



# Les Challenges de la Robotique dans le cadre des Tokamak

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Avec la collaboration de l'équipe CEA de Tore Supra  
à Cadarache

# L'équipe Tore Supra



Environ 320 personnes, dont 50 étrangers

# L'équipe de Robotique pour les TOKAMAK



Fontenay aux Roses

# ROBOTIQUE & Tokamak



• *Contexte Fusion- Tokamak*

• *Maintenance de ITER*

• *Quelques Robots*



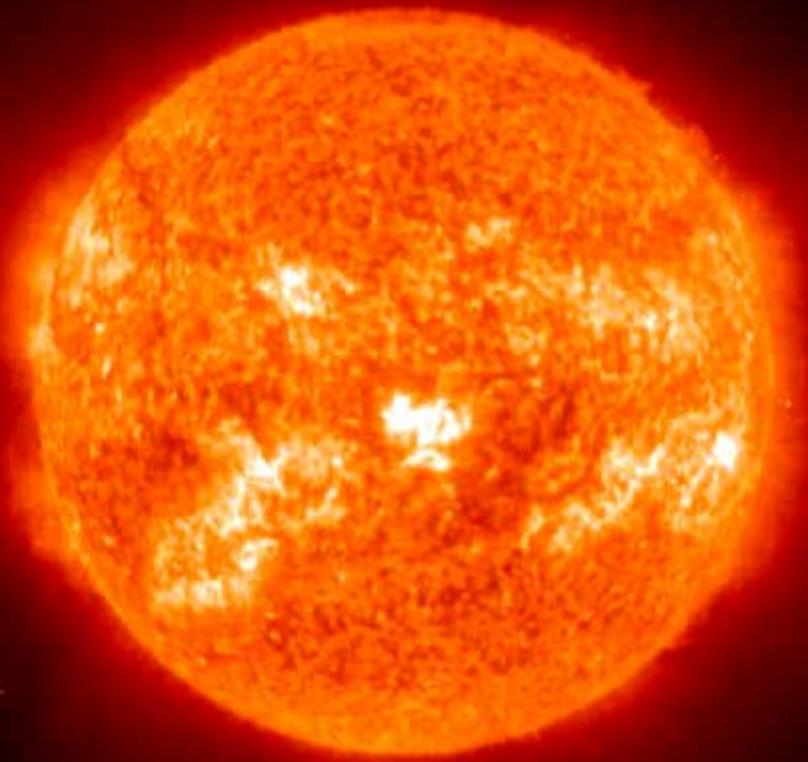
# L'énergie : un enjeu majeur pour le 21<sup>ème</sup> siècle

- L'énergie est un élément clef du développement économique  
La Chine et l'Inde (37 % de la population mondiale)  
ne consomment que 17 % de l'énergie
- Plus de 80 % de l'énergie primaire provient des ressources fossiles
- Les nouvelles découvertes de pétrole sont désormais plus faibles que l'accroissement de la consommation
- Les gaz à effet de serre représentent un danger potentiel pour la planète
- Il est impératif de maîtriser la consommation d'énergie (en particulier en Occident) et de diversifier le "mix" énergétique
- La fusion présente de grands avantages. **C'est une des voies à explorer !**

# Fusion... dans le soleil



esa  
ISD VisuLab



Extreme ultraviolet Imaging Telescope

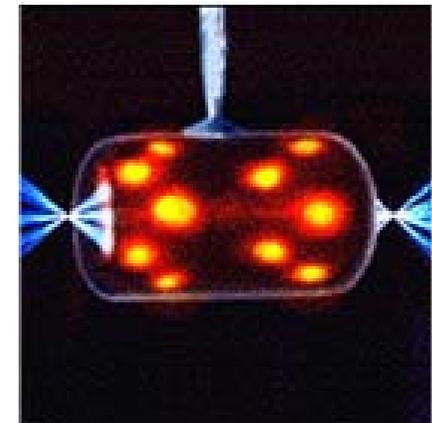
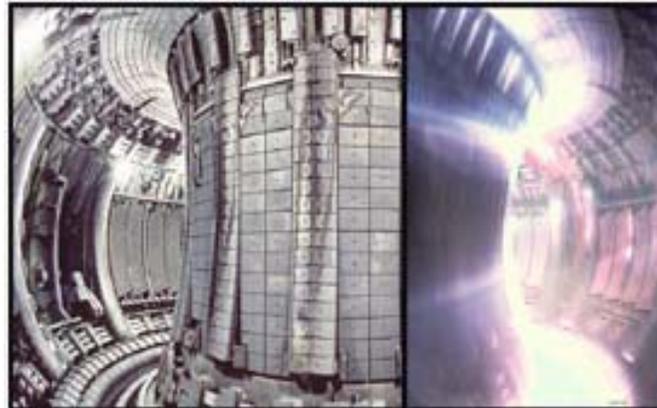
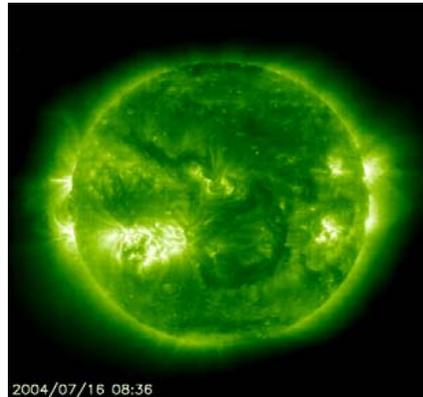
(304 Å, i.e. 60 to 80 000 K)

2003/05/26 13:36

Sun

Tokamak JET

NOVA (laser on target)



**Confinement:**

Size:

Duration:

Pressure:

**Gravitational**

$1.3 \cdot 10^8$  m

$3 \cdot 10^{16}$  s

$10^9$  atm

**Magnetic**

10 m

400 s

2 atm

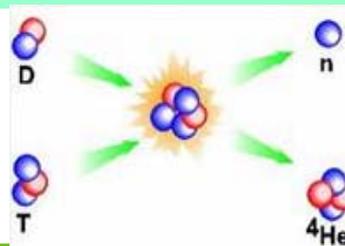
**Inertial :**

$10^{-2}$  m

$10^{-8}$  s

$10^9$  atm

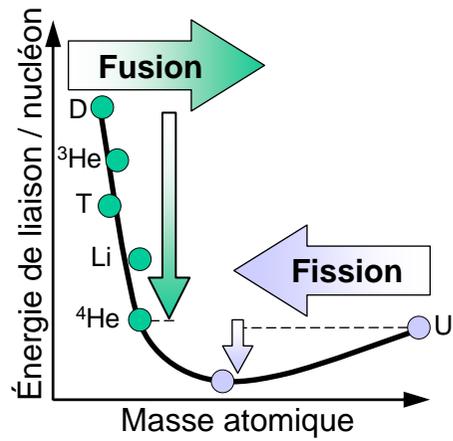
Temperature :  $10^8$  K  $\Leftrightarrow$  thermal energy : 10 keV



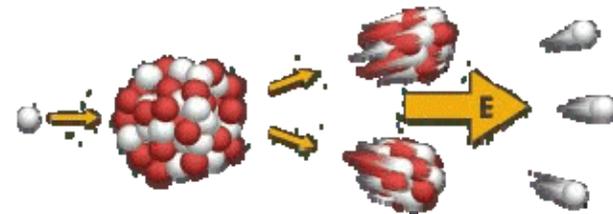
# Fission/Fusion : $E = mc^2$



**Fusion**

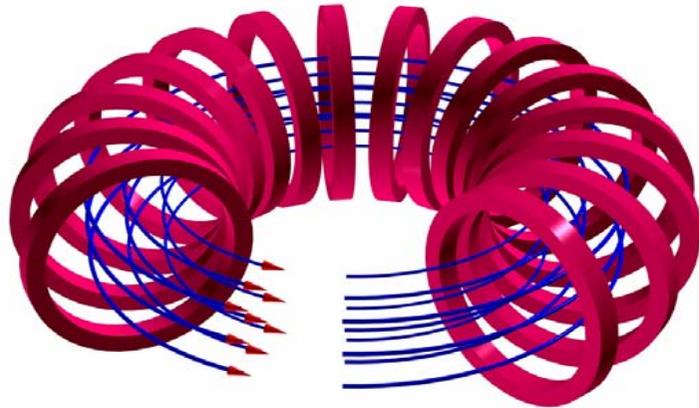


**Fission**

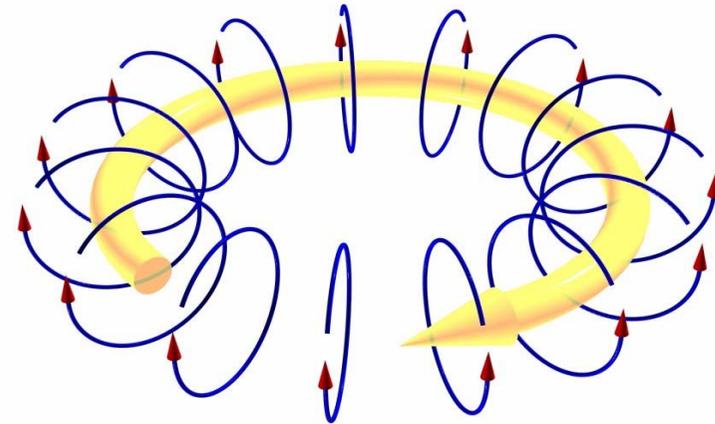


# Principe du tokamak : confinement magnétique

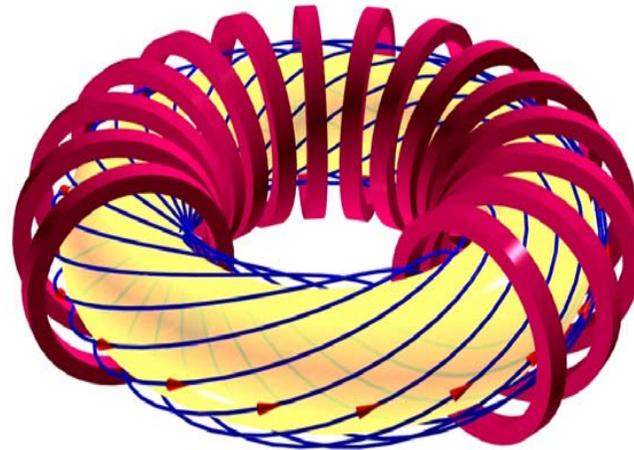
En Russe  
Tok: courant  
Mak: machine



Champ toroïdal



Champ poloïdal induit par le courant plasma

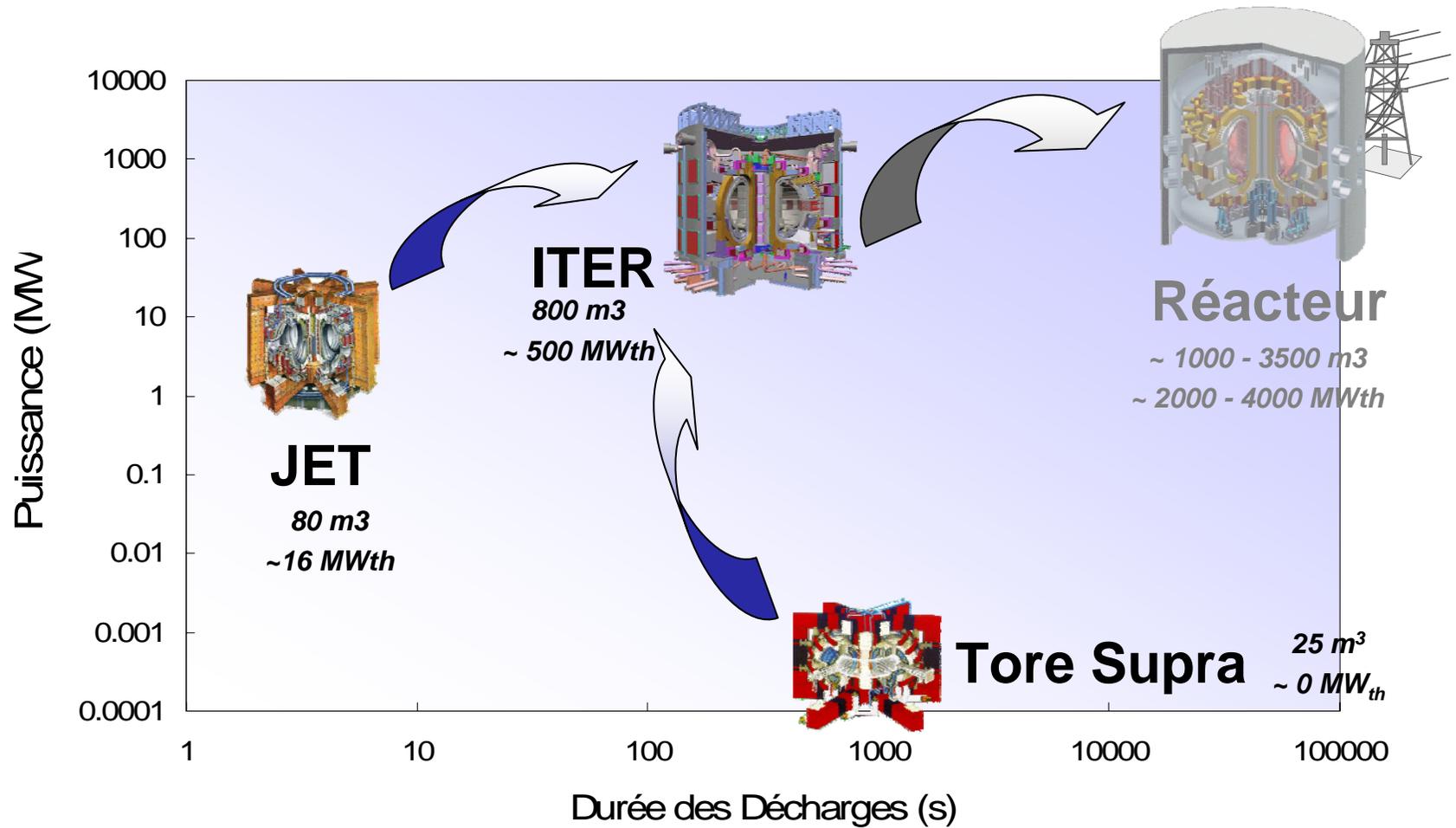


Champ résultant

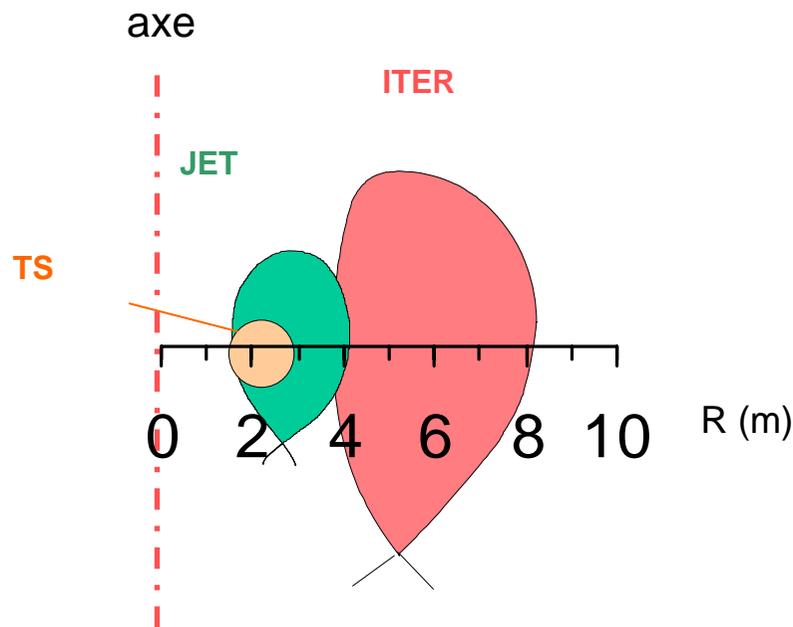
Un plasma... dans Tore Supra

12-02 18:06:35:05

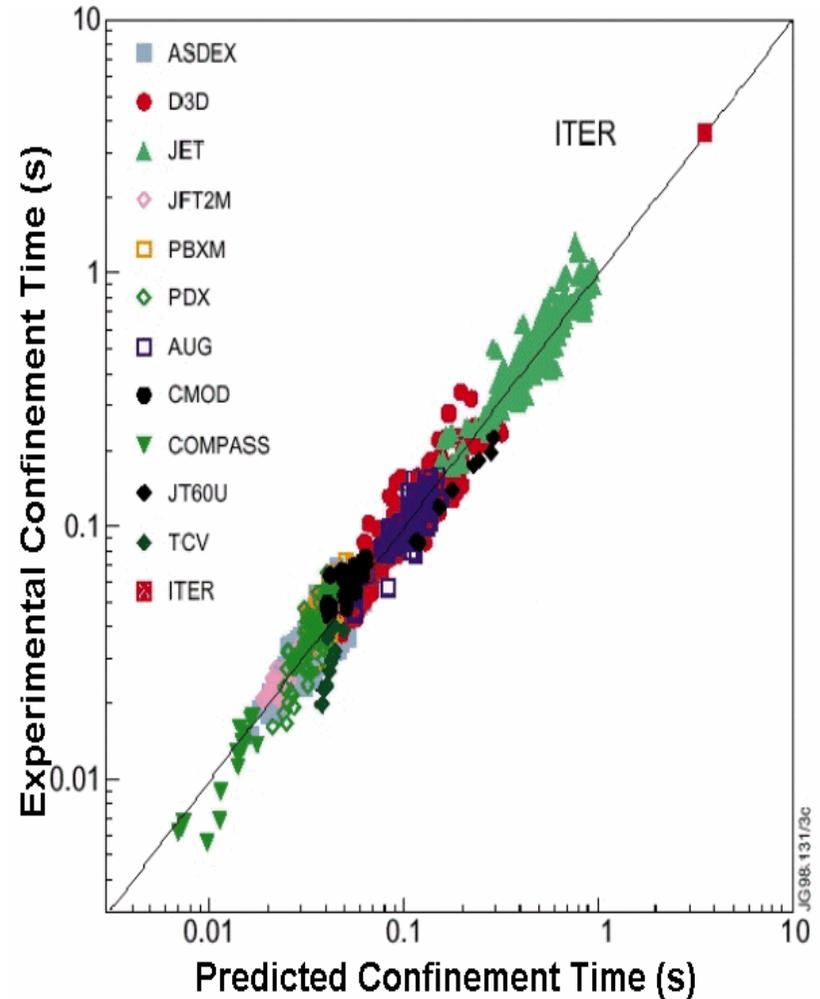
# ITER : le chemin vers le réacteur



# PLASMA CONFINEMENT TIME HAS BEEN IN CONSTANT PROGRESS



The scaling law of the confinement time is today well understood

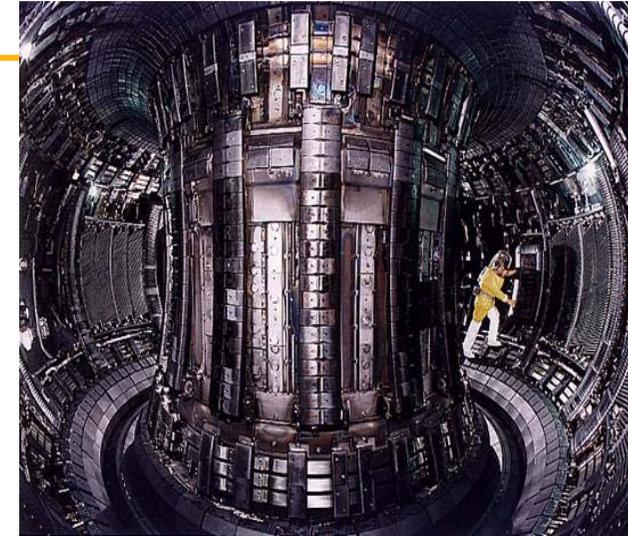
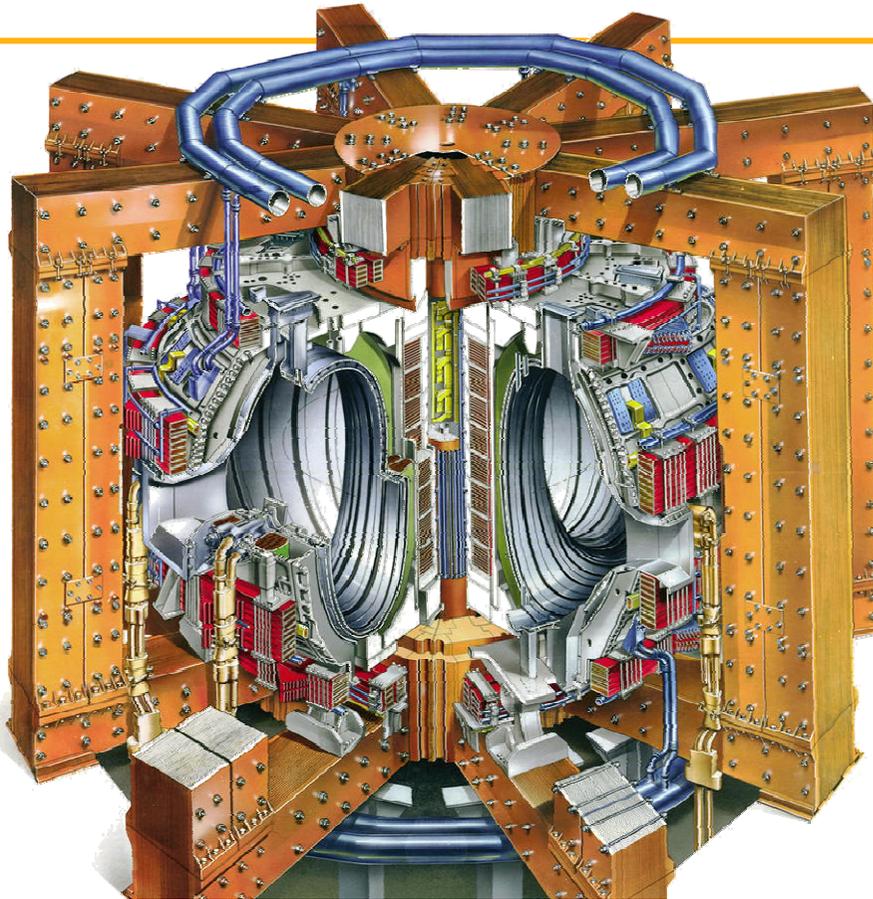


# ITER @ Cadarache

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# JET AND JT60-U REACHED NEAR "BREAKEVEN"

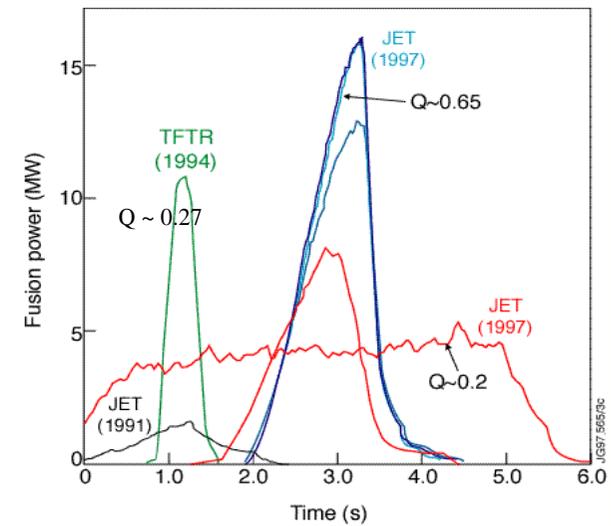


## JET (constructed and operated by the EU)

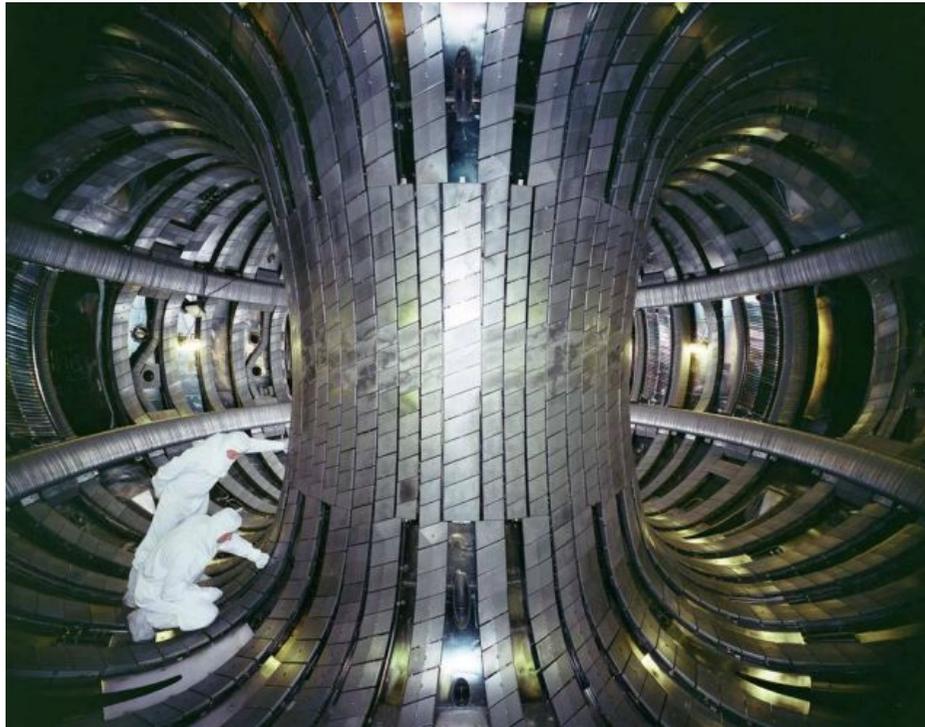
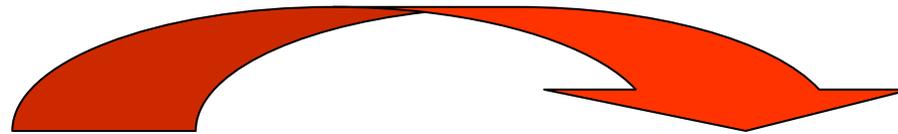
D / T , beryllium

Remote handling

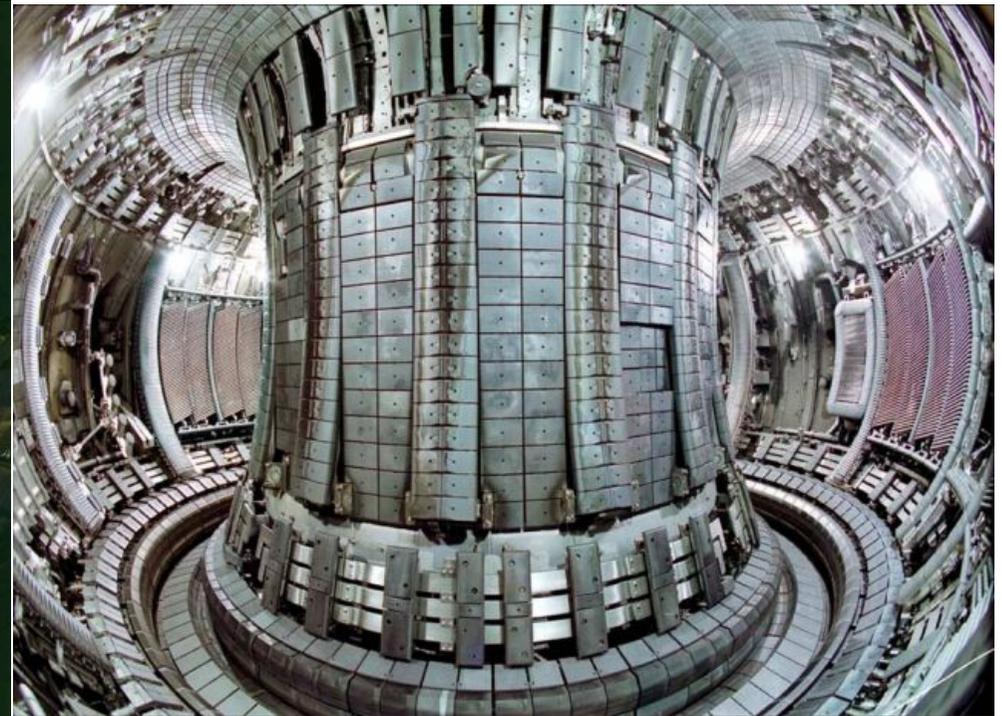
International organisation since 1978



# JET Experience : VV configuration

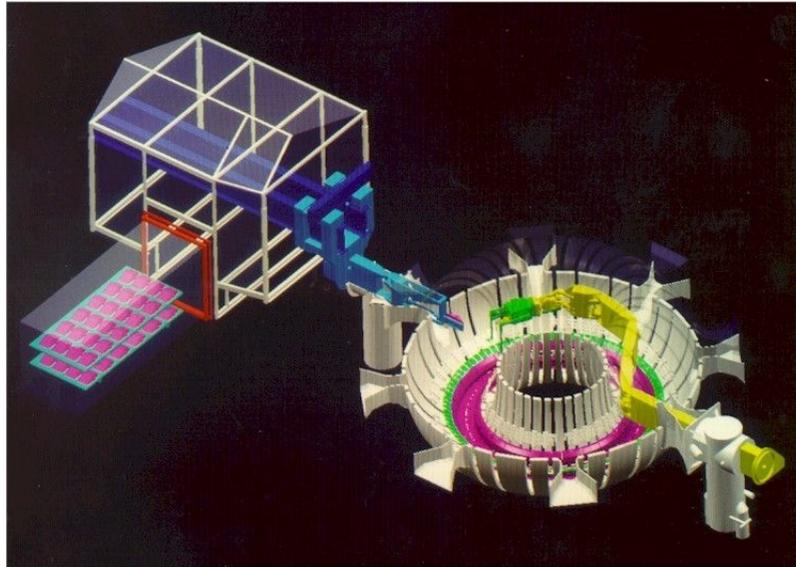


JET 1987

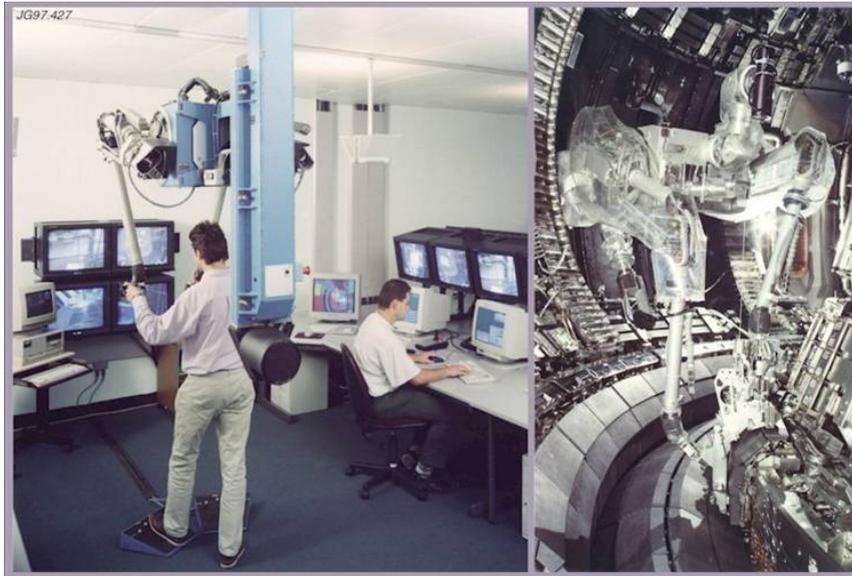
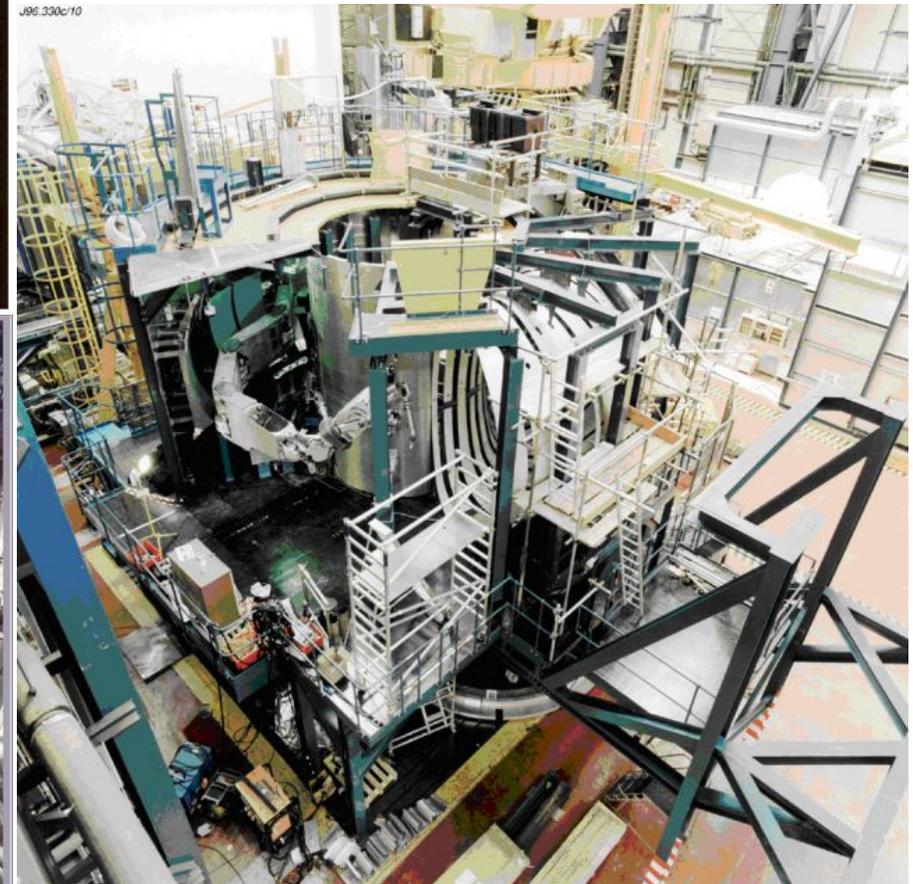


JET 2005

# JET Experience



**Banc test échelle 1**



**DTSI / Service Robotique Interactive**



# JET Experience



## 1998 - Remote Tile Exchange(RTE)

All **144 high** power Mark II divertor tile carrier modules were replaced by **2 new** Mark II gb modules

## 1999 - Inboard Port Launcher Installation

All **25 types** of tasks over 7 weeks.  
« **sealing and locking 12mm diameter pipes** in the torus wall ».

## 2001 - Septum Replacement Plate

All **66 types of tasks** over 16 weeks.

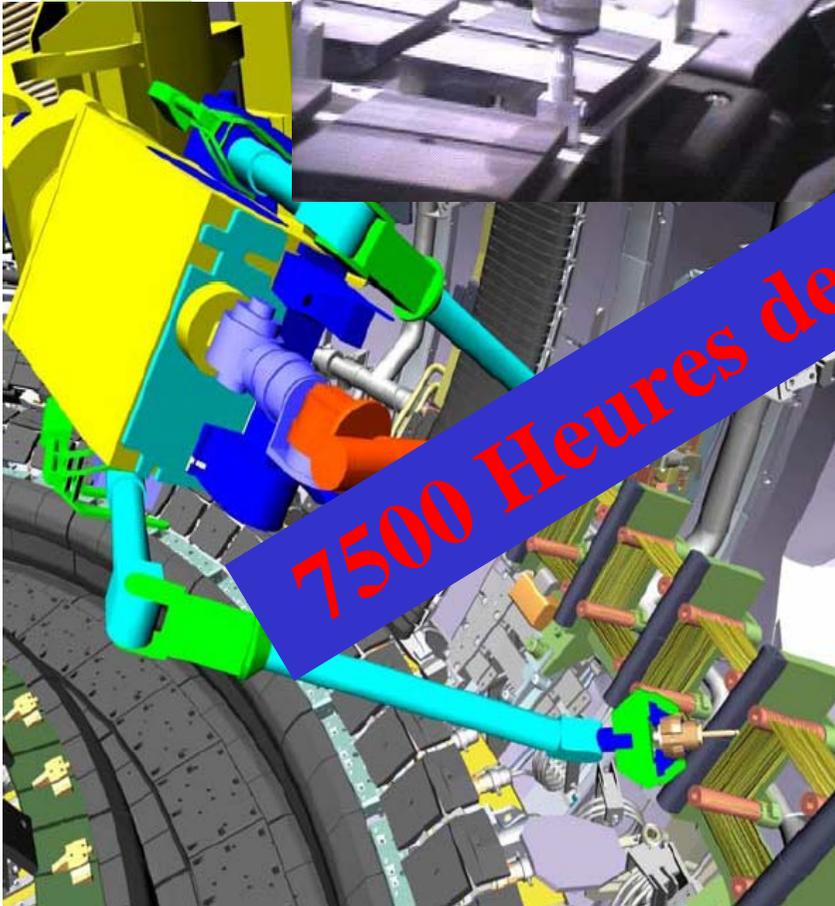
## 2004 JET Shutdown

- 212 remote tasks from Mar 2003 to Jan2004
- ~ 2000 remote tools used.
- 2 years planning & preparing remote tasks

## JET enhanced Performances

All **300 types of tasks** over 58 weeks.

7500 Heures de Remote Handling





# ITER Major Challenges

- The size.
- The heat load and the neutron flux through the walls.
- The heat and particles exhaust from the Divertor.
- The remote maintenance of the machine.



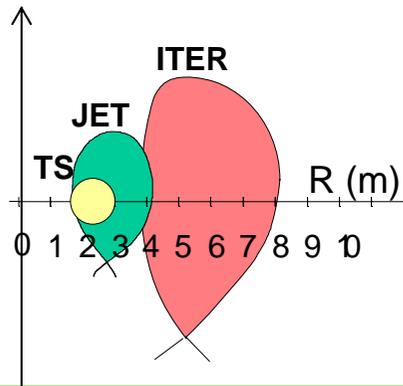
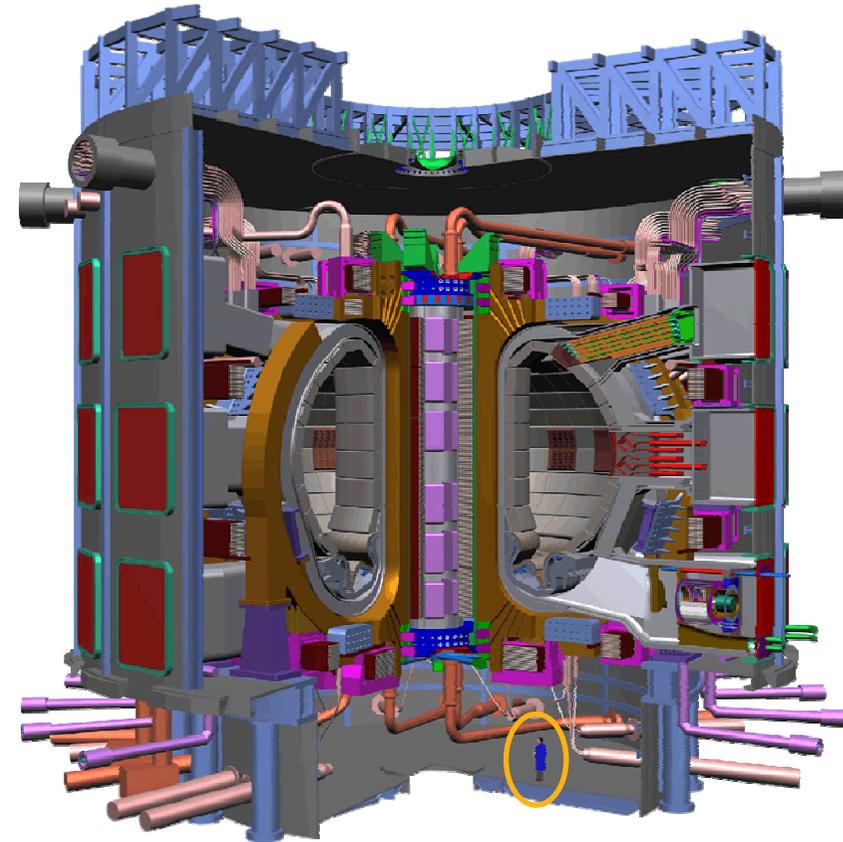
EFDA

EUROPEAN FUSION DEVELOPMENT AGREEMENT  
CLOSE SUPPORT UNIT GARCHING

Workshop de Barcelone des 13 et 14 décembre 2005 : “ITER : des opportunités pour l’industrie européenne ”

# ITER : principales caractéristiques

Paramètre	ITER
Grand rayon (m)	6,2
Petit rayon (m)	2
Élongation verticale	1,7 / 1,85
Volume plasma (m <sup>3</sup> )	837
Champ magnétique (T)	5,3
Courant plasma (MA)	15
Puissance fusion (MW)	500
Flux de neutrons (MW/m <sup>2</sup> )	0,5
Facteur d'amplification (Q)	10 (ignition possible)



Ingénierie	Construction	Exploitation
1990	2008	2035

# ITER : les enjeux technologiques



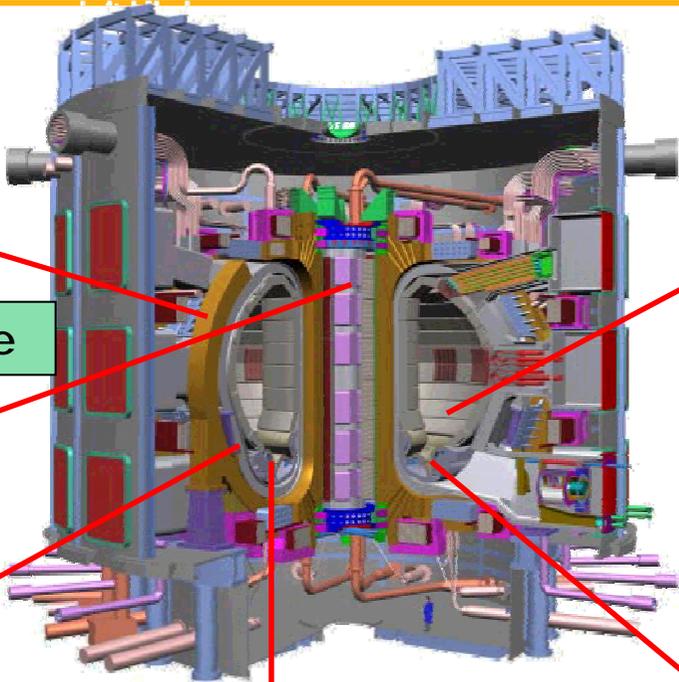
L2 : bobine toroïdale



L1 : solénoïde central

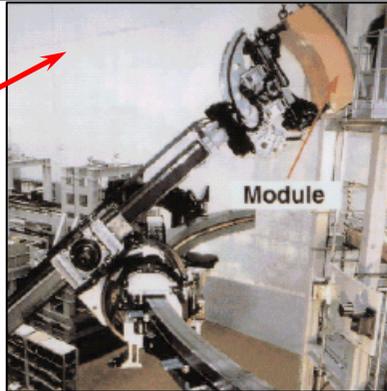


L3 : fabrication de l'enceinte

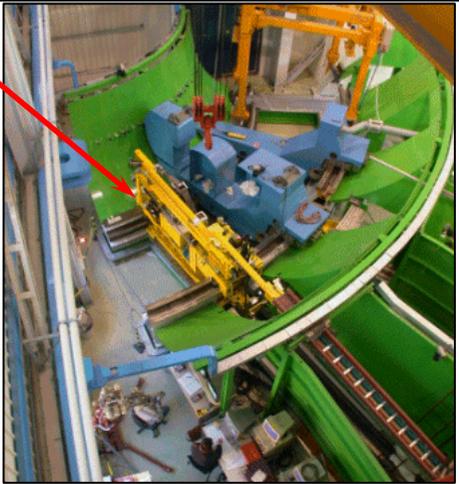


L4+L5 : module de couverture + divertor

L6 : maintenance couverture JAPON



L7 : maintenance divertor EUROPE



# LA ROBOTIQUE SUR ITER



## ACCES CRYOSTAT

- Vide Cryostat & température
- Accès personnel temps limité (de 0,001 à 1Gy/h)

## Maintenance exceptionnelle

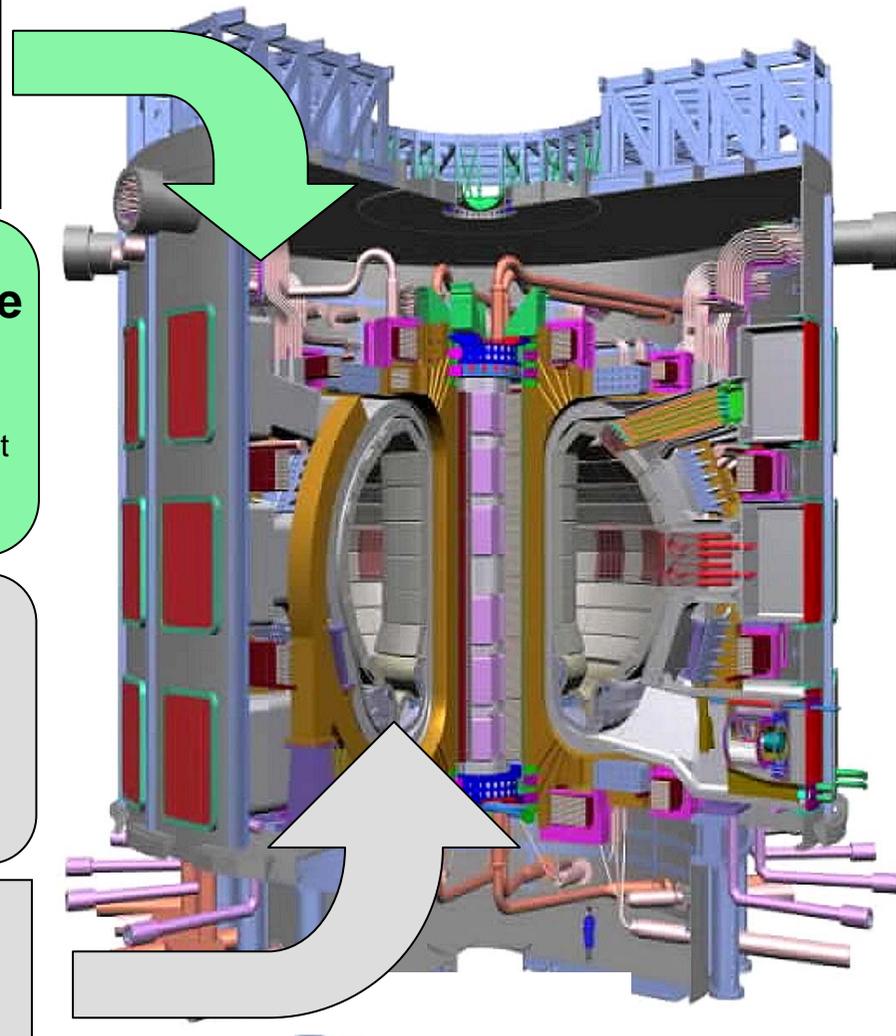
- Accès personnel difficile => Protection biologique mise en « air » du Cryostat
- « Assistance Téléopérée »

## Maintenance régulière

- **54 cassettes @ 12 t, 420 blanket modules @ 4 t**
- « larges » accès à la chambre à vide sur 2 niveaux
- **Maintenance téléopérée exclusivement**

## ACCES CHAMBRE A VIDE

- Rayonnement gamma (**630 Gy/h**)



# LA ROBOTIQUE SUR ITER

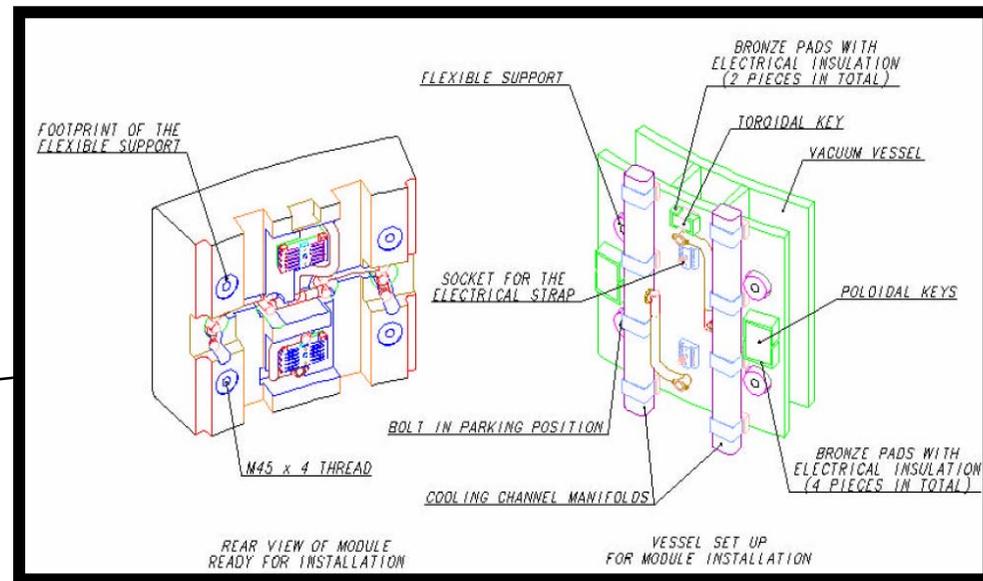
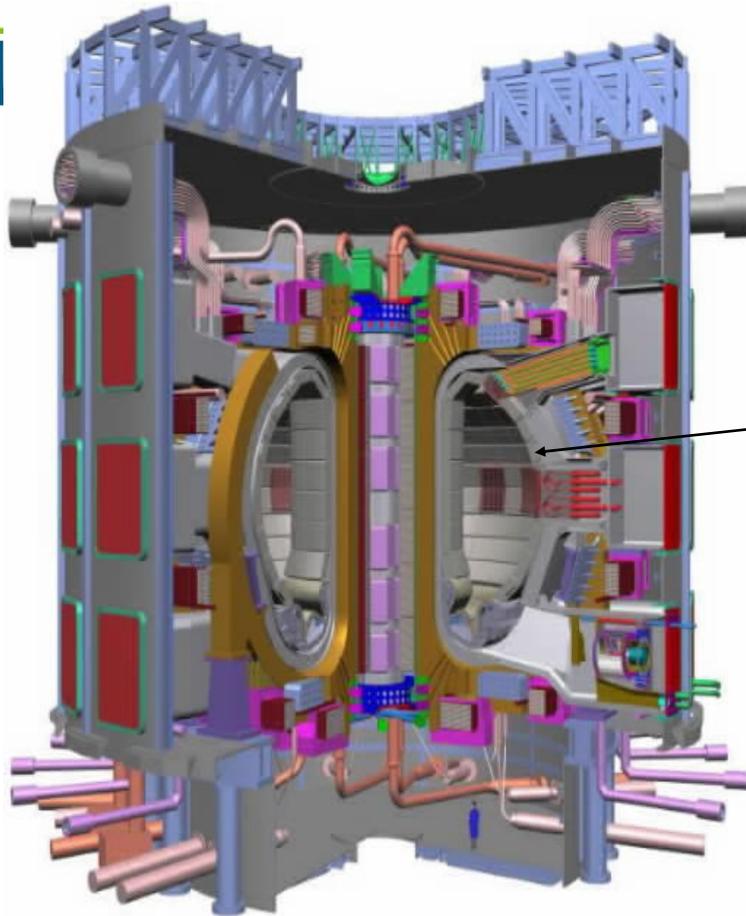


## DEFI TECHNOLOGIQUE

- Masse, dimensions et forme des composants.
- Nombre important de composants
- Trajectoires de manipulation complexes
- Assemblages à jeu réduit, tolérances de positionnement
- Environnement extrême
- Peu de capteurs disponibles (tenue au rayonnement)
- Fiabilité des équipements de maintenance

# ITER L6 - Maintenance des blankets

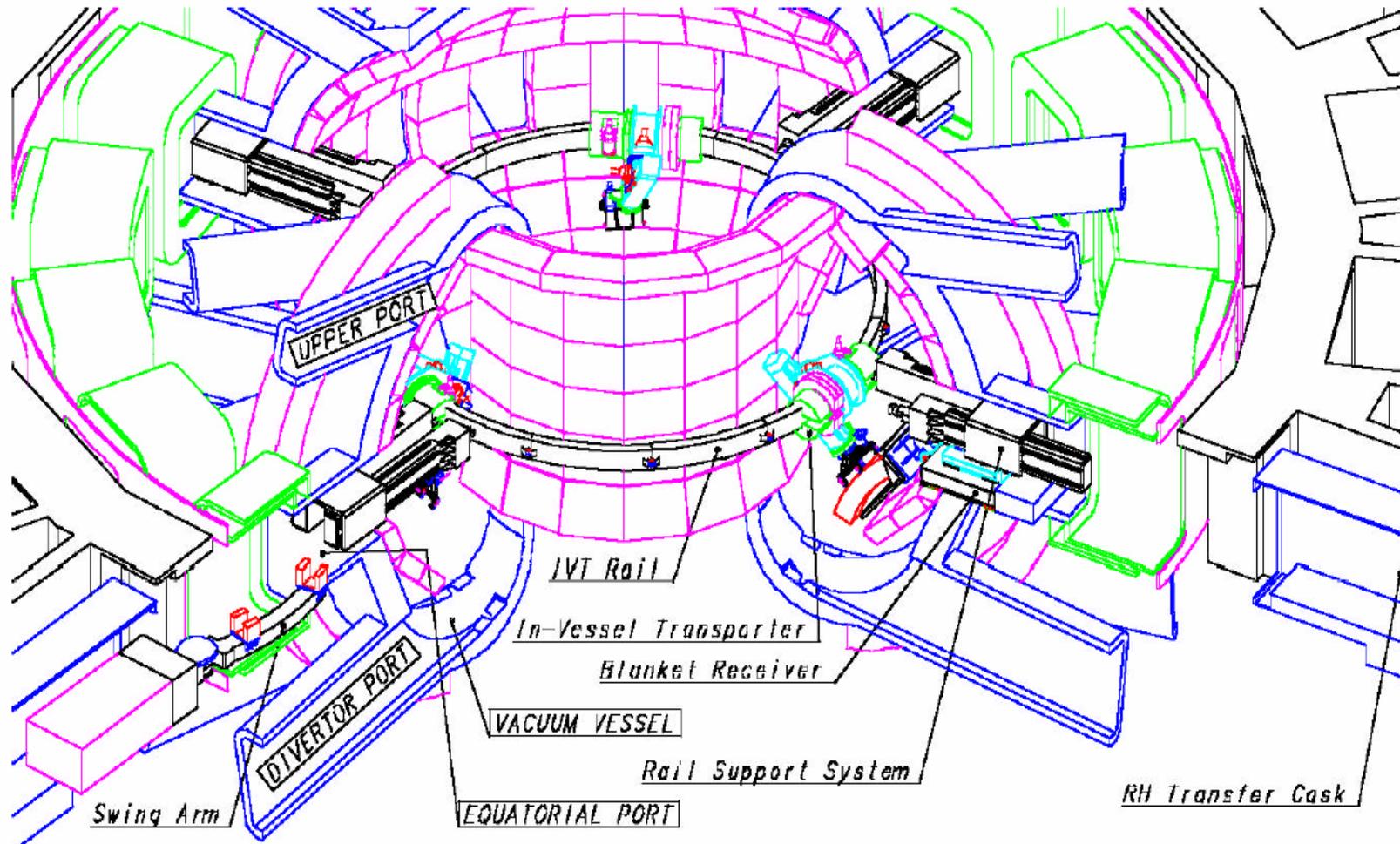
## PROJET L6 JAPON MAINTENANCE DES MODULES BLANKET



# ITER L6 - Maintenance des blankets – IVT

## *In Vessel Transporter*

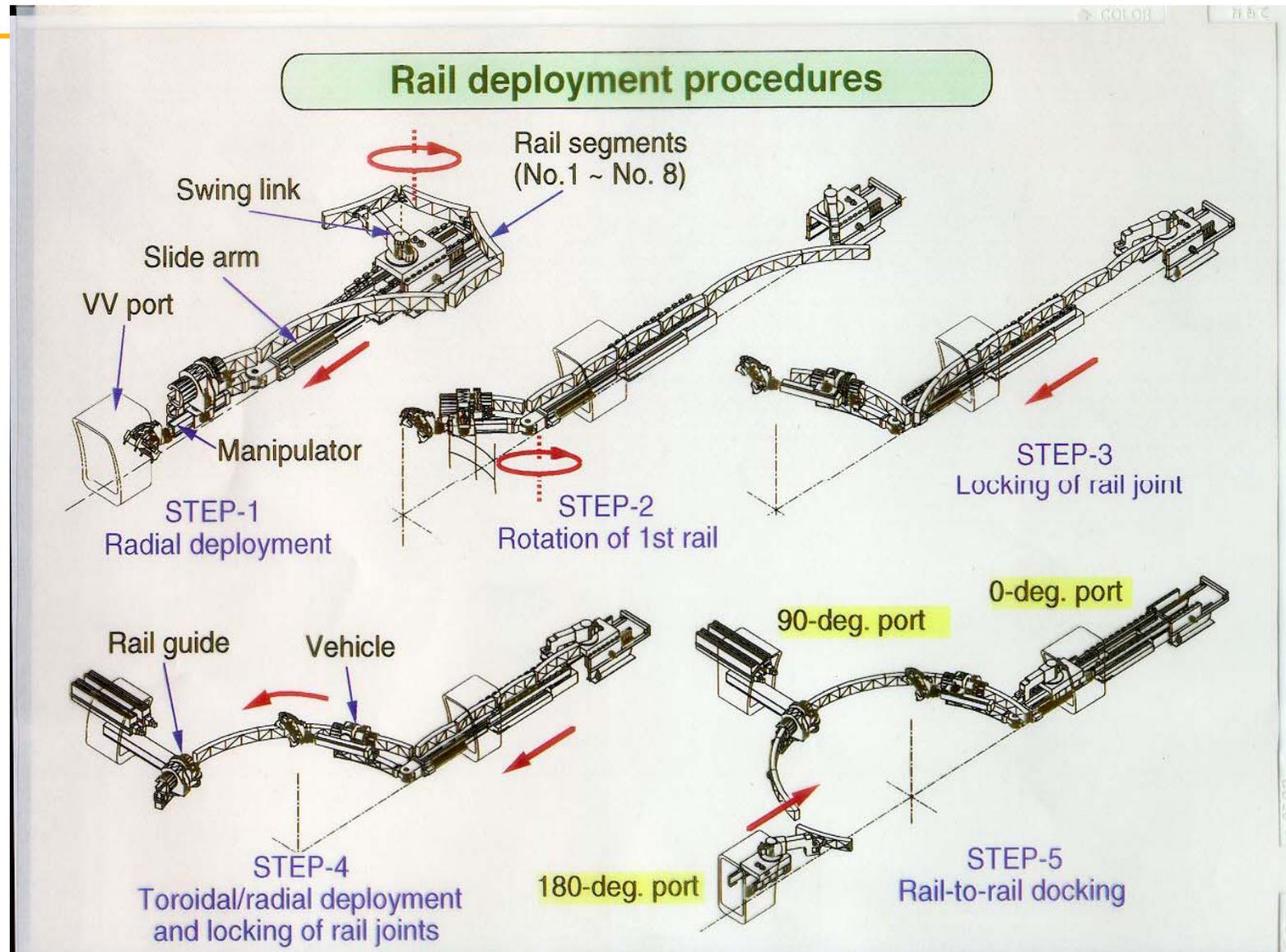
cea  
list



From Drawing 23.182.1

Figure 2.9.3-1 Blanket Maintenance Concept

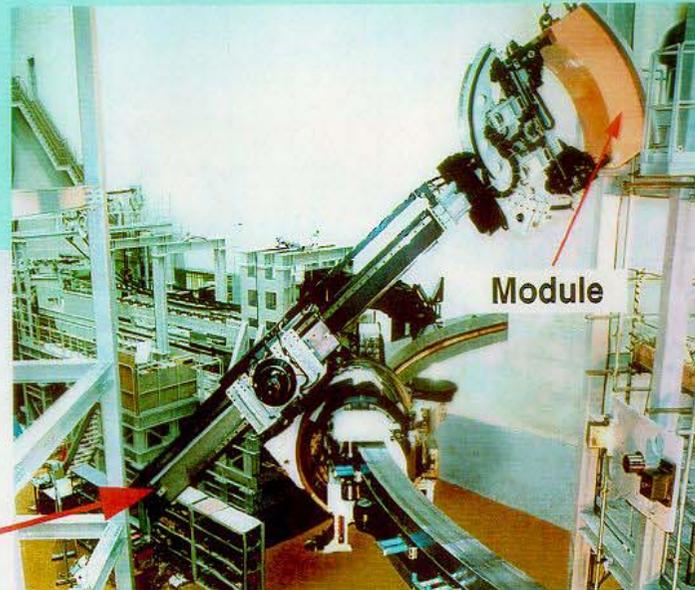
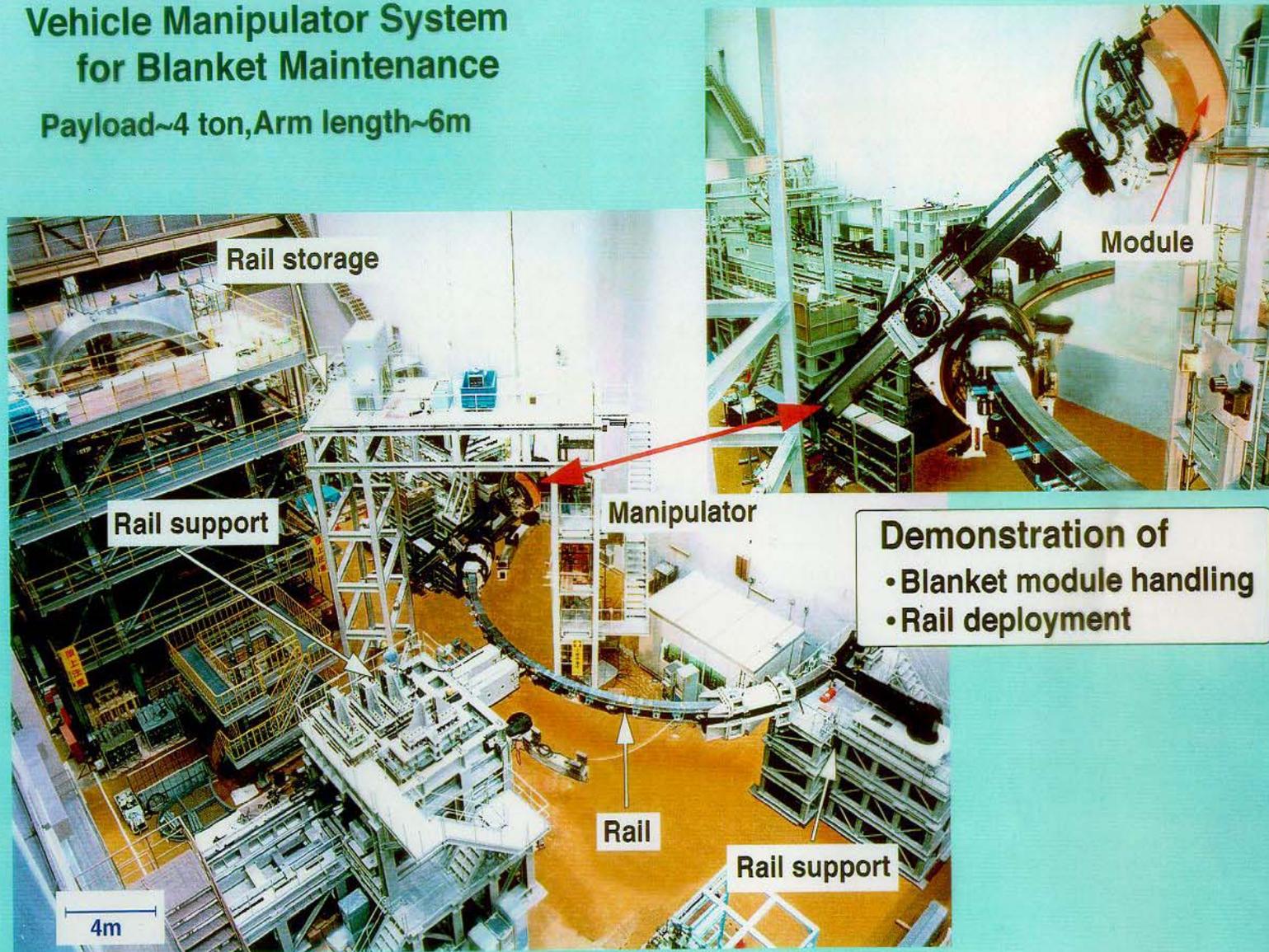
# ITER L6 - Maintenance des blankets - IVT



# ITER L6 - Maintenance des blankets - IVT



**Vehicle Manipulator System  
for Blanket Maintenance**  
Payload~4 ton, Arm length~6m



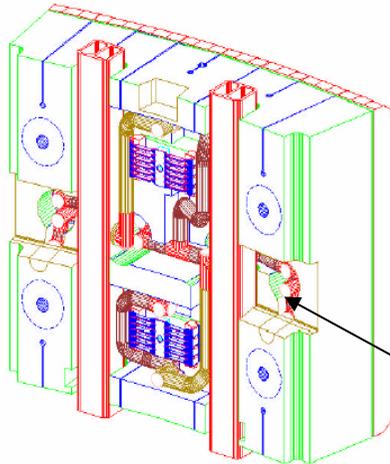
**Demonstration of**  
• Blanket module handling  
• Rail deployment

# ITER L6 - Maintenance des blankets - IVT

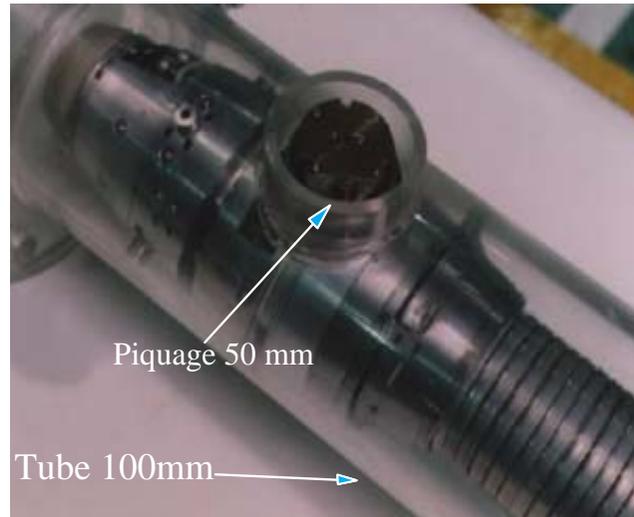


# ITER L6 - Maintenance des blankets

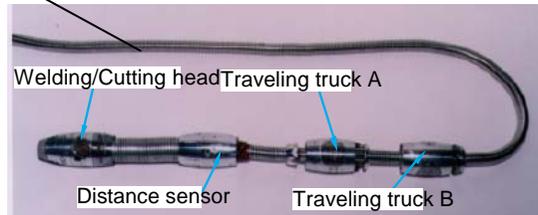
« BORE TOOLS » DECOUPE SOUDAGE CONDUITES REFROIDISSEMENT DES BLANKETS - PIQUAGE



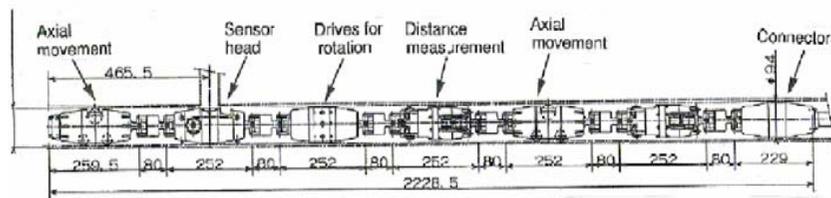
In Board Blanket Module



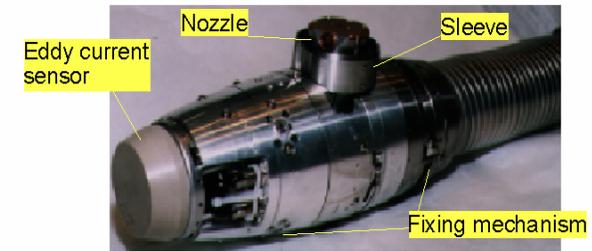
Welding / cutting nozzle



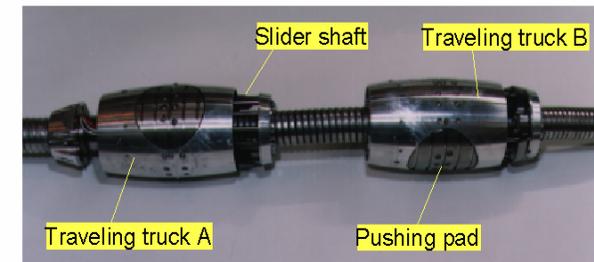
YAG Laser Processing Head



## Drive mechanism of the bore tool



Processing head



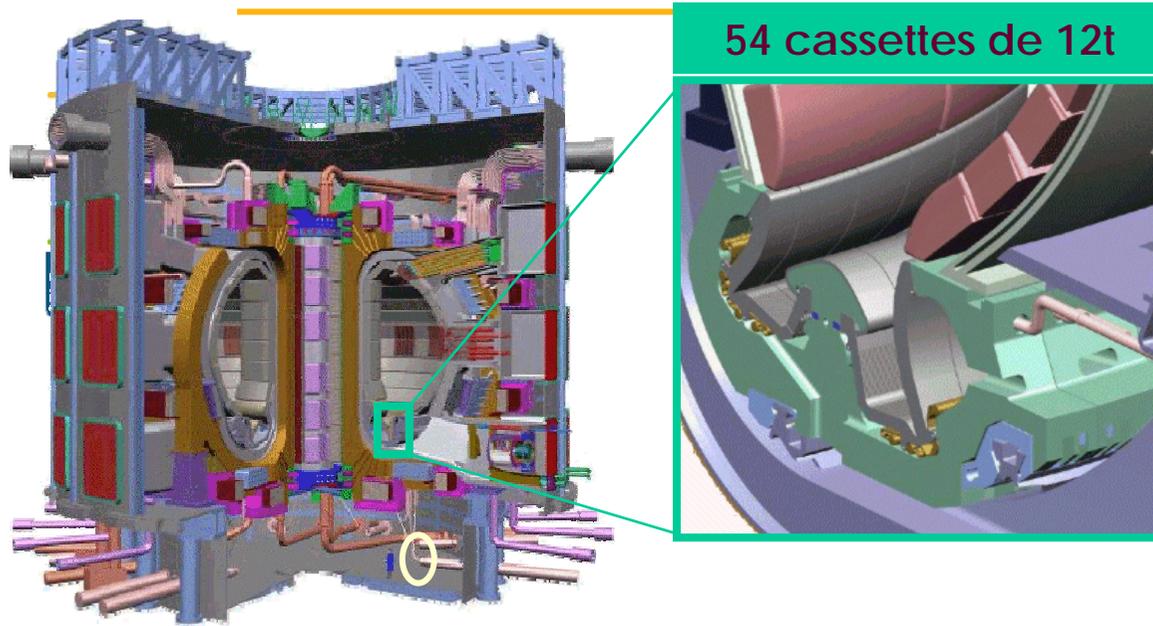
Traveling trucks

Axis name	Symbol	Velocity	Movement range	Axis name	Velocity	Movement range
Head rotation	$\theta$	16 sec/rev	$\pm 180$ deg.	Truck A support	8 mm/sec	8 mm
Nozzle movement	Z	30 mm/sec	20 mm	Truck A slider shaft	21 mm/sec	60 mm
Nozzle up & down	R	0.3 mm/sec	0~37 mm*	Truck B support	8 mm/sec	8 mm
Nozzle rotation	$\rho$	15 sec/rev	$\pm 180$ deg.	Truck B slider shaft	21 mm/sec	60 mm

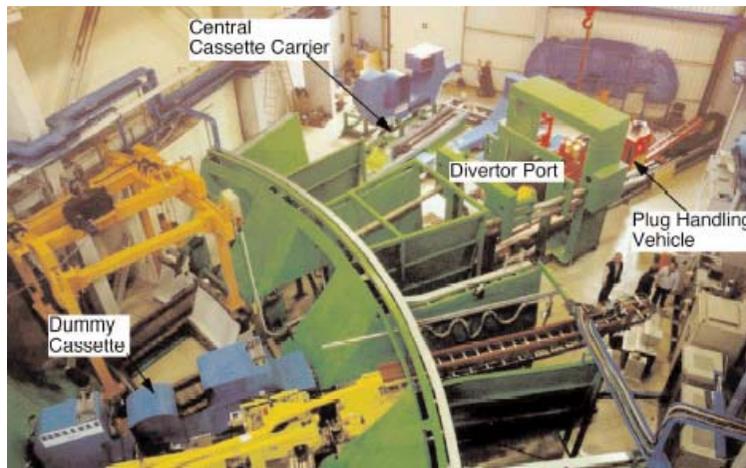
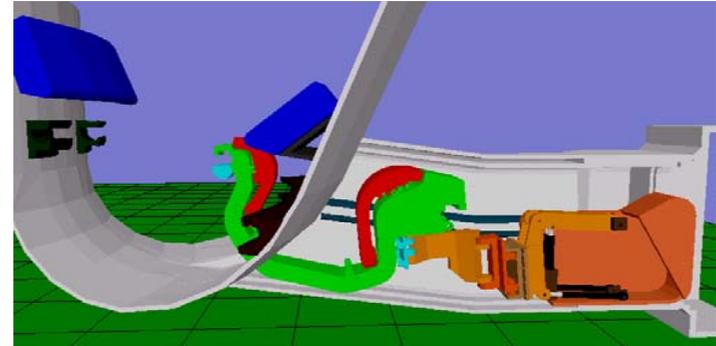
\* Welding/cutting region : 8 mm



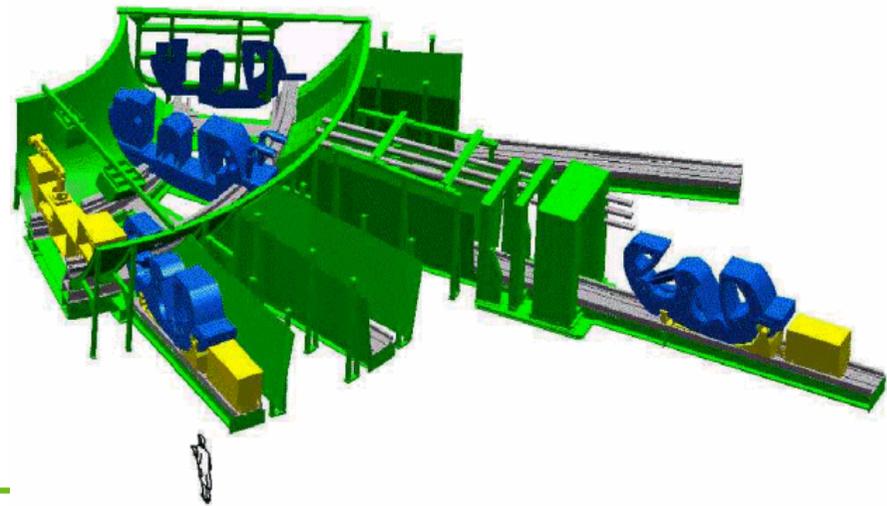
# ITER L7 - Maintenance du Divertor



Projet L7 -  
EUROPE  
Maintenance des  
cassettes divertor

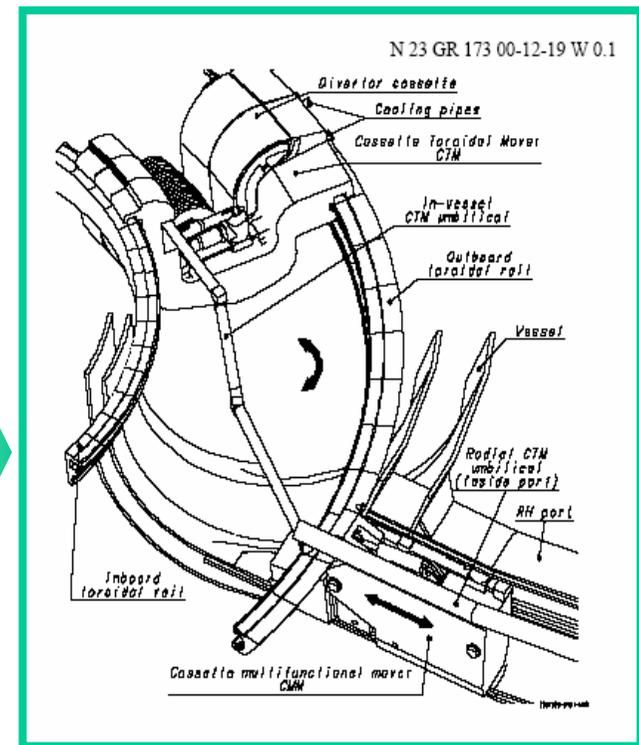
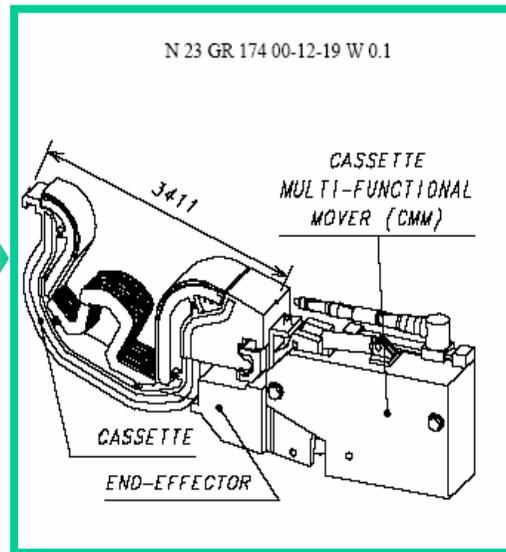
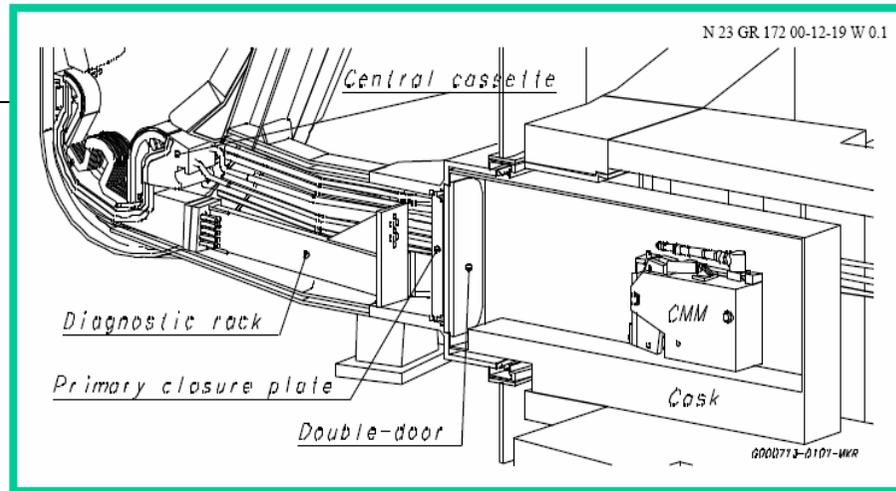


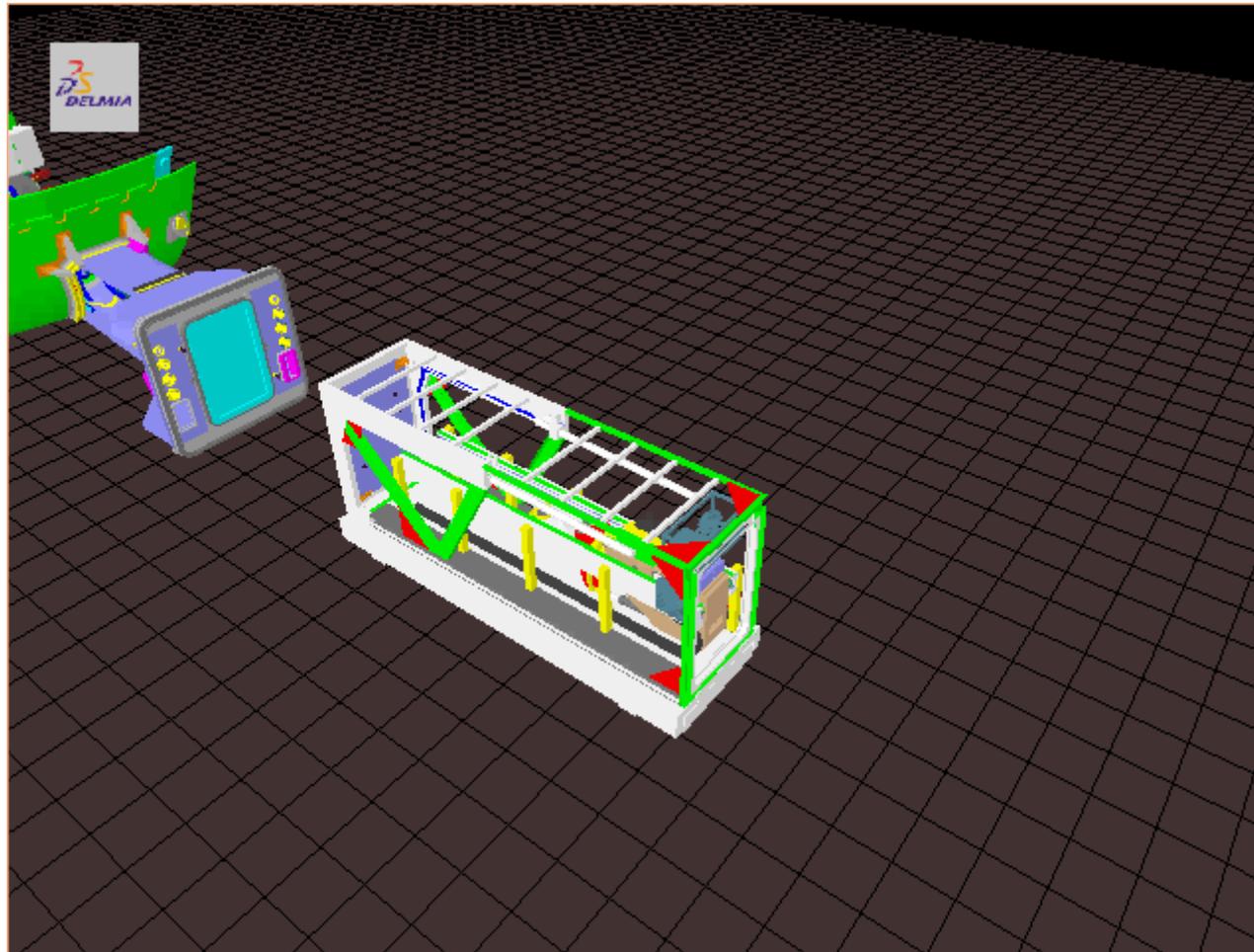
Divertor Test Platform (ENEA)



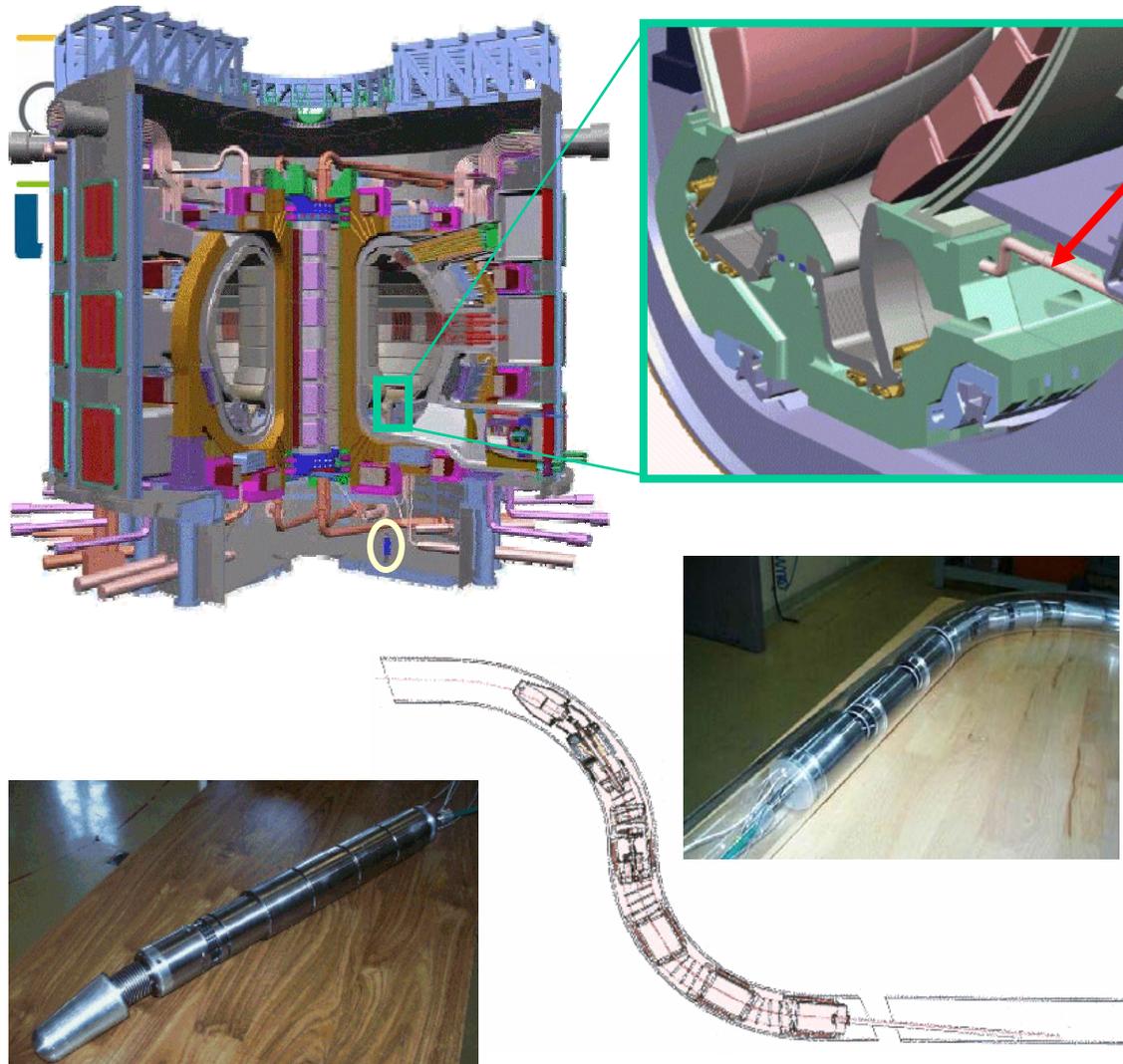
DTSI / Service Robotique Interactive







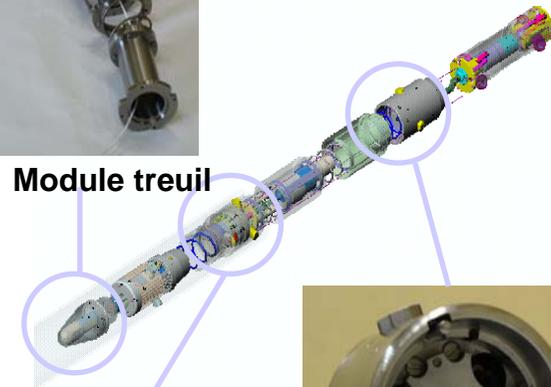
# ITER – L7 Maintenance du Divertor



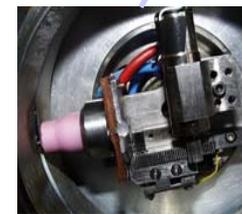
Maintenance des conduites de refroidissement du divertor d'ITER (CEA/LIST)



Module treuil



Module de clampage



Torche de pointage

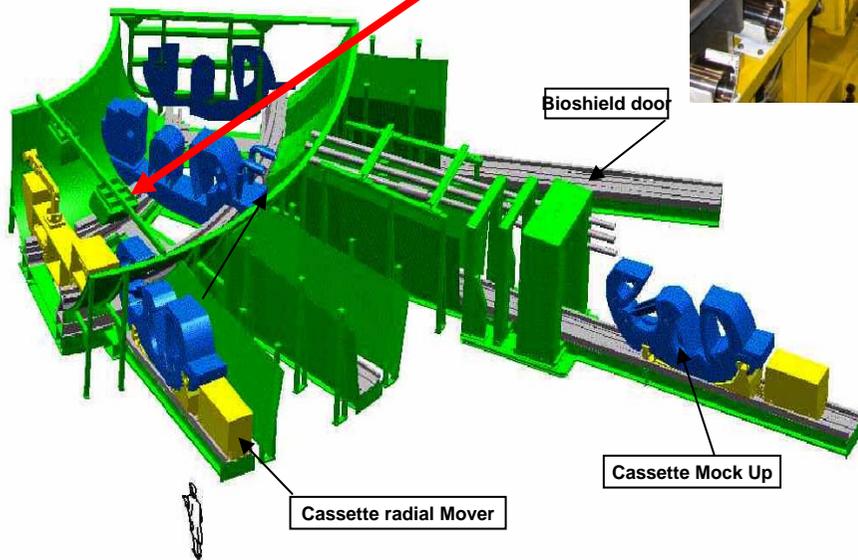
# ITER – L7 Maintenance du Divertor



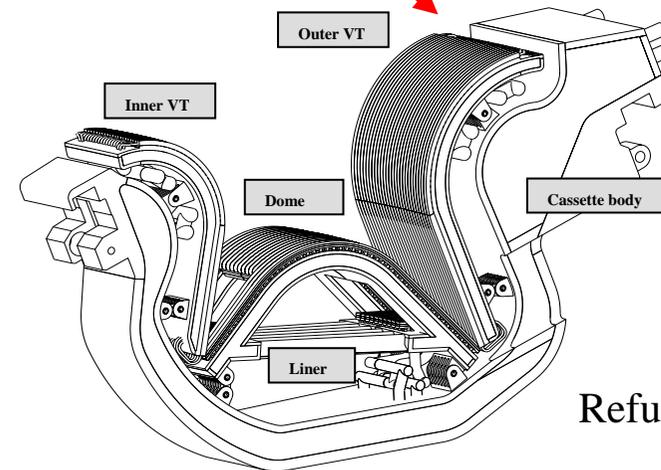
**MAESTRO (CEA)**  
ROBOT  
HYDRAULIQUE



Télérobotique à retour  
d'effort (CEA/LIST)



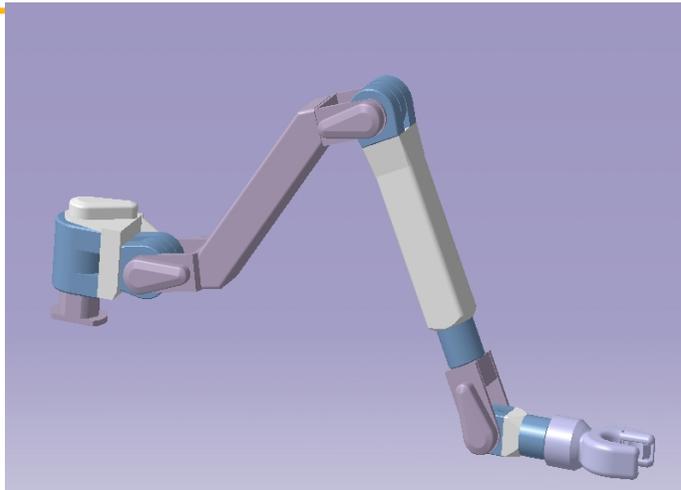
Divertor Test Platform (ENEA)



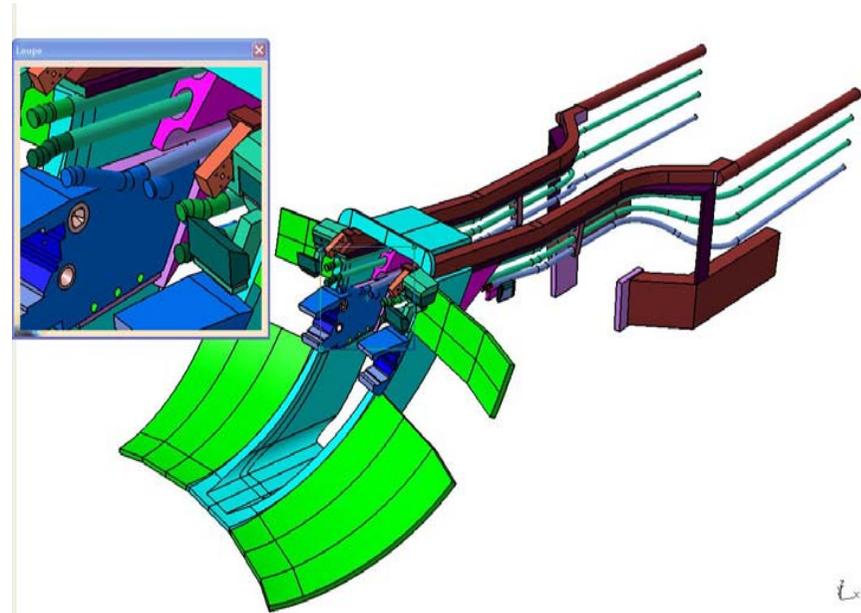
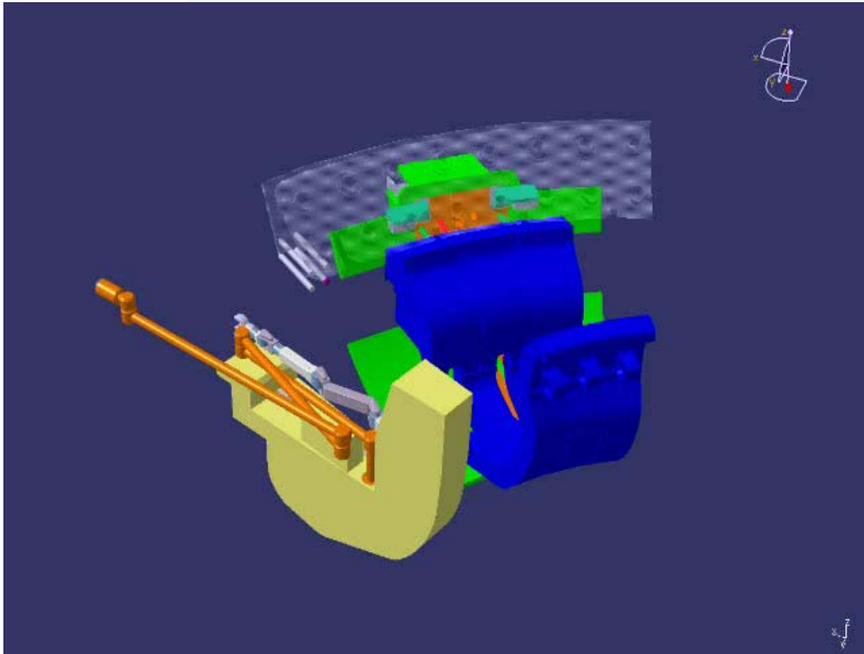
Divertor  
Refurbishment  
Platform



# ITER – L7 Maintenance du Divertor



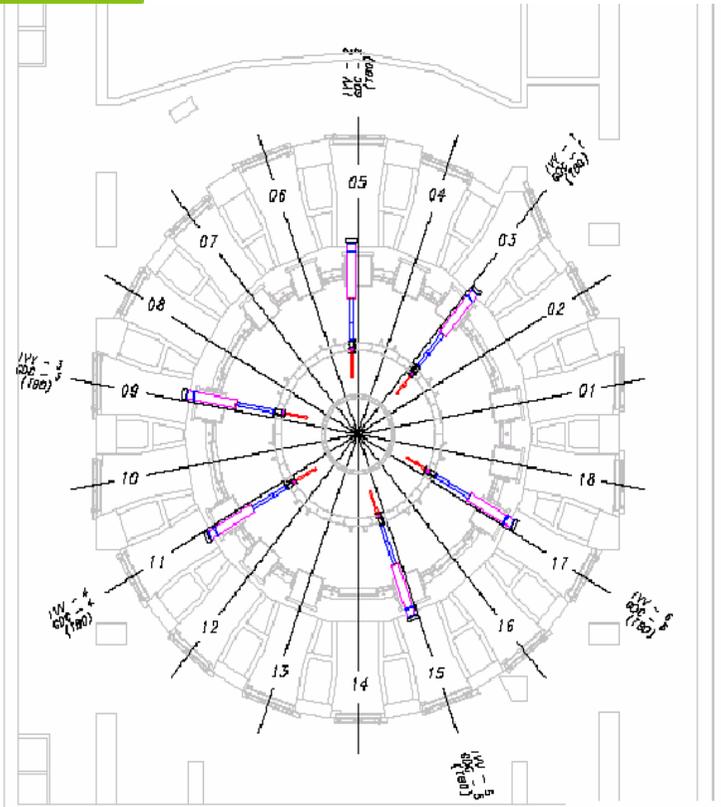
- Manipulator geometry based on the MAESTRO hydraulic slave arm :
  - 2m30, 150kg
  - 70kg Payload
  - Only existing today with oil technology.



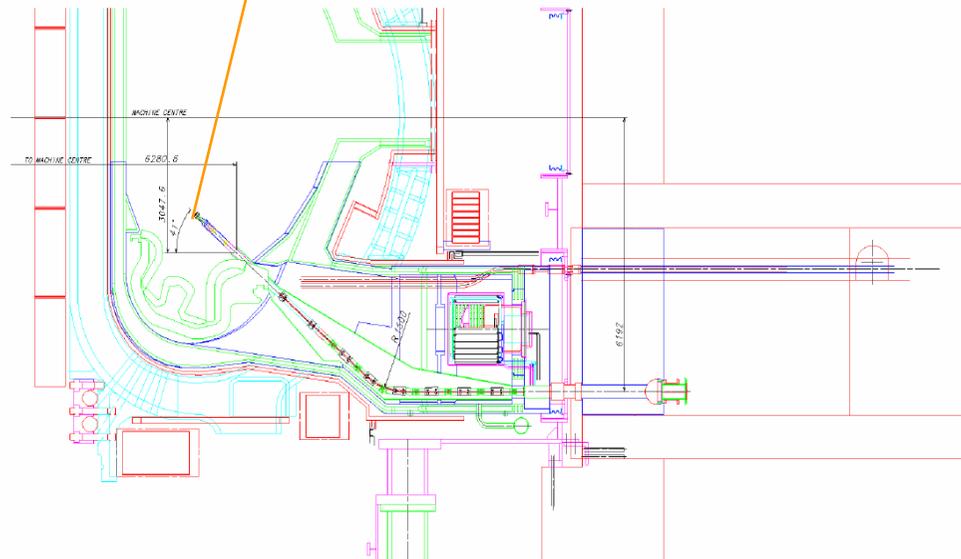
# ITER – L7 Maintenance du Divertor - Inspection



## IVVS In Vessel Viewing System



**Vision  
&  
Métrologie**



# ITER – L7 Maintenance du Divertor - AIA



## Objectifs :

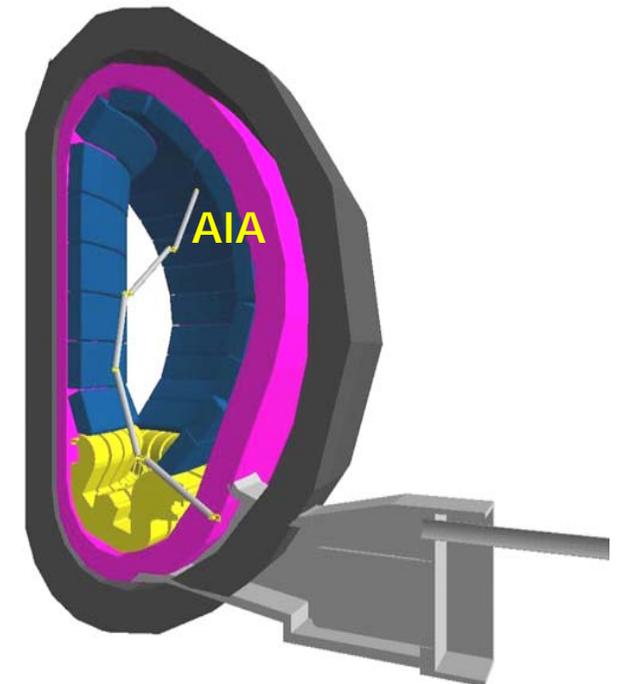
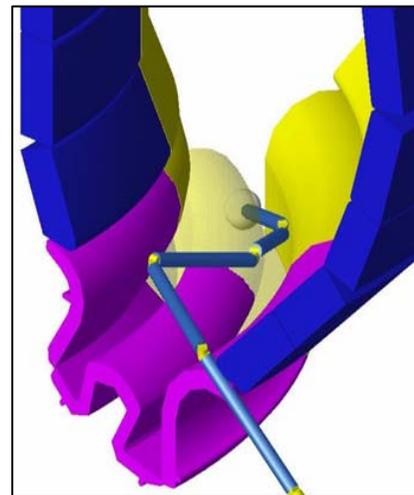
- inspection visuelle première paroi et Divertor,
- recherche de fuite sur K7 ou module de blanket,

## Autres applications possibles à développer :

- métrologie,
- aspiration poussières Be, W et CFC,
- détritiation laser
- prélèvement d'échantillons...

## AIA

élançement : 8m  
charge en bout : 10 kg  
Vide et température  
(120°C)



Articulated Inspection Arm

# ITER – L7 Maintenance du Divertor - AIA

cea

## Prototype « en air » - AREVA

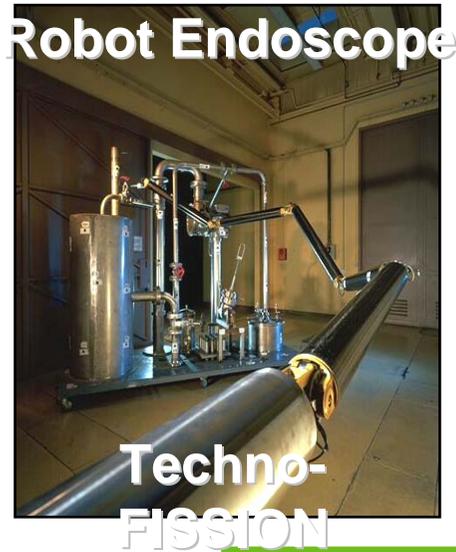
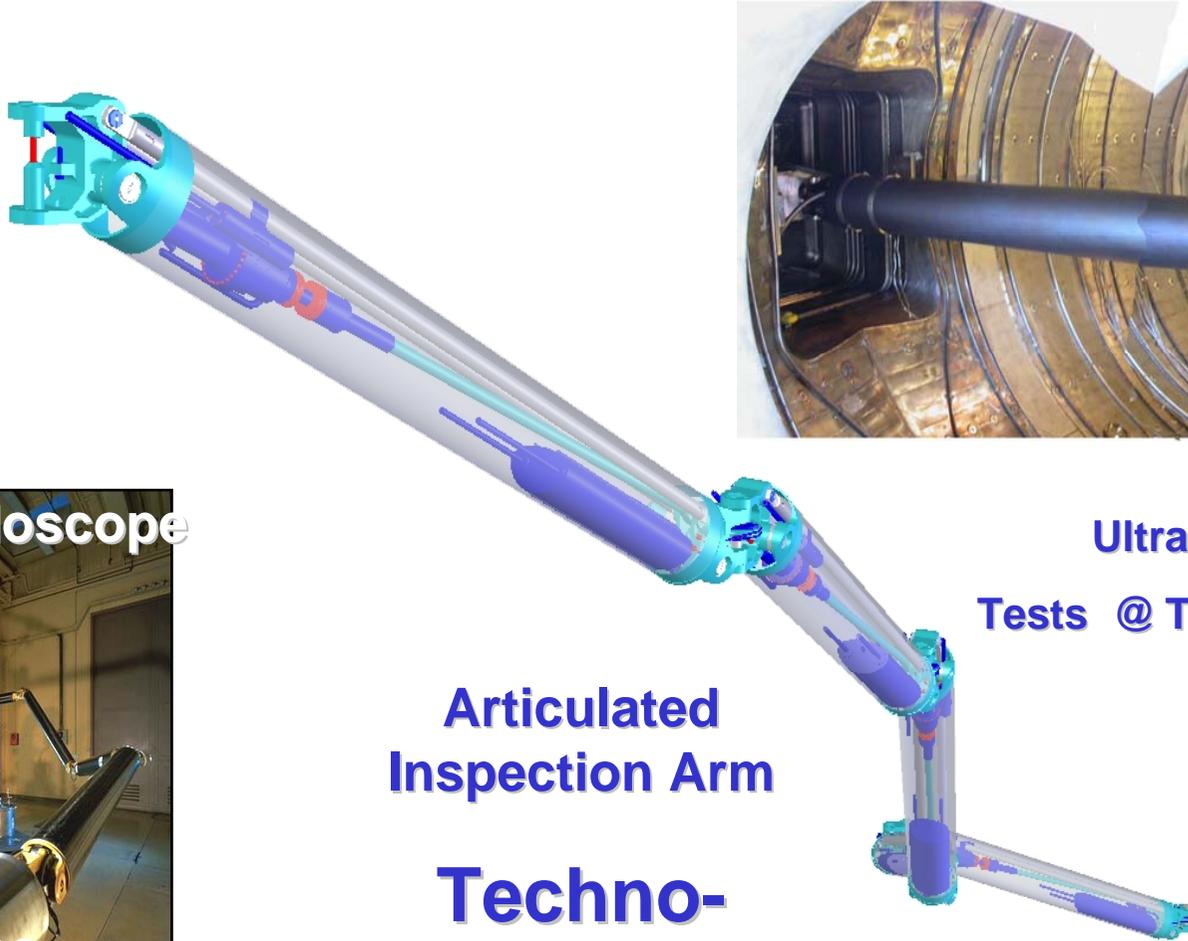
( 6 segments 11 axes,  $L=7.2m$ , *pression atmosphérique, T ambiante* )

list



# Robotique – Articulated Inspection Arm

Premiers succès du robot AIA en **Ultravide** et **Température**



**UltraVide & T° (120°)**

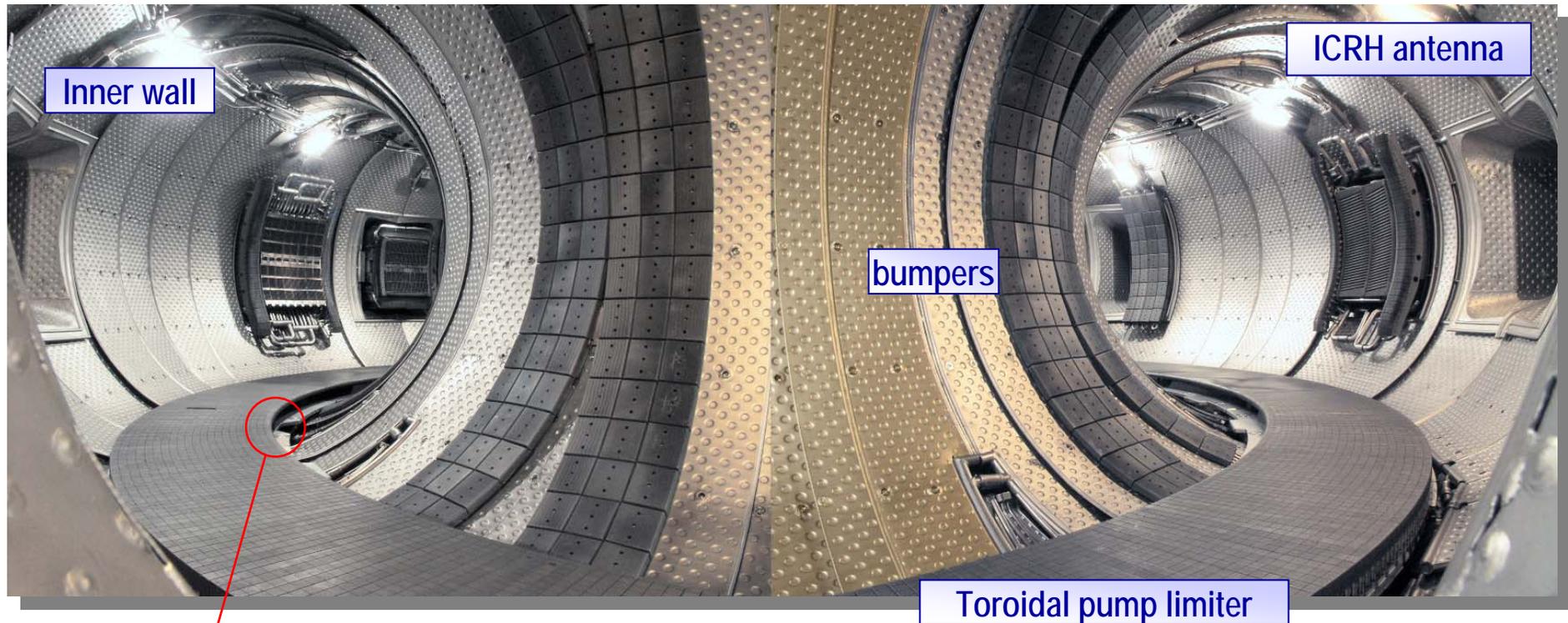
**Tests @ Tore Supra Cadarache**

**Articulated  
Inspection Arm**

**Techno-  
Fusion**



# TEST AIA en configuration réelle sur Tore Supra



Rather Large Tokamak

$$R_0 = 2.35 \text{ m}$$

$$a = 0.75 \text{ m}$$

DTSI / Service Robotique Interactive





## Pour plus d'information...



- **Projet ITER**

- [www.iter.org](http://www.iter.org)

- **European Fusion Development Agreement**

- [www.efda.org](http://www.efda.org)

- **Information sur la fusion contrôlée (CEA)**

- [www-fusion-magnetique.cea.fr](http://www-fusion-magnetique.cea.fr)

- **Cadarache, site de construction d'ITER**

- [www.itercad.org](http://www.itercad.org)

