

A posteriori estimates and mesh adaptation for the thermistor problem

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Outline

- The Grenoble High Magnetic Field Lab
- In the thermistor problem: study and numerical resolution
- A posteriori estimate
- Application to adaptation

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1. The Grenoble High Magnetic Field Lab

- Resistive magnets (34 Tesla, 30000A, 20 MW)
- Water cooling, high flow (201/s)



Polyhelice



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- Geometrical optimization [1].
- Heating effect and mechanical stress: Joule, Lorentz.

1. The Grenoble High Magnetic Field Lab



Potential ϕ in a cut of a 3D Magnet... under some simplifications.

... on an helix

• Magnetic field **b** and current density **j**:

$$\forall x \in \Omega, \quad \mathbf{j}(x) = \sigma(u) \nabla \phi(x),$$

$$\forall x \in \omega, \quad \mathbf{b}(x) = \mu \int_{\Omega} \mathbf{j}(y) \wedge \nabla G(x, y) \, dy,$$

Model

Find $(\phi, u) : \Omega \to \mathbb{R}$ s.t.: $\begin{pmatrix}
-div (\sigma(u) \nabla \phi) &= f & \text{in } \Omega, \\
-div (\kappa(u) \nabla u) &= \sigma(u) |\nabla \phi|^2 & \text{in } \Omega, \\
\phi &= \phi_0 & \text{on } \Gamma_1, \\
-\sigma(u) \nabla \phi.\mathbf{n} &= 0 & \text{on } \Gamma_2, \\
u &= u_W & \text{on } \Gamma_2, \\
-\kappa(u) \nabla u.\mathbf{n} &= 0 & \text{on } \Gamma_1.
\end{pmatrix}$



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- $\Omega, \omega \subset \mathbb{R}^2, \omega \cap \Omega = \emptyset$.
- σ et κ bounded, Lipschitz-continuous on $\mathbb{R}^{+*}.$

Difficulties

- Geometry: highly non convex, fissures, holes.
- Numeric: mesh, method?
- A posteriori estimate on b?

Model

Let Ω be a polygonal domain, and ω_i the interior angle between two consecutive edges of Ω . Let $\omega_i^* s.t.$: $\omega_i^* = \omega_i$ if the two edges have the same BC, $\omega_i^* = 2\omega_i$ else. Let $\omega^* = max_i(\omega_i^*)$

If
$$\kappa$$
, $\sigma : \Omega \mapsto \mathbb{R}$, $\in C^m(\overline{\Omega})$ and $f \in L^s(\Omega)$, $s > 1$.
 $\implies u, \phi \in H^{1+2/q}(\Omega)$, $q > max(q^*, 2)$, $q^* = \frac{2}{\pi}\omega_f^*$

 (C_h) : Find $u_h \in V_h$ and $\phi_h \in W_h$ s.t.

$$\int_{\Omega} \kappa(u_h) \nabla u_h \nabla v_h dx = \int_{\Omega} \sigma(u_h) |\nabla \phi_h|^2 v_h dx, \forall v_h \in V_h$$

$$\int_{\Omega} \sigma(u_h) \nabla \phi_h \nabla \psi_h dx = \int_{\Omega} f \psi_h dx, \quad \forall \psi_h \in W_h$$

Model

If more general conditions on Ω , well-posed problem, associated to the limit-problem [2,3]:

Let $\tau(\theta) = \sigma \ o \ \kappa^{-1}(u)$, $(C') : Find \ \theta \in L^2(\Omega) \ and \ \phi \in H^1_0(\Omega) \ s.t.$

$$\begin{split} \int_{\Omega} \theta.\xi \, \mathrm{d}x &= \int_{\Omega} \tau(\theta) \, |\nabla \phi|^2 \, (\Delta^{-1}\xi) \, \mathrm{d}x, \, \forall \xi \in L^2(\Omega) \\ \int_{\Omega} \tau(\theta) \nabla \phi. \nabla \psi \, \mathrm{d}x &= \int_{\Omega} f \psi \, \mathrm{d}x, \, \forall \psi \in H^1(\Omega) \end{split}$$

 $\implies \exists (\theta, \phi) \in H^{s}(\Omega) \times H^{1}_{0}(\Omega), \, s < 1/2 \text{ solutions of } (C').$

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Numerical simulation

Relaxed Fixed-Point Algorithm:

$$\int_{\Omega} u^{n+1} v \, dx + \Delta t \int_{\Omega} \kappa(u^n) \, \nabla u^{n+1} \nabla v \, dx = \Delta t \int_{\Omega} \sigma(u^n) |\nabla \phi^{n+1}|^2 \, v dx + \int_{\Omega} u^n \, v dx \quad \forall v \in V_h,$$
$$\int_{\Omega} \sigma(u^n) \, \nabla \phi^{n+1} \nabla w dx = \int_{\Omega} f \, w \, dx \quad \forall w \in W_h,$$

 $u^{n+1} = \sum_{i} u_i^{n+1} v_i, v_i \text{ finite element of order } k \text{ on quads.}$ (gmsh, deal.ii) Stop when $||u^{n+1} - u^n||_{L^2} < \varepsilon.$

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3. A posteriori estimates

Looking forward an estimate η s.t. $\|u - u_h\|_{H^1} + \|\phi - \phi_h\|_{H^1} \leq \eta \leq h^p$.

- Theoretical estimate [5] with residual and edge terms.
- Kelly estimate of u defined on an element K [6]:

 $\eta_{\mathcal{K}}^{2}(u) = \frac{h}{24} \int_{\partial \mathcal{K}} \left[\frac{\kappa(u_{h}) \, \partial u_{h}}{\partial \mathbf{n}} \right]^{2} \, ds \qquad \Longrightarrow \text{ convergence order } \gamma$

• Comparison of $\gamma + 1$ with λ solution of [3]:

(1)
$$\frac{\|u_{h_{n-1}}-u_{h_{n-2}}\|_{L^{2}(\Omega)}}{\|u_{h_{n}}-u_{h_{n-1}}\|_{L^{2}(\Omega)}} = \frac{(h_{n-2}/h_{n-1})^{\lambda}-1}{1-(h_{n}/h_{n-1})^{\lambda}}$$

 \implies Validation of Kelly estimate.

 \implies Numerical indicators for the error: γ et λ .



3. A posteriori estimates

Comparison with an analytical solution



	Q ₁			Q ₂			<i>Q</i> ₃		
	rel. err.	λ	γ	rel. err.	λ	γ	rel. err.	λ	γ
ø	1.99	1.97	0.84	2.97	2.95	2.73	3.99	3.51	2.85
u	2.00	2.00	0.98	2.98	2.54	2.49	3.96	2.41	2.96

Convergence orders for ϕ and *u* and several Q_k .

rel. err. =
$$\frac{\|u - u_h\|_{L^2}}{\|u\|_{L^2}}$$
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4. Application to adaptation



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4. Application to adaptation

Non convex geometry

	6) 1	G) ₂	Q_3	
	γ	λ	γ	λ	γ	λ
ø	1.42	0.70	1.43	0.67	1.45	0.67
u	1.52	0.55	1.82	0.53	1.76	0.54

Convergence orders for ϕ and *u* and several Q_k .

 \implies Ok with the theory, *u* and $\phi \in H^s$, with *s* > 1.66.

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Conclusion and perspectives

- Numerical study of an efficient A posteriori estimate for the thermistor problem [3].
- Efficiency of the adaptive scheme.
- Limitation by hanging nodes on quads?
- Future developpements: A posteriori error estimate for the magnetic field, by means of a optimal control approach [7].

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