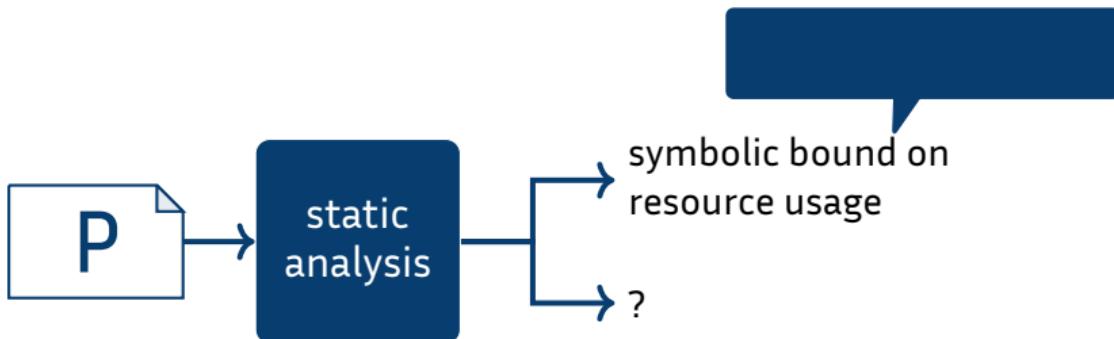


On Continuation-Passing Transformations and Expected Cost Analysis

Martin Avanzini and Gilles Barthe and Ugo Dal Lago



Static Resource Analysis



Motivations

- ★ integral part of software verification
- ★ embedded-systems
- ★ detect side-channel attacks ...
- ★ help programmers and compilers ...

Solutions

- ★ recurrence relations
- ★ type systems
- ★ term rewriting
- ★ ...

Conventional vs Probabilistic Programs

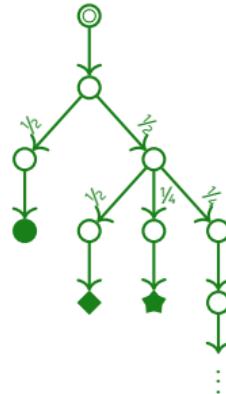
Sequential



Semantics

$$\llbracket P \rrbracket (\odot) = \bullet$$

Probabilistic



$$\llbracket P \rrbracket (\odot) = \{\bullet^{1/2}, \blacklozenge^{1/4}, \blackstar^{1/8}, \dots\}$$

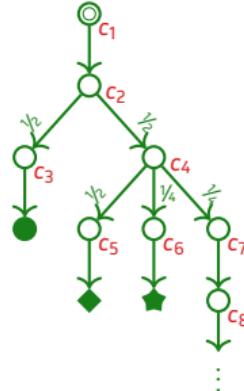
- ★ randomised algorithms
- ★ statistical inference

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Cost Analysis

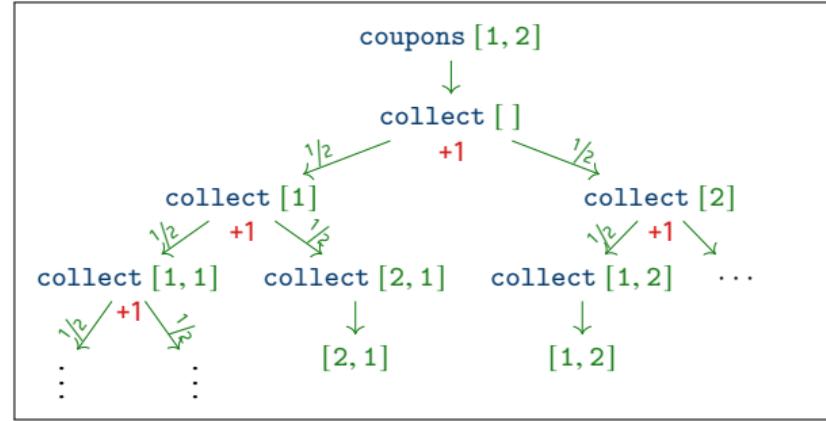
- ★ assign cost c_i to each operation
- ★ total cost of computation given by sum of all operation costs

$$cost(\odot) \stackrel{?}{\leq} b(\odot)$$

$$E[cost(\odot)] \stackrel{?}{\leq} b(\odot)$$

Example: Coupon Collector

```
coupons : [Coupons] → [Coupons]
let coupons cs =
  letrec collect os =
    if cs ⊆ os
    then os
    else collect (draw(cs) ✓ :: os)
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```



Recursion tree of `coupons [1, 2]`.

- ★ potentially non-terminating

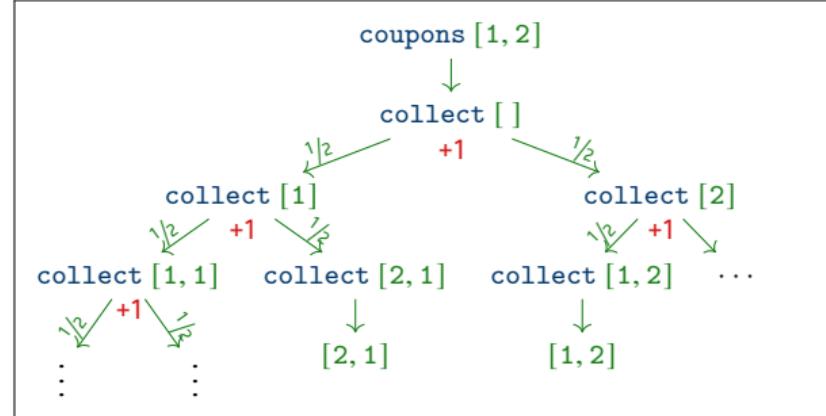
$\text{coupons } [1, 2] \rightsquigarrow \text{collect } [] \rightsquigarrow^{1/2} \text{collect } [1] \rightsquigarrow^{1/2} \text{collect } [1, 1] \rightsquigarrow^{1/2} \text{collect } [1, 1, 1] \rightsquigarrow^{1/2} \dots$

- ★ expected cost finite

$$E[\text{cost}(\text{coupons } 1)] \leq |1| \cdot \sum_{i=1}^{|1|} 1/i \in O(|1| \cdot \log(|1|))$$

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Recursion tree of `coupons [1, 2]`.

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`coupons [1, 2] ↪ collect`

How to formally derive such bounds?

- ★ expected cost finite

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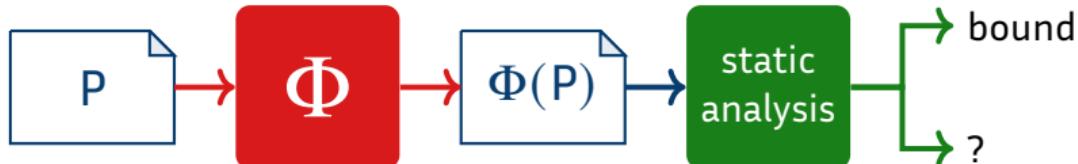
Expected Cost (Runtime) Analysis

State of the Art

ARS	<ul style="list-style-type: none">★ Lyapunov ranking functions (RF)	<u>[Bournez and Garnier'05]</u> <u>[A., Dal Lago & Yamada'19]</u>
imperative programs	<ul style="list-style-type: none">★ super martingale RF★ pre-expectation calculi & upper invariants	<u>[Chakarov and Sankaranarayanan'13]</u> <u>[Ngo et al.'18]</u> <u>[Wang et al.'19]</u> <u>[Kaminski et al.'16]</u> <u>[A., Moser & Schaper'20]</u>
functional programs	<ul style="list-style-type: none">★ type systems	<u>[A., Dal Lago & Ghyselen'19]</u> <u>[Wang, Kahn & Hoffmann'20]</u>

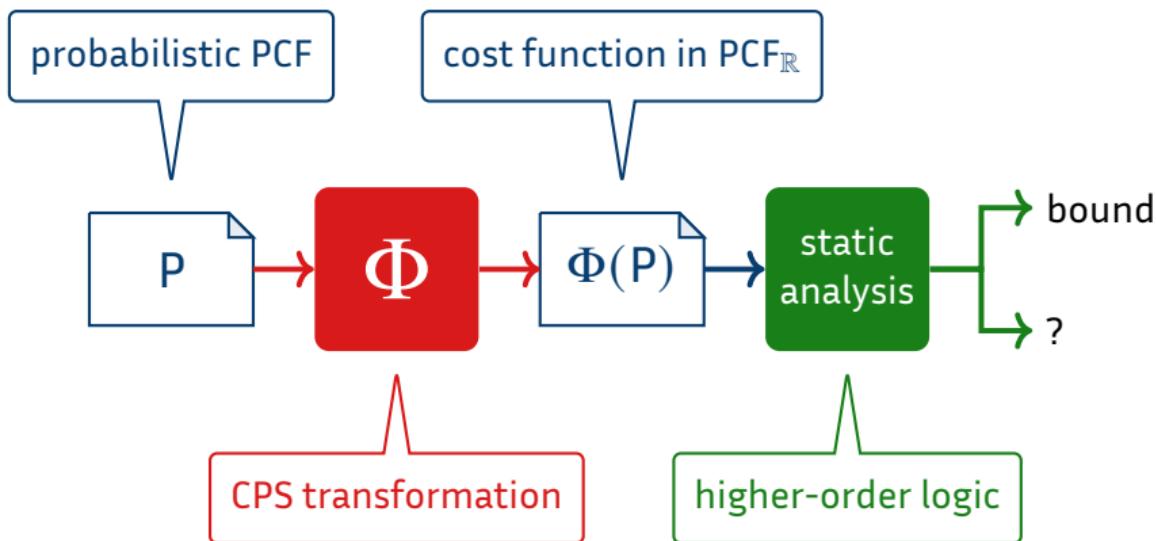
$$S \rightarrow D \implies \eta(S) \geq \text{cost}(S) + E[\eta(D)]$$

Expected Cost Analysis via Transformations



★ **Requirement:** $\text{cost}(P) \leq \text{cost}_\Phi(\Phi(P))$ (or better, $\text{cost}(P) = \text{cost}_\Phi(\Phi(P))$)

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From Programs to Cost Functions: Inspirations

1. Step-Counting Programs

[Rosendahl'89]

- $\mathcal{T}(E)$ is instrumentation of Lisp-program E with step-counter

$$[\![\mathcal{T}(E)]\!] : D^* \rightarrow (D_\perp \times \mathbb{N}^\infty)$$

- \mathbb{N}^∞ ordered "vertically", thus $(n \leq_{\mathbb{N}^\infty} m \text{ iff } n \leq m \text{ or } m = \infty)$

$$[\![\text{letrec } fx = 1 + fx]\!] = [\![\lambda x.\infty]\!] \quad \text{and} \quad [\![\text{letrec } fx = fx]\!] = [\![\lambda x.0]\!]$$

⇒ nice for modeling non-terminating computations of finite cost

⇒ no negative costs

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2. Runtime Transformers

[Kaminski et al.'16]

- expected cost of probabilistic program P context dependent

$$\mathcal{T}(\mathcal{E}[P_1 \oplus_p P_2]) = p \cdot \mathcal{T}(\mathcal{E}[P_1]) + (1 - p) \cdot \mathcal{T}(\mathcal{E}[P_2])$$

⇒ most naturally modeled in continuation passing style

$$[\![\mathcal{T}(P)]\!] : D^* \rightarrow (D \rightarrow \mathbb{R}^{+\infty}) \rightarrow \mathbb{R}^{+\infty}$$

Input Language Λ_p

pure PCF
+ constants

Types $\sigma, \tau ::= B \mid \sigma \rightarrow \tau$

Values $V, W ::= x \mid \lambda x. M \mid \text{letrec } f x = M \mid c(V_1, \dots, V_n)$

Terms $M, N ::= V$

$| M \cdot N$

$| c(M_1, \dots, M_n)$

$| \text{case } M \text{ of } \{c(x_1, \dots, x_k) \mapsto N_1 \mid y \mapsto N_2\}$

$| \text{fn}(M_1, \dots, M_n)$

$| M^\checkmark$ // cost annotation

$| d(M_1, \dots, M_n)$ // sampling primitives

Target Language $\Lambda_{\mathbb{R}}$

pure PCF
+ constants

Types $\sigma, \tau ::= B \mid \text{Real} \mid \sigma \rightarrow \tau$

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$$\frac{\Gamma; f : \sigma_1 \rightarrow \dots \rightarrow \sigma_k \rightarrow \text{Real}; \dots; x_i : \sigma_i, \dots ; \vdash M : \text{Real}}{\Gamma \vdash \text{letrec } f x_1 \dots x_k = M : \text{Real}}$$

Target Language

Semantics

- ★ term $\Gamma \vdash M : \sigma$ interpreted as continuous function

$$\llbracket M \rrbracket : [\llbracket \Gamma \rrbracket \longrightarrow \llbracket \sigma \rrbracket],$$

where, particularly,

$$\llbracket \sigma_1 \rightarrow \cdots \rightarrow \sigma_k \rightarrow \text{Real} \rrbracket = [\llbracket \sigma_1 \rrbracket \longrightarrow \cdots \longrightarrow \llbracket \sigma_k \rrbracket \longrightarrow \mathbb{R}^{+\infty}]$$

ordered pointwise by $\leq_{\mathbb{R}^{+\infty}}$, with bottom element $_ \mapsto 0$ and top element $_ \mapsto \infty$

⇒ Real-valued primitives are monotone

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⇒ Real-valued primitives are monotone

- ★ recursion well-defined by monotone convergence theorem, even if “finite result” not computed in “finite time”

$$\llbracket \text{letrec fn } x = ^1/x + \text{fn } (x+1) : \text{Nat} \rightarrow \text{Real} \rrbracket = n \mapsto$$

Expected Cost Transformer

Mapping of Types

$$B_i^\dagger \triangleq B_i$$

$$(\sigma \rightarrow \tau)^\dagger \triangleq \sigma^\dagger \rightarrow (\tau^\dagger \rightarrow \text{Real}) \rightarrow \text{Real}$$

Transformation on Values

call-by-value
one-pass CPS
[Danvy and Nielson'03]

$$x^\dagger \triangleq x$$

$$(\lambda x.M)^\dagger \triangleq \lambda x k. \text{ect}[M]\{k\}$$

$$c(\vec{V})^\dagger \triangleq c(\vec{V}^\dagger)$$

$$(\text{letrec } f x = M)^\dagger \triangleq \text{letrec } f x k = \text{ect}[M]\{k\}$$

Transformation on Terms

$$\text{ect}[\cdot]\{\cdot\} : \Lambda_p(\sigma) \rightarrow \Lambda_{\mathbb{R}}(\sigma^\dagger \rightarrow \text{Real}) \rightarrow \Lambda_{\mathbb{R}}(\text{Real})$$

$$\text{ect}[V]\{k\} \triangleq k \cdot V^\dagger$$

$$\text{ect}[M \cdot N]\{k\} \triangleq \text{ect}[N]\{\lambda z. \text{ect}[M]\{\lambda y. y \cdot z \cdot k\}\}$$

⋮

$$\text{ect}[M^\checkmark]\{k\} \triangleq \underline{1} + \text{ect}[M]\{k\}$$

$$\text{ect}[d(\vec{M})]\{k\} = \text{ect}[\vec{M}]\{\lambda \vec{z}. E_d(\vec{z})(k)\} \text{ where }$$

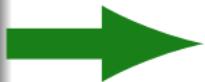
$$E_d(\cdot)(\cdot) : B_1 \times \cdots \times B_n \rightarrow (B \rightarrow \text{Real}) \rightarrow \text{Real} \in \Lambda_{\mathbb{R}}^{+\infty} \text{ for }$$

$$d : B_1 \times \cdots \times B_n \rightarrow B$$

expected
cost

Coupon Collector Revisited

```
coupons : [Coupons] → [Coupons]
let coupons cs =
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    then os
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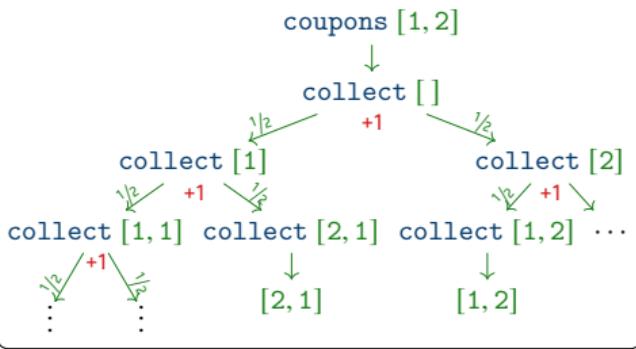


```
coupons : [Coupons]
          → ([Coupons] → Real) → Real
let coupons cs k =
  letrec collect os k =
    if cs ⊆ os
    then k os
    else 1 +  $\sum_{c \in cs} \frac{\text{collect}(c :: os) k}{|cs|}$ 
  in collect [] k

cost : [Coupons] → Real
let cost cs = coupons cs ( $\lambda \_. 0$ )
```

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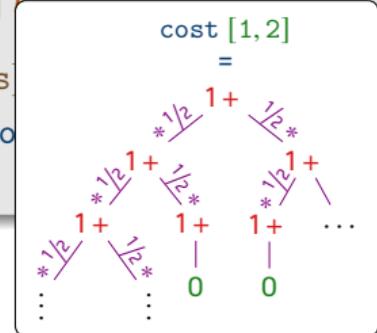
then k os

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in collect [] /

cost : [Coupons]

let cost cs = co

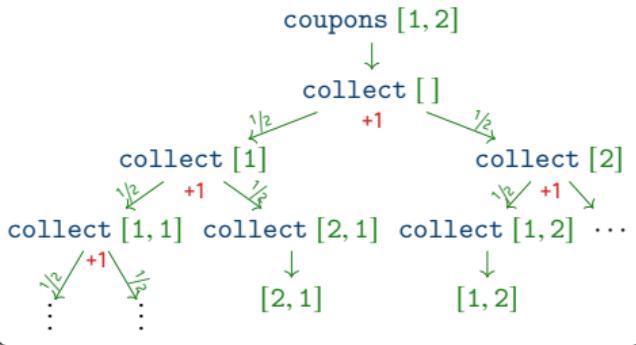


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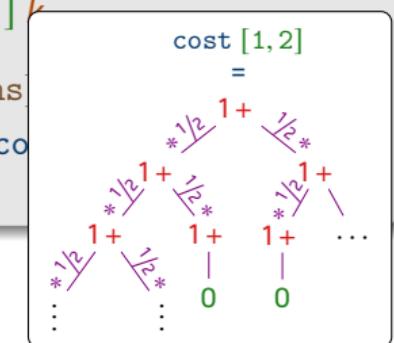
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cost : [Coupons]

let cost cs = co



Theorem (Soundness)

For any $M \in \Lambda_p$, $E[\text{cost}(M)] = \llbracket \text{ect}[M]\{\lambda_. .0\} \rrbracket$

$$\Gamma \mid \Phi \vdash M : \sigma \mid \phi$$

- ★ $\Gamma \vdash M : \sigma$
- ★ Φ are assumptions on Γ
- ★ ϕ is conclusion over distinguished variable $r : \sigma$ representing M

Example

$$x : \text{Int}; f : \text{Int} \rightarrow \text{Int} \mid x \leq 3; \forall z : \text{Int}. fz = z + 1 \vdash fx : \text{Int} \mid r \leq 4$$

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Theorem (Soundness)

If $\Gamma \mid \Phi \vdash M : \sigma \mid \phi$ then for any environment $\rho \in \llbracket \Gamma \rrbracket$,

$$\llbracket \Phi \rrbracket \rho \implies \llbracket \phi \rrbracket \rho \{r \mapsto \llbracket M \rrbracket\}$$

In particular $\vdash M : \sigma \mid \phi \implies \llbracket \phi \rrbracket \{r \mapsto \llbracket M \rrbracket\}$.

A Higher-Order Logic for Reasoning About $\Lambda_{\mathbb{R}}^{+\infty}$

$$\frac{\Gamma \vdash x : \sigma \quad \Gamma \mid \Phi \vdash \phi[x/r]}{\Gamma \mid \Phi \vdash x : \sigma \mid \phi} \text{[Var]} \quad \frac{\Gamma, x : \sigma \mid \Phi, \phi \vdash M : \tau \mid \psi}{\Gamma \mid \Phi \vdash \lambda x. M : \sigma \rightarrow \tau \mid \forall x : \sigma. \phi \Rightarrow \psi[r x/r]} \text{[Abs]}$$

$$\frac{\Gamma \mid \Phi \vdash M : \sigma \rightarrow \tau \mid \forall x : \sigma. \phi[x/r] \Rightarrow \psi[r x/r] \quad \Gamma \mid \Phi \vdash V : \sigma \mid \phi}{\Gamma \mid \Phi \vdash M \cdot V : \tau \mid \psi} \text{[App]}$$

$$\frac{\Gamma \mid \Phi \vdash M : \sigma \mid \phi \quad \Gamma \mid \Phi \vdash \phi[x/r] \Rightarrow \psi[x/r]}{\Gamma \mid \Phi \vdash M : \sigma \mid \psi} \text{[Sub]}$$

$$\frac{\Gamma \mid \cdot \vdash \text{admissible}(\psi) \quad \Gamma, f : \vec{\sigma} \rightarrow \text{Real}, \vec{x} : \vec{\sigma} \mid \Phi, \forall \vec{x} : \vec{\sigma}. \phi \Rightarrow \psi[f \vec{x}/r], \phi \vdash M : \text{Real} \mid \psi}{\Gamma \mid \Phi \vdash \text{letrec } f \vec{x} = M : \vec{\sigma} \rightarrow \text{Real} \mid \forall \vec{x} : \vec{\sigma}. \phi \Rightarrow \psi[r \vec{x}/r]} \text{[Letrec]}$$

⋮

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$$\frac{\Gamma \mid \Phi \vdash M : \sigma \rightarrow \tau \mid \forall x : \sigma. \phi[x/r] \Rightarrow \psi}{\Gamma \mid \Phi \vdash M \cdot V : \sigma \rightarrow \tau} \text{[Ext]}$$

$$\frac{\Gamma \mid \Phi \vdash M : \sigma \mid \phi \quad \Gamma \mid \Phi \vdash N : \sigma}{\Gamma \mid \Phi \vdash M \cdot N : \sigma} \text{[Conj]}$$

$$\psi[0/r] \wedge \bigwedge_{s \in S \subseteq \mathbb{R}^{+\infty}} \psi[s/r] \Rightarrow \psi[\sup S/r]$$

- ★ $r \leq t$ but not $t \leq r$
- ★ closed e.g. under \wedge and \vee , but not \neg
 \Rightarrow upper but no lower-bounds

$\Gamma \mid \cdot \vdash \text{admissible}(\psi)$

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⋮

Analysing Coupon Collector

1. $\overbrace{cs : [\text{Coupons}]}^{\triangleq \Gamma} \mid T$

$\vdash \text{letrec } \text{collect } os\ k = M : \dots \mid \forall os\ k. (os \subseteq cs \wedge \forall os'. k\ os' = 0) \Rightarrow r\ os\ k \leq Q(os)$

let `coupons` $cs\ k$ =
letrec `collect` $os\ k$ =
 M [if $cs \subseteq os$
then $k\ os$
else $1 + \sum_{c \in cs} \frac{(\text{collect } (c :: os)\ k)}{|cs|}$
in `collect` [] k

let `cost` cs = `coupons` $cs\ (\lambda_. 0)$

Analysing Coupon Collector

- $\triangleq \Gamma$
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2. $\overbrace{\Gamma \mid \forall os\ k. (os \subseteq cs \wedge \forall os'. k\ os' = 0) \Rightarrow \text{collect } os\ k \leq Q(os); os \subseteq cs; \forall os'. k\ os' = 0}^{\triangleq \Phi}$
 $\vdash M : \text{Real} \mid r \leq Q(os)$

```
let coupons cs k =
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let cost cs = coupons cs (λ_.0)
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 $\vdash M : \text{Real} \mid r \leq Q(os)$
 - 2.1 $\Gamma \mid \Phi; cs \subseteq os \vdash k\ os : \text{Real} \mid r \leq 0$
 - 2.2 $\Gamma \mid \Phi; \neg(cs \subseteq os) \vdash 1 + \sum_{c \in cs} \frac{(\text{collect } (c :: os)\ k)}{|cs|} : \text{Real} \mid r \leq 1 + \sum_{c \in cs} \frac{Q(c :: os)}{|cs|}$

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\Rightarrow constraints 2.1 $\Phi; cs \subseteq os \models 0 \leq Q(os)$ and 2.2 $\Phi; \neg(cs \subseteq os) \models 1 + \sum_{c \in cs} \frac{Q(c :: os)}{|cs|} \leq Q(os)$

```

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    else 1 + ∑c ∈ cs  $\frac{(\text{collect } (c :: os)\ k)}{|cs|}$ 
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Analysing Coupon Collector

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 $\vdash M : \text{Real} \mid r \leq Q(os)$
 - 2.1 $\Gamma \mid \Phi; cs \subseteq os \vdash k \ os : \text{Real} \mid r \leq 0$
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Define $Q(os) \triangleq |cs| \cdot H(|cs \setminus os|)$ where $H(n) = \sum_{i=1}^n 1/i$

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let cost cs = coupons cs (λ_.0)
  
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Analysing Coupon Collector

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$$= 1 + |os| \cdot H(|cs \setminus os|) + |cs \setminus os| \cdot H(|cs \setminus os| - 1)$$

$$= |cs| \cdot H(|cs \setminus os|) = Q(os)$$

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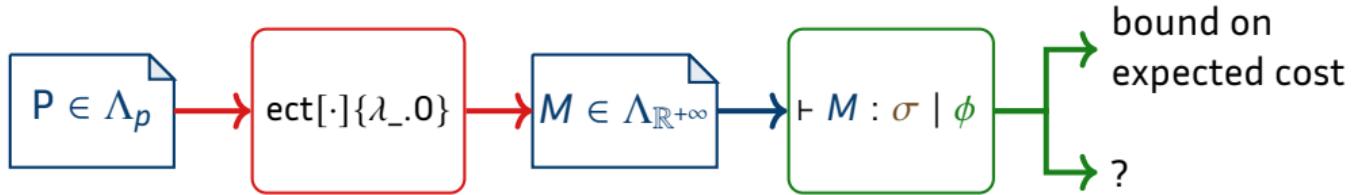
$$\Rightarrow E[\text{cost}(\text{coupons } l)] = \lceil \text{cost } l \rceil \leq |l| \cdot H(|l|)$$

```

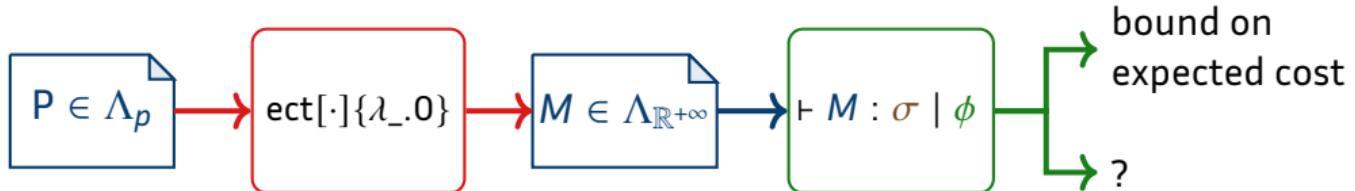
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Conclusion



Conclusion



Remarks

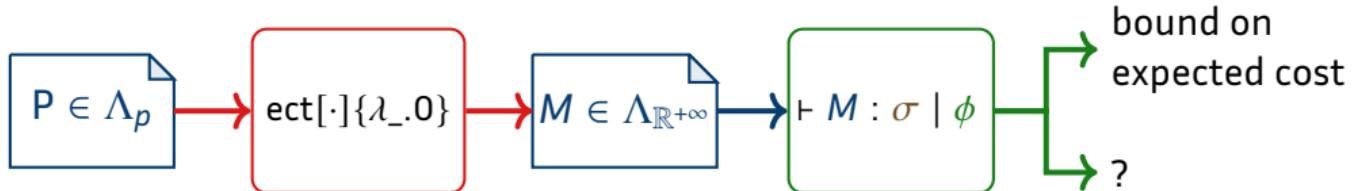
- ★ embeds the *ert*-calculus of Kaminski et al. for imperative programs

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- ★ allows reasoning about pre-expectation of $\kappa : B \rightarrow \text{Real}$

$$\llbracket \text{ect}[M] \{ \kappa \} \rrbracket = E(\text{cost}(M)) + E(\llbracket \kappa M \rrbracket)$$

Conclusion



Remarks

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Open Questions

1. expressiveness?
2. implementation?
3. lower bounds?

Thank you for your attention!