

# Conjectural Variations Equilibria

## *Part II: Dynamic Equilibria*

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# Contents

## Dynamic conjectures, bounded rationality and learning

- The principle.
- A learning model.
- Friedman Mezzetti model.

## Consistent conjectures in a dynamic setting

- The principle.
- Consistent conjectures in differential games.
- Theoretical framework in discrete time, infinite horizon.



# *Dynamic conjectures, bounded rationality and learning*

# The idea

## Ingredients

- Dynamic conjectures
- Limited rationality
- Updating of conjectures

## Conjecture adjustment process

$$\dot{r}_{ij}(t) = \mu_i(r'_{ij}(t) - r_{ij}(t)), \quad r_{ij}(t+1) = (1 - \mu_i)r_{ij}(t) + \mu_i r'_{ij}(t)$$

$\mu_i$  → speed of adjustment.

$r_{ij}(t)$  → conjecture of  $i$  about  $j$ .

$r'_{ij}(t)$  → conjecture to be used, based on observations.

# The learning model

- $n$  players,  $e_i$  strategy of  $i$ ,  $e$  profile of strategies,
- $e^b$  a **given** benchmark strategy,
- $V^i$  instantaneous payoff of player  $i$ .

Player  $i$  makes a conjecture about  $j$  of the form

$$e_j = e_j^b + r_{ij}(e_i - e_i^b), \quad r_{ij} \in \mathbb{R}$$

and solves

$$\max_{e_i} V^i(e_i, (e_j^b + r_{ij}(e_i - e_i^b))_{i \neq j}).$$

There exists a unique solution  $e_i = \phi_i(e^b; r_i)$ , ( $r_i = (r_{ij})_{i \neq j}$ ).

## Learning model (continued)

$i$  **observes** that  $j$  has played  $e_j$  and concludes that her conjecture should have been  $r'_{ij}$  /

$$e_j = e_j^b + r'_{ij} (e_i - e_i^b), \quad \implies \quad r'_{ij} = \frac{e_j - e_j^b}{e_i - e_i^b}$$

### Adjustment process of conjectures

$$r_{ij}(t+1) = (1 - \mu_i)r_{ij}(t) + \mu_i \frac{e_j(t) - e_j^b}{e_i(t) - e_i^b}$$

with  $e_i(t) = \phi_i(e^b, r_i(t))$ .

# Properties of fixed points

**Proposition 1:** If  $r_{ij}(t) \rightarrow r_{ij}$  as  $t \rightarrow \infty$ , then

$$r_{i_1 i_2} r_{i_2 i_3} \cdots r_{i_p i_1} = 1 \quad \forall i_1 \dots i_p$$

in particular

$$r_{ji} = (r_{ij})^{-1}$$

The vector  $(r_{i_1 \dots i_{i-1}}, 1, r_{i_{i+1} \dots i_n})$  is the direction of the line (passing through  $e^b$ ) of the space of strategy profiles, on which player  $i$  chooses her own strategy.

$e_i = \phi_i(e^b, r_i)$  is the strategy played by  $i$  in the limit.

## Properties of fixed points (continued)

### Proposition 2: Pareto optimality

If  $e$  is a limit point obtained by the convergence of the adjustment recurrence then  $e$  is a **candidate** Pareto-optimal solution.

**candidate** i.e. it verifies necessary optimal conditions.

### Proposition 3: In the case of identical players:

$\phi_i(e^b, r) = \phi(e^b, r)$ ,  $e_i^b = e^b \forall i$ ; the recurrence converges to 1 for any  $0 < \mu < 1$  and any (common) initial condition.



## Example

Cournot's oligopoly:

$$V^i(e_i, e_{-i}) = (\alpha - \beta \sum_j e_j) e_i - (b e_i + c) = \beta e_i (\Gamma - \sum_j e_j) - c.$$

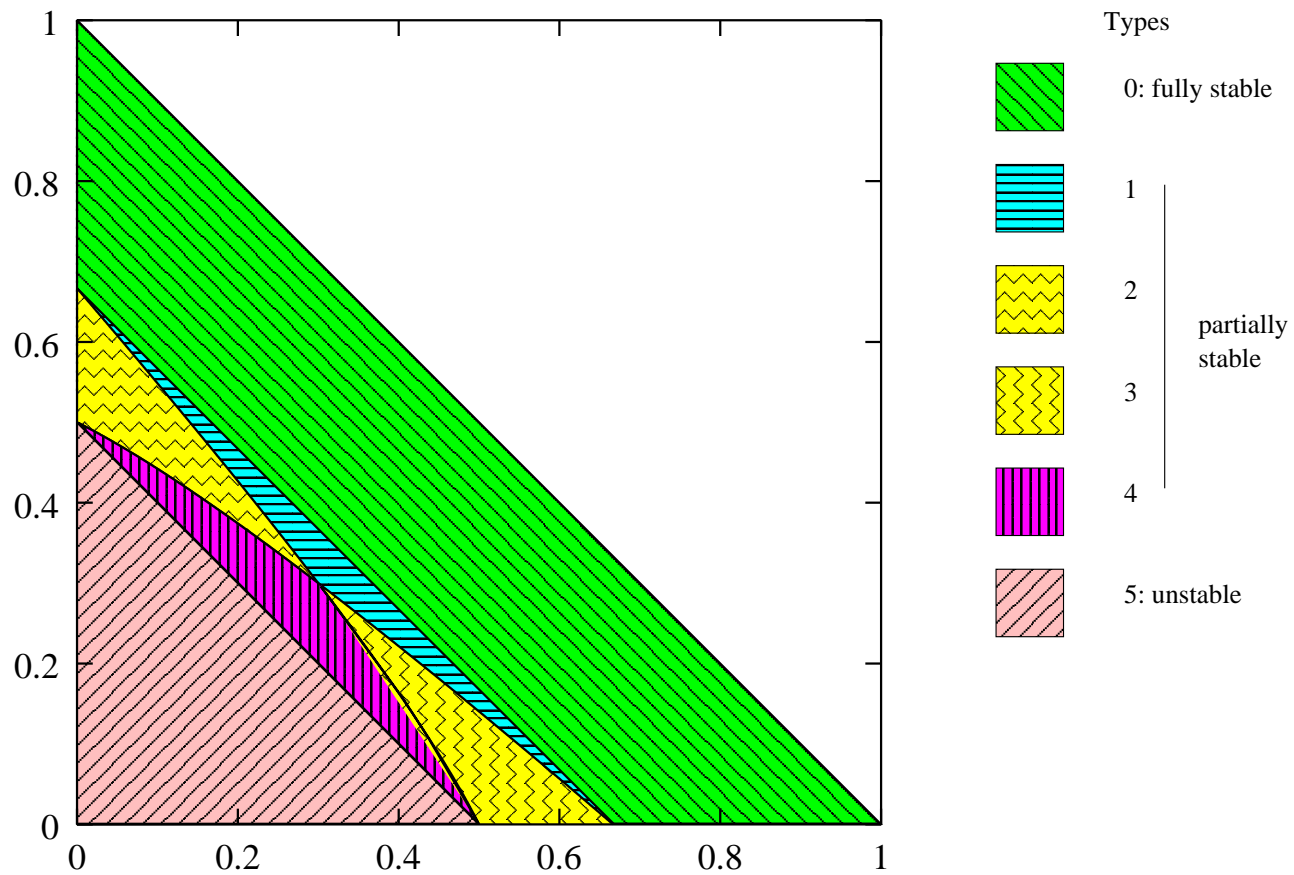
Where  $\Gamma = \frac{\alpha - b}{\beta} > 0$ .

**Theorem:** the unique fixed point of the adjustment process are  $r_{ij} = e_j^b / e_i^b$  and the corresponding strategies are Pareto optima.

The learning procedure selects among the Pareto outcomes the only one with quantities proportional to that of the reference point.

# Zones of stability

Zones of stability in the Cournot case ( $\Gamma = 1$ ).



# The Friedman-Mezzetti model

Friedman-Mezzetti (2002) study a discounted **repeated game**, discrete time, infinite horizon, where agents form **fixed** conjectures about the others agents **but they update the reference point**.

$$e_j(t + 1) = e_j(t) + r_{ij}(e_i(t) - e_i(t - 1))$$

## Optimization

$$e_i(t) = \phi_t^i(e(t - 1), e_i(t - 2))$$

**Optimal policy**  $\rightarrow \phi_1^i$  at time  $t = 1$ , she observes  $e(1)$  and applies  $\phi_1^i$ .

$$e_i(t) = \phi_1^i(e(t - 1), e_i(t - 2)), i = 1 \dots n$$

## Result

**Theorem:** let  $e_i^s(r, \theta)$  be a fixed point of the dynamical system

$$e_i(t) = \phi_1^i(e(t-1), e_i(t-2)), i = 1 \dots n$$

for a fixed vector of conjectures  $r$ . Let  $e_i^c(r)$  be a conjectural variations equilibrium with constant vector of conjectures  $r$ , for the associated static game.

If there exists  $e_i^s(r, \theta)$ , then there exists a  $e_i^c(\theta r)$ , and conversely. If both are unique then

$$e_i^s(r, \theta) = e_i^c(\theta r)$$

# Adapting reference point in our learning model

$$e_j(t + 1) = e_j(t) + r_{ij}(e_i(t) - e_i(t - 1))$$

optimization

$$e_i(t + 1) = \phi_i(e(t), r_i)$$

if the recurrence converges to  $\bar{e}$

$$\bar{e}_i = \phi_i(\bar{e}, r_i)$$

# Adapting the reference point in Cournot's duopoly

$$V^i(e_i, e_{-i}) = \beta e_i (\Gamma - \sum_j e_j) - c.$$

$$e_i = \frac{(1 + r_{ij})\Gamma}{(2 + r_{12})(2 + r_{21}) - 1}$$

$$(e_1, e_2) \text{ Pareto} \iff r_{12}r_{21} = 1$$

**EXTENSION: Adapting conjectures and reference points.**



# *Consistent conjectures in a dynamic setting*

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# *Consistent conjectures in a dynamic setting*

## Ingredients

- Dynamic game. Repeated game
- Conjectures on how the other players react
- Consistency: conjectures of each player  $\equiv$  best response reactions of the others players

# Principle

- $n$  players, time horizon  $T$
- $x(t) = (x_1(t), \dots, x_n(t)) \in \mathbb{R}^m$  state variable
- $e_i(t)$  control variable of  $i$  in  $[t, t + 1]$ ,  $e(t)$

## Dynamics

$$x(t + 1) = f(x(t), e(t)), \quad x(0) = x_0$$

(repeated game  $\rightarrow x(t + 1) = e(t)$ )

## Payoff

$$V^i(x_0, e(0), \dots, e(T - 1)) = \sum_{t=1}^T \theta^{t-1} \Pi^i(x(t), e(t))$$

## Principle (continued)

### Conjecture of $i$

$$e_j^c(t) = \phi_t^{ij}(x(t)) \quad \rightarrow \quad x(t+1) = \tilde{f}_i(x(t), e_i(t)) .$$

### optimal control problem

optimal policy  $e_i^{i^*}(t)$  that we suppose unique. Player  $i$  can compute  $e_j^{i^*}(t)$  and  $x^{i^*}(t)$  via  $\phi_t^{ij}$ .

Call  $x^a(t)$  the actual trajectory (replacing  $e_i^{i^*}$  in the dynamics).

# Different definitions of consistency

**Definition 1:**  $\phi_t^1, \dots, \phi_t^n$  is a **state-consistent conjectural equilibrium**  $\iff$

$$x^{i*}(t) = x^a(t), \quad \forall i, t, x(0) = x_0$$

**Definition 2:**  $\phi_t^1, \dots, \phi_t^n$  is a **(weak) control-consistent conjectural equilibrium**  $\iff$

$$e^{i*}(t) = e^{j*}(t), \quad \forall i \neq j, t, x(0) = x_0 \text{ (a } x(0) \text{ given)}$$

control-consistent c.e.  $\implies$  state-consistent c.e.

## Different definitions of consistency (continued)

Optimization problem:  $\rightarrow e_i^{i^*}(t) = \psi_t^i(x(t))$

**Definition 3:**  $\phi_t^1, \dots, \phi_t^n$  is a **feedback-consistent conjectural equilibrium**  $\iff$

$$\psi_t^i = \phi_t^{ji}, \quad \forall i \neq j, t, x(0) = x_0$$

as a consequence

$$\phi_t^{ji} = \phi_t^{ki}, \quad \forall i \neq j \neq k, t.$$

# *Consistency in differential games*

Fershman and Kamien (1985) define consistent conjectures in differential games.

- Open-loop Nash equilibria are weak control-consistent conjectural equilibria
- Control-consistent conjectural equilibria and feedback Nash equilibria coincide

## The model of Friedman (1968)

Discrete time, infinite horizon, repeated game.

$$\begin{aligned} V^i(x_0, e(0), \dots) &= \sum_{t=1}^{\infty} \theta^{t-1} \Pi^i(x(t)) \\ x(t+1) &= e(t) \\ x_j(t+1) &= \phi^i(x(t)) \end{aligned}$$

Solution: Solve the control problem with finite horizon  $T$  and let  $T$  goes to infinity.

Repeated static Nash equilibria is a feedback-consistent conjectural equilibria

∃ other feedback-consistent conjectural equilibria?

# The linear-quadratic case: setting of the problem

Instantaneous payoff

$$\Pi^i(x) = \frac{1}{2}x^t K^i x + L^i x + M^i$$

Discounted payoff

$$V^i(x_0, e(0), \dots) = \sum_{t=1}^{\infty} \theta^{t-1} \Pi^i(x(t))$$

Dynamics

$$x_i(t+1) = e_i(t)$$

$$x_j(t+1) = e_j^c(t) = \sum_{k=1}^n f_{jk}^i(\tau) x_k(t) + g_j^i(\tau)$$

$\tau = T - (t + 1)$  is the number of time units left before the end of the game.

optimization problem



## The L-Q case: setting of the problem (continued)

The optimization problem for player  $i$ , for a finite time  $T$  is:

$$W_T(x_0) = \max_{e(0), \dots, e(T-1)} V^i(x_0, x(1), \dots, x(T))$$

such that

$$x(t+1) = e(t)b_i + F^i(\tau)x(t) + g^i(\tau), \quad x(0) = x_0.$$

$b_i = (0, \dots, 1, \dots, 0)^t$  with '1' in position  $i$ .

The function  $W_T$  is the value function of the control problem.

We can obtain

- recurrence formulas for the optimal reaction function
- necessary and sufficient conditions of convergence when  $T \rightarrow \infty$ .

# Results

- The repeated static Nash equilibrium is **the unique** feedback consistent conjectural equilibrium in quadratic symmetric Cournot and Bertrand oligopoly.
- Consider a distance game, that is a game where player 1 wishes to minimize her distance to point  $(1,0)$  whereas player 2 wishes to minimize her distance to  $(0,1)$ . We can prove that there exists **an infinity** of feedback consistent conjectural equilibria.

Other examples with finite number of feedback consistent conjectural equilibria?

# Conclusions

Existing results call for further studies on:

- More examples of feedback-consistent equilibria.
- Learning with adaptation of conjectures and the reference point.
- Evolutionary games.

Dixon and Somma (2001) have proved in Cournot's duopoly that the unique evolutionary stable strategy is the *consistent* CVE of the static game.

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