Ultrarigid periodic frameworks

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Abstract

I will present recent progress on algebraic and combinatorial characterizations of periodic frameworks obtained with Justin Malestein in [3].

Background

A periodic framework is an infinite structure in Euclidean d-space, made of fixed-length bars connected by universal joints and symmetric with respect to a lattice $\Gamma \cong \mathbb{Z}^d$. The allowed motions preserve the lengths and connectivity of the bars, and symmetry with respect to the action of Γ on the graph \tilde{G} that has as its edges the bars (but not necessarily the geometric representation of Γ). A periodic framework is periodically rigid if the allowed motions all arise from applying a Euclidean isometry to the whole structure and periodically flexible otherwise.

For this setting there are good algebraic [1] and, in dimension 2, combinatorial [2] characterizations of rigidity and flexibility. These results (and other similar ones) make use of the fact that the configurations spaces of periodic frameworks are homeomorphic to finite-dimensional algebraic varieties. Simply dropping the symmetry constraints on the motions invalidates this assumption, so tools from [1, 2] don't apply.

Ultrarigidity

In this talk, I will discuss *periodically ultrarigid* periodic frameworks, which are periodically rigid and remain so when the symmetry constraint on the motions is relaxed to require only symmetry with respect to any finite index sub-lattice $\Lambda < \Gamma$.

In particular, I will describe:

- An *algebraic characterization* of infinitesimal ultrarigidity based on new rigidity matrices with entries in an appropriate group ring.
- A simple *algorithm* for checking whether a framework is periodically ultrarigid that uses new bounds on the minimal orders of torsion points in varieties.
- Polynomial-time checkable *combinatorial characterizations* of generically ultrarigid graphs in dimension d = 2 with n vertices and m = 2n + 1 edges.

References

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