Numerical approach for Hamilton-Jacobi equations on a network: application to traffic

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Flows on a network



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Flows on a network



A network is like a (oriented) graph made of edges and vertices

Examples:

- traffic flow,
- gas pipelines,
- blood vessels,
- shallow water,
- internet communications...

Outline

Introduction

- Numerical scheme 2
- 3 Traffic interpretation
- Numerical simulation 4
- Recent developments 5

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Motivation

Classical approaches (see A. Bressan's lectures):

- Macroscopic modeling on (homogeneous) sections
- Coupling conditions at (pointwise) junction

For instance, consider

$$\begin{cases} \rho_t + (Q(\rho))_x = 0, & \text{scalar conservation law,} \\ \rho(., t = 0) = \rho_0(.), & \text{initial conditions,} \\ \psi(\rho(x = 0^-, t), \rho(x = 0^+, t)) = 0, & \text{coupling condition.} \end{cases}$$
(1)

See Garavello, Piccoli [3], Lebacque, Khoshyaran [6] and Bressan et al. [1]





 $Q(\rho) = \rho V(\rho)$ with $V(\rho) =$ velocity function



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HJ junction model

Star-shaped junction



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Junction model

Proposition (Junction model [IMZ, '13])

That leads to the following junction model (see [5])

$$\begin{cases} u_t^{\alpha} + H_{\alpha}(u_x^{\alpha}) = 0, & x > 0, \ \alpha = 1, \dots, N \\ u^{\alpha} = u^{\beta} =: u, & x = 0, \\ u_t + \mathcal{H}(u_x^1, \dots, u_x^N) = 0, & x = 0 \end{cases}$$
(2)

with initial condition $u^{\alpha}(0,x) = u^{\alpha}_0(x)$ and

$$\mathcal{H}(u_x^1,\ldots,u_x^N) = \underbrace{\max_{\substack{\alpha=1,\ldots,N\\ \text{from optimal control}}}^{\max} \left\{ H_{\alpha}^{-}(u_x^{\alpha}) \right\}}_{\text{from optimal control}}.$$

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Basic assumptions

For all $\alpha = 1, ..., N$, (A0) The initial condition u_0^{α} is Lipschitz continuous. (A1) The Hamiltonians H_{α} are $C^1(\mathbb{R})$ and convex such that:



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Numerics on networks

Godunov scheme mainly used for conservation laws:

- [Bretti, Natalini, Piccoli '06, '07]: Godunov scheme compared to kinetic schemes / fast algorithms
- [Blandin, Bretti, Cutolo, Piccoli '09]: Godunov scheme adapted for Colombo model (only tested for 1 × 1 junctions)

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For Hamilton-Jacobi equations on networks:

- [Göttlich, Ziegler, Herty '13]: Lax-Freidrichs scheme outside the junction + coupling conditions (density) at the junction
- [Han, Piccoli, Friesz, Yao '12]: Lax-Hopf formula for HJ equation coupled with a Riemann solver at junction
- [Camilli, Festa, Schieborn '13]: semi-Lagrangian scheme only designed for Eikonal equations

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Outline



2 Numerical scheme

- 3) Traffic interpretation
- Numerical simulation
- 5) Recent developments

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Presentation of the scheme

Proposition (Numerical Scheme)

Let us consider the discrete space and time derivatives:

$$p_i^{\alpha,n} := \frac{U_{i+1}^{\alpha,n} - U_i^{\alpha,n}}{\Delta x} \quad \text{and} \quad (D_t U)_i^{\alpha,n} := \frac{U_i^{\alpha,n+1} - U_i^{\alpha,n}}{\Delta t}$$

Then we have the following numerical scheme:

$$\begin{cases} (D_t U)_i^{\alpha,n} + \max\{H_{\alpha}^+(p_{i-1}^{\alpha,n}), H_{\alpha}^-(p_i^{\alpha,n})\} = 0, & i \ge 1\\ U_0^n := U_0^{\alpha,n}, & i = 0, & \alpha = 1, ..., N\\ (D_t U)_0^n + \max_{\alpha = 1, ..., N} H_{\alpha}^-(p_0^{\alpha,n}) = 0, & i = 0 \end{cases}$$
(3)

With the initial condition $U_i^{\alpha,0} := u_0^{\alpha}(i\Delta x)$.

 Δx and Δt = space and time steps satisfying a CFL condition

CFL condition

The natural CFL condition is given by:

$$\frac{\Delta x}{\Delta t} \geq \sup_{\substack{\alpha=1,...,N\\i\geq 0, \ 0\leq n\leq n_T}} |H'_{\alpha}(p_i^{\alpha,n})|$$

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Gradient estimates

Theorem (Time and Space Gradient estimates)

Assume (A0)-(A1). If the CFL condition (4) is satisfied, then we have that:

(i) Considering $M^n = \sup_{\alpha,i} (D_t U)_i^{\alpha,n}$ and $m^n = \inf_{\alpha,i} (D_t U)_i^{\alpha,n}$, we have the following time derivative estimate:

$$m^0 \leq m^n \leq m^{n+1} \leq M^{n+1} \leq M^n \leq M^0$$

(ii) Considering $\underline{p}_{\alpha} = (H_{\alpha}^{-})^{-1}(-m^{0})$ and $\overline{p}_{\alpha} = (H_{\alpha}^{+})^{-1}(-m^{0})$, we have the following gradient estimate:

$$\underline{p}_{\alpha} \leq p_{i}^{\alpha,n} \leq \overline{p}_{\alpha}, \quad \textit{for all} \quad i \geq 0, \quad n \geq 0 \quad \textit{and} \quad \alpha = 1, ..., N$$

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Stronger CFL condition



As for any $\alpha = 1, \ldots, N$, we have that:

$$\underline{p}_{\alpha} \leq p_{i}^{\alpha,n} \leq \overline{p}_{\alpha}$$
 for all $i, n \geq 0$

Then the CFL condition becomes:

$$\frac{\Delta x}{\Delta t} \ge \sup_{\substack{\alpha=1,\dots,N\\p_{\alpha}\in[\underline{p}_{\alpha},\overline{p}_{\alpha}]}} |H_{\alpha}'(p_{\alpha})|$$
(5)

Existence and uniqueness

(A2) Technical assumption (Legendre-Fenchel transform)

$$H_{lpha}(p) = \sup_{q \in \mathbb{R}} (pq - L_{lpha}(q))$$
 with $L_{lpha}'' \geq \delta > 0$, for all index $lpha$

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Existence and uniqueness

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$$H_lpha(p) = \sup_{q \in \mathbb{R}} \ (pq - L_lpha(q)) \quad ext{with} \quad L_lpha'' \geq \delta > 0, \quad ext{for all index } lpha$$

Theorem (Existence and uniqueness [IMZ, '13])

Under (A0)-(A1)-(A2), there exists a unique viscosity solution u of (2) on the junction, satisfying for some constant $C_T > 0$

$$|u(t,y)-u_0(y)| \leq C_T$$
 for all $(t,y) \in J_T$.

Moreover the function u is Lipschitz continuous with respect to (t, y).

Convergence

Theorem (Convergence from discrete to continuous [CML, '13]) Assume that (A0)-(A1)-(A2) and the CFL condition (5) are satisfied. Then the numerical solution converges uniformly to u the unique viscosity solution of (2) when $\varepsilon \rightarrow 0$, locally uniformly on any compact set \mathcal{K} :

$$\limsup_{\varepsilon \to 0} \sup_{(n\Delta t, i\Delta x) \in \mathcal{K}} |u^{\alpha}(n\Delta t, i\Delta x) - U_i^{\alpha, n}| = 0$$

▶ Proof

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Outline



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- 3 Traffic interpretation

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Setting



N_I incoming and N_O outgoing roads

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Car densities

The car density ρ^{α} solves the LWR equation on branch α :

$$\rho_t^{\alpha} + (Q^{\alpha}(\rho^{\alpha}))_x = 0$$

By definition

$$\rho^{\alpha} = \gamma^{\alpha} \partial_{x} U^{\alpha}$$
 on branch α

And

$$\begin{cases} u^{\alpha}(x,t) = -U^{\alpha}(-x,t), & x > 0, \text{ for incoming roads} \\ u^{\alpha}(x,t) = -U^{\alpha}(x,t), & x > 0, \text{ for outgoing roads} \end{cases}$$

where the car index u^{α} solves the HJ equation on branch α :

$$u_t^{lpha} + H^{lpha}(u_x^{lpha}) = 0, \quad ext{for } x > 0$$

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Flow



for
$$\alpha = 1, ..., N_I$$





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Links with "classical" approach

Definition (Discrete car density)

The discrete car density $\rho_i^{\alpha,n}$ with $n \ge 0$ and $i \in \mathbb{Z}$ is given by:

$$\rho_i^{\alpha,n} := \begin{cases} \gamma^{\alpha} p_{|i|-1}^{\alpha,n} & \text{for } \alpha = 1, ..., N_I, \quad i \le -1 \\ \\ -\gamma^{\alpha} p_i^{\alpha,n} & \text{for } \alpha = N_I + 1, ..., N_I + N_O, \quad i \ge 0 \end{cases}$$
(6)



Traffic interpretation

Proposition (Scheme for vehicles densities)

The scheme deduced from (3) for the discrete densities is given by:

$$\frac{\Delta x}{\Delta t} \{\rho_i^{\alpha,n+1} - \rho_i^{\alpha,n}\} = \begin{cases} F^{\alpha}(\rho_{i-1}^{\alpha,n}, \rho_i^{\alpha,n}) - F^{\alpha}(\rho_i^{\alpha,n}, \rho_{i+1}^{\alpha,n}) & \text{for } i \neq 0, -1 \\ F_0^{\alpha}(\rho_0^{\gamma,n}) - F^{\alpha}(\rho_i^{\alpha,n}, \rho_{i+1}^{\alpha,n}) & \text{for } i = 0 \\ F^{\alpha}(\rho_{i-1}^{\alpha,n}, \rho_i^{\alpha,n}) - F_0^{\alpha}(\rho_0^{\gamma,n}) & \text{for } i = -1 \end{cases}$$

With
$$\begin{cases} F^{\alpha}(\rho_{i-1}^{\alpha,n},\rho_{i}^{\alpha,n}) := \min\left\{Q_{D}^{\alpha}(\rho_{i-1}^{\alpha,n}), \ Q_{S}^{\alpha}(\rho_{i}^{\alpha,n})\right\}\\ F_{0}^{\alpha}(\rho_{0}^{\gamma,n}) := \gamma^{\alpha}\min\left\{\min_{\beta \leq N_{I}} \frac{1}{\gamma^{\beta}}Q_{D}^{\beta}(\rho_{0}^{\beta,n}), \ \min_{\lambda > N_{I}} \frac{1}{\gamma^{\lambda}}Q_{S}^{\lambda}(\rho_{0}^{\lambda,n})\right\}\end{cases}$$



Supply and demand functions

Remark

It recovers the seminal Godunov scheme with passing flow = minimum between upstream demand Q_D and downstream supply Q_S .



Supply and demand VS Hamiltonian

$$egin{aligned} \mathcal{H}^{-}_{lpha}(p) &= egin{cases} -rac{1}{\gamma^{lpha}} \mathcal{Q}^{lpha}_{D}(\gamma^{lpha}p) \ -rac{1}{\gamma^{lpha}} \mathcal{Q}^{lpha}_{\mathcal{S}}(-\gamma^{lpha}p) \end{aligned}$$

for
$$\alpha = 1, ..., N_I$$

for
$$\alpha = N_I + 1, \dots, N_I + N_O$$

And

$$H_{\alpha}^{+}(p) = \begin{cases} -\frac{1}{\gamma^{\alpha}} Q_{\mathcal{S}}^{\alpha}(\gamma^{\alpha} p) & \text{for} \quad \alpha = 1, ..., N_{I} \\ \\ -\frac{1}{\gamma^{\alpha}} Q_{D}^{\alpha}(-\gamma^{\alpha} p) & \text{for} \quad \alpha = N_{I} + 1, ..., N_{I} + N_{O} \end{cases}$$

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- 4 Numerical simulation
 - 5) Recent developments

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Example of a Diverge

An off-ramp:



with

$$\begin{cases} \gamma^{e} = 1, \\ \gamma^{\prime} = 0.75, \\ \gamma^{r} = 0.25 \end{cases}$$

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Fundamental Diagrams



Initial conditions (t=0s)



Numerical solution: densities



Numerical solution: Hamilton-Jacobi



Trajectories



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Gradient estimates



Outline

- Numerical scheme

- 6 Recent developments

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New junction model

Proposition (Junction model [IM, '14]) From [4], we have

$$\begin{cases} u_t^{\alpha} + H_{\alpha}(u_x^{\alpha}) = 0, & x > 0, \ \alpha = 1, \dots, N \\ u^{\alpha} = u^{\beta} =: u, & x = 0, \\ u_t + \mathcal{H}(u_x^1, \dots, u_x^N) = 0, & x = 0 \end{cases}$$
(7)

with initial condition $u^{\alpha}(0,x) = u_0^{\alpha}(x)$ and

$$\mathcal{H}(u_{x}^{1},\ldots,u_{x}^{N}) = \max\left[\overbrace{\mathcal{L}}^{flux\ limiter}, \underbrace{\max_{\alpha=1,\ldots,N}}_{\substack{\alpha=1,\ldots,N\\ demand\ and\ supply}} \left\{H_{\alpha}^{-}(u_{x}^{\alpha})\right\}\right].$$

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Weaker assumptions on the Hamiltonians

For all $\alpha = 1, ..., N$, (A0) The initial condition u_0^{α} is Lipschitz continuous. (A1) The Hamiltonians H_{α} are continuous and quasi-convex i.e. there exists points p_0^{α} such that

$$\begin{cases} H_{\alpha} & \text{is non-increasing on} \quad (-\infty, p_0^{\alpha}], \\ \\ H_{\alpha} & \text{is non-decreasing on} \quad [p_0^{\alpha}, +\infty). \end{cases}$$

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Homogenization on a network

Proposition (Homogenization on a periodic network [IM'14])

Assume (A0)-(A1). Consider a periodic network. If u^{ε} satisfies (oscillating) HJ equation on network, then u^{ε} converges uniformly towards u^{0} when $\varepsilon \to 0$, with u^{0} solution of

$$u_t^0+\overline{H}\left(
abla_{ imes}u^0
ight)=0,\quad t>0,\,\,x\in\mathbb{R}^d$$

See Prof. R. Monneau's lecture and [4]

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Numerical homogenization on a network

Numerical scheme adapted to the cell problem



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First example

Proposition (Effective Hamiltonian for fixed coefficients [IM'14]) If (γ^H, γ^V) are fixed, then the

• (Hamiltonian) effective Hamiltonian H is given by

$$\overline{H}(u_{H,x}, u_{V,x}) = \max\left\{\mathcal{L}, \max_{i=\{H,V\}} H(u_{i,x})\right\},\$$

• (traffic flow) effective flow \overline{Q} is given by

$$\overline{Q}(\rho_H, \rho_V) = \min\left\{-\mathcal{L}, \frac{Q(\rho_H)}{\gamma^H}, \frac{Q(\rho_V)}{\gamma^V}\right\}$$

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First example

<u>Numerics</u>: assume $Q(\rho) = 4\rho(1-\rho)$ and $\mathcal{L} = -1.5$,



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Second example

Two consecutive traffic signals on a 1D road



Homogenization theory by [G. Galise, C. Imbert, R. Monneau, '14]

Second example

Effective flux limiter $-\overline{\mathcal{L}}$ (numerics only)



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THANKS FOR YOUR ATTENTION

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HJ on networks

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Fundamental diagram

Fundamental diagram: multi-valued in congested case



[S. Fan, M. Herty, B. Seibold, 2013], NGSIM dataset

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Motivation: the simple divergent road



LWR model [Lighthill, Whitham '55; Richards '56] on each branch α :

$$ho_t^lpha + (Q^lpha(
ho^lpha))_x = 0$$

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Getting the Hamilton-Jacobi equation

LWR model on each branch (outside the junction point)

$$ho_t^lpha + (\mathcal{Q}^lpha(
ho^lpha))_{\scriptscriptstyle X} = 0$$
 on branch $lpha$

Primitive:

$$\begin{cases} U^{\alpha}(x,t) = U^{\alpha}(0,t) + \frac{1}{\gamma^{\alpha}} \int_{0}^{x} \rho^{\alpha}(y,t) dy, \\ U^{\alpha}(0,t) = g(t) = \text{index of the single car at the junction point} \end{cases}$$



Getting the Hamilton-Jacobi equation

LWR model on each branch (outside the junction point)

$$ho_t^lpha + (\mathcal{Q}^lpha(
ho^lpha))_x = 0$$
 on branch $lpha$

Primitive:

$$\begin{cases} U^{\alpha}(x,t) = U^{\alpha}(0,t) + \frac{1}{\gamma^{\alpha}} \int_{0}^{x} \rho^{\alpha}(y,t) dy, \\ U^{\alpha}(0,t) = g(t) = \text{index of the single car at the junction point} \end{cases}$$



Sketch of the proof (gradient estimates):

Time derivative estimate:

- 1. Estimate on $m^{\alpha,n} = \inf_i (D_t U)_i^{\alpha,n}$ and partial result for $m^n = \inf_{\alpha} m^{\alpha,n}$
- 2. Similar estimate for M^n
- 3. Conclusion

Space derivative estimate:

- 1. New bounded Hamiltonian $\tilde{H}_{\alpha}(p)$ for $p \leq \underline{p}_{\alpha}$ and $p \geq \overline{p}_{\alpha}$
- 2. Time derivative estimate from above
- 3. Lemma: if for any (i, n, α) , $(D_t U)_i^{\alpha, n} \ge m^0$ then

$$\underline{p}_{\alpha} \leq p_{i}^{\alpha, n} \leq \overline{p}_{\alpha}$$

4. Conclusion as
$$\tilde{H}_{\alpha} = H_{\alpha}$$
 on $[\underline{p}_{\alpha}, \overline{p}_{\alpha}]$
See [2]

Convergence with uniqueness assumption

- Sketch of the proof: (Comparison principle very helpful)
- 1. $\overline{u}^{\alpha}(t,x) := \limsup_{\varepsilon} U_i^{\alpha,n}$ is a subsolution of (2) (contradiction on Definition inequality with a test function φ)
- 2. Similarly, \underline{u}^{α} is a supersolution of (2)
- 3. Conclusion: $\overline{u}^{\alpha} = \underline{u}^{\alpha}$ viscosity solution of (2) See [2]

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Convergence without uniqueness assumption

Sketch of the proof: (No comparison principle)

- 1. Discrete Lipschitz bounds on $u_{\varepsilon}^{\alpha}(n\Delta t, i\Delta x) := U_{i}^{\alpha,n}$
- 2. Extension by continuity of u_{ε}^{α}
- 3. Ascoli theorem (convergent subsequence on every compact set)
- 4. The limit of one convergent subsequence $(u_{\varepsilon}^{\alpha})_{\varepsilon}$ is super and sub-solution of (2)

