Advanced Logic

http://www-sop.inria.fr/members/Martin.Avanzini/teaching/2021/AL/

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Summer Semester 2021

Last Lecture

- * a language $L \subseteq \Sigma^{\omega}$ is ω -regular if $L = \bigcup_{0 \le i \le n} U_i \cdot V_i^{\omega}$ for regular languages U_i, V_i $(0 \le i \le n)$
- * a Büchi Automaton is structurally similar to an NFA, but recognizes words $w \in \Sigma^{\infty}$ that visit final states infinitely often

Theorem

For recognisable $U \in \Sigma^*$ and $V, W \in \Sigma^{\omega}$ the following are recognisable:

- 1. union $V \cup W$
- 2. intersection $V \cap W$
- 3. left-concatenation $U \cdot V$

4. ω -iteration U^{ω}

5. complement \overline{V}

Theorem

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L \in \omega \mathsf{REG}(\Sigma) if and only if L = \mathsf{L}(\mathcal{A}) for some NBA \mathcal{A}
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Theorem

For every MSO formula ϕ there exists an NBA \mathcal{A}_{ϕ} s.t. $\hat{\mathsf{L}}(\phi) = \mathsf{L}(\mathcal{A}_{\phi})$.

Today's Lecture

- 1. Linear temporal logic (LTL)
- 2. LTL model checking



Linear temporal logic



Motivation

* linear temporal logic is a logic for reasoning about events in time

– always not $(\phi \land \psi)$	safety
 always (Request implies eventually Grant) 	liveness
 always (Request implies (Request until Grant)) 	liveness

 \star LTL shares algorithmic solutions with MSO



* the set of LTL formulas over propositions $\mathcal{P} = \{p, q, ...\}$ is given by

 $\phi, \psi ::= p \mid \phi \lor \psi \mid \neg \phi$ $\mid X \phi \mid \phi \cup \psi$

(Propositional Formulas)

(Next and Until)



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 $\phi, \psi ::= p | \phi \lor \psi | \neg \phi$ (Propositional Formulas) | $X \phi | \phi \cup \psi$ (Next and Until)

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- ★ LTL is a logic of temporal sequences, modeled as infinite words over $\Sigma \triangleq 2^{\mathcal{P}}$
- ★ for a sentence ϕ and $w = P_0 P_1 P_2 \dots$, we define $w \models \phi$ as w; $0 \models \phi$ where

$$w; i \models p \qquad :\Leftrightarrow \qquad p \in P_i$$

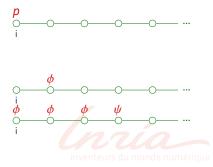
$$w; i \models \phi \lor \psi \qquad :\Leftrightarrow \qquad w; i \models \phi \text{ or } w; i \models \psi$$

$$w; i \models \neg \phi \qquad :\Leftrightarrow \qquad w; i \not\models \phi$$

$$w, i \models X \phi \qquad :\Leftrightarrow \qquad w; i + 1 \models \phi$$

$$w; i \models \phi \cup \psi \qquad :\Leftrightarrow \qquad \text{exists } k \ge i \text{ s.t. } w; k \models \phi$$

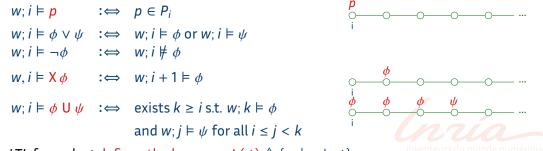
and $w; j \models \psi \text{ for all } i \le j < k$



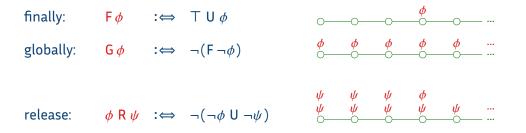
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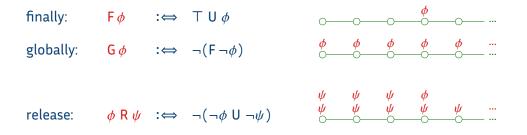
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★ a LTL formula ϕ defines the language $L(\phi) \triangleq \{w \mid w \vDash \phi\}$

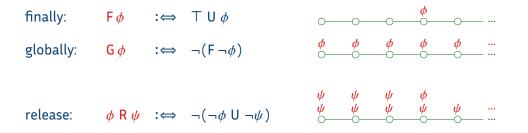






★ F ϕ , G ϕ and X ϕ are sometimes denoted by $\diamond \phi$, □ ϕ and $\circ \phi$, respectively



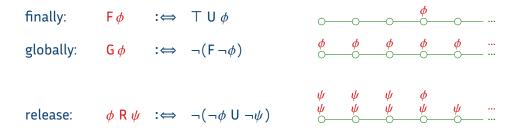


- ★ F ϕ , G ϕ and X ϕ are sometimes denoted by $\diamond \phi$, □ ϕ and $\circ \phi$, respectively
- \star a formula ϕ is in positive normal form (PNF) if it is derived from the following grammar:

$$\phi, \psi ::= p \quad | \quad \neg p \quad | \quad \phi \land \psi \quad | \quad \phi \lor \psi \quad | \quad X \phi \quad | \quad \phi \sqcup \psi \quad | \quad \phi \Vdash \psi$$

- negation only in front of literals





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Lemma

Every formula ϕ can be turned into an equivalent formula ψ in PNF with $|\psi| \leq 2|\phi|$

Safety = something bad never happens = $G \neg \phi_{bad}$



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Example



- * a ...A train is approaching
- * c ... A train is crossing
- ★ l...The light is blinking
- ★ b ...The barrier is down



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 $G(c \rightarrow b) \equiv G \neg (c \land \neg b)$



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 $G(\neg b \land \neg l \rightarrow \neg a \land \neg c) \equiv G \neg (\neg b \land \neg l \land (a \lor c))^{\text{teurs du monde numérique}}$

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★ approaching trains eventually cross:

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★ when a train is approaching, the barrier is down before it crosses:

 $G(a \rightarrow \neg c U b)$

★ if a train finished crossing, the barrier will be eventually risen

 $G(c \land X \neg c \rightarrow X F \neg b)$



Characterising LTL

- ★ LTL can be "expressed" within MSO = Büchi Automata
- ★ MSO and Büchi Automata are strictly more expressive

LTL recognisability < ω -regular

- ★ LTL most naturally translated to alternating Büchi Automata (ABA)
- * loop-free (very weak) ABA characterise precisely the class of LTL recognisable languages



Characterising LTL

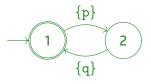
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Example

the Büchi Automaton \mathcal{A} over $\mathcal{P} = \{p, q\}$ given by



is not loop-free $\Rightarrow L(\mathcal{A})$ not expressible in LTL



(Very Weak) Alternating Büchi Automata

- * an alternating Büchi Automaton (ABA) is a tuple $\mathcal{A} = (Q, \Sigma, q_I, \delta, F)$ identical to an AFA
- ★ execution on words $w \in \Sigma^{\omega}$ are now infinite tree T_w
- ★ an execution is accepting in the sense of Büchi: every path visits *F* infinitely often
- ★ L(\mathcal{A}) ≜ { $w \in \Sigma^{\omega}$ | there exist an accepting execution T_w for w}



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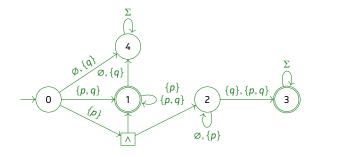
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Example





LTL and Automata

Theorem

Let L be a language over $\Sigma = 2^{\mathcal{P}}$. The following are equivalent:

- ★ L is LTL definable.
- ★ L is recognizable by VWABA.



From Automata to LTL

fix a VWABA $\mathcal{A} = (\{q_0, \ldots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$ where wlog. $q_0 > q_1 > \cdots > q_n$



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- ★ for propositions $P \subseteq P$, the construction uses the characteristic function

$$\boldsymbol{\chi}_{\boldsymbol{P}} \triangleq \left(\bigwedge_{p \in \boldsymbol{P}} \boldsymbol{p} \right) \land \left(\bigwedge_{p \notin \boldsymbol{P}} \neg \boldsymbol{p} \right)$$



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 $\star\,$ the construction differs whether the state is final, we thus consider two cases



From Automata to LTL (II)

fix a VWABA $\mathcal{A} = (\{q_0, \ldots, q_n\}, 2^{\mathcal{P}}, q_0, \delta, F)$ where wlog. $q_0 > q_1 > \cdots > q_n$

* note that $L_{\mathcal{A}}(q_i)$ satisfies

 $\mathsf{L}_{\mathcal{A}}(q_{i}) \equiv \bigvee_{P \subseteq \mathcal{P}} \chi_{P} \wedge \mathsf{X}\left(\delta(q_{i}, P)[q_{i}/\mathsf{L}_{\mathcal{A}}(q_{i}), q_{i+1}/\mathsf{L}_{\mathcal{A}}(q_{i+1}) \dots, q_{n}/\mathsf{L}_{\mathcal{A}}(q_{i})]\right)$

★ if $q_i \notin F$ then we rewrite $L_A(q_i)$ as $\psi \lor (\rho \land X L_A(q_i))$ and set

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★ if $q_i \in F$ then we rewrite $L_A(q_i)$ as $\psi \land (\rho \lor X L_A(q_i))$ and set

 $\phi_{i} \triangleq \mathsf{G}\psi \lor (\psi \mathsf{U}(\rho \land \psi))$



the ABA \mathcal{A}_{ϕ} for a PNF formula ϕ is given by $(Q, 2^{\mathcal{P}}, \phi, \delta, F)$ where $\star Q \triangleq \{\top, \bot\} \cup \{q_{\psi} \mid \psi \text{ occurs as sub-formula in } \phi\}$



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$$\delta(\top, P) \triangleq \top \quad \delta(\bot, P) \triangleq \bot \quad \delta(q_p, P) \triangleq \begin{cases} \top & \text{if } p \in P \\ \bot & \text{if } p \notin P \end{cases} \quad \delta(q_{\neg p}, P) \triangleq \begin{cases} \bot & \text{if } p \in P \\ \top & \text{if } p \notin P \end{cases}$$
$$\delta(q_{\psi_1 \land \psi_2}, P) \triangleq \delta(q_{\psi_1}, P) \land \delta(q_{\psi_2}, P) \qquad \delta(q_{\psi_1 \lor \psi_2}, P) \triangleq \delta(q_{\psi_1}, P) \lor \delta(q_{\psi_2}, P) \end{cases}$$

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$$\delta(q_{\psi_1 \cup \psi_2}, P) \triangleq \delta(q_{\psi_2}, P) \lor (\delta(q_{\psi_1}, P) \land q_{\psi_1 \cup \psi_2})$$

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 $\star\,$ the only final states are op and $q_{\psi_1 {\sf R} \psi_2} \in {\sf Q}$



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Notes

 $\star \ \mathcal{A}_{\phi}$ is linear in size in $|\phi|$

* using the construction for AFAs, this ABA can be transformed to an NBA of size $O(2^{|\phi|})^{-1}$

consider $\phi = G p \wedge F q \equiv ((p \wedge \neg p) R p) \wedge ((p \vee \neg p) U q)$

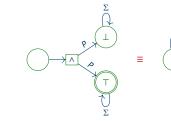


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$$\delta(q_{p \lor \neg p}, P) = \delta(q_p, P) \lor \delta(q_{\neg p}, P) = \bot \lor \top \approx \top$$





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Example _____

$$\begin{aligned} \operatorname{consider} \phi &= \operatorname{G} p \land \operatorname{F} q \equiv ((p \land \neg p) \operatorname{R} p) \land ((p \lor \neg p) \lor q) \\ \delta(q_p, P) &= \begin{cases} \top & \operatorname{if} p \in P \\ \bot & \operatorname{if} p \notin P \end{cases} \\ \delta(q_{\neg p}, P) &= \begin{cases} \bot & \operatorname{if} p \in P \\ \top & \operatorname{if} p \notin P \end{cases} \\ \delta(q_{p \land \neg p}, P) &= \delta(q_p, P) \land \delta(q_{\neg p}, P) = \top \land \bot \approx \bot \\ \delta(q_{p \lor \neg p}, P) &= \delta(q_p, P) \lor \delta(q_{\neg p}, P) = \bot \lor \top \approx \top \end{aligned} \\ \delta(q_{(p \land \neg p)\operatorname{R} p}, P) &= \delta(p, P) \land (\delta(q_{p \land \neg p}, P) \lor q_{(p \land \neg p)\operatorname{R} p}) \approx \begin{cases} q_{(p \land \neg p)\operatorname{R} p} & \operatorname{if} p \in P \\ \bot & \operatorname{if} p \notin P \end{cases} \\ \delta(q_{(p \lor \neg p)\operatorname{U} q}, P) &= \delta(q, P) \lor (\delta(q_{p \lor \neg p}, P) \lor q_{(p \land \neg p)\operatorname{R} p}) \approx \begin{cases} q_{(p \land \neg p)\operatorname{R} p} & \operatorname{if} p \in P \\ \bot & \operatorname{if} p \notin P \end{cases} \\ \delta(q_{(p \lor \neg p)\operatorname{U} q}, P) &= \delta(q, P) \lor (\delta(q_{p \lor \neg p}, P) \land q_{(p \lor \neg p)\operatorname{R} q}) \approx \begin{cases} T & \operatorname{if} q \in P \\ q_{(p \lor \neg p)\operatorname{U} q} & \operatorname{if} q \notin P \end{cases} \\ \delta(q_{(p \lor \neg p)\operatorname{U} q}, P) &= \delta(q_{(p \land \neg p)\operatorname{R} p}, P) \land \delta(q_{(p \lor \neg p)\operatorname{U} q}, P) \approx \begin{cases} \bot & \operatorname{if} P = \emptyset \\ 1 & \operatorname{if} P = \{q\} \\ q_{(p \land \neg p)\operatorname{R} p} & \operatorname{If} P = \{p, q\} \end{aligned}$$

Model Checking



- ★ transition systems capture evolution of state based programs etc.
- ★ they can be seen as finite representations of potentially infinitely many program runs



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- ★ a transition system (TR) is a tuple $S = (S, \rightarrow, s_I, \lambda)$ where
 - 1. S is a set of states
 - 2. $\rightarrow \subseteq S \times S$ is a transition relation
 - 3. $s_1 \in S$ is an initial state
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★ $L(S) \triangleq \{w \mid w \text{ is a run in } S\}$ is the set of all runs



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Theorem

The above model checking problem is decidable in time $O(|S|^2) \cdot 2^{O(|\phi|)}$

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★ emptyness of $S \otimes A_{\neg \phi}$ is decidable in time linear in $|S \otimes A_{\neg \phi}| \in O(|S|^2) \cdot 2^{O(|\phi|)}$

Explicit Model Checking: each automaton node is an individual state

* SPIN model checker: http://spinroot.com/

Symbolic Model Checking: each automaton node represents a set of state, symbolically

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Main Challenge

- while real problems have a finite number of states, we deal with an astronmoical number of cases
- * industrial-strength tools such as the ones above generate $S \otimes A_{\neg \phi}$ on-the-fly and implement several techniques to combat state-space explosion
 - partial order reduction: detects when an ordering of interleavings is irrelevant. E.g., the n! transitions of n concurrently executing processes is reduced to 1 representative transition, when ordering irrelevant for property under investigation
 - Bounded Model Checking: check that ϕ is violated in $\leq k$ steps

nventeurs du monde numérique

Thanks!

