To Satisfy Impatient Web Surfers is Hard

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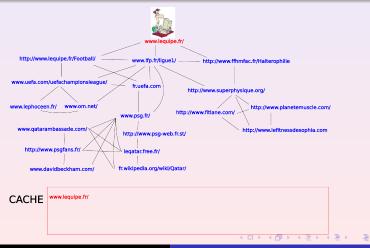
² MASCOTTE, INRIA, I3S (CNRS, UNS) Sophia Antipolis, France

³ LIRMM, MAESTRO, INRIA, Montpellier, France

Séminaire MASCOTTE, October 25th, 2011

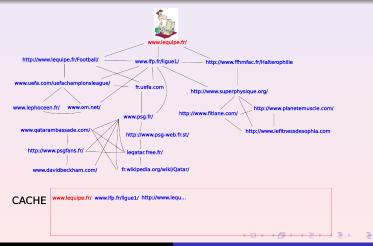
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Web: pre-loading web pages before the web Surfer accesses it Goal: Avoid the web Surfer to wait



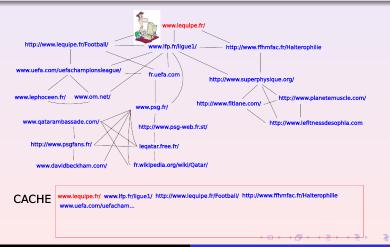
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the web Surfer starts from a given web page in cache try to load web pages in cache \rightarrow TAKES TIME



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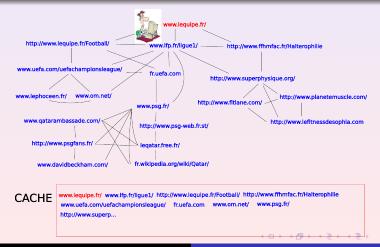
at some point, web Surfer moves if web page reached already in the cache



OK

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web Surfer follows the hyperlinks in an unpredictable way web pages to be loaded may be "guessed"



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if time is not sufficient...

web Surfer may access a page not in cache



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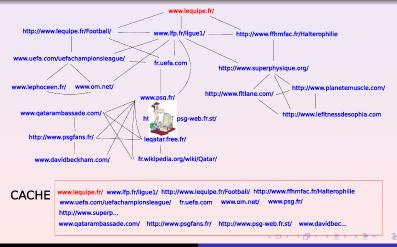
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even if we guessed well choices might be too numerous



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again... web Surfer may access a page not in cache



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Issue: download speed, NOT size of cache **Instance:** network KNOWN ((di)graph)

Related work: Probabilistic algorithms (arcs + transition probabilities)

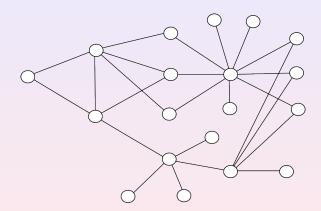
- Markovian model [Vitter,Krishnan. JACM'96] [Morad,Jean-Marie. ROADEF'10]
- Stochastic Dynamic Programming framework [Joseph,Grunwald. ISCA'97]
 [Grigoras,Charvillat,Douze. ACM Multimedia'02]

Our work:

minimize download speed to insure web Surfer never waits (worst case, deterministic)

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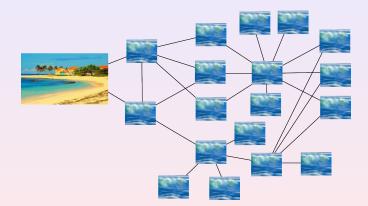
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Web = connected (di)graph

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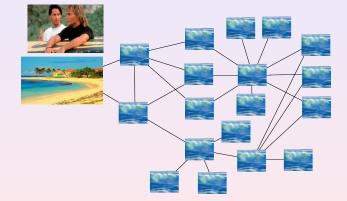
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Web = (di)graph with a specified starting point (beach)

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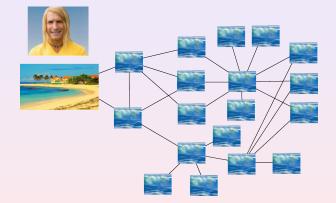
then, we need a (web) Surfer

..not them...

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then, we need a (web) Surfer

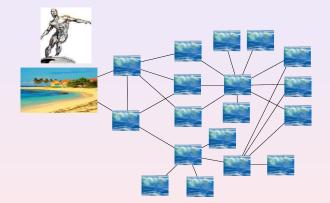
...definitively not...

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then, we need a (web) Surfer

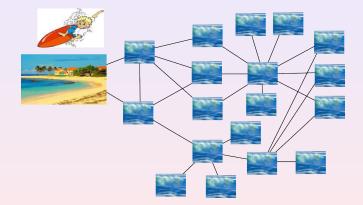
..almost...

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then, we need a (web) Surfer

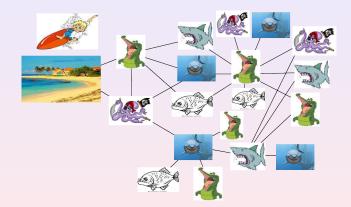
...let's take this one

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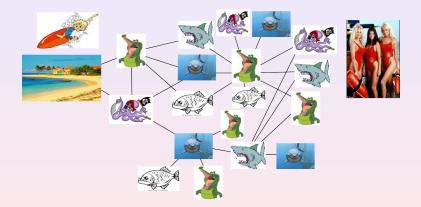
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unloaded page = dangerous node

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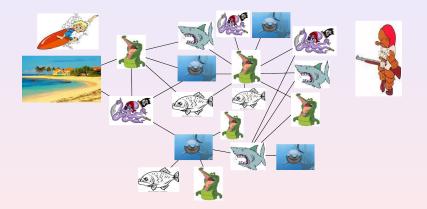


we need someone to help the Surfer

oups... sorry

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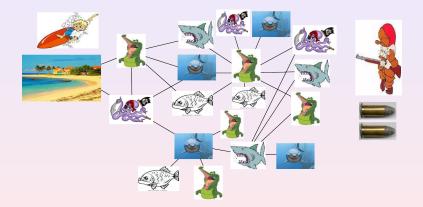
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we need someone to help the Surfer let's call it the Guard

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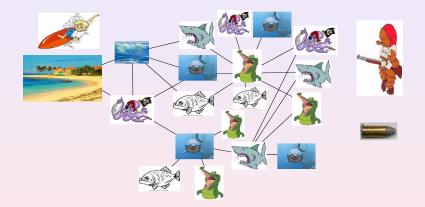


download speed = amount of balls

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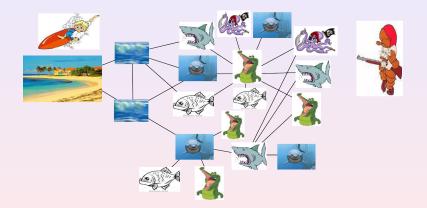
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Guard uses one ball to secure one node

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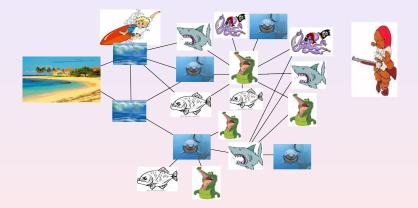


clearly, $degree(beach) \le \#$ of balls required to save Surfer

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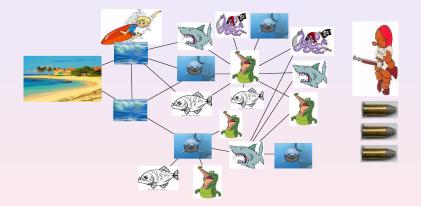


then, Surfer may move

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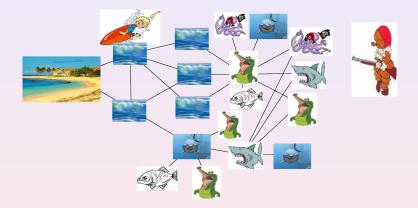
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here one more ball is needed

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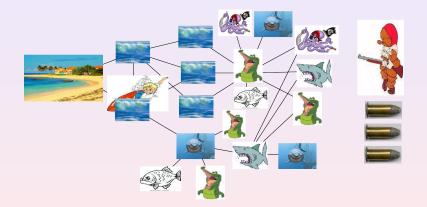
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$degree(beach) \leq amount of balls \leq max degree$

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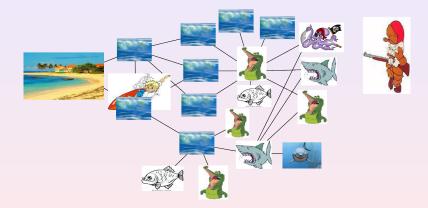


Surfer may move anywhere in its neighborhood

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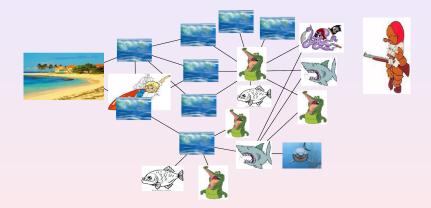


balls may be used to prevent future moves

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are 3 balls sufficient to make sure Surfer never eaten?

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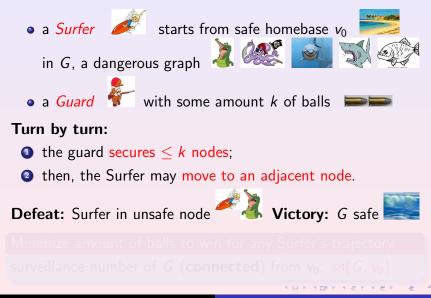
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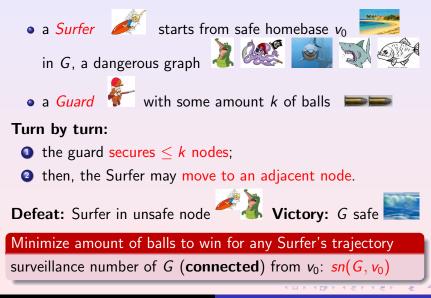
Model: a Two players game



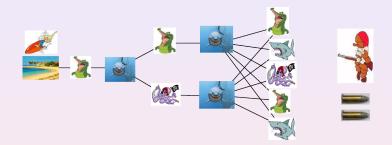
Model: a Two players game



Model: a Two players game



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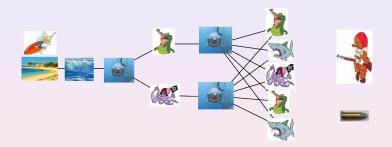


with 1 ball: after 2 steps, Surfer faces 2 dangerous nodes!!

 $sn(G, v_0) > 1$

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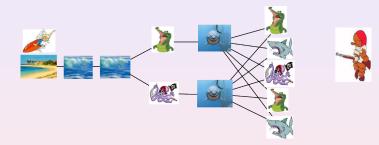
Guard uses his balls

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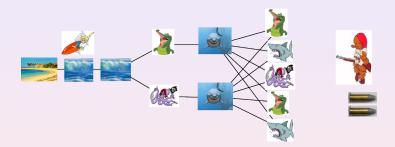


Guard uses (all) his balls

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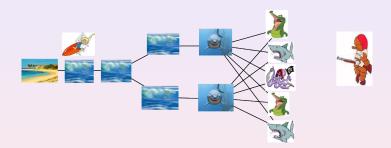


Guard uses (all) his balls, **then** Surfer may move Clearly: worst case if Surfer always move

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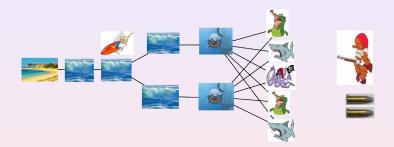
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Guard uses (all) his balls, then Surfer may move

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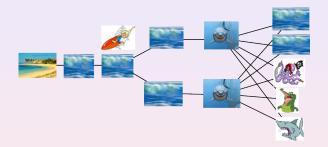
A (B) > A (B) > A (B) >



Guard uses (all) his balls, then Surfer moves

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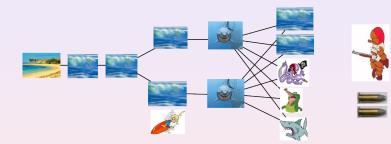


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Guard uses (all) his balls, then Surfer moves

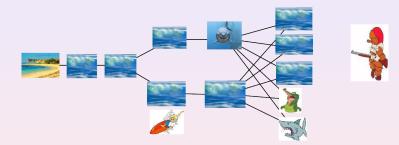
Guard may secure any node in the graph



Guard uses (all) his balls, then Surfer moves

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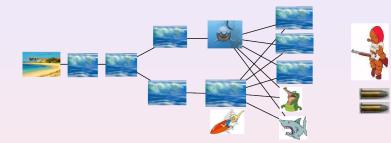


Guard uses (all) his balls, then Surfer moves

strategy: safe nodes + Surfer's node $\Rightarrow \leq k$ nodes to secure

6/15

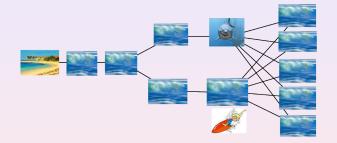
A (10) A (10)



Guard uses (all) his balls, then Surfer moves

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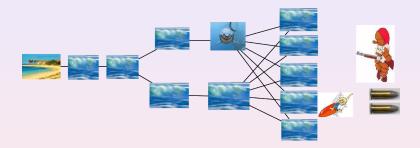




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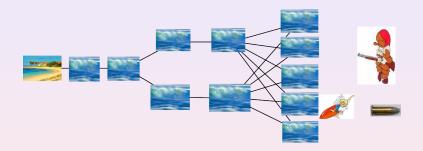
Guard uses (all) his balls, then Surfer moves



Guard uses (all) his balls, then Surfer moves

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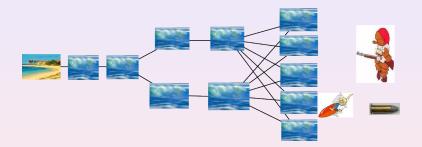
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Guard uses (all) his balls, then Surfer moves

All nodes safe: Victory against this trajectory of the Surfer

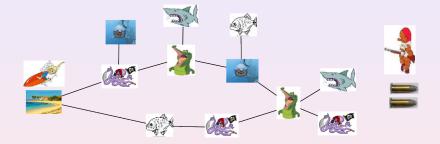
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In this example, all Surfer's trajectory similar (by symmetry) victory whatever Surfer's trajectory $\Rightarrow sn(G, v_0) = 2$

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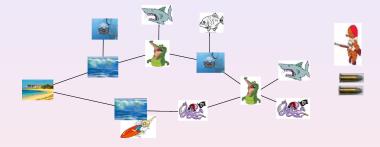
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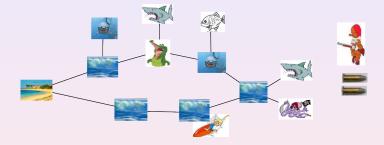
degree of homebase $= 2 \Rightarrow \ge 2$ balls required!! $sn(G, v_0) \ge 2$ **Question:** Is it more difficult to protect "fast" Surfers?

7/15

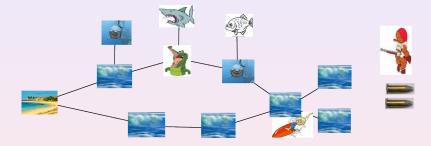
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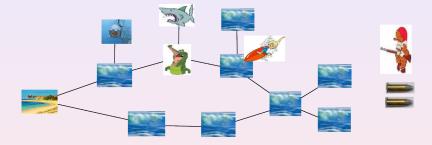
let's try with 2 balls if Surfer moves anti-clockwise...



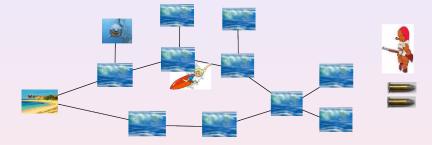
let's try with 2 balls if Surfer moves anti-clockwise...



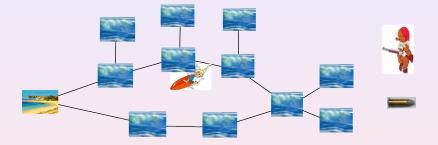
let's try with 2 balls if Surfer moves anti-clockwise...



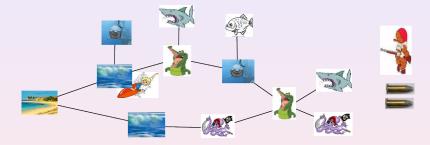
let's try with 2 balls if Surfer moves anti-clockwise...



let's try with 2 balls if Surfer moves anti-clockwise...

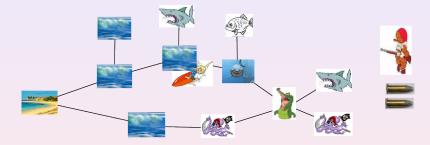


let's try with 2 balls if Surfer moves anti-clockwise, Guard manage to secure G!!



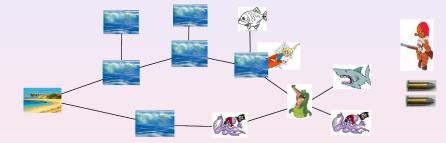
let's try with 2 balls if Surfer moves clockwise...

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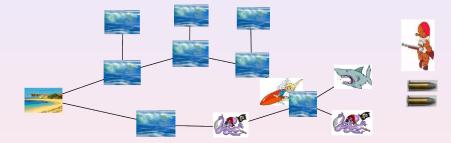
let's try with 2 balls if Surfer moves clockwise...

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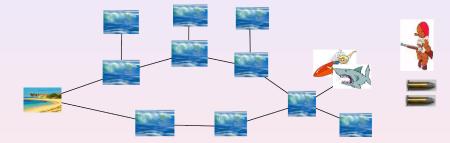


let's try with 2 balls if Surfer moves clockwise...

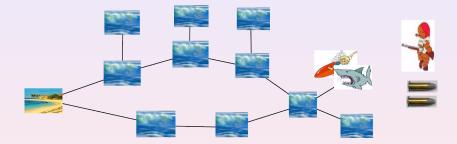
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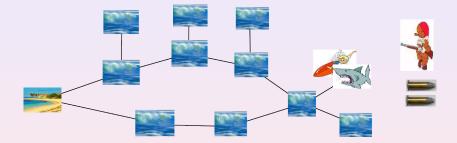
let's try with 2 balls if Surfer moves clockwise...



let's try with 2 balls if Surfer moves clockwise, a shark is happy!!



following a longest path may be more dangerous for the Surfer we cannot restrict our study to shortest paths :(

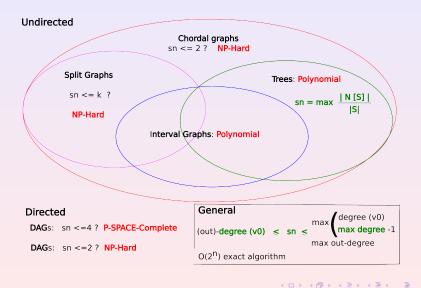


.... however, we can restrict our study to induced paths

Theorem 1: Worst case when Surfer follows induced paths Restricting Surfer to induced paths does not decrease *sn*

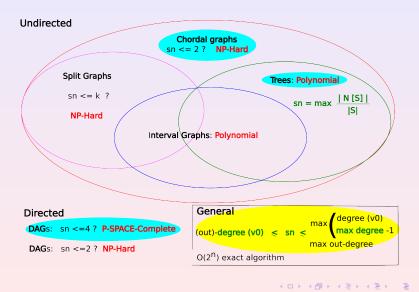
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Results: Complexity, Algorithms and Combinatoric



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Results: Complexity, Algorithms and Combinatoric



Chordal graph: no induced cycle of length > 3.

reduction from

3-Hitting Set

Inputs:

- set $E = \{e_1, \cdots, e_n\}$
- $S = \{S_1, \dots, S_\ell = \{e_i, e_j, e_t\}, \dots, S_m\}$ of triples of *E*

sn < 2

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(NP-complete)

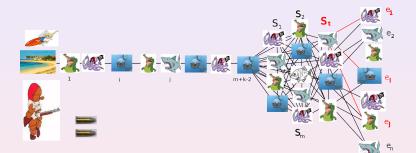
• integer $k \geq 1$

Question: \exists ? $H \subseteq E$ such that

•
$$|H| \leq k$$

• $H \cap S_i \neq \emptyset$ for any $i \leq m$

Input: $E = \{e_1, \dots, e_n\}, S = \{S_1, \dots, S_m\}$ and $k \ge 1$.

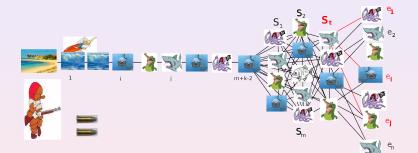


sn < 2?

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Input:
$$E = \{e_1, \cdots, e_n\}$$
, $S = \{S_1, \cdots, S_m\}$ and $k \ge 1$.

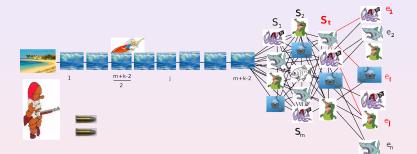


sn <u>≤ 2?</u>

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Input:
$$E = \{e_1, \cdots, e_n\}$$
, $\mathcal{S} = \{S_1, \cdots, S_m\}$ and $k \ge 1$.



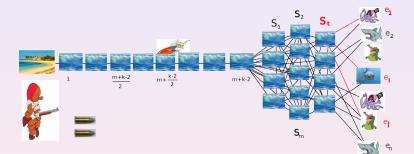
 $sn \leq 2?$

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Input:
$$E = \{e_1, \cdots, e_n\}$$
, $\mathcal{S} = \{S_1, \cdots, S_m\}$ and $k \ge 1$.

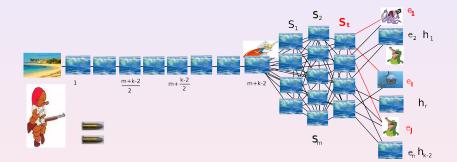


 $sn \leq 2?$

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Input: $E = \{e_1, \dots, e_n\}, S = \{S_1, \dots, S_m\}$ and $k \ge 1$.



$sn(G, v_0) \leq 2 \Leftrightarrow hittingSet(E, S) \leq k$

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sn < 2?

DAG: Directed Acyclic Graph.

reduction from

3-QSAT

Inputs:

- set of variables $\{x_1, \cdots, x_n, y_1, \cdots, y_n\}$
- logical formula $\Phi(x_1, \cdots, x_n, y_1, \cdots, y_n)$

Question: is it true?

$$\forall x_1 \exists y_1 \forall x_2 \exists y_2 \cdots \forall x_n \exists y_n \ \Phi(x_1, \cdots, x_n, y_1, \cdots, y_n)$$



(PSPACE-complete)

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PSPACE-hardness in DAGs

DAG: Directed Acyclic Graph.

reduction from

3-QSAT

Inputs:

- set of variables $\{x_1, \cdots, x_n, y_1, \cdots, y_n\}$
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sn

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(PSPACE-complete)

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- " $\forall x_i$ " depends on Surfer's path
- "∃y_i" depends on Guard's strategy

PSPACE-hardness in DAGs

Input: $\{x_1, \dots, x_n, y_1, \dots, y_n\}$ and $\Phi(x_1, \dots, x_n, y_1, \dots, y_n)$ $y_i = 1$ $y_i = 0$ $x_i = 1$ $x_i = 0$

sn <

10/15

Gadget for x_i and y_i : When Surfer reaches the right, 2 "sharks" have left \Rightarrow assignment of x_i (Surfer choice) and y_i (Guard choice)

PSPACE-hardness in DAGs

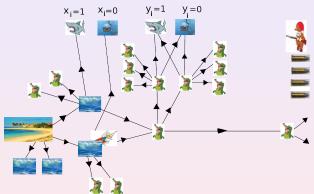
Input: $\{x_1, \dots, x_n, y_1, \dots, y_n\}$ and $\Phi(x_1, \dots, x_n, y_1, \dots, y_n)$ $y_i = 1$ $y_i = 0$ $x_i = 1$ $x_i = 0$

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Gadget for x_i and y_i : When Surfer reaches the right, 2 "sharks" have left \Rightarrow assignment of x_i (Surfer choice) and y_i (Guard choice)

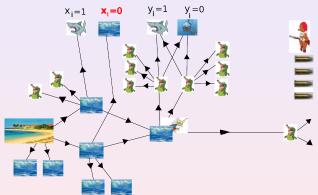
Input: $\{x_1, \dots, x_n, y_1, \dots, y_n\}$ and $\Phi(x_1, \dots, x_n, y_1, \dots, y_n)$



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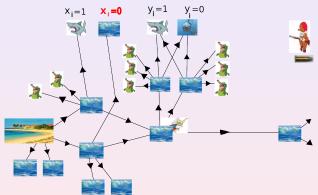
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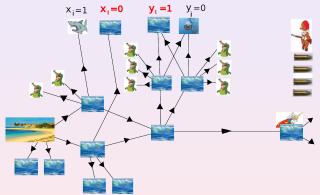
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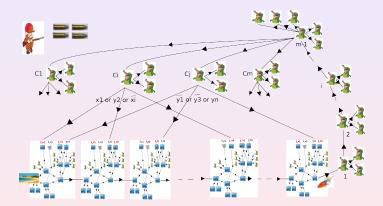
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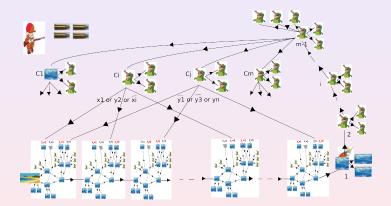


When Surfer reaches the bottom-right, all variables have been 10/15 assigned: x_i 's by Surfer, y_i 's by Guard

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Input: $\{x_1, \dots, x_n, y_1, \dots, y_n\}$ and $\Phi(x_1, \dots, x_n, y_1, \dots, y_n)$



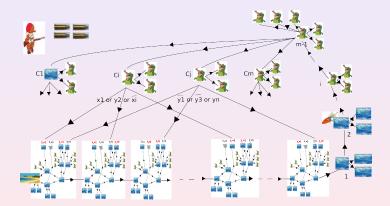
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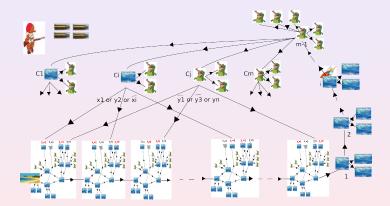


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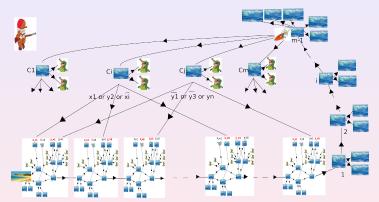


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Input: $\{x_1, \dots, x_n, y_1, \dots, y_n\}$ and $\Phi(x_1, \dots, x_n, y_1, \dots, y_n)$

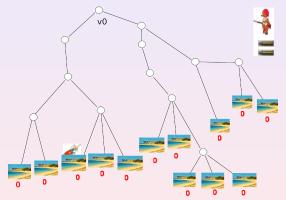


 $sn(D, v_0) \leq 4 \Leftrightarrow \forall x_1 \cdots \exists y_n \Phi true$

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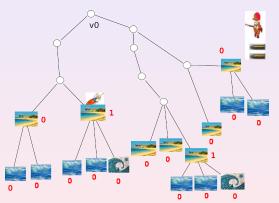
Dynamic Programming: amount of balls fixed to k



 $label(v) = \min \#$ of nodes to be secured **before starting** to win in T_v starting in v, with k balls label(leaf) = 0

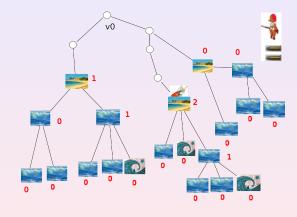
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Dynamic Programming: amount of balls fixed to k



 $label(v) = \min \#$ of nodes to be secured **before starting** to win in T_v starting in v, with k balls

Dynamic Programming: amount of balls fixed to k

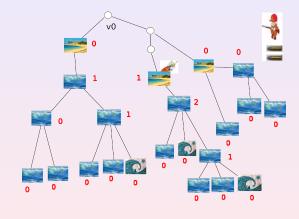


 $label(v) = \max\{0; deg(v) - k + \sum_{i=1}^{n} k_{i}\}$ label(w)} w child of v

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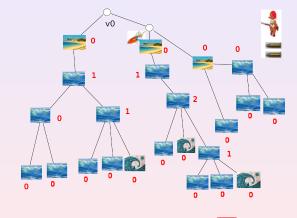
Dynamic Programming: amount of balls fixed to k



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Dynamic Programming: amount of balls fixed to k



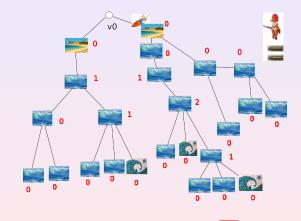
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Dynamic Programming: amount of balls fixed to k



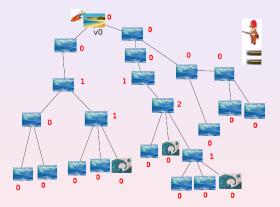
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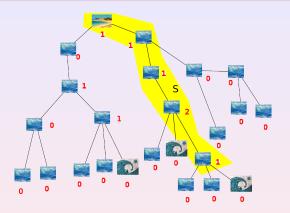
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Dynamic Programming: amount of balls fixed to k



 $sn(T, v_0) \leq k \Leftrightarrow label(v_0) = 0$

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Upper bound: if $k < sn(T, v_0)$, $label(v_0) > 0$ maximal subtree S of nodes v with label(v) > 0 containing v_0

$$\frac{|N[S]|-1}{|S|} > k \qquad \text{hence max} \frac{|N[S]|-1}{|S|} \ge sn(T, v_0)$$

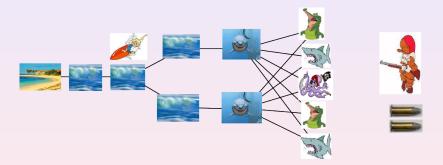
Combinatorial characterization in Trees

For any tree T, $v_0 \in V(T)$, $sn(T, v_0) = \max\left\lceil \frac{|N[S]|-1}{|S|} \right\rceil$, taken for any subtree S containing v_0 .

Exact Algorithms

- $O(2^n)$ algorithm in *n*-node graphs;
- sn(T, v₀) can be computed in time O(n log n) in any n-node tree T and for any v₀ ∈ V(T);
- sn(G, v₀) can be computed in time O(n · Δ³) in any n-node interval graph G with maximum degree Δ and for any v₀ ∈ V(T).

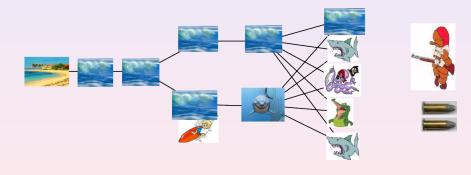
Constraint: safe vertices must induce a connected subgraph



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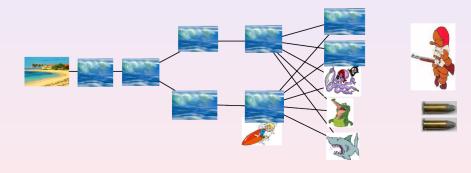
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Constraint: safe vertices must induce a connected subgraph



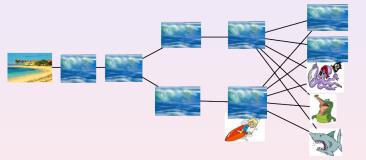
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Constraint: safe vertices must induce a connected subgraph



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Constraint: safe vertices must induce a connected subgraph





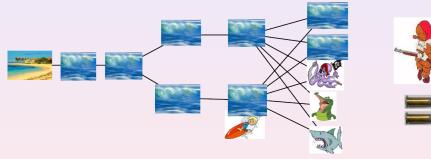
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Connectivity costs:

connected- $sn(G, v_0) = 3 > sn(G, v_0) = 2$ All previous results hold for the connected variant

Constraint: safe vertices must induce a connected subgraph



Connectivity costs: connected- $sn(G, v_0) = 3 > sn(G, v_0) = 2$ $\exists ? G \text{ and } v_0 \text{ such that } c-sn(G, v_0) \ge sn(G, v_0) + 2 ????$

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• complexity in bounded degree graphs?

(polynomial if $\Delta \leq 3$)

- complexity in bounded treewidth graphs?
- $\exists ?c < 2 \text{ and } O(c^n) \text{ algorithm in } n \text{-node graphs}?$
- sn(G, v₀) = max[^{|N[S]|-1}/_{|S|}], taken for any connected subgraph S containing v₀?
- cost of connectivity? $\frac{connected sn}{sn} \le cte$? \exists ? *G* and v_0 such that $c-sn(G, v_0) \ge sn(G, v_0) + 2$????
- ...

Thank you for your attention¹

¹No seafood... no animal has been hurt when preparing this talk. = $\sqrt{2}$ Fomin, Giroire, Jean-Marie, Mazauric and Nisse To Satisfy Impatient Web Surfers is Hard