

Union of Balls and α -Complexes

Jean-Daniel Boissonnat
Geometrica, INRIA

<http://www-sop.inria.fr/geometrica>

Winter School, University of Nice Sophia Antipolis
January 26-30, 2015

Laguerre geometry

Power distance of two balls or of two weighted points.

ball $b_1(p_1, r_1)$, center p_1 radius $r_1 \iff$ weighted point $(p_1, r_1^2) \in \mathbb{R}^d$

ball $b_2(p_2, r_2)$, center p_2 radius $r_2 \iff$ weighted point $(p_2, r_2^2) \in \mathbb{R}^d$

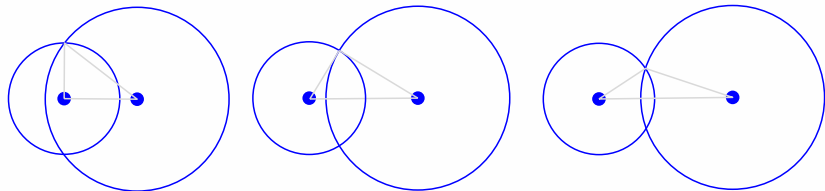
$$\pi(b_1, b_2) = (p_1 - p_2)^2 - r_1^2 - r_2^2$$

Orthogonal balls

b_1, b_2 closer $\iff \pi(b_1, b_2) < 0 \iff (p_1 - p_2)^2 \leq r_1^2 + r_2^2$

b_1, b_2 orthogonal $\iff \pi(b_1, b_2) = 0 \iff (p_1 - p_2)^2 = r_1^2 + r_2^2$

b_1, b_2 further $\iff \pi(b_1, b_2) > 0 \iff (p_1 - p_2)^2 \geq r_1^2 + r_2^2$



Laguerre geometry

Power distance of two balls or of two weighted points.

ball $b_1(p_1, r_1)$, center p_1 radius $r_1 \iff$ weighted point $(p_1, r_1^2) \in \mathbb{R}^d$

ball $b_2(p_2, r_2)$, center p_2 radius $r_2 \iff$ weighted point $(p_2, r_2^2) \in \mathbb{R}^d$

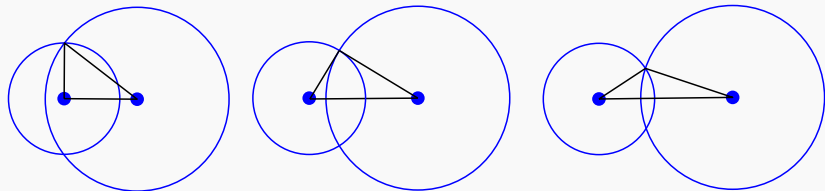
$$\pi(b_1, b_2) = (p_1 - p_2)^2 - r_1^2 - r_2^2$$

Orthogonal balls

b_1, b_2 closer $\iff \pi(b_1, b_2) < 0 \iff (p_1 - p_2)^2 \leq r_1^2 + r_2^2$

b_1, b_2 orthogonal $\iff \pi(b_1, b_2) = 0 \iff (p_1 - p_2)^2 = r_1^2 + r_2^2$

b_1, b_2 further $\iff \pi(b_1, b_2) > 0 \iff (p_1 - p_2)^2 \geq r_1^2 + r_2^2$



Power distance of a point wrt a ball

If b_1 is reduced to a point p : $\pi(p, b_2) = (p - p_2)^2 - r_2^2$

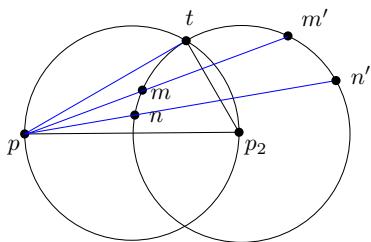
Normalized equation of bounding sphere :

$$p \in \partial b_2 \iff \pi(p, b_2) = 0$$

$$p \in \text{int}b_2 \iff \pi(p, b) < 0$$

$$p \in \partial b_2 \iff \pi(p, b) = 0$$

$$p \notin b_2 \iff \pi(p, b) > 0$$



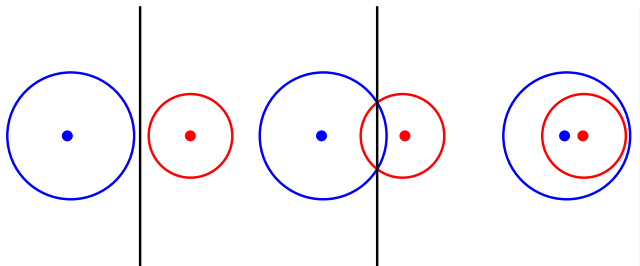
Tangents and secants through p

$$\pi(p, b) = pt^2 = \overline{pm} \cdot \overline{pm'} = \overline{pn} \cdot \overline{pn'}$$

Radical Hyperplane

The locus of point $\in \mathbb{R}^d$ with same power distance to balls $b_1(p_1, r_1)$ and $b_2(p_2, r_2)$ is a hyperplane of \mathbb{R}^d

$$\begin{aligned}\pi(x, b_1) = \pi(x, b_2) &\iff (x - p_1)^2 - r_1^2 = (x - p_2)^2 - r_2^2 \\ &\iff -2p_1x + p_1^2 - r_1^2 = -2p_2x + p_2^2 - r_2^2 \\ &\iff 2(p_2 - p_1)x + (p_1^2 - r_1^2) - (p_2^2 - r_2^2) = 0\end{aligned}$$

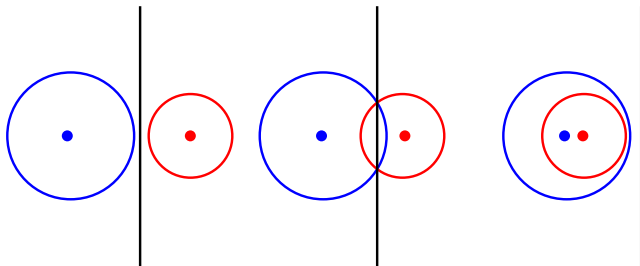


A point in h_{12} is the center of a ball orthogonal to b_1 and b_2

Radical Hyperplane

The locus of point $\in \mathbb{R}^d$ with same power distance to balls $b_1(p_1, r_1)$ and $b_2(p_2, r_2)$ is a hyperplane of \mathbb{R}^d

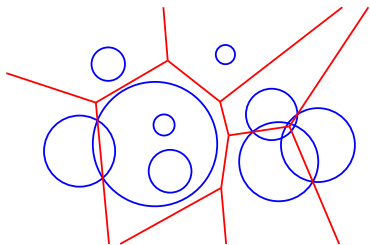
$$\begin{aligned}\pi(x, b_1) = \pi(x, b_2) &\iff (x - p_1)^2 - r_1^2 = (x - p_2)^2 - r_2^2 \\ &\iff -2p_1x + p_1^2 - r_1^2 = -2p_2x + p_2^2 - r_2^2 \\ &\iff 2(p_2 - p_1)x + (p_1^2 - r_1^2) - (p_2^2 - r_2^2) = 0\end{aligned}$$



A point in h_{12} is the center of a ball orthogonal to b_1 and b_2

Power Diagrams

also named Laguerre diagrams or weighted Voronoi diagrams



Sites : n balls $B = \{b_i(p_i, r_i), i = 1, \dots, n\}$

Power distance: $\pi(x, b_i) = (x - p_i)^2 - r_i^2$

Power Diagram: $\text{Vor}(B)$

One cell $V(b_i)$ for each site

$V(b_i) = \{x : \pi(x, b_i) \leq \pi(x, b_j), \forall j \neq i\}$

- Each cell is a polytope
- $V(b_i)$ may be empty
- p_i may not belong to $V(b_i)$

Weighted Delaunay triangulations

$B = \{b_i(p_i, r_i)\}$ a set of balls

$\text{Del}(B) = \text{nerve of Vor}(B)$:

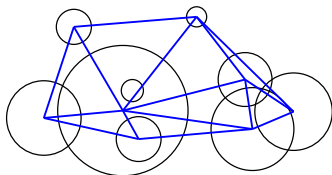
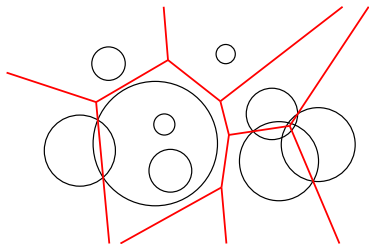
$B_\tau = \{b_i(p_i, r_i), i = 0, \dots, k\} \subset B$

$B_\tau \in \text{Del}(B) \iff \bigcap_{b_i \in B_\tau} V(b_i) \neq \emptyset$

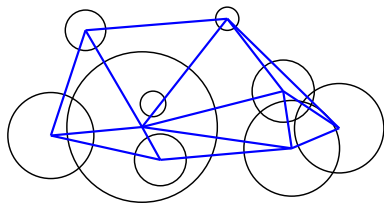
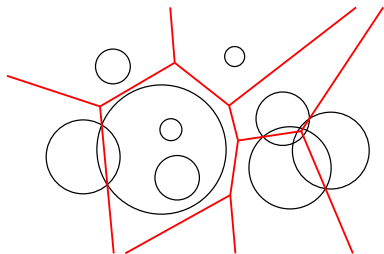
To be proved (next slides):

under a **general position** condition on B ,

$B_\tau \longrightarrow \tau = \text{conv}(\{p_i, i = 0 \dots k\})$
embeds $\text{Del}(B)$ as a triangulation in \mathbb{R}^d ,
called the **weighted Delaunay triangulation**



Characteristic property of weighted Delaunay complexes



$$\begin{aligned}\tau \in \text{Del}(B) &\iff \bigcap_{b_i \in B_\tau} V(b_i) \neq \emptyset \\ &\iff \exists x \in \mathbb{R}^d \text{ s.t. } \forall b_i, b_j \in B_\tau, b_l \in B \setminus B_\tau \\ &\quad \pi(x, b_i) = \pi(x, b_j) < \pi(x, b_l) \\ &\iff \exists \text{ball } b(x, \omega) \text{ s.t. } \forall b_i \in B_\tau, b_l \in B \setminus B_\tau \\ &\quad 0 = \pi(b, b_i) < \pi(b, b_l)\end{aligned}$$

The space of spheres

$b(p, r)$ ball of \mathbb{R}^d

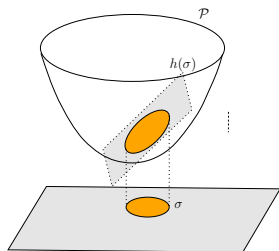
→ point $\phi(b) \in \mathbb{R}^{d+1}$

$$\phi(b) = (p, s = p^2 - r^2)$$

→ polar hyperplane $h_b = \phi(b)^* \in \mathbb{R}^{d+1}$

$$\mathcal{P} = \{\hat{x} \in \mathbb{R}^{d+1} : x_{d+1} = x^2\}$$

$$h_b = \{\hat{x} \in \mathbb{R}^{d+1} : x_{d+1} = 2p \cdot x - s\}$$



- Balls with null radius are mapped onto \mathcal{P}

h_p is tangent to \mathcal{P} at $\phi(p)$.

- The vertical projection of $h_b \cap \mathcal{P}$ onto $x_{d+1} = 0$ is ∂b

The space of spheres

$b(p, r)$ ball of \mathbb{R}^d

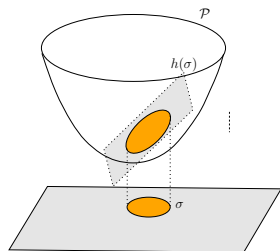
→ point $\phi(b) \in \mathbb{R}^{d+1}$

$$\phi(b) = (p, s = p^2 - r^2)$$

→ polar hyperplane $h_b = \phi(b)^* \in \mathbb{R}^{d+1}$

$$\mathcal{P} = \{\hat{x} \in \mathbb{R}^{d+1} : x_{d+1} = x^2\}$$

$$h_b = \{\hat{x} \in \mathbb{R}^{d+1} : x_{d+1} = 2p \cdot x - s\}$$



- Balls with null radius are mapped onto \mathcal{P}

h_p is tangent to \mathcal{P} at $\phi(p)$.

- The vertical projection of $h_b \cap \mathcal{P}$ onto $x_{d+1} = 0$ is ∂b

The space of spheres

$b(p, r)$ ball of \mathbb{R}^d

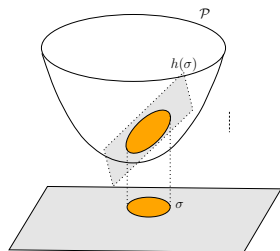
→ point $\phi(b) \in \mathbb{R}^{d+1}$

$$\phi(b) = (p, s = p^2 - r^2)$$

→ polar hyperplane $h_b = \phi(b)^* \in \mathbb{R}^{d+1}$

$$\mathcal{P} = \{\hat{x} \in \mathbb{R}^{d+1} : x_{d+1} = x^2\}$$

$$h_b = \{\hat{x} \in \mathbb{R}^{d+1} : x_{d+1} = 2p \cdot x - s\}$$



- Balls with null radius are mapped onto \mathcal{P}

h_p is tangent to \mathcal{P} at $\phi(p)$.

- The vertical projection of $h_b \cap \mathcal{P}$ onto $x_{d+1} = 0$ is ∂b

The space of spheres

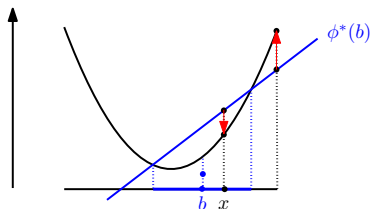
$b(p, r)$ ball of \mathbb{R}^d

→ point $\phi(b) \in \mathbb{R}^{d+1}$

$$\phi(b) = (p, s = p^2 - r^2)$$

→ polar hyperplane $h_b = \phi(b)^* \in \mathbb{R}^{d+1}$

$$h_b = \{\hat{x} \in \mathbb{R}^{d+1} : x_{d+1} = 2p \cdot x - s\}$$



- The vertical distance between $\hat{x} = (x, x^2)$ and h_b is equal to

$$x^2 - 2p \cdot x + s = \pi(x, b)$$

- The faces of the power diagram of B are the vertical projections onto $x_{d+1} = 0$ of the faces of the polytope $\mathcal{V}(B) = \bigcap_i h_b^+$ of \mathbb{R}^{d+1}

The space of spheres

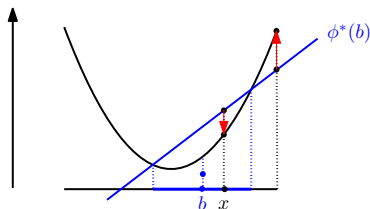
$b(p, r)$ ball of \mathbb{R}^d

→ point $\phi(b) \in \mathbb{R}^{d+1}$

$$\phi(b) = (p, s = p^2 - r^2)$$

→ polar hyperplane $h_b = \phi(b)^* \in \mathbb{R}^{d+1}$

$$h_b = \{\hat{x} \in \mathbb{R}^{d+1} : x_{d+1} = 2p \cdot x - s\}$$

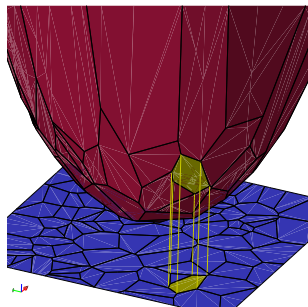


- The vertical distance between $\hat{x} = (x, x^2)$ and h_b is equal to

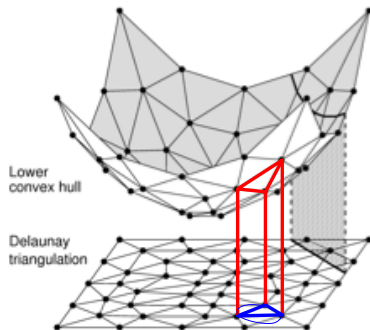
$$x^2 - 2p \cdot x + s = \pi(x, b)$$

- The faces of the power diagram of B are the vertical projections onto $x_{d+1} = 0$ of the faces of the polytope $\mathcal{V}(B) = \bigcap_i h_b^+$ of \mathbb{R}^{d+1}

Power diagrams, weighted Delaunay triangulations and polytopes



$$\mathcal{V}(B) = \cap_i \phi(b_i)^{*+}$$



$$\mathcal{D}(B) = \text{conv}^-(\hat{P})$$

Proof of the theorem

$$B_\tau \subset B, |B_\tau| = d + 1, \tau = \text{conv}(\{p_i, b_i(p_i, r_i) \in B_\tau\}), \\ \phi(\tau) = \text{conv}(\{\phi(b_i), b_i \in B_\tau\})$$

$$\exists b(p, r) \text{ s.t. } h_b = \phi(b)^* = \text{aff}(\{\phi(b_i), b_i \in B_\tau\})$$

$$\begin{aligned} \phi(\tau) \in \mathcal{D}(B) &= \text{conv}^-(\{\phi(b_i)\}) \\ &\iff \forall b_i \in B_\tau, \phi(b_i) \in h_b \quad \forall b_j \notin B_\tau, \phi(b_j) \in h_b^{*+} \\ &\iff \forall b_i \in B_\tau, \pi(b, b_i) = 0 \quad \forall b_j \notin B_\tau, \pi(b, b_j) > 0 \\ &\iff p \in \bigcap_{b_i \in B_\tau} V(b_i) \\ &\iff \tau \in \text{Del}(B) \end{aligned}$$

Delaunay's theorem extended

$B = \{b_1, b_2 \dots b_n\}$ is said to be in general position wrt spheres if

$\nexists x \in \mathbb{R}^d$ with equal power to $d + 2$ balls of B

$P = \{p_1, \dots, p_n\}$: set of centers of the balls of B

Theorem

If B is in general position wrt spheres, the simplicial map

$$f : \text{vert}(\text{Del}(B)) \rightarrow P$$

provides a realization of $\text{Del}(B)$

$\text{Del}(B)$ is a triangulation of $P' \subseteq P$ called the **Delaunay triangulation of B**

Delaunay's theorem extended

$B = \{b_1, b_2 \dots b_n\}$ is said to be in general position wrt spheres if

$\nexists x \in \mathbb{R}^d$ with equal power to $d + 2$ balls of B

$P = \{p_1, \dots, p_n\}$: set of centers of the balls of B

Theorem

If B is in general position wrt spheres, the simplicial map

$$f : \text{vert}(\text{Del}(B)) \rightarrow P$$

provides a realization of $\text{Del}(B)$

$\text{Del}(B)$ is a triangulation of $P' \subseteq P$ called the **Delaunay triangulation of B**

Power diagrams, Delaunay triangulations and polytopes

If B is a set of balls in general position wrt spheres :

$$\mathcal{V}(B) = h_{b_1}^+ \cap \dots \cap h_{b_n}^+ \xrightarrow{\text{duality}} \mathcal{D}(B) = \text{conv}^-(\{\phi(b_1), \dots, \phi(b_n)\})$$

↑

↓

Voronoi Diagram of B

$\xrightarrow{\text{nerve}}$

Delaunay Complex of B

Complexity and algorithm for weighted VD and DT

Number of faces = $\Theta\left(n^{\lfloor \frac{d+1}{2} \rfloor}\right)$ (Upper Bound Th.)

Construction can be done in time $\Theta\left(n \log n + n^{\lfloor \frac{d+1}{2} \rfloor}\right)$ (Convex hull)

Main predicate

$$\text{power_test}(b_0, \dots, b_{d+1}) = \text{sign} \begin{vmatrix} 1 & \dots & 1 \\ p_0 & \dots & p_{d+1} \\ p_0^2 - r_0^2 & \dots & p_{d+1}^2 - r_{d+1}^2 \end{vmatrix}$$

Complexity and algorithm for weighted VD and DT

Number of faces = $\Theta\left(n^{\lfloor \frac{d+1}{2} \rfloor}\right)$ (Upper Bound Th.)

Construction can be done in time $\Theta\left(n \log n + n^{\lfloor \frac{d+1}{2} \rfloor}\right)$ (Convex hull)

Main predicate

$$\text{power_test}(b_0, \dots, b_{d+1}) = \text{sign} \begin{vmatrix} 1 & \dots & 1 \\ p_0 & \dots & p_{d+1} \\ p_0^2 - r_0^2 & \dots & p_{d+1}^2 - r_{d+1}^2 \end{vmatrix}$$

Complexity and algorithm for weighted VD and DT

Number of faces = $\Theta\left(n^{\lfloor \frac{d+1}{2} \rfloor}\right)$ (Upper Bound Th.)

Construction can be done in time $\Theta\left(n \log n + n^{\lfloor \frac{d+1}{2} \rfloor}\right)$ (Convex hull)

Main predicate

$$\text{power_test}(b_0, \dots, b_{d+1}) = \text{sign} \begin{vmatrix} 1 & \dots & 1 \\ p_0 & \dots & p_{d+1} \\ p_0^2 - r_0^2 & \dots & p_{d+1}^2 - r_{d+1}^2 \end{vmatrix}$$

Power diagrams are maximization diagrams

Cell of b_i in the power diagram $\text{Vor}(B)$

$$\begin{aligned}V(b_i) &= \{x \in \mathbb{R}^d : \pi(x, b_i) \leq \pi(x, b_j), \forall j \neq i\} \\ &= \{x \in \mathbb{R}^d : 2p_i x - s_i = \max_{j \in [1, \dots, n]} \{2p_j x - s_j\}\}\end{aligned}$$

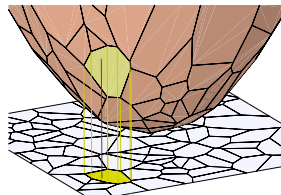
$\text{Vor}(B)$ is the **maximization diagram** of the set of affine functions

$$\{f_i(x) = 2p_i x - s_i, i = 1, \dots, n\}$$

Affine diagrams (regular subdivisions)

Affine diagrams are defined as the maximization diagrams of a finite set of affine functions

They are equivalently defined as the vertical projections of polyhedra intersection of a finite number of upper half-spaces of \mathbb{R}^{d+1}

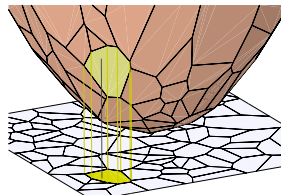


- Voronoi diagrams and power diagrams are affine diagrams.
- Any affine diagram of \mathbb{R}^d is the power diagram of a set of balls.
- Delaunay and weighted Delaunay triangulations are regular triangulations
- Any regular triangulation is a weighted Delaunay triangulation

Affine diagrams (regular subdivisions)

Affine diagrams are defined as the maximization diagrams of a finite set of affine functions

They are equivalently defined as the vertical projections of polyhedra intersection of a finite number of upper half-spaces of \mathbb{R}^{d+1}

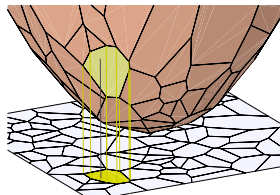


- Voronoi diagrams and power diagrams are affine diagrams.
- Any affine diagram of \mathbb{R}^d is the power diagram of a set of balls.
- Delaunay and weighted Delaunay triangulations are regular triangulations
- Any regular triangulation is a weighted Delaunay triangulation

Affine diagrams (regular subdivisions)

Affine diagrams are defined as the maximization diagrams of a finite set of affine functions

They are equivalently defined as the vertical projections of polyhedra intersection of a finite number of upper half-spaces of \mathbb{R}^{d+1}



- Voronoi diagrams and power diagrams are affine diagrams.
- Any affine diagram of \mathbb{R}^d is the power diagram of a set of balls.
- Delaunay and weighted Delaunay triangulations are regular triangulations
- Any regular triangulation is a weighted Delaunay triangulation

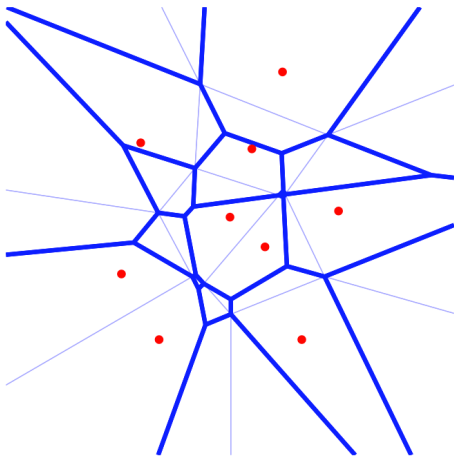
Examples of affine diagrams

- 1 The intersection of a power diagram with an affine subspace (Exercise)
- 2 A Voronoi diagram defined with a **quadratic distance function**

$$\|x - a\|_Q = (x - a)^t Q (x - a) \quad Q = Q^t$$

- 3 k order Voronoi diagrams

k -order Voronoi Diagrams



Let P be a set of sites.

Each cell in the k -order Voronoi diagram $\text{Vor}_k(P)$ is the locus of points in \mathbb{R}^d that have the same subset of P as k -nearest neighbors.

k -order Voronoi diagrams are power diagrams

Let S_1, S_2, \dots denote the subsets of k points of P .

The k -order Voronoi diagram is the minimization diagram of $\delta(x, S_i)$:

$$\begin{aligned}\delta(x, S_i) &= \frac{1}{k} \sum_{p \in S_i} (x - p)^2 \\ &= x^2 - \frac{2}{k} \sum_{p \in S_i} p \cdot x + \frac{1}{k} \sum_{p \in S_i} p^2 \\ &= \pi(b_i, x)\end{aligned}$$

where b_i is the ball

- 1 centered at $c_i = \frac{1}{k} \sum_{p \in S_i} p$
- 2 with $s_i = \pi(o, b_i) = c_i^2 - r_i^2 = \frac{1}{k} \sum_{p \in S_i} p^2$
- 3 and radius $r_i^2 = c_i^2 - \frac{1}{k} \sum_{p \in S_i} p^2$.

Combinatorial complexity of k -order Voronoi diagrams

Theorem

If P be a set of n points in \mathbb{R}^d , the number of vertices and faces in all the Voronoi diagrams $\text{Vor}_j(P)$ of orders $j \leq k$ is:

$$O\left(k^{\lceil \frac{d+1}{2} \rceil} n^{\lfloor \frac{d+1}{2} \rfloor}\right)$$

Proof

uses :

- ▶ bijection between k -sets and cells in k -order Voronoi diagrams
- ▶ the sampling theorem (from randomization theory)

Combinatorial complexity of k -order Voronoi diagrams

Theorem

If P be a set of n points in \mathbb{R}^d , the number of vertices and faces in all the Voronoi diagrams $\text{Vor}_j(P)$ of orders $j \leq k$ is:

$$O\left(k^{\lceil \frac{d+1}{2} \rceil} n^{\lfloor \frac{d+1}{2} \rfloor}\right)$$

Proof

uses :

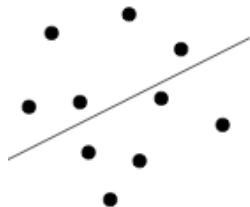
- ▶ bijection between k -sets and cells in k -order Voronoi diagrams
- ▶ the sampling theorem (from randomization theory)

k -sets and k -order Voronoi diagrams

P a set of n points in \mathbb{R}^d

k -sets

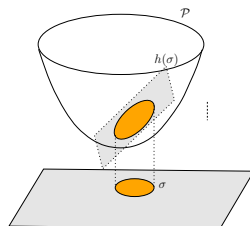
A k -set of P is a subset P' of P with size k that can be separated from $P \setminus P'$ by a hyperplane



k -order Voronoi diagrams

k points of P have a cell in $\text{Vor}_k(P)$ iff there exists a ball that contains those points and only those

\Rightarrow each cell of $\text{Vor}_k(P)$ corresponds to a k -set of $\phi(P)$

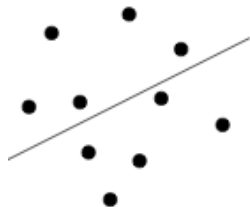


k -sets and k -order Voronoi diagrams

P a set of n points in \mathbb{R}^d

k -sets

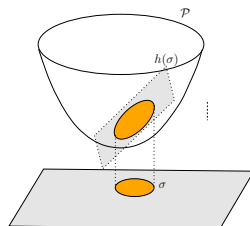
A k -set of P is a subset P' of P with size k that can be separated from $P \setminus P'$ by a hyperplane



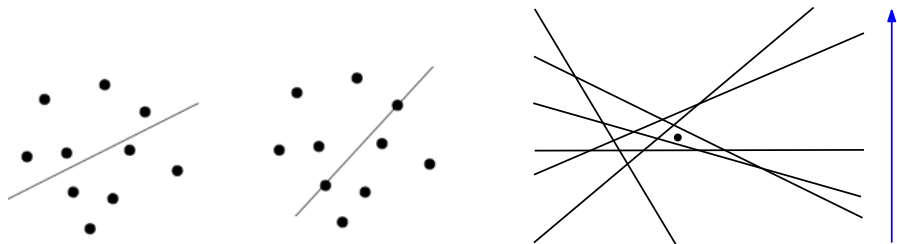
k -order Voronoi diagrams

k points of P have a cell in $\text{Vor}_k(P)$ iff there exists a ball that contains those points and only those

\Rightarrow each cell of $\text{Vor}_k(P)$ corresponds to a k -set of $\phi(P)$

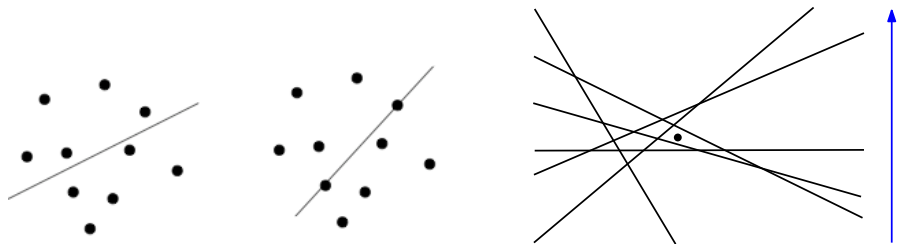


k -sets and k -levels in arrangements of hyperplanes



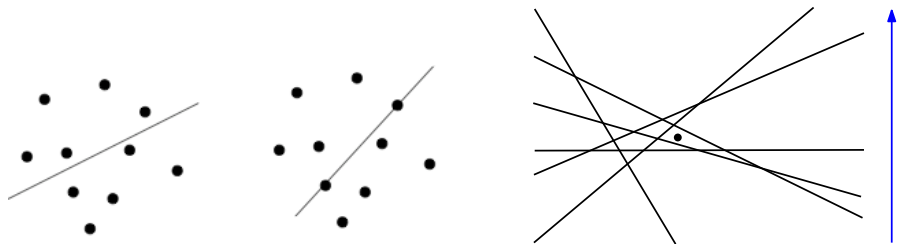
- For a set of points $P \in \mathbb{R}^d$, we consider the arrangement of the **dual** hyperplanes $\mathcal{A}(P^*)$
- h defines a k set $P' \Rightarrow h$ separates P' (below h) from $P \setminus P'$ (above h)
 $\Rightarrow h^*$ is below the k hyperplanes of P'^* and above those of $P^* \setminus P'^*$
- k -sets of P are in 1-1 correspondance with the cells of $\mathcal{A}(P^*)$ of **level** k , i.e. with k hyperplanes of P^* above it.

k -sets and k -levels in arrangements of hyperplanes



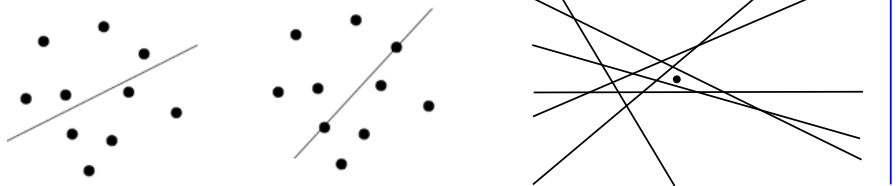
- For a set of points $P \in \mathbb{R}^d$, we consider the arrangement of the **dual** hyperplanes $\mathcal{A}(P^*)$
- h defines a k set $P' \Rightarrow h$ separates P' (below h) from $P \setminus P'$ (above h)
 $\Rightarrow h^*$ is below the k hyperplanes of P'^* and above those of $P^* \setminus P'^*$
- k -sets of P are in 1-1 correspondance with the cells of $\mathcal{A}(P^*)$ of **level** k , i.e. with k hyperplanes of P^* above it.

k -sets and k -levels in arrangements of hyperplanes



- For a set of points $P \in \mathbb{R}^d$, we consider the arrangement of the **dual** hyperplanes $\mathcal{A}(P^*)$
- h defines a k set $P' \Rightarrow h$ separates P' (below h) from $P \setminus P'$ (above h)
 $\Rightarrow h^*$ is below the k hyperplanes of P'^* and above those of $P^* \setminus P'^*$
- k -sets of P are in 1-1 correspondance with the cells of $\mathcal{A}(P^*)$ of **level** k , i.e. with k hyperplanes of P^* above it.

Bounding the number of k -sets



$c_k(P)$: Number of k -sets of P = Number of **cells** of level k in $\mathcal{A}(P^*)$

$$c_{\leq k}(P) = \sum_{l \leq k} c_l(P)$$

$c'_{\leq k}(P)$: Number of **vertices** of $\mathcal{A}(P^*)$ with level at most k

$$c_{\leq k}(n) = \max_{|P|=n} c_{\leq k}(P) \quad c'_{\leq k}(n) = \max_{|P|=n} c'_{\leq k}(P)$$

Hyp. in **general position** : each vertex $\in d$ hyperplanes incident to 2^d cells

Vertices of level k are incident to cells with level $\in [k, k + d]$

Cells of level k have incident vertices with level $\in [k - d, k]$

$$c_{\leq k}(n) = O(c'_{\leq k}(n))$$

Regions, conflicts and the sampling theorem

O a set of n objects.

$\mathcal{F}(O)$ set of configurations defined by O

- each configuration is defined by a subset of b objects
- each configuration is in conflict with a subset of O

$\mathcal{F}_j(O)$ set of configurations in conflict with j objects

$|\mathcal{F}_{\leq k}(O)|$ number of configurations defined by O
in conflict with at most k objects of O

$f_0(r) = \text{Exp}(|\mathcal{F}_0(R)|)$ expected number of configurations
defined and without conflict on a random r -sample of O .

The sampling theorem [Clarkson & Shor 1992]

For $2 \leq k \leq \frac{n}{b+1}$, $|\mathcal{F}_{\leq k}(O)| \leq 4 (b+1)^b k^b f_0(\lfloor \frac{n}{k} \rfloor)$

Regions, conflicts and the sampling theorem

O a set of n objects.

$\mathcal{F}(O)$ set of configurations defined by O

- each configuration is defined by a subset of b objects
- each configuration is in conflict with a subset of O

$\mathcal{F}_j(O)$ set of configurations in conflict with j objects

$|\mathcal{F}_{\leq k}(O)|$ number of configurations defined by O
in conflict with at most k objects of O

$f_0(r) = \text{Exp}(|\mathcal{F}_0(R)|)$ expected number of configurations
defined and without conflict on a random r -sample of O .

The sampling theorem [Clarkson & Shor 1992]

For $2 \leq k \leq \frac{n}{b+1}$, $|\mathcal{F}_{\leq k}(O)| \leq 4 (b+1)^b k^b f_0(\lfloor \frac{n}{k} \rfloor)$

Proof of the sampling theorem

$$f_0(r) = \sum_j |\mathcal{F}_j(O)| \frac{\binom{n-b-j}{r-b}}{\binom{n}{r}} \geq |\mathcal{F}_{\leq k}(O)| \frac{\binom{n-b-k}{r-b}}{\binom{n}{r}}$$

then, we prove that
for $r = \frac{n}{k}$

$$\frac{\binom{n-b-k}{r-b}}{\binom{n}{r}} \geq \frac{1}{4(b+1)^b k^b}$$

$$\frac{\binom{n-b-k}{r-b}}{\binom{n}{r}} = \frac{r!}{(r-b)!} \frac{(n-b)!}{n!} \frac{(n-r)!}{(n-r-k)!} \frac{(n-b-k)!}{(n-b)!}$$

$\underbrace{\hspace{10em}}_{\geq \frac{1}{(b+1)^b k^b}} \quad \underbrace{\hspace{10em}}_{\geq \frac{1}{4}}$

Proof of the sampling theorem

end

$$\begin{aligned}\frac{(n-r)!}{(n-r-k)!} \frac{(n-b-k)!}{(n-b)!} &= \prod_{j=1}^k \frac{n-r-k+j}{n-b-k+j} \geq \left(\frac{n-r-k+1}{n-b-k+1} \right)^k \\ &\geq \left(\frac{n-n/k-k+1}{n-k} \right)^k \\ &\geq (1-1/k)^k \geq 1/4 \text{ pour } (2 \leq k),\end{aligned}$$

$$\begin{aligned}\frac{r!}{(r-b)!} \frac{(n-b)!}{n!} &= \prod_{l=0}^{b-1} \frac{r-l}{n-l} \geq \prod_{l=1}^b \frac{r+1-b}{n} \\ &\geq \prod_{l=1}^b \frac{n/k-b}{n} \\ &\geq 1/k^b (1 - \frac{bk}{n})^b \geq \frac{1}{k^b (b+1)^b} \text{ pour } (k \leq \frac{n}{b+1}).\end{aligned}$$

Bounding the number of k -sets

$c_k(P)$: Number of k -sets of P = Number of cells of level k in $\mathcal{A}(P^*)$.

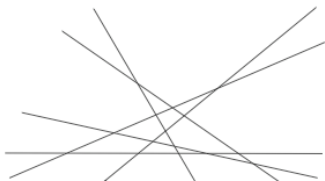
$$c_{\leq k}(P) = \sum_{l \leq k} c_l(P)$$

$c'_{\leq k}(P)$: Number of vertices of $\mathcal{A}(P^*)$ with level at most k .

Objects O : n hyperplanes of \mathbb{R}^d

Configurations : vertices in $\mathcal{A}(O)$, $b = d$

Conflict between v and h : $v \in h^+$



$$\left. \begin{array}{l} \text{Sampling th: } c'_{\leq k}(P) \leq 4(d+1)^d k^d f_0\left(\lfloor \frac{n}{k} \rfloor\right) \\ \text{Upper bound th: } f_0\left(\lfloor \frac{n}{k} \rfloor\right) = O\left(\frac{n \lfloor \frac{d}{2} \rfloor}{k \lfloor \frac{d}{2} \rfloor}\right) \end{array} \right\} \Rightarrow c'_{\leq k}(n) = O\left(k^{\lceil \frac{d}{2} \rceil} n^{\lfloor \frac{d}{2} \rfloor}\right)$$

Combinatorial complexities

- Number of vertices of level $\leq k$ in an arrangement of n hyperplanes in \mathbb{R}^d

Number of cells of level $\leq k$ in an arrangement of n hyperplanes in \mathbb{R}^d

Total number of $j \leq k$ sets for a set of n points in \mathbb{R}^d

$$\left(k^{\lceil \frac{d}{2} \rceil} n^{\lfloor \frac{d}{2} \rfloor} \right)$$

- Total number of faces in the Voronoi diagrams of order $j \leq k$ for a set of n points in \mathbb{R}^d

$$\left(k^{\lceil \frac{d+1}{2} \rceil} n^{\lfloor \frac{d+1}{2} \rfloor} \right)$$

Combinatorial complexities

- Number of vertices of level $\leq k$ in an arrangement of n hyperplanes in \mathbb{R}^d

Number of cells of level $\leq k$ in an arrangement of n hyperplanes in \mathbb{R}^d

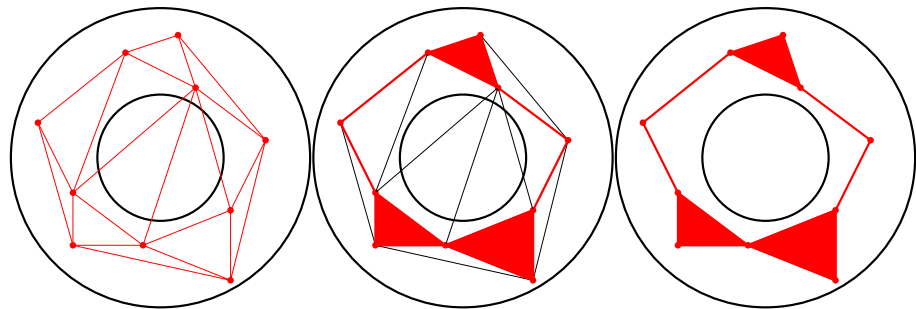
Total number of $j \leq k$ sets for a set of n points in \mathbb{R}^d

$$\left(k^{\lceil \frac{d}{2} \rceil} n^{\lfloor \frac{d}{2} \rfloor} \right)$$

- Total number of faces in the Voronoi diagrams of order $j \leq k$ for a set of n points in \mathbb{R}^d

$$\left(k^{\lceil \frac{d+1}{2} \rceil} n^{\lfloor \frac{d+1}{2} \rfloor} \right)$$

Restriction of Delaunay triangulation



Let $\Omega \subseteq \mathbb{R}^d$ and $P \in \mathbb{R}^d$ a finite set of points.

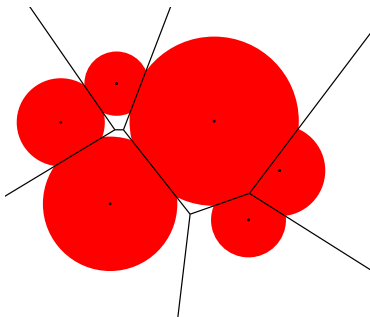
$\text{Vor}(E) \cap \Omega$ is a cover of Ω . Its **nerve** is called the Delaunay triangulation of E restricted to Ω , noted $\text{Del}_{|\Omega}(P)$

If $\text{Vor}(E) \cap \Omega$ is a **good cover** of Ω , $\text{Del}_{|\Omega}(P)$ is **homotopy equivalent** to Ω
(Nerve theorem)

Union of balls

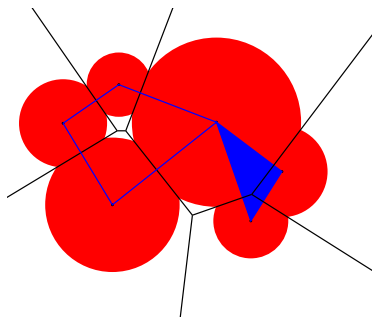
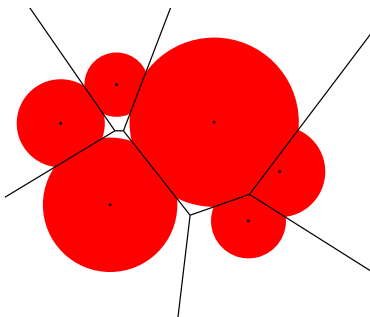
- What is the combinatorial complexity of the boundary of the union U of n balls of \mathbb{R}^d ?
- Compare with the complexity of the arrangement of the bounding hyperspheres
- How can we compute U ?
- What is the image of U in the space of spheres ?

Restriction of $\text{Del}(B)$ to $U = \bigcup_{b \in B} b$



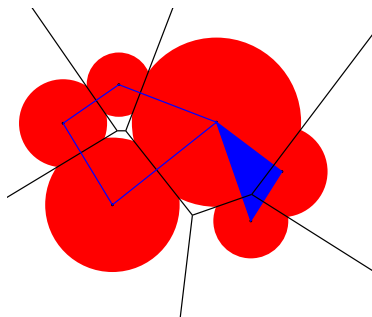
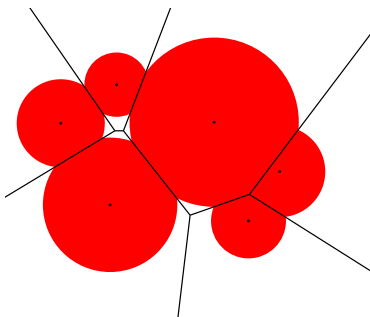
- $U = \bigcup_{b \in B} b \cap V(b)$ and $\partial U \cap \partial b = V(b) \cap \partial b$.
- The nerve of \mathcal{C} is the restriction of $\text{Del}(B)$ to U , i.e. the subcomplex $\text{Del}|_U(B)$ of $\text{Del}(B)$ whose faces have a circumcenter in U
- $\forall b, b \cap V(b)$ is convex and thus contractible
- $\mathcal{C} = \{b \cap V(b), b \in B\}$ is a good cover of U
- The nerve of \mathcal{C} is a deformation retract of U
homotopy equivalent (Nerve theorem)

Restriction of $\text{Del}(B)$ to $U = \bigcup_{b \in B} b$



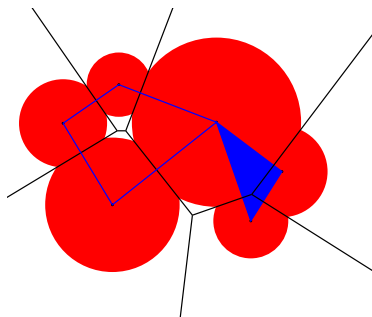
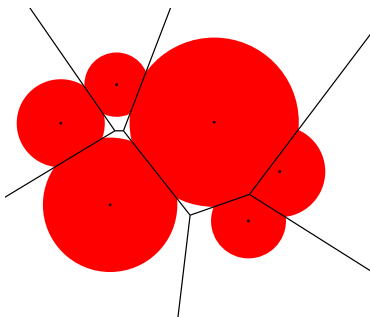
- $U = \bigcup_{b \in B} b \cap V(b)$ and $\partial U \cap \partial b = V(b) \cap \partial b$.
- The nerve of \mathcal{C} is the restriction of $\text{Del}(B)$ to U , i.e. the subcomplex $\text{Del}|_U(B)$ of $\text{Del}(B)$ whose faces have a circumcenter in U
- $\forall b, b \cap V(b)$ is convex and thus contractible
- $\mathcal{C} = \{b \cap V(b), b \in B\}$ is a good cover of U
- The nerve of \mathcal{C} is a deformation retract of U
homotopy equivalent (Nerve theorem)

Restriction of $\text{Del}(B)$ to $U = \bigcup_{b \in B} b$



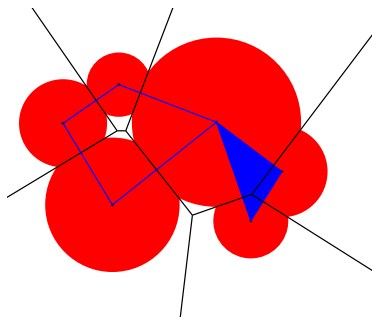
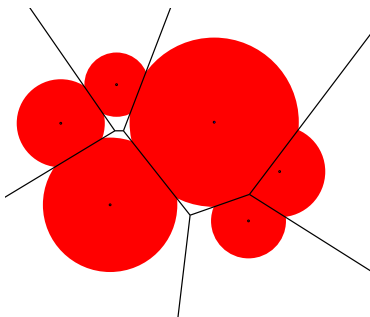
- $U = \bigcup_{b \in B} b \cap V(b)$ and $\partial U \cap \partial b = V(b) \cap \partial b$.
- The nerve of \mathcal{C} is the restriction of $\text{Del}(B)$ to U , i.e. the subcomplex $\text{Del}|_U(B)$ of $\text{Del}(B)$ whose faces have a circumcenter in U
- $\forall b, b \cap V(b)$ is convex and thus contractible
- $\mathcal{C} = \{b \cap V(b), b \in B\}$ is a good cover of U
- The nerve of \mathcal{C} is a deformation retract of U
homotopy equivalent (Nerve theorem)

Restriction of $\text{Del}(B)$ to $U = \bigcup_{b \in B} b$



- $U = \bigcup_{b \in B} b \cap V(b)$ and $\partial U \cap \partial b = V(b) \cap \partial b$.
- The nerve of \mathcal{C} is the restriction of $\text{Del}(B)$ to U , i.e. the subcomplex $\text{Del}|_U(B)$ of $\text{Del}(B)$ whose faces have a circumcenter in U
- $\forall b$, $b \cap V(b)$ is convex and thus contractible
- $\mathcal{C} = \{b \cap V(b), b \in B\}$ is a good cover of U
- The nerve of \mathcal{C} is a deformation retract of U
homotopy equivalent (Nerve theorem)

Restriction of $\text{Del}(B)$ to $U = \bigcup_{b \in B} b$



- $U = \bigcup_{b \in B} b \cap V(b)$ and $\partial U \cap \partial b = V(b) \cap \partial b$.
- The nerve of \mathcal{C} is the restriction of $\text{Del}(B)$ to U , i.e. the subcomplex $\text{Del}|_U(B)$ of $\text{Del}(B)$ whose faces have a circumcenter in U
- $\forall b$, $b \cap V(b)$ is convex and thus contractible
- $\mathcal{C} = \{b \cap V(b), b \in B\}$ is a good cover of U
- The nerve of \mathcal{C} is a **deformation retract** of U
homotopy equivalent (Nerve theorem)

Cech complex versus $\text{Del}_U(B)$

- Both complexes are homotopy equivalent to U
- The size of $\text{Cech}(B)$ is $\Theta(n^d)$
- The size of $\text{Del}_U(B)$ is $\Theta(n^{\lceil \frac{d}{2} \rceil})$

Filtration of a simplicial complex

- 1 A filtration of K is a sequence of subcomplexes of K

$$\emptyset = K^0 \subset K^1 \subset \dots \subset K^m = K$$

such that: $K^{i+1} = K^i \cup \sigma^{i+1}$, where σ^{i+1} is a simplex of K

- 2 Alternatively a filtration of K can be seen as an ordering $\sigma_1, \dots, \sigma_m$ of the simplices of K such that the set K^i of the first i simplices is a subcomplex of K

The ordering should be consistent with the dimension of the simplices

Filtration plays a central role in topological persistence

Filtration of a simplicial complex

- 1 A filtration of K is a sequence of subcomplexes of K

$$\emptyset = K^0 \subset K^1 \subset \dots \subset K^m = K$$

such that: $K^{i+1} = K^i \cup \sigma^{i+1}$, where σ^{i+1} is a simplex of K

- 2 Alternatively a filtration of K can be seen as an ordering $\sigma_1, \dots, \sigma_m$ of the simplices of K such that the set K^i of the first i simplices is a subcomplex of K

The ordering should be consistent with the dimension of the simplices

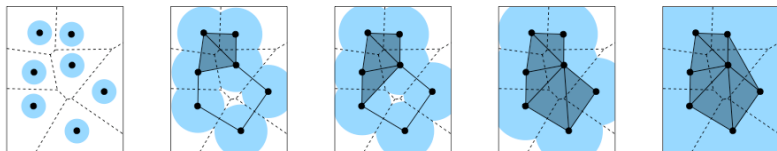
Filtration plays a central role in topological persistence

α -filtration of Delaunay complexes

P a finite set of points of \mathbb{R}^d

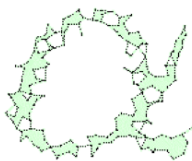
$$U(\alpha) = \bigcup_{p \in P} B(p, \alpha)$$

$$\alpha\text{-complex} = \text{Del}_{|U(\alpha)}(P)$$

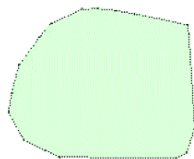
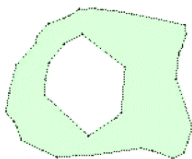
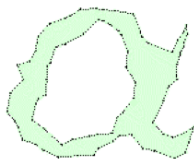


The filtration $\{\text{Del}_{|U(\alpha)}(P), \alpha \in \mathbb{R}^+\}$ is called the α -filtration of $\text{Del}(P)$

Shape reconstruction using α -complexes (2d)

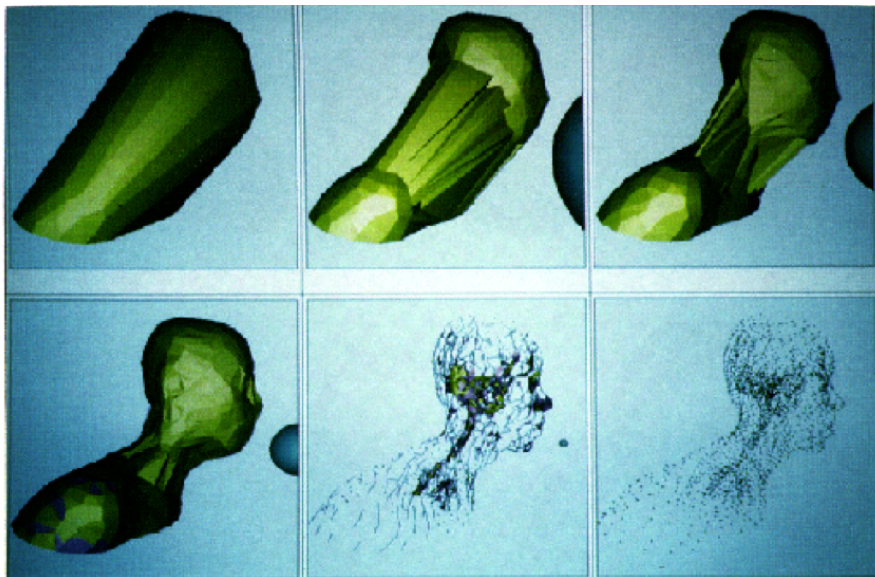


Alpha Controls the desired level of detail.



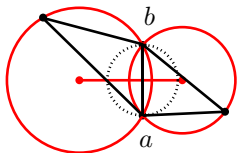
$$\alpha = \infty$$

Shape reconstruction using α -complexes (3d)

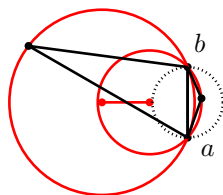


Constructing the α -filtration of $\text{Del}(P)$

$\sigma \in \text{Del}(P)$ is said to be Gabriel iff $\sigma \cap \sigma^* \neq \emptyset$



A Gabriel edge



A non Gabriel edge

Algorithm

for each d -simplex $\sigma \in \text{Del}(P)$: $\alpha_{min}(\sigma) = r(\sigma)$

for $k = d - 1, \dots, 0$,

for each k -face $\sigma \in \text{Del}(P)$

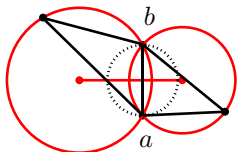
$$\alpha_{med}(\sigma) = \min_{\sigma \in \text{coface}(\sigma)} \alpha_{min}(\sigma)$$

if σ is Gabriel then $\alpha_{min}(\sigma) = r(\sigma)$

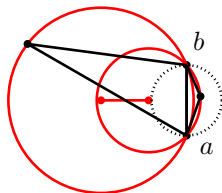
else $\alpha_{min}(\sigma) = \alpha_{med}(\sigma)$

Constructing the α -filtration of $\text{Del}(P)$

$\sigma \in \text{Del}(P)$ is said to be Gabriel iff $\sigma \cap \sigma^* \neq \emptyset$



A Gabriel edge



A non Gabriel edge

Algorithm

for each d -simplex $\sigma \in \text{Del}(P)$: $\alpha_{min}(\sigma) = r(\sigma)$

for $k = d - 1, \dots, 0$,

for each k -face $\sigma \in \text{Del}(P)$

$$\alpha_{med}(\sigma) = \min_{\sigma \in \text{coface}(\sigma)} \alpha_{min}(\sigma)$$

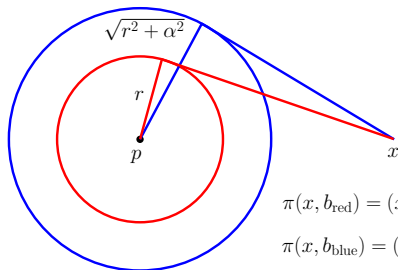
if σ is Gabriel then $\alpha_{min}(\sigma) = r(\sigma)$

else $\alpha_{min}(\sigma) = \alpha_{med}(\sigma)$

α -filtration of weighted Delaunay complexes

$$B = \{b_i = (p_i, r_i)\}_{i=1, \dots, n}$$

$$W(\alpha) = \bigcup_{i=1}^n B \left(p_i, \sqrt{r_i^2 + \alpha^2} \right)$$



$$\pi(x, b_{\text{red}}) = (x - p)^2 - r^2$$

$$\pi(x, b_{\text{blue}}) = (x - p)^2 - r^2 - \alpha^2$$

$$\alpha\text{-complex} = \text{Del}_{W(\alpha)}(B)$$

$$\text{Filtration} : \{ \text{Del}_{W(\alpha)}(B), \alpha \in \mathbb{R}^+ \}$$