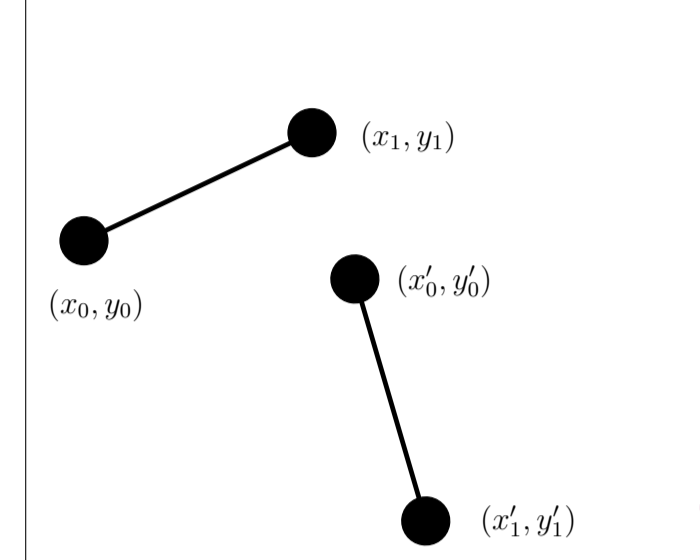


Whether algebraic or differential, one can distinguish two families of computational applications for invariants of group actions: equivalence problems and symmetry reduction. Both applications raise algorithmic issues: can we compute a generating set of invariants and can we determine their syzygies, i.e. the relationships the generating set satisfies. AIDA is a Maple package to compute generating sets of differential invariants and their differential syzygies for any given group action. It works on top of DifferentialGeometry, Groebner, and diffalg for non commuting derivations. This poster presents classical examples as introduction, theoretical foundations of the package, and original applications.

## Equivalence

Are two objects identical under the action of a group element?

### Equivalence of pairs of points

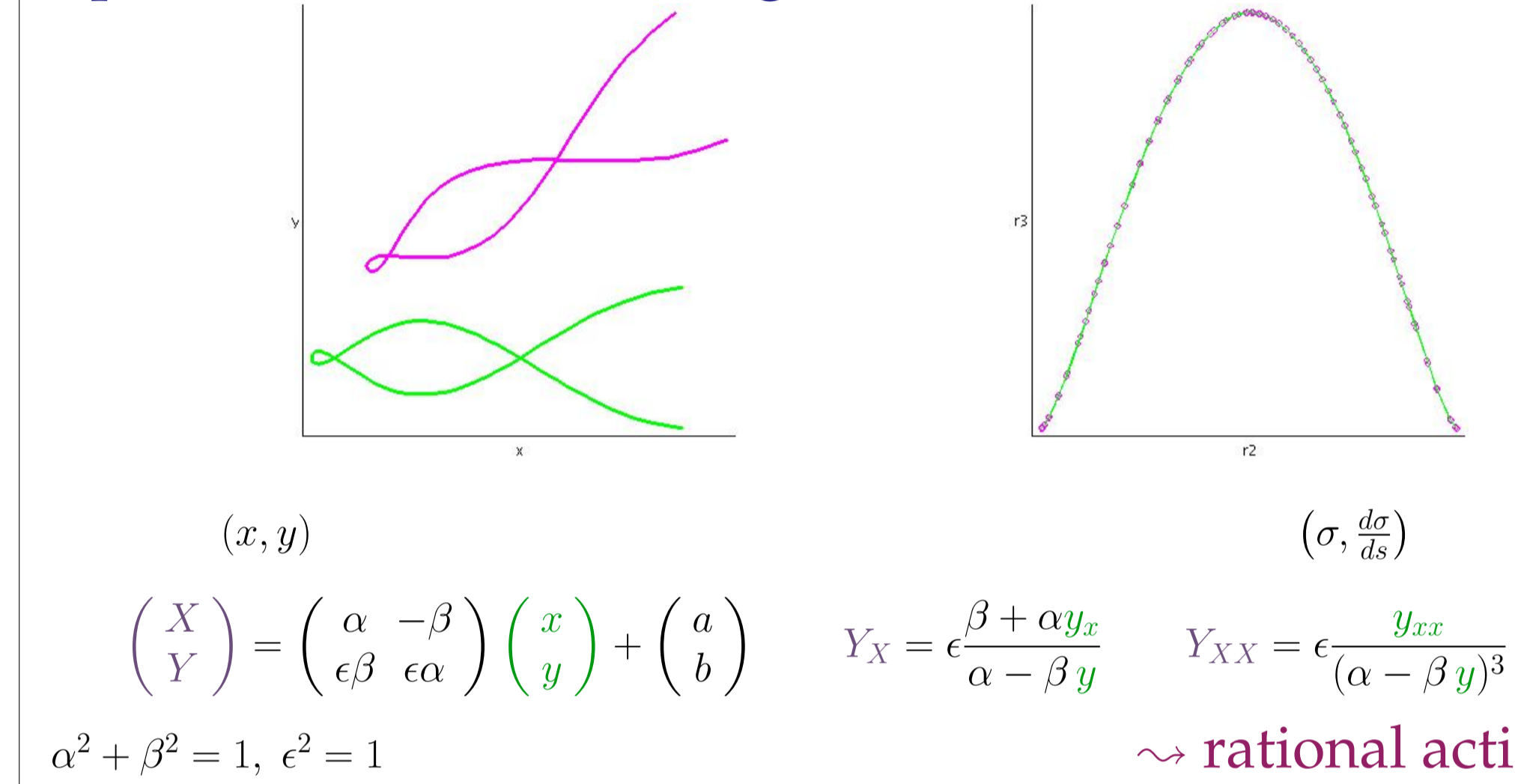


$$\begin{pmatrix} x'_i \\ y'_i \end{pmatrix} = \begin{pmatrix} \alpha & -\beta \\ \epsilon\beta & \epsilon\alpha \end{pmatrix} \begin{pmatrix} x_i \\ y_i \end{pmatrix} + \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\alpha^2 + \beta^2 = 1, \epsilon^2 = 1$$

$$(x_1 - x_0)^2 + (y_1 - y_0)^2 = (x'_1 - x'_0)^2 + (y'_1 - y'_0)^2$$

### Equivalence of curves ~ signature curves [O'95]



Differential invariant  $\sigma = \sqrt{\frac{y_{xx}^2}{(1+y_x^2)^3}}$  the curvature  
 Invariant derivation:  $\frac{1}{\sqrt{1+y_x^2}} \frac{d}{dx} = \frac{d}{ds}$  s the arc length  
 ~ algebraic functions

## Symmetry reduction

- group of symmetry
- rewriting algorithm
- generating invariants
- reduced problem solving
- relations among those
- solution lifting

### Biological models redimensioning with A.Sedoglavic

Prey-predator model [Murray, 2002]

$$\begin{cases} \dot{n} = \left( (1 - \frac{n}{k_1}) r - k_2 \frac{p}{n+c} \right) n, \\ \dot{p} = s \left( 1 - h \frac{p}{n} \right) p. \end{cases} \quad \rightsquigarrow \quad \begin{cases} \dot{n} = (1 - n - \frac{p}{n+c}) n, \\ \dot{p} = s \left( 1 - h \frac{p}{n} \right) p. \end{cases}$$

r, s, e, h, k<sub>1</sub>, k<sub>2</sub> parameters. s, e, h parameters

where  $t = r t, n = \frac{n}{k_1}, p = \frac{k_2 p}{k_1 r}, s = \frac{s}{r}, e = \frac{e}{k_1}, h = \frac{r h}{k_2}$  are the invariants of the symmetry group

$$\begin{aligned} t &\rightarrow \lambda^{-1} t, & r &\rightarrow \lambda r, & h &\rightarrow \nu h, \\ n &\rightarrow \mu n, & s &\rightarrow \lambda s, & k_1 &\rightarrow \mu k_1, \\ p &\rightarrow \mu \nu^{-1} p, & e &\rightarrow \mu e, & k_2 &\rightarrow \lambda \nu k_2 \end{aligned}$$

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## Local invariants of a group action [HK07]

### Semi-regular Lie group action

$$g: \mathcal{G} \times \mathcal{M} \rightarrow \mathcal{M} \quad (\lambda \cdot \mu) \star z = \lambda \star (\mu \star z)$$

$$(\lambda, z) \mapsto \lambda \star z$$

$\mathcal{G}$  a r-dimensional Lie group,  $\mathcal{M}$  a n-dimensional manifold

Orbit of z:  $\mathcal{O}_z = \{\lambda \star z \mid \lambda \in \mathcal{G}\} \subset \mathcal{M}$

Semi-regularity: the orbits have dimension d.

Lie algebra:  $v_1, \dots, v_r$  right invariant vector fields on  $\mathcal{G}$

Maurer-Cartan forms:  $\omega_1, \dots, \omega_r$  their duals

Infinitesimal generators:  $V_1, \dots, V_r$  vector fields on  $\mathcal{M}$

Local invariant:  $f: \mathcal{M} \rightarrow \mathbb{R}$  smooth s.t.

$$V_1(f) = 0, \dots, V_r(f) = 0 \Leftrightarrow f(\lambda \star z) = f(z) \text{ for } \lambda \in \mathcal{G}_e$$

### Local cross-section $\mathcal{P}$

-  $\mathcal{P}$  an embedded manifold of dimension  $n - d$

$$\mathcal{P} = \{z \in \mathcal{M} \mid p_1(z) = \dots = p_s(z) = 0\}$$

-  $\mathcal{P}$  is transverse to  $\mathcal{O}_z$  at  $z \in \mathcal{P}$ .

$$V(P) = (V_i(p_j))_{ij} \text{ has rank } s \text{ at } z_0 \in \mathcal{P}$$

-  $\mathcal{P}$  intersect  $\mathcal{O}_z$  at a unique point,  $\forall z \in \mathcal{M}$ .

$\mathcal{O}_z^0$  is the connected component of  $\mathcal{O}_z$ .

Local invariants  $\cong$  smooth functions on the cross-section.

### Invariantization $\bar{t}f$ of a smooth function f

$$f: \mathcal{M} \rightarrow \mathbb{R} \text{ smooth} \quad \bar{t}f(z) = f(\mathcal{O}_z^0 \cap \mathcal{P})$$

$\bar{t}f$  is the unique local invariant with  $\bar{t}f|_{\mathcal{P}} = f|_{\mathcal{P}}$

Cartan's normalized invariants:  $\bar{t}z_1, \dots, \bar{t}z_n$

**Thm:** for f local invariant  $f(z_1, \dots, z_n) = f(\bar{t}z_1, \dots, \bar{t}z_n)$

$\Rightarrow$  Cartan's normalized invariants form a generating set

**Thm:** a maximally independent set of relations is

$$p_1(\bar{t}z_1, \dots, \bar{t}z_n) = 0, \dots, p_r(\bar{t}z_1, \dots, \bar{t}z_n) = 0$$

## Moving frame map [FO'99]

$$\rho: \mathcal{U} \rightarrow \mathcal{G} \text{ equivariant} \quad \rho(\lambda \star z) = \rho(z) \cdot \lambda^{-1}$$

$$\Rightarrow z \mapsto \rho(z) \star z \text{ invariant}$$

Locally free action:  $\mathcal{G}_z = \{\lambda \mid \lambda \star z = z\}$  finite

The equation  $\rho(z) \star z \in \mathcal{P}$  defines a m.f. map

**Thm:**  $\bar{t}f(z) = f(\rho(z) \star z)$

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## Action on jet spaces

$$\mathcal{J}^0 = \mathcal{X} \times \mathcal{U}$$

$(x_1, \dots, x_m)$  coordinates on  $\mathcal{X}$ ; independent variables

$(u_1, \dots, u_n)$  coordinate on  $\mathcal{U}$ ; dependent variables

$(u_\alpha \mid \alpha \in \mathbb{N}^m)$  other coordinates on  $\mathcal{J}^\infty$ ; derivatives

Total derivations:

$$D = (D_1, \dots, D_m)^t \text{ s.t. } D_i(x_j) = \delta_{ij}, D_i(u_\alpha) = u_{\alpha+\epsilon_i}$$

$$g: \mathcal{G} \times \mathcal{J}^0 \rightarrow \mathcal{J}^0 \text{ prolonged to } g: \mathcal{G} \times \mathcal{J}^k \rightarrow \mathcal{J}^k$$

by  $g^* \circ D = \tilde{D} \circ g^*$  where  $\tilde{D} = A^{-1} D$  with  $A = (D_i(g^* x_j))_{ij}$

$g: \mathcal{G} \times \mathcal{J}^0 \rightarrow \mathcal{J}^0$  effective on subset  $\Rightarrow$   
 $\dim \mathcal{O}^0 \leq \dim \mathcal{O}^1 \leq \dots \leq \dim \mathcal{O}^s = \dim \mathcal{O}^{s+1} = r$

Stabilisation order: s. The action on  $\mathcal{J}^{s+k}$  is locally free.

Differential invariant of order k:

$$f: \mathcal{J}^k \rightarrow \mathbb{R} \text{ smooth s.t. } V_1^k(f) = 0, \dots, V_r^k(f) = 0$$

$\mathcal{P}$  a cross-section to the orbits on  $\mathcal{J}^s$ , and therefore on  $\mathcal{J}^{s+k}$ .

$$\mathcal{P}: p_1(z) = 0, \dots, p_r(z) = 0$$

$\rho: \mathcal{J}^s \rightarrow \mathcal{G}$  the associated moving frame map:  $\rho(z) \star z \in \mathcal{P}$

$$\sigma: \mathcal{J}^{s+k} \rightarrow \mathcal{G} \times \mathcal{J}^{s+k}$$

$$z \mapsto (\rho(z), z)$$

## Invariant derivations

$$\mathfrak{D} = (\mathfrak{D}_1, \dots, \mathfrak{D}_m)^t \text{ s.t. } V_\alpha \circ \mathfrak{D}_i = \mathfrak{D}_i \circ V_\alpha$$

f a diff. inv. of order k  $\Rightarrow \mathfrak{D}_i(f)$  a diff. inv. of order k+1, k >> 0.

Classical construction:  $\mathfrak{D} = A^{-1} D$ ,  $A = (D_i(f_j))_{ij}, f_1, \dots, f_m$  diff. inv.

[FO'99]:  $\mathfrak{D} = (\sigma^* A)^{-1} D$  where  $A = (D_i(g^* x_j))_{ij}$

**Thm:**  $\mathfrak{D}(\bar{t}f) = \bar{t}(Df) - K \bar{t}(V(f))$  where  $K = \bar{t}D(P) V(P)^{-1}$

$$D(P) = (D_i(p_j))_{ij}, V(P) = (V_i(p_j))_{ij}$$

**Cor:** f a diff. inv.  $\Rightarrow \mathfrak{D}(f) = \bar{t}(D(f))$

$$\text{Prop: } [\mathfrak{D}_i, \mathfrak{D}_j] = \sum_{k=1}^m \Lambda_{ijk} \mathfrak{D}_k$$

where  $\Lambda_{ijk} = \sum_{c=1}^d K_{ic} \bar{t}(D_j(\xi_{ck})) - K_{jc} \bar{t}(D_i(\xi_{ck})), \xi_{ck} = V_c(x_k)$

## Cartan Normalized invariants

$$\mathcal{J}^k = \{\bar{t}x_1, \dots, \bar{t}x_m\} \cup \{\bar{t}u_\alpha \mid |\alpha| \leq k\}$$

$\mathcal{J}^{s+k}$  a generating set of differential invariants of order s+k.

**CN Thm:**  $\mathcal{J}^{s+1}$  is a differentially generating set of differential invariants and a complete set of syzygies is given by

$$\mathfrak{D}_i(x_j) = \delta_{ij} + \sum_{a=1}^r K_{ia} \bar{t}(V(x_j))$$

$$\mathfrak{D}_i(\bar{t}u_\alpha) = \bar{t}u_{\alpha+\epsilon_i} + \sum_{a=1}^r K_{ia} \bar{t}(V(u_\alpha)), |\alpha| \leq s$$

$$\mathfrak{D}_i(\bar{t}u_\alpha) - \mathfrak{D}_j(\bar{t}u_\beta) = \sum_{a=1}^r K_{ia} \bar{t}(V(u_\alpha)) - K_{ja} \bar{t}(V(u_\beta))$$

$$\alpha + \epsilon_i = \beta + \epsilon_j, |\alpha| = |\beta| = s + 1.$$

**MO Thm:** If  $\mathcal{P}$  is a cross-section of minimal order then  $\mathfrak{D} \cup \{\bar{t}(D_i(p_j))\}$  is a differentially generating set of differential invariants.

## Maurer-Cartan invariants

$\mathfrak{K}$  the set of entries  $K_{ia}$  of the  $m \times r$  matrix  $K = \bar{t}D(P) V(P)$ .

**Thm:**  $\rho^* \omega = -K^T \mathfrak{r} \text{ mod } \Theta$

where  $\Theta$  contact ideal,  $\mathfrak{r} = (\mathfrak{r}_1, \dots, \mathfrak{r}_m)$  duals of  $\mathfrak{D}$

Structure equations:  $d\omega_c = -\sum_{a<b} \gamma_{abc} \omega_a \wedge \omega_b$

$$\Rightarrow d\mu_c = -\sum_{a<b} \gamma_{abc} \mu_a \wedge \mu_b, \text{ where } \mu = \rho^* \omega$$

**MC Thm:**  $\mathfrak{K}$  is a differentially generating set of differential invariants, if the action is transitive on  $\mathcal{J}^0$ . A complete set of syzygies is given by

$$\mathfrak{D}_j(K_{ic}) - \mathfrak{D}_i(K_{jc}) = \sum_{1 \leq a < b \leq r} \gamma_{abc} (K_{ja} K_{ib} - K_{ia} K_{jb}) - \sum_{k=1}^m \Lambda_{ijk} K_{kc}$$

## Differential invariants for surfaces with P.Olver

With the infinitesimal generators of the group action and a choice of cross-section as data we show that the algebra of differential invariants is generated by a single differential invariants.

The invariant derivations satisfy  $[\mathfrak{D}_1, \mathfrak{D}_2] = \phi \mathfrak{D}_1 - \psi \mathfrak{D}_2$

By differential elimination [H'05] we show that the invariants of theorem MO or MC can be written in terms of the monotone derivatives of  $\phi$  and  $\psi$ .

Observe then that  $\psi = \frac{1}{\mathfrak{D}_2(\phi)} (\phi \mathfrak{D}_1(\phi) - \mathfrak{D}_1 \mathfrak{D}_2(\phi) + \mathfrak{D}_2 \mathfrak{D}_1(\phi))$ .

## Conformal geometry

The infinitesimal generators for this action of  $SO(4, 1)$  are

$$\begin{aligned} \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial u} - u \frac{\partial}{\partial y}, (x^2 - y^2 - u^2) \frac{\partial}{\partial x} + 2xy \frac{\partial}{\partial y} + 2xu \frac{\partial}{\partial u}, \\ \frac{\partial}{\partial y}, x \frac{\partial}{\partial u} - u \frac{\partial}{\partial x}, 2xy \frac{\partial}{\partial x} + (x^2 - y^2 - u^2) \frac{\partial}{\partial y} + 2yu \frac{\partial}{\partial u}, \\ \frac{\partial}{\partial u}, x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x}, 2xu \frac{\partial}{\partial u} + 2yu \frac{\partial}{\partial y} + (x^2 - y^2 - u^2) \frac{\partial}{\partial u}. \end{aligned}$$

Cross-section:  $x=y=u_0=u_{10}=u_{20}=1=u_{11}=u_{02}=u_{21}=u_{12}=0$

$$\text{Maurer-Cartan matrix: } K = \begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 & -\psi & \sigma & \kappa & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & \phi & \tau & -\sigma & -\frac{1}{2}\phi \end{pmatrix}$$

where  $\phi = \bar{t}u_{03}, \psi = \bar{t}u_{30}, \tau = \frac{1}{2}\bar{t}u_{13}, \kappa = -\frac{1}{2}\bar{t}u_{31}, \sigma = \frac{1}{2}\bar{t}u_{22}$

Syzygies:  $\tau_{00} - \frac{1}{2}\phi_{10} = \psi_{00}\phi_{00}, \sigma_{10} + \kappa_{01} = 2\phi_{00}\kappa_{00} - 2\psi_{00}\sigma_{00}$

$\phi_{10} + \psi_{01} = 2\tau_{00} - 2\kappa_{00}, \sigma_{01} - \tau_{10} = \frac{1}{2}\phi_{00} + 2\phi_{00}\sigma_{00} + 2\psi_{00}\tau_{00}, \dots$

By differential elimination on the syzygies we obtain:

$$\tau = \frac{1}{2}\phi_{10} + \psi_{00}\phi_{00} \quad \kappa = \psi_{00}\phi_{00} - \frac{1}{2}\psi_{01}$$

$$\sigma = \frac{\tau_{00} + \kappa_{02}}{4(\kappa_{00} - \tau_{00})} + \frac{5(\psi_{00}\tau_{10} - \phi_{00}\kappa_{01}) + 2(\psi_{10}\tau_{00} - \phi_{01}\kappa_{00})}{4(\kappa_{00} - \tau_{00})} + \frac{12(\phi_{00}^2\kappa_{00} + \psi_{00}^2\tau_{00}) + \psi_{00}\phi_{00} + 2\tau_{00}}{8(\kappa_{00} - \tau_{00})}$$

## Projective geometry

The infinitesimal generators of the action are:

$$\begin{aligned} \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial u}, x \frac{\partial}{\partial x}, y \frac{\partial}{\partial x}, u \frac{\partial}{\partial x}, x \frac{\partial}{\partial y}, y \frac{\partial}{\partial y}, u \frac{\partial}{\partial y}, x \frac{\partial}{\partial u}, y \frac{\partial}{\partial u}, u \frac{\partial}{\partial u}, \\ x^2 \frac{\partial}{\partial x} + xy \frac{\partial}{\partial y} + xu \frac{\partial}{\partial u}, xy \frac{\partial}{\partial x} + y^2 \frac{\partial}{\partial y} + yu \frac{\partial}{\partial u}, xu \frac{\partial}{\partial x} + yu \frac{\partial}{\partial y} + u^2 \frac{\partial}{\partial u}. \end{aligned}$$

Minimal order cross-section:

$$x=0, y=0, u_0=0, u_{10}=0, u_{01}=0, u_{20}=0, u_{11}=1, u_{02}=0, u_{30}=1, u_{21}=0, u_{12}=0, u_{03}=1, u_{31}=0, u_{22}=0, u_{13}=0.$$

$$\text{Then } K = \begin{pmatrix} 1 & 0 & 0 & 2\psi & 0 & \kappa & -\frac{1}{2}\psi & \tau & 0 & 1 & 3\psi & -\tau & \frac{1}{4} - \kappa & \frac{1}{2}\sigma + \frac{3}{8}\psi \\ 0 & 1 & 0 & \phi & -\frac{1}{2}\sigma & 0 & 2\phi & \eta & 1 & 0 & 3\phi & \frac{1}{4} - \eta & -\sigma & \frac{3}{8}\phi + \frac{1}{2}\tau \end{pmatrix}$$

where  $\phi = -\frac{1}{3}u_{04}, \psi = -\frac{1}{3}u_{40}, \eta = -\frac{1}{2}u_{14} - \frac{1}{4}, \tau = \frac{1}{4}u_{04} - \frac{1}{2}u_{23}, \sigma = \frac{1}{4}u_{40} + \frac{1}{4}u_{40} - \frac{1}{2}u_{32}, \kappa = -\frac{1}{2}u_{41} - \frac{1}{4}$

Syzygies:

$$\begin{aligned} \phi_{10} - 2\psi_{01} = \frac{1}{2} - 2\eta + \phi\psi, \sigma_{10} - \kappa_{01} = \frac{3}{8}\phi + 3\phi\kappa + 2\psi\sigma \\ 2\phi_{10} - \psi_{01} = 2\kappa + \phi\psi - \frac{1}{2}, \eta_{10} - \tau_{01} = -3\psi\eta - \frac{3}{8}\psi - 2\phi\tau \\ \frac{1}{2}\tau_{10} - \frac{1}{2}\sigma_{01} + \frac{3}{8}\phi_{10} - \frac{3}{8}\psi_{01} = \frac{1}{4}\kappa - \frac{1}{4}\eta - 2\phi\sigma + 2\psi\tau \end{aligned}$$

From which:  $\eta = \frac{1}{4} - \frac{1}{2}\phi_{10} + \psi_{01} - \frac{1}{2}\phi_{00}\psi_{00}, \kappa = \frac{1}{4} + \phi_{10} - \frac{1}{2}\psi_{01} - \frac{1}{2}\phi_{00}\psi_{00}$   
 A challenging differential elimination with non-commuting derivations produces  $\tau$  and  $\sigma$  in terms of  $\psi$  and  $\phi$  and their monotone derivatives.