Advanced Logic

http://www-sop.inria.fr/members/Martin.Avanzini/teaching/2023/AL/

Martin Avanzini (martin.avanzini@inria.fr)
Etienne Lozes (etienne.lozes@univ-cotedazur.fr)



2nd Semester M1, 2023

Last Lecture

- * a language $L \subseteq \Sigma^{\omega}$ is ω -regular if $L = \bigcup_{0 \le i \le n} U_i \cdot V_i^{\omega}$ for regular languages U_i, V_i $(0 \le i \le n)$
- * a Büchi Automaton is structurally similar to an NFA, but recognizes words $w \in \Sigma^{\infty}$ that visit final states infinitely often

Theorem

For recognisable $U \in \Sigma^*$ and $V, W \in \Sigma^{\omega}$ the following are recognisable:

- 1. union $V \cup W$ 4. ω -iteration U^{ω}
- 2. intersection $V \cap W$ 5. complement \overline{V}
- 3. left-concatenation $U \cdot V$

Theorem

$$L \in \omega REG(\Sigma)$$
 if and only if $L = L(A)$ for some NBA A

Theorem

For every MSO formula ϕ there exists an NBA A_{ϕ} s.t. $\hat{L}(\phi) = L(A_{\phi})$.

/ MIVIASTER

Today's Lecture

- 1. Linear temporal logic (LTL)
- 2. LTL model checking

Linear temporal logic



Motivation

- ★ linear temporal logic is a logic for reasoning about events in time
 - always not $(\phi \wedge \psi)$

liveness

safety

always (Request implies eventually Grant)

liveness

- always (Request implies (Request until Grant))
- ★ LTL shares algorithmic solutions with MSO



★ the set of LTL formulas over propositions $\mathcal{P} = \{p, q, \dots\}$ is given by

$$\phi, \psi ::= \rho \mid \phi \lor \psi \mid \neg \phi$$
$$\mid X \phi \mid \phi \cup \psi$$

(Propositional Formulas)

(Next and Until)

★ the set of LTL formulas over propositions $\mathcal{P} = \{p, q, \dots\}$ is given by

$$\phi, \psi ::= p \mid \phi \lor \psi \mid \neg \phi \qquad \qquad (Propositional Formulas)$$
$$\mid X \phi \mid \phi \cup \psi \qquad \qquad (Next and Until)$$

★ LTL is a logic of temporal sequences, modeled as infinite words over $\Sigma \triangleq 2^{\mathcal{P}}$



★ the set of LTL formulas over propositions $P = \{p, q, ...\}$ is given by

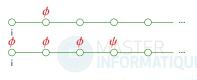
$$\phi, \psi ::= p \mid \phi \lor \psi \mid \neg \phi \qquad \qquad (Propositional \ Formulas)$$

$$\mid X \phi \mid \phi \cup \psi \qquad \qquad (Next \ and \ Until)$$

- ★ LTL is a logic of temporal sequences, modeled as infinite words over $\Sigma \triangleq 2^{\mathcal{P}}$
- \star for a sentence ϕ and $w = P_0 P_1 P_2 \dots$, we define $w \models \phi$ as w, $0 \models \phi$ where

$$w; i \models p$$
 : $\Leftrightarrow p \in P_i$
 $w; i \models \phi \lor \psi$: $\Leftrightarrow w; i \models \phi \text{ or } w; i \models \psi$
 $w; i \models \neg \phi$: $\Leftrightarrow w; i \not\models \phi$
 $w, i \models X \phi$: $\Leftrightarrow w; i + 1 \models \phi$
 $w; i \models \phi \cup \psi$: $\Leftrightarrow \text{ exists } k \ge i \text{ s.t. } w; k \models \phi$
and $w; j \models \psi \text{ for all } i \le j < k$





* the set of LTL formulas over propositions $\mathcal{P} = \{p, q, \dots\}$ is given by

$$\phi, \psi ::= p \mid \phi \lor \psi \mid \neg \phi \qquad \qquad (Propositional Formulas)$$
$$\mid X \phi \mid \phi \cup \psi \qquad \qquad (Next and Until)$$

- ★ LTL is a logic of temporal sequences, modeled as infinite words over $\Sigma \triangleq 2^{\mathcal{P}}$
- \star for a sentence ϕ and $w = P_0 P_1 P_2 \dots$, we define $w \models \phi$ as w, $0 \models \phi$ where

$$w; i \models p \qquad :\Leftrightarrow p \in P_i$$

$$w; i \models \phi \lor \psi \qquad :\Leftrightarrow w; i \models \phi \text{ or } w; i \models \psi$$

$$w; i \models \neg \phi \qquad :\Leftrightarrow w; i \not\models \phi$$

$$w, i \models X \phi \qquad :\Leftrightarrow w; i + 1 \models \phi$$

$$w; i \models \phi \lor \psi \qquad :\Leftrightarrow \text{ exists } k \ge i \text{ s.t. } w; k \models \phi$$

$$\text{and } w; j \models \psi \text{ for all } i \le j < k$$

* a LTL formula ϕ defines the language $L(\phi) \triangleq \{w \mid w \models \phi\}$

Derived Operators and Positive Normal Forms ____

finally: $F\phi$: \Leftrightarrow $T \cup \phi$

globally: $G \phi : \Leftrightarrow \neg (F \neg \phi)$

release: $\phi \ \mathsf{R} \ \psi \ :\Leftrightarrow \ \neg (\neg \phi \ \mathsf{U} \ \neg \psi)$

Derived Operators and Positive Normal Forms ____

 \star F ϕ , G ϕ and X ϕ are sometimes denoted by $\diamond \phi$, $\Box \phi$ and $\circ \phi$, respectively



Derived Operators and Positive Normal Forms _____

- \star F ϕ , G ϕ and X ϕ are sometimes denoted by $\diamond \phi$, $\Box \phi$ and $\circ \phi$, respectively
- \star a formula ϕ is in positive normal form (PNF) if it is derived from the following grammar:

$$\phi, \psi ::= \rho \quad | \quad \neg \rho \quad | \quad \phi \land \psi \quad | \quad \phi \lor \psi \quad | \quad X \phi \quad | \quad \phi \lor \psi \quad | \quad \phi R \psi$$

negation only in front of literals



Derived Operators and Positive Normal Forms ____

- \star F ϕ , G ϕ and X ϕ are sometimes denoted by $\diamond \phi$, $\Box \phi$ and $\circ \phi$, respectively
- \star a formula ϕ is in positive normal form (PNF) if it is derived from the following grammar:

$$\phi, \psi ::= \rho \quad | \quad \neg \rho \quad | \quad \phi \land \psi \quad | \quad \phi \lor \psi \quad | \quad \mathsf{X} \phi \quad | \quad \phi \ \mathsf{U} \ \psi \quad | \quad \phi \ \mathsf{R} \ \psi$$

negation only in front of literals



Lemma

Every formula ϕ can be turned into an equivalent formula ψ in PNF with $|\psi| \le 2|\phi|$

Safety = something bad never happens = $G \neg \phi_{bad}$

 ${\color{red}\mathsf{Safety}} = \mathsf{something} \,\, \mathsf{bad} \,\, \mathsf{never} \,\, \mathsf{happens} = \quad \mathsf{G} \, \neg \phi_{\mathsf{bad}}$



- ★ a ...A train is approaching
- ★ c ...A train is crossing
- ★ | ...The light is blinking
- ★ b ... The barrier is down



Safety = something bad never happens = $G \neg \phi_{bad}$



- ★ a ...A train is approaching
- ★ c ...A train is crossing
- ★ | ...The light is blinking
- ★ b ...The barrier is down
- ★ when a train is crossing, the barrier is down:



Safety = something bad never happens = $G \neg \phi_{bad}$



- ★ a ...A train is approaching
- ★ c ...A train is crossing
- ★ | ...The light is blinking
- ★ b ...The barrier is down
- ★ when a train is crossing, the barrier is down:

$$G(c \rightarrow b) \equiv G \neg (c \land \neg b)$$



Safety = something bad never happens = $G \neg \phi_{bad}$

Example



- ★ a ... A train is approaching
- ★ c ...A train is crossing
- ★ | ...The light is blinking
- ★ b ...The barrier is down
- ★ when a train is crossing, the barrier is down:

$$G(c \rightarrow b) \equiv G \neg (c \land \neg b)$$

★ if a train is approaching or crossing, the light must be blinking:



Safety = something bad never happens = $G \neg \phi_{bad}$

Example



- ★ a ...A train is approaching
- ★ c ...A train is crossing
- ★ | ...The light is blinking
- ★ b ...The barrier is down
- ★ when a train is crossing, the barrier is down:

$$G(c \rightarrow b) \equiv G \neg (c \land \neg b)$$

★ if a train is approaching or crossing, the light must be blinking:

$$G(a \lor c \rightarrow I) \equiv G \neg ((a \lor c) \land \neg I)$$



Safety = something bad never happens = $G \neg \phi_{bad}$

Example



- ★ a ...A train is approaching
- ★ c ...A train is crossing
- ★ | ...The light is blinking
- ★ b ...The barrier is down
- ★ when a train is crossing, the barrier is down:

$$G(c \rightarrow b) \equiv G \neg (c \land \neg b)$$

★ if a train is approaching or crossing, the light must be blinking:

$$G(a \lor c \rightarrow I) \equiv G \neg ((a \lor c) \land \neg I)$$

★ if the barrier is up and the light is off, no train is approaching or crossing: FORMATIQUE

Safety = something bad never happens = $G \neg \phi_{bad}$

Example



- ★ a ...A train is approaching
- ★ c ...A train is crossing
- ★ | ...The light is blinking
- ★ b ...The barrier is down
- ★ when a train is crossing, the barrier is down:

$$G(c \rightarrow b) \equiv G \neg (c \land \neg b)$$

★ if a train is approaching or crossing, the light must be blinking:

$$G(a \lor c \rightarrow I) \equiv G \neg ((a \lor c) \land \neg I)$$

★ if the barrier is up and the light is off, no train is approaching or crossing: FORMATIQUE

$$G(\neg b \land \neg l \rightarrow \neg a \land \neg c) \equiv G \neg (\neg b \land \neg l \land (a \lor c))^{RSITE COTE}$$

Liveness = something intiated eventually terminates = $G(\phi_{init} \rightarrow F \phi_{term})$

Liveness = something intiated eventually terminates = $G(\phi_{init} \rightarrow F\phi_{term})$

★ approaching trains eventually cross:



Liveness = something intiated eventually terminates = $G(\phi_{init} \rightarrow F \phi_{term})$

★ approaching trains eventually cross:

$$G(a \rightarrow Fc)$$



Liveness = something intiated eventually terminates = $G(\phi_{init} \rightarrow F \phi_{term})$

★ approaching trains eventually cross:

$$G(a \rightarrow Fc)$$

★ when a train is approaching, the barrier is down before it crosses:



Liveness = something intiated eventually terminates = $G(\phi_{init} \rightarrow F \phi_{term})$

★ approaching trains eventually cross:

$$G(a \rightarrow Fc)$$

★ when a train is approaching, the barrier is down before it crosses:

$$G(a \rightarrow \neg c U b)$$



Liveness = something intiated eventually terminates = $G(\phi_{init} \rightarrow F \phi_{term})$

★ approaching trains eventually cross:

$$G(a \rightarrow Fc)$$

★ when a train is approaching, the barrier is down before it crosses:

$$G(a \rightarrow \neg c U b)$$

★ if a train finished crossing, the barrier will be eventually risen



Liveness = something intiated eventually terminates = $G(\phi_{init} \rightarrow F\phi_{term})$

★ approaching trains eventually cross:

$$G(a \rightarrow Fc)$$

★ when a train is approaching, the barrier is down before it crosses:

$$G(a \rightarrow \neg c U b)$$

★ if a train finished crossing, the barrier will be eventually risen

$$G(c \land X \neg c \rightarrow X F \neg b)$$



Characterising LTL

- **★** LTL can be "expressed" within MSO ≡ Büchi Automata
- ★ MSO and Büchi Automata are strictly more expressive

LTL recognisability $< \omega$ -regular

- ★ LTL most naturally translated to alternating Büchi Automata (ABA)
- ★ loop-free (very weak) ABA characterise precisely the class of LTL recognisable languages



Characterising LTL

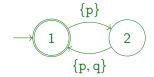
- **★** LTL can be "expressed" within MSO ≡ Büchi Automata
- ★ MSO and Büchi Automata are strictly more expressive

LTL recognisability $< \omega$ -regular

- ★ LTL most naturally translated to alternating Büchi Automata (ABA)
- ★ loop-free (very weak) ABA characterise precisely the class of LTL recognisable languages

Example

the Büchi Automaton \mathcal{A} over $\mathcal{P} = \{p, q\}$ given by



MASTER INFORMATIQUE

is not loop-free (and cannot be turned into equivalent loop-free one) $\Rightarrow L(A)$ not expressible in LTL

(Very Weak) Alternating Büchi Automata ___

- * an alternating Büchi Automaton (ABA) is a tuple $\mathcal{A} = (Q, \Sigma, q_l, \delta, F)$ identical to an AFA
- \star execution on words $w \in \Sigma^{\omega}$ are now infinite tree T_w
- \star an execution is accepting in the sense of Büchi: every path visits F infinitely often
- ★ $L(A) \triangleq \{w \in \Sigma^{\omega} \mid \text{there exist an accepting execution } T_w \text{ for } w\}$



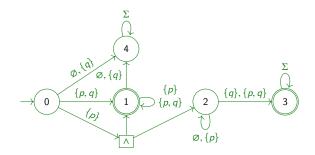
(Very Weak) Alternating Büchi Automata

- * an alternating Büchi Automaton (ABA) is a tuple $\mathcal{A} = (Q, \Sigma, q_l, \delta, F)$ identical to an AFA
- ★ execution on words $w \in \Sigma^{\omega}$ are now infinite tree T_w
- \star an execution is accepting in the sense of Büchi: every path visits F infinitely often
- ★ $L(A) \triangleq \{w \in \Sigma^{\omega} \mid \text{there exist an accepting execution } T_w \text{ for } w\}$
- * very weak ABA (VWABA) is an ABA if for every $a \in \Sigma$, $\stackrel{a}{\longrightarrow} \subseteq \subseteq I$ for some linear order $I \subseteq I$ $I \subseteq I$ for every $I \subseteq I$ $I \subseteq I$ for every $I \subseteq I$ f



(Very Weak) Alternating Büchi Automata

- * an alternating Büchi Automaton (ABA) is a tuple $\mathcal{A} = (Q, \Sigma, q_l, \delta, F)$ identical to an AFA
- \star execution on words $w \in \Sigma^{\omega}$ are now infinite tree T_w
- \star an execution is accepting in the sense of Büchi: every path visits F infinitely often
- ★ $L(A) \triangleq \{w \in \Sigma^{\omega} \mid \text{there exist an accepting execution } T_w \text{ for } w\}$
- * very weak ABA (VWABA) is an ABA if for every $a \in \Sigma$, $\stackrel{a}{\longrightarrow} \subseteq \subseteq$ for some linear order $\subseteq \subseteq Q \times Q$





LTL and Automata

Theorem

Let L be a language over $\Sigma = 2^{\mathcal{P}}$. The following are equivalent:

- * L is LTL definable.
- ★ L is recognizable by VWABA.



From Automata to LTL

fix a VWABA $\mathcal{A} = (\{q_0, \dots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$ where wlog. $q_0 > q_1 > \dots > q_n$

From Automata to LTL

fix a VWABA $\mathcal{A} = (\{q_0, \dots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$ where wlog. $q_0 > q_1 > \dots > q_n$

★ since A is very weak, there are transitions from q_i to q_i only if $i \ge j$

fix a VWABA $\mathcal{A} = (\{q_0, \dots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$ where wlog. $q_0 > q_1 > \dots > q_n$

- ★ since A is very weak, there are transitions from q_i to q_j only if $i \ge j$
- * we now associate each state q_i with a formula ϕ_i s.t.

$$\mathsf{L}(\phi_i) = \mathsf{L}_{\mathcal{A}}(q_i)$$



fix a VWABA $\mathcal{A} = (\{q_0, \dots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$ where wlog. $q_0 > q_1 > \dots > q_n$

- ★ since A is very weak, there are transitions from q_i to q_j only if $i \ge j$
- * we now associate each state q_i with a formula ϕ_i s.t.

$$\mathsf{L}(\phi_i) = \mathsf{L}_{\mathcal{A}}(q_i)$$

* this can be done inductively: while construction ϕ_i , we already have suitable formulas ϕ_j for i > j



fix a VWABA $\mathcal{A} = (\{q_0, \dots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$ where wlog. $q_0 > q_1 > \dots > q_n$

- ★ since A is very weak, there are transitions from q_i to q_j only if $i \ge j$
- * we now associate each state q_i with a formula ϕ_i s.t.

$$\mathsf{L}(\phi_i) = \mathsf{L}_{\mathcal{A}}(q_i)$$

- * this can be done inductively: while construction ϕ_i , we already have suitable formulas ϕ_j for i > j
- ★ for propositions $P \subseteq \mathcal{P}$, the construction uses the characteristic function

$$\chi_P \triangleq \left(\bigwedge_{p \in P} p \right) \land \left(\bigwedge_{p \notin P} \neg p \right)$$



fix a VWABA $\mathcal{A} = (\{q_0, \dots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$ where wlog. $q_0 > q_1 > \dots > q_n$

- ★ since A is very weak, there are transitions from q_i to q_j only if $i \ge j$
- * we now associate each state q_i with a formula ϕ_i s.t.

$$\mathsf{L}(\phi_i) = \mathsf{L}_{\mathcal{A}}(q_i)$$

- * this can be done inductively: while construction ϕ_i , we already have suitable formulas ϕ_j for i > j
- ★ for propositions $P \subseteq \mathcal{P}$, the construction uses the characteristic function

$$\chi_P \triangleq \left(\bigwedge_{p \in P} p \right) \land \left(\bigwedge_{p \notin P} \neg p \right)$$

* the construction differs whether the state is final, we thus consider two cases



From Automata to LTL (II)

fix a VWABA
$$\mathcal{A} = (\{q_0, \dots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$$
 where wlog. $q_0 > q_1 > \dots > q_n$

 \star informally, ϕ_i should satisfy

$$\phi_i \equiv \bigvee_{P \subseteq \mathcal{P}} \chi_P \wedge X \left(\delta(q_i, P) [q_i / \phi_i, q_{i+1} / \phi_{i+1} \dots, q_n / \phi_n] \right)$$

- ★ to get rid of the "recursive definition", we distinguish two cases:
 - − if $q_i \notin F$ then we rewrite the right-hand side as $\psi \lor (\rho \land X \phi_i)$ and set

$$\phi_i \triangleq \rho \cup \psi$$

− if $q_i ∈ F$ then we rewrite the right-hand side as $\psi \land (\rho \lor X \phi_i)$ and set

$$\phi_i \triangleq \mathsf{G}\psi \vee (\psi \cup (\rho \wedge \psi))$$



the ABA \mathcal{A}_{ϕ} for a PNF formula ϕ is given by $(Q, 2^{\mathcal{P}}, \phi, \delta, F)$ where

 $\star \ \ Q \triangleq \{\top, \bot\} \cup \{q_{\psi} \mid \psi \text{ occurs as sub-formula in } \phi\}$

the ABA \mathcal{A}_{ϕ} for a PNF formula ϕ is given by $(Q, 2^{\mathcal{P}}, \phi, \delta, F)$ where

- $\star \ \ Q \triangleq \{\top, \bot\} \cup \{q_{\psi} \mid \psi \text{ occurs as sub-formula in } \phi\}$
- * the transition function $\delta: Q \times 2^{\mathcal{P}} \to \mathbb{B}^+(Q)$ is given by

$$\delta(\top, P) \triangleq \top \quad \delta(\bot, P) \triangleq \bot \quad \delta(q_p, P) \triangleq \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases} \quad \delta(q_{\neg p}, P) \triangleq \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$
$$\delta(q_{\psi_1 \land \psi_2}, P) \triangleq \delta(q_{\psi_1}, P) \land \delta(q_{\psi_2}, P) \quad \delta(q_{\psi_2}, P) \triangleq \delta(q_{\psi_1}, P) \lor \delta(q_{\psi_2}, P)$$

$$\begin{split} &\delta(q_{X\psi},P)\triangleq q_{\psi}\\ &\delta(q_{\psi_{1}\cup\psi_{2}},P)\triangleq\delta(q_{\psi_{2}},P)\vee(\delta(q_{\psi_{1}},P)\wedge q_{\psi_{1}\cup\psi_{2}})\\ &\delta(q_{\psi_{1}\mathsf{R}\psi_{2}},P)\triangleq\delta(q_{\psi_{2}},P)\wedge(\delta(q_{\psi_{1}},P)\vee q_{\psi_{1}\mathsf{R}\psi_{2}}) \end{split}$$



the ABA \mathcal{A}_{ϕ} for a PNF formula ϕ is given by $(Q, 2^{\mathcal{P}}, \phi, \delta, F)$ where

- $\star \ \ Q \triangleq \{\top, \bot\} \cup \{q_{\psi} \mid \psi \text{ occurs as sub-formula in } \phi\}$
- * the transition function $\delta: Q \times 2^{\mathcal{P}} \to \mathbb{B}^+(Q)$ is given by

$$\delta(\top, P) \triangleq \top \quad \delta(\bot, P) \triangleq \bot \quad \delta(q_p, P) \triangleq \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases} \quad \delta(q_{\neg p}, P) \triangleq \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$
$$\delta(q_{\psi_1 \land \psi_2}, P) \triangleq \delta(q_{\psi_1}, P) \land \delta(q_{\psi_2}, P) \quad \delta(q_{\psi_1 \lor \psi_2}, P) \triangleq \delta(q_{\psi_1}, P) \lor \delta(q_{\psi_2}, P)$$

$$\delta(q_{X\psi}, P) \triangleq q_{\psi}$$

$$\delta(q_{\psi_{1} \cup \psi_{2}}, P) \triangleq \delta(q_{\psi_{2}}, P) \vee (\delta(q_{\psi_{1}}, P) \wedge q_{\psi_{1} \cup \psi_{2}})$$

$$\delta(q_{\psi_{1} R \psi_{2}}, P) \triangleq \delta(q_{\psi_{2}}, P) \wedge (\delta(q_{\psi_{1}}, P) \vee q_{\psi_{1} R \psi_{2}})$$

★ the only final states are \top and $q_{\psi_1 R \psi_2} \in Q$



the ABA \mathcal{A}_{ϕ} for a PNF formula ϕ is given by $(Q, 2^{\mathcal{P}}, \phi, \delta, F)$ where

- ★ $Q \triangleq \{\top, \bot\} \cup \{q_{\psi} \mid \psi \text{ occurs as sub-formula in } \phi\}$
- ★ the transition function $\delta: Q \times 2^{\mathcal{P}} \to \mathbb{B}^+(Q)$ is given by

$$\delta(\top, P) \triangleq \top \quad \delta(\bot, P) \triangleq \bot \quad \delta(q_p, P) \triangleq \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases} \quad \delta(q_{\neg p}, P) \triangleq \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$
$$\delta(q_{\psi_1 \land \psi_2}, P) \triangleq \delta(q_{\psi_1}, P) \land \delta(q_{\psi_2}, P) \quad \delta(q_{\psi_2}, P) \triangleq \delta(q_{\psi_1}, P) \lor \delta(q_{\psi_2}, P)$$

$$\delta(q_{X\psi}, P) \triangleq q_{\psi}$$

$$\delta(q_{\psi_1 \cup \psi_2}, P) \triangleq \delta(q_{\psi_2}, P) \vee (\delta(q_{\psi_1}, P) \wedge q_{\psi_1 \cup \psi_2})$$

$$\delta(q_{\psi_1 R \psi_2}, P) \triangleq \delta(q_{\psi_2}, P) \wedge (\delta(q_{\psi_1}, P) \vee q_{\psi_1 R \psi_2})$$

★ the only final states are \top and $q_{\psi_1 R \psi_2} \in Q$

Notes

- \star \mathcal{A}_{ϕ} is linear in size in $|\phi|$
- * using the construction for AFAs, this ABA can be transformed to an NBA of size $O(2^{|\phi|})$



consider $\phi = G p \land F q \equiv ((p \land \neg p) R p) \land ((p \lor \neg p) U q)$



$$\begin{aligned} & \text{consider } \phi = \mathsf{G} \, p \wedge \mathsf{F} \, q \equiv ((p \wedge \neg p) \, \mathsf{R} \, p) \wedge ((p \vee \neg p) \, \mathsf{U} \, q) \\ & \delta(q_p, P) = \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases} \\ & \delta(q_{\neg p}, P) = \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$



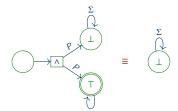
consider
$$\phi = G p \wedge F q \equiv ((p \wedge \neg p) R p) \wedge ((p \vee \neg p) U q)$$

$$\delta(q_p, P) = \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{\neg p}, P) = \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$

$$\delta(q_{p \land \neg p}, P) = \delta(q_p, P) \land \delta(q_{\neg p}, P) = \top \land \bot \approx \bot$$

$$\delta(q_{p \lor \neg p}, P) = \delta(q_p, P) \lor \delta(q_{\neg p}, P) = \bot \lor \top \approx \top$$





consider
$$\phi = G p \wedge F q \equiv ((p \wedge \neg p) R p) \wedge ((p \vee \neg p) U q)$$

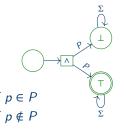
$$\delta(q_p, P) = \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{\neg p}, P) = \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$

$$\delta(q_{p \land \neg p}, P) = \delta(q_p, P) \land \delta(q_{\neg p}, P) = \top \land \bot \approx \bot$$

$$\delta(q_{p \lor \neg p}, P) = \delta(q_p, P) \lor \delta(q_{\neg p}, P) = \bot \lor \top \approx \top$$

$$\delta(q_{(p \wedge \neg p) R p}, P) = \delta(p, P) \wedge (\delta(q_{p \wedge \neg p}, P) \vee q_{(p \wedge \neg p) R p}) \approx \begin{cases} q_{(p \wedge \neg p) R p} & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$





consider
$$\phi = G p \wedge F q \equiv ((p \wedge \neg p) R p) \wedge ((p \vee \neg p) U q)$$

$$\delta(q_{p}, P) = \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{\neg p}, P) = \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$

$$\delta(q_{p \land \neg p}, P) = \delta(q_{p}, P) \land \delta(q_{\neg p}, P) = \top \land \bot \approx \bot$$

$$\delta(q_{p \lor \neg p}, P) = \delta(q_{p}, P) \lor \delta(q_{\neg p}, P) = \bot \lor \top \approx \top$$

$$\delta(q_{(p \land \neg p)Rp}, P) = \delta(p, P) \land (\delta(q_{p \land \neg p}, P) \lor q_{(p \land \neg p)Rp}) \approx \begin{cases} q_{(p \land \neg p)Rp} & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{(p \land \neg p) R p}, P) = \delta(p, P) \land (\delta(q_{p \land \neg p}, P) \lor q_{(p \land \neg p) R p}) \approx \begin{cases} 1 & \text{if } p \notin P \\ 1 & \text{if } p \notin P \end{cases}$$

$$\delta(q_{(p \lor \neg p) \lor q}, P) = \delta(q, P) \lor (\delta(q_{p \lor \neg p}, P) \land q_{(p \lor \neg p) R q}) \approx \begin{cases} 1 & \text{if } q \in P \\ 1 & \text{if } q \notin P \end{cases}$$



$$\mathsf{consider}\ \phi = \mathsf{G}\ p \land \mathsf{F}\ q \equiv ((p \land \neg p)\ \mathsf{R}\ p) \land ((p \lor \neg p)\ \mathsf{U}\ q)$$

$$\delta(q_p, P) = \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{\neg p}, P) = \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$

$$\delta(q_{p \land \neg p}, P) = \delta(q_p, P) \land \delta(q_{\neg p}, P) = \top \land \bot \approx \bot$$

$$\delta(q_{p \lor \neg p}, P) = \delta(q_p, P) \lor \delta(q_{\neg p}, P) = \bot \lor \top \approx \top$$

$$\delta(q_{(p \wedge \neg p) R p}, P) = \delta(p, P) \wedge (\delta(q_{p \wedge \neg p}, P) \vee q_{(p \wedge \neg p) R p}) \approx \begin{cases} q_{(p \wedge \neg p) R p} & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{(p\vee \neg p)\cup q},P)=\delta(q,P)\vee(\delta(q_{p\vee \neg p},P)\wedge q_{(p\vee \neg p)\mathsf{R}q})\approx \begin{cases} \top &\text{if }q\in P\\ q_{(p\vee \neg p)\cup q} &\text{if }q\notin P \end{cases}$$

$$\delta(\phi, P) = \delta(q_{(p \land \neg p) R p}, P) \land \delta(q_{(p \lor \neg p) U q}, P) \approx \begin{cases} \bot & \text{if } P = \emptyset \\ q_{(p \land \neg p) R p} \land q_{(p \lor \neg p) U q} & \text{if } P = \{p\} & \bot \\ \downarrow q_{(p \land \neg p) R p} & \text{if } P = \{q\} & \bot \end{cases}$$

$$UNIV \text{if } P = \{p, q\} \land P = \{p, q\}$$

consider
$$\phi = G p \wedge F q \equiv ((p \wedge \neg p) R p) \wedge ((p \vee \neg p) U q)$$

$$\delta(q_{p}, P) = \begin{cases} T & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{\neg p}, P) = \begin{cases} \bot & \text{if } p \in P \\ T & \text{if } p \notin P \end{cases}$$

$$\delta(q_{p \wedge \neg p}, P) = \delta(q_{p}, P) \wedge \delta(q_{\neg p}, P) = T \wedge \bot \approx \bot$$

$$\delta(q_{p \vee \neg p}, P) = \delta(q_{p}, P) \vee \delta(q_{\neg p}, P) = \bot \vee T \approx T$$

$$\delta(q_{p \wedge \neg p}, P) = \delta(p, P) \wedge (\delta(q_{p \wedge \neg p}, P) \vee q_{(p \wedge \neg p) R p}) \approx \begin{cases} q_{(p \wedge \neg p) R p} & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{(p \wedge \neg p)Rp}, P) = \delta(p, P) \wedge (\delta(q_{p \wedge \neg p}, P) \vee q_{(p \wedge \neg p)Rp}) \approx \begin{cases} q_{(p \wedge \neg p)Rp} & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases}$$

$$\delta(q_{(p \vee \neg p)Uq}, P) = \delta(q, P) \vee (\delta(q_{p \vee \neg p}, P) \wedge q_{(p \vee \neg p)Rq}) \approx \begin{cases} \top & \text{if } q \in P \\ q_{(p \vee \neg p)Uq} & \text{if } q \notin P \end{cases}$$

$$\delta(\phi, P) = \delta(q_{(p \wedge \neg p)Rp}, P) \wedge \delta(q_{(p \vee \neg p)Uq}, P) \approx \begin{cases} \bot & \text{if } P = \emptyset \\ q_{(p \wedge \neg p)Rp} \wedge q_{(p \vee \neg p)Uq} & \text{if } P \neq \{p\} \mid P \} \\ \bot & \text{if } P = \{q\} \end{cases}$$

$$UNV \text{if } P = \{p, q\} \text{ AZUR}$$

Model Checking



- ★ transition systems capture evolution of state based programs etc.
- ★ they can be seen as finite representations of potentially infinitely many program runs



- ★ transition systems capture evolution of state based programs etc.
- ★ they can be seen as finite representations of potentially infinitely many program runs
- ★ a transition system (TR) is a tuple $S = (S, \rightarrow, s_l, \lambda)$ where
 - 1. *S* is a set of states
 - 2. $\rightarrow \subseteq S \times S$ is a transition relation
 - 3. $s_i \in S$ is an initial state
 - 4. $\lambda: S \to 2^{\mathcal{P}}$ a labeling of states by propositions \mathcal{P}



- ★ transition systems capture evolution of state based programs etc.
- ★ they can be seen as finite representations of potentially infinitely many program runs
- ★ a transition system (TR) is a tuple $S = (S, \rightarrow, s_l, \lambda)$ where
 - 1. *S* is a set of states
 - 2. $\rightarrow \subseteq S \times S$ is a transition relation
 - 3. $s_i \in S$ is an initial state
 - 4. $\lambda: S \to 2^{\mathcal{P}}$ a labeling of states by propositions \mathcal{P}
- ★ we assume S is total, i.e. every node has a successor: $\forall s \in S. \exists t \in S. s \rightarrow t$



- ★ transition systems capture evolution of state based programs etc.
- ★ they can be seen as finite representations of potentially infinitely many program runs
- ★ a transition system (TR) is a tuple $S = (S, \rightarrow, s_l, \lambda)$ where
 - 1. *S* is a set of states
 - 2. $\rightarrow \subseteq S \times S$ is a transition relation
 - 3. $s_i \in S$ is an initial state
 - 4. $\lambda: S \to 2^{\mathcal{P}}$ a labeling of states by propositions \mathcal{P}
- ★ we assume S is total, i.e. every node has a successor: $\forall s \in S. \exists t \in S. s \rightarrow t$
- * a run in a total TS is an infinite word $w = P_0 P_1 P_2 \dots$ such that $\lambda(s_i) = P_i$ for an infinite path

$$s_I = s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$$



- ★ transition systems capture evolution of state based programs etc.
- ★ they can be seen as finite representations of potentially infinitely many program runs
- ★ a transition system (TR) is a tuple $S = (S, \rightarrow, s_l, \lambda)$ where
 - 1. *S* is a set of states
 - 2. $\rightarrow \subseteq S \times S$ is a transition relation
 - 3. $s_i \in S$ is an initial state
 - 4. $\lambda: S \to 2^{\mathcal{P}}$ a labeling of states by propositions \mathcal{P}
- ★ we assume S is total, i.e. every node has a successor: $\forall s \in S. \exists t \in S. s \rightarrow t$
- * a run in a total TS is an infinite word $w = P_0 P_1 P_2 \dots$ such that $\lambda(s_i) = P_i$ for an infinite path

$$s_I=s_0\to s_1\to s_2\to \cdots$$

★ $L(S) \triangleq \{w \mid w \text{ is a run in } S\}$ is the set of all runs



We are interested in the following decision problem:

- ★ Given: An TS $S = (S, \rightarrow, s_I, \lambda)$ and specification as LTL formula ϕ
- ★ Question: $L(S) \subseteq L(\phi)$?

We are interested in the following decision problem:

- \star Given: An TS $S = (S, \rightarrow, s_l, \lambda)$ and specification as LTL formula ϕ
- ★ Question: $L(S) \subseteq L(\phi)$?

Theorem

The above model checking problem is decidable in time $O(|S|^2) \cdot 2^{O(|\phi|)}$

We are interested in the following decision problem:

- \star Given: An TS $\mathcal{S} = (S, \rightarrow, s_l, \lambda)$ and specification as LTL formula ϕ
- ★ Question: $L(S) \subseteq L(\phi)$?

Theorem

The above model checking problem is decidable in time $O(|S|^2) \cdot 2^{O(|\phi|)}$

* let
$$\mathcal{A}_{\neg \phi} = (Q, 2^{\mathcal{P}}, q_l, \delta, F)$$
 be the NBA with $L(\neg \phi) = L(\mathcal{A}_{\neg \phi})$ of size $2^{O(|\phi|)}$

We are interested in the following decision problem:

- \star Given: An TS $S = (S, \rightarrow, s_l, \lambda)$ and specification as LTL formula ϕ
- ★ Question: $L(S) \subseteq L(\phi)$?

Theorem

The above model checking problem is decidable in time $O(|S|^2) \cdot 2^{O(|\phi|)}$

- * let $\mathcal{A}_{\neg \phi} = (Q, 2^{\mathcal{P}}, q_I, \delta, F)$ be the NBA with $L(\neg \phi) = L(\mathcal{A}_{\neg \phi})$ of size $2^{O(|\phi|)}$
- * define the NBA $S \otimes A_{\neg \phi} \triangleq (S \times Q, \{\bullet\}, (s_l, q_l), \Delta, S \times F)$ where

$$\Delta((s,q),\bullet) \triangleq \{(s',q') \mid s \to s' \text{ and } q' \in \delta(q,\lambda(s))\}$$

We are interested in the following decision problem:

- \star Given: An TS $S = (S, \rightarrow, s_l, \lambda)$ and specification as LTL formula ϕ
- ★ Question: $L(S) \subseteq L(\phi)$?

Theorem

The above model checking problem is decidable in time $O(|S|^2) \cdot 2^{O(|\phi|)}$

- * let $\mathcal{A}_{\neg \phi} = (Q, 2^{\mathcal{P}}, q_I, \delta, F)$ be the NBA with $L(\neg \phi) = L(\mathcal{A}_{\neg \phi})$ of size $2^{O(|\phi|)}$
- \star define the NBA $S \otimes A_{\neg \phi} \triangleq (S \times Q, \{\bullet\}, (s_l, q_l), \Delta, S \times F)$ where

$$\Delta((s,q), \bullet) \triangleq \{(s',q') \mid s \to s' \text{ and } q' \in \delta(q,\lambda(s))\}$$

$$\star \ \, \mathsf{then} \, \, \mathsf{L}(\mathcal{S}) \subseteq \mathsf{L}(\phi) \quad \Longleftrightarrow \quad \mathsf{L}(\mathcal{S}) \cap \mathsf{L}(\neg \phi) = \varnothing \quad \Longleftrightarrow \quad \mathsf{L}(\mathcal{S} \otimes \mathcal{A}_{\neg \, \phi}) = \varnothing$$

We are interested in the following decision problem:

- \star Given: An TS $S = (S, \rightarrow, s_l, \lambda)$ and specification as LTL formula ϕ
- ★ Question: $L(S) \subseteq L(\phi)$?

Theorem

The above model checking problem is decidable in time $O(|S|^2) \cdot 2^{O(|\phi|)}$

- * let $\mathcal{A}_{\neg \phi} = (Q, 2^{\mathcal{P}}, q_l, \delta, F)$ be the NBA with $L(\neg \phi) = L(\mathcal{A}_{\neg \phi})$ of size $2^{O(|\phi|)}$
- \star define the NBA $S \otimes A_{\neg \phi} \triangleq (S \times Q, \{\bullet\}, (s_l, q_l), \Delta, S \times F)$ where

$$\Delta((s,q),\bullet) \triangleq \{(s',q') \mid s \to s' \text{ and } q' \in \delta(q,\lambda(s))\}$$

- $\star \ \, \mathsf{then} \, \, \mathsf{L}(\mathcal{S}) \subseteq \mathsf{L}(\phi) \quad \Longleftrightarrow \quad \mathsf{L}(\mathcal{S}) \cap \mathsf{L}(\neg \phi) = \varnothing \quad \Longleftrightarrow \quad \mathsf{L}(\mathcal{S} \otimes \mathcal{A}_{\neg \phi}) = \varnothing$
- $\star \text{ emptyness of } \mathcal{S} \otimes \mathcal{A}_{\neg \phi} \text{ is decidable in time linear in } |\mathcal{S} \otimes \mathcal{A}_{\neg \phi}| \in \mathrm{O}(|\mathcal{S}|^2) \cdot 2^{\mathrm{O}(|\phi|)}$

Explicit Model Checking: each automaton node is an individual state

★ SPIN model checker: http://spinroot.com/

Symbolic Model Checking: each automaton node represents a set of state, symbolically

* SMV model checker: http://www.cs.cmu.edu/~modelcheck/smv.html



Explicit Model Checking: each automaton node is an individual state

★ SPIN model checker: http://spinroot.com/

Symbolic Model Checking: each automaton node represents a set of state, symbolically

* SMV model checker: http://www.cs.cmu.edu/~modelcheck/smv.html

they have been successfully applied in industrial contexts (see e.g. http://spinroot.com/spin/success.html)



Explicit Model Checking: each automaton node is an individual state

★ SPIN model checker: http://spinroot.com/

Symbolic Model Checking: each automaton node represents a set of state, symbolically

* SMV model checker: http://www.cs.cmu.edu/~modelcheck/smv.html

they have been successfully applied in industrial contexts (see e.g. http://spinroot.com/spin/success.html)

Main Challenge

 while real problems have a finite number of states, we deal with an astronmoical number of cases



Explicit Model Checking: each automaton node is an individual state

★ SPIN model checker: http://spinroot.com/

Symbolic Model Checking: each automaton node represents a set of state, symbolically

* SMV model checker: http://www.cs.cmu.edu/~modelcheck/smv.html

they have been successfully applied in industrial contexts (see e.g. http://spinroot.com/spin/success.html)

Main Challenge

- ★ while real problems have a finite number of states, we deal with an astronmoical number of cases
- * industrial-strength tools such as the ones above generate $\mathcal{S} \otimes \mathcal{A}_{\neg \phi}$ on-the-fly and implement several techniques to combat state-space explosion
 - partial order reduction: detects when an ordering of interleavings is irrelevant. E.g., the n! transitions of n concurrently executing processes is reduced to 1 representative transition, when ordering irrelevant for property under investigation
 - − Bounded Model Checking: check that ϕ is violated in ≤ k steps

Thanks!

