Spectral Clustering & Reproducing Kernels

Ilaria Giulini

INRIA Saclay

Joint work with Olivier Catoni

23 October 2015

RDMath IdF Domaine d'Intérêt Majeur (DIM) en Mathématiques



▲ロト ▲ □ ト ▲ □ ト ▲ □ ト ● ● の Q ()

Clustering: task of grouping objects into classes (clusters) according to their similarities.

Spectral clustering methods use data-dependent matrices (Laplacian matrix) to perform unsupervised clustering.

Setting: Spectral clustering in a Hilbert space (where the points are i.i.d. according to an unknown distribution whose support is a union of compact connected components).

Our approach:

View spectral clustering as a change of representation in a RKHS

< □ > < 同 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

- Modify the Ng, Jordan, Weiss algorithm (interpretation in terms of Markov chains with exp transitions)
- Estimate automatically the number of clusters.

EXAMPLE

Goal: Cluster $X_1, \ldots, X_n \in \mathbb{R}^2$ (n = 900)



data[,1]

・ロト ・ 四ト ・ ヨト ・ ヨト

æ

EXAMPLE



Note: clusters are at the vertices of a simplex \rightarrow classification becomes trivial

NG, JORDAN, WEISS ALGORITHM

Input:

- X_1, \ldots, X_n the points to cluster
- *c* the number of clusters

1. Form
$$A_{ij} = \begin{cases} \exp(-\beta ||X_i - X_j||^2) & \text{if } i \neq j \\ 0 & \text{otherwise} \end{cases}$$

- 2. Construct $L = D^{-1/2}AD^{-1/2}$ where $D_{ii} = \sum_j A_{ij}$
- 3. Compute *c* largest eigenvectors v_1, \ldots, v_c of *L* and form $X = [v_1 \ldots v_c]_{n \times c}$
- 4. Cluster each (renormalized) row of *X* into *c* clusters (e.g. via *k*-means)

INTUITION

Let decompose

$$L = U \operatorname{diag}(\lambda_1, \ldots, \lambda_n) U^{\top}$$

The Ng, Jordan, Weiss algorithm is based on

$$U \operatorname{diag}(\lambda_1,\ldots,\lambda_c,0,\ldots,0) U^{\top}$$

Idea: Replace the projection with a smooth cut-off of the eigenvalues. More precisely

$$U \operatorname{diag}(\lambda_1^m,\ldots,\lambda_n^m) U^{\top}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三回 - のへぐ

UNDERLYING INTEGRAL OPERATORS

Idea: View previous matrices as empirical versions of underlying integral operators.

Assume $X_1, \ldots, X_n \in \mathcal{H} \sim P$ (unknown).

 $A \quad (affinity matrix) \qquad \longleftrightarrow \qquad K(x, y) = \exp\left(-\beta ||x - y||^2\right)$ $L = D^{-1/2}AD^{-1/2} \qquad \longleftrightarrow \qquad \bar{K}(x, y) = \mu(x)^{-1/2}K(x, y)\mu(y)^{-1/2}$ $D_{ii} = \sum_{j} A_{ij} \qquad \longleftrightarrow \qquad \mu(x) = \int K(x, z) \, dP(z)$ $\{\xi_i\}_{i=1}^n \mapsto \frac{1}{n} \sum_{j=1}^n L_{ij}\xi_j \quad \longleftrightarrow \qquad L_{\bar{K}} : f \mapsto \int \bar{K}(x, z)f(z) \, dP(z)$

▲□▶▲圖▶▲圖▶▲圖▶ 圖 のへで

MARKOV CHAIN ANALYSIS OF SPECTRAL CLUSTERING

The matrix A is used to form $M = D^{-1}A$ (Markov matrix with exp transitions).

Note:

$$\{\xi_i\}_{i=1}^n \mapsto \frac{1}{n} \sum_{j=1}^n L_{ij}\xi_j = \frac{1}{n} \sum_{j=1}^n D_{ii}^{1/2} M_{ij} D_{jj}^{-1/2}\xi_j$$

To determine clusters, use $M^{\exp(\beta T)}$

Hope for a similar behavior in the continuous case:

Define $M(x, y) = \mu(x)^{-1}K(x, y)$, so that

$$L_{\bar{K}}: f \mapsto \int \bar{K}(x,z) f(z) \, \mathrm{dP}(z) = \mu(x)^{1/2} \int M(x,z) \mu(z)^{-1/2} f(z) \, \mathrm{dP}(z)$$

< □ > < 同 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Idea: Consider an iterate of $L_{\bar{K}}$.

MARKOV CHAINS AND LAPLACIAN ITERATES

Remark that

$$L_{\bar{K}}^{2m}f(x) = L_{\bar{K}_{2m}}f(x) = \int \bar{K}_{2m}(x,z) f(z) \, \mathrm{d}\mathbf{P}(z),$$

where

$$\bar{K}_{2m}(x,y) = \int \bar{K}(y,z_1)\bar{K}(z_1,z_2)\dots\bar{K}(z_{2m-1},x) \,\mathrm{d}\mathbf{P}^{\otimes(2m-1)}(z_1,\dots,z_{2m-1})$$

whereas the kernel *M* defines a Markov chain $(Z_k)_{k \in \mathbb{N}}$ with transitions

$$M(x, y) = \frac{\mathrm{d} \mathbf{P}_{Z_k \mid Z_{k-1} = x}}{\mathrm{d} \mathbf{P}}(y)$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三回 - のへぐ

and invariant measure Q defined by its density $dQ/dP = \mu$.

PROPOSITION. For any $x, y \in \text{supp}(P)$,

$$\left\langle \frac{\mathrm{d}\mathbf{P}_{Z_m \mid Z_0 = x}}{\mathrm{d}\mathbf{Q}}, \frac{\mathrm{d}\mathbf{P}_{Z_m \mid Z_0 = y}}{\mathrm{d}\mathbf{Q}} \right\rangle_{L^2_{\mathbf{Q}}} = \mu(x)^{-1/2} \bar{K}_{2m}(x, y) \mu(y)^{-1/2}$$

Introduce

$$K_m(x,y) = \bar{K}_{2m}(x,x)^{-1/2} \bar{K}_{2m}(x,y) \bar{K}_{2m}(y,y)^{-1/2}$$

In the new representation points are concentrated around ON vectors

IDEAL ALGORITHM IN TERMS OF KERNELS

Let
$$K(x, y) = \exp\left(-\beta ||x - y||^2\right)$$

1. Form (Laplacian operator)

$$\bar{K}(x,y) = \mu(x)^{-1/2} K(x,y) \mu(y)^{-1/2}$$

2. Construct

$$\bar{K}_{2m}(x,y) = \int \bar{K}(y,z_1)\bar{K}(z_1,z_2)\dots\bar{K}(z_{2m-1},x)\,\mathrm{d}\mathsf{P}^{\otimes(2m-1)}(z_1,\dots,z_{2m-1})$$

3. Renormalize to obtain

$$K_m(x,y) = \bar{K}_{2m}(x,x)^{-1/2} \bar{K}_{2m}(x,y) \bar{K}_{2m}(y,y)^{-1/2}$$

< □ > < 同 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

4. Cluster points according to the new representation defined by the symmetric kernel K_m .

NEXT STEP

Construct an empirical algorithm

by estimating the kernels

$$\bar{K}(x,y) = \mu(x)^{-1/2} K(x,y) \mu(y)^{-1/2}$$

and

$$\bar{K}_{2m}(x,y) = \int \bar{K}(y,z_1)\bar{K}(z_1,z_2)\dots\bar{K}(z_{2m-1},x)\,\mathrm{d}\mathbf{P}^{\otimes(2m-1)}(z_1,\dots,z_{2m-1})$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Provide convergence results

TOWARD AN EMPIRICAL ALGORITHM: GRAM OPERATORS

Idea: Link the previous kernels (\overline{K} and \overline{K}_{2m}) with Gram operators

Note: the kernel \overline{K} defines

▶ a RHKS \mathcal{H} where

$$\bar{K}(x,y) = \langle \phi_{\bar{K}}(x), \phi_{\bar{K}}(y) \rangle_{\mathcal{H}}$$

► a Gram operator

$$\mathcal{G}_{\bar{K}}\phi_{\bar{K}}(x) = \int \langle \phi_{\bar{K}}(x), \phi_{\bar{K}}(z) \rangle_{\mathcal{H}} \phi_{\bar{K}}(z) \, \mathrm{d}\mathbf{P}(z)$$
$$= \int \bar{K}(x, z) \, \phi_{\bar{K}}(z) \, \mathrm{d}\mathbf{P}(z)$$

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ ▲ □ ● ● ● ●

AN ESTIMATOR OF \overline{K}

Goal: Estimate $\bar{K}(x,y) = \mu(x)^{-1/2} K(x,y) \mu(y)^{-1/2}$ where $\mu(x) = \int K(x,z) \, d\mathbf{P}(z)$

Note: The kernel $A(x, y) = K(x, y)^{1/2} = \exp\left(-\frac{\beta}{2}||x - y||^2\right)$ defines

- a RKHS \mathcal{H}_A where $A(x, y) = \langle \phi_A(x), \phi_A(y) \rangle_{\mathcal{H}_A}$
- a Gram operator $\mathcal{G}_A v = \int \langle v, \phi_A(z) \rangle_{\mathcal{H}_A} \phi_A(z) d\mathbf{P}(z)$

so that

$$\mu(x) = \int \langle \phi_A(x), \phi_A(z) \rangle_{\mathcal{H}_A}^2 \, \mathrm{d}\mathbf{P}(z) = \langle \mathcal{G}_A \phi_A(x), \phi_A(x) \rangle_{\mathcal{H}_A}$$

AN ESTIMATOR OF \overline{K}

Given any estimator of \mathcal{G}_A , we can estimate

$$\mu(x) = \langle \mathcal{G}_A \phi_A(x), \phi_A(x) \rangle_{\mathcal{H}_A} \simeq \hat{\mu}(x)$$

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ ▲ □ ● ● ● ●

and thus we estimate $\bar{K}(x,y) = \mu(x)^{-1/2}K(x,y)\mu(y)^{-1/2}$ with $\hat{K}(x,y) = \hat{\mu}(x)^{-1/2}K(x,y)\hat{\mu}(y)^{-1/2}$

AN ESTIMATOR OF \bar{K}_{2m}

PROPOSITION. With the previous notation,

$$\bar{K}_{2m}(x,y) = \langle \mathcal{G}_{\bar{K}}^{2m-1} \phi_{\bar{K}}(x), \phi_{\bar{K}}(y) \rangle_{\mathcal{H}}$$

where $\mathcal{G}_{\bar{K}}\phi_{\bar{K}}(x) = \int \bar{K}(x,z) \phi_{\bar{K}}(z) \, d\mathbf{P}(z)$.

We need to estimate $\mathcal{G}_{\bar{K}}$ that depends on \bar{K} and P. Thus

$$\bar{K}_{2m}(x,y) = \langle \mathcal{G}_{\bar{K}}^{2m-1} \phi_{\bar{K}}(x), \phi_{\bar{K}}(y) \rangle_{\mathcal{H}} \simeq \langle \mathcal{G}_{\hat{K}}^{2m-1} \phi_{\hat{K}}(x), \phi_{\hat{K}}(y) \rangle_{\mathcal{H}}$$

where $\mathcal{G}_{\hat{K}} \phi_{\hat{K}}(x) = \int \hat{K}(x,z) \phi_{\hat{K}}(z) \, d\mathbf{P}(z)$ (still unknown!)

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ● □ ● ● ● ●

AN ESTIMATOR OF \bar{K}_{2m}

Given $\hat{\mathcal{Q}}$ any estimator of $\mathcal{G}_{\hat{K}}$ we obtain

$$\bar{K}_{2m}(x,y) \simeq \langle \mathcal{G}_{\hat{K}}^{2m-1} \phi_{\hat{K}}(x), \phi_{\hat{K}}(y) \rangle_{\mathcal{H}}$$
$$\simeq \langle \hat{\mathcal{Q}}^{2m-1} \phi_{\hat{K}}(x), \phi_{\hat{K}}(y) \rangle_{\mathcal{H}} =: \hat{K}_{2m}(x,y)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

where
$$\phi_{\hat{K}}(x) = \chi(x)\phi_{\bar{K}}(x)$$
 and $\chi(x) = \left(\mu(x)/\hat{\mu}(x)\right)^{1/2}$.

Recall:
$$\hat{K}_{2m}(x, y) = \langle \hat{\mathcal{Q}}^{2m-1} \phi_{\hat{K}}(x), \phi_{\hat{K}}(y) \rangle_{\mathcal{H}}$$

where $\phi_{\hat{K}}(x) = \chi(x)\phi_{\bar{K}}(x)$ and $\chi(x) = \left(\mu(x)/\hat{\mu}(x)\right)^{1/2}$.

PROPOSITION. For any $x, y \in \text{supp}(P)$,

$$\begin{split} |\hat{K}_{2m}(x,y) - \bar{K}_{2m}(x,y)| \\ &\leq \frac{\max\{1, \|\chi\|_{\infty}\}^2}{\mu(x)^{1/2}\mu(y)^{1/2}} \left(\|\hat{\mathcal{Q}}^{2m-1} - \mathcal{G}_{\bar{K}}^{2m-1}\|_{\infty} + 2\|\chi - 1\|_{\infty} \right) \end{split}$$

and

$$\|\hat{\mathcal{Q}}^{2m-1} - \mathcal{G}_{\bar{K}}^{2m-1}\|_{\infty} \le (2m-1)\|\hat{\mathcal{Q}} - \mathcal{G}_{\bar{K}}\|_{\infty} \left(1 + \|\hat{\mathcal{Q}} - \mathcal{G}_{\bar{K}}\|_{\infty}\right)^{2m-2}$$

CHOICE OF m

Notation:

- let $\hat{\lambda}_1 \geq \hat{\lambda}_2 \geq \ldots$ be the eigenvalues of \hat{Q}
- let p the maximal number of classes

The number of iterations m is the solution of

$$\left(\frac{\hat{\lambda}_p}{\hat{\lambda}_1}\right)^m \simeq \frac{1}{100}$$

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ ▲ □ ● ● ● ●

Note: *p* can be overestimated

ESTIMATE OF A GRAM OPERATOR

Recall: We have seen that $|\hat{K}_{2m}(x,y) - \bar{K}_{2m}(x,y)|$ depends on $\chi(x) = (\mu(x)/\hat{\mu}(x))^{1/2}$ $\|\hat{Q} - \mathcal{G}_{\bar{K}}\|_{\infty}$

Last step: Provide some estimate of Gram operators

Notation:

- Let *K* be a symmetric kernel
- let \mathcal{H} be the RKHS defined by *K*

Goal: Estimate

$$\mathcal{G}v = \int \langle v, z \rangle_{\mathcal{H}} \, z \, \mathrm{d}\mathbf{P}(z), \qquad v \in \mathcal{H}$$

< □ > < 同 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

from an i.i.d. sample $X_1, \ldots, X_n \in \mathcal{H} \sim P$

Assume that $\operatorname{tr}(\mathcal{G}) < +\infty$

THE EMPIRICAL ESTIMATOR

The classical empirical estimator is defined by

$$\bar{\mathcal{G}}v = \frac{1}{n}\sum_{i=1}^{n} \langle v, X_i \rangle X_i$$

Let

$$\blacktriangleright R = \max_{i=1,\dots,n} \|X_i\|$$

• $X \in \mathcal{H}$ be a r.v. of law P.

Assume that

$$\kappa = \sup_{\theta} \frac{\mathbb{E}[\langle \theta, X \rangle^4]}{\mathbb{E}[\langle \theta, X \rangle^2]^2} < +\infty$$

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ ▲ □ ● ● ● ●

THEOREM. With probability $\geq 1 - 2\epsilon$, $\|\mathcal{G} - \bar{\mathcal{G}}\|_{\infty} \leq 4 \max \{\|\mathcal{G}\|_{\infty}, \sigma\} \left[B_*(\|\mathcal{G}\|_{\infty}) + \tau_*(\|\mathcal{G}\|_{\infty})\right] + \sigma$

where

$$B_*(\|\mathcal{G}\|_{\infty}) = \sqrt{\frac{2.032(\kappa-1)}{n} \left(\frac{0.73 \operatorname{tr}(\mathcal{G})}{\max\{\|\mathcal{G}\|_{\infty},\sigma\}} + b + \log(\epsilon^{-1})\right)} + \sqrt{\frac{98.5\kappa \operatorname{tr}(\mathcal{G})}{n \max\{\|\mathcal{G}\|_{\infty},\sigma\}}},$$

$$\tau_*(\|\mathcal{G}\|_{\infty}) = \frac{0.86 R^4}{n(\kappa-1) \max\{\|\mathcal{G}\|_{\infty}, \sigma\}^2} \left[\frac{0.73 \operatorname{tr}(\mathcal{G})}{\max\{\|\mathcal{G}\|_{\infty}, \sigma\}} + b + \log(\epsilon^{-1})\right]$$

- コン・4回シュービン・4回シューレー

and $b \simeq \log(\log(n)) \le 4.35$ if $n \le 10^{20}$.

It is possible to use a PAC-Bayesian approach to construct a more robust estimator $\hat{\mathcal{G}}$ such that

THEOREM. With probability $\geq 1 - 2\epsilon$,

$$\|\mathcal{G} - \hat{\mathcal{G}}\|_{\infty} \leq 4 \max \{\|\mathcal{G}\|_{\infty}, \sigma\} B_*(\|\mathcal{G}\|_{\infty}) + \sigma.$$

◆□▶ ◆□▶ ◆目▶ ◆目▶ 目 のへで

Note: In light tail situations, $\overline{\mathcal{G}}$ and $\hat{\mathcal{G}}$ behave in the same way

WORK IN PROGRESS: IMAGE CLASSIFICATION

Test the algorithm in the setting of image classification



Work in progress: choice of β

Recall: we consider the Gaussian kernel

$$K(x, y) = K_{\beta}(x, y) = \exp\left(-\beta ||x - y||^2\right)$$

The choice of β is based on the estimation of the trace of

$$L_{\beta}f(x) = \int K_{\beta}(x,z)f(z) \,\mathrm{d}\mathbf{P}(z)$$

Note: Let $\lambda_1 \geq \lambda_2 \geq \ldots$ be the eigenvalues of L_{β}

$$\sum_{i} \lambda_{i} = \int K_{\beta}(x, x) \, \mathrm{dP}(x) = 1$$
$$\sum_{i} \lambda_{i}^{2} = \int K_{\beta}(x, z)^{2} \, \mathrm{dP}(x) \mathrm{dP}(z) \le 1$$

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ ▲ □ ● ● ● ●

Work in progress: choice of β

Note:

$$F(\beta) = \int K_{\beta}(x,z)^2 \, d\mathbf{P}(x) d\mathbf{P}(z) \quad \begin{cases} \longrightarrow 1 & \text{if } \beta \to 0 \\ \longrightarrow 0 & \text{if } \beta \to \infty \end{cases}$$

< □ > < 同 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Thus $F(\beta)$ controls the spread of the eigenvalues

 \longrightarrow we have to choose β sufficiently large

Goal: Find a way to calibrate β

THANK YOU



◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ● ●