# Graph Theory and Optimization Weighted Graphs Shortest Paths & Spanning Trees

Nicolas Nisse

Université Côte d'Azur, Inria, CNRS, I3S, France

October 2018









Kruskal Algorithm

### Outline



- Weighted Graphs, distance
- 2 Shortest paths and Spanning trees
- Breadth First Search (BFS)
- 4 Dijkstra Algorithm
- 5 Kruskal Algorithm

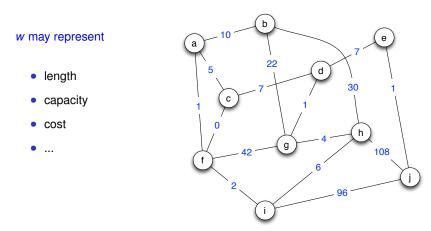






# Weighted graphs (length/capacity/cost/distance)

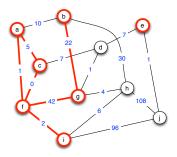
Let G = (V, E) be a graph, we can assign a weight to the edges  $w : E \to \mathbb{R}^+$ 





#### Weighted graphs

## (length/capacity/cost/distance)



• weigth of subgraph *H*: 
$$w(H) = \sum_{e \in E(H)} w(e)$$
 ex:  $w(H) = 72$ 



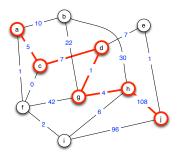




## Weighted graphs

# (length/capacity/cost/distance)

Innia



- weigth of subgraph *H*:  $w(H) = \sum_{e \in E(H)} w(e)$
- length of path  $P = (v_1, \dots, v_\ell)$ :  $w(P) = \sum_{e \in E(P)^*} w(e) = \sum_{1 \le i < \ell} w(\{v_i, v_{i+1}\})$ sum of weights of edges of Pex: w(P) = 125

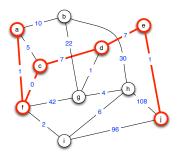
COATI

\* a path  $P = (v_1, \cdots, v_\ell)$  is seen as the subgraph  $P = (\{v_1, \cdots, v_\ell\}, \{\{v_i, v_{i+1}\} \mid 1 \le i < \ell\})$ 



## Weighted graphs

# (length/capacity/cost/distance)



- weigth of subgraph *H*:  $w(H) = \sum_{e \in E(H)} w(e)$
- length of path  $P = (v_1, \dots, v_\ell)$ :  $w(P) = \sum_{e \in E(P)} w(e) = \sum_{1 \le i < \ell} w(\{v_i, v_{i+1}\})$ sum of weights of edges of P
- <u>distance</u> dist(x, y): minimum length of a path from  $x \in V$  to  $y \in V$ . ex: dist(a, j) = 16

COATI



Kruskal Algorithm

## Outline



- Weighted Graphs, distance
- 2 Shortest paths and Spanning trees
- Breadth First Search (BFS)
- 4 Dijkstra Algorithm
- 5 Kruskal Algorithm







# Weighted graphs: two important questions

- Computing distances and shortest paths
  - Breadth First Search (BFS) (unweighted graph, i.e., weights= 1)
  - Dijkstra's algorithm (1956)
  - Bellman-Ford algorithm (1958)
     handle negative weights

**Applications:** GPS, routing in the Internet, basis of many algorithms...

You think it is easy?









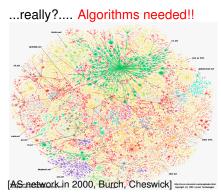
# Weighted graphs: two important questions

- Computing distances and shortest paths
  - Breadth First Search (BFS) (unweighted graph, i.e., weights=1)
  - Dijkstra's algorithm (1956)
  - Bellman-Ford algorithm (1958)
     handle negative weights

**Applications:** GPS, routing in the Internet, basis of many algorithms...

COATI





Graph Theory and applications 5/16

nría



# Weighted graphs: two important questions

- Computing distances and shortest paths
  - Breadth First Search (BFS) (unweighted graph, i.e., weights= 1)
  - Dijkstra's algorithm (1956)
  - Bellman-Ford algorithm (1958)
     handle negative weights

**Applications:** GPS, routing in the Internet, basis of many algorithms...

Computing minimum spanning trees

**Goal:** given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum

• Borůvska (1926), Kruskal (1956), Prim (1957)

#### **Applications:**

Minimum (cheapest) substructure (subgraph) preserving connectivity. ex: "first published by Borůvska as a method of constructing an efficient electricity network" (Wikipedia)









Kruskal Algorithm

## Outline

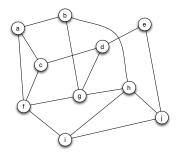


- Weighted Graphs, distance
- 2 Shortest paths and Spanning trees
- Breadth First Search (BFS)
- 4 Dijkstra Algorithm
- 5 Kruskal Algorithm





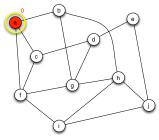










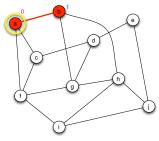


ToBeExplored=(a)







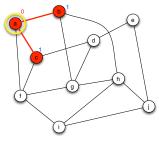


ToBeExplored=(a,b)







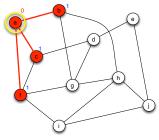


ToBeExplored=(a,b,c)







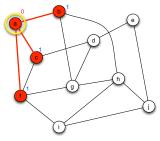


ToBeExplored=(a,b,c,f)







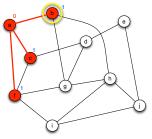


ToBeExplored=(b,c,f)







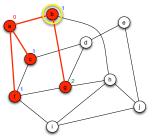


ToBeExplored=(b,c,f)







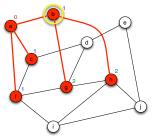


ToBeExplored=(b,c,f,g)







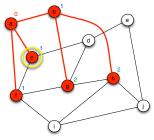


ToBeExplored=(b,c,f,g,h)







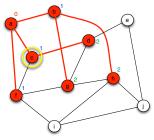


ToBeExplored=(c,f,g,h)







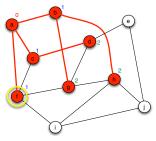


ToBeExplored=(c,f,g,h,d)







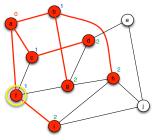


ToBeExplored=(f,g,h,d)







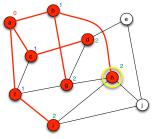


ToBeExplored=(f,g,h,d,i)









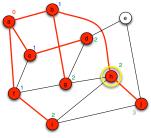
ToBeExplored=(h,d,i)







In unweighted graph, length of path P = # of edges of P = |E(P)|

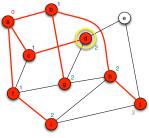


ToBeExplored=(h,d,i,j)









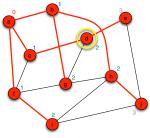
ToBeExplored=(d,i,j)







In unweighted graph, length of path P = # of edges of P = |E(P)|



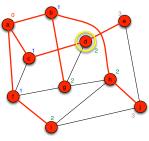
ToBeExplored=(d,i,j,e)







In unweighted graph, length of path P = # of edges of P = |E(P)|



ToBeExplored=(d,i,j,e)

Breadth First Search **input:** unweighted graph G = (V, E) and  $r \in V$ **Initially:** d(r) = 0, ToBeExplored = (r)Done =  $\emptyset$  and  $T = (V(T), E(T)) = (\{r\}, \emptyset)$ While ToBeExplored  $\neq \emptyset$  do Let v = head (ToBeExplored) for  $u \in N(v) \setminus (ToBeExplored \cup Done)$  do  $d(u) \leftarrow d(v) + 1$ add u in V(T) and  $\{v, u\}$  in E(T)add u at the end of ToBeExplored remove v from ToBeExplored, add v to Done

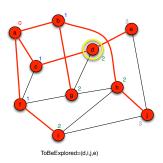




Breadth First Search (BFS

h (BFS) Dijkstra Alge

#### BFS: Connectivity and distances in unweighted graphs In unweighted graph, length of path P = # of edges of P = |E(P)|



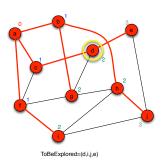
**Breadth First Search input:** unweighted graph G = (V, E) and  $r \in V$ **Initially:** d(r) = 0, ToBeExplored = (r)Done =  $\emptyset$  and  $T = (V(T), E(T)) = (\{r\}, \emptyset)$ While ToBeExplored  $\neq \emptyset$  do Let v = head (ToBeExplored) for  $u \in N(v) \setminus (ToBeExplored \cup Done)$  do  $d(u) \leftarrow d(v) + 1$ add u in V(T) and  $\{v, u\}$  in E(T)add u at the end of ToBeExplored remove v from ToBeExplored, add v to Done

**Output:** for any  $v \in V$ , d(v) = dist(r, v).

*T* is a shortest path tree of *G* rooted in *r*: i.e., *T* spanning subtree of *G* s.t. for any  $v \in V$ , the path from *r* to *v* in *T* is a shortest path from *r* to *v* in *G*. Graph Theory and applications 7/16

N. Nisse

#### BFS: Connectivity and distances in unweighted graphs In unweighted graph, length of path P = # of edges of P = |E(P)|



**Breadth First Search input:** unweighted graph G = (V, E) and  $r \in V$ **Initially:** d(r) = 0, ToBeExplored = (r)Done =  $\emptyset$  and  $T = (V(T), E(T)) = (\{r\}, \emptyset)$ While ToBeExplored  $\neq \emptyset$  do Let v = head (ToBeExplored) for  $u \in N(v) \setminus (ToBeExplored \cup Done)$  do  $d(u) \leftarrow d(v) + 1$ add u in V(T) and  $\{v, u\}$  in E(T)add u at the end of ToBeExplored remove v from ToBeExplored, add v to Done

Inría

**Time-Complexity:** # operations = O(|E|)

\_**i2**5

each edge is considered

Graph Theory and applications 7/16

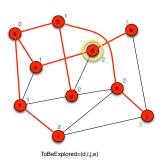
Exercise: Give an algorithm that decides if a graph is connected Horestei Ner seine erstenen

COATI

Breadth First Search (BFS

h (BFS) Dijkstra Alg

#### BFS: Connectivity and distances in unweighted graphs In unweighted graph, length of path P = # of edges of P = |E(P)|



**Breadth First Search input:** unweighted graph G = (V, E) and  $r \in V$ **Initially:** d(r) = 0, ToBeExplored = (r)Done =  $\emptyset$  and  $T = (V(T), E(T)) = (\{r\}, \emptyset)$ While ToBeExplored  $\neq \emptyset$  do Let v = head (ToBeExplored) for  $u \in N(v) \setminus (ToBeExplored \cup Done)$  do  $d(u) \leftarrow d(v) + 1$ add u in V(T) and  $\{v, u\}$  in E(T)add u at the end of ToBeExplored remove v from ToBeExplored, add v to Done

 Time-Complexity: # operations = O(|E|) each edge is considered

 Rmk1: allows to decide whether G is connected
 G connected iff dist(r, v) <  $\infty$  defined for all  $v \in V$  

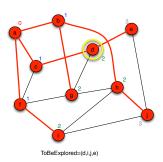
 G connected iff dist(r, v) <  $\infty$  defined for all  $v \in V$  

 Graph Theory and applications 7/16

Breadth First Search (BFS

arch (BFS) Dijkstra

#### BFS: Connectivity and distances in unweighted graphs In unweighted graph, length of path P = # of edges of P = |E(P)|



**Breadth First Search input:** unweighted graph G = (V, E) and  $r \in V$ **Initially:** d(r) = 0, ToBeExplored = (r)Done =  $\emptyset$  and  $T = (V(T), E(T)) = (\{r\}, \emptyset)$ While ToBeExplored  $\neq \emptyset$  do Let v = head (ToBeExplored) for  $u \in N(v) \setminus (ToBeExplored \cup Done)$  do  $d(u) \leftarrow d(v) + 1$ add u in V(T) and  $\{v, u\}$  in E(T)add u at the end of ToBeExplored remove v from ToBeExplored, add v to Done

**Time-Complexity:** # operations = O(|E|) each edge is considered **Rmk2:** gives only one shortest path tree, may be more...

depends on the ordering in which vertices are considered Graph Theory and applications 7/16 Graph Theory and applications 7/16

Diameter of a graph *G*: maximum distance between two vertices of *G*.  $diam(G) = \max_{u,v \in V(G)} dist(u,v)$ 

Exercise: Give an algorithm that computes the diameter of a graph.

What is the number of operations?







Diameter of a graph *G*: maximum distance between two vertices of *G*.  $diam(G) = \max_{u,v \in V(G)} dist(u,v)$ 

Exercise: Give an algorithm that computes the diameter of a graph.

What is the number of operations?

#### Exercise: What does this algorithm computes??

**input:** unweighted tree T = (V, E) and  $r \in V$ 

- Execute a BFS rooted in r
- Let u be a node maximizing the distance from r
- Execute a BFS rooted in u
- Let w be a node maximizing the distance from u

return dist(u, w)

What is the number of operations?









Breadth First Search (BF

nría

#### **Diameter of trees**

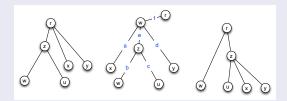
#### Theorem: Previous algorithm computes the diameter of T

Termination: two executions of BFS

**Correctness:** *u* is a leaf (otherwise, there would be a vertex further from *r*) Similarly, *w* is a leaf For contradiction, assume that diam(T) = dist(x, y) > dist(u, w)

(x and y must be leaves)

Several Cases:



As an example, consider the second one (from the left)  $f + e + c \ge \max\{f + a; f + e + b; f + d\}$  (*u* further from *r*)  $b \ge \max\{e + a; e + f; e + d\}$  (*w* further from *u*) So  $dist(u, w) = b + c \ge a + d = dist(x, y)$ , a contradiction

COATI



### Outline



- Weighted Graphs, distance
- 2 Shortest paths and Spanning trees
- Breadth First Search (BFS)
- 4 Dijkstra Algorithm
- 5 Kruskal Algorithm





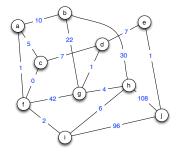


#### Dijkstra's algorithm

## (required positive weights)

BFS algorithm does not work in weighted graphs

Exercise: Example?



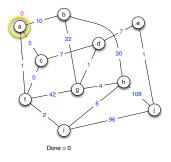






## Dijkstra's algorithm

## (required positive weights)



Dijkstra

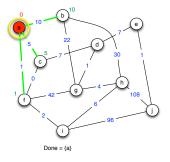
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

# (required positive weights)



Dijkstra

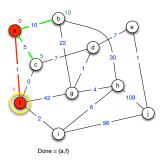
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

## (required positive weights)



#### Dijkstra

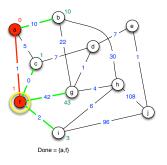
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

# (required positive weights)



Dijkstra

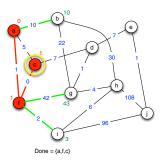
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





#### Dijkstra's algorithm

## (required positive weights)



Dijkstra

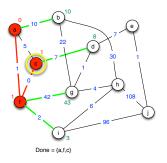
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

# (required positive weights)



Dijkstra

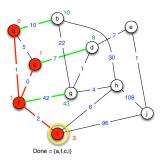
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

## (required positive weights)



#### Dijkstra

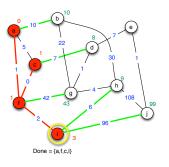
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

## (required positive weights)



Dijkstra

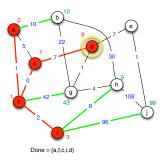
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

## (required positive weights)



Dijkstra

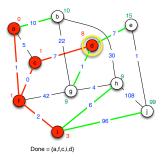
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

## (required positive weights)



Dijkstra

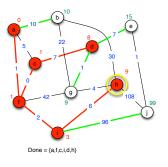
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





### Dijkstra's algorithm

## (required positive weights)



#### Dijkstra

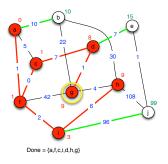
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





### Dijkstra's algorithm

## (required positive weights)



Dijkstra

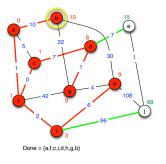
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

## (required positive weights)



Dijkstra

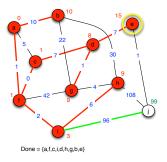
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

# (required positive weights)



#### Dijkstra

input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,

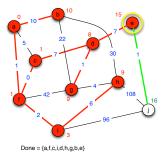




#### iskal Algorithm

## Dijkstra's algorithm

# (required positive weights)



#### Dijkstra

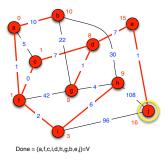
input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,





## Dijkstra's algorithm

# (required positive weights)



Dijkstra

input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,

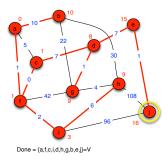




## Dijkstra's algorithm

## (required positive weights)

Dijkstra



#### input: graph G = (V, E), weight w, and $r \in V$ Initially: d(r) = 0, $(V_T, E_T) = (\emptyset, \emptyset)$ , $Done = \emptyset$ , and $\forall v \in V \setminus \{r\} d(v) = \infty$ , parent(v) = $\emptyset$ While Done $\neq$ V do Let $v \in V \setminus Done$ with d(v) minimum \* Add v in $V_T$ and $\{v, parent(v)\}$ in $E_T$ Add v in Done for $u \in N(v) \setminus Done$ do if $d(u) > d(v) + w(\{u, v\})$ then $d(u) \leftarrow d(v) + w(\{u, v\})$ parent(u) $\leftarrow v$

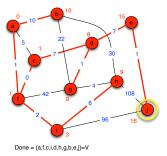






### Dijkstra's algorithm

## (required positive weights)



#### Dijkstra

input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} d(v) = \infty$ , parent(v) =  $\emptyset$ While  $Done \neq V$  do Let  $v \in V \setminus Done$  with d(v) minimum \* Add v in  $V_T$  and  $\{v, parent(v)\}$  in  $E_T$ Add v in Done for  $u \in N(v) \setminus Done$  do if  $d(u) > d(v) + w(\{u, v\})$  then  $d(u) \leftarrow d(v) + w(\{u, v\})$ parent(u)  $\leftarrow v$ 

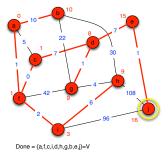
**Output:**  $\forall v \in V$ , d(v) = dist(r, v), *T* is a shortest path tree of *G* rooted in *r* **Time-complexity:**  $O(|E| + |V| \log |V|)$  (requires sorting \*)





### Dijkstra's algorithm

## (required positive weights)



#### Dijkstra

input: graph G = (V, E), weight w, and  $r \in V$ Initially: d(r) = 0,  $(V_T, E_T) = (\emptyset, \emptyset)$ ,  $Done = \emptyset$ , and  $\forall v \in V \setminus \{r\} \ d(v) = \infty$ ,  $parent(v) = \emptyset$ While  $Done \neq V$  do Let  $v \in V \setminus Done$  with d(v) minimum \* Add v in  $V_T$  and  $\{v, parent(v)\}$  in  $E_T$ Add v in Donefor  $u \in N(v) \setminus Done$  do if  $d(u) > d(v) + w(\{u, v\})$  then  $d(u) \leftarrow d(v) + w(\{u, v\})$ 

**Output:**  $\forall v \in V$ , d(v) = dist(r, v), *T* is a shortest path tree of *G* rooted in *r* **proof:** since *w* positive  $\Rightarrow$  a subpath of a shortest path is a a shortest path





parent(u)  $\leftarrow v$ 

## Dijkstra's algorithm

# Proof of correctness

Termination: After *i*<sup>th</sup> iteration of *while* loop, |Done| = i, then the algorithm terminates in |V| iterations of *while* loop Correctness: By induction on  $1 \le i < |V|$ , after the *i*<sup>th</sup> iteration of *while* loop, |Done| = i, and  $\forall v \in Done$ , d(v) = dist(r, v). ok for i = 0

Assume the hypothesis holds ater the *i*<sup>th</sup> iteration. Let  $v \in V \setminus Done$  be chosen at the (i + 1)<sup>th</sup> iteration.

- By minimality of d(v) (in V \ Done),
   if G connected, then d(v) < ∞ and Done ∩ N(v) ≠ Ø, and</li>
   d(v) = min<sub>u∈Done∩N(v)</sub> d(u) + w({u, v}) by induction: d(v) ≥ dist(v, r)
- For contradiction, assume that d(v) < dist(v, r): there is a shortest path P = (r, ..., x, v) of length < d.</li>
  - *x* ∈ *Done*: otherwise it would contradict minimality of *d*(*v*)
  - $dist(v,r) = dist(x,r) + w(\{x,v\}) = d(x) + w(\{x,v\}) < d(v) = min_{u \in Done \cap N(v)} d(u) + w(\{u,v\}) \le d(x) + w(\{x,v\})$

a contradiction





### Outline



- Weighted Graphs, distance
- 2 Shortest paths and Spanning trees
- Breadth First Search (BFS)
- 4 Dijkstra Algorithm
- 5 Kruskal Algorithm

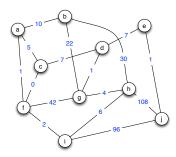






## Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



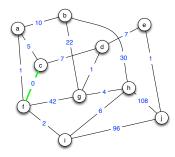






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



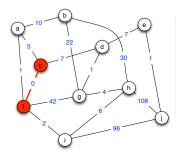
**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 





# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree T of G with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \leq m$  **do** 

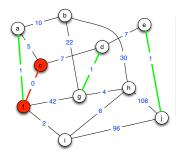






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



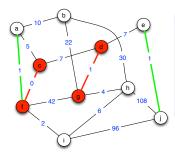
**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 





# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



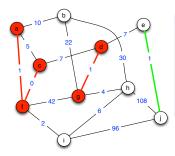
**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \leq m$  **do** 





# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



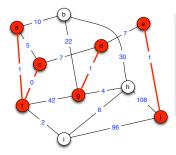
**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \leq m$  **do** 





# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 

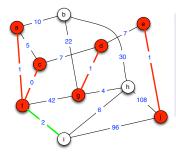






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 

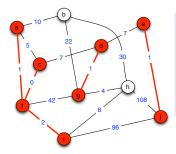






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 

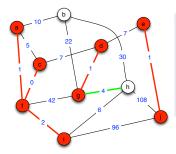






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 

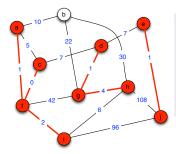






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \leq m$  **do** 

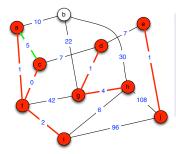






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree T of G with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 

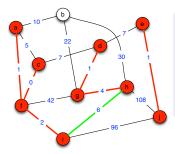






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



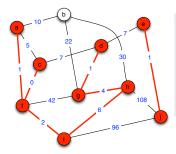
**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \leq m$  **do** 





# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \leq m$  **do** 

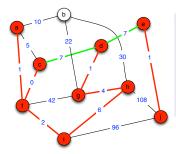






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



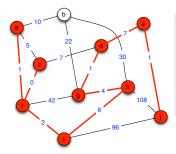
**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \leq m$  **do** 





# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 

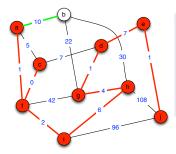






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \leq m$  **do** 

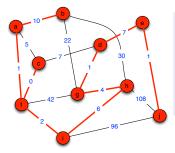






# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree *T* of *G* with w(T) minimum



**Kruskal input:** connected graph G = (V, E), weight *w*  **Initially:** Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ **For**  $i \le m$  **do** 



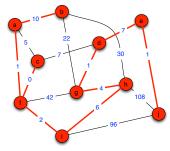




## Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ Compute a spanning tree T of G with w(T) minimum

COATI



Kruskal input: connected graph G = (V, E), weight wInitially: Let  $(e_1, \dots, e_m)$  be an ordering of E in non decreasing ordering of w, and  $T = (\emptyset, \emptyset)$ For  $i \le m$  do Add  $e_i$  in T if it does not create a cycle.

ría

**Time-Complexity:** # operations =  $O(|E|\log|E|)$ 

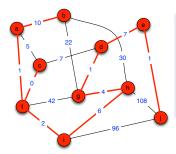
sorting



# Minimum Spanning Tree

*Reminder:* given G = (V, E) with weight  $w : E \to \mathbb{R}$ 

Compute a spanning tree T of G with w(T) minimum



#### Kruskal

input: connected graph G = (V, E), weight *w* Initially: Let  $(e_1, \dots, e_m)$  be an ordering of *E* in non decreasing ordering of *w*, and  $T = (\emptyset, \emptyset)$ For  $i \le m$  do Add  $e_i$  in *T* if it does not create a cycle.

nía

Graph Theory and applications 14/16

**Exercise:** Prove that, *T* returned by the Alg. is a minimum spanning tree *Idea of proof: by contradiction* 

COATI

## Proof of correctness

Terminaison: obvious

Correctness: (Sketch) Clearly, T is a spanning tree (it is acyclic by definition, and if it is not connected, some edges connecting the components should have been added)

Assume it is not minimum and let  $(e_1, \dots, e_{n-1})$  be its edges in non decreasing ordering of their weights.

Among the min. spanning tree of *G*, let  $T^*$  with edges  $(f_1, \dots, f_{n-1})$  such that the minimum index *i* with  $e_i \neq f_i$  is maximized.

 $T^* \cup e_i$  contains a cycle *C* and, there is j > i such that  $f_j \in E(C) \setminus E(T)$  and  $w(f_j) \le w(e_i)$  (otw,  $T^*$  is not minimum).

- if  $w(f_j) < w(e_i)$  then the algorithm should have chosen  $f_j$  instead of  $e_i$
- if  $w(f_j) = w(e_i)$ , T' obtained from  $T^*$  by replacing  $f_j$  by  $e_i$  is a minimum spanning tree, contradicting the maximality of *i*.





## Summary: To be remembered

- weighted graph, distances
- Deciding connectivity Shortest path tree in undirected graph O(|E|), BF
- Computing Shortest path tree
- Computing Min. spanning tree

h O(|E|), BFS $O(|E| + |V| \log |V|), Dijkstra$  $O(|E| \log |E|), Kruskal$ 







