Curve/surface intersection problem by means of matrix representations

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Matrix based implicit representation

- The implicit equation of a parametrized surface
- What is the matrix representation of a surface S?
- How to find the matrix representations?

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- Curve/Surface intersection problem
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The implicit equation of a parametrized surface What is the matrix representation of a surface S? How to find the matrix representations?

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Suppose given a parametrization

$$\begin{array}{ccc} \mathbb{P}^2_{\mathbb{K}} & \xrightarrow{\phi} & \mathbb{P}^3_{\mathbb{K}} \\ (s:t:u) & \mapsto & (f_1:f_2:f_3:f_4)(s,t,u) \end{array}$$

of a surface $\boldsymbol{\mathsf{S}}$ such that

i) f_i are the homogeneous polynomial with the same degree d. ii) $gcd(f_1, \ldots, f_4) \in \mathbb{K} \setminus \{0\}.$

The implicit equation of a parametrized surface What is the matrix representation of a surface S? How to find the matrix representations?

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We have $\mathbf{S} := \overline{\operatorname{Im} \phi} := \{(x : y : z : w) \in \mathbb{P}^3_{\mathbb{K}} : S(x, y, z, w) = 0\}$ where $S(x, y, z, w) \in \mathbb{K}[x, y, z, w]$ is irreducible homogeneous polynomial. The equationle S(x, y, z, w) = 0 is called the implicit equation of \mathbf{S} .

The implicit equation of a parametrized surface What is the matrix representation of a surface S? How to find the matrix representations?

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Definition

A matrix $M(\mathbf{f})$ with entries in $\mathbb{K}[x, y, z, w]$ is said to be a representation of a given homogeneous polynomial $S \in \mathbb{K}[x, y, z, w]$ if

- i) M(f) is generically full rank,
- ii) the rank of $M(\mathbf{f})$ drops exactly on the surface of equation S = 0,
- iii) the GCD of the maximal minors of M(f) is equal to S, up to multiplication by a nonzero constant in \mathbb{K} .

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'Moving Plane ' :

For all $u \in \mathbb{N}$, consider the set $\mathcal{L}_{
u}$ of polynomials of the form

$$a_1(s,t,u)x + a_2(s,t,u)y + a_3(s,t,u)z + a_4(s,t,u)w$$

such that

• $a_i(s, t, u) \in \mathbb{K}[s, t, u]$ is homogeneous of degree ν for all $i = 1, \dots, 4$,

•
$$\sum_{i=1}^{4} a_i(s,t,u) f_i(s,t,u) \equiv 0$$
 in $\mathbb{K}[s,t,u]$.

Denote by $L^{(1)}, \ldots, L^{(n_{\nu})}$ a basis of \mathbb{K} -vector space \mathcal{L}_{ν} . Then, define the matrix $\mathbb{M}(\mathbf{f})_{\nu}$ by the equality

$$\begin{bmatrix} s^{\nu} & s^{\nu-1}t & \cdots & u^{\nu} \end{bmatrix} \mathbb{M}(\mathbf{f})_{\nu} = \begin{bmatrix} L^{(1)} & L^{(2)} & \cdots & L^{(n_{\nu})} \end{bmatrix}$$

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'Aproximate Complexes' :

Denote $A := \mathbb{K}[s, t, u]$ with naturally graded by $\deg(s) = \deg(t) = \deg(u) = 1.$ We consider the Koszul complex $(K_{\bullet}(f_1, f_2, f_3, f_4), d_{\bullet}))$:

$$0 \to A[-4d] \xrightarrow{d_4} A[-3d]^4 \xrightarrow{d_3} A[-2d]^6 \xrightarrow{d_2} A[-d]^4 \xrightarrow{d_1} A$$

$$(K_{\bullet}(f_1, f_2, f_3, f_4), u_{\bullet}))$$
:

 $0 \to A[\underline{x}][-4d] \xrightarrow{u_4} A[\underline{x}][-3d]^4 \xrightarrow{u_3} A[\underline{x}][-2d]^6 \xrightarrow{u_2} A[\underline{x}][-d]^4 \xrightarrow{u_1} A[\underline{x}]$ $(K_{\bullet}(x, y, z, w), v_{\bullet})):$

 $0 \to A[\underline{x}][-4] \xrightarrow{v_4} A[\underline{x}][-3]^4 \xrightarrow{v_3} A[\underline{x}][-2]^6 \xrightarrow{v_2} A[\underline{x}][-1]^4 \xrightarrow{v_1} A[\underline{x}]$

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Define $Z_i := \ker(d_i)$ and $Z_i := Z_i \bigotimes_A A[\underline{x}]$. We obtain the bi-graded complex : $(Z_{\bullet}, v_{\bullet})$:

 $0 \to \mathcal{Z}_4[-4] \xrightarrow{v_4} \mathcal{Z}_3[-3]^4 \xrightarrow{v_3} \mathcal{Z}_2[-2]^6 \xrightarrow{v_2} \mathcal{Z}_1[-1]^4 \xrightarrow{v_1} \mathcal{Z}_0 = A[\underline{x}]$

Theorem

Suppose that $I = (f_1, f_2, f_3, f_4)A$ is of codimension at least 2 and $\mathbf{P} = Proj(A/I)$ is locally defined by 3 equations. Then for all $v \ge v_0 := 2(d-1) - indeg(I_{\mathbf{P}})$, the matrix of surjective map

$$\begin{array}{rcl} \mathcal{Z}_{1[v]}[-1]^4 & \stackrel{v_1}{\longrightarrow} & \mathcal{Z}_{0[v]} = \mathcal{A}[\underline{x}] \\ (g_1, g_2, g_3, g_4) & \longmapsto & xg_1 + yg_2 + zg_3 + wg_4. \end{array}$$

is matrix representation of S.

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Suppose given an algebraic surface ${\bf S}$ with represented by a parameterization and a rational space curve ${\bf C}$ represented by a parameterization

$$\Psi: \mathbb{P}^1_{\mathbb{K}} \to \mathbb{P}^3_{\mathbb{K}}: (s:t) \mapsto (x(s,t):y(s,t):z(s,t):w(s,t))$$

where x(s, t), y(s, t), z(s, t), w(s, t) are homogeneous polynomials of the same degree and without common factor in $\mathbb{K}[s, t]$. Determine the set $\mathbf{C} \cap \mathbf{S} \subset \mathbb{P}^3_{\mathbb{K}}$

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Assume that M(x, y, z, w) is a matrix representation of the surface **S**, meaning a representation of implicit equation S(x, y, z, w). By replacing the variables x, y, z, w by the homogeneous polynomials x(s, t), y(s, t), z(s, t), w(s, t) respectively, we get the matrix

M(s,t) = M(x(s,t), y(s,t), z(s,t), w(s,t)).

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Lemma

For all point $(s_0 : t_0) \in \mathbb{P}^1_{\mathbb{K}}$ the rank of the matrix $M(s_0, t_0)$ drops if and only if the point $(x(s_0, t_0) : y(s_0, t_0) : z(s_0, t_0) : w(s_0, t_0))$ belongs to the intersection locus $\mathbf{C} \cap \mathbf{S}$.

It follows that points in $\mathbb{C} \cap \mathbb{S}$ associated to points (s : t) such that $s \neq 0$, are in correspondence with the set of values $t \in \mathbb{K}$ such that M(1, t) drops of rank strictly less than its row and column dimensions.

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Given an
$$m imes n$$
-matrix $M(t)=(a_{i,j}(t))$ with $a_{i,j}(t)\in\mathbb{K}[t].$

$$M(t) = M_d t^d + M_{d-1} t^{d-1} + \ldots + M_0$$

where $M_i \in \mathbb{K}^{m \times n}$ and $d = \max_{i,j} \{ \deg(a_{i,j}(t)) \}$.

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Definition

The generalized companion matrices A, B of the matrix M(t) are the matrices with coefficients in \mathbb{K} of size $((d-1)m + n) \times dm$ that are given by

$$A = \begin{pmatrix} 0 & I & \dots & \dots & 0 \\ 0 & 0 & I & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & \dots & I \\ M_0^t & M_1^t & \dots & M_{d-1}^t \end{pmatrix}$$
$$B = \begin{pmatrix} I & 0 & \dots & \dots & 0 \\ 0 & I & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & I & 0 \\ 0 & 0 & \dots & \dots & -M_d^t \end{pmatrix}$$

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Theorem

$$\operatorname{rank} M(t_0) < m \Leftrightarrow \operatorname{rank}(A - t_0 B) < dm.$$

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We recall some known properties of the Kronecker form of pencils of matrices.

$$L_k(t) = \left(egin{array}{ccccccc} 1 & t & 0 & \dots & 0 \ 0 & 1 & t & \dots & 0 \ dots & dots & dots & dots & dots & dots & dots \ dots & dots & dots & dots & dots \ dots & dots & dots \ dots & dots \ dots & dots \ dots & dots \ do$$

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$$\Omega_k(t) = \left(egin{array}{ccccccc} 1 & t & 0 & \dots & 0 \ 0 & 1 & t & \dots & 0 \ dots & do$$

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Theorem

 $P(A - tB)Q = diag\{L_{i_1}, ..., L_{i_s}, L_{j_1}^t, ..., L_{j_u}^t, \Omega_{k_1}, ..., \Omega_{k_v}, A' - tB'\}$ where A', B' are square matrices and B' is invertible.

Remark : The dimension $i_1, ..., i_s, j_1, ..., j_u, k_1, ..., k_v$ and the determinant of A' - tB' (up to a scalar) are independent of the representation and A' - tB' is a square regular pencil.

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Theorem

We have

$$\operatorname{rank}(A - tB) \ drops \ \Leftrightarrow \operatorname{rank}(A' - tB') \ drops.$$

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We start with a pencil A - tB where A, B are constant matrices of size $p \times q$. Set $\rho = \operatorname{rank} B$. In the following algorithm, all computational steps are easily realized via the classical LU-decomposition.

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$$B_1 = P_0 B Q_0 = \left[\underbrace{B_{1,1}}_{\rho} \mid \underbrace{0}_{q-\rho}\right]$$

where $B_{1,1}$ is an echelon matrix. Then, compute

$$A_1 = P_0 A Q_0 = [\underbrace{A_{1,1}}_{
ho} | \underbrace{A_{1,2}}_{q-
ho}]$$

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Step 2.

Matrices A_1 and B_1 are represented under the form

$$P_1 A_1 Q_1 = \begin{pmatrix} A'_{1,1} & A'_{1,2} \\ \hline A_2 & 0 \end{pmatrix} \quad P_1 B_1 Q_1 = \begin{pmatrix} B'_{1,1} & 0 \\ \hline B_2 & 0 \end{pmatrix}$$

where

• $A'_{1,2}$ has full row rank, • $\left(\frac{B'_{1,1}}{B_2}\right)$ has full column rank, • $\left(\frac{B'_{1,1}}{B_2}\right)$ and B_2 are in echelon form. After steps 1 and 2, we obtain a new pencil of matrices, namely $A_2 - tB_2$.

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Starting from j = 2, repeat the above steps 1 and 2 for the pencil $A_j - tB_j$ until the $p_j \times q_j$ matrix B_j has full column rank, that is to say until rank $B_j = q_j$.

If B_j is not a square matrix, then we repeat the above procedure with the transposed pencil $A_i^t - tB_j^t$.

At last, we obtain the regular pencil A' - tB' where A', B' are two square matrices and B' is invertible.

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Matrix intersection algorithm

Input : A matrix representation of a surface S and a parametrization of a rational space curve C.

Output: The intersection points of **S** and **C**.

- 1. Compute the matrix representation M(t).
- 2. Compute the generalized companion matrices A and B of M(t).
- 3. Compute the companion regular matrices A' and B'.
- 4. Compute the eigenvalues of (A', B').
- 5. For each eigenvalue t_0 , the point $P(x(t_0) : y(t_0) : z(t_0) : w(t_0))$ is one of the intersection points.

Let **S** be the rational surface which is parametrized by

$$\phi: \mathbb{P}^2 \to \mathbb{P}^3: (s:t:u) \mapsto (f_1:f_2:f_3:f_4)$$

where

$$f_1 = s^3 + t^2 u, f_2 = s^2 t + t^2 u, f_3 = s^3 + t^3, f_4 = s^2 u + t^2 u.$$

the rational space curve $\boldsymbol{\mathsf{C}}$ given by the parameterization

$$x(t) = 1, y(t) = t, z(t) = t^{2}, w(t) = t^{3}.$$

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First, on computes a matrix representation of S :



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Examples

Conclution

$$M(t) := \begin{pmatrix} 0 & 0 & 0 & t^3 - t & 0 & 0 & t^2 - 1 \\ t^3 & 0 & 0 & 1 & t^3 - t & 0 & 0 \\ 1 - t - t^2 & 0 & 0 & -t^2 & 0 & t^3 - t & 0 \\ 0 & t^3 & 0 & 0 & 1 & 0 & -t \\ 0 & 1 - t - t^2 & -t^3 & 0 & -t^2 & 1 & t^2 + t - 1 \\ 0 & 0 & 1 - t - t^2 & 0 & 0 & -t^2 & 0 \end{pmatrix}$$

We have $M(t) = M_3 t^3 + M_2 t^2 + M_1 t + M_0$

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The generalized companion matrices of M(t) are

$$A = \begin{pmatrix} 0 & I & 0 \\ 0 & 0 & I \\ M_0^t & M_1^t & M_2^t \end{pmatrix}, B = \begin{pmatrix} I & 0 & 0 \\ 0 & I & 0 \\ 0 & 0 & -M_3^t \end{pmatrix}$$

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We find that the regular part of the pencil A - tB is the pencil A' - tB' where A' is given by

/ 0	0	0	0	0	0	0	0	0	0	0	1	0	\
0	1	0	0	1	0	1	0	0	0	0	$^{-1}$	1	
0	0	0	0	0	0	0	1	0	0	0	$^{-1}$	0	
1	0	0	0	0	0	0	0	0	0	0	0	0	
0	0	0	0	0	0	0	0	$^{-1}$	0	0	0	$^{-1}$	
0	2	0	0	2	0	2	0	$^{-1}$	$^{-1}$	$^{-2}$	$^{-2}$	1	
0	$^{-1}$	0	0	-1	0	-1	0	2	0	1	1	0	Ι,
0	1	0	0	1	0	1	0	$^{-1}$	$^{-1}$	$^{-1}$	$^{-1}$	0	
0	1	0	$^{-1}$	1	0	1	0	0	0	$^{-1}$	$^{-1}$	1	
0	0	0	0	0	$^{-1}$	0	0	1	0	0	0	0	
0	1	0	0	1	0	0	0	$^{-1}$	0	$^{-1}$	$^{-1}$	0	
0	1	$^{-1}$	0	1	0	1	0	$^{-1}$	$^{-1}$	$^{-1}$	$^{-1}$	0	
0 /	$^{-1}$	0	0	$^{-2}$	0	$^{-1}$	0	0	0	1	2	-1 ,	/

and B' is the identity matrix.

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Then, we compute the following eigenvalues : $t_1 = 1$, $t_2 = -1$ and the roots of the equation $Z^7 + 3Z^6 - Z^5 - Z^3 + Z^2 - 2Z + 1 = 0$.

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- Introduce new matrix based representation of rational surfaces that are allowed to be non square.

- Transfer the solving of the curve/surface intersection problem into the eigenvalues computing problems

- Develop a symbolic/numeric algorithm to manipulate these new representations.

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Thank you for attention

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