

Tradeoffs for Routing Reconfiguration in WDM Networks

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Routing in WDM Networks

Physical Network, Links provide several wavelengths

multi-graph $G = (V, E)$

an edge $(u, v) \Leftrightarrow$ one wavelength on the link (u, v)

Routing of a set of requests/connections

set of requests $\mathcal{R} \subseteq 2^{V \times V}$

routing: for each request (u, v) ,
a path from u to v and 1 wavelength.

Problem: due to dynamicity of traffic, failures

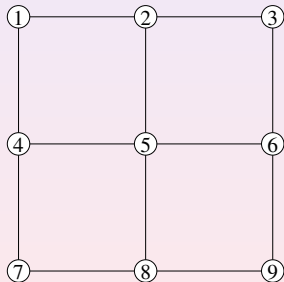
how to maintain an efficient routing?

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links

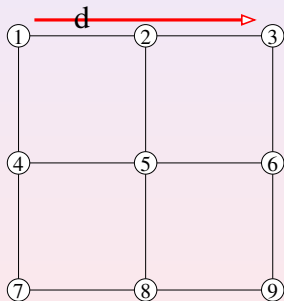


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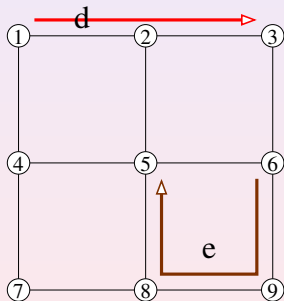
Request $d : 1 \rightarrow 3$

What happens in "real" world

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Example of a grid network with directed symmetric links



Request d : $1 \rightarrow 3$

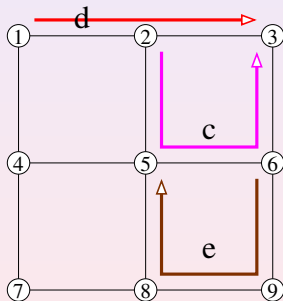
Request e : $6 \rightarrow 5$

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links



Request d : 1 → 3

Request e : 6 → 5

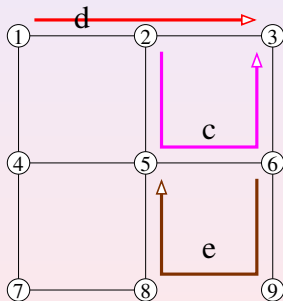
Request c : 2 → 3

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links



Request d : $1 \rightarrow 3$

Request e : $6 \rightarrow 5$

Request c : $2 \rightarrow 3$

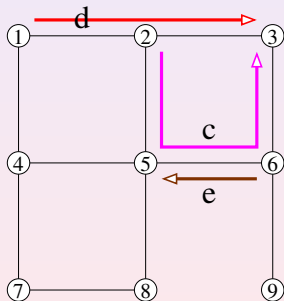
Failure of link $\{8,9\}$

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links



Request d : $1 \rightarrow 3$

Request e : $6 \rightarrow 5$

Request c : $2 \rightarrow 3$

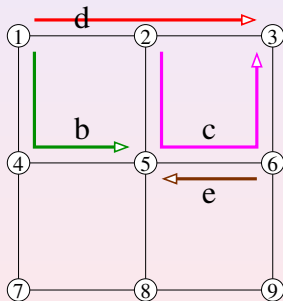
Rerouting of request e

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links



Request d : 1 → 3

Request e : 6 → 5

Request c : 2 → 3

Request b : 1 → 5

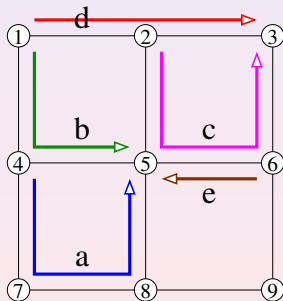
New link {8,9}

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links



Request d : 1 → 3

Request e : 6 → 5

Request c : 2 → 3

Request b : 1 → 5

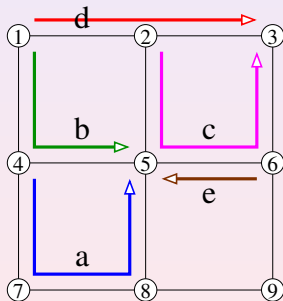
Request a : 4 → 5

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links



Leads to a poor usage of resources

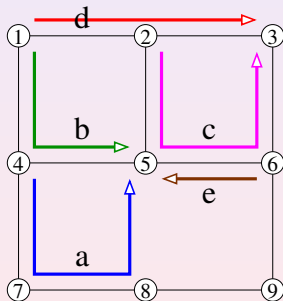
Sometimes greedy routing is impossible even if several requests are allowed to be moved

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links



Leads to a poor usage of resources

Sometimes greedy routing is impossible even if several requests are allowed to be moved

If $\{5, 8\}$ fails:

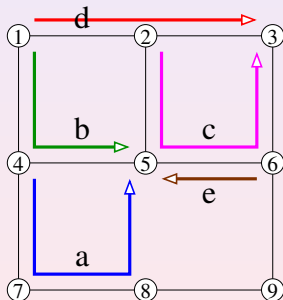
Move-to-Vacant impossible

What happens in "real" world

Variation of traffic + dynamicity induced by failures

⇒ Online processes to route all requests: e.g., greedy routing

Example of a grid network with directed symmetric links



2 questions arise:

- 1 Compute new routing
- 2 Switch from initial routing to final one

We focus on 2

Two ways of switching one request

Make-before-break:

Establish new path before switching the connection

⇒ Destination resources must be available

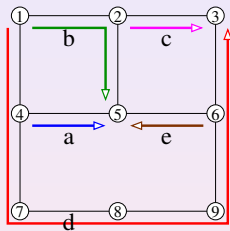
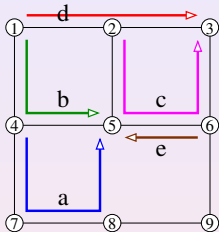
Break-before-make:

Break connection before establishing the new path

⇒ Traffic stopped = **interruption**

The Routing Reconfiguration Problem

How to go from the initial routing (left) to the final one (right)?



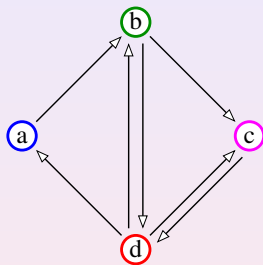
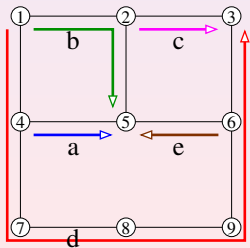
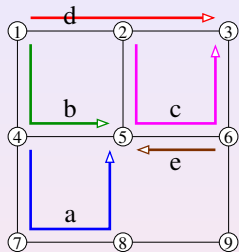
Inputs: Set of connection requests + current & new routing

Output: Scheduling for switching connection requests from current to new routes

Constraint: A connection is switched **only once**

Objective: Number of Interruptions (detailed later)

Dependency digraph



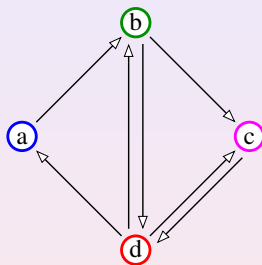
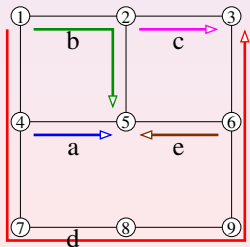
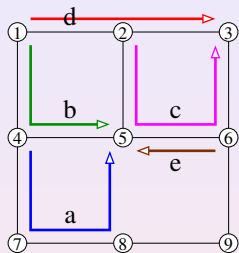
$u \rightarrow v$

if u needs resources of v

if v must be rerouted/interrupted before u

b needs resources used by d and c

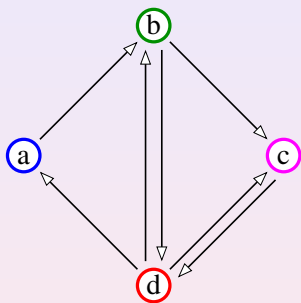
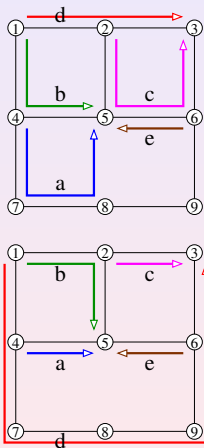
Dependency digraph



Dependency Digraph

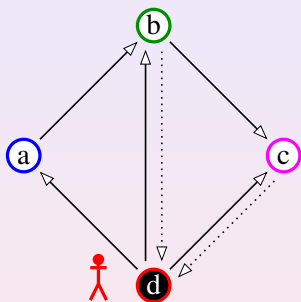
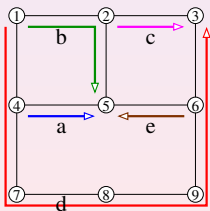
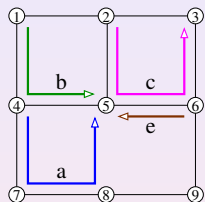
- one vertex per connection with different routes in \mathcal{I} and \mathcal{F}
- arc from u to v if resources needed by u in \mathcal{F} are used by v in \mathcal{I}

A game on dependency digraph



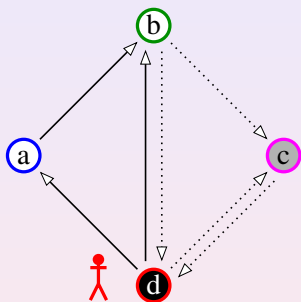
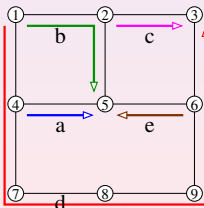
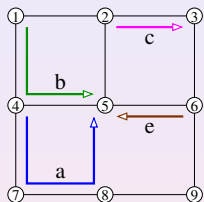
cyclic dependencies
⇒ **Interruption required**

A game on dependency digraph



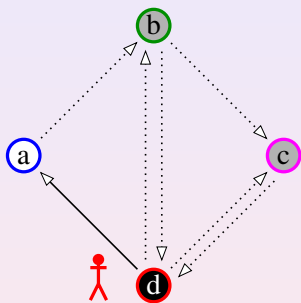
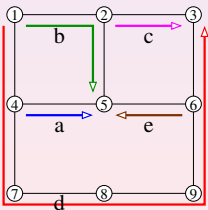
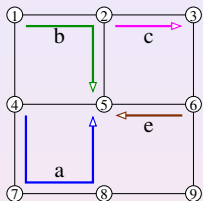
put an agent on node d
break request d

A game on dependency digraph



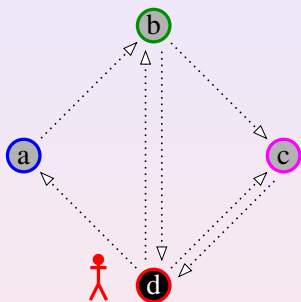
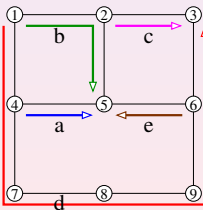
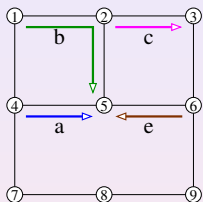
process node c
reroute request c

A game on dependency digraph



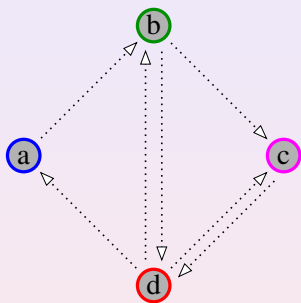
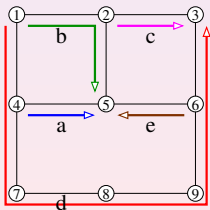
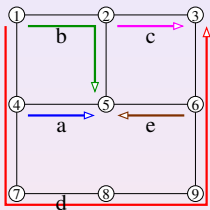
process node *b*
reroute request *b*

A game on dependency digraph



process node *a*
reroute request *a*

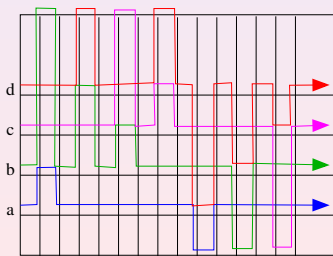
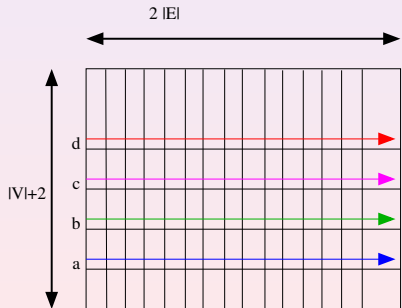
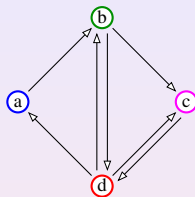
A game on dependency digraph



process node d
and remove agent
route request d

From now on: problem on digraphs

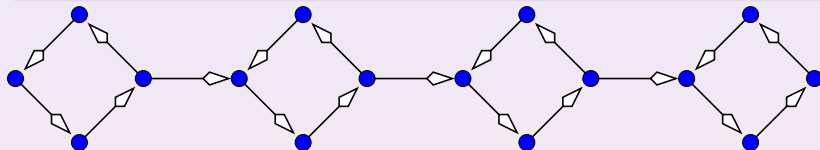
Any directed graph is a dependency digraph



Two possible objectives

Minimize overall number of interrupted requests

Minimum Feedback Vertex Set (MFVS), here $N/4$

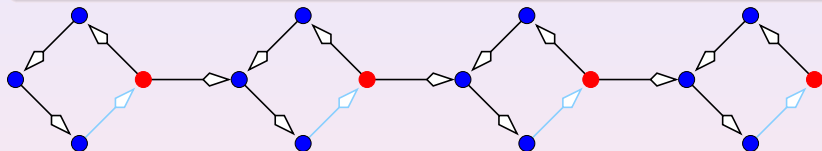


Remarks: MFVS is NP-complete and non APX in digraphs
2-approx in undirected (directed symmetric) graphs

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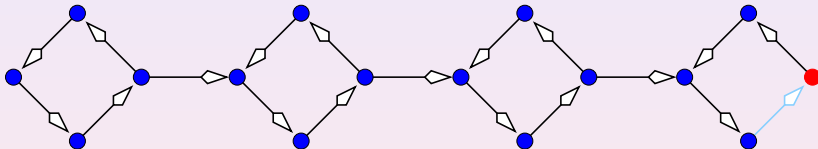


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Minimize number of **simultaneous** interrupted requests

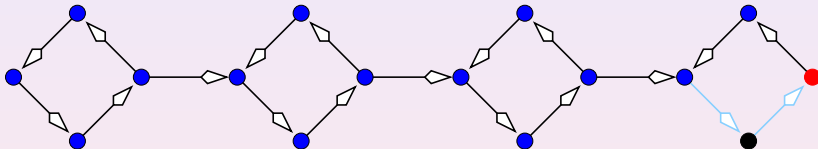
Process Number, pn = smallest number of requests that have to be **simultaneously** interrupted.

Here, $pn = 1 \Rightarrow$ Gap with MFVS up to $N/2$

Two possible objectives

Minimize overall number of interrupted requests

Minimum Feedback Vertex Set (MFVS), here $N/4$



Minimize number of **simultaneous** interrupted requests

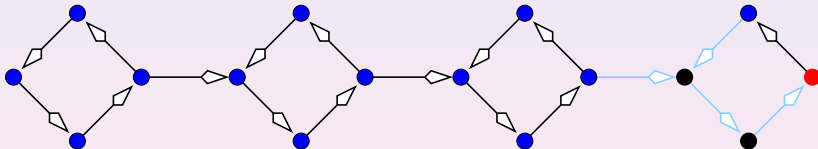
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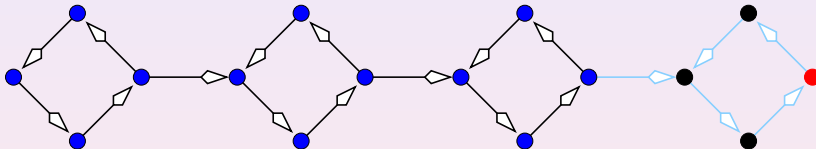
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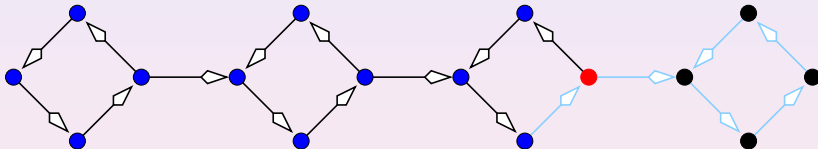
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Minimize number of **simultaneous** interrupted requests

Process Number, pn = smallest number of requests that have to be **simultaneously** interrupted.

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Routing Reconfiguration, Process number

Game with Agents on the Dependency digraph D

Sequence of three basic operations, . . .

- 1 **Place** a searcher at a node = **interrupt the request**;
- 2 **Process** a node if all its out-neighbors are either processed or occupied by an agent = **(Re)route a connection when final resources are available**;
A processed node is removed from the dependency digraph.
- 3 **Remove** an agent from a node, after having processed it.

. . . that must result in processing all nodes

Process number $pn(D) = \min p \mid D \text{ can be processed with } p \text{ agents}$

Remark: In undirected graphs or symmetric digraphs:

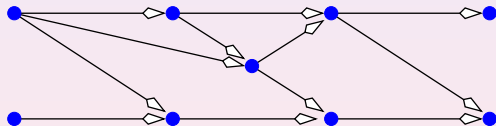
Graph Searching game when a fugitive is captured when surrounded

Example: DAG

Only one operation is used

- 1 Place a searcher at a node = interrupt the request;
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- 3 Remove an agent from a node, after having processed it.

DAG



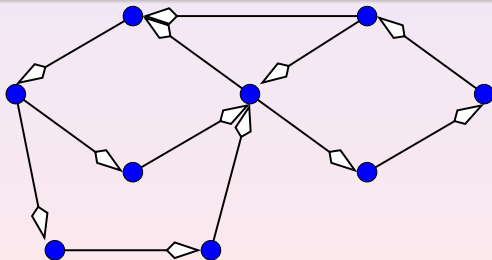
Theorem

$pn(D) = 0$ iff D is a DAG

Digraphs with process number 1

One agent is used

- 1 Place a searcher at a node = **interrupt the request**;
- 2 Process a node if all its out-neighbors are either processed or occupied by an agent = **(Re)route a connection when final resources are available**;
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Theorem

$$pn(D) = 1 \Leftrightarrow \forall SCC, MFVS(SCC) = 1$$

$$O(N + M)$$

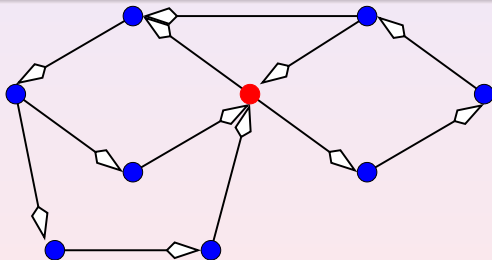
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Digraphs with process number 1

One agent is used

- 1 Place a searcher at a node = interrupt the request;
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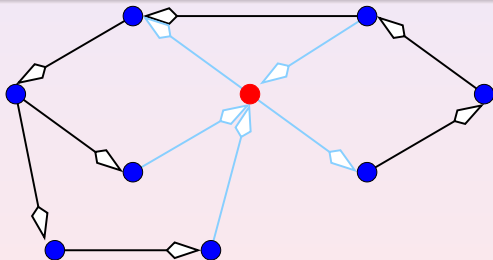
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Digraphs with process number 1

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$$pn(D) = 1 \Leftrightarrow \forall SCC, MFVS(SCC) = 1$$

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Process number versus Other Parameters

a parameter of directed (and undirected) graphs

vs, vertex separation

in undirected graph or symmetric digraph: $vs = \text{pathwidth}$

$$vs(G) = pw(G)$$

Kinnersley [IPL 92]

Theorem

(Coudert & Sereni, 2007)

$$vs(D) \leq pn(D) \leq vs(D) + 1$$

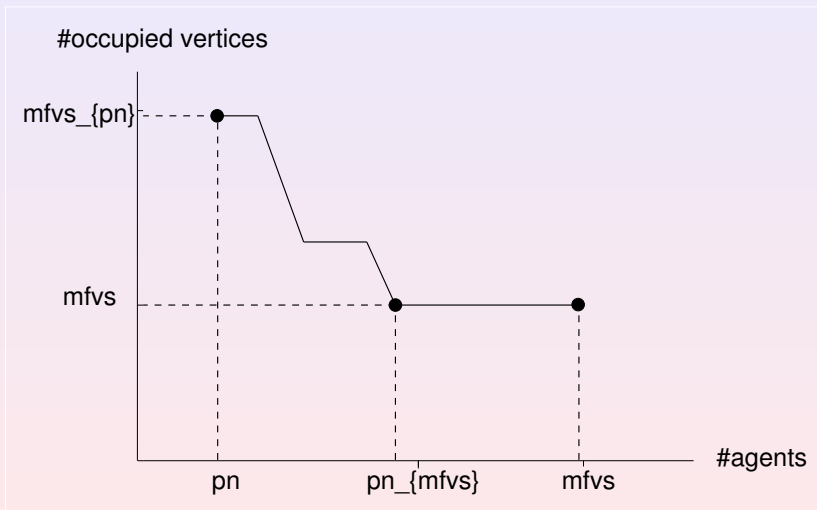
Complexity: NP-Complete, Not APX

- Characterization of digraphs with process number 0, 1, 2
(Coudert & Sereni, 2007)

State of the Art

- distributed $O(n \log n)$ -time exact algorithm in trees
(Coudert, Huc, Mazauric [DISC 08])
- generalized Model handling **priority connections**
connections that cannot be interrupted
heuristic using random walk
(Coudert, Huc, Mazauric, Nisse, Sereni [ONDM 09])
heuristic using LP (Solano [Globecom 09])
- generalized Model allowing bandwidth sharing
deciding whether reconfiguration may be done without interruption:
NP-complete (Coudert, Mazauric, Nisse [AGT 09])

Tradeoff: total/ max simultaneous interruptions



Complexity

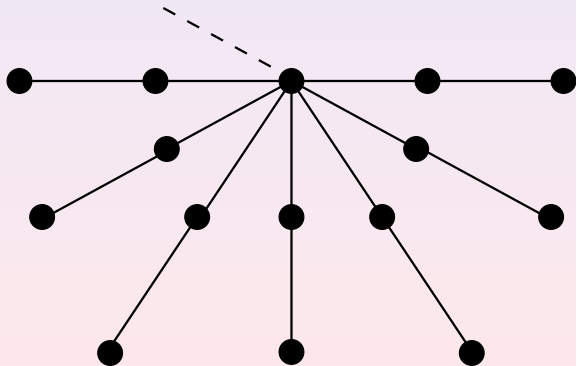
- Smallest number of agents such that the number of occupied vertices is minimum = $pn_{mfvs}(D)$
- $\mu = \frac{pn_{mfvs}(D)}{pn(D)}$
- Smallest total number of occupied vertices such that the number of agents is minimum = $mfvs_{pn}(D)$
- $\lambda = \frac{mfvs_{pn}(D)}{mfvs(D)}$

Theorem

The problems of determining $pn_{mfvs}(D)$, $mfvs_{pn}(D)$, μ , and λ are NP-Complete and not APX.

agents for minimizing # occupied vertices

\exists digraphs with arbitrary large ratio: $\mu = \frac{pn_{mfvs}(D)}{pn(D)}$.



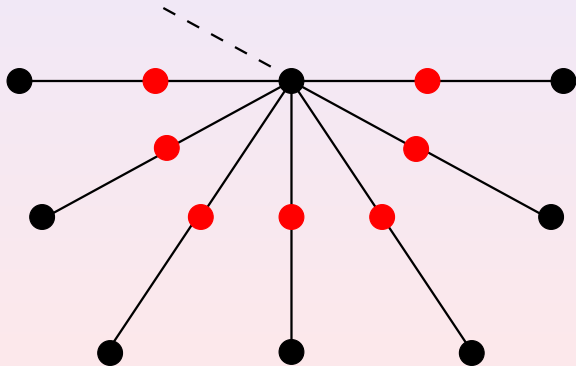
$$mfvs(D) = n$$

$$pn(D) = 2$$

$$pn_{mfvs}(D) = n$$

agents for minimizing # occupied vertices

\exists digraphs with arbitrary large ratio: $\mu = \frac{pn_{mfvs}(D)}{pn(D)}$.



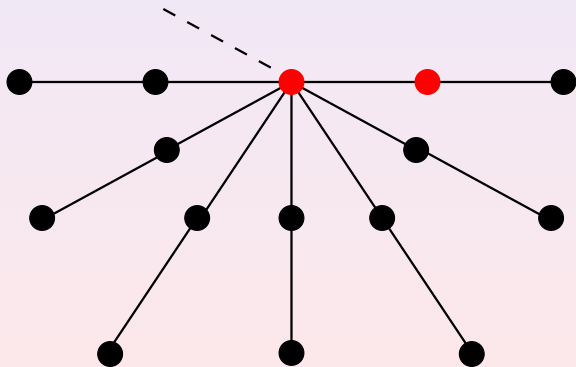
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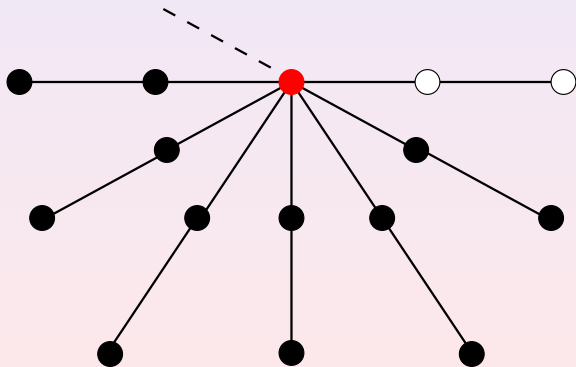
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agents for minimizing # occupied vertices

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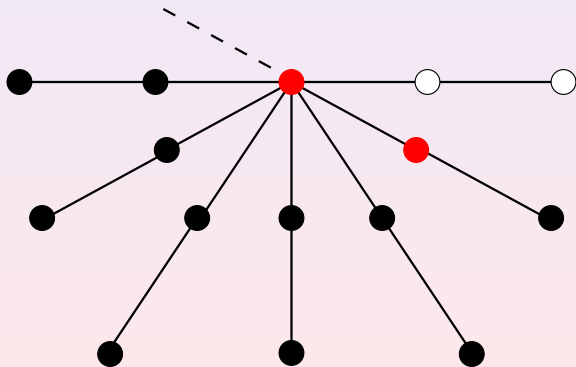
$$mfvs(D) = n$$

$$pn(D) = 2$$

$$pn_{mfvs}(D) = n$$

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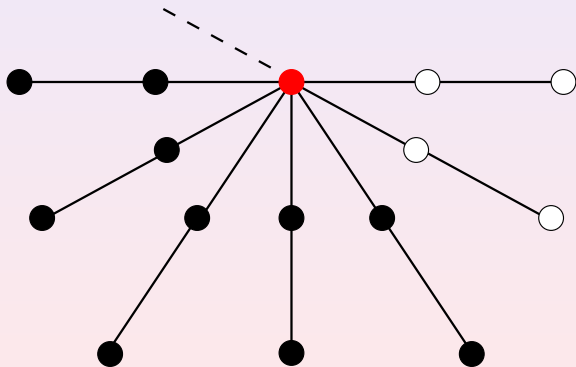
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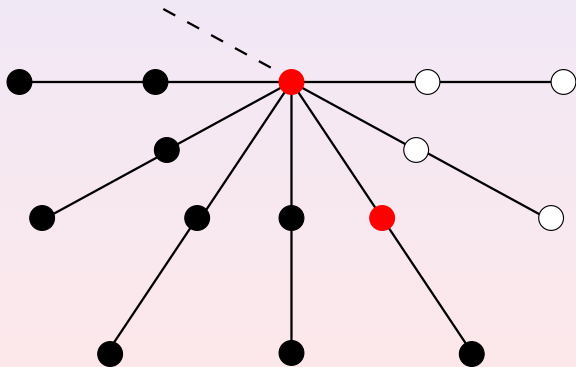
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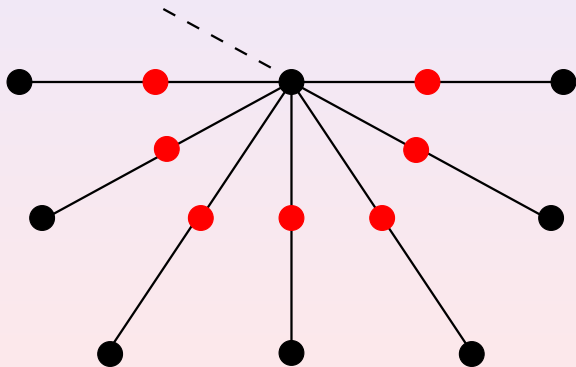
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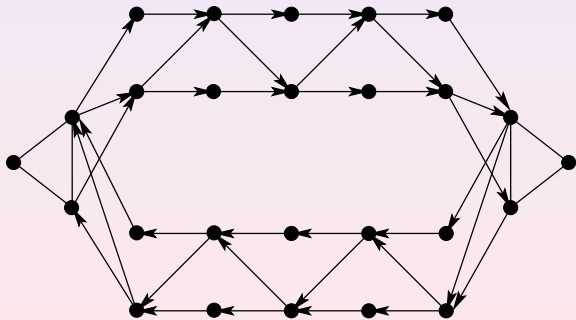
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occupied vertices by the minimum # agents

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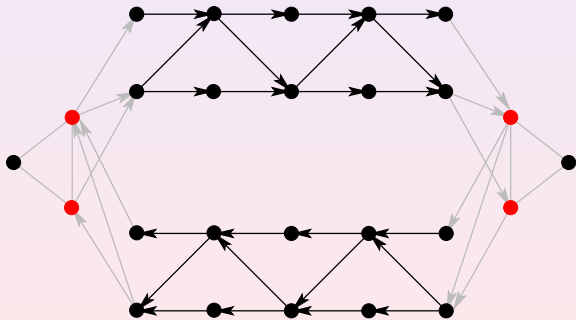
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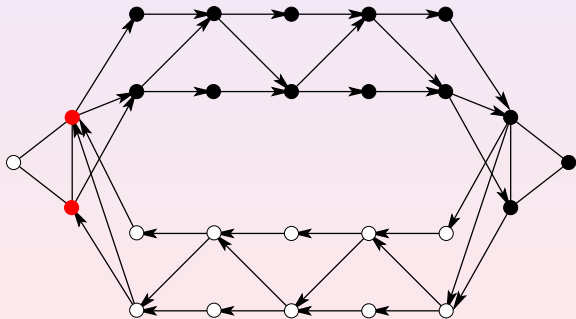
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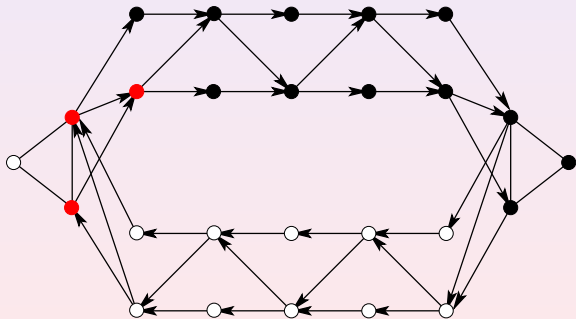
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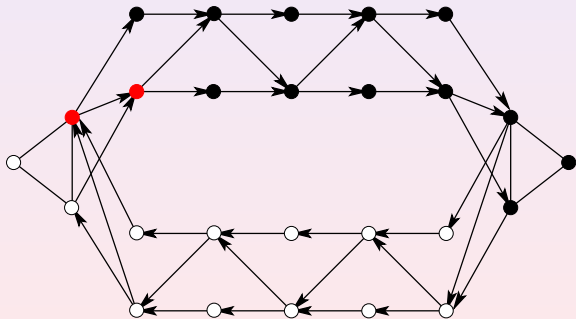
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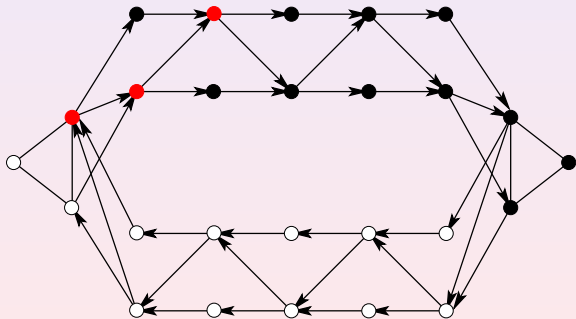
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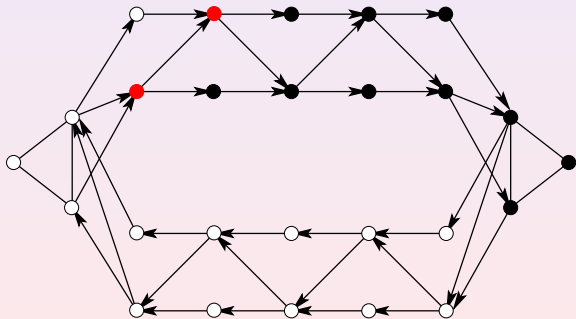
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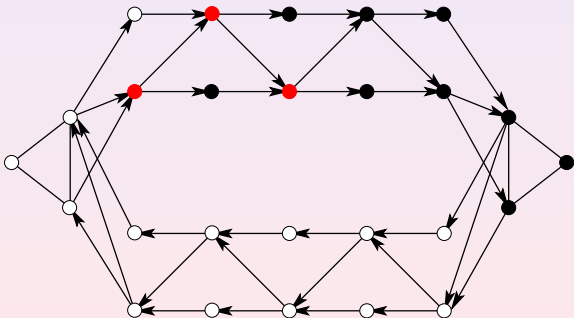
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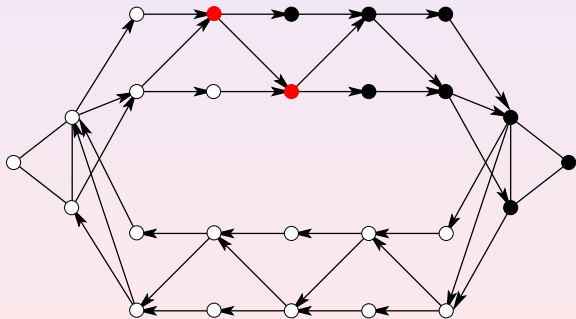
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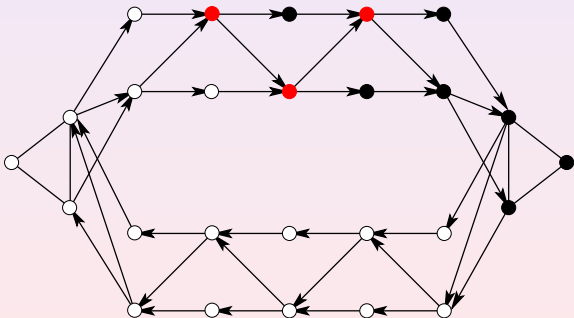
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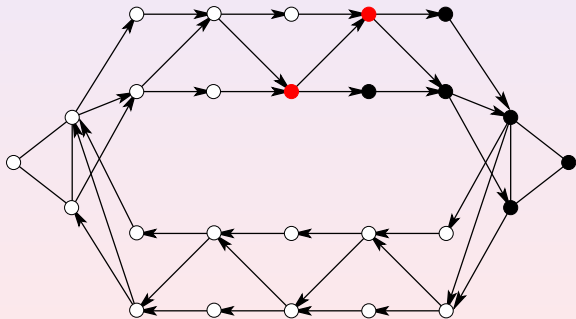
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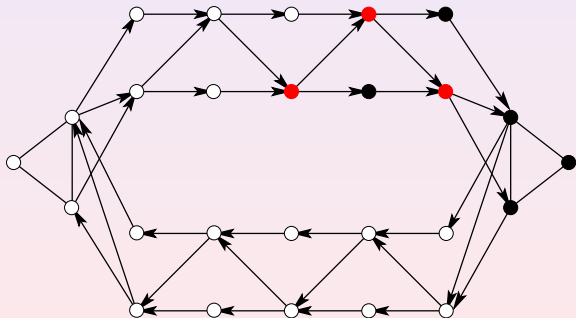
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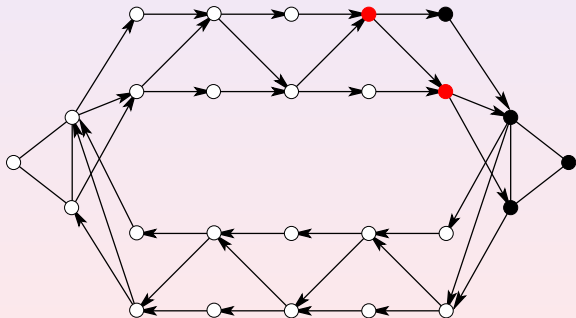
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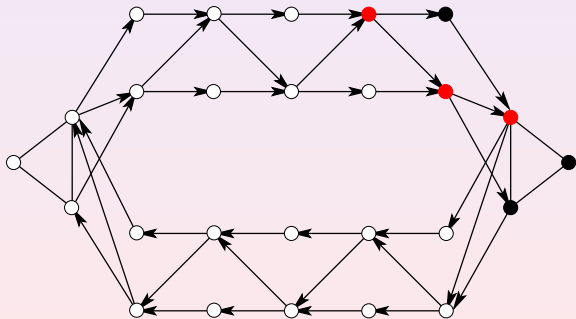
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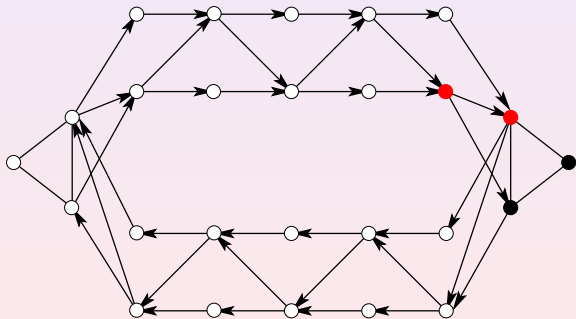
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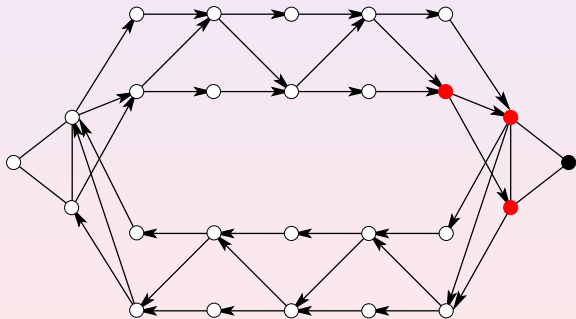
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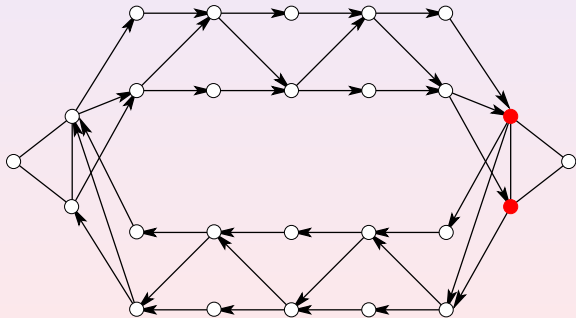
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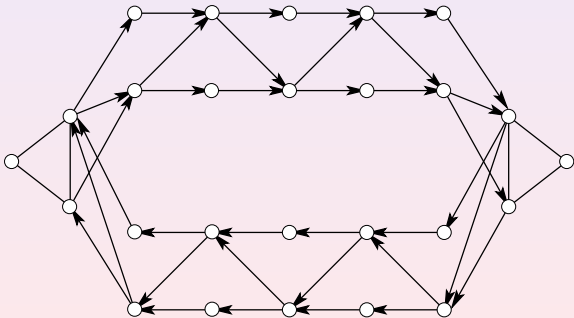
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occupied vertices by the minimum # agents

Directed graphs with BOUNDED Process Number:

$\lambda = \text{occupied vertices} / \text{mfvs}$ UNBOUNDED

What if G is undirected ??

Let G be a symmetric directed/undirected graph,

$$\lambda = \frac{\text{mfvs}_{pn}(G)}{\text{mfvs}(G)} \leq pn(G)$$

occupied vertices by the minimum # agents

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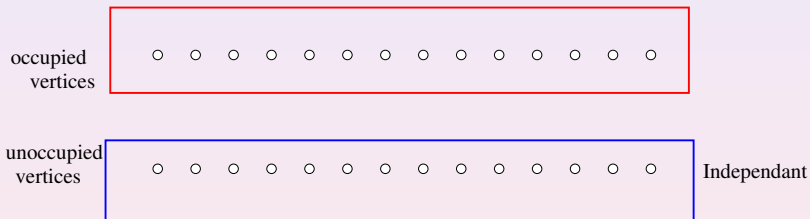
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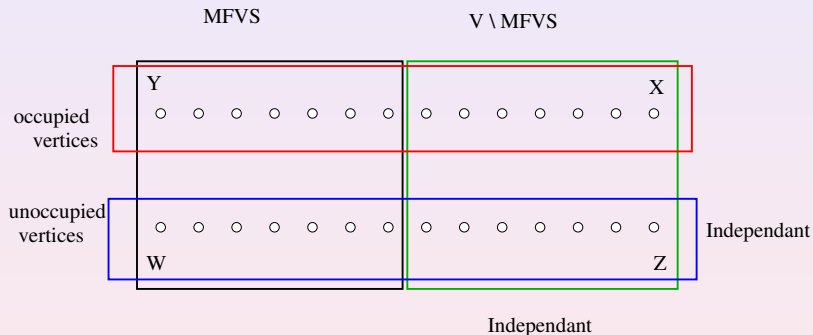
occupied vertices by the minimum # agents

Consider a MFVS of G . S using $pn(G)$ agents and occupying $mfvs_{pn}(G)$ vertices, such that occupies the minimum number of vertices in MFVS



occupied vertices by the minimum # agents

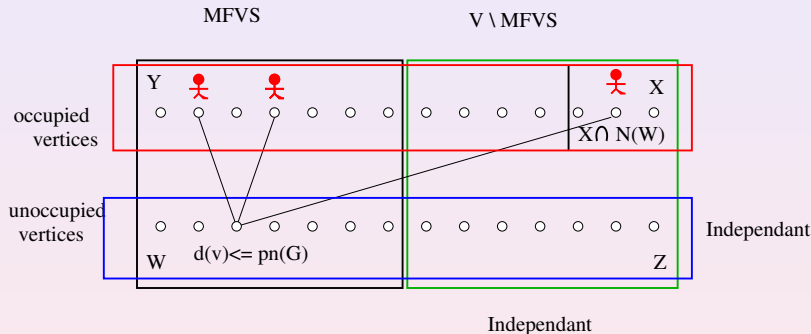
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$$\lambda = \frac{mfvs_{pn}(G)}{mfvs(G)} = \frac{Y+X}{Y+W}$$

occupied vertices by the minimum # agents

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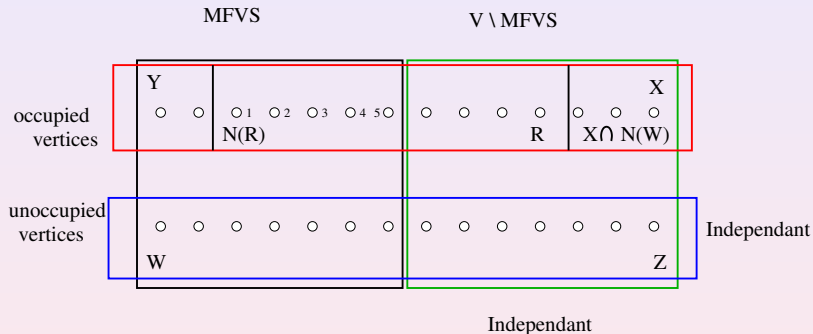


$$\lambda = \frac{mfvs_{pn}(G)}{mfvs(G)} = \frac{|Y| + |X|}{|Y| + |W|}$$

$$|X| = |X \cap N(W)| + |R| \leq |W| \cdot pn(G) + |R|$$

occupied vertices by the minimum # agents

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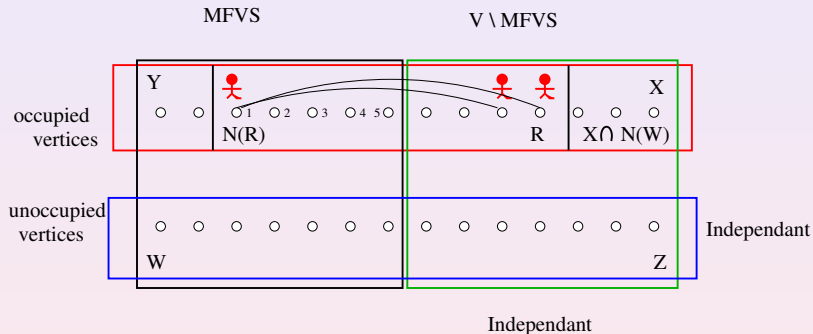


$$\lambda = \frac{mfvs_{pn}(G)}{mfvs(G)} = \frac{|Y|+|X|}{|Y|+|W|} \leq \frac{|Y|+|W|.pn(G)+|R|}{|Y|+|W|}$$

$N(R) = \{v_1, \dots, v_r\} \subseteq Y$: ordering in which agents are removed

occupied vertices by the minimum # agents

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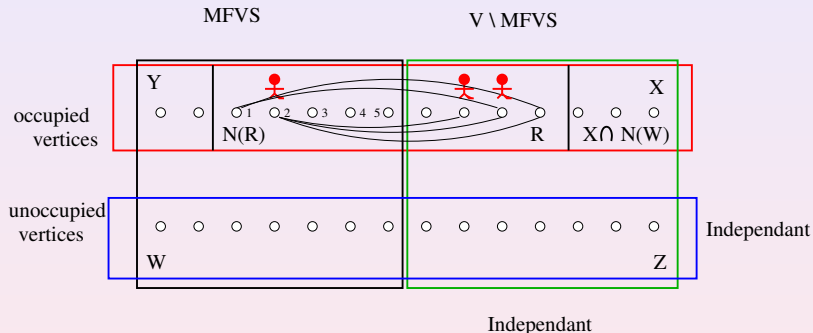


$$\lambda = \frac{mfvs_{pn}(G)}{mfvs(G)} = \frac{|Y|+|X|}{|Y|+|W|} \leq \frac{|Y|+|W|.pn(G)+|R|}{|Y|+|W|}$$

$$|N(v_1)| \leq pn(G) - 1$$

occupied vertices by the minimum # agents

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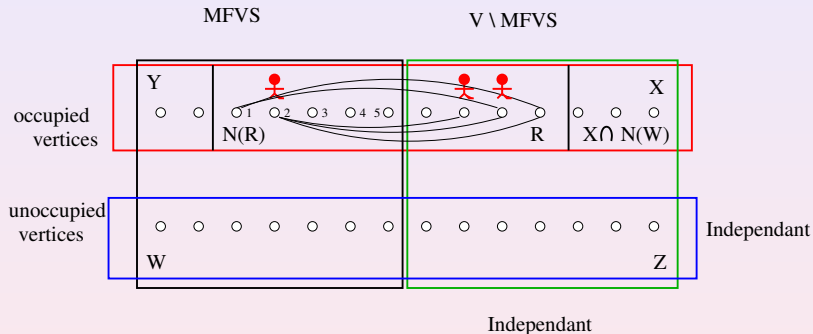


$$\lambda = \frac{mfvs_{pn}(G)}{mfvs(G)} = \frac{|Y|+|X|}{|Y|+|W|} \leq \frac{|Y|+|W|.pn(G)+|R|}{|Y|+|W|}$$

$$|N(v_2) \setminus N(v_1)| \leq pn(G) - 1, |N(v_i) \setminus \bigcup_{j < i} N(v_j)| \leq pn(G) - 1$$

occupied vertices by the minimum # agents

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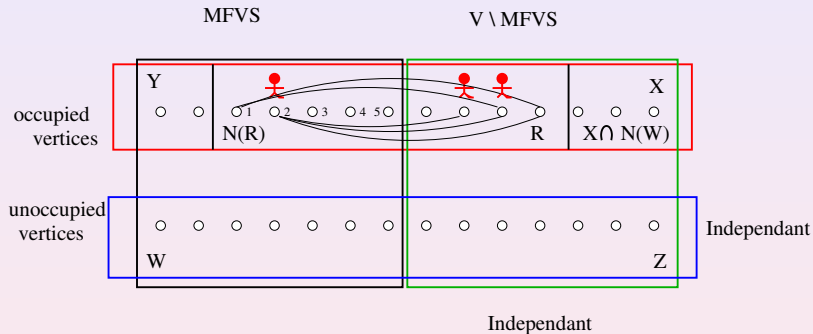


$$\lambda = \frac{mfvs_{pn}(G)}{mfvs(G)} = \frac{|Y|+|X|}{|Y|+|W|} \leq \frac{|Y|+|W|.pn(G)+|R|}{|Y|+|W|}$$

$$\text{so } |R| \leq |N(R)|(pn(G) - 1) \leq |Y|(pn(G) - 1)$$

occupied vertices by the minimum # agents

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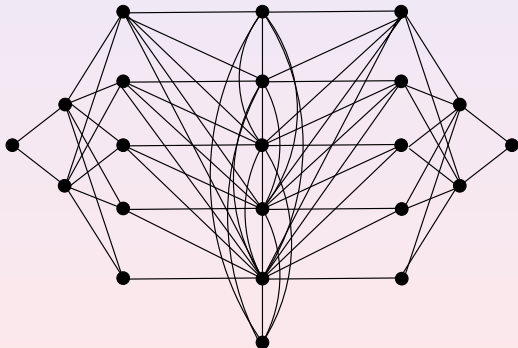


$$\lambda = \frac{mfvs_{pn}(G)}{mfvs(G)} = \frac{|Y|+|X|}{|Y|+|W|} \leq \frac{|Y|+|W|.pn(G)+|R|}{|Y|+|W|}$$

$$\lambda \leq \frac{|Y|+|W|.pn(G)+|Y|(pn(G)-1)}{|Y|+|W|} = pn(G)$$

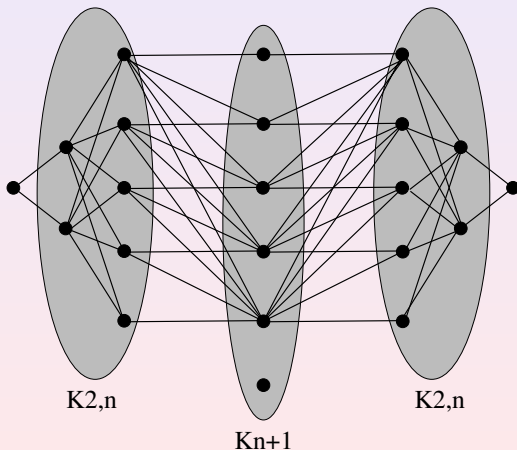
occupied vertices by the minimum # agents

$\forall \epsilon, \exists$ symmetric digraphs D : $\lambda = \frac{mfvs_{pn}(D)}{mfvs(D)} > 3 - \epsilon$.



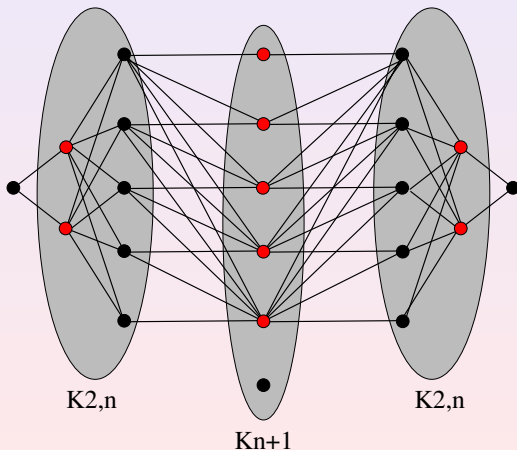
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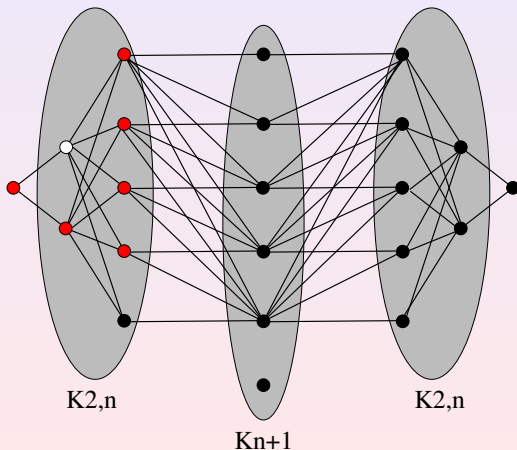
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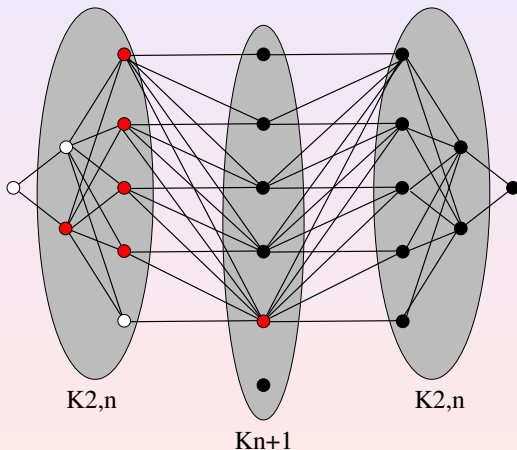


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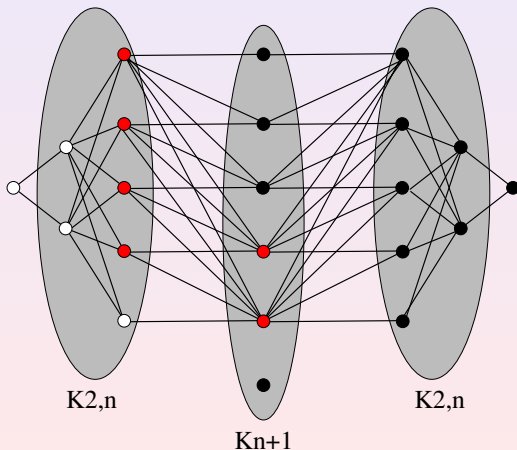


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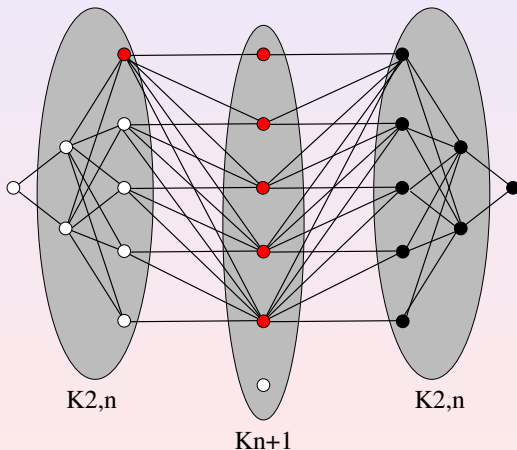


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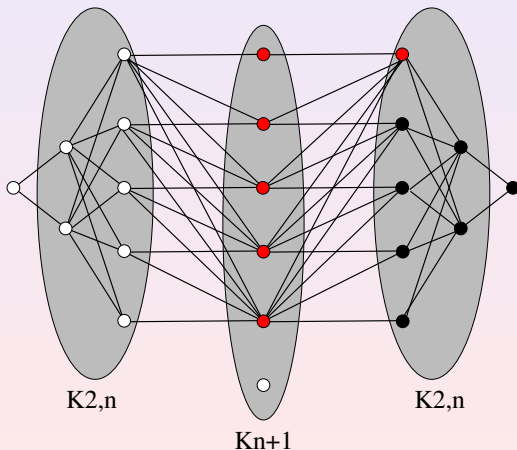


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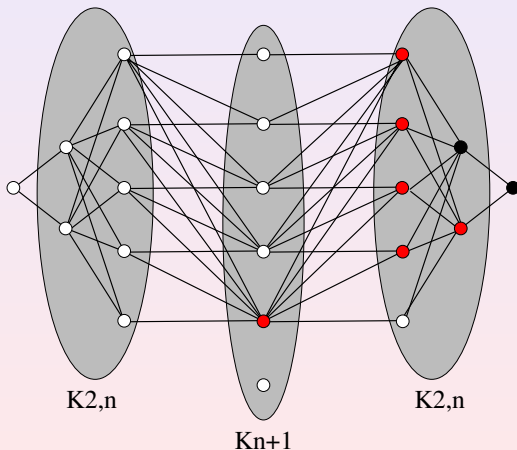


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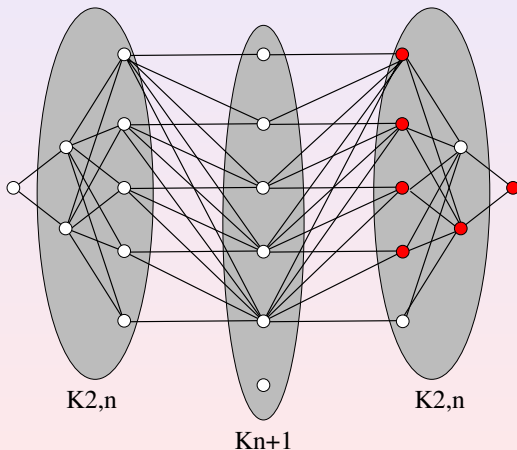


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$$mfvs(D) = n + 4$$

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$$mfvs_{pn}(D) = 3n + 2$$

Some open questions

A lot of "bad" news... No tradeoff ?

Can we restrict the class of dependancy digraphs ?

No... even if the physical network is a directed path...

Conjecture

Let G be a symmetric directed/undirected graph,

$$\lambda = \frac{mfvs_{pn}(G)}{mfvs(G)} \leq 3$$

- Approximation and Heuristic algorithms for these parameters
Link between random walks and separators of graphs ?

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Merci