### leam NeuroMathComp



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# A Retinotopic neural fields model of perceptual switching in 2D motion integration

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#### Abstract

The underlying cortical dynamics that select one percept out of multiple competing possibilities are not fully understood. Switching behaviour for a classical psychophysics stimulus, the multistable barberpole, was successfully captured in a feature-only, one-layer model of MT with adaptation and noise. However, without a representation of space, only some very specific stimulus could be considered. Here we propose a model that takes into account the spatial domain in a two-layer configuration modelling V1 and MT cortical areas whilst incorporating both adaptation and noise.

Keywords: Motion Perception, Multistability, Neural fields, Dynamical systems, Competition, Bifurcation

#### A NEURAL FIELD COMPETITION MODEL TO STUDY MULTI STABILITY

#### EXTENSION: TWO CORTICAL RETINOTOPIC AREAS



J. Rankin, A. I. Meso, et al., **Bifurcations study of a Neural fields Competition Model with an application to perceptual switching in Motion Integration**, Journal of Computational Neuroscience, 2013

#### ► Main features

One cortical area, feature only

• Continuous representation of MT activity across direction space (p(t, v))





#### CONTEXT AND MOTIVATION

#### Psychophysical observations on motion perception

• Motion perception results from a non-local integration process.



2D



 Motion integration is a dynamical process (Masson, Rybarczyk, et al., Visual Neuroscience 2000).

## An adaptation on the slow-time scale (α(t, v)) Noise included in the model for comparison with psychophysics (X(t, v), see paper)

### ► A slow-fast system

 $\begin{aligned} \frac{\partial p}{dt}(t,v) &= -p(t,v) + S(\lambda[J(v) * p(t,v) - \alpha(t,v) + X(t,v) + k_I I(v)]), \\ \tau \frac{\partial \alpha}{dt}(t,v) &= -\alpha(t,v) + p(t,v) \end{aligned}$ 



#### Description of the input



#### ► Summary of results from Rankin, Meso et al. 2013



#### $(\alpha(t,x,v))$

#### Mathematical description of the model

 $\begin{aligned} \frac{\partial p_1}{\partial t}(t,x,v) &= -p_1(t,x,v) + S\left(J_1 * p_1(t,x,v) + p_0(t,x,v)(1+\lambda_m p_2(t,x,v))\right) \\ \frac{\partial p_2}{\partial t}(t,x,v) &= -p_2(t,x,v) + S\left(G \overset{x}{*} p_1(t,x,v) + J_2 * p_2(t,x,v) - \alpha(x,t,v)\right) \\ \frac{\partial \alpha}{\partial t}(t,x,v) &= \varepsilon\left(-\alpha(t,x,v) + p_2(t,x,v)\right) \end{aligned}$ 

#### Description of the input



#### Numerical implementation

• After discretization, the dimensionality of  $p_i(t, x, v)$  and  $\alpha(t, x, v)$  at any





• These dynamical process can have multiple solutions resulting in perceptual switching: Perceptual multistability is a phenomenon in which alternate interpretations of a fixed stimulus are perceived intermittently.



► About underlying neural mechanisms and cortical area MT

- Several cortical areas are involved in motion estimation
- MT is highly specialized for visual motion (Born and Bradley, 2005)
- MT has a rich set of interconnections with other regions, including feedbacks to V1 (Angelucci and Bulier, 2003)
- Cortical responses of MT have been linked specifically to the perception of motion (Britten, 2003)

#### ► Modeling neural mechanisms of motion perception

- Building on the first linear/non-linear models (Chey et al. 1997; Simoncelli and Heeger 1998), several approaches added extensions to modulate the motion integration stages: feedback between hierarchi- cal layers (Grossberg et al. 2001; Bayerl and Neumann 2004), inclusion of input form cues (Berzhanskaya et al. 2007; Bayerl and Neumann 2007), luminance diffusion gating (Tlapale et al. 2010), or depth cues (Beck and Neumann 2010)
- Although these models reproduce the predominant percepts in a wide range of stimuli, in none of the articles describing them are multistable results depicted.

- We investigated multi stability w.r.t contrast alongside concurrent pyschophysics experiments
- Modeling results showed a shifting balance between adaptation and noise drives switching in different contrast regimes
- We provided predictions to test this hypothesis in psychophysics

#### Symmetric/Asymmetric aperture

#### • Examples of simulations (without noise)



- time time  $t_i$  is  $256 \times 256 \times 64$
- The simulations are performed with help of GPUs using CUDA.





- -A regime predicted in the simulations is not feasible for experimental study
- How to select the aperture ratio to reflect the shape of the aperture?

CONCLUSION

#### ► About this work

- We work within the neural fields formalism: Neural fields are spatially structured neural networks which represent the spatial organization of cerebral cortex; the neural field approximation represents the mean firing rate of a neural population at the continuum limit (Bressloff, 2012)
- Neural fields equations have been successfully applied to the study of motion in, e.g., Giese (1998), Deco and Roland (2010) and Tlapale et al. (2010a)
  We aim to develop tractable models of manageable complexity that allows for a detailed study of the temporal dynamics of multistable motion perception using powerful tools from dynamical systems theory



- Our feature only model has been previously used to study multistable switching for a symmetric aperture
- It can also capture asymmetry but it is ignoring the detail of the spatial interaction
- We proposed a retinotopic model that includes recurrent multi layer interactions that solve motion integration and captures multi stable behavior

• The retinotopic model allows us to investigate other stimuli

Videos are available

 We need bifurcation analysis to investigate selectivity properties of different kernels (e.g., subtractive inhibition, DOG)

