

Complimentarity constraints with a system of nonlinear PDE's

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- In a deep underground nuclear waste disposal.
- Production of hydrogen from corrosion of waste packages.
- Migration of this hydrogen ?
- Flow can be **saturated (only liquid)** or **unsaturated (liquid/gas)**.
- Numerical difficulties when gas phase appears/disappears.
- **Examples of complementarity problems for porous media flow:**
 - **Chavent-Jaffré**, *Mathematical models and finite elements for reservoir simulation (North-Holland, 1986)*.
 - **Jaffré-Sbouï**. *Henry's law and gas phase disappearance*. Transport in Porous Media 12 (2010).
 - **Lauser-Hager-Helmig-Wohlmuth**. *Advances in Water Resources* 34 (2011).
 - **Buchholzer-Kanzow-Knabner-Kraütle**. Computational Optimization and Applications 50 (2011).

Advantage of formulation with complementarity constraints:
Valid whether the gas phase exists or not.

Goals

- Address numerical difficulties coming from **gas phase appearance/disappearance**.
- Construct a **robust algorithm** to resolve these difficulties.
- **Develop a solver** for nonlinear complementarity problems.

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2 fluid phases: liquid ($i = \ell$) and gas ($i = g$)

Darcy's law: $\mathbf{q}_i = -K(x)k_i(s_i)(\vec{\nabla} p_i - \rho_i g \vec{\nabla} z)$, $i = \ell, g$

K the absolute permeability

\mathbf{q}_i Darcy velocity, s_i saturation, p_i fluid pressure, k_i mobility

Phases occupy the entire pore space: $s_\ell + s_g = 1$.

Capillary pressure law: $p_c(s_\ell) = p_g - p_\ell \geq 0$, p_c decreasing, $p_c(1) = 0$.

Since liquid phase does not disappear while gas phase may disappear, the **main unknowns** will be s_ℓ and p_ℓ .

2 components: water ($j = w$) and hydrogen ($j = h$).

Mass density of phase i : $\rho_i = \rho_w^i + \rho_h^i$, $i = \ell, g$.

Molar concentration of phase i : $c_i = c_w^i + c_h^i = \frac{s_i \rho_w^i}{M^w} + \frac{s_i \rho_h^i}{M^h}$, $i = \ell, g$.

Molar fractions: $\chi_h^i = \frac{c_h^i}{c_i}$, $\chi_w^i = \frac{c_w^i}{c_i}$, $i = \ell, g$, ($\chi_w^i + \chi_h^i = 1$).

Physical assumptions :

- Liquid phase contains both components.
- Gas phase contains only hydrogen.
- Gas is compressible $\rho_g = \kappa_g p_g$.
- Liquid incompressible $\rho_w^\ell = \text{constant}$, $c_h^\ell \ll c_w^\ell$,

$$\chi_h^\ell \simeq \frac{c_h^\ell}{c_w^\ell} = C_\ell \rho_h^\ell \text{ with } C_\ell = \frac{M^h}{M^w \rho_w^\ell}.$$

χ_h^ℓ is the third main unknown.

Water:
$$\phi \frac{\partial}{\partial t} (s_\ell \rho_w^\ell) + \text{div}(\rho_w^\ell \mathbf{q}_\ell + \mathbf{j}_w^\ell) = Q_w$$

Hydrogen:
$$\phi \frac{\partial}{\partial t} (s_\ell \rho_h^\ell + s_g \rho_g) + \text{div}(\rho_h^\ell \mathbf{q}_\ell + \rho_g \mathbf{q}_g + \mathbf{j}_h^\ell) = Q_h,$$

where **diffusion of the components in the liquid phase** is modeled by

$$\mathbf{j}_h^\ell = -\phi M^h s_\ell c_\ell D_h^\ell \vec{\nabla} \chi_h^\ell, \quad \mathbf{j}_h^\ell + \mathbf{j}_w^\ell = 0.$$

ϕ = porosity, D_h^ℓ = molecular diffusion coefficient.

Complementarity equations

- **Henry's law** is $\tilde{H}(T)M^h p_g = H p_g = \rho_h^\ell = C_\ell \chi_h^\ell$. It is valid when both phases are present.
- To integrate Henry's law into a formulation which includes the case with no gas phase, introduce the liquid pressure $p_\ell = p_g - p_c(s_\ell)$, and
 - either **gas phase exists**: $1 - s_\ell > 0$ and $H(p_\ell + p_c(s_\ell)) - C_\ell \chi_h^\ell = 0$,
 - or **gas phase does not exist**: $s_\ell = 1$, $p_c(s_\ell) = 0$ and $H p_\ell - C_\ell \chi_h^\ell \geq 0$, that is χ_h^ℓ is too small for gas to appear.

Complementarity constraints

$$(1 - s_\ell)(H(p_\ell + p_c(s_\ell)) - C_\ell \chi_h^\ell) = 0, \quad 1 - s_\ell \geq 0, \\ H(p_\ell + p_c(s_\ell)) - C_\ell \chi_h^\ell \geq 0.$$

Advantage: Avoid the change of variables and equations in saturated/unsaturated regions.

$$\phi \frac{\partial}{\partial t} (\rho_w^\ell s_\ell) + \operatorname{div}(\rho_w^\ell \mathbf{q}_\ell - j_h^\ell) = Q_w$$

$$\phi \frac{\partial}{\partial t} (s_\ell C_\ell \chi_h^\ell + (1 - s_\ell) \kappa_g(p_\ell + p_c(s_\ell))) + \operatorname{div}(C_\ell \chi_h^\ell \mathbf{q}_\ell + \kappa_g(p_\ell + p_c(s_\ell)) \mathbf{q}_g + j_h^\ell) = Q_h$$

where $j_h^\ell = -\phi s_\ell^2 C_\ell (1 + \chi_h^\ell) D_h^\ell \vec{\nabla} \chi_h^\ell$

$$\mathbf{q}_\ell = -K(x) k_\ell(s_\ell) (\vec{\nabla} p_\ell - \rho_\ell g \vec{\nabla} z)$$

$$\mathbf{q}_g = -K(x) k_g(1 - s_\ell) (\vec{\nabla} (p_\ell + p_c(s_\ell)) - \kappa_g(p_\ell + p_c(s_\ell)) g \vec{\nabla} z),$$

$$(1 - s_\ell) (H(p_\ell + p_c(s_\ell)) - C_\ell \chi_h^\ell) = 0, \quad 1 - s_\ell \geq 0, \\ H(p_\ell + p_c(s_\ell)) - C_\ell \chi_h^\ell \geq 0.$$

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Discretized with **cell-centered finite volumes** : N , the number of cells.

$x \in \mathbb{R}^{3N}$, vector of unknowns for $s_\ell, p_\ell, \chi_h^\ell$

$\mathcal{H} : \mathbb{R}^{3N} \rightarrow \mathbb{R}^{2N}$ for discrete **conservation equations**

$\mathcal{F} : \mathbb{R}^{3N} \rightarrow \mathbb{R}^N$ for discrete $1 - s_\ell$

$\mathcal{G} : \mathbb{R}^{3N} \rightarrow \mathbb{R}^N$ for discrete $H(p_\ell + p_c(s_\ell)) - C_\ell \chi_h^\ell$

Problem in compact form

$$\mathcal{H}(x) = 0,$$

$$\mathcal{F}(x) \top \mathcal{G}(x) = 0, \quad \mathcal{F}(x) \geq 0, \quad \mathcal{G}(x) \geq 0.$$

Introduce $K = \mathbb{R}^n \times \mathbb{R}_+^p$.

Find $(x, u) \in K$

$$\begin{pmatrix} \mathcal{H}(x) \\ \mathcal{F}(x) - u \\ \mathcal{G}(x) \end{pmatrix}^\top \begin{pmatrix} y - x \\ v - u \end{pmatrix} \geq 0, \quad \forall (y, v) \in K.$$

How to solve this nonlinear complementarity problem ?

Idea: Replace complementarity conditions by equalities.

Introduce a **C-function** $\varphi : \mathbb{R}^2 \rightarrow \mathbb{R}$ that satisfies

$$\varphi(a, b) = 0 \iff a \geq 0, \quad b \geq 0, \quad ab = 0,$$

An efficient choice is **the minimum function**.

Replace complementarity constraints by $\varphi(x) = \min\{\mathcal{F}(x), \mathcal{G}(x)\} = 0$.

The problem is equivalent to

$$\psi(x) = 0, \quad \text{where} \quad \psi(x) := \begin{pmatrix} \mathcal{H}(x) \\ \varphi(x) \end{pmatrix}.$$

- The system is **nonsmooth due to the min function**.
- Apply **Newton-min**, a nonsmooth Newton method.
- Local convergence of Newton-min.

See I. Ben Gharbia & J. Ch Gilbert (2010), S. Kräutle (2011), P. Knabner et al. (2009), Ito & Kunish (2009) and C. Kanzow (2004)

For $k = 1, 2, \dots$, do the following

- Choose complementary index sets A_k and A_k^c , where

$$A_k := \{i : \mathcal{F}_i(x^k) < \mathcal{G}_i(x^k)\},$$

$$A_k^c := \{i : \mathcal{F}_i(x^k) \geq \mathcal{G}_i(x^k)\}.$$

$$\varphi(x^k) = \min\{\mathcal{F}(x^k), \mathcal{G}(x^k)\} = \begin{cases} \mathcal{F}_i(x^k) & \text{if } i \in A_k, \\ \mathcal{G}_i(x^k) & \text{if } i \in A_k^c. \end{cases}$$

- Select an element $\mathcal{J}_{x^k}^k \in \partial\varphi(x^k)$ such that

$$(\mathcal{J}_{x^k}^k)_i = \begin{cases} \mathcal{F}'_i(x^k) & \text{if } i \in A_k, \\ \mathcal{G}'_i(x^k) & \text{if } i \in A_k^c. \end{cases}$$

- Let x^{k+1} be a solution to

$$\mathcal{H}(x^k) + \mathcal{H}'(x^k)(x^{k+1} - x^k) = 0,$$

$$\varphi(x^k) + \mathcal{J}_{x^k}^k(x^{k+1} - x^k) = 0.$$

Theorem:

Let x^* be a solution of the nonlinear system $\psi(x) = 0$ and such that J is nonsingular for all $J \in \partial\psi(x^*)$. Then there exists ϵ such that for every starting point $x^0 \in B_\epsilon(x^*)$:

- ▶ The Newton-min algorithm is well-defined and produces a sequence $\{x^k\}$ that converges to x^* .
- ▶ The rate of convergence is **quadratic**.

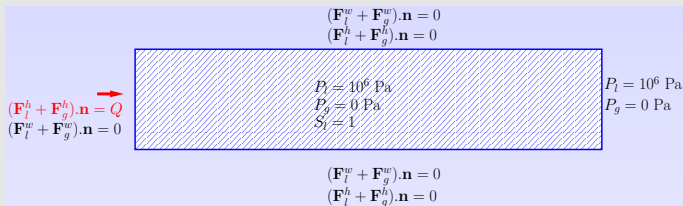
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Homogeneous setting

Test inspired from the **Couplex Gas benchmark**:

- Inject hydrogen gas on the left of a 1-D porous medium saturated at initial time with liquid ($T_{inj} = 5 \cdot 10^5$ years).
- After a while the hydrogen injection is stopped ($T_{simul} = 10^6$ years).



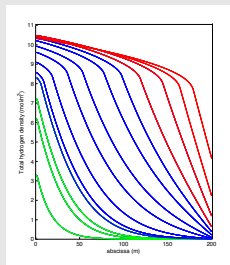
- **Van Genuchten-Mualem model** for capillary pressure and relative permeabilities.
- Initial conditions: $p_\ell = 10^6$ Pa, $s_\ell = 1$ and $\chi_h^\ell = 0$.

Numerical results - Homogeneous setting

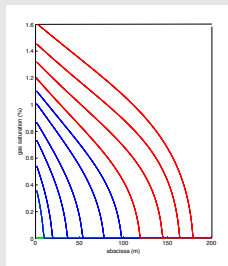
During injection: $0 < t < 5 \cdot 10^5$ years

- Period 1: Only Hydrogen density increases.
- Period 2: Gas phase appears and liquid pressure increases.
- Period 3: Smaller $\vec{\nabla} p_\ell$ and no water injection push down the liquid pressure.

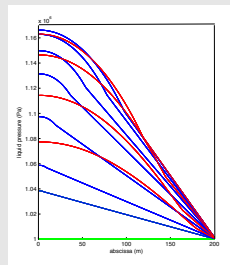
H₂ density



Gas saturation



Liquid pressure

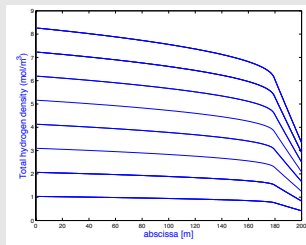


Numerical results - Homogeneous setting

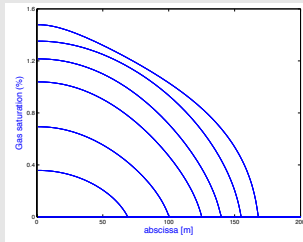
After injection is stopped: $t > 5 \cdot 10^5$ years

- Gas saturation and H_2 density decrease.
- Liquid pressure increases.
- When $t \rightarrow \infty$, gas phase disappears and the system reaches a stationary state.

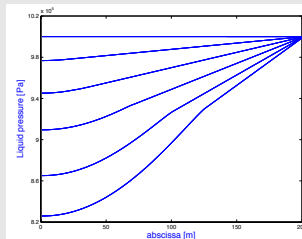
H_2 density

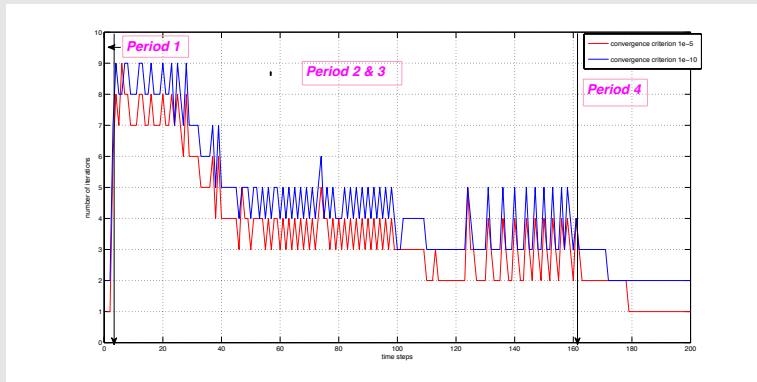


Gas saturation



Liquid pressure

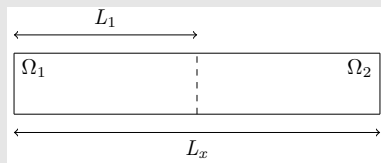




I. Ben Gharbia and J. Jaffré, Gas phase appearance and disappearance as a problem with complementarity constraints, *Mathematics and Computers in Simulation* (submitted).

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- ▶ Consider MOMAS heterogeneous benchmark Problem 2.
- ▶ The porous medium characteristics and the fluids properties are from http://sources.univ-lyon1.fr/cast_test/multi.mat.pdf.



- ▶ The characteristics of porous medium (in particular capillary pressure) are different in each subdomain. $\mathcal{L}_x = 200$, $\mathcal{L}_1 = 100$.
- ▶ Boundary and initial conditions
 - At $t = 0$: $p_\ell = 10^6$ Pa, $s_\ell = 1$ and $\chi_h^\ell = 0$,
 - At $x = 200$: $p_\ell = 10^6$ Pa,
 - At $x = 0$: $\text{flux}_{\text{hydrogen}} = 5.57 \text{ mg/m}^2/\text{yr}$, $\text{flux}_{\text{water}} = 0$.

▷ Interface conditions

- Liquid pressure should be continuous: $p_\ell^{(1)} = p_\ell^{(2)}$.
- Water flux should be continuous: $\mathbf{u}_w^{(1)} = \mathbf{u}_w^{(2)}$.
- Hydrogen flux should be continuous: $\mathbf{u}_h^{(1)} = \mathbf{u}_h^{(2)}$.
- Capillary pressure continuity condition: $p_c^{(1)}(s^{(1)}) = p_c^{(2)}(s^{(2)})$.

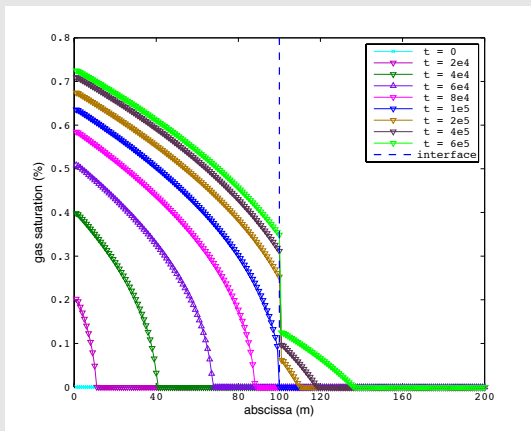
▷ Meshes

- Uniform in space: $\Delta x = 1\text{m}$ in each subdomain.
- In time: $\Delta t = 2000$ years.

▷ Convergence criterion: 10^{-8} .

Numerical results - Heterogeneous setting

Gas saturation at several times (in years)



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- The formulation handles well appearance and disappearance of the gas phase.
- Newton-min is well adapted for our problem.
- Locally quadratic convergence.

F. Clément, J. Ch. Gilbert, M. Kern, J. E. Roberts, M. Vohralik, P. Weis, G. Chavent.

- Mixed finite elements on meshes of deformed cubes.
- A posteriori error estimates.
- Time-space domain decomposition.
- Discrete fracture flow models with matrix-fracture interaction: fractures are modeled as $n - 1$ dimensional interfaces.
- Solvers and HPC.
- Some inverse problems from hydrogeology.
- Safe scientific computing using Ocaml.