

Thick Triangulations

Jean-Daniel Boissonnat
Geometrica, INRIA

`http://www-sop.inria.fr/geometrica`

Winter School, University of Nice Sophia Antipolis
January 26-30, 2015

Some optimality properties of Delaunay triangulations

Among all possible triangulations of \mathcal{P} , $\text{Del}(\mathcal{P})$

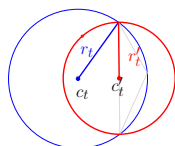
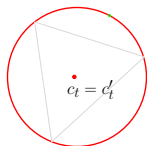
1 (2d) maximizes the smallest angle [Lawson]

2 (2d) Linear interpolation of $\{(p_i, f(p_i))\}$ that minimizes [Rippa]

$$R(T) = \sum_i \int_{T_i} \left(\left(\frac{\partial \phi_i}{\partial x} \right)^2 + \left(\frac{\partial \phi_i}{\partial y} \right)^2 \right) dx dy \quad (\text{Dirichlet energy})$$

$\phi_i =$ linear interpolation of the $f(p_j)$ over triangle $T_i \in T$

3 minimizes the radius of the maximal smallest ball enclosing a simplex) [Rajan]



Some optimality properties of Delaunay triangulations

Among all possible triangulations of \mathcal{P} , $\text{Del}(\mathcal{P})$

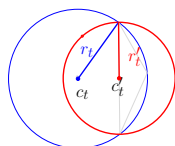
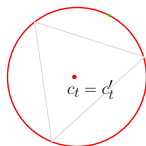
1 (2d) maximizes the smallest angle [Lawson]

2 (2d) Linear interpolation of $\{(p_i, f(p_i))\}$ that minimizes [Rippa]

$$R(T) = \sum_i \int_{T_i} \left(\left(\frac{\partial \phi_i}{\partial x} \right)^2 + \left(\frac{\partial \phi_i}{\partial y} \right)^2 \right) dx dy \quad (\text{Dirichlet energy})$$

$\phi_i =$ linear interpolation of the $f(p_j)$ over triangle $T_i \in T$

3 minimizes the radius of the maximal smallest ball enclosing a simplex) [Rajan]



Some optimality properties of Delaunay triangulations

Among all possible triangulations of \mathcal{P} , $\text{Del}(\mathcal{P})$

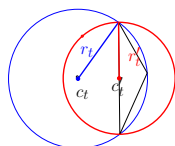
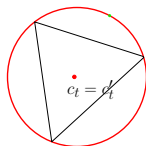
1 (2d) maximizes the smallest angle [Lawson]

2 (2d) Linear interpolation of $\{(p_i, f(p_i))\}$ that minimizes [Rippa]

$$R(T) = \sum_i \int_{T_i} \left(\left(\frac{\partial \phi_i}{\partial x} \right)^2 + \left(\frac{\partial \phi_i}{\partial y} \right)^2 \right) dx dy \quad (\text{Dirichlet energy})$$

$\phi_i =$ linear interpolation of the $f(p_j)$ over triangle $T_i \in T$

3 minimizes the radius of the maximal smallest ball enclosing a simplex) [Rajan]



Optimizing the angular vector ($d = 2$)

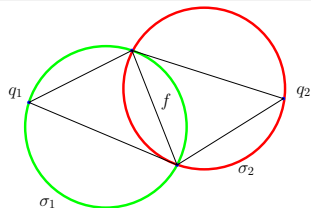
Angular vector of a triangulation $T(\mathcal{P})$

$$\text{ang}(T(\mathcal{P})) = (\alpha_1, \dots, \alpha_{3t}), \quad \alpha_1 \leq \dots \leq \alpha_{3t}$$

Optimality Any triangulation of a given point set \mathcal{P} whose angular vector is maximal (for the lexicographic order) is a Delaunay triangulation of \mathcal{P}

Good for matrix conditioning in FE methods

Local characterization of Delaunay complexes



Pair of regular simplices

$$\sigma_2(q_1) \geq 0 \quad \text{and} \quad \sigma_1(q_2) \geq 0$$

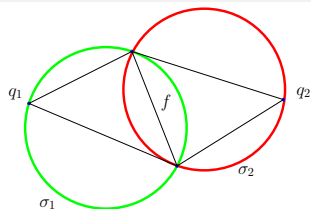
$$\Leftrightarrow \hat{c}_1 \in h_{\sigma_2}^+ \quad \text{and} \quad \hat{c}_2 \in h_{\sigma_1}^+$$

Theorem A triangulation $T(P)$ such that all pairs of simplexes are regular is a Delaunay triangulation $\text{Del}(P)$

Proof The PL function whose graph G is obtained by lifting the triangles is locally convex and has a convex support

$$\Rightarrow G = \text{conv}^-(\hat{Q}) \quad \Rightarrow T(Q) = \text{Del}(Q)$$

Local characterization of Delaunay complexes



Pair of regular simplices

$$\sigma_2(q_1) \geq 0 \quad \text{and} \quad \sigma_1(q_2) \geq 0$$

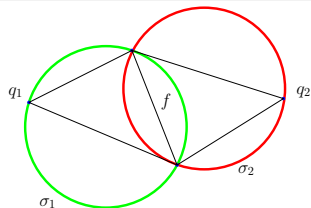
$$\Leftrightarrow \hat{c}_1 \in h_{\sigma_2}^+ \quad \text{and} \quad \hat{c}_2 \in h_{\sigma_1}^+$$

Theorem A triangulation $T(P)$ such that all pairs of simplexes are regular is a Delaunay triangulation $\text{Del}(P)$

Proof The PL function whose graph G is obtained by lifting the triangles is locally convex and has a convex support

$$\Rightarrow G = \text{conv}^-(\hat{Q}) \quad \Rightarrow T(Q) = \text{Del}(Q)$$

Local characterization of Delaunay complexes



Pair of regular simplices

$$\sigma_2(q_1) \geq 0 \quad \text{and} \quad \sigma_1(q_2) \geq 0$$

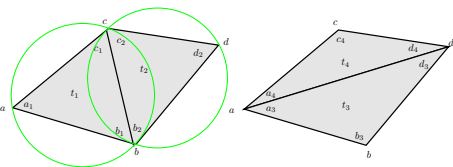
$$\Leftrightarrow \hat{c}_1 \in h_{\sigma_2}^+ \quad \text{and} \quad \hat{c}_2 \in h_{\sigma_1}^+$$

Theorem A triangulation $T(P)$ such that all pairs of simplexes are regular is a Delaunay triangulation $\text{Del}(P)$

Proof The PL function whose graph G is obtained by lifting the triangles is locally convex and has a convex support

$$\Rightarrow G = \text{conv}^-(\hat{Q}) \quad \Rightarrow T(Q) = \text{Del}(Q)$$

Constructive proof using flips



While \exists a non regular pair (t_3, t_4)

/ $t_3 \cup t_4$ is convex */*

replace (t_3, t_4) by (t_1, t_2)

Regularize \Leftrightarrow improve $\text{ang}(T(\mathcal{P}))$

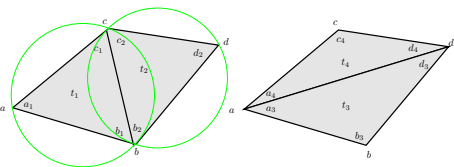
$$\text{ang}(t_1, t_2) \geq \text{ang}(t_3, t_4)$$

$$a_1 = a_3 + a_4, \quad d_2 = d_3 + d_4,$$

$$c_1 \geq d_3, \quad b_1 \geq d_4, \quad b_2 \geq a_4, \quad c_2 \geq a_3$$

- ▶ The algorithm terminates since the number of triangulations of \mathcal{P} is finite and $\text{ang}(T(\mathcal{P}))$ cannot decrease
- ▶ The obtained triangulation is a Delaunay triangulation of \mathcal{P} since all its edges are regular

Constructive proof using flips



While \exists a non regular pair (t_3, t_4)

/* $t_3 \cup t_4$ is convex */

replace (t_3, t_4) by (t_1, t_2)

Regularize \Leftrightarrow improve $\text{ang}(T(\mathcal{P}))$

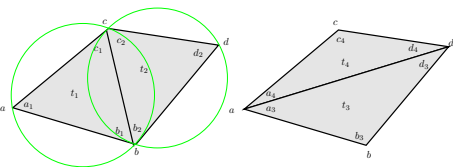
$$\text{ang}(t_1, t_2) \geq \text{ang}(t_3, t_4)$$

$$a_1 = a_3 + a_4, \quad d_2 = d_3 + d_4,$$

$$c_1 \geq d_3, \quad b_1 \geq d_4, \quad b_2 \geq a_4, \quad c_2 \geq a_3$$

- ▶ The algorithm terminates since the number of triangulations of \mathcal{P} is finite and $\text{ang}(T(\mathcal{P}))$ cannot decrease
- ▶ The obtained triangulation is a Delaunay triangulation of \mathcal{P} since all its edges are regular

Constructive proof using flips



While \exists a non regular pair (t_3, t_4)

/ $t_3 \cup t_4$ is convex */*

replace (t_3, t_4) by (t_1, t_2)

Regularize \Leftrightarrow improve $\text{ang}(T(\mathcal{P}))$

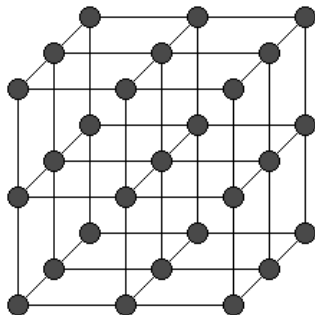
$$\text{ang}(t_1, t_2) \geq \text{ang}(t_3, t_4)$$

$$a_1 = a_3 + a_4, \quad d_2 = d_3 + d_4,$$

$$c_1 \geq d_3, \quad b_1 \geq d_4, \quad b_2 \geq a_4, \quad c_2 \geq a_3$$

- ▶ The algorithm terminates since the number of triangulations of \mathcal{P} is finite and $\text{ang}(T(\mathcal{P}))$ cannot decrease
- ▶ The obtained triangulation is a Delaunay triangulation of \mathcal{P} since all its edges are regular

Flat simplices may exist in higher dimensional DT



- Each square face can be circumscribed by an empty sphere
- This remains true if the grid points are slightly perturbed therefore creating flat tetrahedra

The long quest for thick triangulations

Differential Topology

[Cairns], [Whitehead], [Whitney], [Munkres]

Differential Geometry

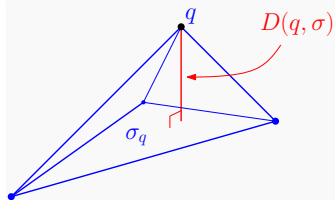
[Cheeger et al.]

Geometric Function Theory

[Peltonen], [Saucan]

Simplex quality

Altitudes



If σ_q , the face opposite q in σ is protected, The *altitude* of q in σ is

$$D(q, \sigma) = d(q, \text{aff}(\sigma_q)),$$

where σ_q is the face opposite q .

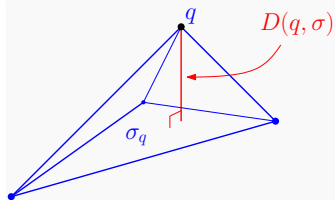
Definition (Thickness [Cairns, Whitney, Whitehead et al.])

The *thickness* of a j -simplex σ with diameter $\Delta(\sigma)$ is

$$\Theta(\sigma) = \begin{cases} 1 & \text{if } j = 0 \\ \min_{p \in \sigma} \frac{D(p, \sigma)}{j\Delta(\sigma)} & \text{otherwise.} \end{cases}$$

Simplex quality

Altitudes



If σ_q , the face opposite q in σ is protected, The *altitude* of q in σ is

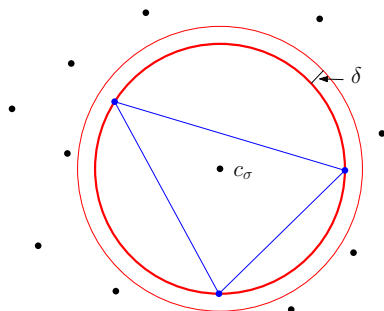
$$D(q, \sigma) = d(q, \text{aff}(\sigma_q)),$$

where σ_q is the face opposite q .

Definition (Thickness [Cairns, Whitney, Whitehead et al.])

The *thickness* of a j -simplex σ with diameter $\Delta(\sigma)$ is

$$\Theta(\sigma) = \begin{cases} 1 & \text{if } j = 0 \\ \min_{p \in \sigma} \frac{D(p, \sigma)}{j \Delta(\sigma)} & \text{otherwise.} \end{cases}$$



δ -protection We say that a Delaunay simplex $\sigma \subset L$ is δ -protected if

$$\|c_\sigma - q\| > \|c_\sigma - p\| + \delta \quad \forall p \in \sigma \text{ and } \forall q \in L \setminus \sigma.$$

Protection implies thickness

Let P be a $(\varepsilon, \bar{\eta})$ -net, i.e.

- $\forall x \in \Omega, \quad d(x, P) \leq \varepsilon$
- $\forall p, q \in P, \quad \|p - q\| \geq \bar{\eta}\varepsilon$

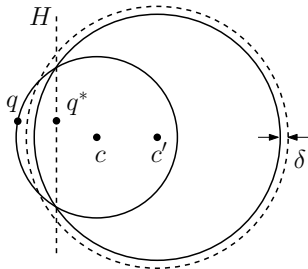
if all d -simplices of $\text{Del}(P)$ are $\bar{\delta}\varepsilon$ -protected, then the thickness of all Delaunay simplices (of all dimensions) is lower bounded

$$\Theta(\sigma) > \Theta_0 = \frac{\bar{\delta}(\bar{\eta} + \bar{\delta})}{8d}$$

(except possibly near the boundary of $\text{conv}(P)$)

Protection implies thickness

Proof : Case 1



σ d -simplex of $\text{Del}(P)$

$$\sigma = q * \tau \quad \sigma' \supset \tau \wedge q \notin \sigma'$$

$$H = \text{aff}(\tau)$$

$$q^* \in B' \Rightarrow \|qq^*\| > \delta$$

Fig in plane $cc'q$

c and c' are on the same side of H

Protection implies thickness

Proof : Case 2

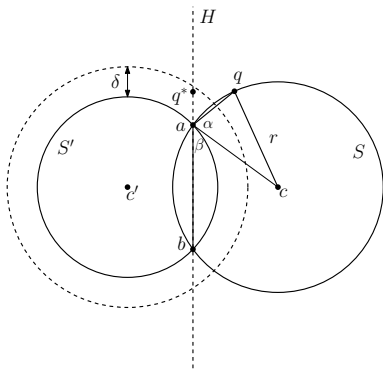


Fig in plane $cc'q$

H separates c and c'

σ d -simplex of $\text{Del}(P)$

$$\sigma = q * \tau \quad \sigma' \supset \tau \wedge q \notin \sigma'$$

$$H = \text{aff}(\tau)$$

$$\gamma = \angle qab, \quad \alpha = \angle qac, \quad \beta = \angle cab$$

$$\text{wlog } \gamma \geq \angle qba$$

$$\gamma = \alpha + \beta \geq \frac{\pi}{2} \quad (\text{otherwise easy})$$

$$\cos \alpha = \frac{\|a-q\|}{2r} \geq \frac{\delta}{2\varepsilon}$$

$$\cos \beta = \frac{\|a-b\|}{2r} \geq \frac{\eta}{2\varepsilon}$$

$$\begin{aligned} \|qq^*\| &= \|aq\| \sin \gamma > \delta \sin \gamma \\ &> \frac{\delta}{4\varepsilon} (\eta + \delta) \end{aligned}$$

$$\Delta(\sigma) \leq 2\varepsilon$$

The Lovász Local Lemma

Motivation

Given: A set of (bad) events A_1, \dots, A_N ,
each happens with $\text{proba}(A_i) \leq p < 1$

Question : what is the probability that none of the events occur?

The case of independent events

$$\text{proba}(\neg A_1 \wedge \dots \wedge \neg A_N) \geq (1 - p)^N > 0$$

What if we allow a limited amount of dependency among the events?

The Lovász Local Lemma

Motivation

Given: A set of (bad) events A_1, \dots, A_N ,
each happens with $\text{proba}(A_i) \leq p < 1$

Question : what is the probability that none of the events occur?

The case of independent events

$$\text{proba}(\neg A_1 \wedge \dots \wedge \neg A_N) \geq (1 - p)^N > 0$$

What if we allow a limited amount of dependency among the events?

The Lovász Local Lemma

Motivation

Given: A set of (bad) events A_1, \dots, A_N ,
each happens with $\text{proba}(A_i) \leq p < 1$

Question : what is the probability that none of the events occur?

The case of independent events

$$\text{proba}(\neg A_1 \wedge \dots \wedge \neg A_N) \geq (1 - p)^N > 0$$

What if we allow a limited amount of dependency among the events?

Under the assumptions

- 1 $\text{proba}(A_i) \leq p < 1$
- 2 A_i depends of $\leq \Gamma$ other events A_j
- 3 $\text{proba}(A_i) \leq \frac{1}{e^{(\Gamma+1)}}$ $e = 2.718\dots$

then

$$\text{proba}(\neg A_1 \wedge \dots \wedge \neg A_N) > 0$$

Moser and Tardos' constructive proof of the LLL [2010]

\mathcal{P} a finite set of mutually independent random variables

\mathcal{A} a finite set of events that are determined by the values of $S \subseteq \mathcal{P}$

Two events are independent iff they share no variable

Algorithm

for all $P \in \mathcal{P}$ **do**

$v_P \leftarrow$ a random evaluation of P ;

while $\exists A \in \mathcal{A} : A$ happens when $(P = v_P, P \in \mathcal{P})$ **do**

pick an arbitrary happening event $A \in \mathcal{A}$;

for all $P \in \text{variables}(A)$ **do**

$v_P \leftarrow$ a new random evaluation of P ;

return $(v_P)_{P \in \mathcal{P}}$;

Moser and Tardos' constructive proof of the LLL [2010]

\mathcal{P} a finite set of mutually independent random variables

\mathcal{A} a finite set of events that are determined by the values of $S \subseteq \mathcal{P}$

Two events are independent iff they share no variable

Algorithm

for all $P \in \mathcal{P}$ **do**

$v_P \leftarrow$ a random evaluation of P ;

while $\exists A \in \mathcal{A} : A$ happens when $(P = v_P, P \in \mathcal{P})$ **do**

pick an arbitrary happening event $A \in \mathcal{A}$;

for all $P \in \text{variables}(A)$ **do**

$v_P \leftarrow$ a new random evaluation of P ;

return $(v_P)_{P \in \mathcal{P}}$;

Moser and Tardos' theorem

if

- 1 $\text{proba}(A_i) \leq p < 1$
- 2 A_i depends of $\leq \Gamma$ other events A_j
- 3 $\text{proba}(A_i) \leq \frac{1}{e^{(\Gamma+1)}}$ $e = 2.718\dots$

then \exists an assignment of values to the variables \mathcal{P} such that no event in \mathcal{A} happens

The randomized algorithm resamples an event $A \in \mathcal{A}$ at most expected times before it finds such an evaluation

$$\frac{1}{\Gamma}$$

The expected total number of resampling steps is at most

$$\frac{N}{\Gamma}$$

- Read the beautiful (rather simple) proof of Moser & Tardos
- Learn about the parallel and the derandomized versions
- Listen to a talk by Aravind Srinivasan on further extensions
<https://video.ias.edu/csdm/2014/0407-AravindSrinivasan>

Protecting Delaunay simplices via perturbation

Picking regions : pick p' in $B(p, \rho)$ Hyp. $\rho \leq \frac{\eta}{4}$ ($\leq \frac{1}{2}$)

Sampling parameters of a perturbed point set

If P is an $(\varepsilon, \bar{\eta})$ -net, P' is an $(\varepsilon', \bar{\eta}')$ -net, where

$$\varepsilon' = \varepsilon(1 + \bar{\rho}) \quad \text{and} \quad \bar{\eta}' = \frac{\bar{\eta} - 2\bar{\rho}}{1 + \bar{\rho}} \geq \frac{\bar{\eta}}{3}$$

Notation : $\bar{x} = \frac{x}{\varepsilon}$

Protecting Delaunay simplices via perturbation

Picking regions : pick p' in $B(p, \rho)$ Hyp. $\rho \leq \frac{\eta}{4}$ ($\leq \frac{1}{2}$)

Sampling parameters of a perturbed point set

If P is an $(\varepsilon, \bar{\eta})$ -net, P' is an $(\varepsilon', \bar{\eta}')$ -net, where

$$\varepsilon' = \varepsilon(1 + \bar{\rho}) \quad \text{and} \quad \bar{\eta}' = \frac{\bar{\eta} - 2\bar{\rho}}{1 + \bar{\rho}} \geq \frac{\bar{\eta}}{3}$$

Notation : $\bar{x} = \frac{x}{\varepsilon}$

The LLL framework

Random variables : P' a set of random points $\{p', p' \in B(p, \rho), p \in P\}$

Event: $\exists \phi' = (\sigma', p')$ (Bad configuration)
 σ' is a d simplex with $R_{\sigma'} \leq \varepsilon + \rho$
 $p' \in Z_\delta(\sigma') \quad Z_\delta(\sigma') = B(c_{\sigma'}, R_{\sigma'} + \delta) \setminus B(c_{\sigma'}, R_{\sigma'})$

Algorithm

Input: P, ρ, δ

while an event $\phi' = (\sigma', p')$ occurs **do**

resample the points of ϕ'

update $\text{Del}(P')$

Output: P' and $\text{Del}(P')$

The LLL framework

Random variables : P' a set of random points $\{p', p' \in B(p, \rho), p \in P\}$

Event: $\exists \phi' = (\sigma', p')$ (Bad configuration)
 σ' is a d simplex with $R_{\sigma'} \leq \varepsilon + \rho$
 $p' \in Z_\delta(\sigma') \quad Z_\delta(\sigma') = B(c_{\sigma'}, R_{\sigma'} + \delta) \setminus B(c_{\sigma'}, R_{\sigma'})$

Algorithm

Input: P, ρ, δ

while an event $\phi' = (\sigma', p')$ occurs **do**

 resample the points of ϕ'

 update $\text{Del}(P')$

Output: P' and $\text{Del}(P')$

Bounding Γ

Lemma : An event is independent of all but at most Γ other bad events where Γ depends on $\bar{\eta}$, $\bar{\rho}$, $\bar{\delta}$ and d

Proof :

- Let $\phi' = (\sigma', p')$ be a bad configuration.

$$\forall p' \in \phi', \quad \|p' - c_{\sigma'}\| \leq R_{\sigma'} + \delta = R = \varepsilon + \rho + \delta = \varepsilon (1 + \bar{\rho} + \bar{\delta})$$

- the number of events that may not be independent from an event (σ', p') is at most the number of subsets of $(d + 1)$ points in $B(c_{\sigma'}, 3R)$.
- Since P' is η' -sparse,

$$\Gamma = \left(\frac{3R + \frac{\eta'}{2}}{\frac{\eta'}{2}} \right)^{d(d+2)}$$

Bounding Γ

Lemma : An event is independent of all but at most Γ other bad events where Γ depends on $\bar{\eta}$, $\bar{\rho}$, $\bar{\delta}$ and d

Proof :

- Let $\phi' = (\sigma', p')$ be a bad configuration.

$$\forall p' \in \phi', \quad \|p' - c_{\sigma'}\| \leq R_{\sigma'} + \delta = R = \varepsilon + \rho + \delta = \varepsilon(1 + \bar{\rho} + \bar{\delta})$$

- the number of events that may not be independent from an event (σ', p') is at most the number of subsets of $(d + 1)$ points in $B(c_{\sigma'}, 3R)$.
- Since P' is η' -sparse,

$$\Gamma = \binom{3R + \frac{\eta'}{2}}{\frac{\eta'}{2}}^{d(d+2)}$$

Bounding Γ

Lemma : An event is independent of all but at most Γ other bad events where Γ depends on $\bar{\eta}$, $\bar{\rho}$, $\bar{\delta}$ and d

Proof :

- Let $\phi' = (\sigma', p')$ be a bad configuration.

$$\forall p' \in \phi', \quad \|p' - c_{\sigma'}\| \leq R_{\sigma'} + \delta = R = \varepsilon + \rho + \delta = \varepsilon(1 + \bar{\rho} + \bar{\delta})$$

- the number of events that may not be independent from an event (σ', p') is at most the number of subsets of $(d + 1)$ points in $B(c_{\sigma'}, 3R)$.
- Since P' is η' -sparse,

$$\Gamma = \binom{3R + \frac{\eta'}{2}}{\frac{\eta'}{2}}^{d(d+2)}$$

Bounding Γ

Lemma : An event is independent of all but at most Γ other bad events where Γ depends on $\bar{\eta}$, $\bar{\rho}$, $\bar{\delta}$ and d

Proof :

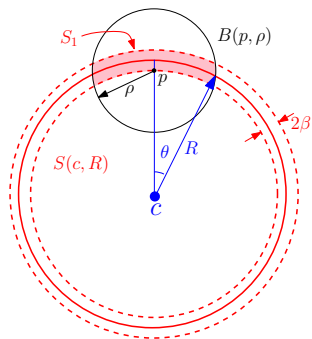
- Let $\phi' = (\sigma', p')$ be a bad configuration.

$$\forall p' \in \phi', \quad \|p' - c_{\sigma'}\| \leq R_{\sigma'} + \delta = R = \varepsilon + \rho + \delta = \varepsilon(1 + \bar{\rho} + \bar{\delta})$$

- the number of events that may not be independent from an event (σ', p') is at most the number of subsets of $(d + 1)$ points in $B(c_{\sigma'}, 3R)$.
- Since P' is η' -sparse,

$$\Gamma = \binom{3R + \frac{\eta'}{2}}{\frac{\eta'}{2}}^{d(d+2)}$$

Bounding $\text{proba}(\sigma, p)$ be a bad configuration



$S(c, R)$ a hypersphere of \mathbb{R}^d

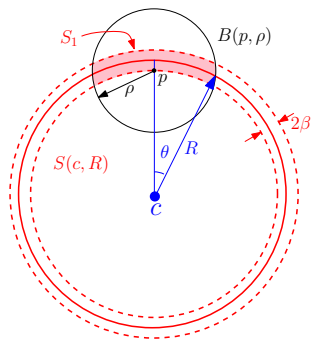
$T_\delta = B(c, R + \delta) \setminus B(c, R)$

B_ρ any d -ball of radius $\rho < R$

$\text{vol}_d(T_\delta \cap B_\rho) \leq U_{d-1} \left(\frac{\pi}{2}\rho\right)^{d-1} \delta,$

$$\text{proba}(p' \in Z_\delta(\sigma')) \leq \varpi = \frac{U_{d-1}}{U_d} \frac{2}{\pi} \frac{\delta}{\rho} < \frac{2^{d+1} \delta}{\pi \rho}$$

Bounding $\text{proba}(\sigma, p)$ be a bad configuration



$S(c, R)$ a hypersphere of \mathbb{R}^d

$T_\delta = B(c, R + \delta) \setminus B(c, R)$

B_ρ any d -ball of radius $\rho < R$

$\text{vol}_d(T_\delta \cap B_\rho) \leq U_{d-1} \left(\frac{\pi}{2}\rho\right)^{d-1} \delta,$

$$\text{proba}(p' \in Z_\delta(\sigma')) \leq \varpi = \frac{U_{d-1}}{U_d} \frac{2}{\pi} \frac{\delta}{\rho} < \frac{2^{d+1} \delta}{\pi \rho}$$

Bound on the number of events

$\Sigma(p')$: number of d -simplices that can possibly make a bad configuration with $p' \in P'$ for some perturbed set P'

$$R = \varepsilon + \rho + \delta$$

$$\sum_{p' \in P'} \Sigma(p') \leq n \times |P' \cap B(p', 2R)| \leq N = n \left(\frac{2R + \frac{\eta'}{2}}{\frac{\eta'}{2}} \right)^{d(d+1)}$$

Main result

Under condition

$$\frac{2^{d+1}e}{\pi} (\Gamma + 1) \delta \leq \rho \leq \frac{\eta}{4}$$

the algorithm terminates.

Guarantees on the output

- ▶ $d_H(P, P') \leq \rho$
- ▶ the d -simplices of $\text{Del}(P')$ are δ -protected
- ▶ and therefore have a positive thickness

Main result

Under condition

$$\frac{2^{d+1}e}{\pi} (\Gamma + 1) \delta \leq \rho \leq \frac{\eta}{4}$$

the algorithm terminates.

Guarantees on the output

- ▶ $d_H(P, P') \leq \rho$
- ▶ the d -simplices of $\text{Del}(P')$ are δ -protected
- ▶ and therefore have a positive thickness

Complexity of the algorithm

- The number of resamplings executed by the algorithm is at most

$$N/\Gamma \leq Cn$$

where C depends on $\bar{\eta}$, $\bar{\rho}$, $\bar{\delta}$ and d

- Each resampling consists in perturbing $O(1)$ points
- Updating the Delaunay triangulation after each resampling takes $O(1)$ time
- The expected complexity is **linear in the number of points**