal{S}$ such that $P(a_1) \in \{P^{(1)}, P^{(2)}\}$. Furthermore, if $P(a_1) = P^{(i)}$, with $i \in \{1, 2\}$, then,

$$P_{A_2|\tilde{A}_2=a_i}(a_1) = P_{A_2}^*(a_1). \quad (27)$$

Zero-Sum Games with Noisy Observations

Relevance of Noisy Observations

Lemma

Let $(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger, P_{A_2}^\dagger) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ be an equilibrium of the game $\mathcal{G}(\underline{u}, \underline{w})$. Let also the tuple $(P_{A_1}^*, P_{A_2}^*) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ be an NE of the game $\mathcal{G}(\underline{u})$.

Then,

$$v(P_{A_1|\tilde{A}_2}^\dagger, P_{A_2}^\dagger) = u(P_{A_1}^*, P_{A_2}^*), \quad (28)$$

if and only if,

- (a) $(u_{1,1} - u_{1,2})(u_{2,2} - u_{2,1}) \leq 0$ or $(u_{1,1} - u_{2,1})(u_{2,2} - u_{1,2}) \leq 0$; or
- (b) $(u_{1,1} - u_{1,2})(u_{2,2} - u_{2,1}) > 0$ and $(u_{1,1} - u_{2,1})(u_{2,2} - u_{1,2}) > 0$ and $\det \underline{w} = 0$.



Zero-Sum Games with **Noisy Observations**

Relevance of Noisy Observations

Lemma

Let $(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger, P_{A_2}^\dagger) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ form an equilibrium of the game $\mathcal{G}(\underline{u}, \underline{w})$. If $|\det \underline{w}| = 1$, then

$$\hat{v}(P_{A_2}^\dagger) = \min\{\max\{u_{1,1}, u_{2,1}\}, \max\{u_{1,2}, u_{2,2}\}\}. \quad (28)$$

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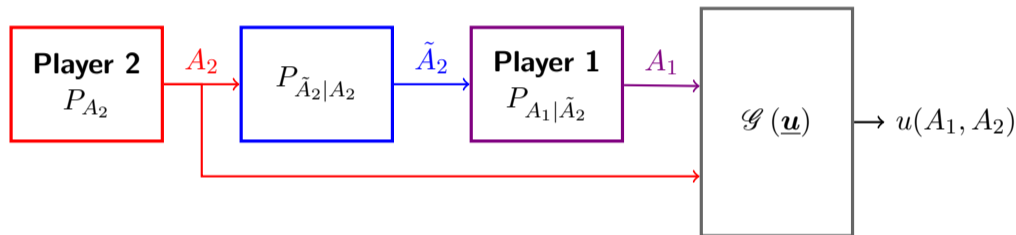
- 1 Empirical Risk and Zero-Sum Games
- 2 Zero-Sum Games with **Noisy Observations**
 - Noisy Observations of the **Actions**
 - Noisy Observations of the **Commitment** and **Actions**
- 3 Connections with Existing Results
 - Aumann's **Games with Incomplete Information**
 - Equilibrium Refinements and **Relative Entropy Regularizations**
- 4 Final Remarks

The logo for Inria, featuring the word "Inria" in a red, cursive script font.

Zero-Sum Games with **Noisy Observations**

Commitment **Mismatch** and **Noisy Observation** of the Actions

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



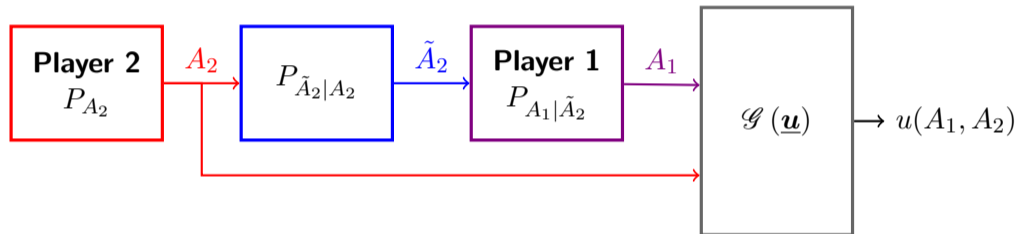
- **Assumptions:**

- Player 2 **publicly and irrevocably** commits to use a strategy and chooses an action;

Zero-Sum Games with **Noisy Observations**

Commitment **Mismatch** and **Noisy Observation** of the Actions

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



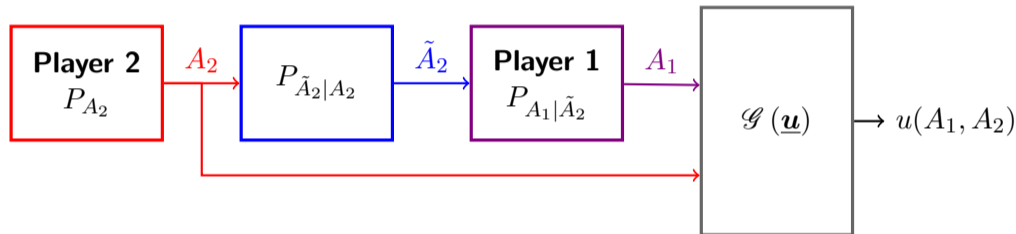
- **Assumptions:**

- Player 2 **publicly and irrevocably** commits to use a strategy and chooses an action;
- Player 1 observes the commitment subject to a **distorsion**;

Zero-Sum Games with **Noisy Observations**

Commitment **Mismatch** and **Noisy Observation** of the Actions

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



- **Assumptions:**

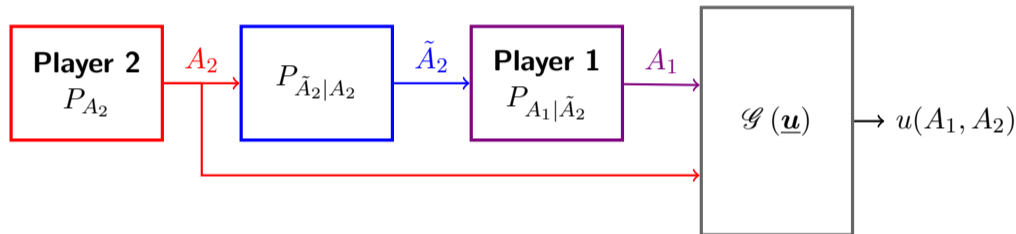
- Player 2 **publicly and irrevocably** commits to use a strategy and chooses an action;
- Player 1 observes the commitment subject to a **distorsion**;
- Player 1 observes the action through a **binary channel** ; and

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Zero-Sum Games with **Noisy Observations**

Commitment **Mismatch** and **Noisy Observation** of the Actions

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



• Assumptions:

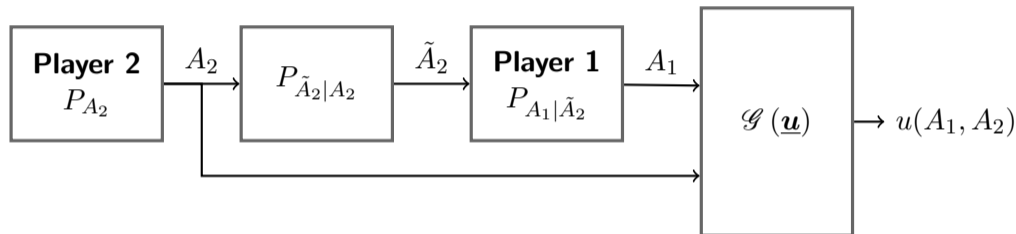
- Player 2 **publicly and irrevocably** commits to use a strategy and chooses an action;
- Player 1 observes the commitment subject to a **distorsion**;
- Player 1 observes the action through a **binary channel** ; and
- Player 1 chooses its strategy.

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Zero-Sum Games with Noisy Observations

Game Formulation

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



• Distorsion of the Commitment

- Let \underline{t} be a given 2×2 nonsingular stochastic matrix.
- Let $P_{A_2} \in \Delta(\mathcal{A}_2)$ be the commitment announced by Player 2.
- The commitment **observed** by Player 1 is

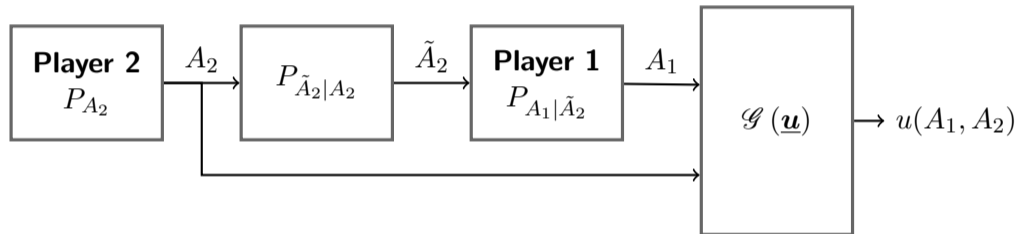
$$\begin{pmatrix} \tilde{P}_{A_2}(a_1) \\ \tilde{P}_{A_2}(a_2) \end{pmatrix} = \underline{t} \begin{pmatrix} P_{A_2}(a_1) \\ P_{A_2}(a_2) \end{pmatrix}.$$

Inria (29)

Zero-Sum Games with Noisy Observations

Game Formulation

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.

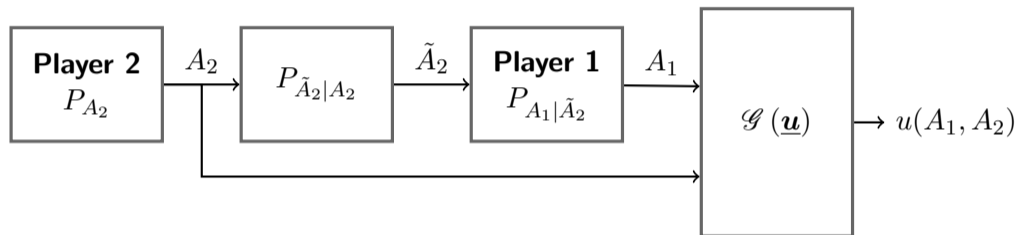


- The follower assumes that \tilde{P}_{A_2} is the actual commitment of leader; and
- The leader is aware of assumption of the follower.

Zero-Sum Games with Noisy Observations

Game Formulation

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



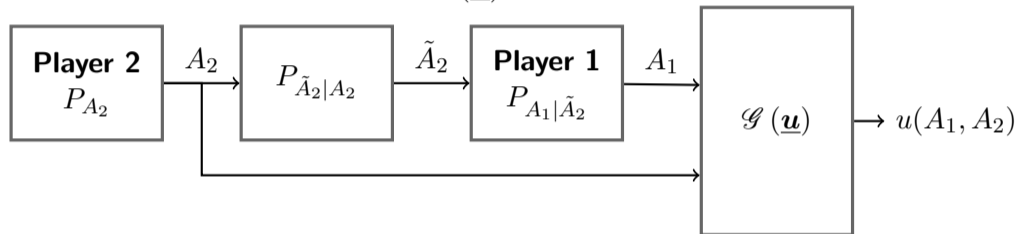
Let the correspondence $\tilde{v} : \Delta(\mathcal{A}_2) \rightarrow \mathbb{R}$ be such that

$$\tilde{v}(P_{A_2}) = \max_{(Q_1, Q_2) \in \text{BR}_1(\tilde{P}_{A_2})} v(Q_1, Q_2, P_{A_2}). \quad (29)$$

Zero-Sum Games with Noisy Observations

Game Formulation

Consider the 2×2 ZSG in normal form $\mathcal{G}(\underline{u})$.



Definition (Equilibrium)

The tuple $(P_{A_1|\tilde{A}_2=a_1}, P_{A_1|\tilde{A}_2=a_2}, P_{A_2}) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ is an equilibrium of the game $\mathcal{G}(\underline{u}, \underline{w}, \underline{t})$ if

$$P_{A_2} \in \arg \min_{P \in \Delta(\mathcal{A}_2)} \tilde{v}(P) \text{ and} \quad (29)$$

$$(P_{A_1|\tilde{A}_2=a_1}, P_{A_1|\tilde{A}_2=a_2}) \in \text{BR}_1(\tilde{P}_{A_2}). \quad (30)$$

Zero-Sum Games with Noisy Observations

A Fundamental Observation

Observation:

- **Assume** that $(u_{1,1} - u_{1,2})(u_{2,2} - u_{2,1}) > 0$ and $(u_{1,1} - u_{2,1})(u_{2,2} - u_{1,2}) > 0$
- **If** Player 2 commits to $P_{A_2} \in \Delta(\mathcal{A}_2)$ such that $P_{A_2}(a_1) = \tilde{P}^{(i)}$, with

$$\begin{pmatrix} \tilde{P}^{(i)} \\ 1 - \tilde{P}^{(i)} \end{pmatrix} = \underline{t}^{-1} \begin{pmatrix} P^{(i)} \\ 1 - P^{(i)} \end{pmatrix}, \quad (31)$$

for some $i \in \{1, 2\}$.

- **Then**, Player 1 observes the commitment $\tilde{P}_{A_2} \in \Delta(\mathcal{A}_2)$ such that $\tilde{P}_{A_2}(a_1) = P^{(i)}$
- **And**
 - $\text{BR}_{1,i}(\tilde{P}_{A_2}) = \Delta(\mathcal{A}_1)$
 - Given $(Q_1, Q_2) \in \text{BR}_1(\tilde{P}_{A_2})$ and $(P_1, P_2) \in \text{BR}_1(\tilde{P}_{A_2})$,

$$v(Q_1, Q_2, P_{A_2}) \neq v(P_1, P_2, P_{A_2}).$$

Inria (32)

Zero-Sum Games with Noisy Observations

The Best Commitment

Lemma

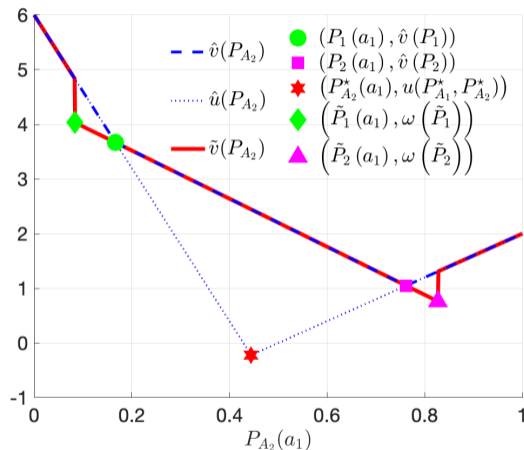
Assume that $(u_{1,1} - u_{1,2})(u_{2,2} - u_{2,1}) > 0$, $(u_{1,1} - u_{2,1})(u_{2,2} - u_{1,2}) > 0$, and $u_{1,1} - u_{1,2} - u_{2,1} + u_{2,2} > 0$. Assume also that $\det \underline{w} > 0$ and $\det \underline{t} > 0$. For all $P \in \Delta(\mathcal{A}_2)$,

- If $P(a_1) > \tilde{P}^{(2)}$, then $\tilde{v}(P) = u_{1,1}P(a_1) + u_{1,2}P(a_2)$.
- If $P(a_1) = \tilde{P}^{(2)}$, then $\tilde{v}(P) = \left\{ (u_{1,1}P(a_1) + u_{1,2}P(a_2))\beta + \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}^T (\underline{u} \circ \underline{w}) \begin{pmatrix} P(a_1) \\ P(a_2) \end{pmatrix} \right) (1 - \beta) : \beta \in [0, 1] \right\}$.
- If $\tilde{P}^{(1)} < P(a_1) < \tilde{P}^{(2)}$, then it follows that $\tilde{v}(P) = \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}^T (\underline{u} \circ \underline{w}) \begin{pmatrix} P(a_1) \\ P(a_2) \end{pmatrix} \right)$.
- If $P(a_1) = \tilde{P}^{(1)}$, then $\tilde{v}(P) = \left\{ (u_{2,1}P(a_1) + u_{2,2}P(a_2))(1 - \beta) + \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}^T (\underline{u} \circ \underline{w}) \begin{pmatrix} P(a_1) \\ P(a_2) \end{pmatrix} \right) \beta : \beta \in [0, 1] \right\}$.
- If $P(a_1) < \tilde{P}^{(1)}$, then it follows that $\tilde{v}(P) = u_{2,1}P(a_1) + u_{2,2}P(a_2)$.



Zero-Sum Games with Noisy Observations

The Best Commitment



$\underline{u} = (-8, 6; 2, -2)$, $\underline{w} = (0.8, 0.2; 0.2, 0.8)$ and $\underline{t} = (0.9, 0.1; 0.1, 0.9)$.

Zero-Sum Games with Noisy Observations

Advantage for the Leader

Lemma

Consider the following assumptions:

- (a) $(u_{1,1} - u_{1,2})(u_{2,2} - u_{2,1}) > 0$, and $(u_{1,1} - u_{2,1})(u_{2,2} - u_{1,2}) > 0$;
- (b) For all $i \in \{1, 2\}$, the probability measures $Q_i \in \Delta(\mathcal{A}_2)$ such that $Q_i(a_1) = P^{(i)}$, satisfy $\hat{u}(Q_1) \neq \hat{u}(Q_2)$; and
- (c) The tuple $(P_{A_1|\tilde{A}_2=a_1}^\dagger, P_{A_1|\tilde{A}_2=a_2}^\dagger, P_{A_2}^\dagger) \in \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_1) \times \Delta(\mathcal{A}_2)$ is an equilibrium of the game $\mathcal{G}(\underline{u}, \underline{w})$.

If $\det \underline{t} \notin \{0, 1\}$, then, there exists a strategy $P \in \Delta(\mathcal{A}_2)$ such that

$$\tilde{v}(P) < \hat{v}(P_{A_2}^\dagger). \quad (33)$$



Zero-Sum Games with Noisy Observations

Existence of Equilibria

The game $\mathcal{G}(\underline{u}, \underline{w}, \underline{t})$, with $\underline{u} = (-8, 6; 2, -2)$, $\underline{w} = (0.8, 0.2; 0.2, 0.8)$ and $\underline{t} = (0.9, 0.1; 0.1, 0.9)$ does not possess an equilibrium.

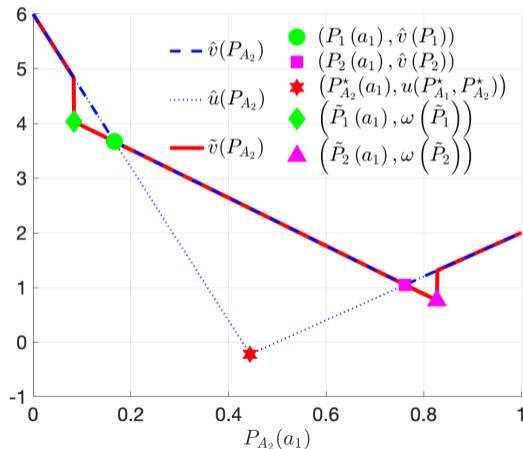


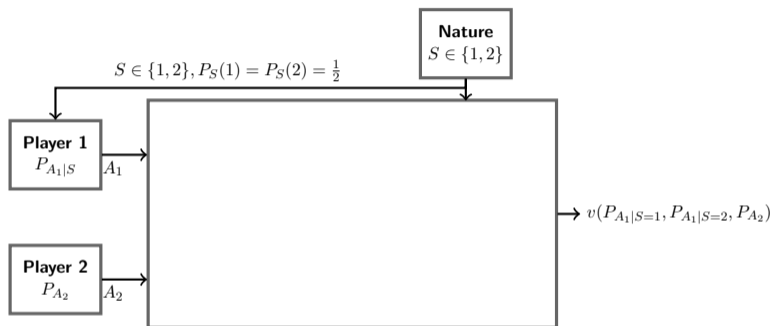
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Connections with Existing Results

Aumann's Games with Incomplete Information

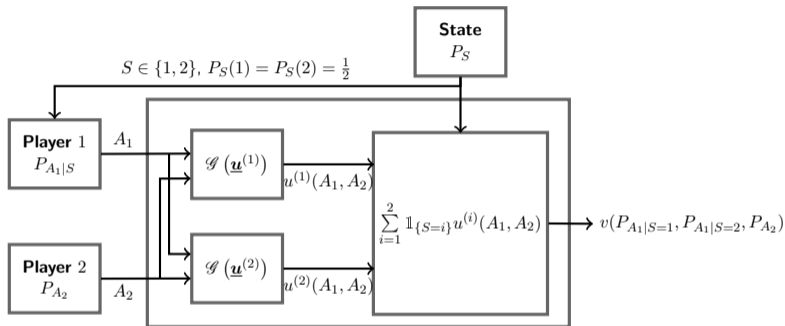


Consider a ZSG with **incomplete information**:

- Both players know the probability distribution P_S ;
- Player 1 **observes** the realization of the state S ; and
- Player 2 **ignores** the realization of the state S .

Connections with Existing Results

Aumann's Games with Incomplete Information



Expected Payoff:

$$\begin{aligned} & v(P_{A_1|S=1}, P_{A_1|S=2}, P_{A_2}) \\ &= \frac{1}{2} \begin{pmatrix} P_{A_1|S=1}(a_1) \\ P_{A_1|S=1}(a_2) \end{pmatrix}^\top \underline{u}^{(1)} \begin{pmatrix} P_{A_2}(a_1) \\ P_{A_2}(a_2) \end{pmatrix} + \frac{1}{2} \begin{pmatrix} P_{A_1|S=2}(a_1) \\ P_{A_1|S=2}(a_2) \end{pmatrix}^\top \underline{u}^{(2)} \begin{pmatrix} P_{A_2}(a_1) \\ P_{A_2}(a_2) \end{pmatrix} \end{aligned}$$

Connections with Existing Results

Aumann's **Games with Incomplete Information**

A ZSG with noisy observation of the actions and **perfect observation** of the commitment can be modelled by an **Aumann's game with incomplete information**.



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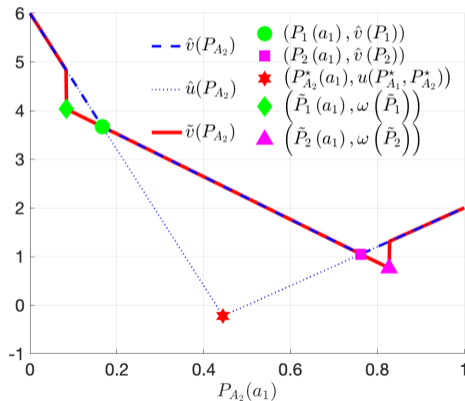
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Equilibrium Refinements

Strong Equilibria

The game $\mathcal{G}(\underline{u}, \underline{w}, \underline{t})$, with $\underline{u} = (-8, 6; 2, -2)$, $\underline{w} = (0.8, 0.2; 0.2, 0.8)$ and $\underline{t} = (0.9, 0.1; 0.1, 0.9)$ **does not possess an equilibrium.**

- An equilibrium exists if Player 1 plays the action that benefits the leader when it is **indifferent to play any of its actions.**
- Player 1 aims to **maximize the expected payoff.**
- How to make Player 1 play the action that **minimizes the expected payoff** ?

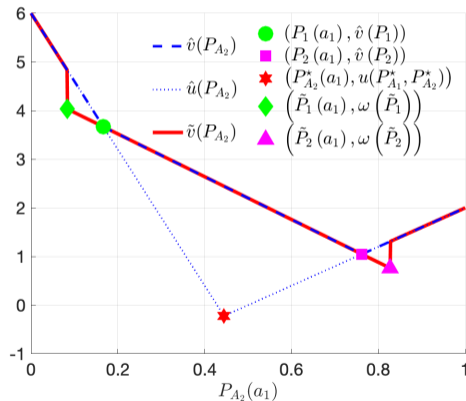


Equilibrium Refinements

ϵ -Equilibria

The game $\mathcal{G}(\underline{u}, \underline{w}, \underline{t})$, with $\underline{u} = (-8, 6; 2, -2)$, $\underline{w} = (0.8, 0.2; 0.2, 0.8)$ and $\underline{t} = (0.9, 0.1; 0.1, 0.9)$ **does not possess an equilibrium.**

- An equilibrium exists if Player 2 adopts a commitment that is δ -suboptimal.

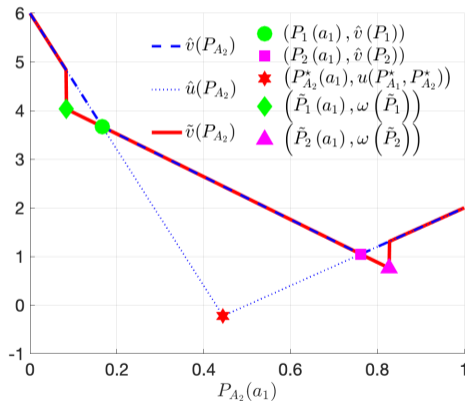


Equilibrium Refinements

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- An equilibrium exists if Player 2 adopts a commitment that is δ -suboptimal.
- A **suboptimal commitment** forces a **unique and predictable** best response from Player 1.



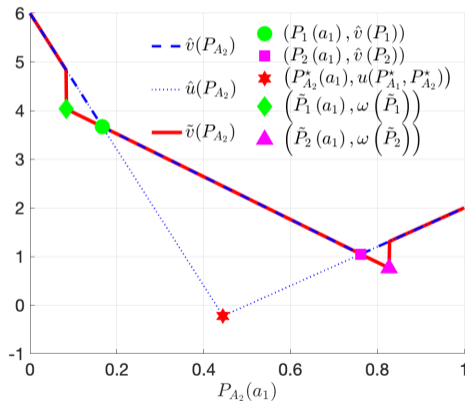
Equilibrium Refinements

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The game $\mathcal{G}(\underline{u}, \underline{w}, \underline{t})$, with $\underline{u} = (-8, 6; 2, -2)$, $\underline{w} = (0.8, 0.2; 0.2, 0.8)$ and $\underline{t} = (0.9, 0.1; 0.1, 0.9)$ **does not possess an equilibrium.**

- An equilibrium exists if Player 2 adopts a commitment that is δ -suboptimal.
- A **suboptimal commitment** forces a **unique and predictable** best response from Player 1.
- **Suboptimal commitment:** Given $\epsilon > 0$, $P_{A_2} \in \Delta(\mathcal{A}_2)$:

$$P_{A_2}(a_1) = \tilde{P}^{(2)} - \epsilon. \quad (34)$$



Equilibrium Refinements

ϵ -Equilibria

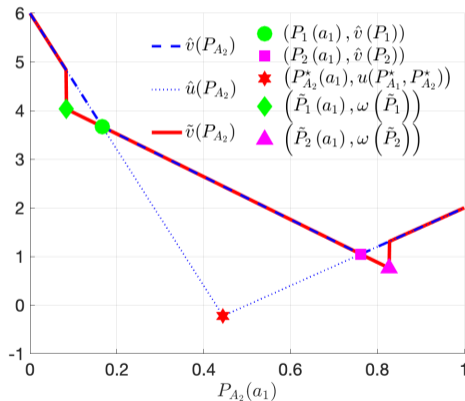
The game $\mathcal{G}(\underline{u}, \underline{w}, \underline{t})$, with $\underline{u} = (-8, 6; 2, -2)$, $\underline{w} = (0.8, 0.2; 0.2, 0.8)$ and $\underline{t} = (0.9, 0.1; 0.1, 0.9)$ **does not possess an equilibrium.**

- How to determine a suboptimal commitment P ?

$$\min_{P \in \Delta(\mathcal{A}_2)} \tilde{v}(P) + \lambda D(P \| Q), \quad (34)$$

with $Q \in \Delta(\mathcal{A}_2)$, such that $Q(a_1) = \tilde{P}^{(2)}$.

- Type-I Empirical Risk Minimization with **Relative Entropy Regularization**



Equilibrium Refinements

ϵ -Equilibria

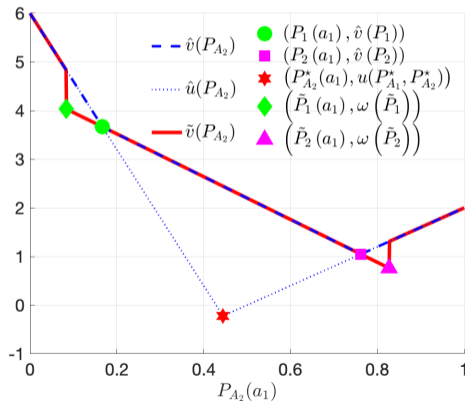
The game $\mathcal{G}(\underline{u}, \underline{w}, \underline{t})$, with $\underline{u} = (-8, 6; 2, -2)$, $\underline{w} = (0.8, 0.2; 0.2, 0.8)$ and $\underline{t} = (0.9, 0.1; 0.1, 0.9)$ **does not possess an equilibrium.**

- How to determine **another** suboptimal commitment P ?

$$\min_{P \in \Delta(\mathcal{A}_2)} \tilde{v}(P) + \lambda D(Q \| P), \quad (34)$$

with $Q \in \Delta(\mathcal{A}_2)$, such that $Q(a_1) = \tilde{P}^{(2)}$.

- Type-II Empirical Risk Minimization with **Relative Entropy Regularization**



Final Remarks

- Often **Robust** ERM is **neither a Nash nor a Stackelberg equilibria** of a ZSG.
 - **Why?** Because of observation of datasets and priors on the datasets.
- A new game formulation is proposed to incorporate:
 - **noisy observations** of the actions; and
 - **Distorted** Commitments
- Priors are associated to commitment mismatches in ZSG with Noise Observations
- Channel Model: **Binary Channels**. More elaborate Channel models:
 - **Erasures** on data points: Erasure Channel
 - **Additive Noise** due to data acquisition: AWGN Channel

Thank you for your attention.



Ke Sun, Samir M. Perlaza, and Alain Jean-Marie. “**Zero-Sum Games with Noisy Observations**”. Preprint arXiv:2211.01703 [cs.GT].

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