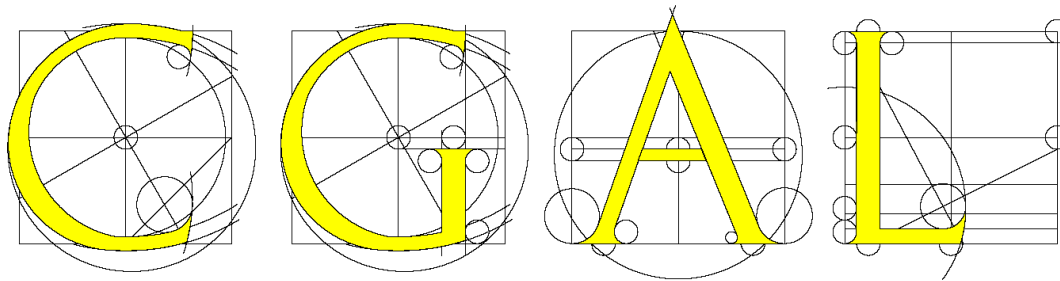


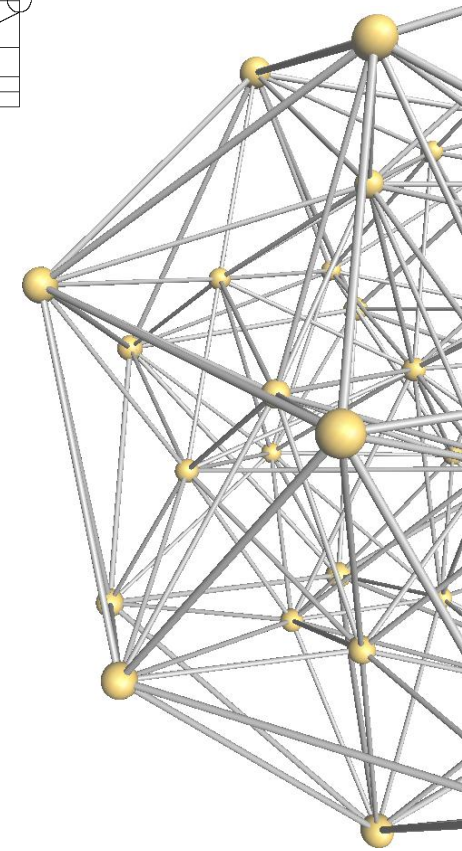
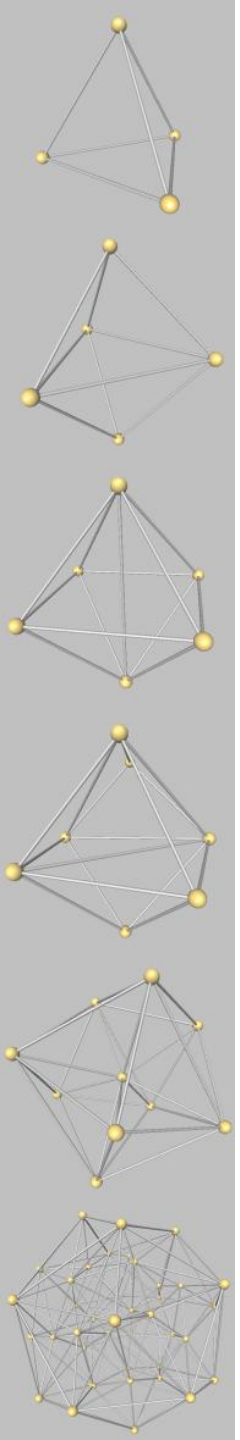
3D Triangulations in



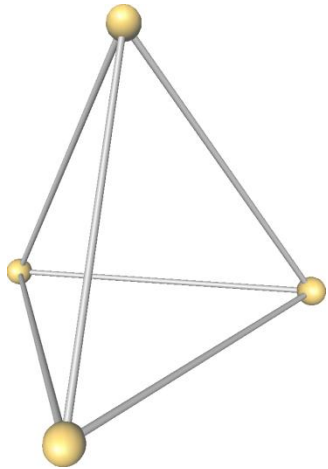
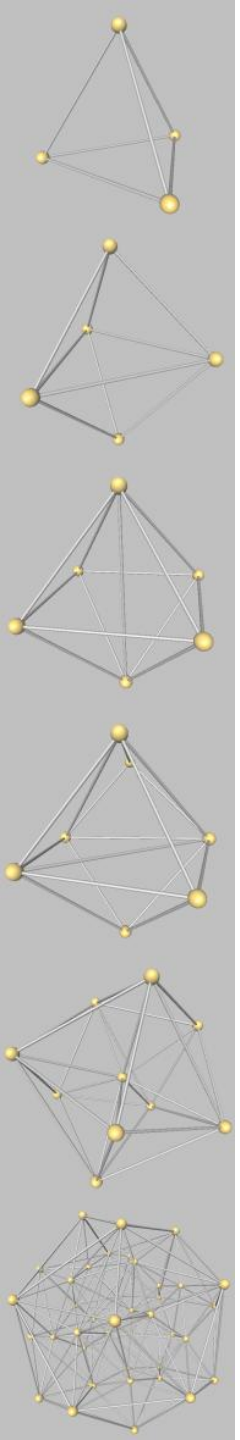
Pierre Alliez



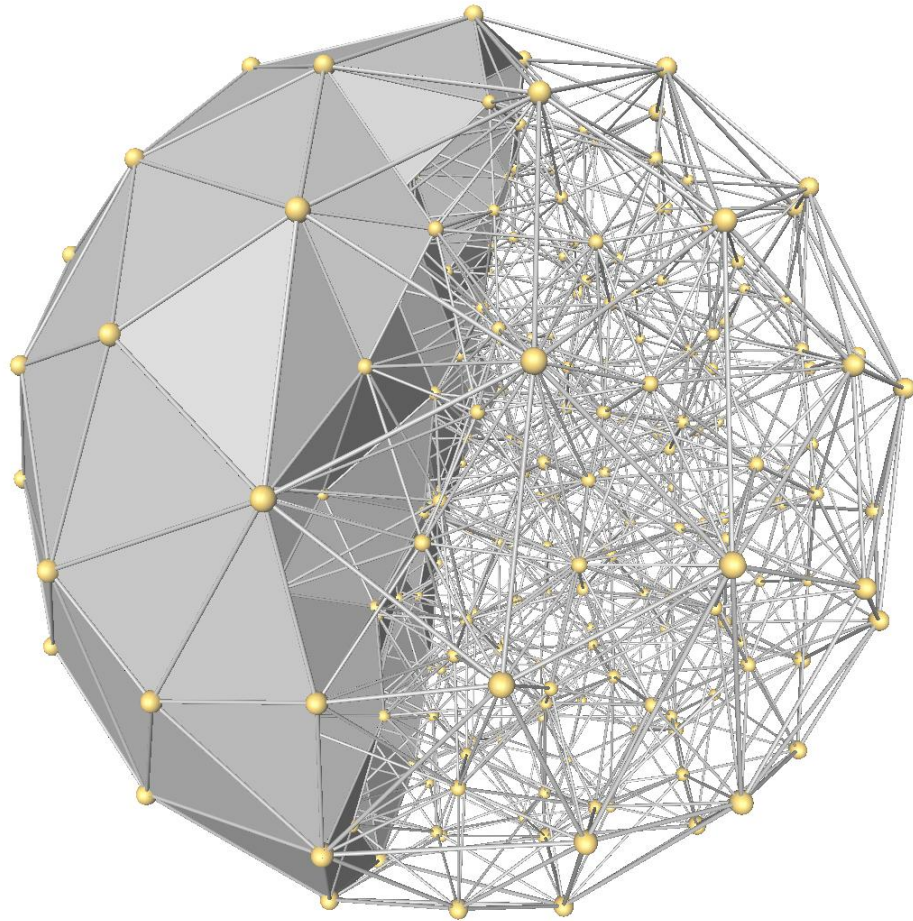
<http://www.cgal.org>



3D Triangulation

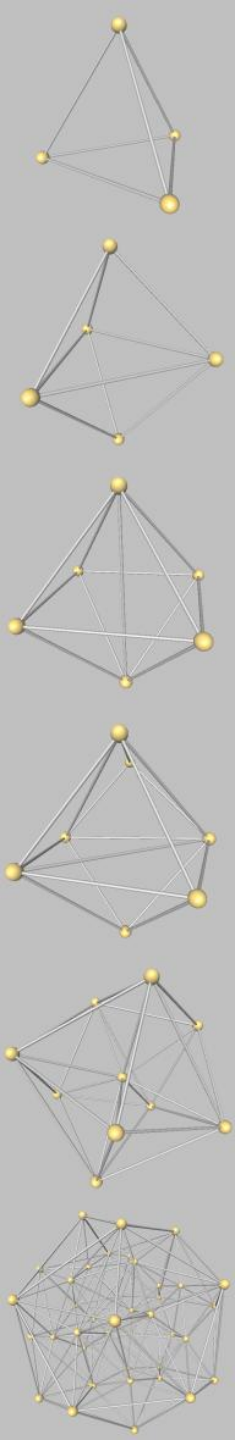


Tetrahedron



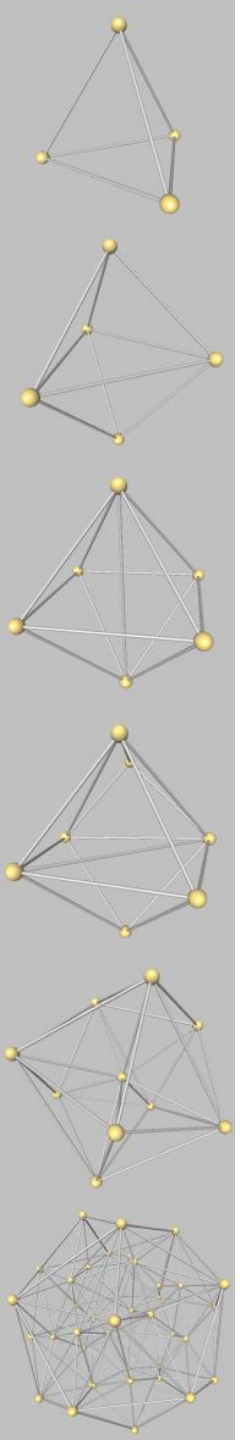
Outline

- Definitions
- Representation
- Types of Triangulations
- Software Design
 - Geometric Traits
 - Customization
- Examples
- Applications



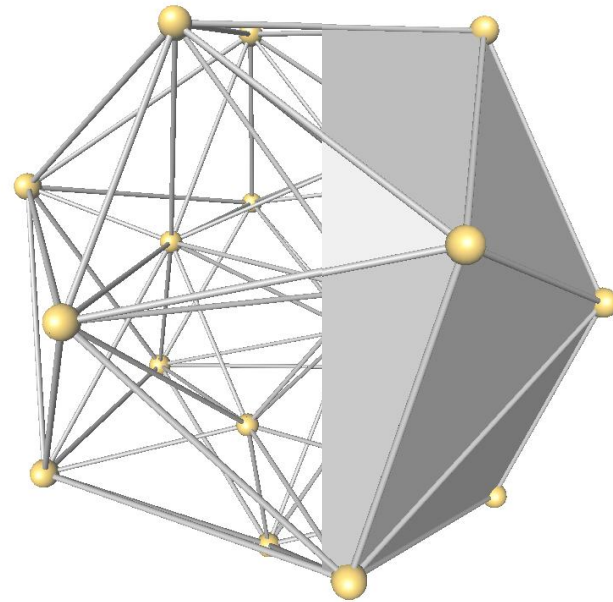
Outline

- **Definitions**
- Representation
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 - Geometric Traits
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- Applications



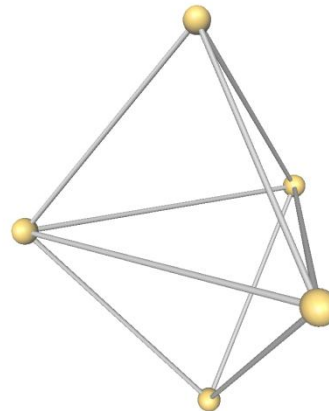
Definitions

3D Triangulation of a point set A:
partition of the convex hull of A into
tetrahedra.



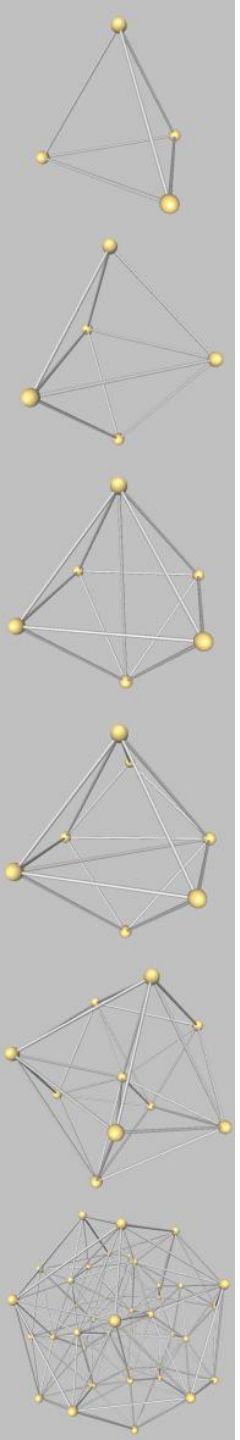
Definitions

- The cells (3-faces) are such that two cells either do not intersect or share a common facet (2-face), edge (1-face) or vertex (0-face).



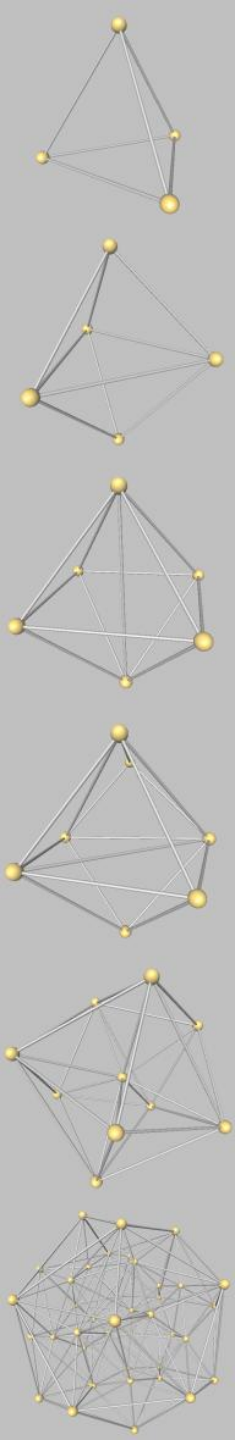
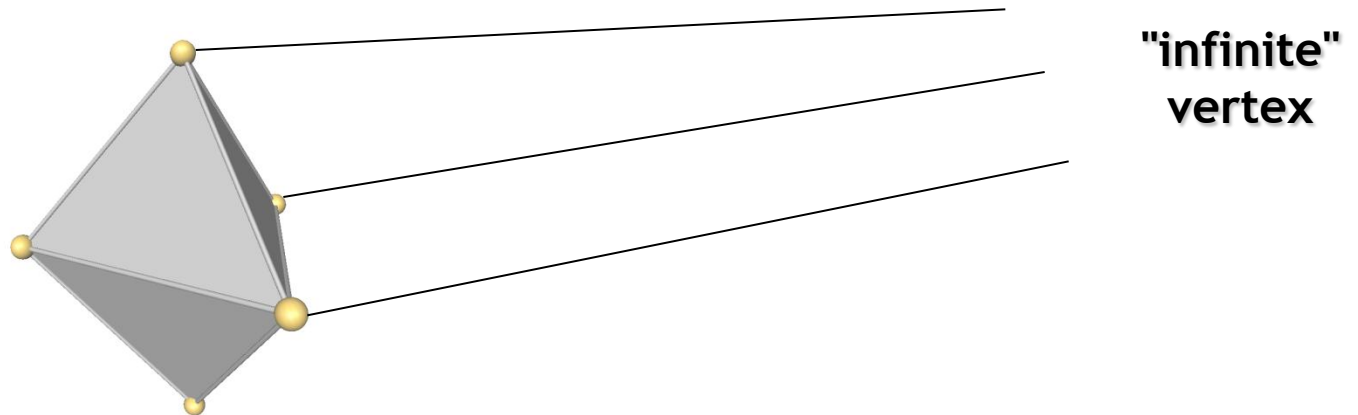
Outline

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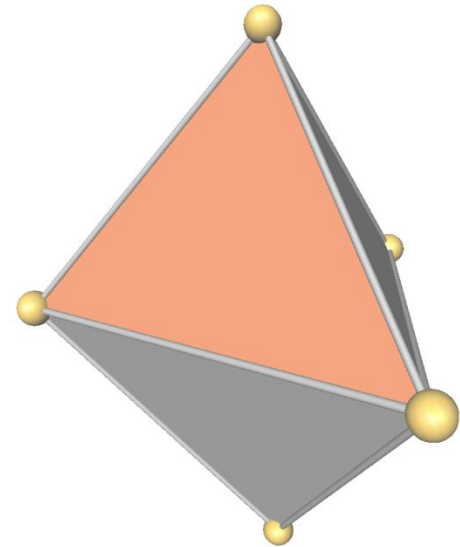
Representation

- **CGAL Triangulation:** partition of \mathbb{R}^3 (add unbounded cell).
- To deal only with Tetrahedra:
 - subdivide unbounded cell into tetrahedra.



Representation

- Dealing only with Tetrahedra:
 - each facet incident to exactly two cells.



3D Triangulation in CGAL

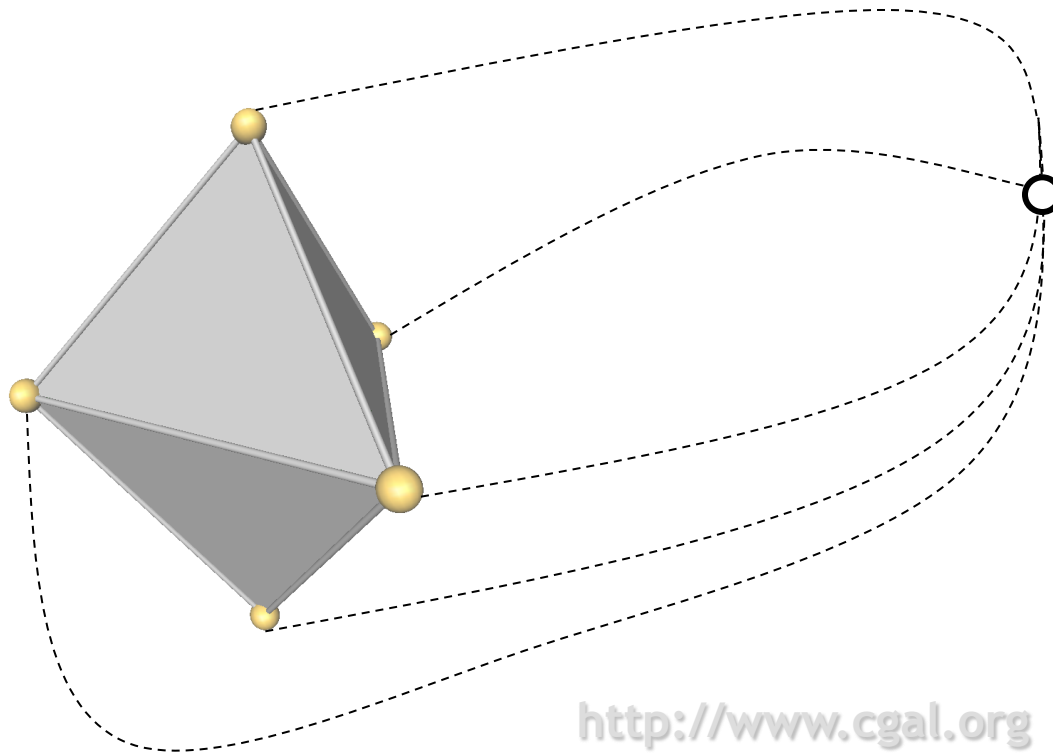
Input point set

Triangulation

- Finite tetrahedra
- One infinite vertex
- Infinite tetrahedra

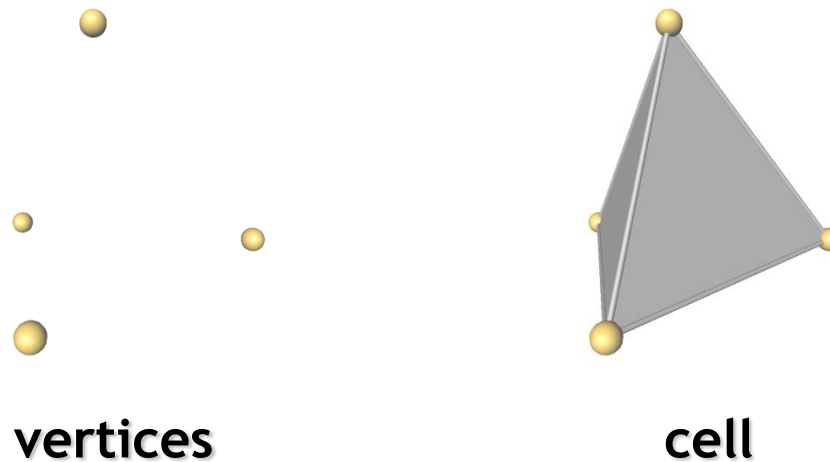
Infinite Vertex?

- No valid coordinates
 - no predicates applicable



Internal Representation

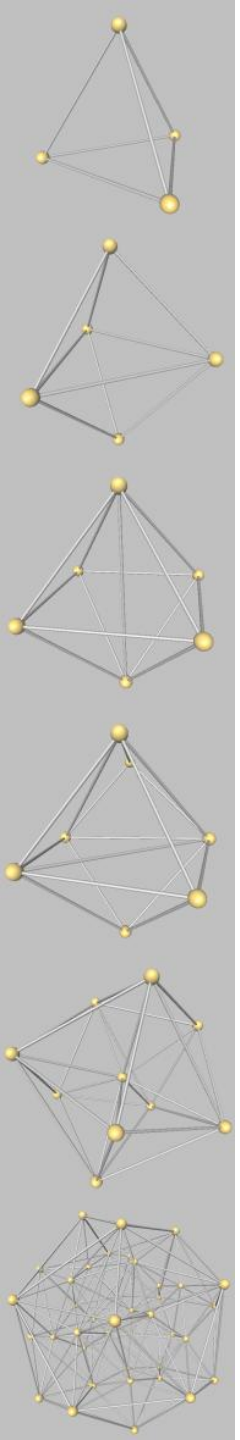
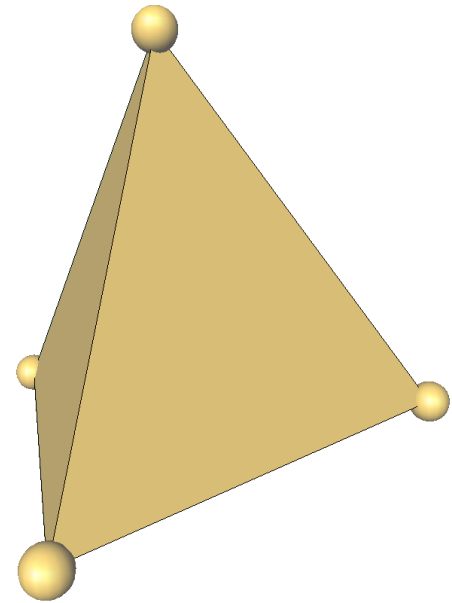
Collection of **vertices** and **cells** linked together through incidence and adjacency relations (faces and edges are not explicitly represented).



Cell

Access to:

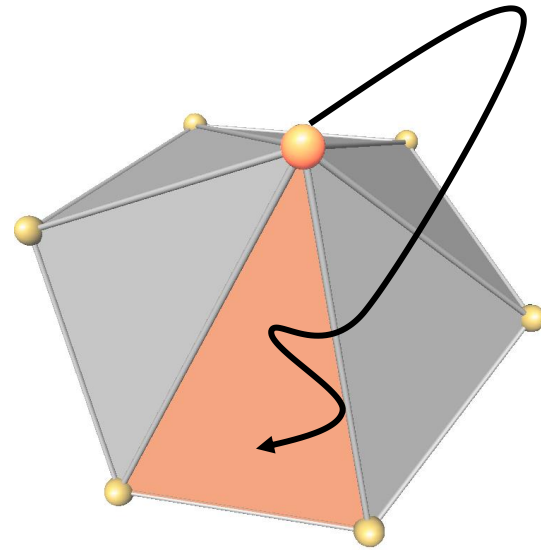
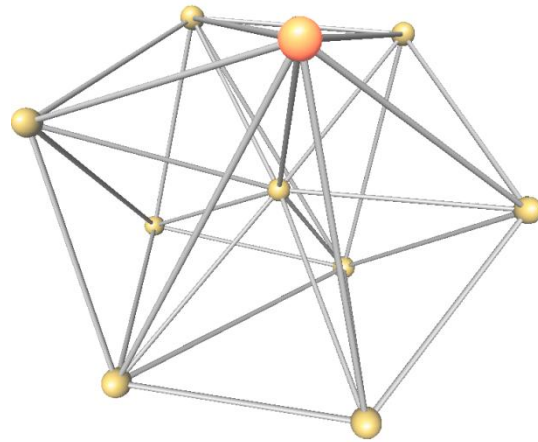
- 4 incident vertices
- 4 adjacent cells



Vertex

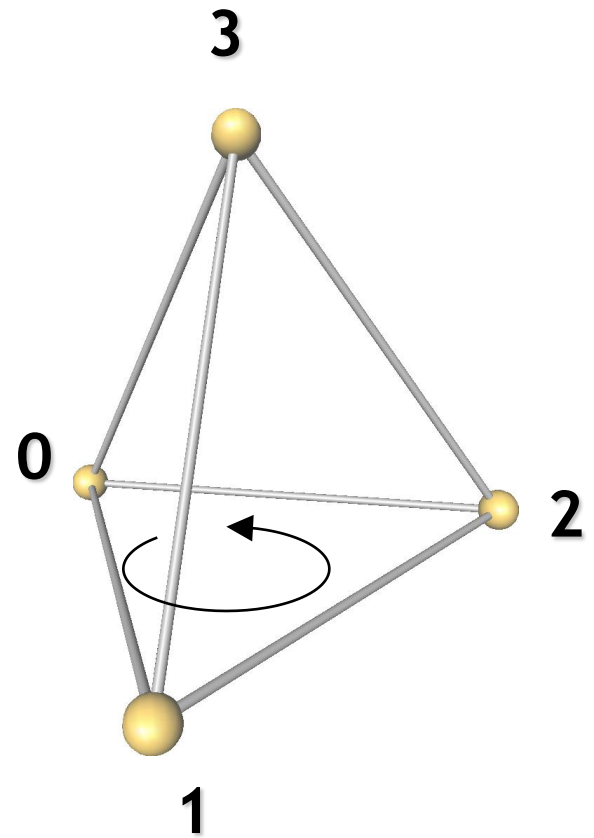
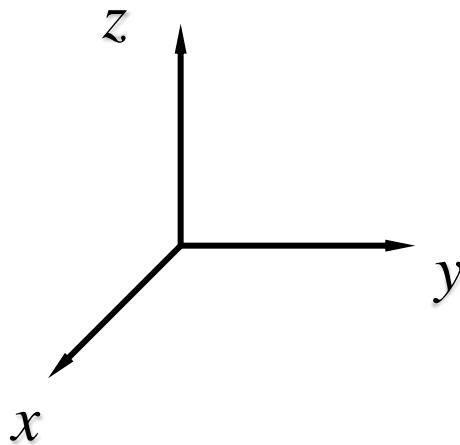
Access to:

- 1 incident cell



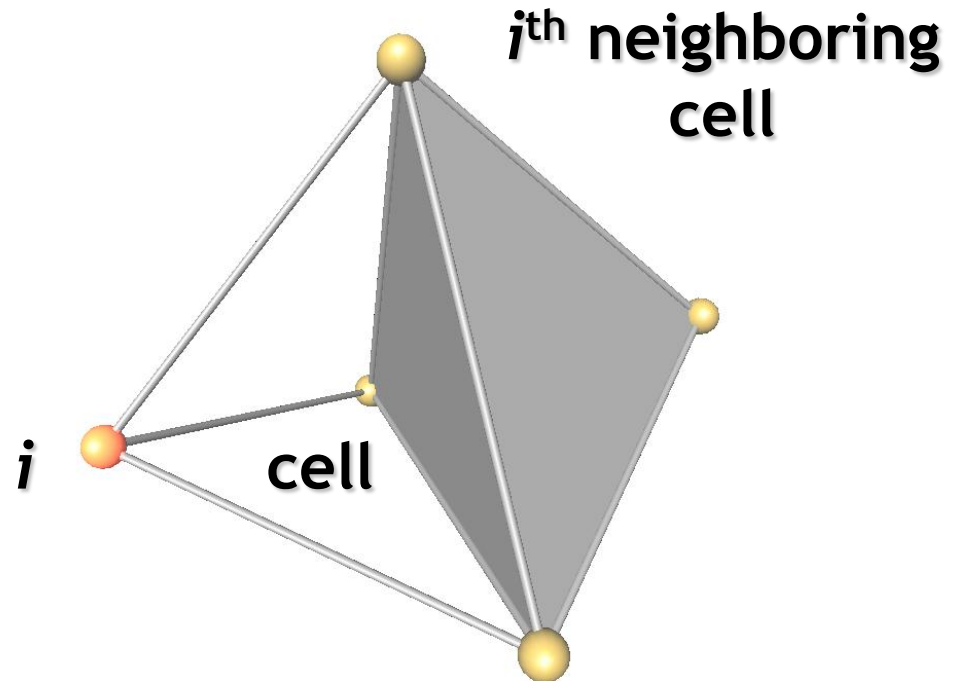
Orientation of a Cell

4 vertices indexed in
positive orientation
(induced by underlying
Euclidean space \mathbb{R}^3).



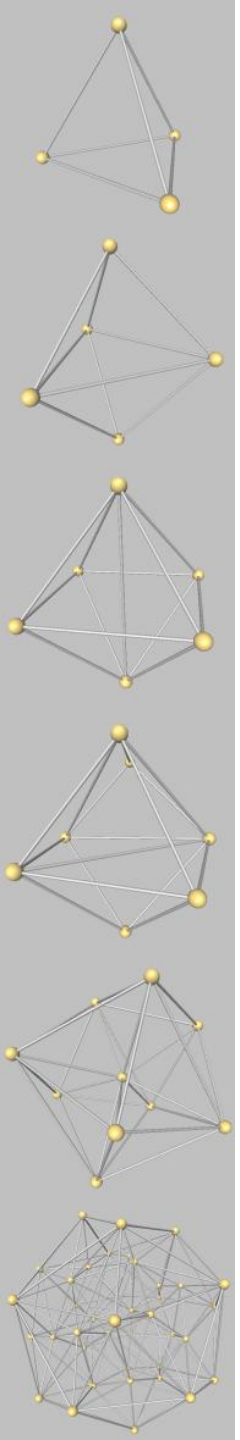
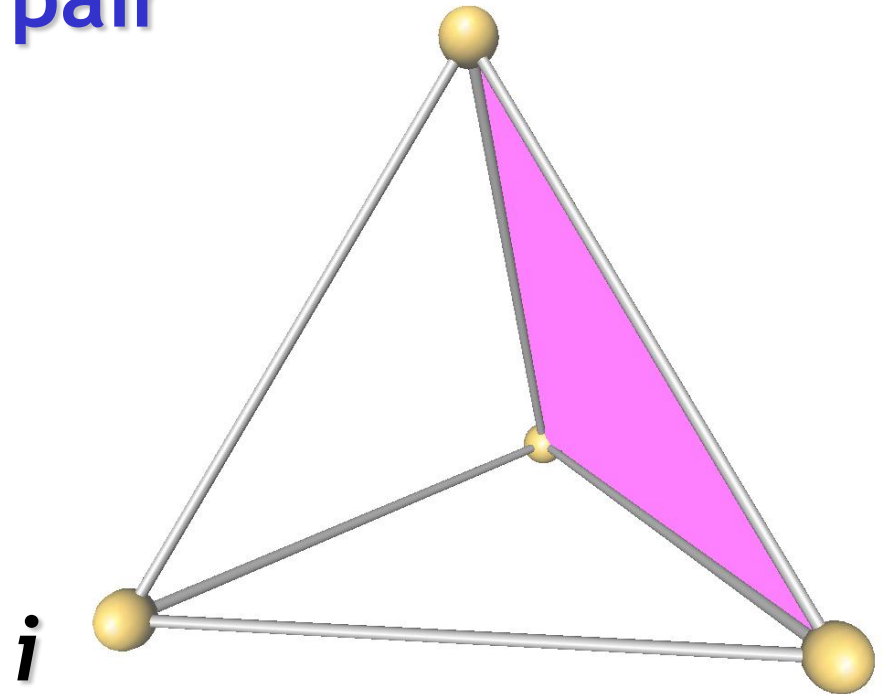
Adjacent Cell Indexing

- Neighboring cell indexed by i opposite to vertex i .



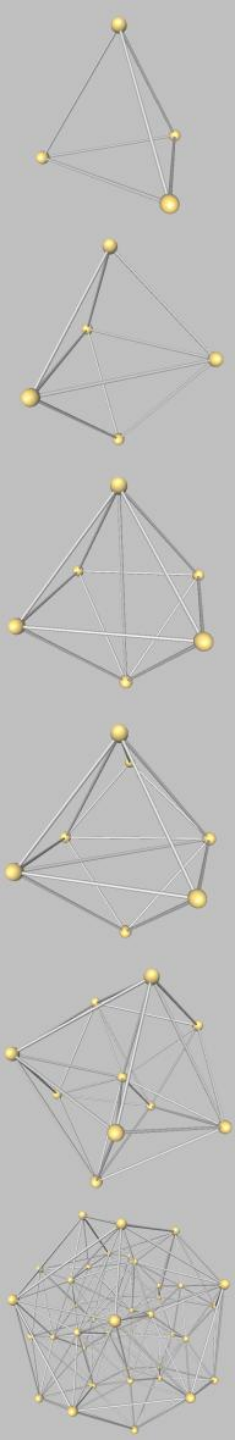
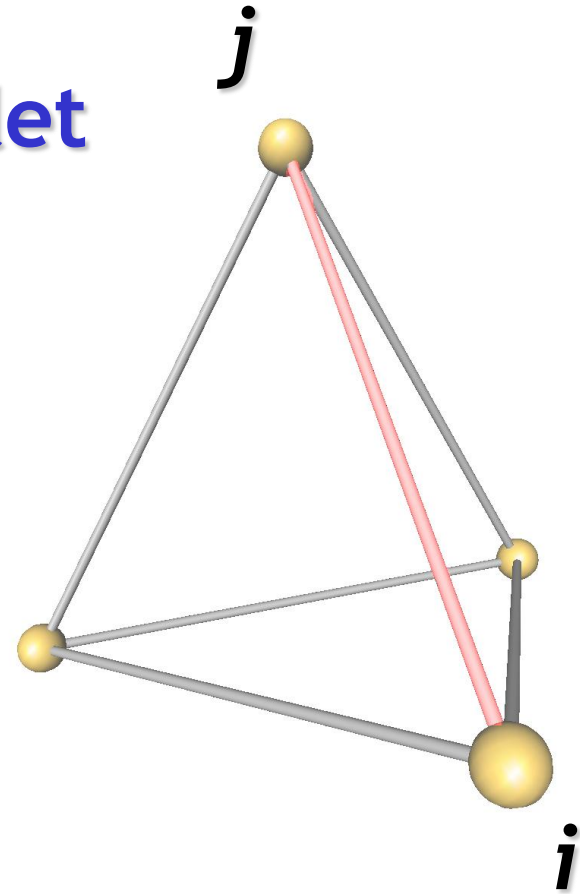
Face

Represented as a **pair**
{cell, index i }



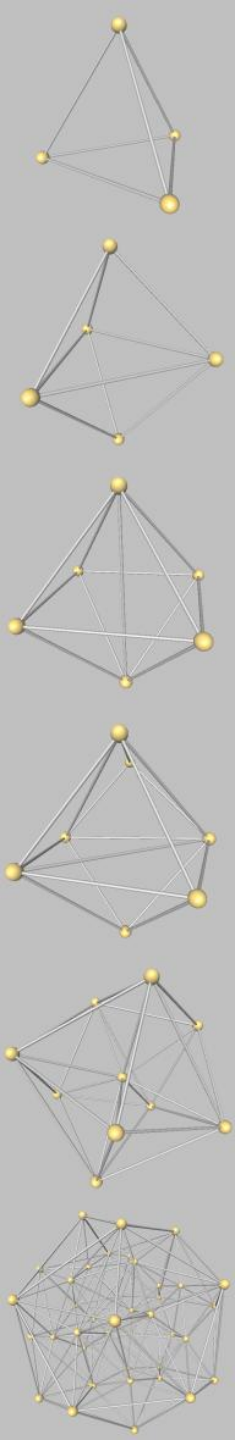
Edge

Represented as a **triplet**
 $\{\text{cell}, \text{index } i, \text{index } j\}$



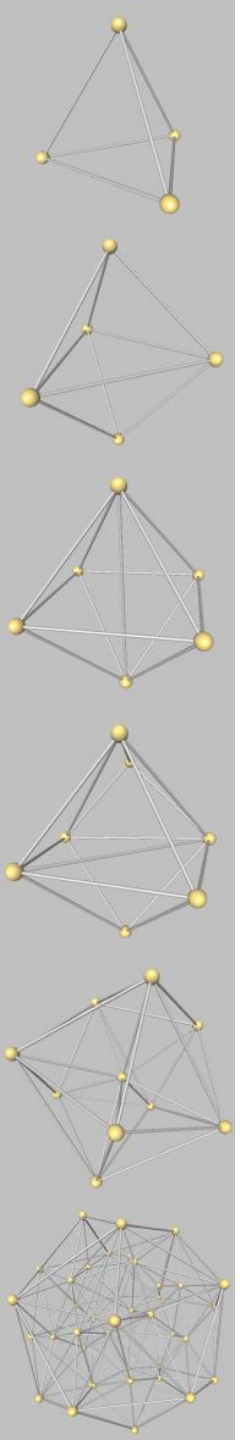
Outline

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3 Types of Triangulations

- Delaunay
- Regular
- Hierarchy



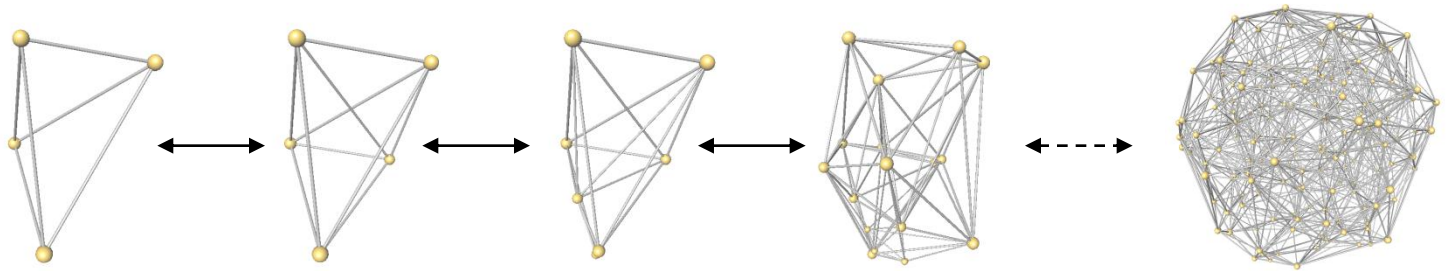
Delaunay Triangulation

- **Empty sphere** property:
 - the circumscribing sphere of each cell does not contain any other vertex in its interior.
- **Uniquely defined** except in degenerate cases where five or more points are cospherical (CGAL computes a unique triangulation even in these cases).

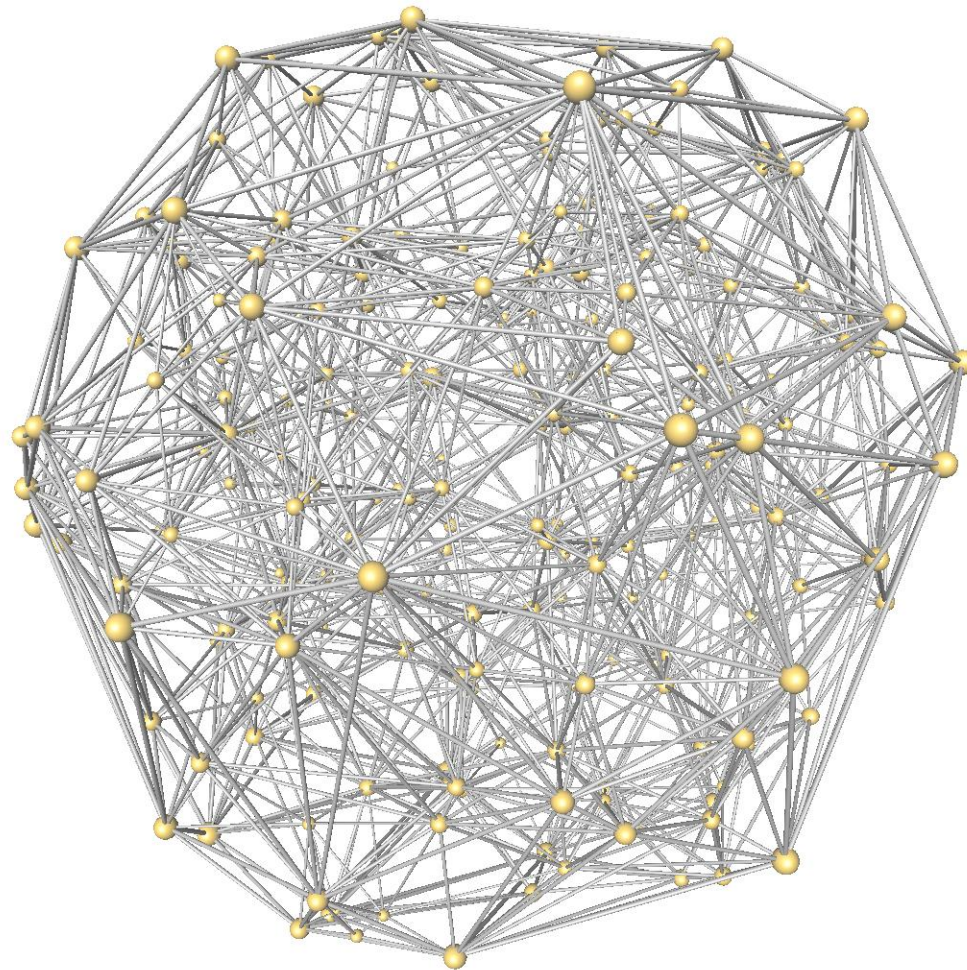
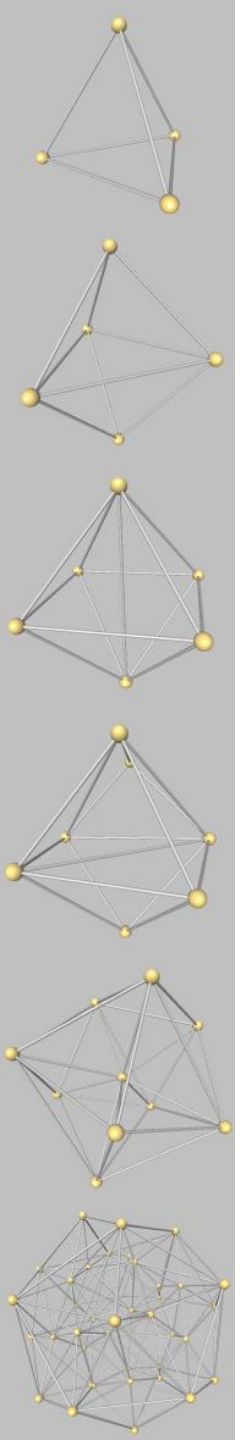
Delaunay Triangulation

Fully dynamic:

- point insertion
- vertex removal



Delaunay Triangulation

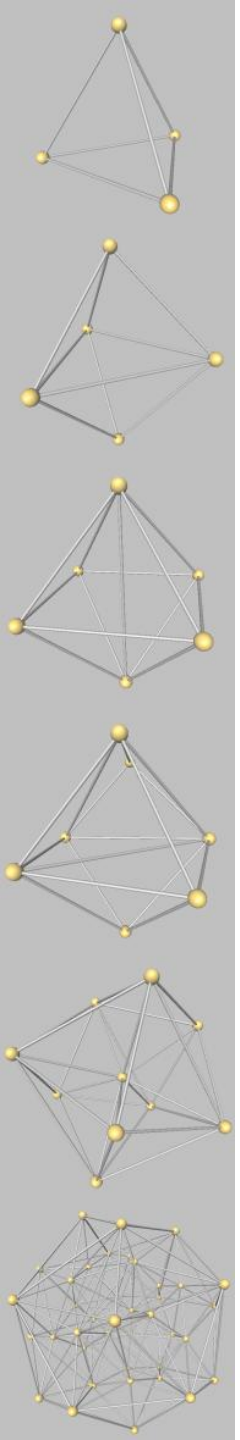
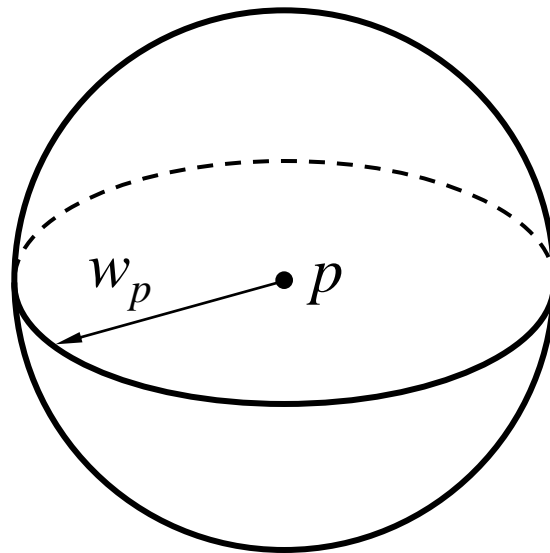


Regular Triangulation

(*weighted Delaunay triangulation*)

Weighted point:

- $p^{(w)} = (p, w_p), p \in \mathbb{R}^3, w_p \in \mathbb{R}.$

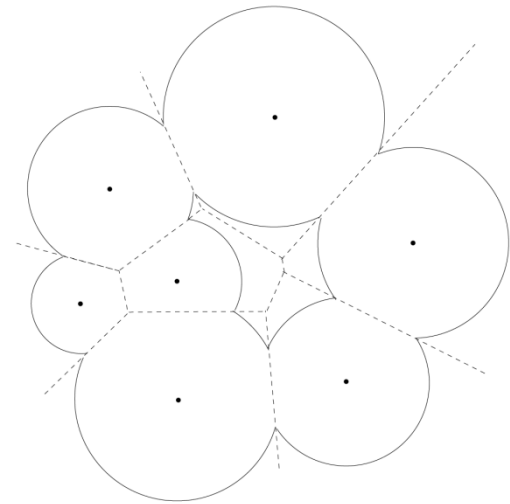
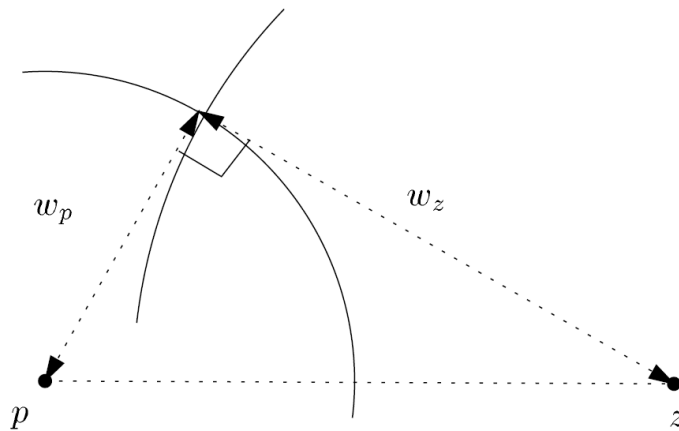


Regular Triangulation

(*weighted Delaunay triangulation*)

Power product:

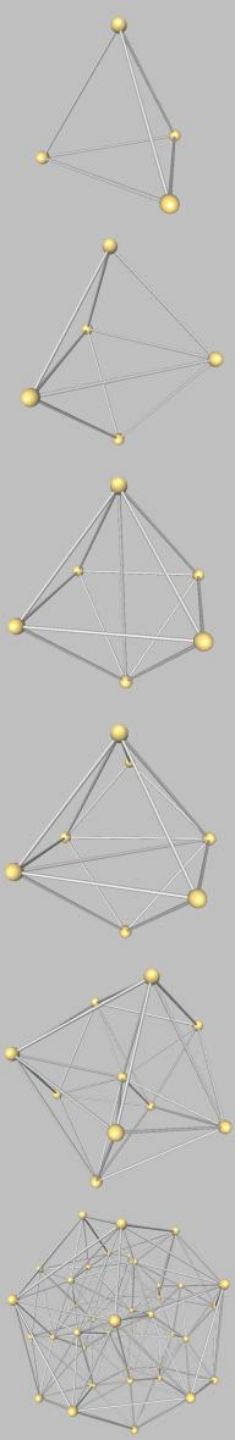
- $\Pi(p^{(w)}, z^{(w)}) = ||p-z||^2 - w_p - w_z$
- $p^{(w)}$ & $z^{(w)}$ said to be *orthogonal* iff = 0



Regular Triangulation

(*weighted Delaunay triangulation*)

4 weighted points have a unique common orthogonal weighted point called *power sphere*.





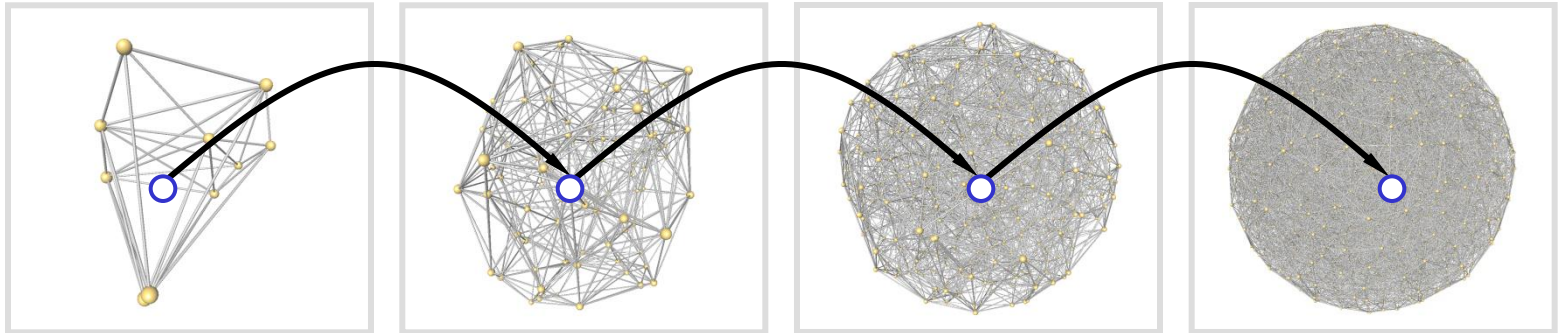
Regular Triangulation

(*weighted Delaunay triangulation*)

- Let $S^{(w)}$ be a set of weighted points.
- A sphere $z^{(w)}$ is said to be regular if for all $p^{(w)} \in S^{(w)}$, $\Pi(p^{(w)}, z^{(w)}) \geq 0$
- A triangulation is *regular* if the power spheres of all simplices are *regular*.

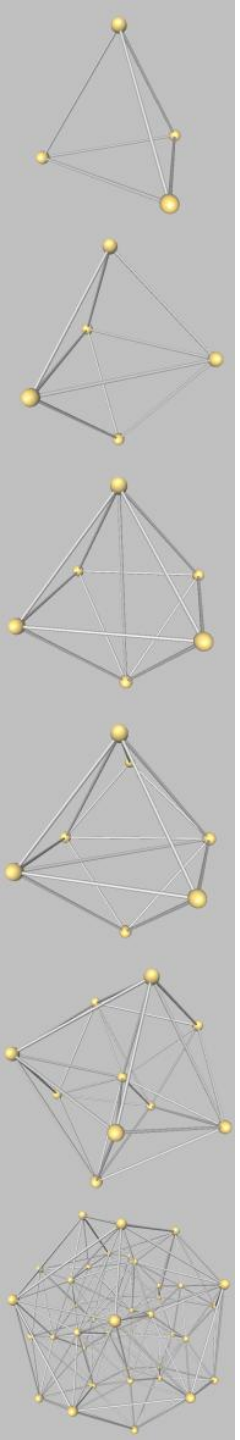
Triangulation Hierarchy

Triangulation augmented with a hierarchical data structure to allow for efficient *point location queries*.

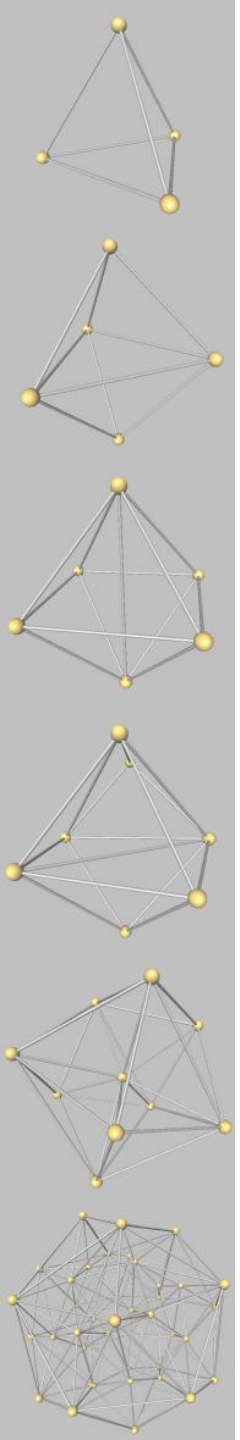
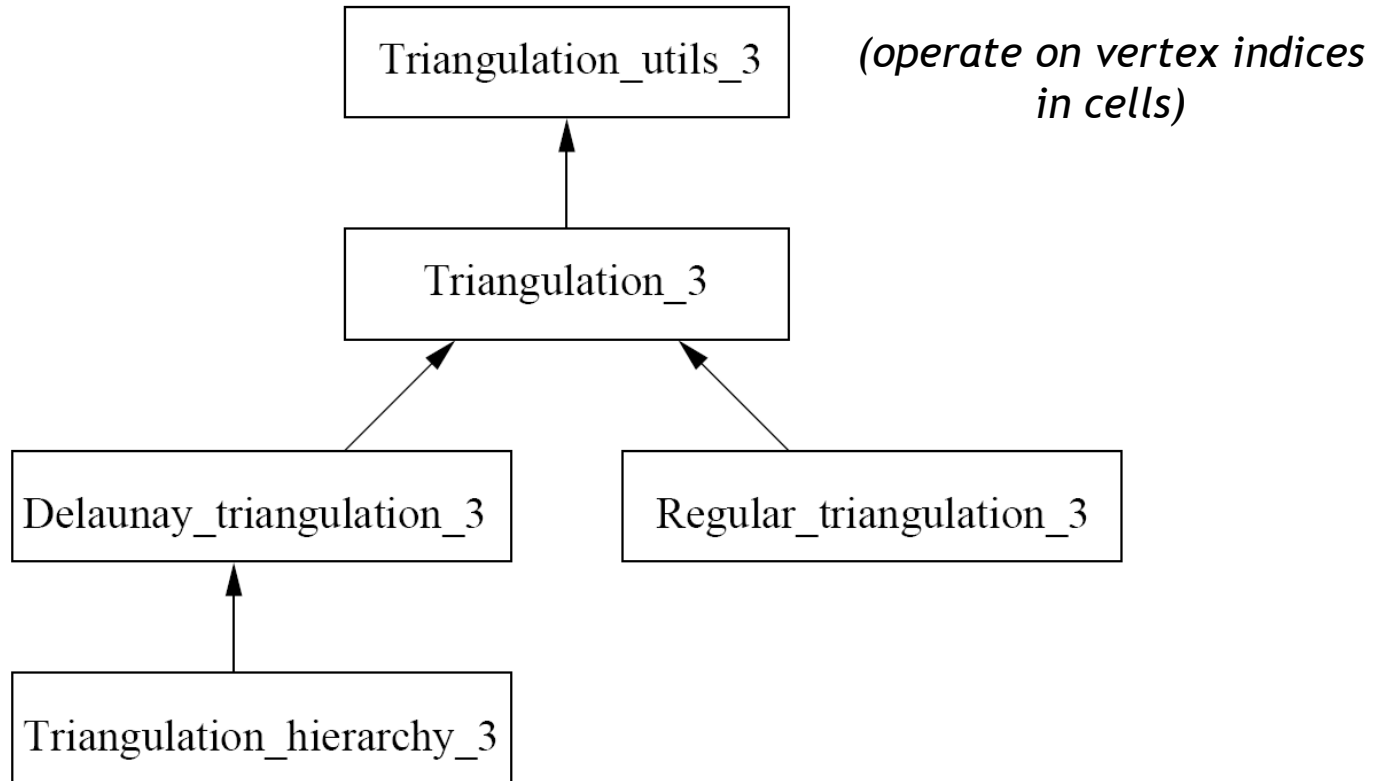


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Derivation Diagram



Software Design

Separation between *geometry* & *combinatorics*.

```
Triangulation_3<  
  TriangulationTraits_3,  
  TriangulationDataStructure_3>
```

Geometric Traits

Defines *geometric objects* & *predicates*.

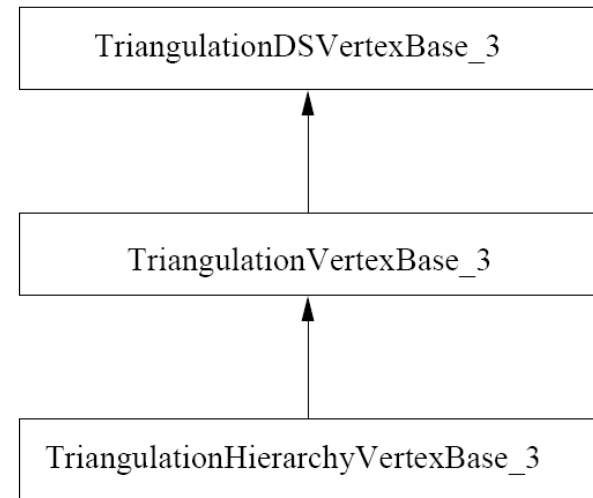
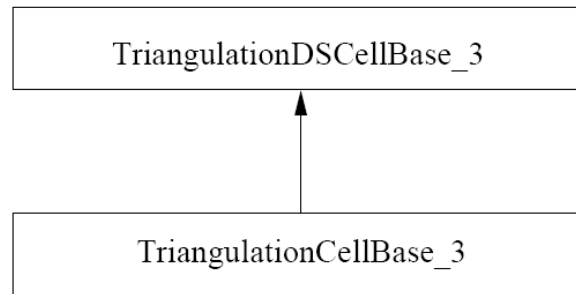
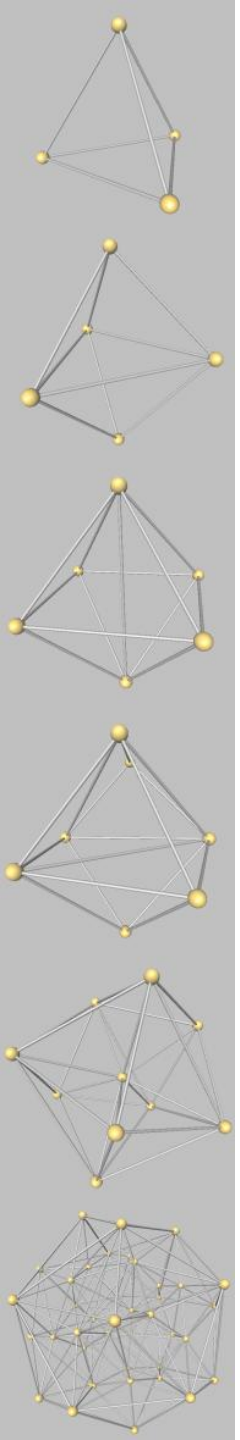
Objects:

- point
- segment
- triangle
- tetrahedron
- [weighted point]

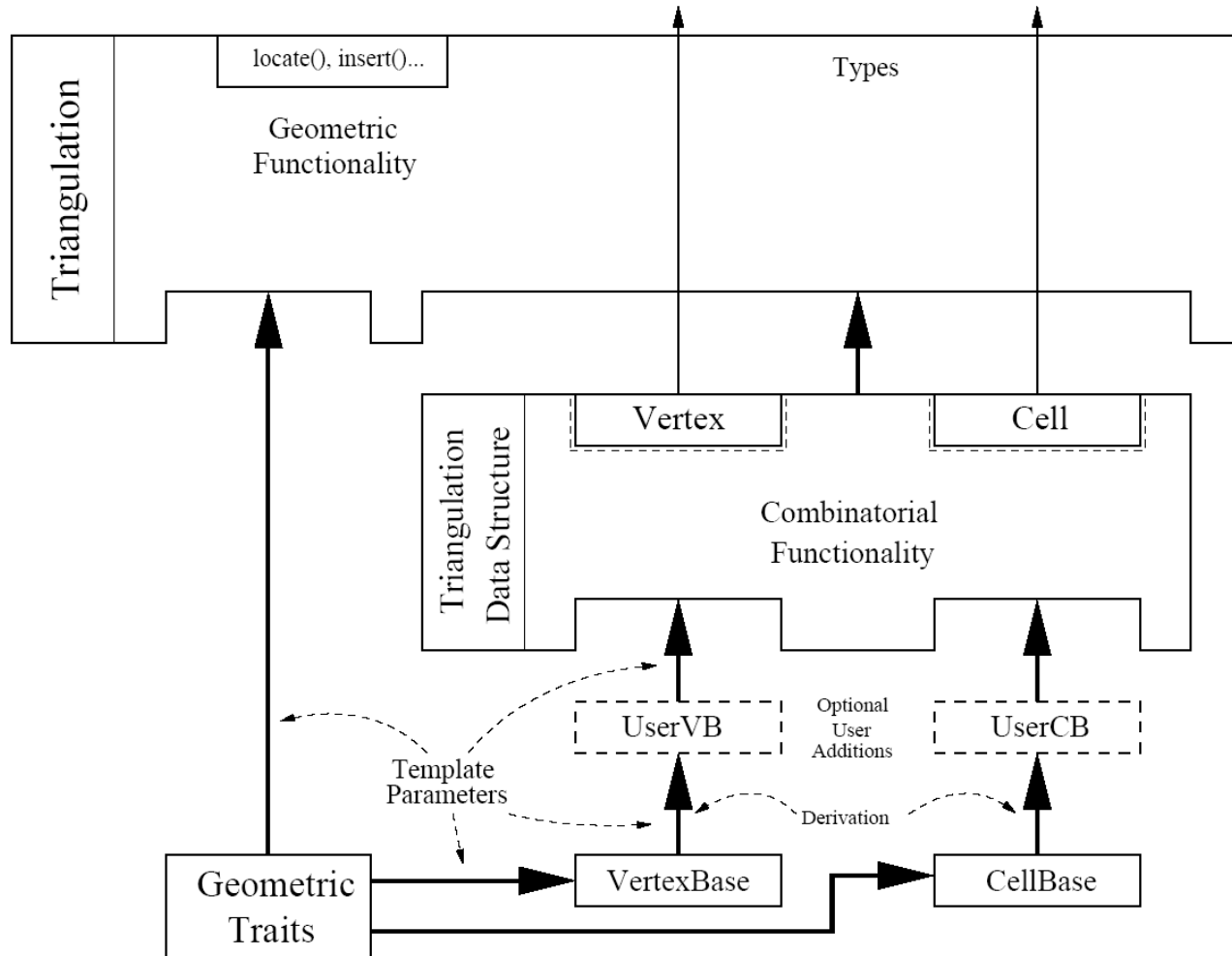
Predicates:

- orientation in space
- orientation of coplanar points
- order of collinear points
- empty sphere property
- [power test]

Triangulation Data Structure

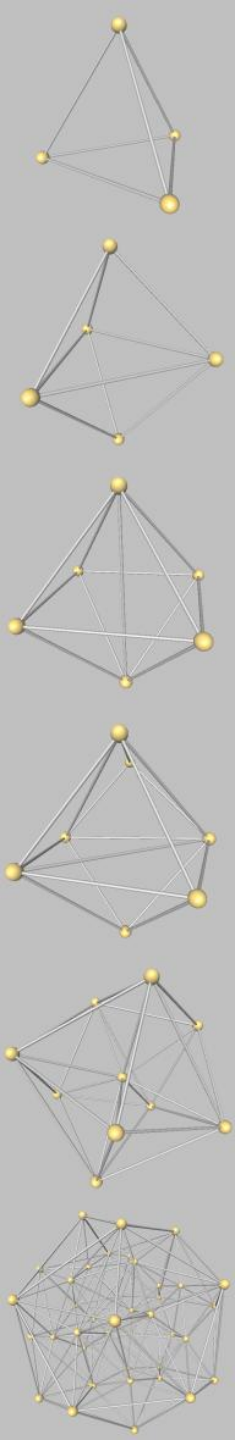


Customization (cells & vertices)



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Construction

```
#include <CGAL/Simple_cartesian.h>
#include <CGAL/Triangulation_3.h>

typedef CGAL::Simple_cartesian<double> Kernel;
typedef CGAL::Triangulation_vertex_base_3< Kernel > Vb;
typedef CGAL::Triangulation_cell_base_3< Kernel > Cb;
typedef CGAL::Triangulation_data_structure_3<Vb,Cb> Tds;
typedef CGAL::Triangulation_3< Kernel,Tds> Triangulation;
typedef Kernel::Point_3 Point;

Triangulation triangulation;

// insertion
triangulation.insert(Point(0,0,0));
triangulation.insert(Point(0,1,0));
triangulation.insert(Point(0,0,1));
triangulation.insert(Point(1,0,1));

// insertion from a list of points
std::list<Point> points;
points.push_front(Point(2,0,0));
points.push_front(Point(3,2,0));
...
triangulation.insert(points.begin(),points.end());
```

Construction

```
#include <CGAL/Simple_cartesian.h>
```

```
#include <CGAL/Triangulation_3.h>
```

```
typedef CGAL::Simple_cartesian<double> Kernel;
```

```
typedef CGAL::Triangulation_vertex_base_3< Kernel > Vb;
```

```
typedef CGAL::Triangulation_cell_base_3< Kernel > Cb;
```

```
typedef CGAL::Triangulation_data_structure_3<Vb,Cb> Tds;
```

```
typedef CGAL::Triangulation_3< Kernel, Tds> Triangulation;
```

```
typedef Kernel::Point_3 Point;
```

```
Triangulation triangulation;
```

```
// insertion
```

```
std::list<Vertex_handle> vertices;
```

```
Vertex_handle v = triangulation.insert(Point(0,0,0));
```

```
vertices.push_back(v);
```

Point Location

```
#include <CGAL/Simple_cartesian.h>
#include <CGAL/Triangulation_3.h>

typedef CGAL::Simple_cartesian<double> kernel;
typedef CGAL::Triangulation_vertex_base_3<kernel> Vb;
typedef CGAL::Triangulation_cell_base_3<kernel> Cb;
typedef CGAL::Triangulation_data_structure_3<Vb,Cb> Tds;
typedef CGAL::Triangulation_3<kernel,Tds> Triangulation;
typedef kernel::Point_3 Point;

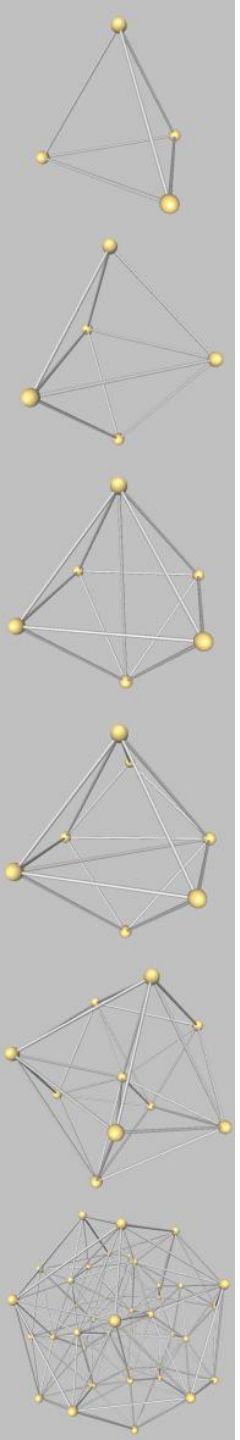
Triangulation triangulation;

// insertion
triangulation.insert(Point(0,0,0));
triangulation.insert(Point(0,1,0));

// locate
Locate_type lt;
int li, lj;
Point p(0,0,0);
Cell_handle cell = triangulation.locate(p, lt, li, lj);
assert(lt == Triangulation::VERTEX);
assert(cell->vertex(li)->point() == p);
```

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Applications

- Meshing
 - simulation
 - numerical engineering
- Reverse Engineering
 - surface reconstruction
- Efficient point location
- Etc.

