

C7 - Macaulay's resultant.

(1)

1) Elimination theorem

We suppose given r homogeneous polynomials in variables x_1, \dots, x_n :

$$f_i(x_1, \dots, x_n) = \sum_{|\alpha| = d_i \geq 1} m_{i,\alpha} x^\alpha \quad \begin{matrix} d \\ \alpha = \alpha_1 \dots \alpha_n \end{matrix}$$

$i = 1, \dots, r.$

We set $A := \mathbb{Z}[m_{i,\alpha} : i = 1, \dots, r, |\alpha| = d_i]$ universal ring of coeffs.

$C := A[x_1, \dots, x_n]$, graded by $\begin{cases} \deg(x_i) = 1 \\ \deg(m_{i,\alpha}) = 0 \end{cases}$

$f_i \in C_{d_i} \quad \mathcal{I} = (f_1, \dots, f_r) \subset C.$
 $\eta = (x_1, \dots, x_n) \in C.$

Question: Let k be a field and $\rho: A \rightarrow k$ a specialization map $m_{i,\alpha} \mapsto c_{i,\alpha}$

We are looking for a necessary and sufficient condition on the $m_{i,\alpha}$ so that $\rho(f_1) = \dots = \rho(f_r) = 0$ (ρ is extended canonically to $A[x_1, \dots, x_n] \rightarrow k[x_1, \dots, x_n]$) have a non-trivial common root in \bar{k} (alg. closure of k).

THM (elimination):

• There exist $P_1, \dots, P_r \in A$ such that

$$\rho(P_1) = \dots = \rho(P_r) = 0 \Leftrightarrow \rho(f_1) = \dots = \rho(f_r) = 0 \text{ has a common root in } \mathbb{P}_k^{n-1}$$

• The resultant ideal $a(\mathcal{I}) := (\mathcal{I}; \eta^\infty) \cap A$ satisfies $= \{a \in A : \forall i \exists m x_i^m a \in \mathcal{I}\}$

$$\lfloor \rho(a(\mathcal{I})) = 0 \Leftrightarrow \rho(f_1) = \dots = \rho(f_r) = 0 \text{ has a common root in } \mathbb{P}_k^{n-1}$$

Example: $r=n=2$: the Sylvester resultant.

(2)

$$f = \sum a_i x_1^i x_2^{d_1-i} \quad g = \sum b_j x_1^j x_2^{d_2-j} \quad \text{Res}(f,g) \in \mathbb{Z}[a_i, b_j]$$

$$\rho(\text{Res}(f,g)) = 0 \Leftrightarrow \rho(f) = \rho(g) = 0 \text{ has a common root in } \mathbb{P}^1_k.$$

[In this case, one can show that $\rho(\mathbb{I}) = (\text{Res}(f,g)) \subset A$.

1) Geometric interpretation

* For a proof of the elimination THM we refer to Cox-Little-O'Shea's book.

* For now, we provide a geometric interpretation of this theorem in the case where $r=n$ (resultant theory), over a field $k = \bar{k}$.

- Homogeneous polynomials of degree d form an affine space:

$$\sum_{|d|=d} u_\alpha x^\alpha \longleftrightarrow (u_\alpha)_{|d|=d} \in \mathbb{A}^{N(d)} \quad N(d) = \binom{n+d-1}{n-1}$$

- Consider the incidence variety $W := V(f_1, \dots, f_r) \subset \mathbb{P}^{n-1} \times \prod_{i=1}^n \mathbb{A}^{N(d_i)}$

$$\begin{array}{ccc} \mathbb{P}^{n-1} \times \prod_{i=1}^n \mathbb{A}^{N(d_i)} & & \\ \cup & & \\ W & \xrightarrow{\pi_2} & \prod_{i=1}^n \mathbb{A}^{N(d_i)} \\ \pi_1 \downarrow & & \\ \mathbb{P}^{n-1} & & \end{array}$$

• π_1 is surjective and its fibers are linear spaces of codimension n
 $\Rightarrow W$ is a fiber bundle: it is an irreducible variety of dimension $(\sum N(d_i)) - 1$.

Let $\Gamma := \pi_2(W)$: this is an irreducible variety (elim. theorem)

As the general fiber is of dimension 0 (finitely many points)

then $\dim(\Gamma) = \dim(W)$ and hence Γ is an irreducible hypersurface in $\prod_{i=1}^n \mathbb{A}^{N(d_i)}$ in resultant theory. Next we turn to a more algebraic treatment of this elimination process.

3) Inertia forms

Take again the notation of 1). But now, let k be any commutative ring and $A := k[x_{i,\alpha}]$ the universal ring of coeffs over k .

Def: The ideal of inertia forms is the ideal $(\mathcal{I} : \mathfrak{m}^\infty) \subset \mathcal{C}$
An inertia form is an element in $(\mathcal{I} : \mathfrak{m}^\infty)$.

Rk: $(\mathcal{I} : \mathfrak{m}^\infty)$ is a graded ideal in $\mathcal{C} = A[x_1, \dots, x_n]$.

We have $\mathcal{e}(\mathcal{I}) = (\mathcal{I} : \mathfrak{m}^\infty)_0 = (\mathcal{I} : \mathfrak{m}^\infty) \cap A$.

Proposition: $f \in (\mathcal{I} : \mathfrak{m}^\infty) \Leftrightarrow \exists i, m$ such that $x_i^m f \in \mathcal{I}$

Proof: Pick $i \in \{1, \dots, n\}$ and for any $j = 1, \dots, r$ set

$$f_j(x_1, \dots, x_n) = \varepsilon_{ij} x_i^{d_j} + \sum_{\substack{|\alpha|=d_j \\ \mu_{j,\alpha} \neq \varepsilon_{ij}}} \mu_{j,\alpha} x^\alpha$$

We have $f_j = x_i^{d_j} \left[\varepsilon_{ij} + \sum_{\substack{|\alpha|=d_j \\ \mu_{j,\alpha} \neq \varepsilon_{ij}}} \mu_{j,\alpha} \frac{x^\alpha}{x_i^{d_j}} \right]$ in $\mathcal{C}[x_i^{-1}]$

Denoting $\mathcal{B} := \mathcal{C}_{x_i}$, we get an isomorphism of k -algebra: graded

$$\left(\frac{\mathcal{C}}{\mathcal{I}}\right)_{x_i} = \mathcal{B}_{x_i} \xrightarrow{\sim} k[\mu_{j,\alpha} \mid \mu_{j,\alpha} \neq \varepsilon_{ij}, j=1..r][x_1, \dots, x_n][x_i^{-1}]$$

$$\varepsilon_{ij} \rightarrow -\sum \mu_{j,\alpha} \frac{x^\alpha}{x_i^{d_j}}$$

(taking quotient with f_j amounts to say $\varepsilon_{ij} = -\sum \mu_{j,\alpha} \frac{x^\alpha}{x_i^{d_j}}$ (division))

As a consequence, x_j is not a zero-divisor in \mathcal{B}_{x_i} for any couple of integers (i,j) .

So we have commutative diagrams

(4)

$$\begin{array}{ccc} C & \longrightarrow & B_{x_i} \\ \downarrow & \uparrow & \downarrow \\ B_{x_j} & \longrightarrow & B_{x_i x_j} \end{array}$$

If $u_i^m f \in \mathcal{I}$, i.e. $f=0$ in B_{x_i}
 then $f=0$ in $B_{x_i x_j}$ and hence
 in B_{x_j} , i.e. $u_j^{m'} f \in \mathcal{I}$. \square

Corollary: If k is a domain then $(\mathcal{I}:_{\mathcal{M}^\infty})$ (and $\mathcal{Q}(\mathcal{I})$) is a prime ideal.

Proof: We have just proved that

$$(\mathcal{I}:_{\mathcal{M}^\infty}) = \ker (C = A[x_1, \dots, x_n] \rightarrow B_{x_n})$$

and that B_{x_n} is a polynomial ring over k , hence a domain.

It follows that $C/(\mathcal{I}:_{\mathcal{M}^\infty})$ is a domain and hence $(\mathcal{I}:_{\mathcal{M}^\infty})$ is prime.

Same conclusion follows for $\mathcal{Q}(\mathcal{I}) = i^{-1}(\mathcal{I}:_{\mathcal{M}^\infty})$

where $i: A \hookrightarrow A[x_1, \dots, x_n]$. \square

Geometrically, $(\mathcal{I}:_{\mathcal{M}^\infty})$ defines the incidence variety (actually scheme) and $\mathcal{Q}(\mathcal{I})$ its image via π_2 . We have just proved that they are both irreducible geom. objects.

THEM (HURWITZ): If $r < n$ then $(\mathcal{I}:_{\mathcal{M}^\infty}) = \mathcal{I}$.

This theorem implies that the projection π_2 of the incidence variety is surjective, and $\mathcal{Q}(\mathcal{I}) = \mathcal{I} \cap A = \mathcal{O}$ as soon as $d_i \geq 1 \forall i$. This means that there always exists common roots.

The proof of HURWITZ's theorem requires the properties of regular sequences that are given in the exercises sheet.

Lemma: If $r \leq n$ then $\{f_1, \dots, f_r\}$ is a regular sequence in C .

Proof: set $f_i = \varepsilon_i x_i^{d_i} + \dots$ for all $i=1, \dots, r$.

Build the sequence $S := \{u_{1,\alpha} \text{ except } \varepsilon_1, u_{2,\alpha} \text{ except } \varepsilon_2, \dots, u_{r,\alpha} \text{ except } \varepsilon_r\}$.

In $C(S)$ we have $\overline{f_i} = \varepsilon_i x_i^{d_i}$.

Now add to S the elements $\varepsilon_1 - x_1, \dots, \varepsilon_r - x_r$ so that $\overline{f_i} = x_i^{d_i+1}$
(obvious)

The sequence $x_1^{d_1+1}, \dots, x_r^{d_r+1}$ is regular, which implies that

$S \cup \{f_1, \dots, f_r\}$ is regular. As the elements are homogeneous, we can permute the order and hence $\{f_1, \dots, f_r\} \cup S$ is regular, hence $\{f_1, \dots, f_r\}$ is regular. \square

Proof of HURWITZ's theorem:

- let $f \in (I : \mathfrak{m}^\infty)$. We want to show that $f \in I$.

By assumption, $\exists s$ such that $x_n^s \cdot f \in I$. If $s=0$ we are done.

If not, it is enough to show that $x_n f \in I \Rightarrow f \in I$

because then one can iterate ($x_n^s \cdot f = x_n(x_n^{s-1} f)$).

- So, let f be such that

$$x_n f = h_1 f_1 + h_2 f_2 + \dots + h_r f_r \quad \text{in } C = A[x_1, \dots, x_n].$$

By specialization $x_n \rightarrow 0$ we get $(P(x_n=0) =: \bar{P})$ (6)

$$0 = \bar{h}_1 \bar{f}_1 + \dots + \bar{h}_r \bar{f}_r \text{ in } A[x_1, \dots, x_{n-1}].$$

Since $r < n$, $\{\bar{f}_1, \dots, \bar{f}_r\}$ is a regular sequence and hence there exists a skew-symmetric matrix $M = (d_{ij})$ such that

$$\begin{pmatrix} \bar{h}_1 \\ \vdots \\ \bar{h}_r \end{pmatrix} = M \begin{pmatrix} \bar{f}_1 \\ \vdots \\ \bar{f}_r \end{pmatrix} \quad \left(\begin{array}{l} d_{ii} = 0 \\ d_{ij} = -d_{ji} \end{array} \right)$$

Set $\begin{pmatrix} g_1 \\ \vdots \\ g_r \end{pmatrix} := M \begin{pmatrix} f_1 \\ \vdots \\ f_r \end{pmatrix}$ i.e. $g_i = \sum_{j=1}^r d_{ij} f_j$.

One has $\sum_{i=1}^r g_i f_i = 0$ (M skew-sym.).

Moreover $\bar{g}_i = \bar{h}_i$ hence $-g_i + h_i = x_n l_i$ in $A[x_1, \dots, x_n]$.

It follows that

$$\begin{aligned} x_n f &= (g_1 + x_n l_1) f_1 + \dots + (g_r + x_n l_r) f_r \\ &= \sum g_i f_i + x_n \sum l_i f_i = x_n \sum l_i f_i. \end{aligned}$$

Therefore $f = \sum l_i f_i \in \mathfrak{I}$ because x_n is not a zero divisor in $A[x_1, \dots, x_n]$. \square

4) The case $r=n$: Macaulay's result

We will prove the following result:

THM ($r=n$): If k is a UFD then $e(\mathfrak{I}) \subset A$ is a principal ideal and has a unique generator, denoted $\text{Res}(f_1, \dots, f_n)$ such that $\text{Res}(x_1^{d_1}, \dots, x_n^{d_n}) = 1$.

* A word on the notation "Res(f₁, ..., f_n)":

Res(f₁, ..., f_n) ∈ k[U_{i,α}] by definition.

Let (g₁, ..., g_n) ∈ S[x₁, ..., x_n], S a commutative ring, g_i = ∑ c_{i,α} x^α

c_{i,α} ∈ S.

One has a ring morphism (specialization)

$$\mathcal{O}: \mathbb{Z}[U_{i,\alpha}] \rightarrow S$$

$$\begin{matrix} U_{i,\alpha} & \mapsto & c_{i,\alpha} \\ 1 & \mapsto & 1 \end{matrix}$$

The resultant of g₁, ..., g_n is defined by specialization:

$$\text{Res}(g_1, \dots, g_n) := \mathcal{O}(\text{Res}(f_1, \dots, f_n)).$$

In this way, one has $\mathcal{O}(\text{Res}(f_1, \dots, f_n)) = \text{Res}(\mathcal{O}(f_1), \dots, \mathcal{O}(f_n))$
(\mathcal{O} is extended canonically to polynomial rings).

Thus Res(-, ..., -) is seen as an operator, similarly to determinant.

* First example of non-trivial inertia forms.

The Jacobian determinant:

$$\text{Jac}(f_1, \dots, f_n) = \det \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_n} \end{pmatrix} \in (\mathbb{I}; \gamma^\infty).$$

It is easy to check that $x_i \text{Jac}(f_1, \dots, f_n) \in \mathbb{I}$ for all i .

* Macaulay determinants (examples of non-trivial inertia forms indep of the variables x_1, \dots, x_n).

These determinants have been historically introduced by Macaulay in 1902.

Set $S := \sum_{i=1}^n (d_i - 1)$ where $d_i := \deg(f_i) \quad i=1, \dots, n.$ (8)

and $\text{Mon}(n; t) := \{x^\alpha \text{ such that } |\alpha| = t\} = \text{Mon}(t)$

For all $t \geq S+1$, any $x^\alpha \in \text{Mon}(t)$ is divisible by $x_i^{d_i}$ for some i .
(because $x_1^{d_1-1} \dots x_n^{d_n-1}$ is of degree S).

Def: Let $t \geq S+1$. For all $x^\alpha \in \text{Mon}(t)$ we define its index as
 $\perp \quad i(\alpha) := \min \{i \text{ such that } d_i \geq d_i\}.$

Def: $M(f; t) = (m_{\alpha\beta})$ is the matrix defined as follows:

$$\begin{aligned} \text{Mon}(n; t) \times \text{Mon}(n; t) &\longrightarrow A = k[u_i, a] \\ (\alpha, \beta) &\longrightarrow m_{\alpha\beta} \end{aligned}$$

where $\perp \quad \frac{x^\beta}{x_{i(\beta)}^{d_{i(\beta)}}} f_{i(\beta)} = \sum_{|\alpha|=t} m_{\alpha\beta} x^\alpha$ with $x^\beta \in \text{Mon}(n; t).$

In other words,

$$M(f; t) = \begin{pmatrix} x_1^t & \dots & x_1^\beta & \dots & x_n^t \\ & & \frac{x^\beta}{x_{i(\beta)}^{d_{i(\beta)}}} f_{i(\beta)} & & \\ & & \downarrow & & \\ & & & & x_n^t \end{pmatrix} \begin{matrix} x_1^t \\ \vdots \\ x_n^t \end{matrix}$$

Exercise: If $r=n=2$ show that the Sylvester matrix is obtained
 as above with $t=S+1$.

Proposition: The determinant $\mathcal{D}(t) := \det(M(\underline{f}; t))$, $t \geq s+1$, (3)
 belongs to $(\mathbb{I} : \gamma^\infty)$, hence to $\mathcal{R}(\mathbb{I}) = (\mathbb{I} : \gamma^\infty)_0$. Moreover,
 $\mathcal{D}(t) \neq 0$ and is homogeneous with respect to the coeff.
 of each polynomial $f_i(x_1, \dots, x_n)$.

Proof: - Multiply the first row by x_1^t (for instance) and then
 add combinations of the other rows to get $\#$ multiples of
 f_i 's in the first row ($L_1 \leftarrow L_1 + \sum x_1^{\alpha} m_{\alpha \beta}$).

It follows that $x_1^t \cdot \mathcal{D}(t) \in \mathbb{I}$, so $\mathcal{D}(t) \in (\mathbb{I} : \gamma^\infty)$.

- Now, by specializing all f_i to $x_i^{d_i}$ respectively, one get
 that $M(\underline{f}; t)$ specializes to the identity matrix, so
 we deduce that $\mathcal{D}(t) \neq 0$.

- Finally the homogeneity property follows from the development
 of the determinant.

Proposition: $\deg_{f_n}(\mathcal{D}(t)) = d_1 \dots d_{n-1}$

Proof: $\deg_{f_i}(\mathcal{D}(t)) = \# \{ \alpha \text{ s.t. } |\alpha| = t \text{ and } i(\alpha) = i \}$

but $i(\alpha) = n \Leftrightarrow 0 \leq \alpha_i \leq d_i - 1 \quad i = 1 \dots n-1$.

Corollary: For all $i = 1, \dots, n \exists \mathcal{D}_i(t) \neq 0$ such that

$\mathcal{D}_i(t) \in (\mathbb{I} : \gamma^\infty)_0$ and $\deg_{f_i} = \frac{d_1 \dots d_n}{d_i}$

Proof: simply permute the f_i 's in the previous construction. \square

* Come back to the proof of the main THM.

(10)

Proposition. Let $f \in (\mathbb{I}: \eta^\infty)$. Then, either $f \in \mathbb{I}$ (in which case f is called a trivial inertia form) or either f depends on each coefficient of each polynomial $f_i, i=1, \dots, n$.

Proof: This is a consequence of HURWITZ's THM.

Let $u := u_{i,\alpha}$ be one coeff. of the polynomial f_i , for some i .

Suppose there exists $f \in (\mathbb{I}: \eta^\infty)$ but f does not depend on u .

We have $f_i = u x^\alpha + g_i = u_{i,\alpha} x^\alpha + \dots$ (notation).

By assumption, $\exists N$ s.t.

$$x_n^N f = h_1 f_1 + \dots + h_n f_n, \quad h_i \in {}_k A[x_1, \dots, x_n]$$

Consider the k -algebra morphism

$$\begin{aligned} \Psi: A[x_1, \dots, x_n] &\longrightarrow A[x_1, \dots, x_n]_{x_1 x_2 \dots x_n} \\ u &\longrightarrow -g_i / x^\alpha \\ u_{j,\beta} &\longrightarrow u_{j,\beta} \quad (j,\beta) \neq (i,\alpha) \\ x_i &\longrightarrow x_i \end{aligned}$$

Since f is indep. of u , one has $\Psi(x_n^N f) = x_n^N f$, hence

$$x_n^N f = \Psi(x_n^N f) = H_1 f_1 + \dots + H_{i-1} f_{i-1} + H_{i+1} f_{i+1} + \dots + H_n f_n$$

since $\Psi(f_i) = 0$

but $x_1 \dots x_n$ is not a zero divisor in $A[x_1, \dots, x_n]$, so there exists x^β s.t.

$$x^\beta x_n^N f = l_1 f_1 + \dots + l_i f_i + l_{i+1} f_{i+1} + \dots + l_n f_n \text{ in } A[x_1, \dots, x_n].$$

Therefore, $f \in (f_1, \dots, f_{i-1}, f_{i+1}, \dots, f_n : x^\alpha)$ and hence $f \in (f_1, \dots, \hat{f}_i, \dots, f_n)$.
(HURWITZ). \square

Proof of the main THM.

Pick a coeff $u := u_{r,\alpha}$ and set $A = A'[U]$ (A' is also a UFD).

We know that:

- $\mathcal{Q}(\mathbb{I}) \neq 0$, because of $D(+)$ determinants
- $\forall a \neq 0 \in \mathcal{Q}(\mathbb{I}), \deg_{\mu}(a) \geq 1$ (previous proposition).

We define $s := \inf_{\substack{a \in \mathcal{Q}(\mathbb{I}) \\ a \neq 0}} (\deg_{\mu}(a)) \geq 1$

• We first show that there exists a prime element $R \in \mathcal{Q}(\mathbb{I})$ such that $\deg_{\mu}(R) = s$:

Let $a \neq 0 \in \mathcal{Q}(\mathbb{I})$ such that $\deg_{\mu}(a) = s$. One can decompose a as follows:

$$a = q_1 \dots q_t \text{ where } q_i \text{ are primes in } A'[U] \text{ (UFD).}$$

But $\mathcal{Q}(\mathbb{I})$ is prime, so there exists i such that $q_i \in \mathcal{Q}(\mathbb{I})$.

Moreover, $1 \leq \deg_{\mu}(q_i) \leq \deg_{\mu}(a) = s$, so by definition of s , $\deg_{\mu}(q_i) = s$. We set $R := q_i$.

• Now, we show that R is a generator of $\mathfrak{a}(I)$:

For any $b \in \mathfrak{a}(I)$ we have ("division" by R in $A'[u]$)

$$\downarrow b = q \cdot R + v \quad \text{with } \downarrow \in A' \text{ and } \begin{cases} v=0 \\ \text{or} \\ \deg_{\mu}(v) < s \end{cases}$$

Thus $v = \downarrow b - q \cdot R \in \mathfrak{a}(I)$.

If $v \neq 0$ then $\deg_{\mu}(v) \geq 1$ (previous property) and even better $\deg_{\mu}(v) \geq s$ by def of s : impossible.

It follows that $v=0$ and hence $\downarrow b = q \cdot R$ in $A'[u]$.

R being unimod., it must divide \downarrow or b . But \downarrow does not depend of u therefore $R | b$ and we conclude that $\mathfrak{a}(I) = (R)$.

• In conclusion, $\mathfrak{a}(I)$ is principal generated by R which is defined up to multiplication by an invertible element in A' , hence in k . This invertible element is set by the condition

$$R_s (r_1^{d_1}, \dots, r_n^{d_n}) = 1$$

□

Rg: $\text{Res}(f_1, \dots, f_n)$ is called the resultant of f_1, \dots, f_n .

↳ $\text{Res}(f_1, f_2)$ is equal to the Sylvester resultant.

• Multi-degree of the resultant

$\text{Res}(f_1, \dots, f_n) \in_k A[x_1, \dots, x_n] = k[u_{i\alpha}] A[x_1, \dots, x_n]$ is homogeneous in the coeff $u_{i\alpha}$ of f_i , for each i , of degree $\frac{d_1 - d_n}{d_i}$.

Proof: • The existence of the Sylvester determinants imply

that $\deg_{f_i} \text{Res}(f_1, \dots, f_n) \leq \frac{d_1 - d_n}{d_i} \quad \forall i$

• Now, specialize each f_i into a product of linear forms:

$$f_i \mapsto g_i := \prod_{j=1}^{d_i} l_{ij} \quad l_{ij} \text{ generic}$$

By divisibility we have $\text{Res}(l_{1,j_1}, \dots, l_{n,j_n}) \mid \text{Res}(g_1, \dots, g_n) \quad \forall j_1, \dots, j_n$

We deduce that $\prod_{\substack{1 \leq j_i \leq d_i \\ 1 \leq j_n \leq d_n}} \text{Res}(l_{1,j_1}, \dots, l_{n,j_n}) \mid \text{Res}(g_1, \dots, g_n) \quad (*)$

Moreover, $\deg_{l_{ijk}} \text{Res}(l_{1,j_1}, \dots, l_{n,j_n}) = 1 \quad \forall i,j,k$

We have $d_1 - d_n$ terms in the product (*). In addition the coeffs of f_i become of degree d_i in the coeff of l_{ijk} via p .

Therefore we conclude that $\deg_{f_i} \text{Res}(f_1, \dots, f_n) \geq \frac{d_1 - d_n}{d_i} \quad \square$

• Multiplicativity If $f_i = f_i' f_i''$ then

$$\text{Res}(f_1, \dots, f_i, \dots, f_n) = \text{Res}(f_1, \dots, f_i', \dots, f_n) \text{Res}(f_1, \dots, f_i'', \dots, f_n)$$

(See Cox-Little-O'Shea).

• Invariance under elementary transformations

(15)

$$R_s(f_1, \dots, f_i + \sum_{j \neq i} h_{ij} f_j, \dots, f_n) = R_s(f_1, \dots, f_i, \dots, f_n). \quad (\text{exercise}).$$

• Staculay formula

Recall that for all $t \geq s+1$, $S = \sum_{i=1}^n (d_i - 1)$, we have built the Staculay determinants

$$D_i(t) \in A = k[V_{i, \alpha}] ; \deg_{f_i} D_i(t) = \frac{d_i - d_n}{d_i}$$

They are inertia forms and are hence divisible by the resultant:

$$D_i(t) = R_s(f_1, \dots, f_n) \cdot H_i(t) \quad i=1, \dots, n.$$

By degree property, it is clear that $H_i(t)$ is indep of the coeff of f_i . This implies the following fact.

$$R_s(f_1, \dots, f_n) = \gcd(D_1(t), \dots, D_n(t)), \quad k \text{ UFD.}$$

Nevertheless, $H_i(t)$ can be computed as follows:

For all $t \geq s+1$ set

$$\text{Dod}(n; t) = \{ \alpha \text{ such that } \exists i \neq j : \alpha_i \geq d_i \text{ and } \alpha_j \geq d_j \}$$

and let $\Delta(f; t)$ the submatrix of $M(f; t)$ indexed by $\text{Dod}(n; t)$.

THM (Staculay): For all $t \geq s+1$ we have

$$\det(M(f; t)) = R_s(f_1, \dots, f_n) \det(\Delta(f; t)).$$

(see e.g. Cox-Little-O'Shea).

□