# Back-engineering of spiking neural networks parameters.

Horacio Rostro-Gonzalez

NeuroMathComp & Cortex Research Teams

#### NIH-INRIA 09



## Outline

- 1. Introduction.
- 2. Problem position.
- 3. Model From the Leaky Integrate and Fire model (LIF) to BMS model (Cessac 2008).
- 4. Master Slave paradigm.
- 5. Solutions Master-Slave paradigm:
  - 5.1 Retrieving weights from the observation of spikes and membrane potential.
  - 5.2 Retrieving weights from the observation of spikes.
  - 5.3 Retrieving delayed weights from the observation of spikes.

NRIA

(日)、

э

- 6. Results
- 7. Conclusion and Perspectives.

#### Introduction

Neurons in the brain communicate by short electrical pulses, the so-called action potentials or spikes.

- How can we understand the process of spike generation?
- How can we understand information transmission by neurons?
- What happens if thousands of neurons are coupled together in a seemingly random network?
- How does the network connectivity determine the activity patterns?
- And, vice versa, how does the spike activity influence the connectivity pattern?



#### Problem position

Given a spiking neural network to which extends observing the spike raster allows to infer the networks parameters ?

Raster



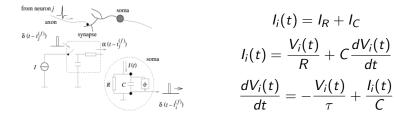
IN INFORMATIOUS

centre de recherche

SOPHIA ANTIPOLIS - MÉDITERRANÉE ◆□▶ ◆□▶ ◆三▶ ◆三▶ ● ● ●

Neurons

## Model - From the Leaky Integrate and Fire model (LIF) to BMS model (Cessac, 2008)



Time discretization of the LIF model using the Euler method:

$$rac{V_i(t+dt)-V_i(t)}{dt}=-rac{V_i(t)}{ au}+rac{I_i(t)}{C}$$



э

Setting dt = 1 (sampling time scale) and  $\gamma = 1 - \frac{1}{\tau}$  we have:

$$egin{aligned} V_i(t+1) &= V_i(t) - rac{V_i(t)}{ au} + rac{I_i(t)}{C} \ V_i(t+1) &= V_i(t) \Big(1 - rac{1}{ au}\Big) + rac{I_i(t)}{C} \ V_i(t+1) &= \gamma V_i(t) + rac{I_i(t)}{C} \end{aligned}$$

The discretization imposes that  $\tau \ge 1$ , thus  $\gamma \in [0, 1[$ . Considering that C = 1 we have:

$$V_i(t+1) = \gamma V_i(t) + I_i(t)$$
$$I_i(t) = I_i^S + I_i^{ext}$$

CENTRE SOPHIA ANTIPOLIS - MÉDITERRANÉE

$$I_i^S(t) = \sum_{j=1}^N W_{ij} Z[V_j]$$

$$V_i(t+1) = \gamma V_i(t) + \sum_{j=1}^N W_{ij} Z[V_j] + I_i^{ext}$$

$$V_i(t+1) = \gamma V_i(t)(1 - Z[V_i]) + \sum_{j=1}^N W_{ij}Z[V_j] + I_i^{ext}$$

$$V_i[k] = \gamma V_i[k-1](1-Z_i[k-1]) + \sum_{j=1}^{N} W_{ij}Z_j[k-d_{ij}] + I_i^{e imes t}$$

$$Z_i[k] = (V < \theta \quad ? \quad 0:1)$$

INTITUT MATERIA De decisione es metodovariane es materiale estructurale estructural

### Master-Slave paradigm

For the master:



- ►  $Z_i[k], k \in \{1..D\}$
- ►  $V_i[k] = 0, k \leq D$
- Weights  $W_{ij} \in \mathcal{R}$
- ▶ Delays  $d_{ij} \in \{1..D\}$

$$V_i[k] = \gamma V_i[k-1](1-Z_i[k-1]) + \sum_{j=1}^N W_{ij}Z_j[k-d_{ij}] + I_i^{ext}$$



For the slave we have 3 possible solutions:

- L Linear problem, if we observe raster and potential and known delays.
- LP Linear programming problem, if we observe raster and known delays.
- NP NP-complete problem, in any general case. Unknown delays and weights.



э



# (L) Retrieving weights from the observation of spikes and membrane potential

We assume:

1.  $V_i[k] = 0, \ k \in \{0, D\}$ , or

2. the neuron *i* has fired at least one.

From the BMS model we have:

$$V_i[k] = \sum_{j=1}^{N} W_{ij} \sum_{\tau=\tau_{jk}}^{0} \gamma^{\tau} Z_j[k-\tau-d_{ij}] + I_i^{ext}$$

with,  $\tau_{jk} = k - \arg \min_{\tau > D} \{ Z_i [k - 1 - \tau] = 1 \}$ 

where:  $\tau_{jk}$  is the delay from the last spiking time, i.e., the last membrane potential reset.

・ロト ・聞ト ・ヨト ・ヨト

-

Last equation writes as a matrix:

$$\mathbf{A}_{i} \mathbf{w}_{i} = \mathbf{b}_{i}$$

$$\mathbf{A}_{i} = \begin{pmatrix} \cdots & \cdots & \cdots & \cdots \\ \cdots & \sum_{\tau=\tau_{j_{t}}}^{0} \gamma^{\tau} Z_{j}(k-\tau-d_{ij}) & \cdots \\ \cdots & \cdots & \cdots \end{pmatrix} \in \mathcal{R}^{T-D \times N}$$

$$\mathbf{w}_{i} = (\cdots W_{ij} \cdots)^{T} \quad \in \mathcal{R}^{N}$$

$$\mathbf{b}_{i} = (\cdots V_{i}[k] - I_{i}^{ext} \cdots)^{T} \quad \in \mathcal{R}^{T-D}$$



# Solving the (L) problem

The Singular Value Decomposition of  $\mathbf{A} \in \mathcal{R}^{M \times N}, M \ge N$ :

$$\mathbf{A} = \mathbf{U} \underbrace{\begin{pmatrix} \sigma_1 & 0 & \cdots & 0 \\ 0 & \sigma_2 & \cdots & 0 \\ \cdots & \cdots & \cdots & 0 \\ 0 & 0 & \cdots & \sigma_N \end{pmatrix}}_{\mathbf{S}} \mathbf{V}^{\mathsf{T}}$$

Given  $\mathbf{b} = \mathbf{A} \mathbf{w}$ , it appears that  $\mathbf{w} = \mathbf{U}^T \mathbf{S}^{\dagger} \mathbf{V}$  is the:

- Solution to  $\mathbf{b} = \mathbf{A} \mathbf{w}$ , if unique
- The smallest solution to  $\mathbf{b} = \mathbf{A} \mathbf{w}$ , i.e. with  $|\mathbf{w}|^2$  minimal, if many.

RINRIA

<ロ> (四) (四) (三) (三) (三) (三)

- The least-square solution, i.e. with  $|\mathbf{b} - \mathbf{A}\mathbf{w}|^2$  minimal, if none. Here  $\mathbf{S}^{\dagger}$  is the diagonal matrix with  $\sigma_i^{-1}$  or 0 as diagonal term.

### (LP) Retrieving weights from the observation of spikes

In this case, the value of  $V_i[k]$  is not known but only its sign with respect to the firing threshold, i.e.:

 $Z_i[k] = 0 \Rightarrow V_i[k] < 1 \quad \text{and} \quad Z_i[k] = 1 \Rightarrow V_i[k] > 1,$ 

which is equivalent to write:

$$(2Z_i[k]-1)(V_i[k]-1) > 0,$$

Expanding the BMS model modified in the previous condition allow us to write the follow:

$$(2Z_i[k]-1)\left(\sum_{j=1}^N W_{ij}\sum_{\tau=\tau_{jk}}^0 \gamma^{\tau} Z_j[k-\tau-d_{ij}]+I_i^{ext}-1\right)>0$$

DE REGIEROIR EC REGIEROIR EN INFORVATIQUE ET EN AUTONATIQUE ▲口 → ▲圖 → ▲ 臣 → ▲ 臣 → □ 臣 □

#### in matrix form:

 $\mathbf{A}_i \mathbf{w}_i + \mathbf{b}_i > 0$ 

writing:

$$\mathbf{A}_{i} = \begin{pmatrix} \cdots & \cdots & \cdots & \cdots \\ \cdots & (2Z_{i}[k] - 1) \sum_{\tau=\tau_{ji}}^{0} \gamma^{\tau} Z_{j}(k - \tau - d_{ij}) & \cdots \\ \cdots & \cdots & \cdots & \cdots \end{pmatrix} \in \mathcal{R}^{T - D \times N}$$
$$\mathbf{w}_{i} = (\cdots W_{ij} \cdots)^{T} \qquad \qquad \in \mathcal{R}^{N}$$
$$\mathbf{b}_{i} = (\cdots (2Z_{i}[k] - 1)(l_{i}^{ext} - 1) \cdots)^{T} \qquad \qquad \in \mathcal{R}^{T - D}$$



1. Replace the inequalities by equalities as follows:

$$\mathbf{A}_i \mathbf{w}_i + \mathbf{b}_i - \mathbf{e}_i = 0$$

RINRIA

TIPOLIS - MÉDITERRANÉE

- 2. We have a maximization problem, with:  $-1 < W_{ijd} < 1$  and  $0 < e_i \le e^{max}$ .
- 3. Solve it by the Simplex method.

# (NP) Retrieving delayed weights from the observation of spikes

From the reduced BMS model we can rewrite the following:

$$V_i[k] = \sum_{j=1}^{N} \sum_{d=1}^{D} W_{ijd} \sum_{\tau=\tau_{jk}}^{0} \gamma^{\tau} Z_j[k-\tau-d] + I_i^{ext}$$

The way to solve it is the same that the LP problem

DC REGHERONE EN INFORMATIQUE EN INFORMATIQUE <ロト <回ト < 注ト < 注ト

#### Results

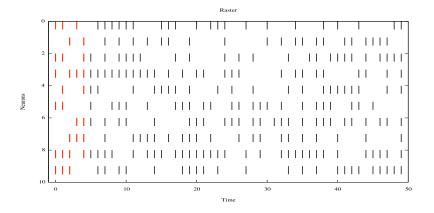


Figure: N = 10, T = 50, D = 5, lext = 0.6,  $\gamma = 0.95$ 

NRIA

DC RECHERCHE EN INFORMATIQUE L'EN AUTOMATIQUE

SOPHIA ANTIPOLIS - MÉDITERRANÉE

æ

▲ロト ▲圖ト ▲屋ト ▲屋ト

10 20 30 нит в стоят вой раз в стоят вовстство войности с в все в

Raster

50 100 150 200

Time

Figure: N = 50, T = 200, D = 5, lext = 0.6,  $\gamma = 0.95$ 

OC REGILEROILE EN INFORMATIQUE.



◆□▶ ◆□▶ ◆三▶ ◆三▶ ● ● ●

Neurons

Neurons



Time

#### Figure: N = 100, T = 400, D = 5, lext = 0.6, $\gamma = 0.95$





< ロ > < 同 > < 回 > < 回 >

Raster

#### Introducing hidden units to match any raster

In all these cases we have seen a solution always exists if the observation period is small enough i.e., T < O(ND). Let now consider the case where T >> O(ND). The key idea, borrowed from the reservoir computing paradigm reviewed in the introduction, is to add a reservoir of "hidden neurons", i.e., to consider not N but N + S neurons.

INSTITUT NATIONAL DE REGHEROHE EN INFORMATIQUE ET ER AUTONATIQUE



centre de recherche SOPHIA ANTIPOLIS - MÉDITERRANÉE

#### Results

Raster



Time

RINRIA

contra de recharche SOPHIA ANTIPOLIS - MÉDITERRANÉE

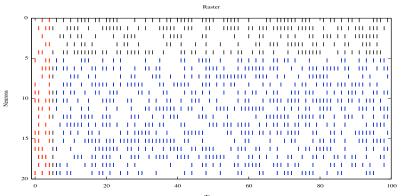
▲日▼ ▲□▼ ▲日▼ ▲日▼ □ ● ○○○

#### Figure: N = 10, T = 200, D = 5, lext = 0.6, $\gamma = 0.95$

BC REGHERONE EN INFORMATIQUE EN AUTOMATIQUE

Veurons

Raster



Time

Figure: N = 5, T = 100, D = 5, lext = 0.6,  $\gamma = 0.95$ 

INRIA MÉDITERRANÉE



Raster

Time

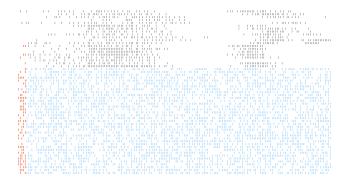
Figure: N = 5, T = 200, D = 5, lext = 0.6,  $\gamma = 0.95$ 

DC RECHERCHE EN INFORMATIQUE ET EN AUTONATIQUE

Veurons

RINRIA SCHUTTER de recherche SOPHIA ANTIPOLIS - MÉDITERRANÉE

## Results from spiking activity in monkey cortex during movement preparation(courtesy of Alexa Riehle et al.)



NRIA

C REOHERO EN INFORMATIO

SOPHIA ANTIPOLIS - MÉDITERRANÉE

э

イロト イポト イヨト イヨト

ENTITUT NATIONAL BC RECHERCHE EN INFORMATIQUE ET EN AUTOMATIQUE



A CONTRACTOR DE TECHNERE SOPHIA ANTIPOLIS - MÉDITERRANÉE slideConclusions and Perspectives

- \* Considering a deterministic time-discretized spiking network of neurons with connection weights having delays, we have been able to investigate in details to which extend it is possible to back-engineer the networks parameters, i.e., the connection weights.
- \* The method proposes here can produce any rasters produced by more realistic models such Hodgkin-Huxley.
- \* We have an useful tool for match raster using Linear Solver and Linear Programming Software. ENAS.
- optimal number of hidden units.
- approximate raster matching.
- application to unsupervised or reinforcement learning.

