
Asynchronous Components

**Asynchronous communications:
from calculi to distributed
components**

Synchronous and asynchronous languages

- Systems build from communicating components :
parallelism, communication, concurrency
- Asynchronous Processes
 - Synchronous communications (rendez-vous)
Process calculi: CCS, CSP, Lotos
 - Asynchronous communications (message queues)
SDL modelisation of channels
- Synchronous Processes (instantaneous diffusion)
Esterel, Sync/State-Charts, Lustre

Question on D. Caromel course: how do you classify
ProActive ?

Asynchrony in CCS

Processes Calculi – what is asynchrony?

- A proposal in π -calculus: Asynchronous π -calculus
- No consequence of output actions
- Equivalent in CCS:

P, Q	$::=$	0	inaction
		$\mu.P$	prefix
		$P \mid Q$	parallel
		$P + Q$	(external) choice
		$(\nu a)P$	restriction
		$\text{rec}_K P$	process P with definition $K = P$
		K	(defined) process name

Processes Calculi – what is asynchrony? (2)

- $\mu.P$ can be $a.P$, $\bar{a}.P$, $\tau.P$
 - An asynchronous version would be to allow only $a.P$, and $\tau.P$, and simply \bar{a} without suffix
 - $\bar{a}.P$ has to be replaced by $(\bar{a}|P)$

 - A very simple notion but sufficient at this level
 - Same expressivity, but simple synchronisation can become more complex
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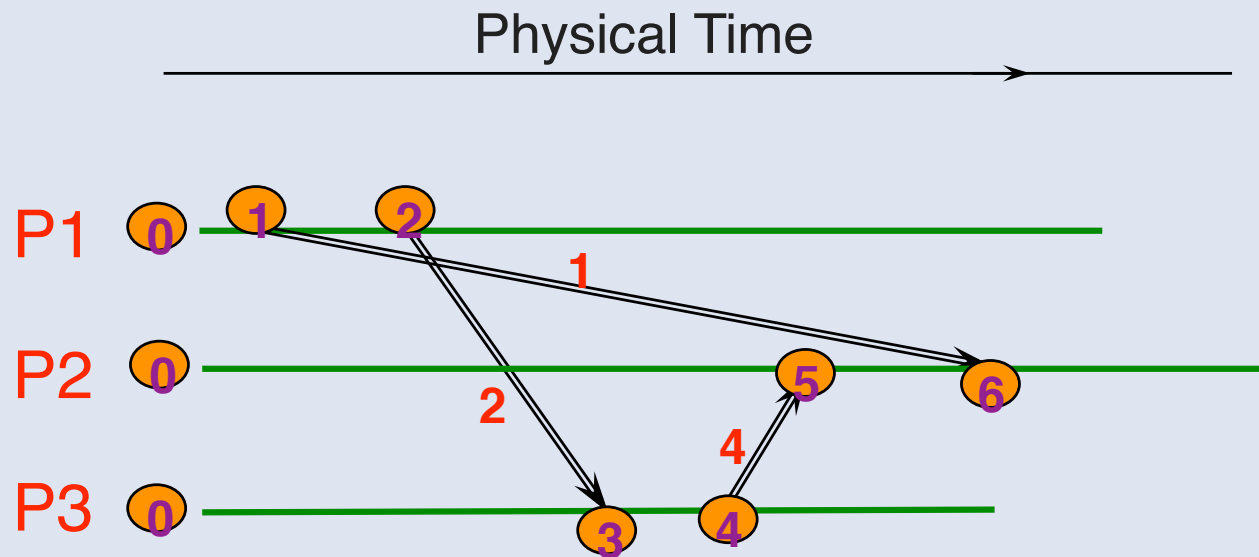
Communication Ordering; A Deeper Study

**Synchronous, asynchronous, and causally
ordered communication**

**Bernadette Charron–Bost, Friedemann
Mattern, Gerard Tel**

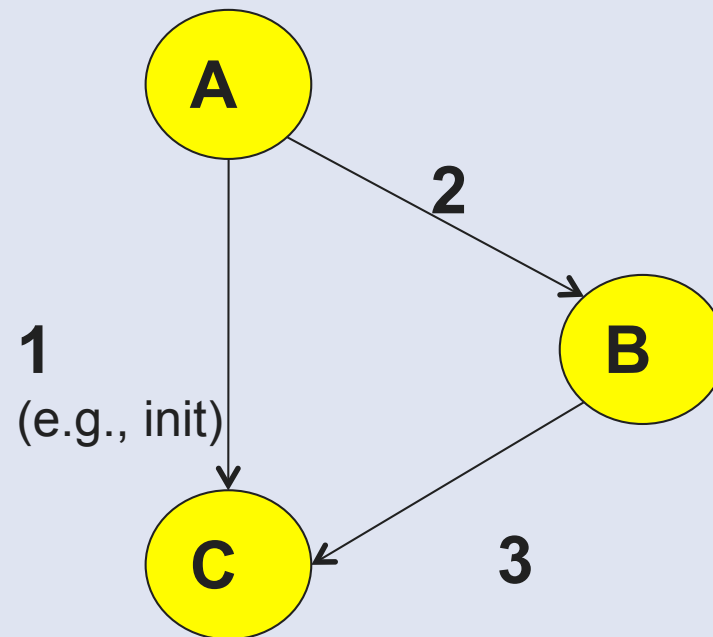
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Causality Violation



- Causality violation occurs when order of messages causes an action based on information that another host has not yet received.

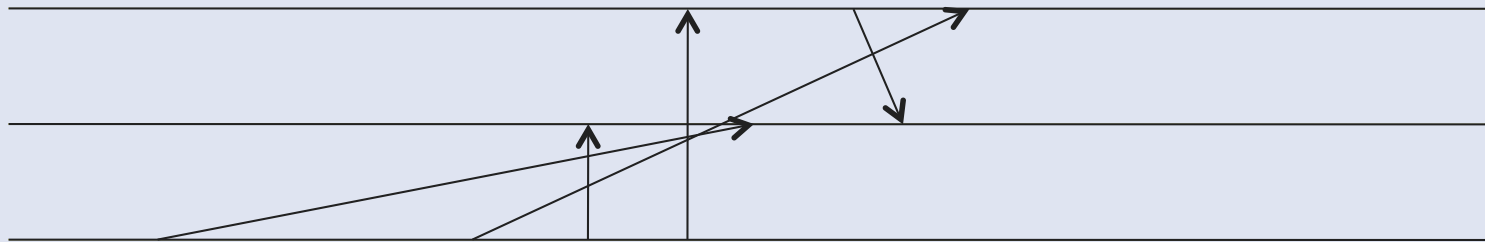
The “triangle pattern”



Objective: Ensure that **3** arrive at **C** after **1**.

Mattern: Communication is not only synchronous or asynchronous

- asynchronous communications, any order is valid (provided messages are received after being sent)



- $(s,r) \in \Gamma$ a communication
- \prec_i local causality relation (total order on events)
- Global causality \prec , verifies at least

$$a \prec_i b \Rightarrow a \prec b$$

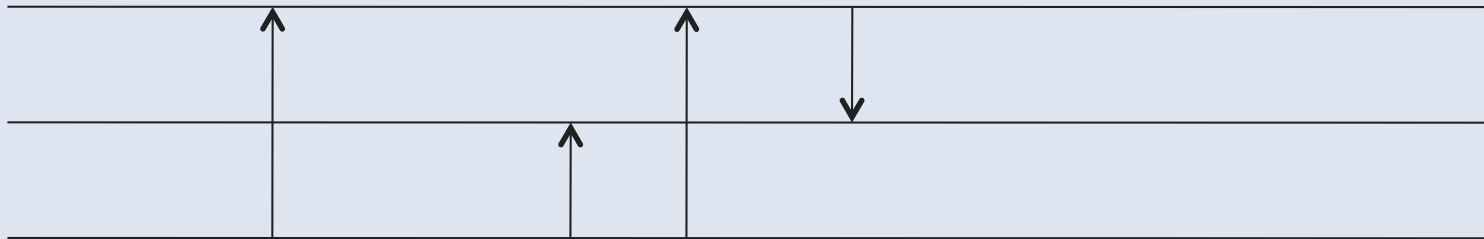
$$s \prec r \text{ (if } (s,r) \in \Gamma \text{)}$$

+ transitivity

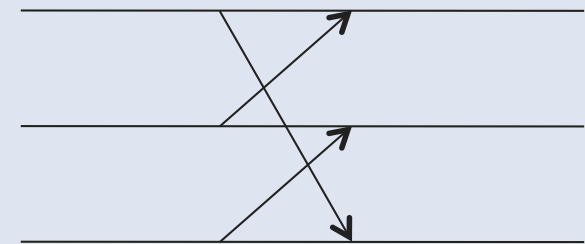
If \prec is a partial order (antisymmetric) then it represents a valid asynchronous communication
i.e. there must be no cycle of different events

Synchronous communication

- Emission and reception is almost the same event

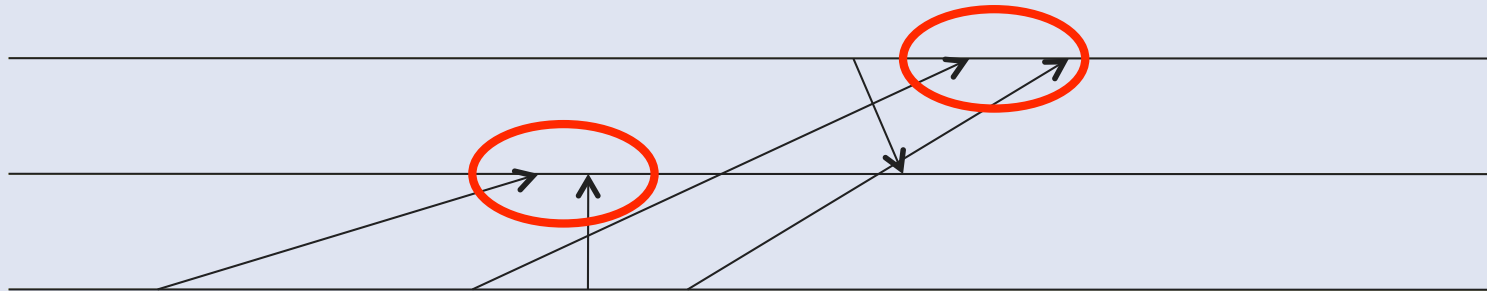


- A first characterization: Additionally if $(s,r) \in \Gamma$, then $a \prec s \Rightarrow a \prec r$ and $r \prec a \Rightarrow s \prec a$ (still no cycle) – strong common past, strong common future
- Or : messages can be all drawn vertically at the same time
- OR: no crown
($s_1 \prec r_2$ and $s_2 \prec r_3$ and ... $s_n \prec r_1$)



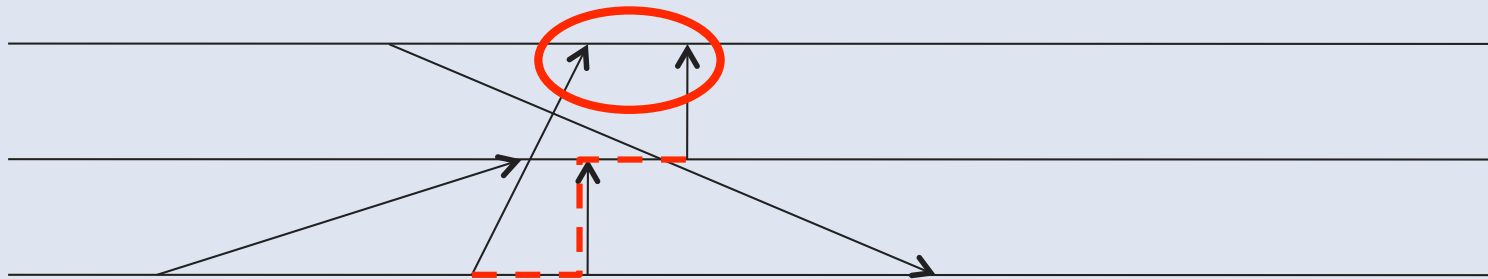
FIFO

- Order of messages sent between two given processes is guaranteed (reception order is the sending order)
- Let $a \sim b$ if a and b on the same process
- Asynchronous +
if $(s,r) \in \Gamma$, $(s',r') \in \Gamma$, $s \sim s'$ and $r \sim r'$
then $s < s' \Rightarrow r < r'$
(still no cycle)



Causal Ordering

- More general than FIFO
- Asynchronous +
if $(s,r) \in \Gamma$, $(s',r') \in \Gamma$, and $r \sim r'$
then $s < s' \Rightarrow r < r'$
(still no cycle)
- A nice characterization: for each message the diagram can be drawn with m as a vertical arrow and no other message go backward



Applications

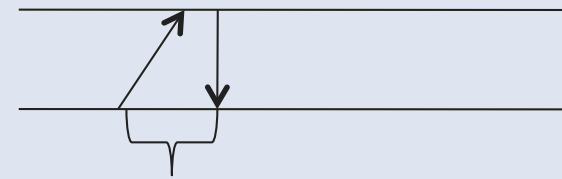
Such characterizations are useful for

- Identifying coherent states (states that could exist)
 - Performing fault-tolerance and checkpointing
 - Study which algorithms are applicable on which communication orderings
 - Might be useful for debugging, or replaying an execution
-

A “few” communication orderings

- Synchronous
- FIFO channels
- Causal ordering
- Synchronous

- What is rendez-vous?
What does rendez-vous ensure?



No event beteen sending
and reception

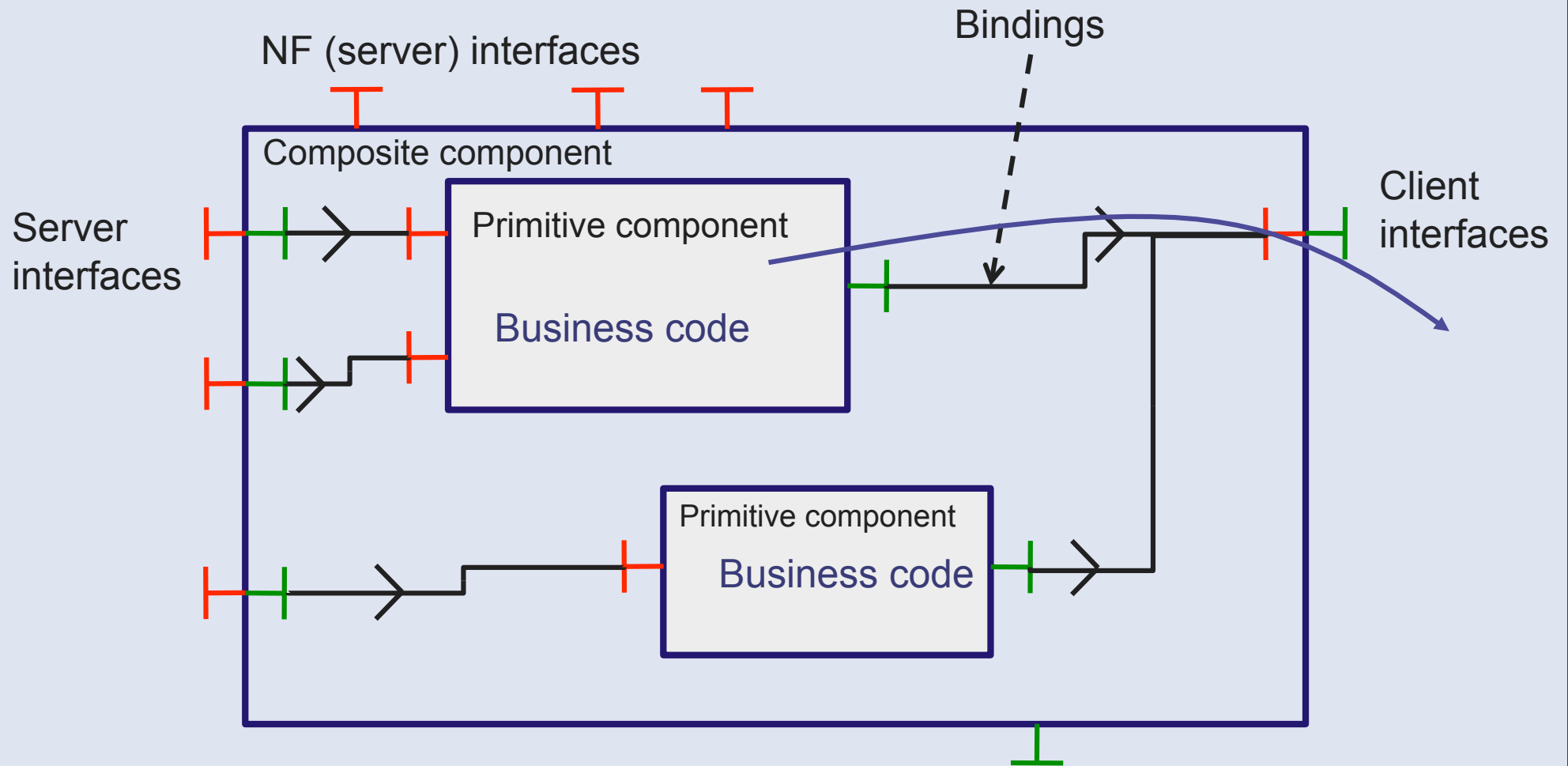
- So why is ProActive said asynchronous?

GCM: “Asynchronous” Fractal Components

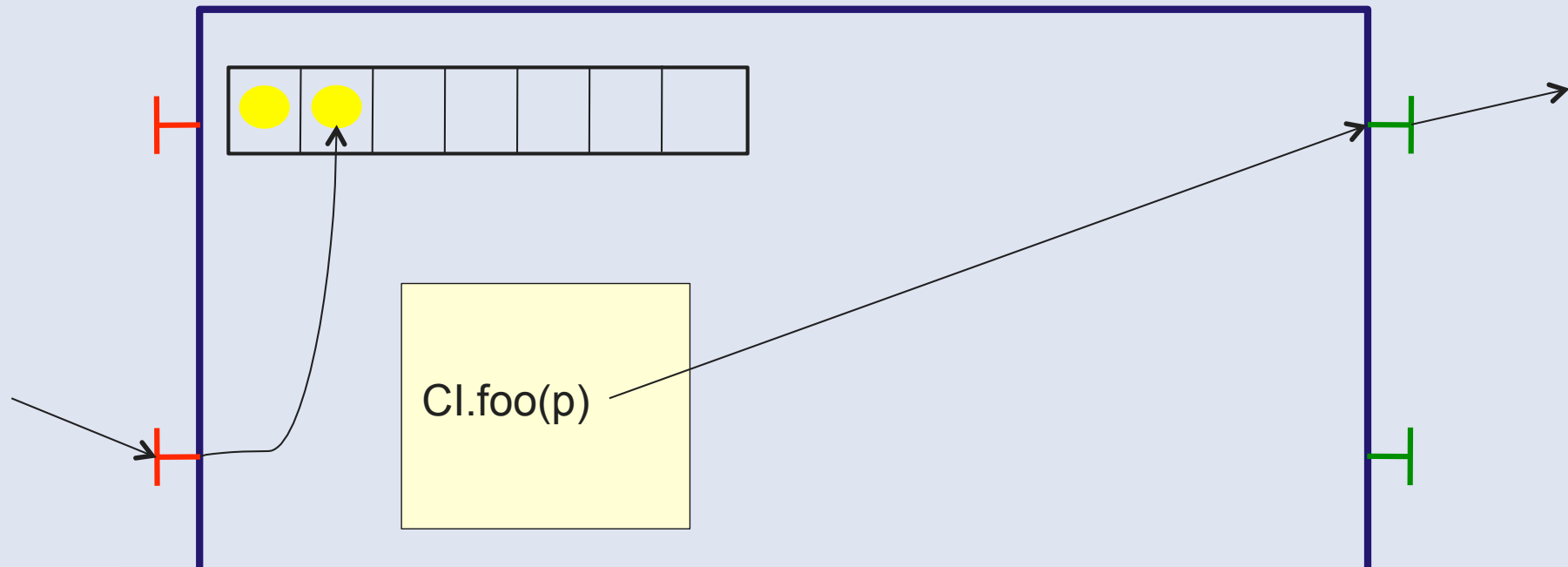
GCM – Quick Context

- Designed in the CoreGrid Network of Excellence, Implemented in the GridCOMP European project
 - Add distribution to Fractal components
 - OUR point of view in OASIS:
 - No shared memory between components
 - Components evolve asynchronously
 - Components are implemented in ProActive
 - Communicate by request/replies (Futures)
 - A good context for presenting asynchronous components futures and many-to-many communications
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What are (GCM/Fractal) Components?



A Primitive GCM Component



Primitive components communicating by *asynchronous* remote method invocations on interfaces (*requests*)

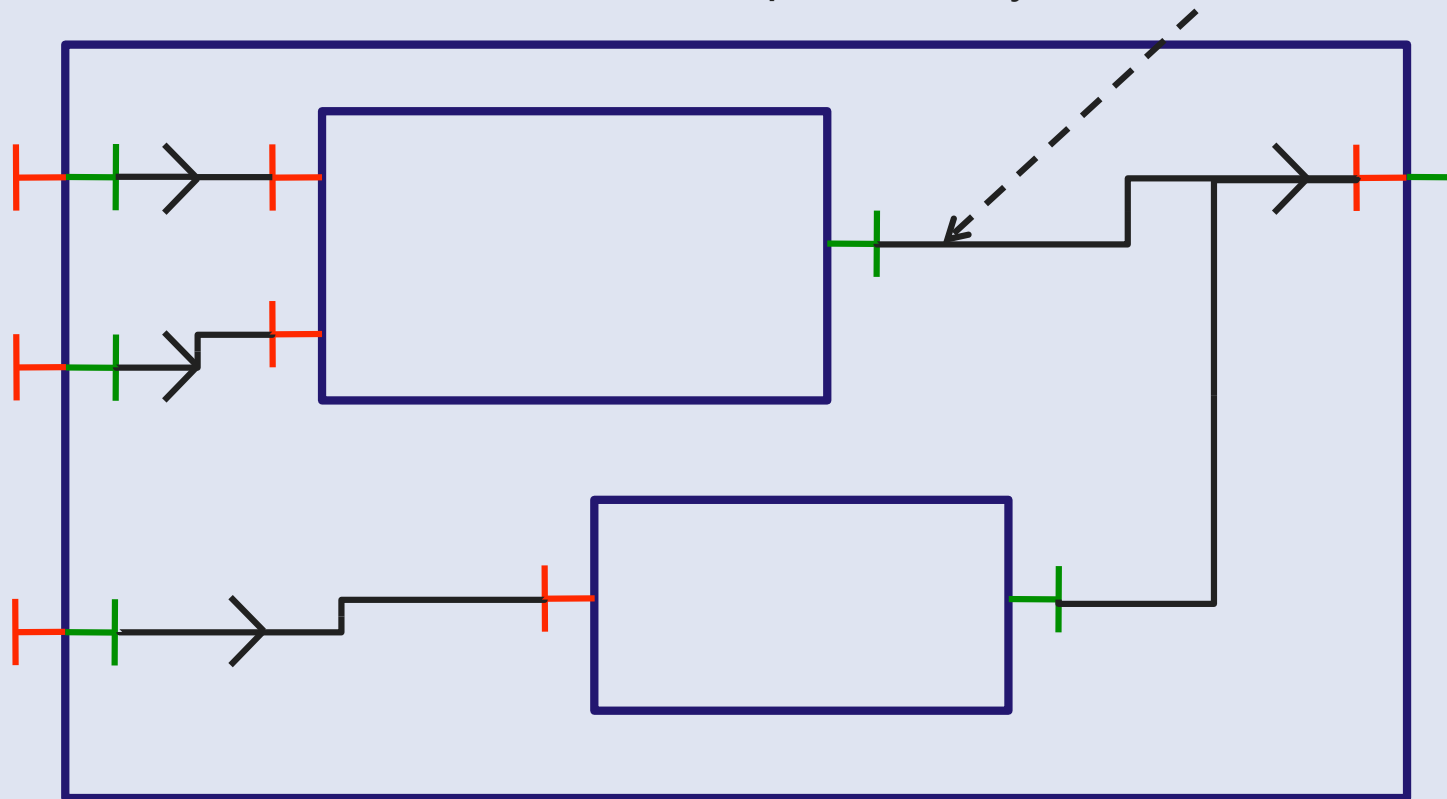
→ Components abstract away distribution and *concurrency*

in ProActive components are mono-threaded

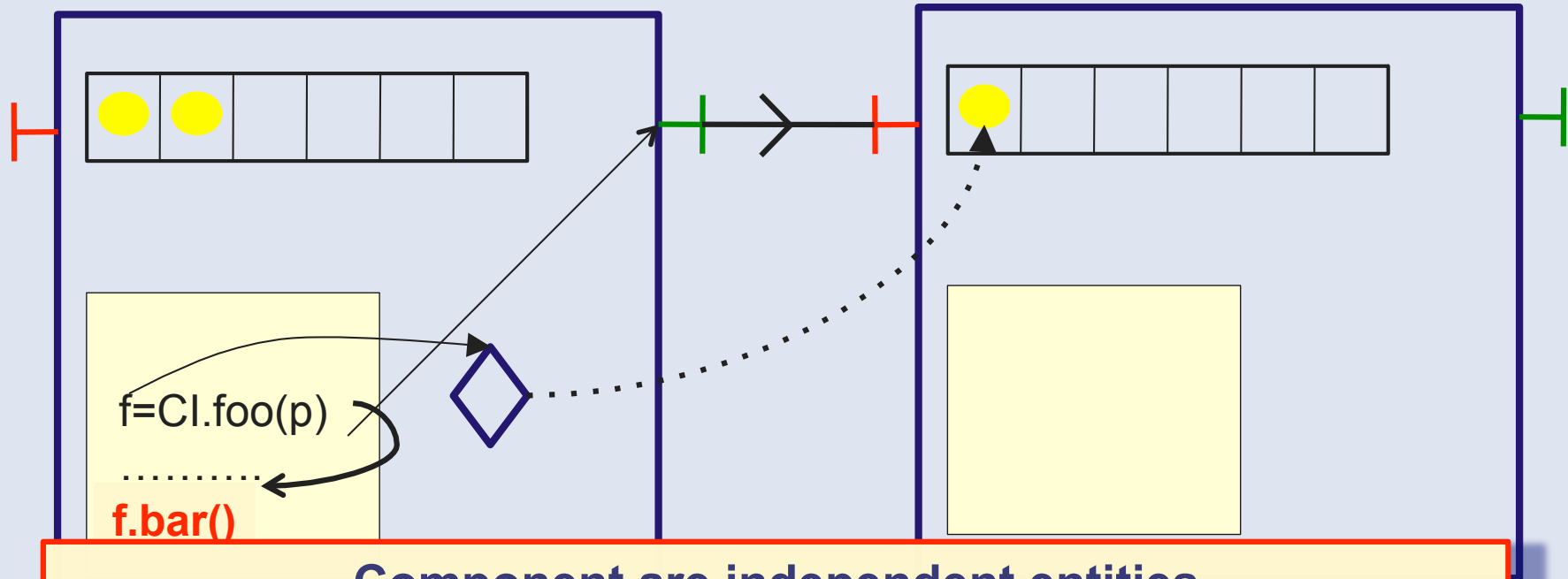
→ **simplifies concurrency** but can create **deadlocks**

Composition in GCM

Bindings:
Requests = Asynchronous method invocations



Futures for Components



**Component are independent entities
(threads are isolated in a component)**

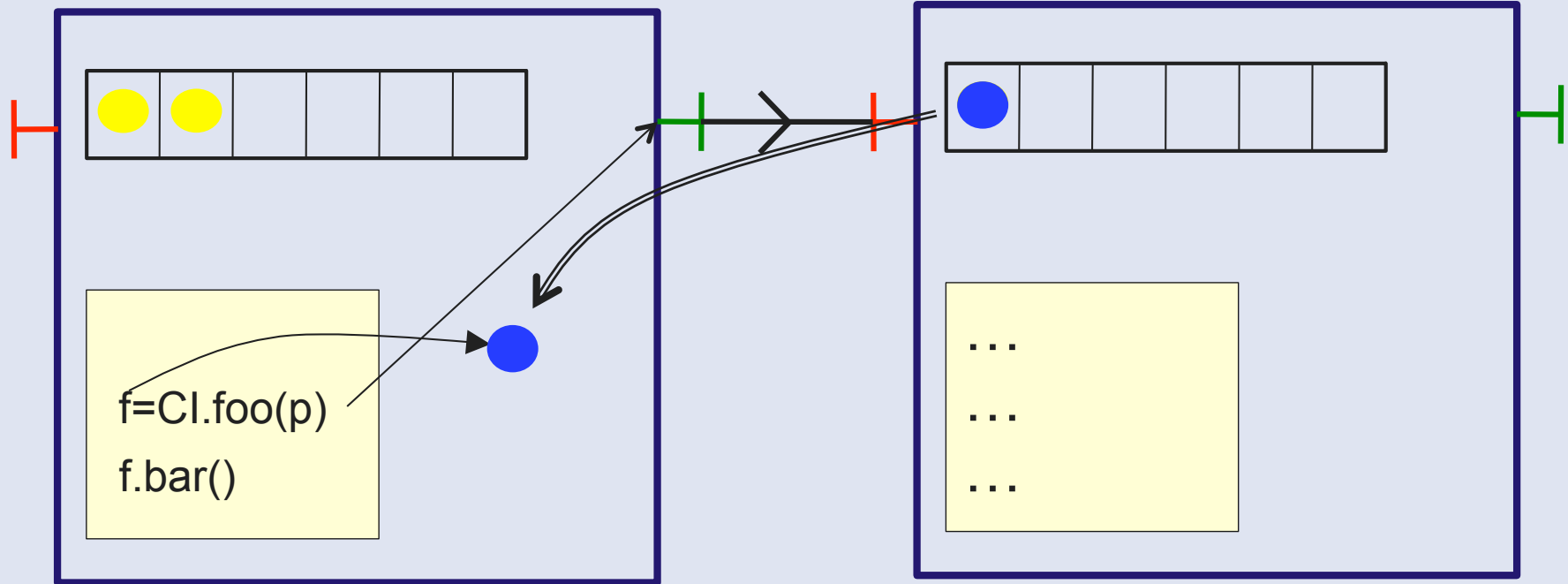
+

Asynchronous method invocations with results

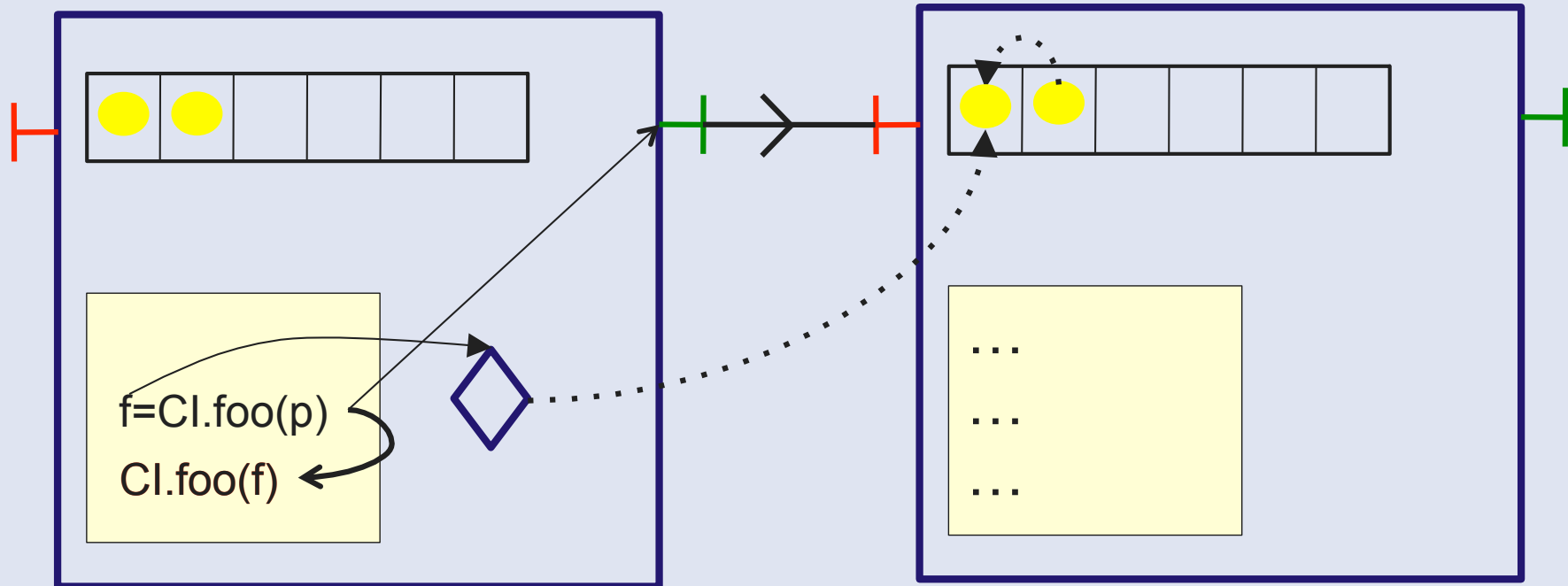


Futures are necessary

Replies

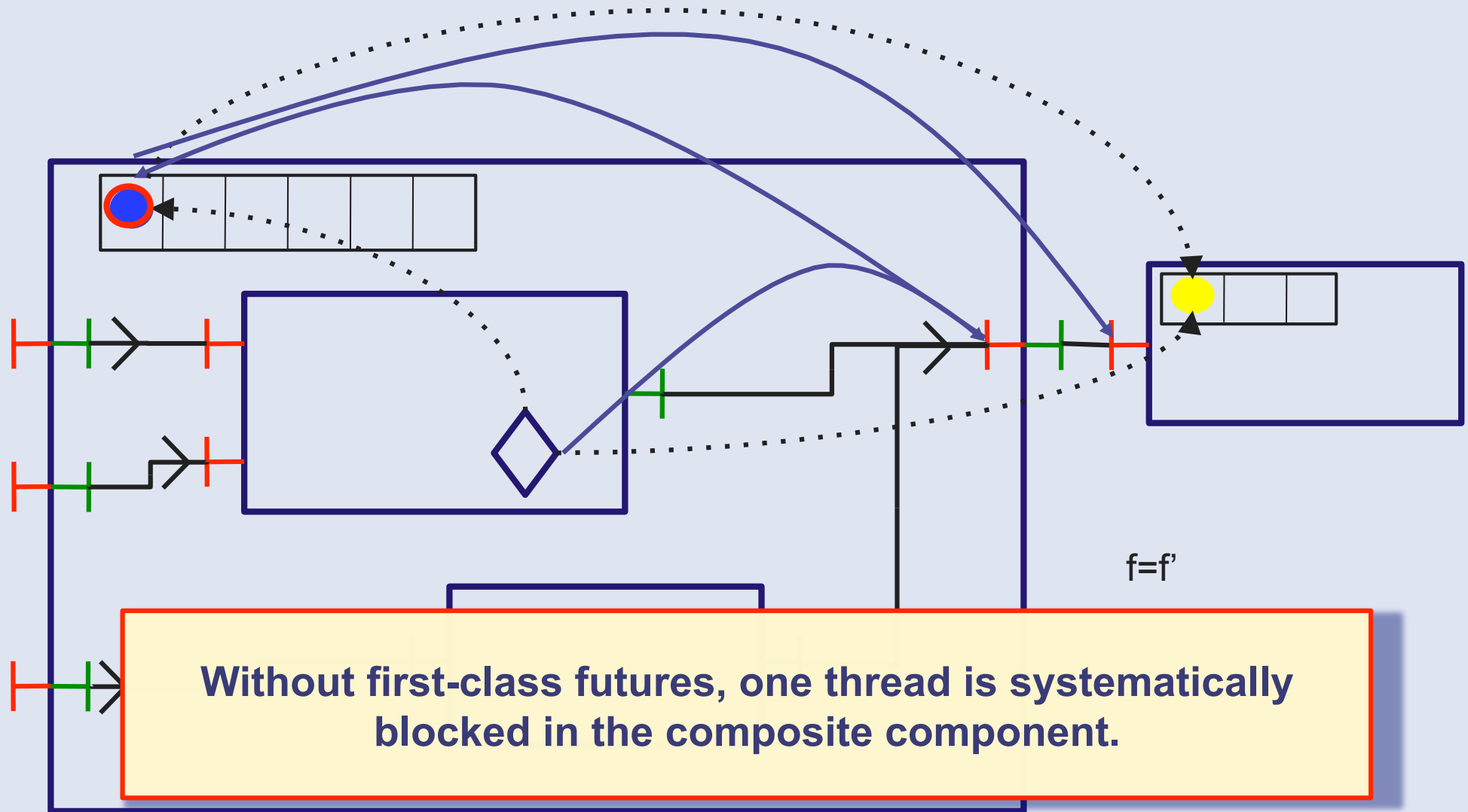


First-class Futures

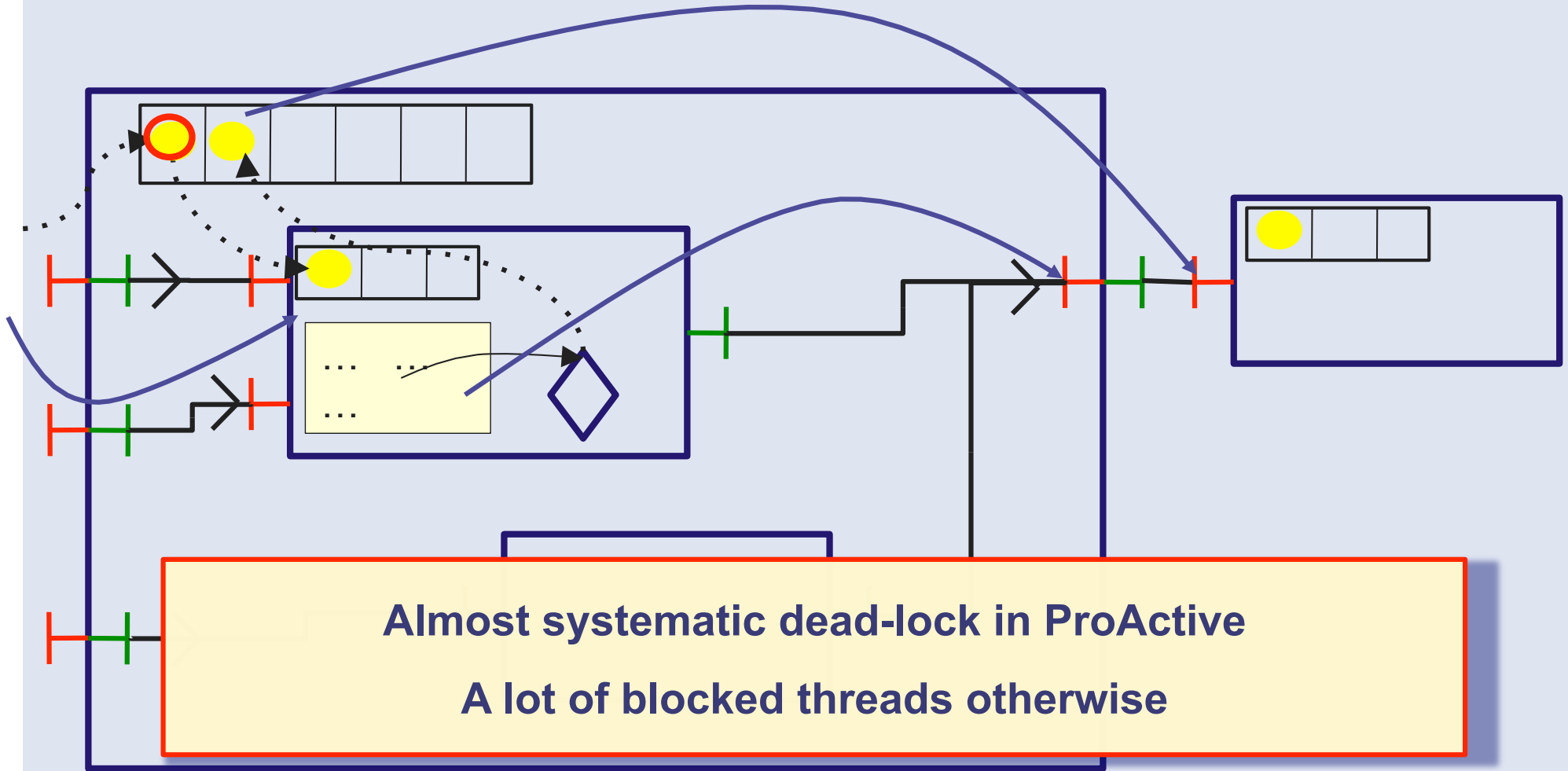


- Only strict operations are blocking (access to a future)
- Communicating a future is not a strict operation

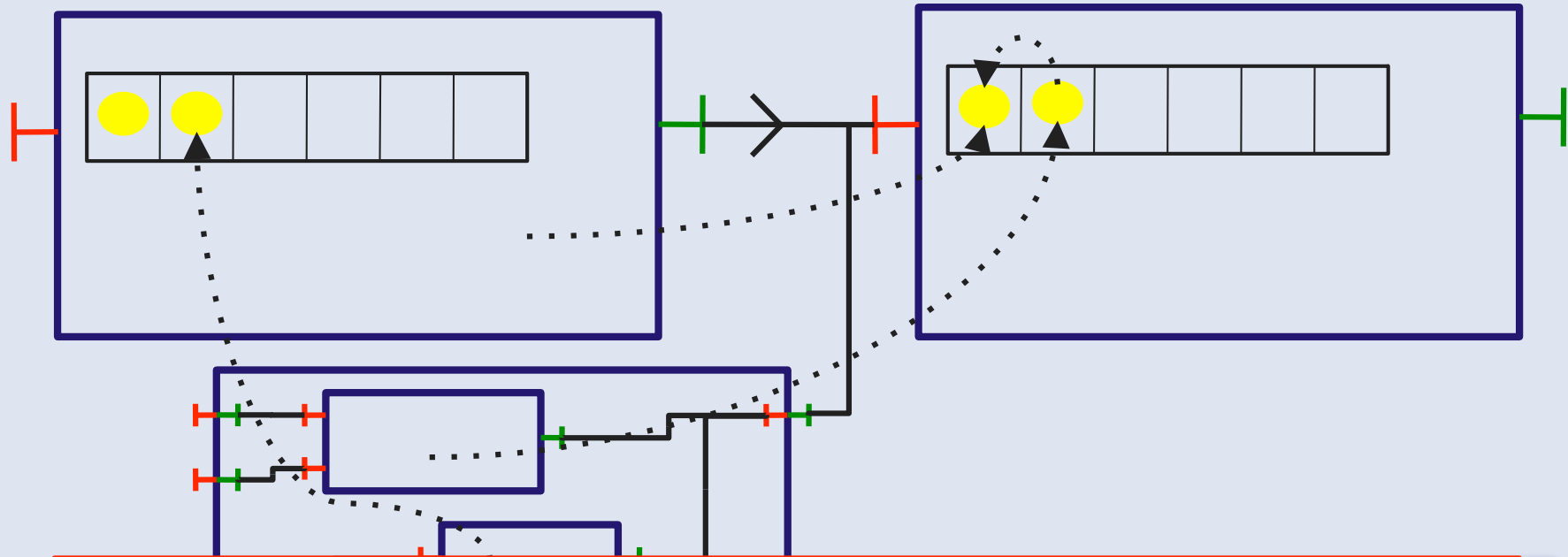
First-class Futures and Hierarchy



First-class Futures and Hierarchy



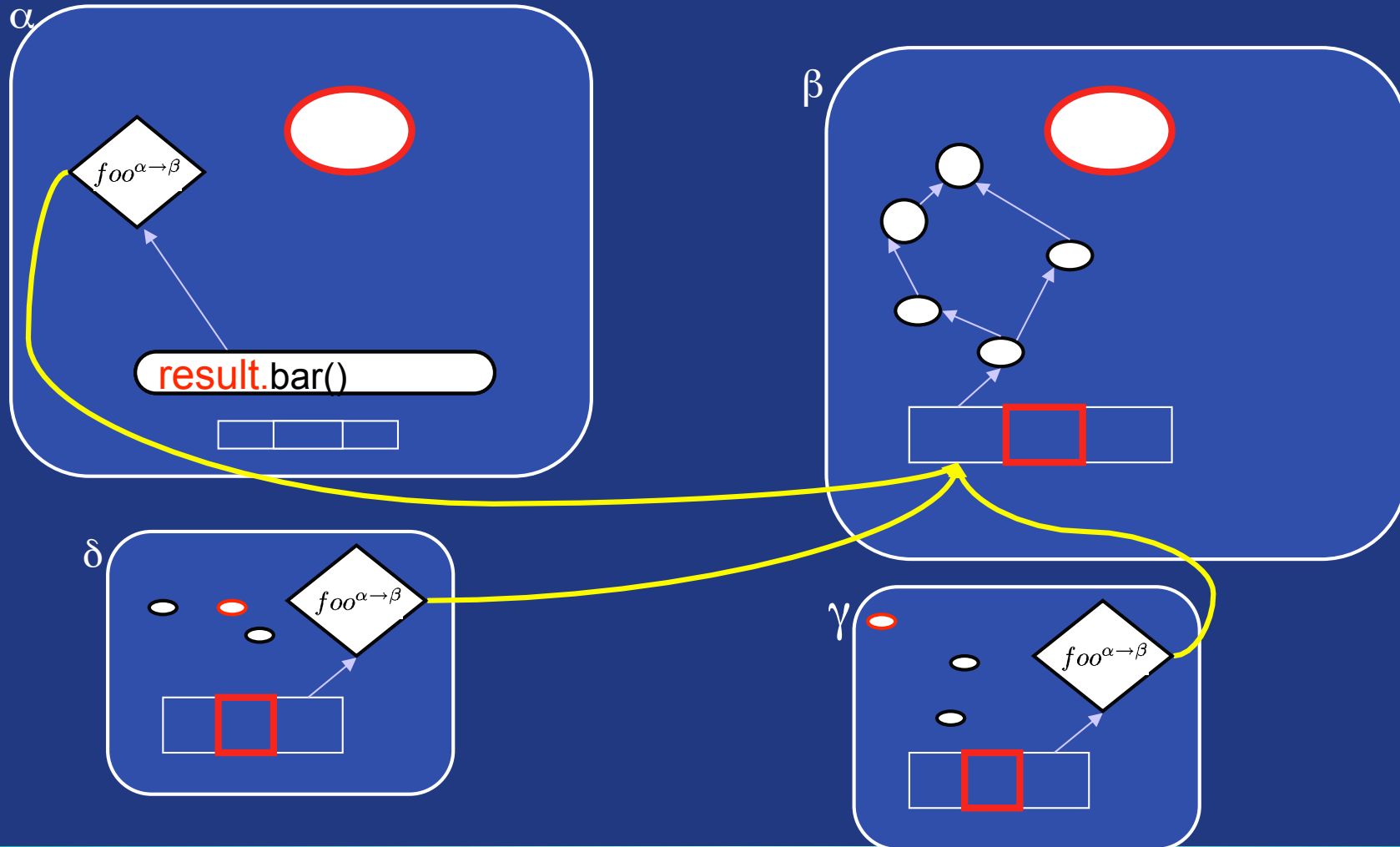
Reply Strategies



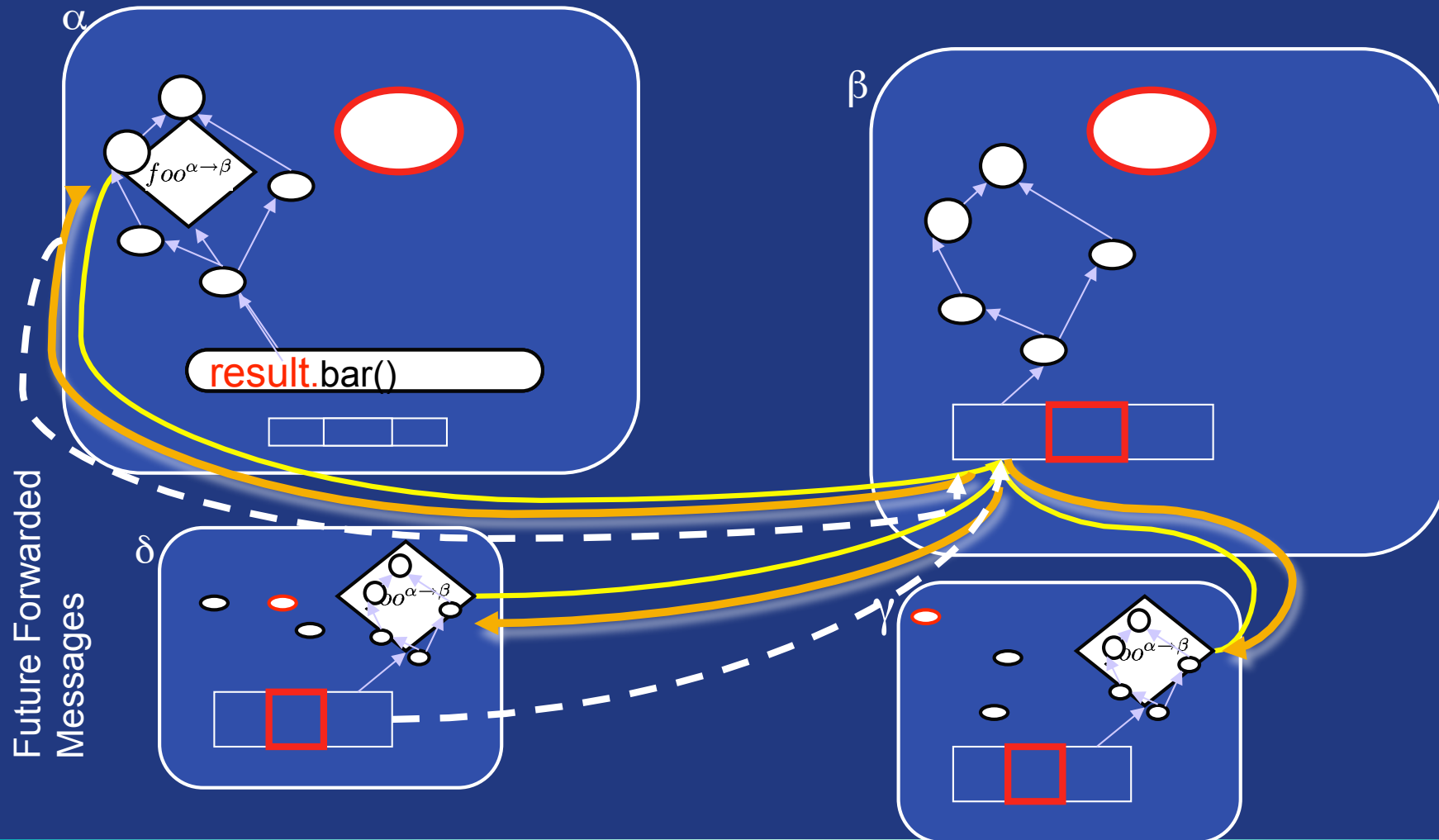
In ASP / ProActive, the result is insensitive to the order of replies (shown for ASP-calculus)

experiments with different strategies

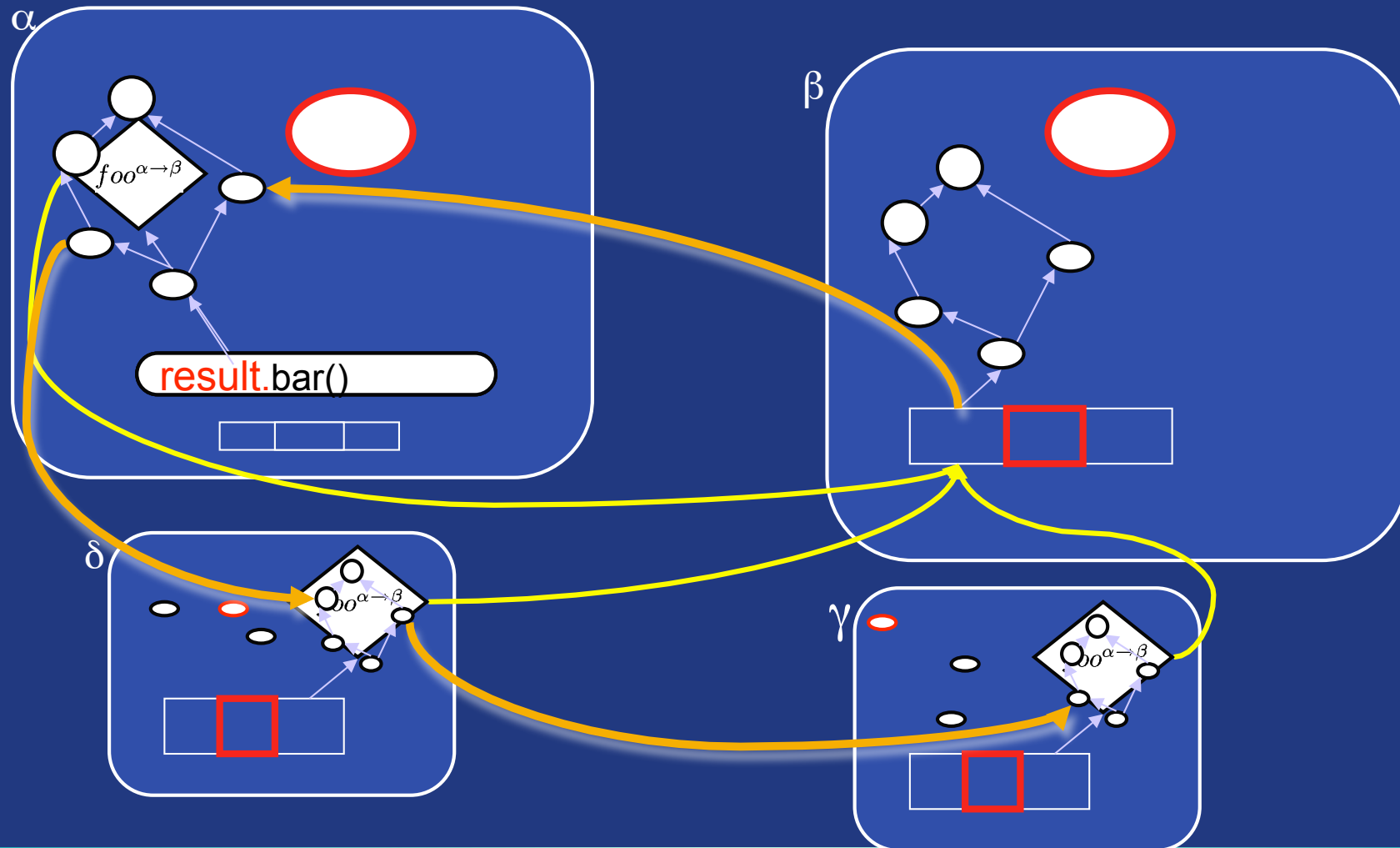
Future Update Strategies



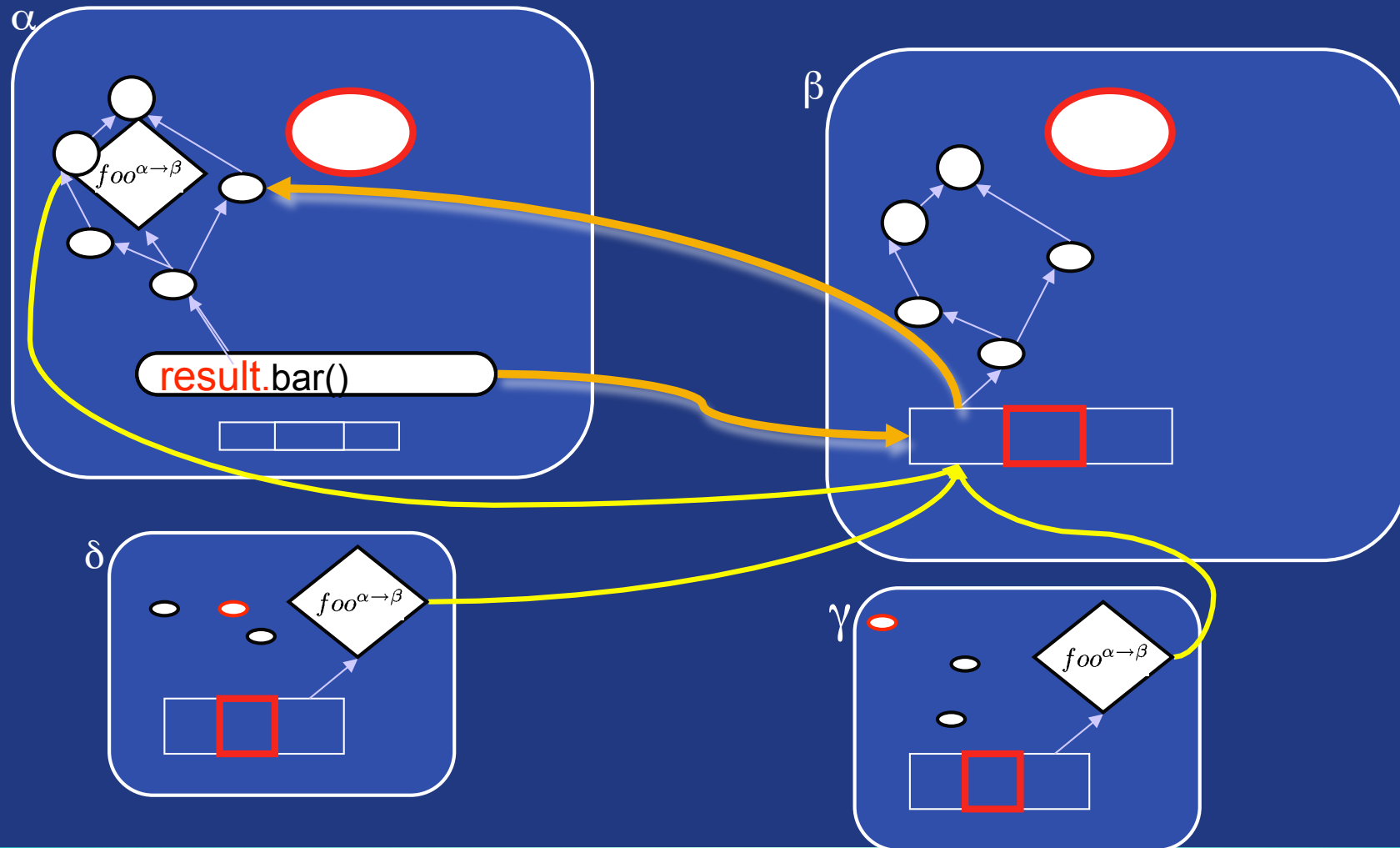
Future Update Strategies: Message-based



Future Update Strategies: Forward-based



Future Update Strategies: Lazy Future Updates



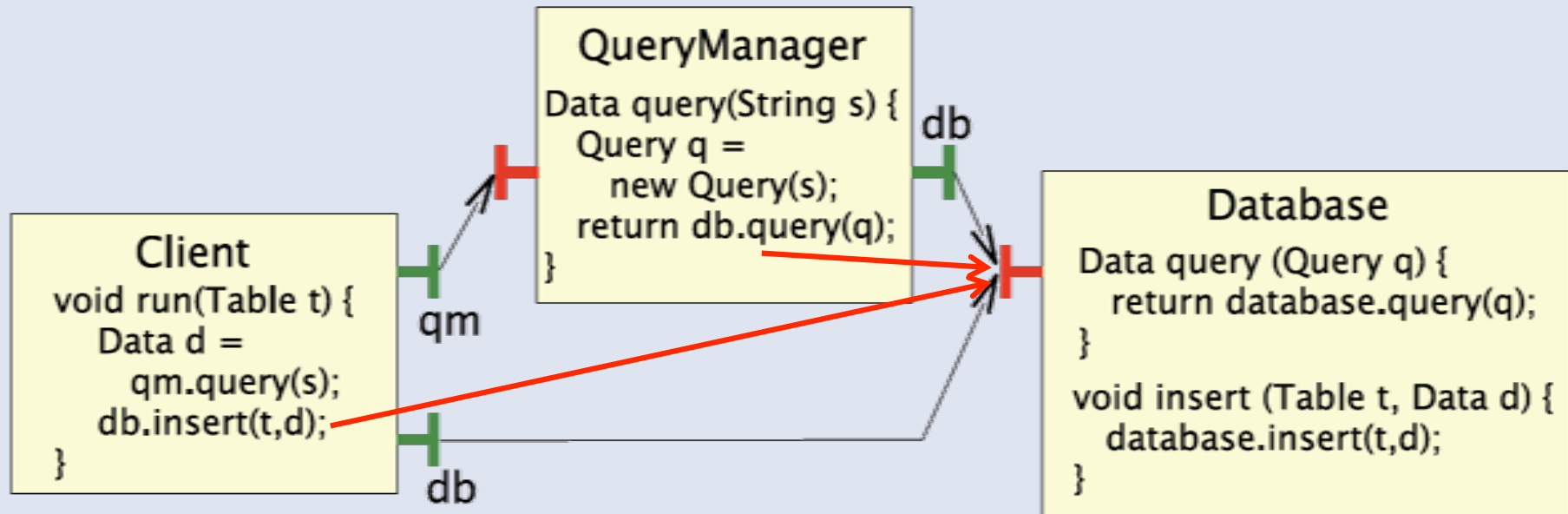
A Distributed Component Model with Futures

- Primitive components contain the business code
- Primitive components act as the unit of distribution and concurrency (each thread is isolated in a component)
- Communication is performed on interfaces and follows component bindings
- Futures allow communication to be asynchronous requests
- **Futures are transparent can lead to optimisations and are a convenient programming abstraction but ...**

...

What Can Create Deadlocks?

- A race condition:



- Detecting deadlocks can be difficult → behavioural specification and verification techniques (cf Eric Madelaine)

Collective Communications

Communications are not necessarily one-to-one:

- One-to-many
- Many-to-One
 - M by N



Collective Communications

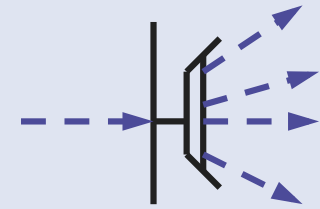
- Simple type system
- Component type = types of its interfaces
- Interface type :

- Name
- Signature
- Role
- Contingency

Fractal type-system

- Cardinality extended to support multicast / gathercast

Multicast interfaces



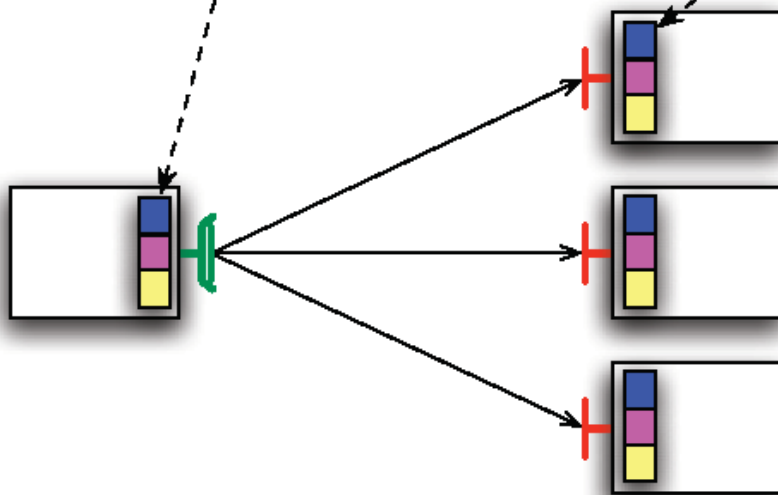
Transform a single invocation into a list of invocations

- Multiple invocations
 - Parallelism
 - Asynchronism
 - Dispatch
- Data redistribution (invocation parameters)
 - Parameterisable **distribution function**
 - Broadcast, scattering
 - Dynamic redistribution (**dynamic dispatch**)
- Result = **list** of results

a.

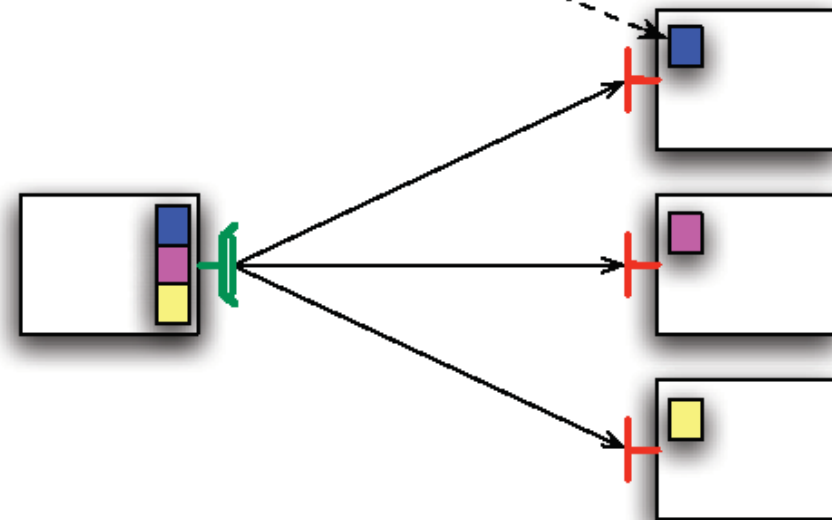
invocation parameter

broadcast invocation parameter
received in server component



b.

scattered
invocation parameter



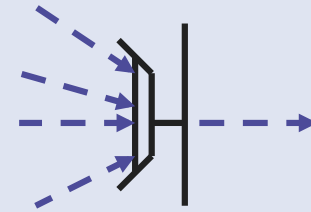
Ordering and Multicast

- FIFO ordering: If a correct process issues *multicast(i,m)* and then *multicast(i,m')*, then every correct process that delivers m' will deliver m before m' .
 - Causal ordering: If *multicast(i,m)* precedes *multicast(i',m')* with i and i' containing the same elements then any correct process that delivers m' will deliver m before m' .
 - Totally ordering (determinism): If a correct process delivers message m before m' , then any other correct process that delivers m' will deliver m before m' .
-

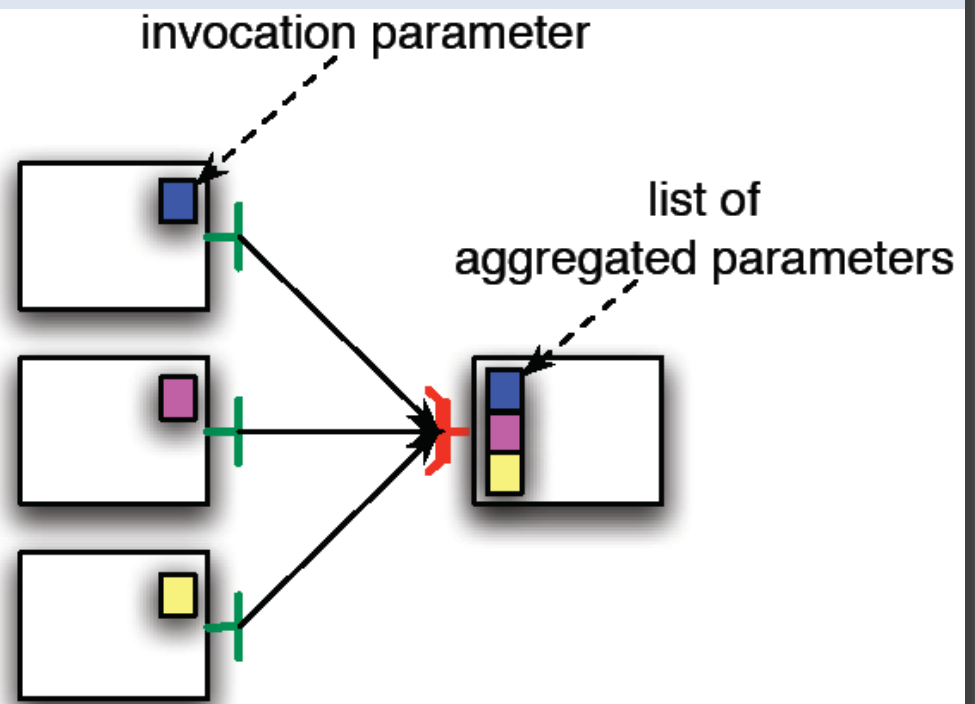
Gathercast interfaces

Transform a list of invocations into a single invocation

- Synchronization of incoming invocations
 - ~ “join” invocations
 - Timeout / drop policy
 - Bidirectional bindings (callers ↔ callee)
- Data gathering
 - Aggregation of parameters into lists



- Redistribution of results
 - Redistribution function

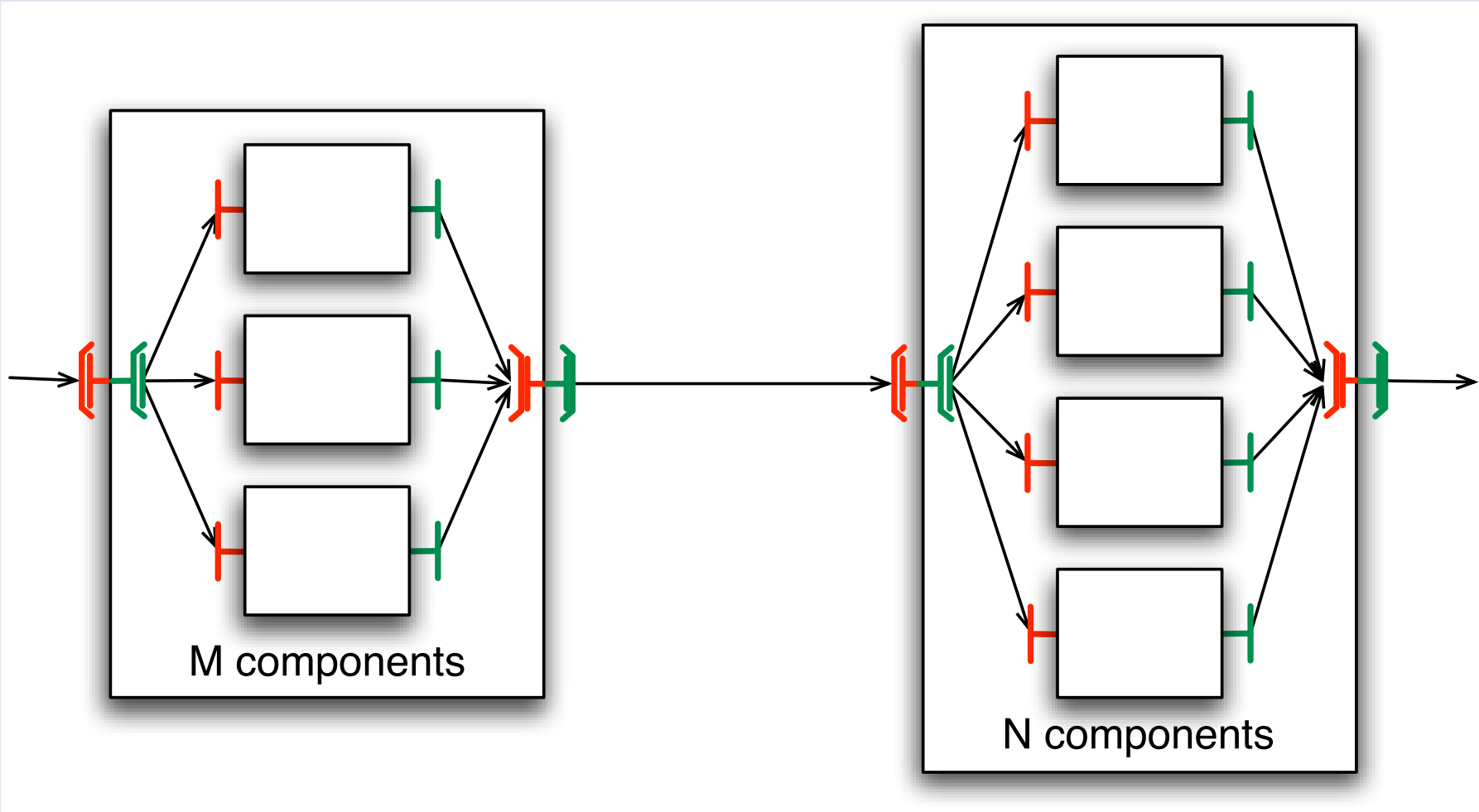


Collective interfaces

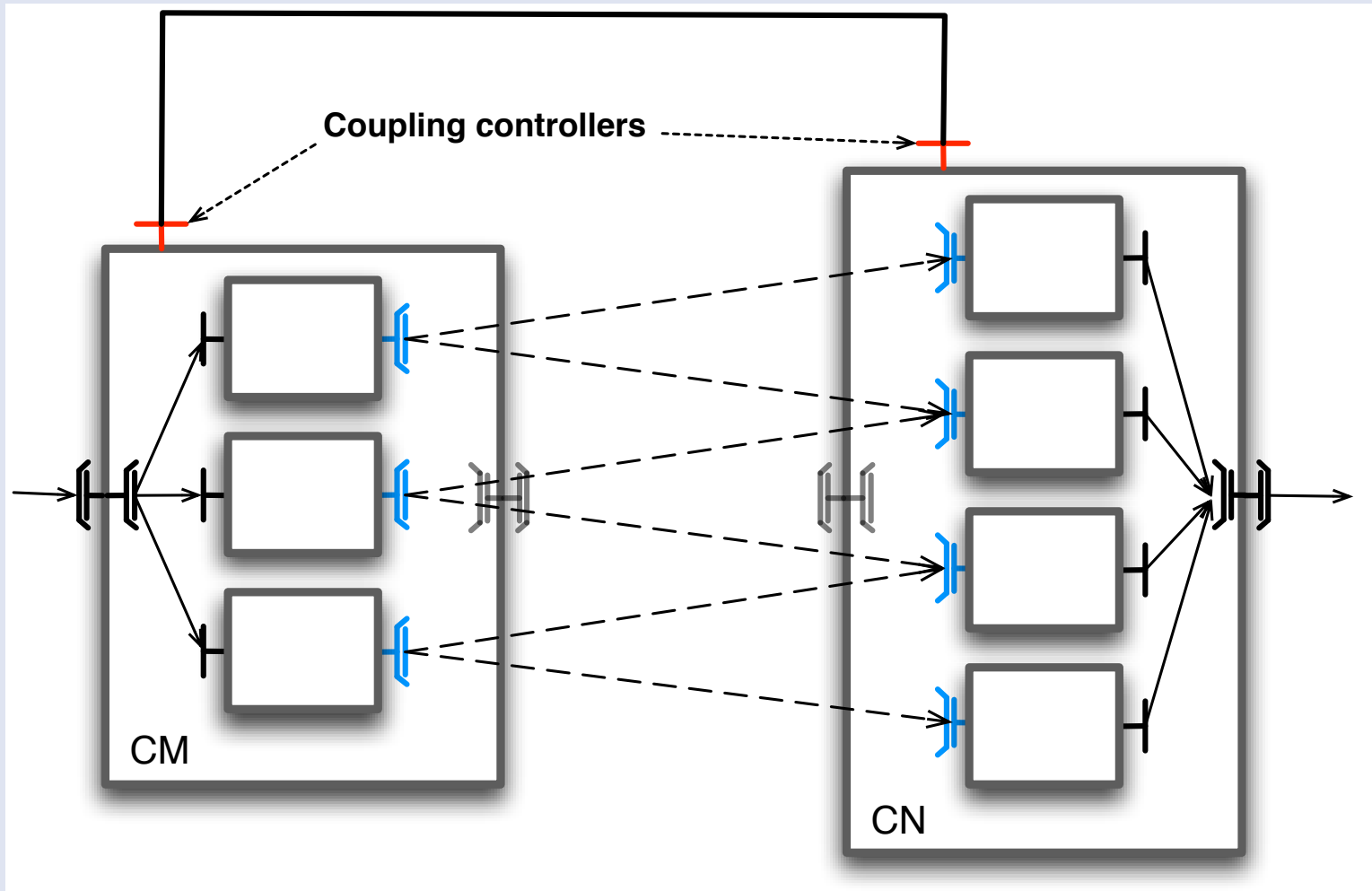
- Specific API → manage collective interfaces and reconfigure them (add client, change policy, ...)
- Allow MxN communications:
 - Redistribution and direct communications for many-to-many communications



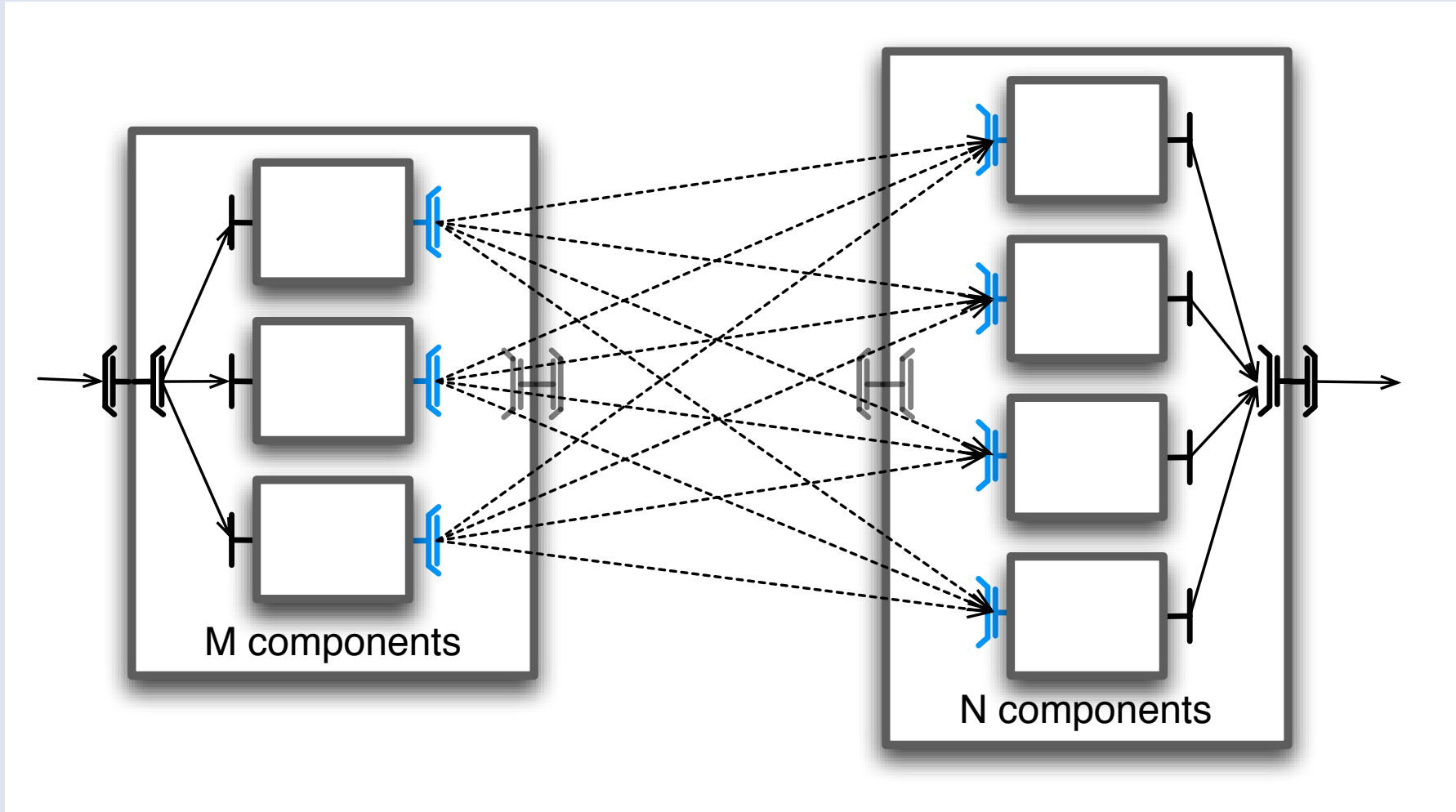
The MxN Problem (1)



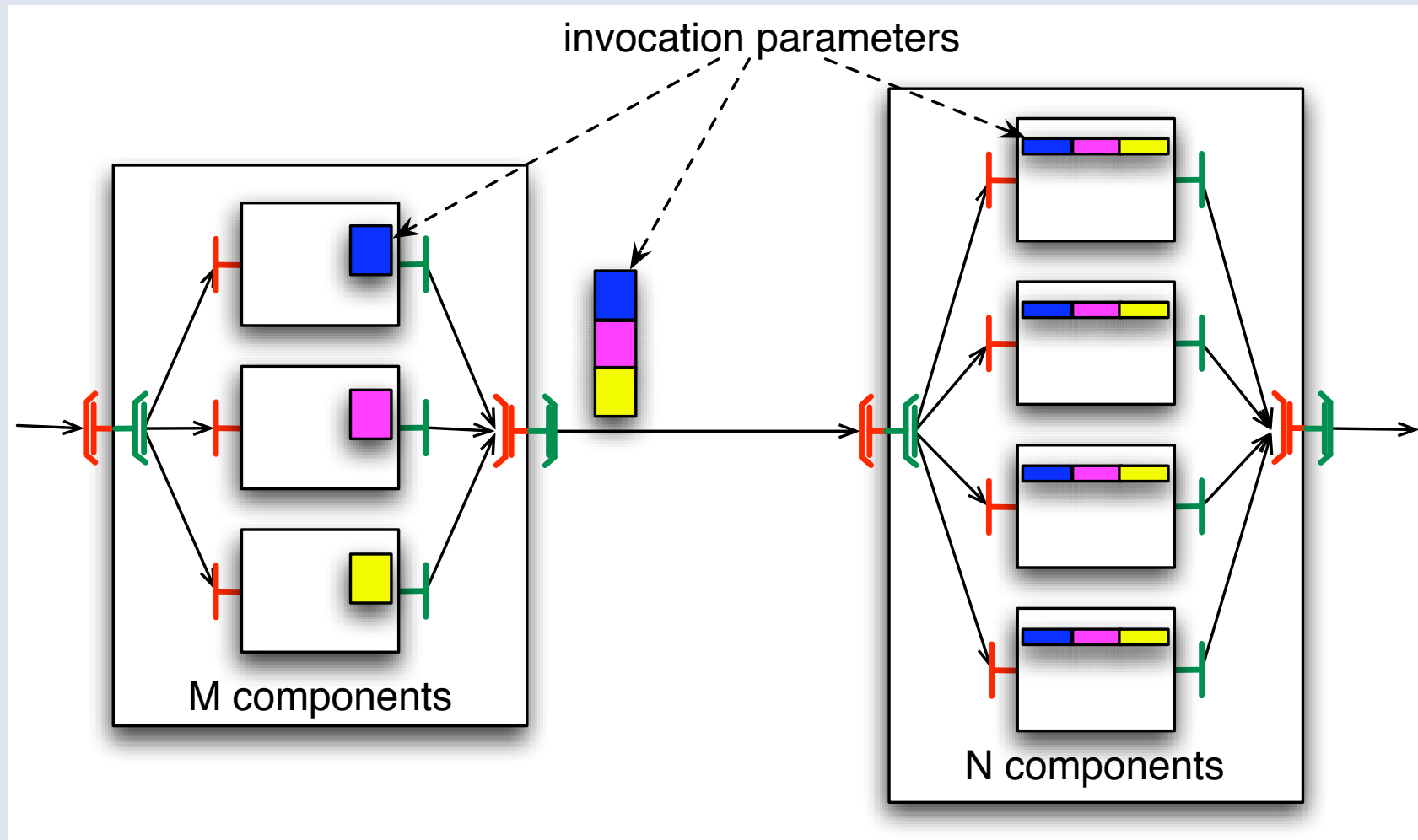
The MxN Problem (2)



The MxN Problem (3)



The MxN Problem (4): data distribution



Summary of Collective Communications

- Simple way of specifying collective operations
- + definition at the level of the interfaces → better for verification and specification
- Rich high levels spec of synchronisation (especially gathercast)
- Easier to optimize
 - The MxN case: synchronisation issues, complex distribution policies avoid bottleneck



A few things we did not cover

- SPMD programming and Synchronization Barriers, cf gathercast???
 - Group communications ~ Multicast
 - Purely synchronous models -> Robert de Simone
 - Shared memory models

 - ... and a lot of more complex communication models
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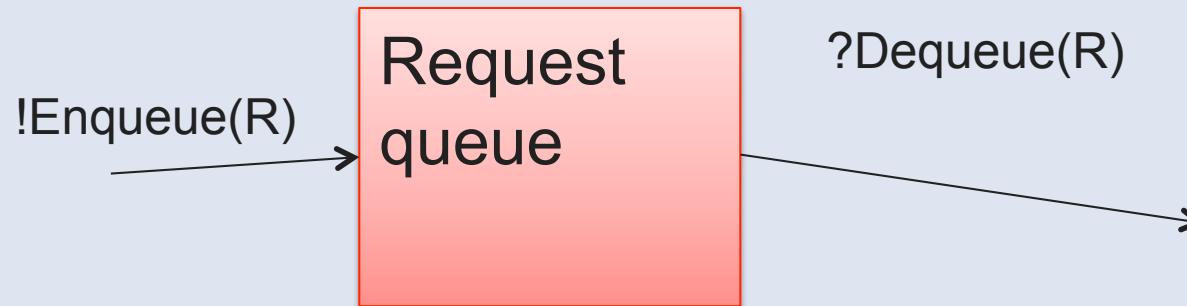
Conclusion

- An overview of asynchronism and different communication timings
 - Applied to components with richer language constructs (futures, collective interfaces, ...)
 - Still a lot of other distributed computing paradigms exist (Ambient Talk, creol, X10 for example)
 - A formalism for expressing communication ordering
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Exercises

Exercise 1: Request queue

- In CCS with parameters (a value can be a request)
 - Express a request queue:

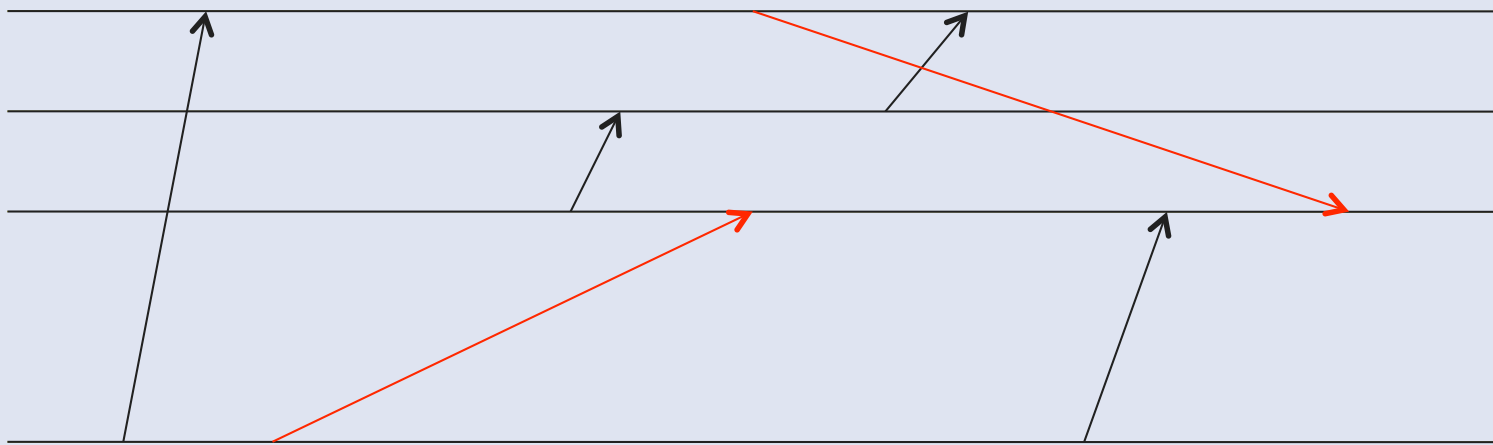
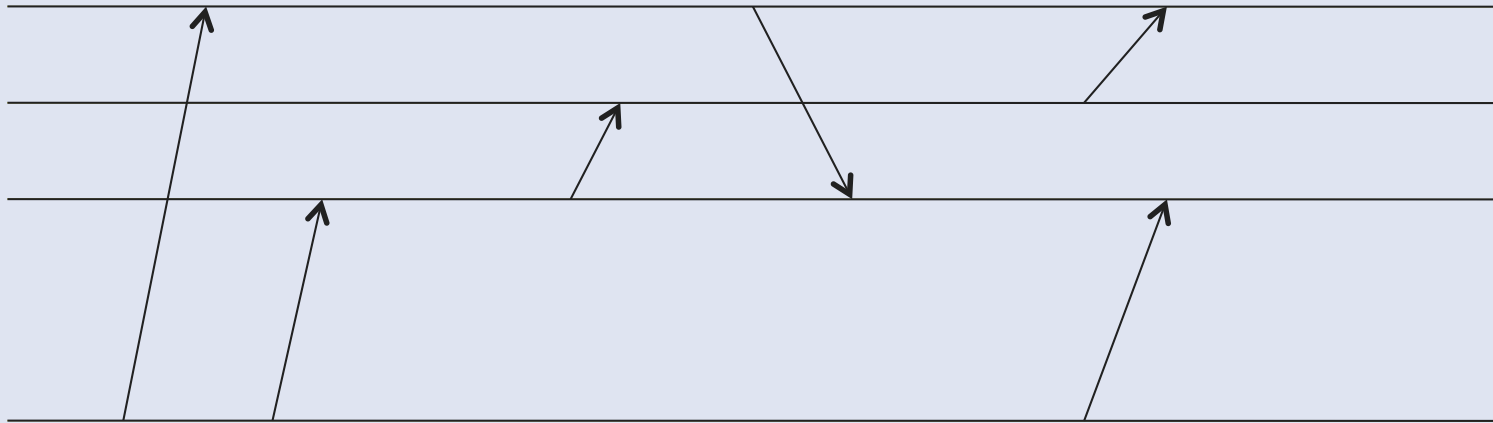


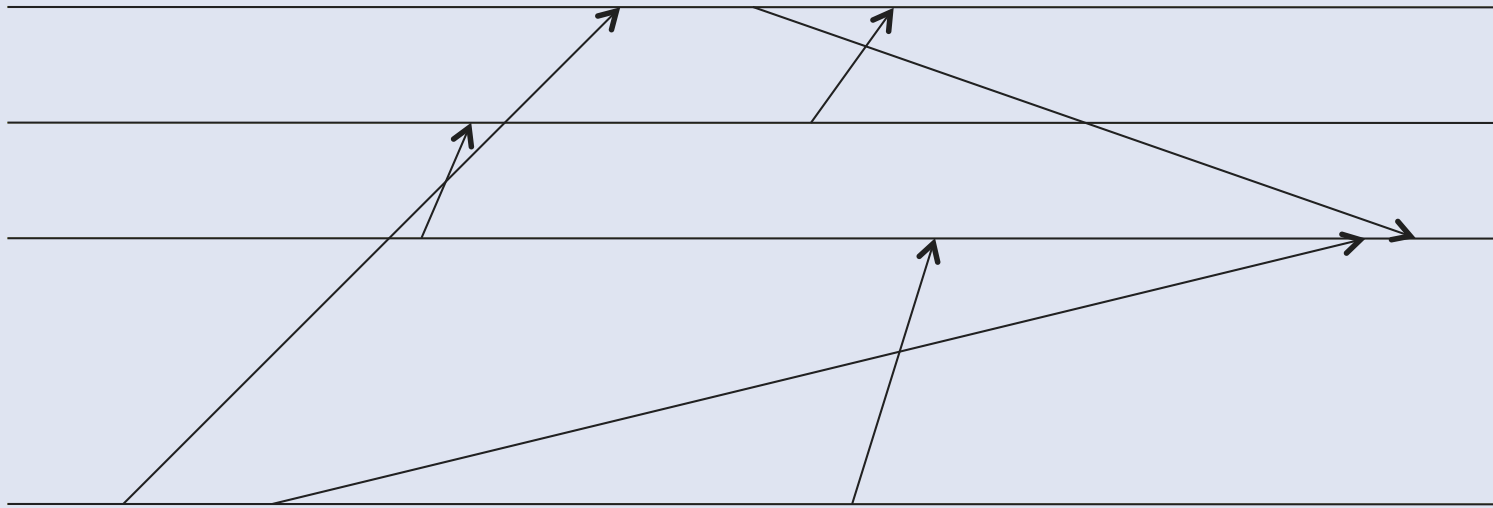
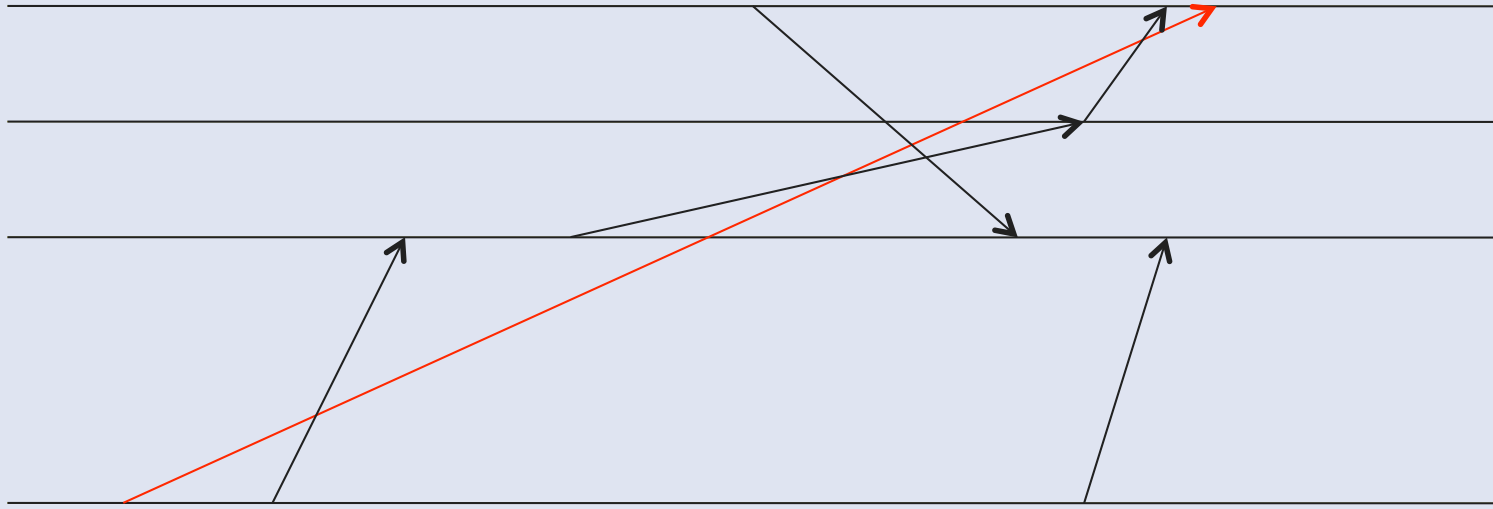
- Also express 2 simple processes accessing it

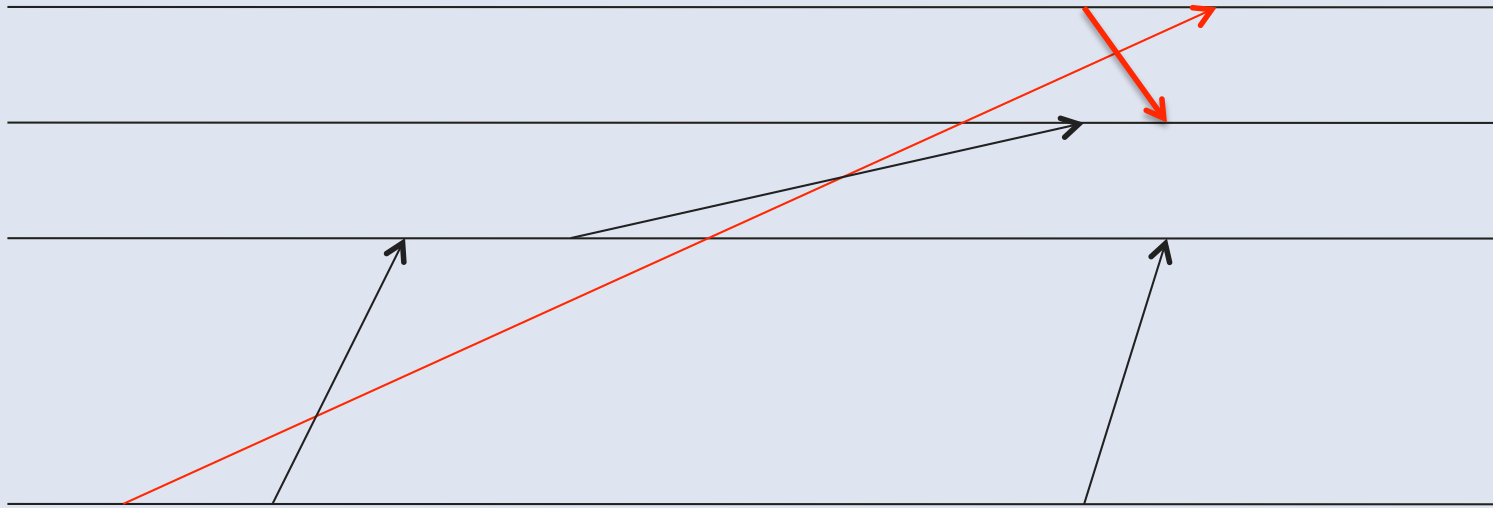
Hint from last course: $\text{Reg}_i = \overline{\text{read}(i)}. \text{Reg}_i + \text{write}(x). \text{Reg}_x$

- Same thing in asynchronous CCS (without and with RDV)

Exercise 2: Are the execution CO, synchronous, asynchronous or FIFO?





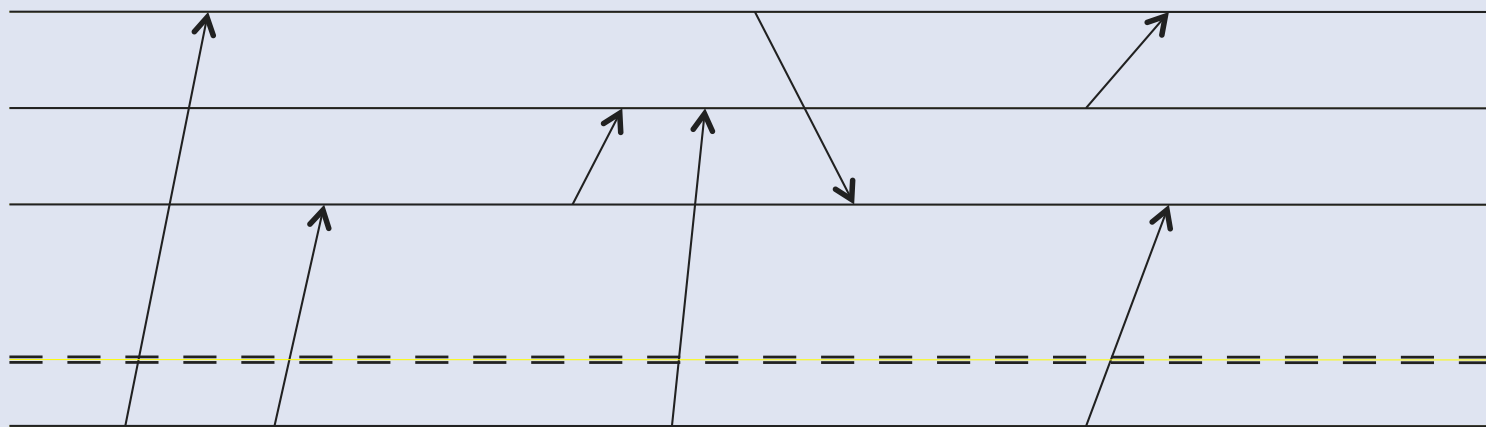


Exercise 3: find a solution to the deadlock slide 31

Exercise 4: Ensuring causal ordering with a sending queue

In the example below, suppose that the bottom thread has a sending queue, that is it sends all messages to an additional thread that emits the final messages.

- Draw the new message exchanges
- Is causal ordering still ensured?
- FIFO ?



Exercise 5: Ensuring causal ordering with many sending queues

- Same thing but with one sending queue per destination process
 - Draw the new message exchanges
 - Is causal ordering still ensured?
 - FIFO ?

