Semantic Formalisms 1: An Overview

- Formal Methods Operational Semantics
- CCS, EquivalencesSoftware Components
- Fractal : hierarchical components Deployment, transformations Specification of components
- Application to distributed applications
 Active object and distributed components
 Behaviour models
 An analysis and verification platform

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Program of the course:
1: Semantic Formalisms

- Semantics and formal methods:
 - motivations, definitions, examples
- Operational semantics, behaviour models : represent the complete behaviour of the system
 - CCS, Labelled Transition Systems
 - Equivalences

Goals of (semi) Formal Methods

- Develop programs and systems as mathematical objects
- Represent them (syntax)
- Interpret/Execute them (semantics)
- Analyze / reason about their behaviours (algorithmic, complexity, verification)
- In addition to debug, using exhaustive tests and property checking.

Software engineering (ideal view)

- Requirements informal
 - User needs, general functionalities.
 - incomplete, unsound, open
- Detailed specification formal ?
 - Norms, standards?..., at least a reference
 - Separation of architecture and function. *No ambiguities*
- development
 - Practical implementation of components
 - Integration, deployment
- Tests (units then global) *vs* verification ?
 - Experimental simulations, certification





Developer Needs

- Notations, syntax
 - textual
 - graphical (charts, diagrams...)
- Meaning, semantics
 - Non ambiguous signification, executability
 - interoperability, standards
- Instrumentation analysis methods
 - prototyping, light-weight simulation
 - verification

How practical is this ?

- Currently an utopia for large software projects, but :
 - Embedded systems
 - Safety is essential (no possible correction)
 - Critical systems
 - Safety, human lives (travel, nuclear)
 - Ligne Meteor, Airbus, route intelligente
 Safety, economy (e-commerce, cost of bugs)

Panne réseau téléphonique US, Ariane 5

• Safety, large volume (microprocessors)

Bug Pentium

Industry succes-stories

- Model-checking for circuit development
 - Finite systems, mixing combinatory logics with register states
- Specification of telecom standards
- Proofs of Security properties for Java code and crypto-protocols.
- Certification of embedded software (trains, aircafts)

Semantics: definition, motivations

• Give a (formal) meaning to words, objects, sentences, programs...

Why?

- Natural language specifications are not sufficient
- A need for understanding languages: eliminate ambiguities, get a better confidence.
- Precise, compact and complete definition.
- Facilitate learning and implementation of languages

Formal semantics, Proofs, and Tools

- Manual proofs are error-prone !
- Tools for Execution and Reasoning
 - semantic definitions are input for meta-tools
- Integrated in the development cycle
 - consistent and safe specifications
 - requires validation (proofs, tests, ...)
- Challenge:

Expressive power versus executability...

Concrete syntax, Abstract syntax, and Semantics

- Concrete syntax:
 - scanners, parsers, BNF, ... many tools and standards.
- Abstract syntax:
 - operators, types, => tree representations
- Semantics:
 - based on abstract syntax
 - static semantics: typing, analysis, transformations
 - dynamic: evaluation, behaviours, ...

This is not only a concern for theoreticians: it is the very basis for compilers, programming environments, testing tools, etc...

Static semantics : examples

Checks non-syntactic constraints

- compiler front-end :
 - declaration and utilisation of variables,
 - typing, scoping, ... static typing => no execution errors ???
- or back-ends :
 - optimisers
- defines legal programs :
 - Java byte-code verifier
 - JavaCard: legal acces to shared variables through firewall

Dynamic semantics

- Gives a meaning to the program (a semantic value)
- Describes the behaviour of a (legal) program
- Defines a language interpreter

 |- e -> e '
 let i=3 in 2*i -> semantic value = 6
- Describes the properties of legal programs

The different semantic families (1)

Denotational semantics

- mathematical model, high level, abstract

• Axiomatic semantics

provides the language with a theory for proving properties / assertions of programs

Operational semantics

- computation of the successive states of an abstract machine
- used to build evaluators, simulators.

Semantic families (2)

• Denotational semantics

- defines a model, an abstraction, an interpretation

 \Rightarrow for the language designers

- Axiomatic semantics
 - builds a logical theory

 \Rightarrow for the programmers

• Operational semantics

- builds an interpreter, or a finite representation \Rightarrow for the language implementors

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Operational Semantics (Plotkin 1981)

- Describes the computation
- States and configuration of an abstract machine:
 - Stack, memory state, registers, heap...
- Abstract machine transformation steps
- Transitions: current state -> next state
 Several different operational semantics

Natural Semantics : big steps (Kahn 1986)

- Defines the results of evaluation.
- Direct relation from programs to results

env |- prog => result

- env: binds variables to values
- result: value given by the execution of prog

Reduction Semantics : small steps

describes each elementary step of the evaluation

- rewriting relation : reduction of program terms
- **stepwise reduction**: <prog, s> -> <prog', s '>
 - infinitely, or until reaching a normal form.

Differences: small / big steps

- Big steps:
 - abnormal execution : add an « error » result
 - non-terminating execution : problem
 - deadlock (no rule applies, evaluation failure)
 - looping program (infinite derivation)
- Small steps:
 - explicit encoding of non termination, divergence
 - confluence, transitive closure ->*

Natural semantics: examples (big steps)

• Type checking :

Terms: X | tt | ff | not t | n | t1 + t2 | if b then t1 else t2 Types: Bool, Int

• Judgements : Typing: $\Gamma \mid -P : \tau$

Reduction: $\Gamma \models P \Rightarrow v$

Deduction rules

Values and expressions:

 $\begin{array}{c} \Gamma \mid - \mbox{ tt} : \mbox{Bool} & \Gamma \mid - \mbox{ tt} : \mbox{Bool} & \Gamma \mid - \mbox{ tt} : \mbox{ bool} & \Gamma \mid - \mbox{ tt} : \mbox{ bool} & \Gamma \mid - \mbox{ tt} : \mbox{ ff} : \mbox{ bool} & \Gamma \mid - \mbox{ tf} : \mbox{ ff} : \mbox{ bool} & \Gamma \mid - \mbox{ tf} : \mbox{ ff} : \mbox{ bool} & \Gamma \mid - \mbox{ tf} : \mbox{ ff} : \mbox{ bool} & \Gamma \mid - \mbox{ tf} : \mbox{ tf} : \mbox{ ff} : \mbox{ bool} & \Gamma \mid - \mbox{ tf} : \mbox{ tf} : \mbox{ ff} : \mbox{ tf} : \mbox{ ff} : \mbox{ tf} : \mbox{ ff} : \mbox{ ff} : \mbox{ tf} : \mbox{ ff} : \mbox{ ff} : \mbox{ ff} : \mbox{ ff} : \mbox{ tf} : \mbox{ ff} : \mbox{ tf} :$

Deduction rules

• Environment :

 $\delta :: \{x \to v\} \mid -x \Rightarrow v \qquad \qquad \delta :: \{x : \tau\} \mid -x : \tau$

• Conditional :

 $\Gamma \mid -\mathbf{b} \Rightarrow \mathbf{true} \qquad \Gamma \mid -\mathbf{e1} \Rightarrow \mathbf{v}$ $\Gamma \mid -\mathbf{if b then \ e1 \ else \ e2} \Rightarrow \mathbf{v}$

Exercice : typing rule ?

Operational semantics: big steps for reactive systems Behaviours

- **Distributed, synchronous/asynchronous programs:** transitions represent communication events
- Non terminating systems
- Application domains:
 - telecommunication protocols
 - reactive systems
 - internet (client/server, distributed agents, grid, e-commerce)
 - mobile / pervasive computing

Synchronous and asynchronous languages

- Systems build from communicating components : parallelism, communication, concurrency
- Asynchronous Processes
 - Synchronous communications (rendez-vous)
 Process calculi: CCS, CSP, Lotos
 - Asynchronous communications (message queues)
 SDL modelisation of channels
- Synchronous Processes (instantaneous diffusion) Esterel, Sync/State-Charts, Lustre

Question on D. Caromel course: how do you classify ProActive ?

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Labelled Transition Systems (LTS)

- Basic model for representing reactive, concurrent, parallel, communicating systems.
- Definition:
 - < S, s0, L, T>
 - S = set of states
 - $S0 \in S = initial state$

L = set of labels (events, communication actions, etc)

 $T \subseteq S \times L \times S = set of transitions$

Notation: $s1 \xrightarrow{a} s2 = (s1, a, s2) \in T$

CCS

(R. Milner, "A Calculus of Communicating Systems", 1980)

• Parallel processes communicating by Rendez-vous :

$$\begin{array}{cccc} & & & & & & & & \\ & & & & & & \\ & & & & & &$$

let rec { st0 = ?a:st1 + !b:st0 } in st0



CCS : behavioural semantics (1) Operators and rules

Inactivity	nil (or skip)	
Action prefix	a : $P \xrightarrow{a} P$	
Non deterministic choice	$\begin{array}{c} P \xrightarrow{a} P' \\ \hline P + Q \xrightarrow{a} P' \end{array}$	$\frac{Q \xrightarrow{\mathbf{a}} Q'}{P + Q \xrightarrow{\mathbf{a}} Q'}$

CCS : behavioural semantics (2)			
More operators, more rules			
	$P \xrightarrow{a} P'$	$Q \xrightarrow{a} Q'$	
Emissions & réceptions are dual actions	$P/ Q \xrightarrow{a} P'/ Q$	$P/ Q \xrightarrow{a} P/ Q'$	
au invisible action (internal communication)	$P \xrightarrow{!a} P'$	$Q \xrightarrow{?a} Q'$	
	$P//Q \xrightarrow{\tau} P'//Q'$		
Recursion : $ [\mu X.P/X]P \xrightarrow{a} P' $	Local action : Tool for forcing synchronisation		
$\mu X.P \xrightarrow{a} P'$	$P \xrightarrow{a} P$?' a∉{?b,!b}	
	local b in P	$\xrightarrow{\mathbf{a}} local \mathbf{b} in \mathbf{P}'$	

Derivations (construction of each transition step)



Par-2(Par_L(Prefix), Prefix) One amongst 3 possible derivations

Another one :

Par-L(Par_L(Prefix))

 $(?a:P \parallel Q) \parallel !a:R \xrightarrow{?a} (P \parallel Q) \parallel !a:R$

Example: Alternated Bit Protocol



Hypotheses: channels can loose messages

Write in CCS ?

Requirement:

the protocol ensures no loss of messages

Example: Alternated Bit Protocol (2)

• emitter =

let rec {em0 = ?ack1 :em0 + ?imss:em1
 and em1 = !in0 :em1 + ?ack0 :em2
 and em2 = ?ack0 :em2 + ?imss :em3
 and em3 = !in1 :em3 + ?ack1 :em0
 }
 in em0

• **ABP** = local {in0, in1, out0, out1, ack0, ack1, ... } in emitter || Fwd_channel || Bwd_channel || receiver

Example: Alternated Bit Protocol (3)

Channels that loose and duplicate messages (in0 and in1) but preserve their order ?

- Exercise :
 - 1) Draw an LTS describing the loosy channel behaviour
 - 2) Write the same description in CCS

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Behavioural Equivalences

- Intuition:
 - Same possible sequences of observable actions
 - Finite / infinite sequences
 - Various refinements of the concept of observation
- Definition: Trace Equivalence

For a LTS (S, s0, L, T) its Trace language T is the set of finite sequences {(t = t₁, ..., t_n such that $\exists s_0, ..., s_n \in S^{n+1}$, and $(s_{n-1}, t_n, s_n) \in T$ }

Two LTSs are Trace equivalent iff their Trace languages are equal.

Corresponding Ordering: Trace inclusion

Trace Languages, Examples

1. Those 2 systems are trace equivalent:

$$a = a / a / c = f(0), (a), (a,b), (a,c)$$

2. A trace language can be an infinite set:

a

$$T = \{(), (a), (a,a), (a,...,a),...$$

(a,b), (a,a,b), (a,a,...,a,b), ... \}

Bisimulation

Behavioural Equivalence

non distinguishable states by observation:

two states are equivalent if for all possible transitions labelled by the same action, there exist equivalent resulting states.

• Bisimulations

- $\mathbf{R} \subseteq \mathbf{S}\mathbf{x}\mathbf{S}$ is a bisimulation iff
- It is a equivalence relation
- $\forall (p,q) \in \mathbb{R}$, (p,l,p') $\in \mathbb{T} \Longrightarrow \exists q'/(q,l,q') \in \mathbb{T}$ and (p',q') $\in \mathbb{R}$

~ is the coarsest bisimulation

2 LTS are bisimilar iff their initial states are in ~ **quotients** = canonical normal forms



Bisimulation (3)

• More precise than trace equivalence :



No state in B is equivalent to A1

• Preserves deadlock properties.

Bisimulation (4)

• Congruence laws:

P1~P2 => a:P1 ~ a:P2 (\forall P1,P2,a) P1~P2, Q1~Q2 => P1+Q1 ~ P2+Q2 P1~P2, Q1~Q2 => P1||Q1 ~ P2||Q2 Etc...

 ~ is a congruence for all CCS operators : for any CCS context C[.], C[P] ~ C[Q] <=> P~Q

Basis for compositional proof methods

Observational Equivalences

- Weak bisimulation
 - Abstraction: hidden actions
 - allows for arbitrary many internal actions



- Branching bisimulation
 - ... only staying in equivalent states

Still existence of a canonical minimal automata Computation is polynomial



Exercice 2 : Bisimulations





Are those LTSs equivalent by:

- Strong bisimulation?
- Weak bisimulation ?

In each case, give a proof.

Exercice 3 : Bisimulation



- Exercice :
 - 1) Compute the strong minimal automaton for A1.
 - 2) Compute the weak minimal automaton for A1.

Exercice 4 : Synchronized Product

Compute the synchronized product of the LTS representing the ABP emitter with the (forward) Channel:



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Automatas with data

from state<i>
provided guard_cond(vars)
then execute body
goto state<j>



• We need add: if_then_else : tree of successor states guards and conditions on external signals local variables (scoping)



Graphical specifications languages : SDL, Statecharts, etc.

The Dream

Provide Analysis and Verification Tools to the (non-specialist) programmer

- Specification Language (textual or graphical)
- Code analysis tools
- Automatic Model-Checking

Tool Set (future...)



Tool Set (future...)



Next courses

- 3) Software Components
 - Fractal : main concepts
 - Deployment, management, transformations
 - Specification of components
- 2) Application to distributed applications
 - ProActive : active object and distributed components
 - Behaviour models
 - Tools : build an analysis and verification platform

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