

TCP in presence of bursty losses

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Outline

- Introduction
 - What do we mean by bursty losses?
- Our models
 - A fluid model for rate evolution
 - A two-state Markovian model for losses
- Performance analysis
 - Moments and throughput calculation
- Model validation, conclusions and future work

TCP and losses

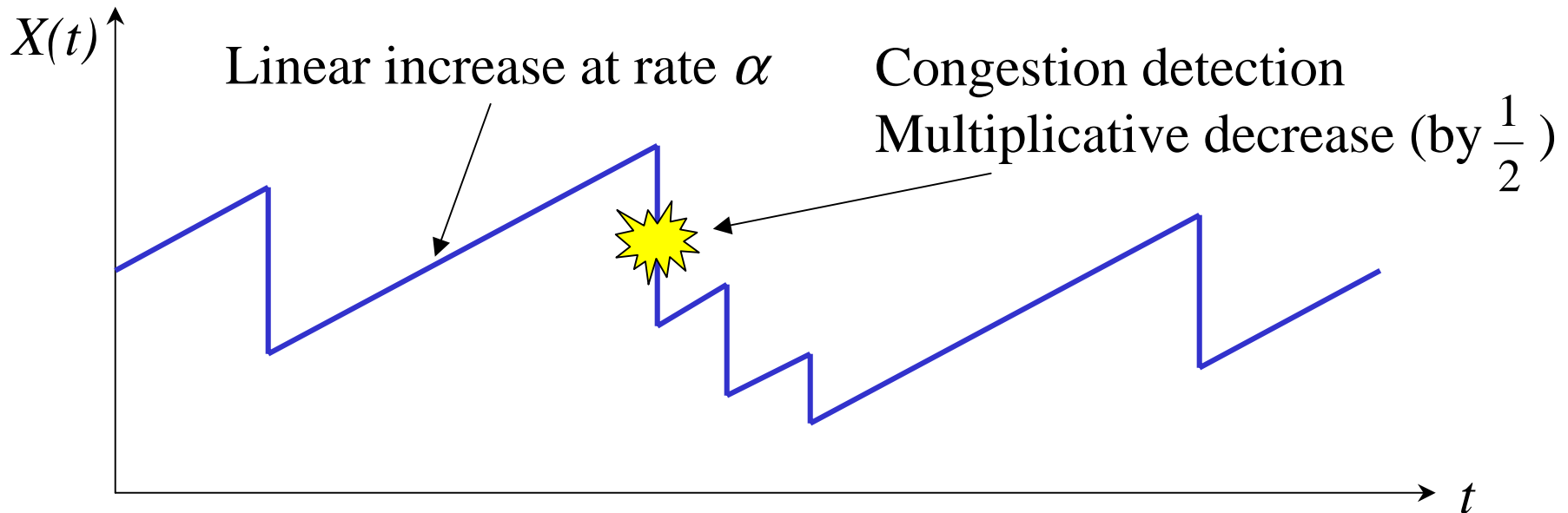
- TCP
 - Internet widely used transport protocol
 - An additive-increase multiplicative-decrease strategy for congestion control
 - Packet losses for congestion detection (possibly ECN)
- Loss event (or congestion event)
 - An event that causes the reduction of the congestion window
 - **Interpretation:** Depends on the version of TCP
 - One packet loss for Reno
 - One lossy round trip-time for Tahoe, New-Reno and SACK

Why bursty losses?

- TCP modeling requires a characterization of inter-losses times
- Simple loss processes have been considered in the literature
(Deterministic e.g. [Mathis et al. 1997], Poisson e.g. [Misra et al. 1999])
- TCP throughput has been only expressed as a function of the average loss rate (e.g. p , λ)
- What happens if, for the same average loss rate, loss events tend to appear in bursts?

Our fluid model for TCP

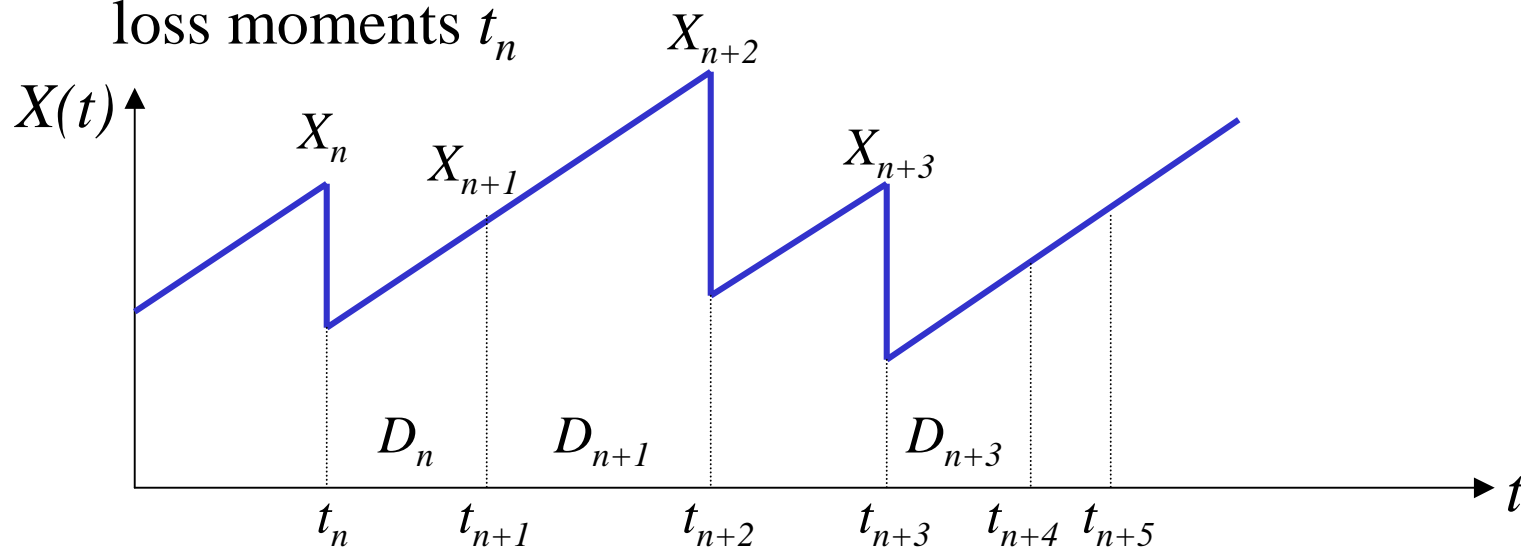
- Consider a long TCP transfer with infinite data to send
- Denote by $X(t)$ the rate of the connection at time t ($=W(t)/RTT$)
- Assume that losses are quickly detected (without long Timeout)



Our Markovian model for losses

Potential loss moments

- Reduce the rate with a certain probability at some potential loss moments t_n

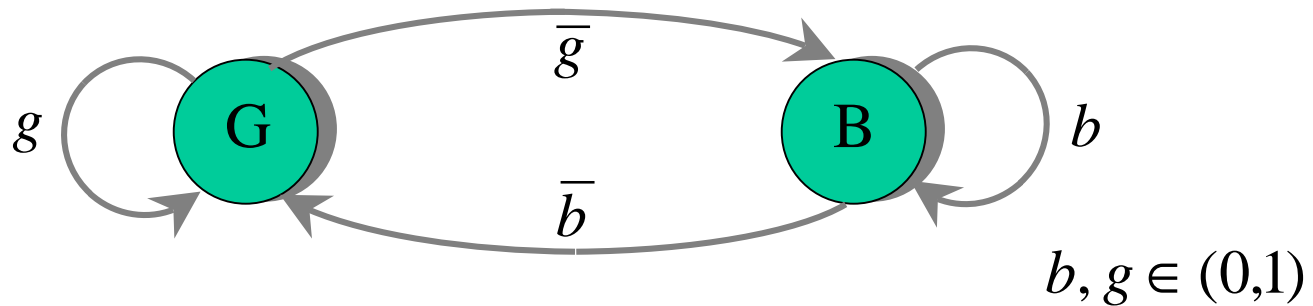


★ **Assumptions:** $\{D_n\}$ are i.i.d., $d = E[D_n] < \infty$, $d^{(2)} = E[D_n^2] < \infty$

Our Markovian model for losses

The Markov chain

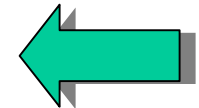
- The path is in one of two states: **Bad** (B) or **Good** (G)
- Reduce the transmission rate (the window) at potential loss moments with different probabilities ($p_G < p_B$)
- Denote by $Y(t)$ the state of the path
- Take $\{Y_n\}$ as a two-state Markov chain (Gilbert model)



Performance analysis

- Input parameters

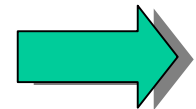
- The average loss rate $R = \frac{p_G \pi_G + p_B \pi_B}{d}$
- The burstiness of losses via b and g



- Output parameter

- The throughput of the connection

$$\bar{x} = \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t X(\tau) d\tau$$



Stochastic difference equation

Let U_n (resp. V_n) $\in \{0,1\}$ indicate whether or not the rate is reduced at t_n in the **Good** (resp. **Bad**) state

$$X_{n+1} = \left(1 - \frac{U_n}{2}\right) X_n 1\{Y_n = G\} + \left(1 - \frac{V_n}{2}\right) X_n 1\{Y_n = B\} + \alpha D_n$$

Using Theorem 2A in [Glasserman and Yao, 1995], and the fact that the reduction factor is one half, $d < \infty$, $\{Y_n\}$ is ergodic, we proved

- The difference equation has a unique stationary solution X_n^*
- X_n converges to X_n^* for any initial state X_0
- $\{X_n\}$ is an ergodic process

Convergence of first moments

Let

$$\chi_n = \begin{bmatrix} E[X_n 1\{Y_n = G\}] \\ E[X_n 1\{Y_n = B\}] \\ P(Y_n = G) \\ P(Y_n = B) \end{bmatrix}$$

We can write $\chi_{n+1} = \Pi \chi_n$ where Π is some matrix with only one eigenvalue equal to 1 and the others less than 1. Thus, χ_n converges and we define

$$x_G = \lim_{n \rightarrow \infty} E[X_n 1\{Y_n = G\}]$$

$$x_B = \lim_{n \rightarrow \infty} E[X_n 1\{Y_n = B\}]$$

Calculation of moments

$$Z(s) = [Z(s, G) \quad Z(s, B)] = \lim_{n \rightarrow \infty} [E[e^{-sX_n} 1\{Y_n = G\}] \quad E[e^{-sX_n} 1\{Y_n = B\}]]$$

From the stochastic difference equation, conditioning on the state of the path, we get the following implicit LT equation

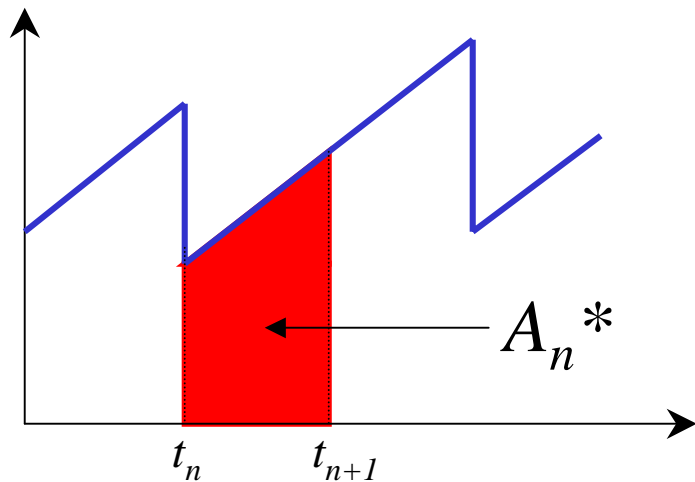
$$Z(s) = D^*(\alpha s)Z(s)P_1 + D^*(\alpha s)Z(s/2)P_2$$

$$P_1 = \begin{bmatrix} g(1-p_G) & \bar{g}(1-p_G) \\ \bar{b}(1-p_B) & b(1-p_B) \end{bmatrix} \quad P_2 = \begin{bmatrix} gp_G & \bar{g}p_G \\ \bar{b}p_B & bp_B \end{bmatrix}$$

By taking derivatives and then setting s to 0, we can get all the moments of X_n^* as a function of d , g , b , p_G and p_B

Calculation of the throughput

$$\bar{x} = \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t X(\tau) d\tau = \lim_{n \rightarrow \infty} \frac{\sum_{i=0}^{n-1} \int_{t_i}^{t_{i+1}} X(\tau) d\tau}{\sum_{i=0}^{n-1} D_i} = \frac{E[A_n^*]}{d}$$



The throughput



$$\bar{x} = \left(1 - \frac{p_G}{2}\right) x_G + \left(1 - \frac{p_B}{2}\right) x_B + \frac{1}{2} \alpha \frac{d^{(2)}}{d}$$

Impact of burstiness

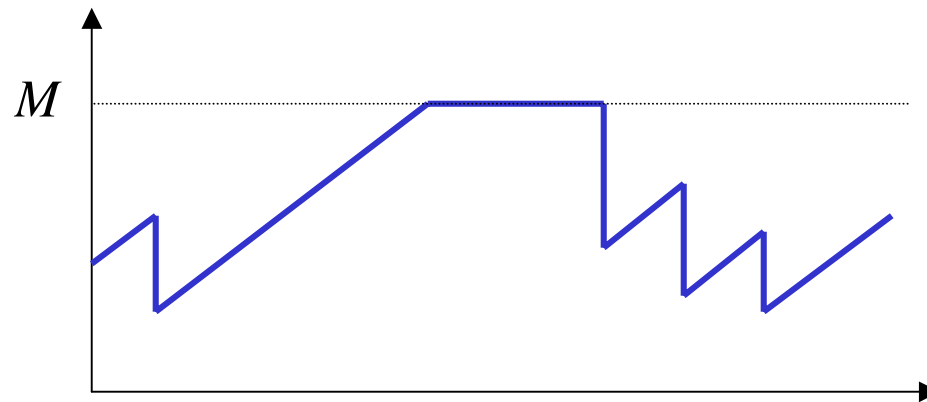
- Consider in the following the case $p_G=0, p_B=1$ (no losses in the **Good** state and always losses in the **Bad** state)
- Define \bar{x}_r as the throughput when losses are not bursty (a path with one state and with a loss probability π_B)

$$\bar{x} = \bar{x}_r + \alpha d \pi_G \left(\frac{1}{1-g} - \frac{1}{\pi_B} \right)$$

- The second term of the right-hand equation is always positive and **increases** with the burstiness (when g and b increase in a way that π_B and π_G remain constant)

Case of rate limitation

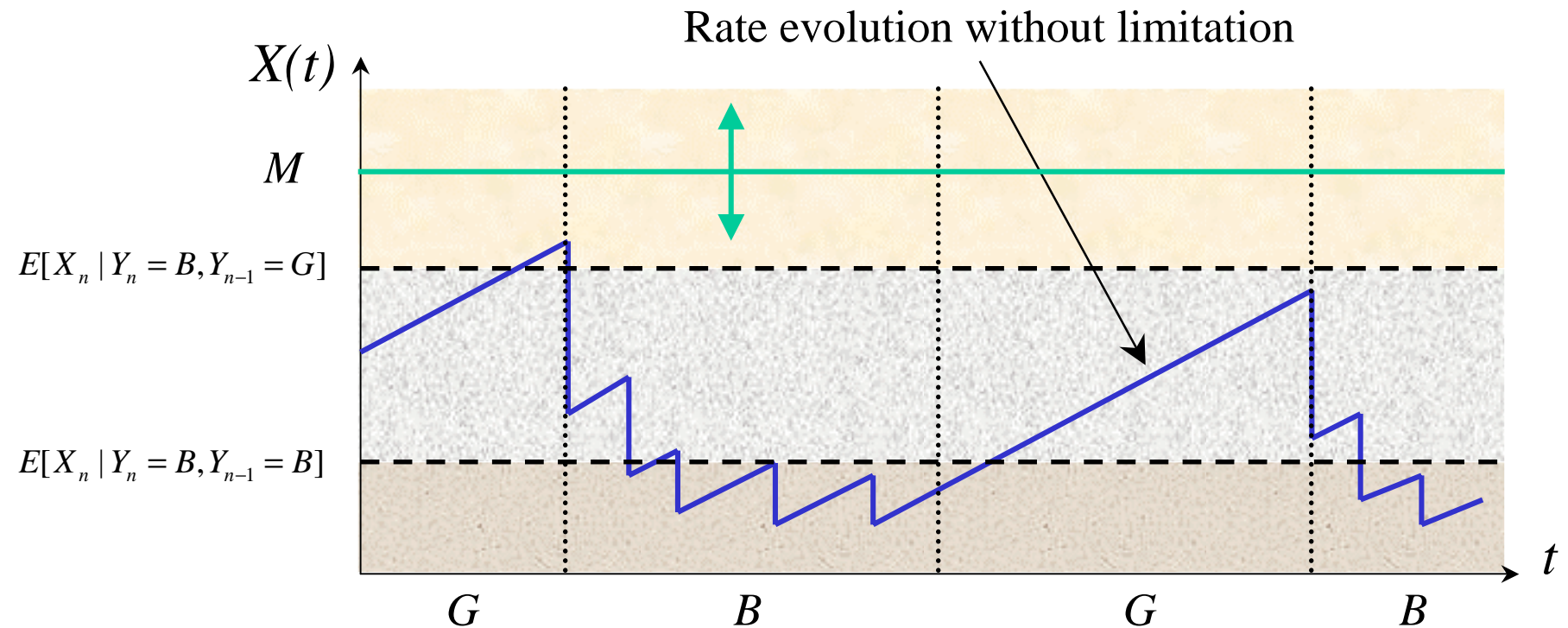
- The transmission rate may not exceed a certain limit (the receiver window in case of TCP, the PCR in case of ABR)



- We use a heuristic similar to that in [Padhye et al. 1998] to approximate the throughput

Throughput approximation

Divide the space of M into three regions



Throughput approximation

Large M

- Use the expression of \bar{x} we found in case $M=\infty$

Medium M

- Assume that during the **Good** state, the rate starts at $x_0 = E[X_n | Y_n = G, Y_{n-1} = B]$, reaches and stays at M until the next loss event where it drops
- Calculate the average rate during the Good state \bar{x}_G
- Calculate the average rate during the Bad state \bar{x}_B using the expression of the throughput in case $M=\infty$

$$\bar{x} = \pi_G \bar{x}_G + \pi_B \bar{x}_B$$

Throughput approximation

Small M

- Take $\bar{x}_G = M$
- Calculate \bar{x}_B using the assumption that the rate reaches M between two potential losses

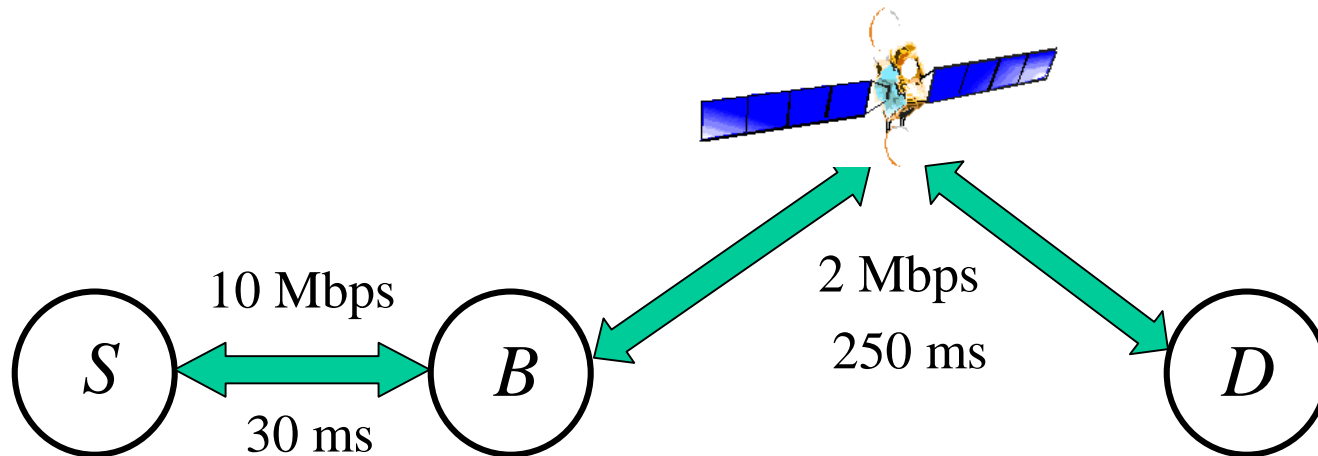
$$\bar{x} = \pi_G \bar{x}_G + \pi_B \bar{x}_B = M - \frac{M^2 \pi_B}{8\alpha d}$$

★ **Difference from [Padhye et al. 1998]**

We obtain more refined bounds by taking into account the bursty occurrence of losses

Model validation

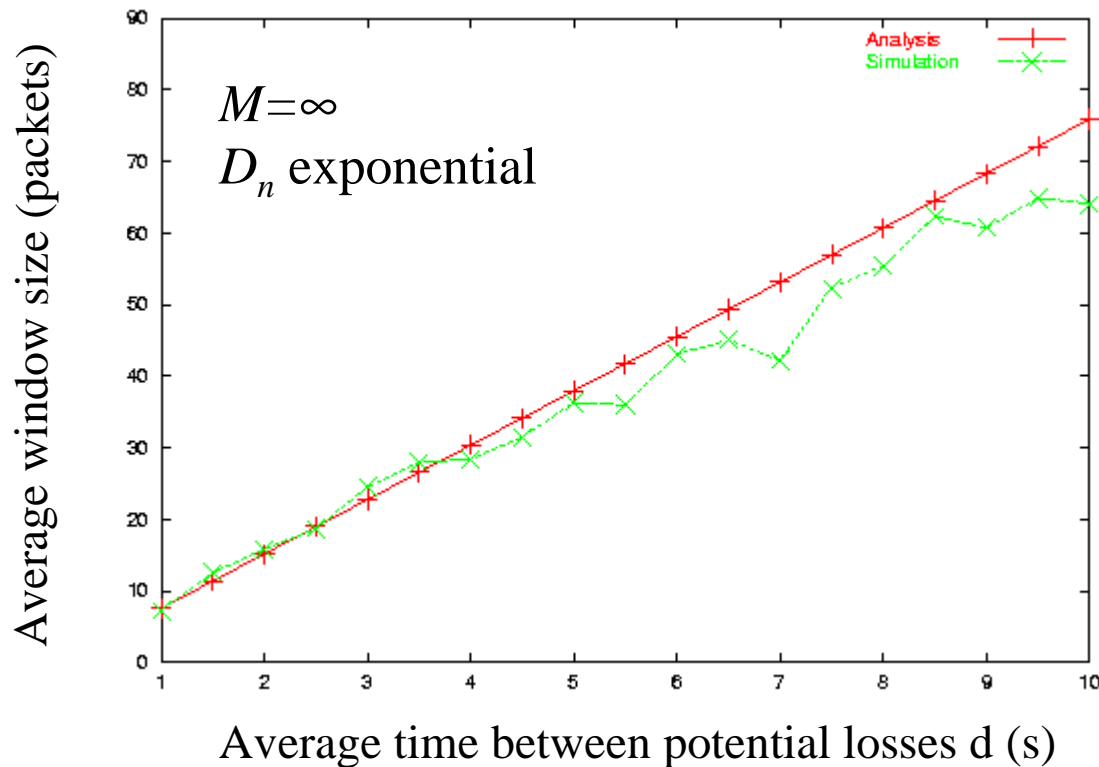
Add our model for losses to the Error Model object of the ns simulator and attach it to a satellite link



- A long ftp transfer (one hour)
- TCP version : SACK
- Packet size : 1000 bytes

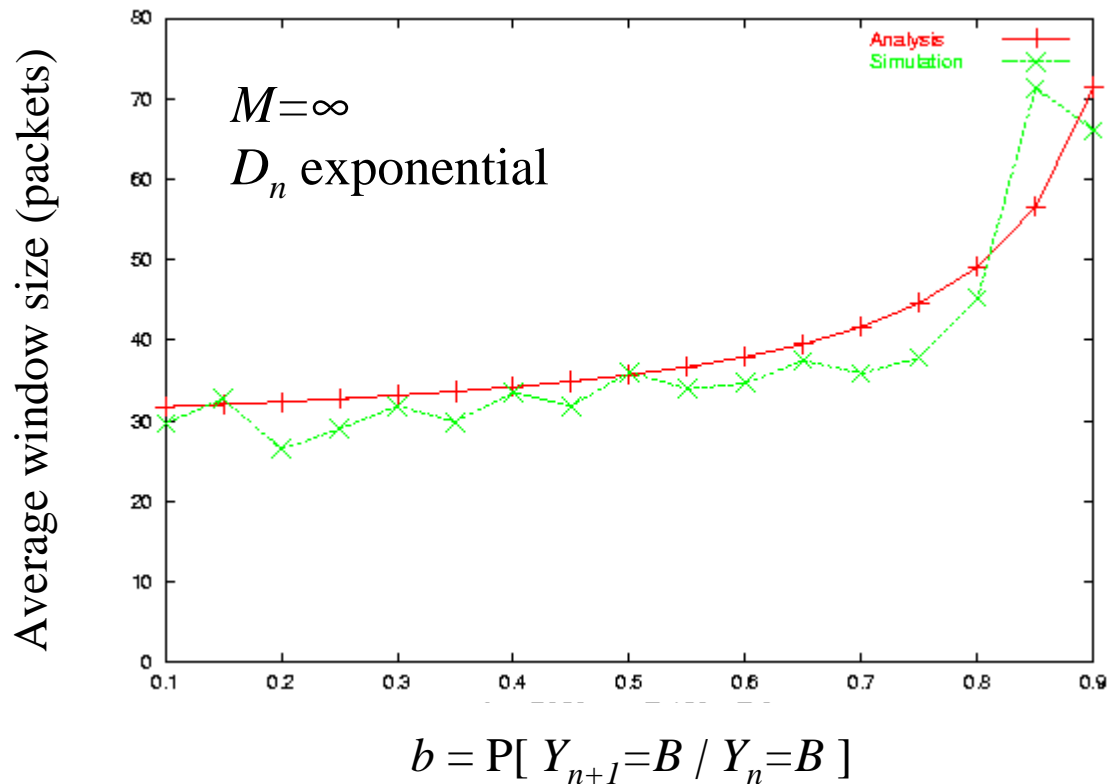
Variation of loss intensity

Fix g and b to 0.6 and change the inter-potential loss time



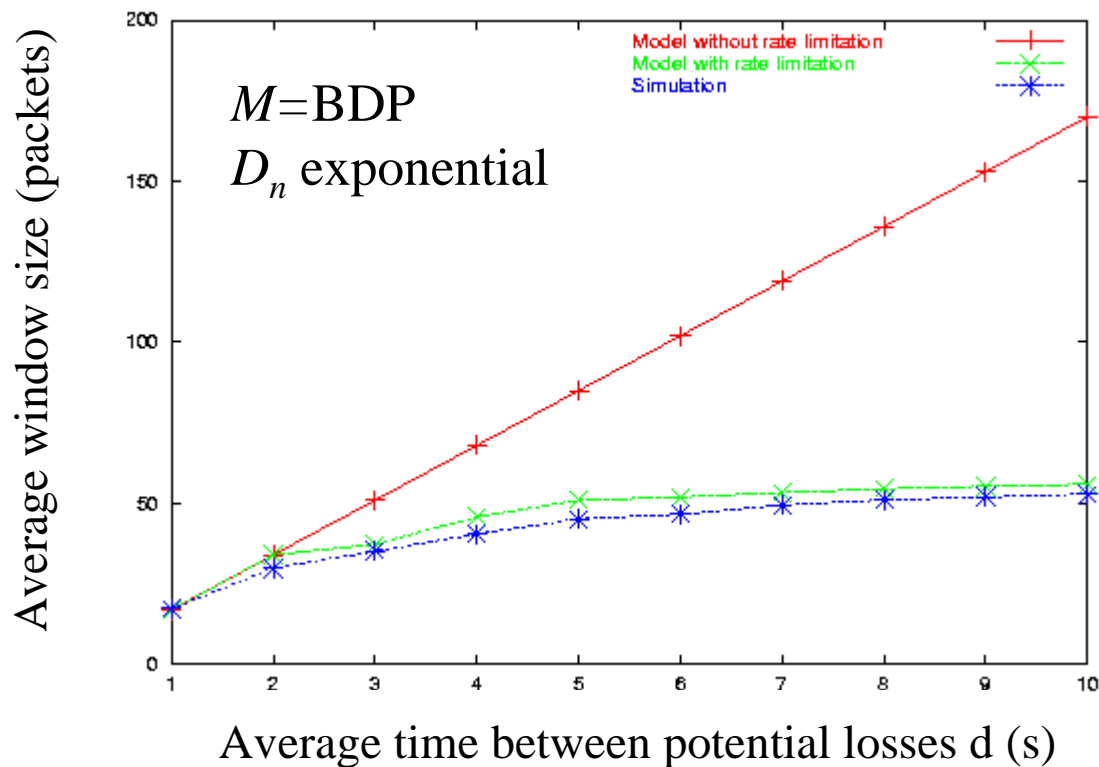
Variation of burstiness

Fix d to 5 s and change b and g in a way that $\pi_G = \pi_B = 0.5$



Variation of loss intensity

Fix g and b to 0.6 and change the inter-potential loss time



Conclusions

- A two-state Markovian model for TCP performance (or any other similar flow control mechanism) on bursty paths
- For the same average loss rate, the performance of TCP *increases* when loss events tend to appear in bursts
- ★ Current formulas are conservative in a bursty environment

Ongoing works

- Generalization of the model to multi-state paths
- Identification of the model parameters from real traces (uniformization technique)

E. Altman, K. Avrachenkov, C. Barakat, P. Dube, “TCP over a multi-state Markovian path”, under submission

- Study of TCP under a general (not only Markovian) loss process

E. Altman, K. Avrachenkov, C. Barakat, “A stochastic model of TCP/IP with stationary random losses”, to appear at ACM SIGCOMM