Analysis of TCP with Several Bottleneck Nodes

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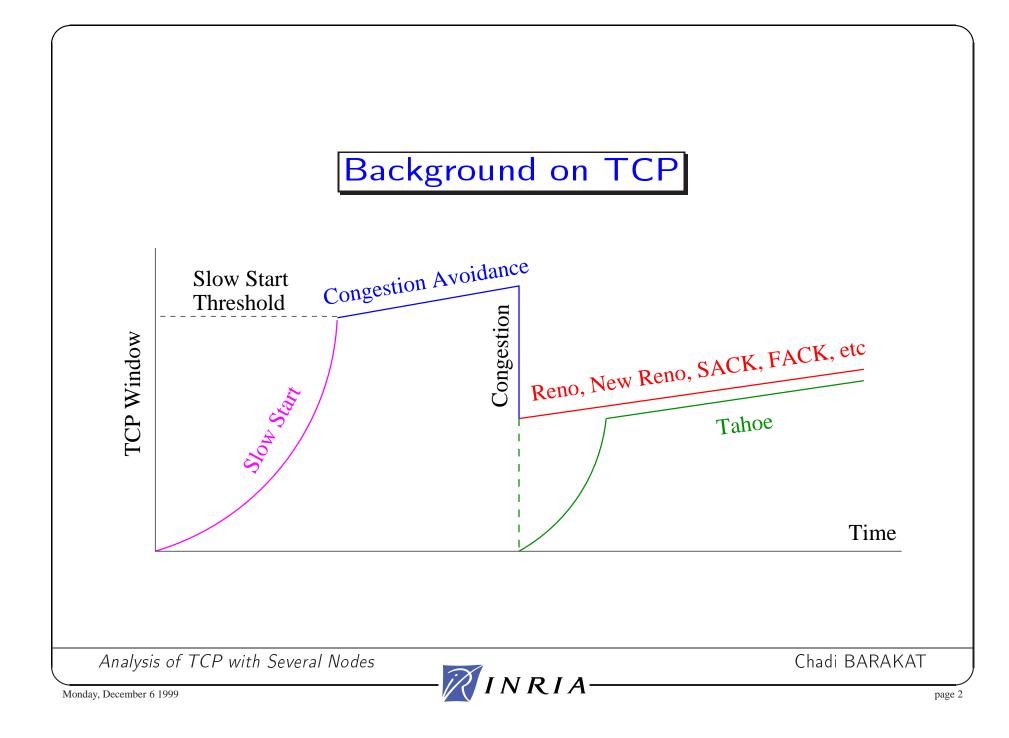


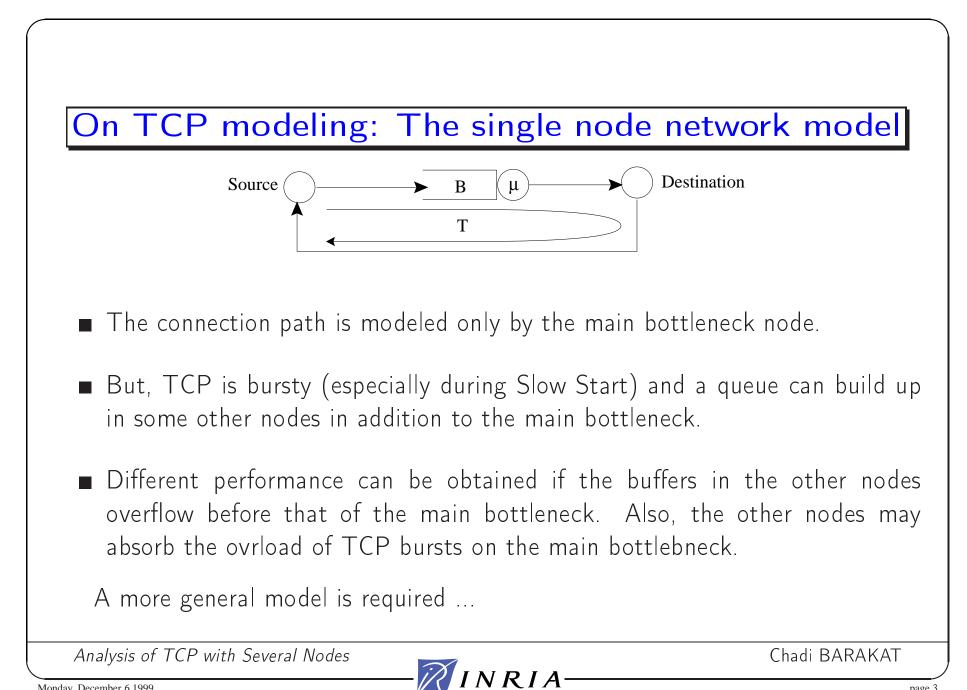
- Background on TCP congestion control algorithms.
- Insufficiency of the single node network model.
- Definition of a general network model for TCP analysis.
- Study of TCP algorithms with the general model.
- Simplification of the general model to a two-node model.
- Impact of network parameters on TCP performance.
- Conclusions and general guidelines.

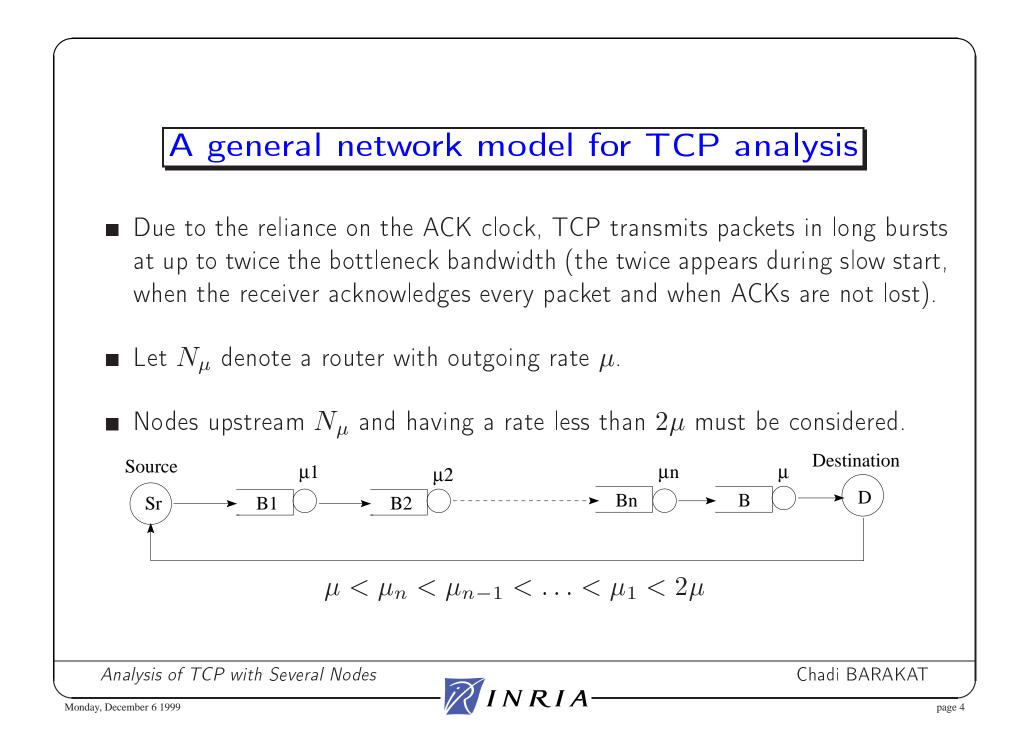
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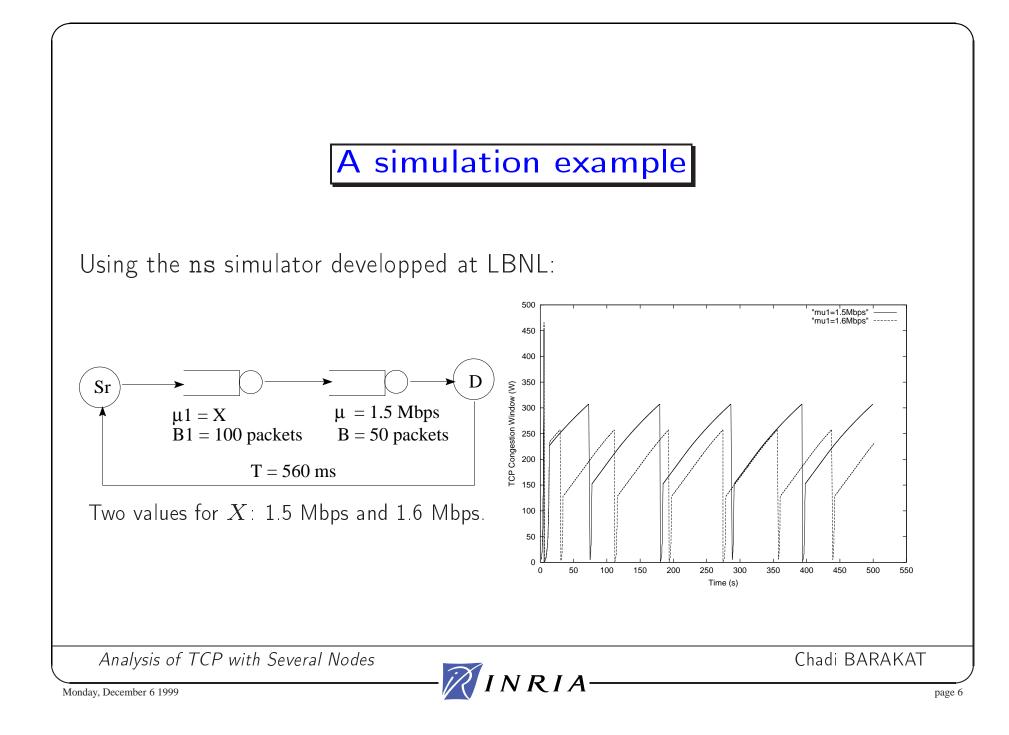


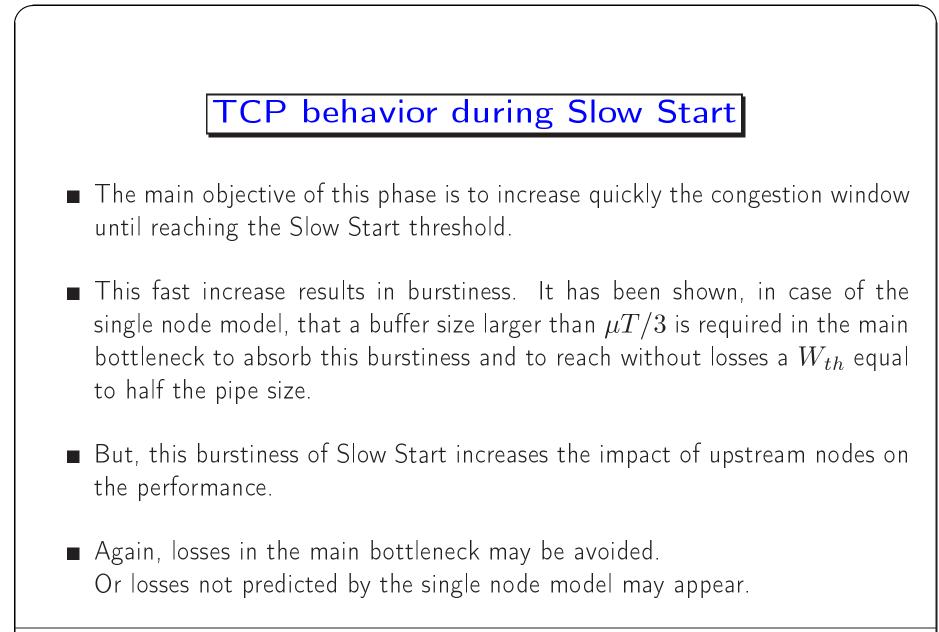
TCP behavior during Congestion Avoidance

- The single node model predicts a queue building in N_{μ} at a rate of one packet per RTT until the window reaches $W_{max} = B + \mu T$.
- But, an increase in the window by one packet every RTT results in a transmission rate $R_{CA} = \frac{W+1}{W}\mu > \mu$.
- Although this rate is very close to μ , the queue will not build up entirely in N_{μ} if one of the upstream nodes has an outgoing rate less than $R_{CA}.$
- Depending on the buffer size in this upstream node, the result can be:
 - \ast A smaller W_{max} , then a poorer performance.
 - \ast Or a larger W_{max} , then a better performance.

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The overflow window

- Let W_B be the window at which losses occur during Slow Start. W_{th} must be set to less than W_B in order to avoid losses during Slow Start and to improve the performance. In contrast to the single node model, we calculate W_B as a function of all network parameters.
- Calculation of W_B :
 - * Packets are transmitted in long bursts that double every RTT.
 - * The burst size (in packets) required to overflow a buffer:

$$\begin{split} S_1 &= 2\mu B_1/(2\mu-\mu_1) & \text{ for } B_1, \\ S_i &= \mu_{i-1} B_i/(\mu_{i-1}-\mu_i) & \text{ for } B_i \; (i=2\dots n), \\ S &= \mu_n B/(\mu_n-\mu) & \text{ for } B. \end{split}$$

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The overflow window

The first buffer that will overflow is the one with the smallest burst size. Thus,

$$W_B \simeq \min(S_1, S_2, \dots, S_n, S)$$

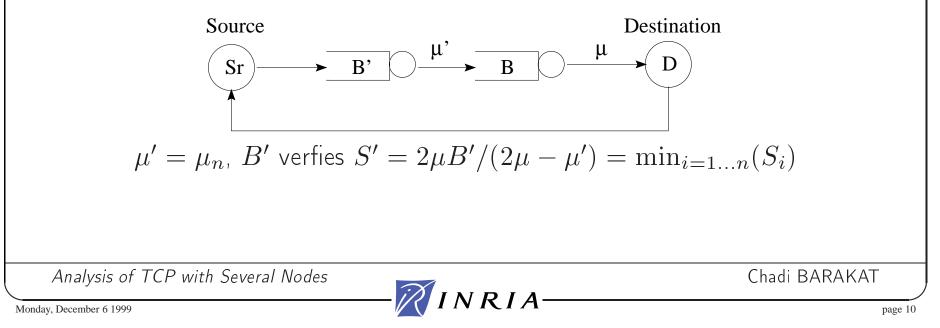
- In contrast to the single node model, W_B is a function not only of B and μ but also of B_i and μ_i $(i = 1 \dots n)$.
- Even if B is large compared to μT , W_B may be smaller than W_{th} due to a small buffer in an upstream node. Unpredicted losses will then appear.
- The single node model underestimates S (then W_B) since it supposes that the input rate at B is equal to 2μ while it can be constrained by an upstream node. The result is in an overestimation of the required buffer size.

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Simplification of the general model

The main bottleneck (μ, B) is required for the modeling of Congestion Avoidance (W_{max}) . And upstream nodes are required for the modeling of Slow Start. We keep the main bottleneck and we substitute the upstream nodes by the node between 1 and n having the smallest burst size.

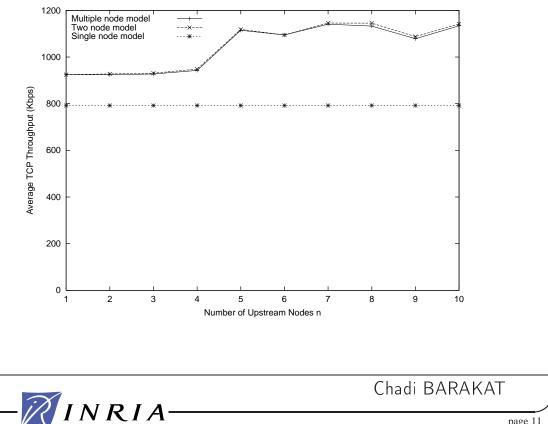


Validation of the simplified model

We change the number of upstream nodes from 1 to 10, and we distribute the inter-upstream node bandwidth equally on $[\mu, 2\mu]$.

For a long TCP Tahoe connection, the single node model predicts always an overflow in B during Slow Start at a small W_B whereas our models predict an overflow at a larger W_B until n = 4 and a disappearance of the overflow after that.

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Impact of network parameters on TCP performance

- Due to the closeness of R_{CA} to μ , the behavior of TCP in the Congestion Avoidance mode is only a function of B and μ and it is identical to that predicted by the single node model.
- The behavior of TCP during Slow Start depends on the position of W_B w.r.t. W_{th} where $W_B = \min(S, S')$ is a function of B, B', μ and the value of μ' between μ and 2μ .
- Given that the minimum value of S and S' are 2B and 2B' respectively, the impact of μ' can be eliminated by taken:

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 $2B > W_{th}$ and $2B' > W_{th}$

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Impact of μ' on the performance

This impact exists when one of the two previous conditions is not satisfied. While μ' decreases, the situation improves and then worsen.

