## **Energy-Efficient Algorithms**

Susanne Albers
University of Freiburg
Germany

# Motivation

- Energy consumption grows exponentially in computing devices computers, embedded systems, portable devices, ...
- Performance of processors doubles every three years

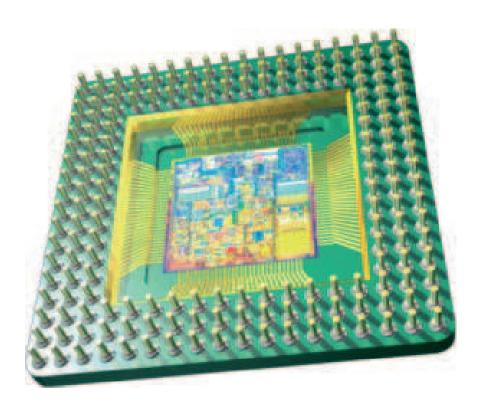
- Critical in battery-operated devices
- Critical in terms of cost (computer centers)
- Critical since energy is converted into heat

## Algorithmic techniques

• Power-down strategies: Put system into sleep state when idle.

• Dynamic speed scaling: Microprocessors can run at variable speed.

## **Dynamic speed scaling**



Microprocessors can run at variable speed

The higher the speed, the higher the power consumption

 $\mathsf{Speed}\ s$ 

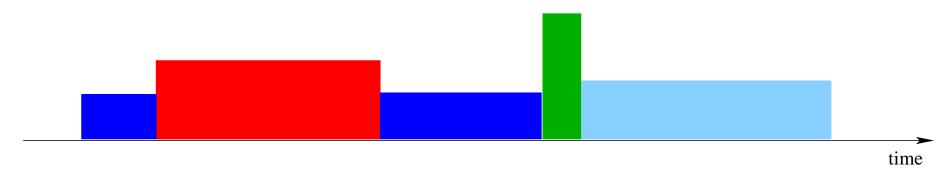
Power consumption

$$P(s) = s^{\alpha} \quad \alpha > 1$$

### **Previous work**

Deadline-based scheduling

1 processor



• Speed s

Energy consumption  $P(s) = s^{\alpha}$   $\alpha > 1$ 

- $\sigma = J_1, \dots, J_n$   $J_i$ :  $a_i$  = arrival time  $b_i$  = deadline  $p_i$  = processing volume  $t = p_i/s$
- Preemption allowed
- Construct feasible schedule minimizing total energy consumption.

### **Competitive analysis**

Online problem: jobs arrive one by one

A:

Online

algorithm

 $A(\sigma)$ 

OPT:

Offline

algorithm

 $OPT(\sigma)$ 

*A* is *c*-competitive, if for all job sequences  $\sigma$ 

$$A(\sigma) \le c \cdot OPT(\sigma).$$

### **Previous work**

#### Offline problem

polynomially solvable
 (Yao, Demers, Shenker 1995)

#### Online problem

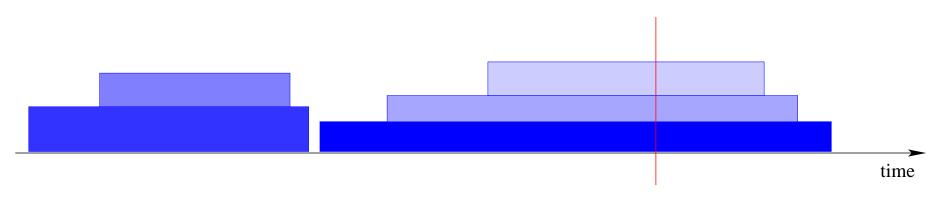
- Average Rate:  $\alpha^{\alpha} \le c \le 2^{\alpha} \alpha^{\alpha}$  (Yao, Demers, Shenker 1995) Optimal Available:  $c = \alpha^{\alpha}$  (Bansal, Kimbrel, Pruhs 2004)
- Upper bound  $2(\alpha/(\alpha-1))^{\alpha}e^{\alpha}$ Lower bound  $\Omega((4/3)^{\alpha})$ (Bansal, Kimbrel, Pruhs 2004)

### **Average Rate**

1. Job density  $\delta_i = p_i/(b_i - a_i)$ 

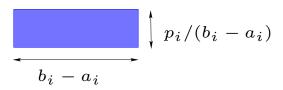
$$\begin{array}{c}
 & \downarrow p_i/(b_i - a_i) \\
 & \downarrow b_i - a_i
\end{array}$$

$$2. \ s(t) = \sum_{i: t \in [a_i, b_i]} \delta_i$$

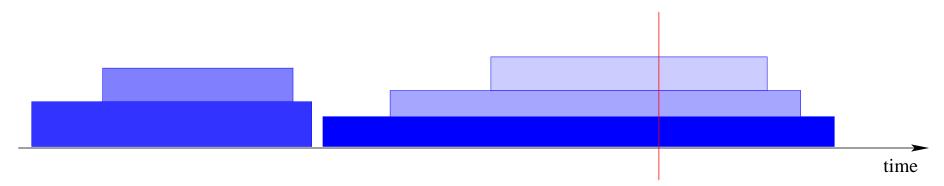


### **Average Rate**

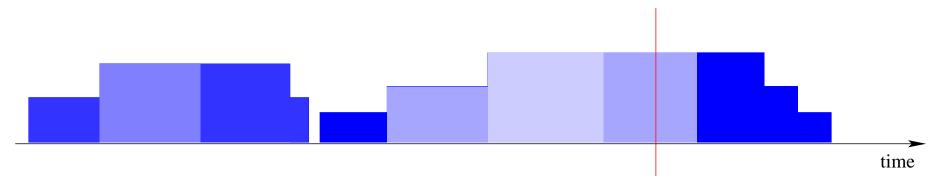
1. Job density  $\delta_i = p_i/(b_i - a_i)$ 



**2.** 
$$s(t) = \sum_{i: t \in [a_i, b_i]} \delta_i$$

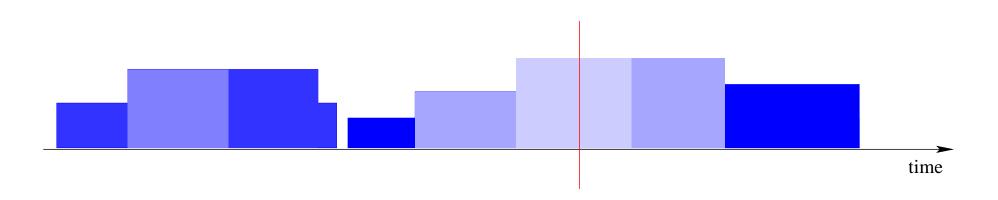


3. Use Earliest Deadline Policy



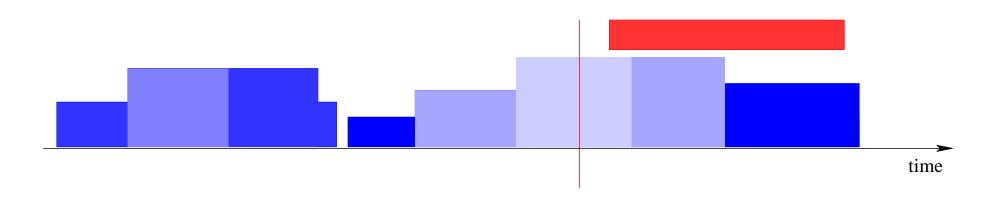
# **Optimal Available**

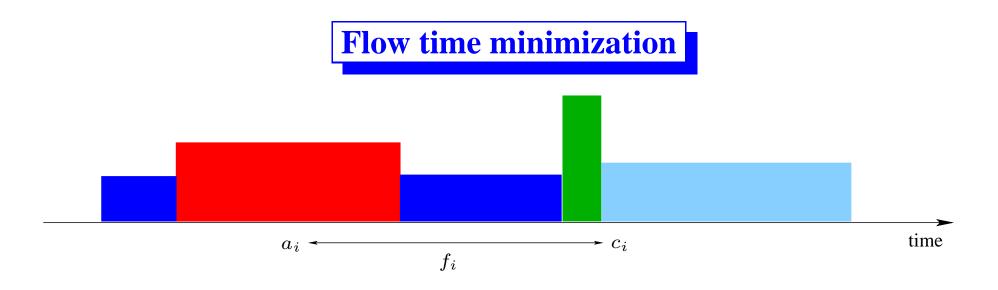
At any time compute optimal schedule for remaining workload.



# **Optimal Available**

At any time compute optimal schedule for remaining workload.





- Computer systems: jobs are not labeled with deadlines
- Users expect good response times
- Flow time of  $J_i$ :  $f_i = c_i a_i$   $c_i =$ completion time
- Energy and flow time minimization are orthogonal objectives low energy ⇒ low speed ⇒ high flow times small flow time ⇒ high speed ⇒ high energy

## **Previous work**

#### Pruhs, Uthaisombut, Woeginger 2004

- ullet Minimize flow time given fixed energy volume V
- $p_i = 1$  for all i
- ullet Polynomial time offline algorithm computing optimal schedules simultaneously for all V.

# Our approach

#### Albers, Fujiwara STACS 2006

$$\min\left(\text{Energy} + \sum_{i=1}^{n} f_i\right)$$

- $\sigma = J_1, \dots, J_n$   $J_i$ :  $a_i$  = arrival time  $p_i$  = processing volume preemption not allowed
- Combined objective functions for facility location, network design,
   TCP-acknowledgement, ...

## Our results

#### $p_i$ arbitrary

• Competitive ratio of  $\Omega(n^{1-1/\alpha})$ 

$$p_i = 1$$

- Competitive ratio of  $8e(1+\Phi)^{\alpha}$   $\Phi=(1+\sqrt{5})/2\approx 1.618$
- Offline problem polynomially solvable using dynamic programming;
   approach also solves problem of Pruhs, Uthaisombut, Woeginger

time

```
S:=\{ 	ext{ jobs with } a_i=0 \} while S 
eq \emptyset 	ext{ do} schedule jobs in S optimally; S:=\{ 	ext{ jobs having arrived in the meantime } \}; endwhile
```



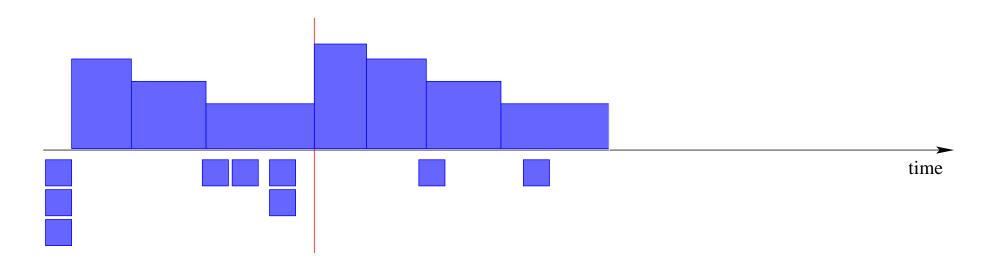
```
S := \{ \text{ jobs with } a_i = 0 \}

while S \neq \emptyset do

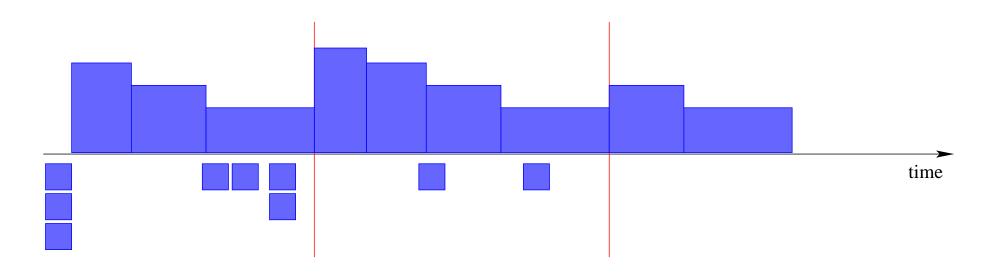
schedule jobs in S optimally;

S := \{ \text{ jobs having arrived in the meantime } \};

endwhile
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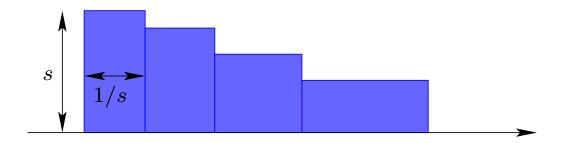


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## **Phase scheduling**

- $n_i$  jobs in phase i
- Speed sequence

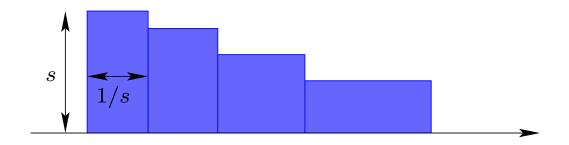
$$\sqrt[\alpha]{\frac{n_i}{\alpha-1}}, \sqrt[\alpha]{\frac{n_i-1}{\alpha-1}}, \dots, \sqrt[\alpha]{\frac{1}{\alpha-1}}$$



## **Speed computation**

First job of phase i

$$f(s) = s^{\alpha - 1} + \frac{n_i}{s}$$



### **Speed computation**

#### First job of phase *i*

$$\min f(s) = s^{\alpha - 1} + \frac{n_i}{s}$$

$$f'(s) = (\alpha - 1)s^{\alpha - 2} - \frac{n_i}{s^2}$$

$$f'(s) = 0 \iff (\alpha - 1)s^{\alpha} = n_i$$

$$\Leftrightarrow s = \sqrt[\alpha]{\frac{n_i}{\alpha - 1}}$$

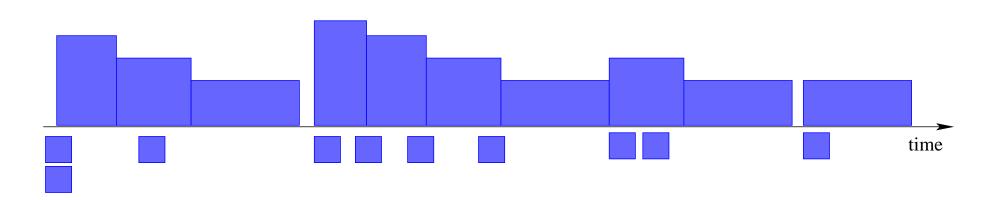
## **Analysis OPT**

**Lemma:** If there are *l* unfinished jobs waiting

$$s \ge \sqrt[\alpha]{\frac{l}{\alpha - 1}}.$$

Lemma: Every job is finished at least as early as in the online schedule.

### **Offline algorithm**



Sub-schedules  $S_1, \ldots, S_m$ .

 $S_j$  processes job with indices  $j_1, \ldots, j_l$ , where

$$c_i > a_{i+1}$$
  $i = j_1, \dots, j_l - 1$ 

$$c_{j_l} \le a_{j_l+1}$$

#### **Speeds in subschedules**

l jobs in interval of length T

• 
$$s_i = \sqrt[\alpha]{\frac{l-i+1}{\alpha-1}}$$
 if  $T \ge \sum_{i=1}^l 1/s_i$ 

• 
$$s_i' = \sqrt[\alpha]{\frac{l-i+1+c}{\alpha-1}}$$
 if  $T < \sum_{i=1}^l 1/s_i$ 

c unique value with  $\sum_{i=1}^{l} 1/s_i' = T$ 

Subproblems

P[i, i+l] = subproblem with  $J_i, \ldots, J_{i+l}$ 

C[i, i+l] = optimal cost of P[i, i+l] if  $J_{i+l}$  must be finished by  $a_{i+l+1}$ 

Determine C[1, n]

### **Multi-processor speed scaling**

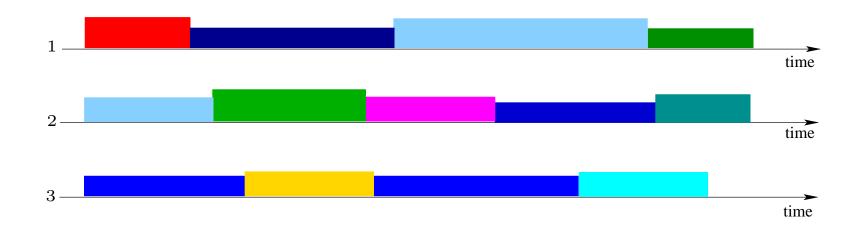
Server systems: several CPUs
 Google engineers: power costs overtake hardware costs

Laptops: dual-processors
 AMD "Quad-core design"
 Architectures with 8 CPUs are being developed

• Intel: experiments with 80 CPUs on one die

## **Multi-processor speed scaling**

Albers, Müller, Schmelzer SPAA 2007



- Each processor may run at individual speed s.
- Deadline based scheduling  $J_i$ :  $a_i$ ,  $b_i$ ,  $p_i$
- Preemption allowed, migration disallowed
- Construct feasible schedule minimizing total energy consumption.

## Unit size jobs, $p_i = 1$

#### Offline problem

Agreeable deadlines

$$a_i < a_j \implies b_i \le b_j$$

Polynomially solvable

Arbitrary deadlines

NP-hard

Approximation factor  $\alpha^{\alpha}2^{4\alpha}$ 

### Arbitrary size jobs

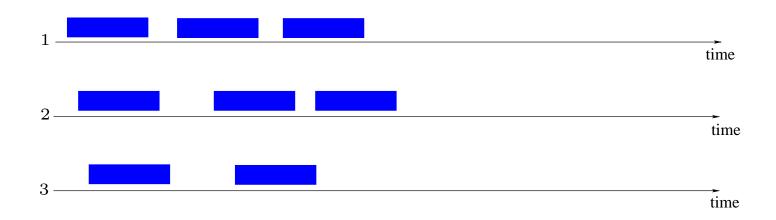
#### Offline problem

- Common release time or common deadline Approximation factor  $2(2-\frac{1}{m})^{\alpha}$
- Arbitrary deadlines Approximation factor  $\alpha^{\alpha}2^{4\alpha}$

## **Online setting**

- $p_i=1$ , agreeable deadlines Competitive factor  $2(\alpha/(\alpha-1))^{\alpha}e^{\alpha}$
- $p_i=1$ , arbitrary deadlines  $p_i$  arbitrary, agreeable deadlines Competitive factor  $\alpha^{\alpha}2^{4\alpha}$

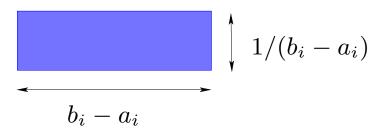
### Unit size jobs, agreeable deadlines



- 1. Sort jobs according to non-decreasing release dates.
- 2. Assign jobs to processors using Round Robin.
- 3. For each processor, compute optimal schedule.

### Unit size jobs, arbitrary deadlines

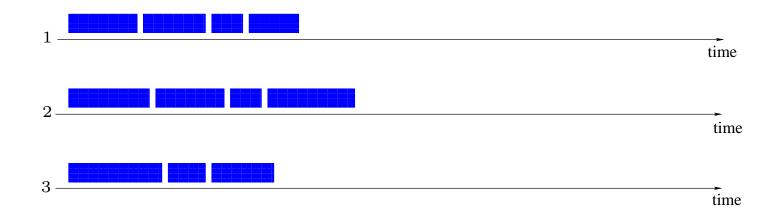
1. Job density  $\delta_i = 1/(b_i - a_i)$   $\Delta = \max_i \delta_i$ 



- 2. Job classes  $C_k = [\Delta 2^{-k}, \Delta 2^{-(k-1)})$
- 3. Apply Round Robin to each class
- 4. For each processor, compute optimal schedule

## Arbitrary size jobs

#### Common release time



- 1. Sort jobs according to non-decreasing deadlines.
- 2. Assign jobs to processors using List scheduling.
- 3. For each processor, compute optimal schedule.

#### **Open problems**

#### Flow time minimization

- Exact competitive ratio of PhaseBalance
- Analyze of following speed scaling algorithm: Speed  $\sqrt[\infty]{i}$  when there are i unfinished jobs waiting

#### Multi-processor setting

- Improve approximation guarantees
- Consider migration