# Discriminant method for the homological monodromy 

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－Introduction．
－Hyphotesis of the discriminant method．
－The main theorem and sketch of the proof．
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## The block decomposition

- Let $f: \mathbb{C}^{n} \rightarrow \mathbb{C}$ be a polynomial function.
- There exists a finite minimal set $B(f)$ such that the restriction map $f \mid: f^{-1}(\mathbb{C} \backslash B(f)) \longrightarrow \mathbb{C} \backslash B(f)$ is a locally trivial fibration.
- Given a geometric basis $\left(\gamma_{i}\right)$ of $\pi_{1}(T \backslash B(f) ; \star)$ ©. B. one has a direct sum decomposition of $\tilde{H}_{q}\left(f^{-1}(\star)\right)$ (reduced homology over $\mathbb{Z}$ ) which depends essentially on the choice of $\left(\gamma_{i}\right)$ (see $[4,6,7,14,15,16]$ for various degrees of generality).
- With this sum decomposition and if $f$ has only isolated singularities, local monodromy

$$
\left(h_{\gamma_{i}}\right)_{*}: \tilde{H}_{q}\left(f^{-1}(\star)\right) \longrightarrow \tilde{H}_{q}\left(f^{-1}(\star)\right)
$$

has a block decomposition.

## The block decomposition

- $\left(h_{\gamma_{i}}\right)_{*}$ has two kinds of blocks:
- local blocks which only depend on the local Milnor fibers.
- global blocks which depend on the embeddings of the local Milnor fibers into the fixed regular fiber $f^{-1}(\star)$.
- These two invariants allow us to compute the intersection matrix of $f^{-1}(\star)$.


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Example
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- Several papers dealing with the local blocks and how to compute them:
- Brieskorn singularities by A. Hefez and F. Lazzeri [13].
- Certain singularities and unimodal singularities by A. M. Gabriélov [8, 9].
- General methods: using real morsifications (N. A'Campo [1, 2] and S. M. Gusein-Zade [11, 12]) and using an inductive argument (A. M. Gabriélov [10]).


## The block decomposition

- This is not the situation for the global blocks.
- There are some relations between local and global blocks (A. Dimca and A. Némethi [6], W. Neumann and P. Norbury [14]) which can give useful constraints.
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- There are some relations between local and global blocks (A. Dimca and A. Némethi [6], W. Neumann and P. Norbury [14]) which can give useful constraints.
- Usually these data are computed depending on the particular polynomial $f$.
- A practical complete algorithmic method does not exist in the literature.


## Case of conjugated polynomials

- Specially interesting is the case of polynomials with coefficients in a number field conjugated by a Galois isomorphism of the field.
- Example: $\left(y^{2} x-(y+1)^{3}\right)\left(s^{2}(2 s-3) y+x-3 s^{2}\right)$ with $s \in\{3+2 \sqrt{3}, 3-2 \sqrt{3}\}$ are conjugated by the Galois isomorphism $a+b \sqrt{3} \mapsto a-b \sqrt{3}, a, b \in \mathbb{Q}$.


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- Due to the Galois isomorphism both have the same algebraic properties (degree, number of components, global Milnor number, type and position of singularities, ...).
- The global blocks reflect how the Milnor fibers sit in the fixed regular fiber and this need not be invariant under Galois isomorphims.


## Tame polynomials: reduction to the Morse case

- The discriminant method is a practical complete algorithmic method to compute local monodromies for a tame polynomial $f$ with $n=2$.
- Let $f$ be a tame polynomial (S. A. Broughton [4])
- $\Rightarrow f$ is good at infinity $\Rightarrow B(f)=\left\{t_{i}\right\}$ contains only critical values coming from affine singularities.
- $\Leftrightarrow \mu(f)<\infty$ and $\mu(f)$ is invariant by morsifications $f(x, y)+a g(x, y), g$ generic lineal form $\Rightarrow$ regular fibers are diffeomorphic.


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- To obtain the block decomposition of $\left(h_{\gamma_{i}}\right)_{*}$ we need to consider special geometric bases of $\pi_{1}(T \backslash B(f+a g) ; \star)$.


## Tame polynomials: reduction to the Morse case



## Tame polynomials: reduction to the Morse case



- Order the set $B(f+a g) \cap D_{i}$ in such a way that the critical values corresponding to the morsification of the same critical point in $f^{-1}\left(t_{i}\right)$ are together.


## Tame polynomials: reduction to the Morse case



- $\left(\gamma_{k}^{i}\right)_{k=1, \ldots, k(i)}$ a geometric basis of $\pi_{1}\left(D_{i} \backslash B(f+a g) \cap D_{i} ; t_{i}^{\prime}\right)$ which respects this order so that $\left(r_{i} \cdot \gamma_{k}^{i} \cdot r_{i}^{-1}\right)_{k=1, \ldots, k(i)}^{i=1, \ldots, \# B(f)}$ is a geometric basis of $\pi_{1}(T \backslash B(f+a g) ; \star)$.


## Tame polynomials: reduction to the Morse case



- $\gamma_{i}=r_{i} \cdot\left(\prod_{k} \gamma_{k}^{i}\right) \cdot r_{i}^{-1} \Rightarrow$ the ordered product of the associated local monodromies of $f+a g$ gives the block decomposition of $\left(h_{\gamma_{i}}\right)_{*}$.


## Hyphotesis

- We can assume $f(x, y)$ to be a tame Morse polynomial function.
- $\ell(x, y)$ generic linear form. One has the polar map

$$
\phi_{f, \ell}: \mathbb{C}^{2} \rightarrow \mathbb{C}^{2},(x, y) \mapsto(f(x, y), \ell(x, y))=(t, \ell)
$$

Let $(x, y)$ be generic coordenates. We take $\ell(x, y)=x$.

- $\mathfrak{D}_{f}:=\left\{(t, x) \in \mathbb{C}^{2} \mid \operatorname{discrim}_{y}(f(x, y)-t)=0\right\}$ the discriminant curve of $\phi_{f, x}$.


## Hyphotesis

- The method needs two data which depend on $\mathfrak{D}_{f}$ :
- The classical monodromy $m$ of the projection

$$
\pi \mid: f^{-1}(\star) \rightarrow \mathbb{C},(x, y) \mapsto x
$$

in a geometric basis associated with the ramification points of $\left.\pi\right|_{f-1}(\star)$ (the set $\mathbf{x}^{\star}$ of $k$ points given by $\mathfrak{D}_{f} \cap\{t=\star\}$ ).

- First datum
- The braid monodromy $\nabla_{\tau}$ of the discriminant $\mathfrak{D}_{f}$ in the geometric basis $\left(\gamma_{i}\right)$. Second datum


## The main theorem

## Theorem 1 (Discriminant method)

Let $f(x, y) \in \mathbb{C}[x, y]$ be a tame Morse polynomial with $(x, y)$ generic coordinates. Then $\left(h_{\gamma_{i}}\right)_{*}$ is determined by the following data:

$$
\begin{gathered}
\left(m\left(\mu_{1}^{\tau}\right), \ldots, m\left(\mu_{k}^{\tau}\right)\right) \subset \Sigma_{N}^{k} \\
\left(\nabla_{\tau}\left(\gamma_{1}\right), \ldots, \nabla_{\tau}\left(\gamma_{\mu(f)}\right)\right) \subset \mathbb{B}_{k}^{\mu(f)}
\end{gathered}
$$

Moreover an explicit method to construct $\left(h_{\gamma_{i}}\right)_{*}$ exists.

## Sketch of the proof.

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1. Finding the vanishing cycles.

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$\| \phi_{f, x}$


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- $\mathbb{B}_{k}$ has the following presentation

$$
\left.\left\langle\sigma_{1}, \ldots, \sigma_{k-1}\right|\left[\sigma_{i}, \sigma_{j}\right]=1 \text { if }|i-j| \geq 2, \sigma_{i+1} \sigma_{i} \sigma_{i+1}=\sigma_{i} \sigma_{i+1} \sigma_{i}\right\rangle
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- $\nabla_{\tau}\left(\gamma_{i}\right)$ is a conjugate of any $\sigma_{j}$. Let $\beta_{i}$ be an element which conjugates, for example, $\sigma_{1}$.
- $\Phi: \pi_{1}(X \backslash \mathbf{k} ; *) \times \mathbb{B}_{k} \rightarrow \pi_{1}(X \backslash \mathbf{k} ; *)$ such that

$$
\mu_{j}^{\sigma_{i}}= \begin{cases}\mu_{i+1} & \text { if } j=i \\ \mu_{i+1} \cdot \mu_{i} \cdot \mu_{i+1}^{-1} & \text { if } j=i+1 \\ \mu_{j} & \text { if } j \neq i, i+1\end{cases}
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- We compute $\left(\mu_{2} \cdot \mu_{1}\right)^{\beta_{i}}$ and $\left(\mu_{2} \cdot \mu_{1}\right)^{\beta_{j} \nabla_{\tau}\left(\gamma_{i}\right)}$


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- A model of $H_{1}\left(V_{\star}(f)\right)$ which depends only of $\left(m\left(\mu_{1}^{\tau}\right), \ldots, m\left(\mu_{k}^{\tau}\right)\right)$


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- A model of $H_{1}\left(V_{\star}(f)\right)$ which depends only of $\left(m\left(\mu_{1}^{\tau}\right), \ldots, m\left(\mu_{k}^{\tau}\right)\right) \Rightarrow \Delta_{i}$ and $\left(h_{\gamma_{i}}\right)_{*}\left(\Delta_{j}\right)$.


## Remarks

- Since our method strongly uses the discriminant curve $\mathfrak{D}_{f}$ we call it the discriminant method.
- The computation of first and second data can be done with the help of computer programs such as [3] and [5]. Since $m$ and $\nabla_{\tau}$ are homotopy invariants we can use any representatives of $\mu_{i}^{\tau}$ and $\gamma_{i}$.
- Different elections of $\beta_{i}$ in $\nabla_{\tau}\left(\gamma_{i}\right)$ result in the same $\Delta_{i}$ and $\left(h_{\gamma_{i}}\right)_{*}\left(\Delta_{j}\right)$ up to orientation.
- The discriminant method is currently implemented in MAPLE $8(-)$ and SINGULAR 3 (J. Martín).


## Applications

- Global and local homological monodromy of two-variable singularities can be effectively computed using the discriminant method.
- The intersection matrix of any Yomdine surface can be computed using Gabrielov's [10] and discriminant methods.
This is currently implemented in MAPLE 8 (-) and SINGULAR 3 (J. Martín).
- Topological properties of polynomial maps can be detected by means the discriminant method.


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Example: $\left(y^{2} x-(y+1)^{3}\right)\left(s^{2}(2 s-3) y+x-3 s^{2}\right)$ with $s \in\{3+2 \sqrt{3}, 3-2 \sqrt{3}\}$ are conjugated by the Galois isomorphism $a+b \sqrt{3} \mapsto a-b \sqrt{3}, a, b \in \mathbb{Q}$ but they are not topologically equivalent polynomials.
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Introduction

## Example

$$
\begin{aligned}
& \left(y^{2} x-(y+1)^{3}\right)\left(s^{2}(2 s-3) y+x-3 s^{2}\right) \text { with } s=3-2 \sqrt{3} \text {. } \\
& \left(h_{\gamma_{1}}\right)_{*}=\left[\begin{array}{c|c|cccc}
1 & 0 & 1 & -1 & 0 & 0 \\
\hdashline 0 & 1 & 1 & 0 & 1 & 2 \\
\hline 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 1
\end{array}\right] \\
& \left(h_{\gamma_{2}}\right)_{*}=\left[\begin{array}{rr|r|rrr}
1 & 0 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 0 \\
\hline-1 & 0 & 1 & 0 & 0 & 0 \\
0 & -1 & 0 & 0 & 0 \\
0 & -1 & 0 & 0 & -1 & 0 \\
0 & -1 & 0 & 1 & 1 & -1 \\
\hline
\end{array}\right. \\
& \mathbb{I}=\left[\begin{array}{c|c|cccc}
0 & 0 & -1 & 1 & 0 & 0 \\
0 & 0 & 0 & -1 & -2 & -1 \\
\hline 1 & 0 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 0 \\
0 & 2 & 0 & -0 & 1 & 1 \\
0 & 1 & 0 & -1 & 0 & 1 \\
\hline
\end{array}\right.
\end{aligned}
$$

## Geometric basis

Let $T \subset \mathbb{C}$ be a geometric disk such that $B(f)=\left\{t_{i}\right\} \subset \operatorname{lnt}(T)$ and $\star \in \partial T$.

## Definition 1

A geometric basis of the group $\pi_{1}(T \backslash B(f)$; $\star)$ is an ordered list $\left(\gamma_{1}, \gamma_{2}, \ldots, \gamma_{\# B(f)}\right)$ such that:

- $\gamma_{i}$ is a simple meridian in $T \backslash B(f)$ based at $\star$.
- $\operatorname{Supp}\left(\gamma_{i}\right) \cap \operatorname{Supp}\left(\gamma_{j}\right)=\{\star\}$ for all $i, j$ with $i \neq j$.
- $\gamma_{\# B(f)} \cdot \ldots \cdot \gamma_{1}$ is homotopic to $\partial T$ which is positively oriented (product from left to right).



## First datum

- Let $X$ be a big geometric disk such that

$$
\mathbf{x}^{\star}, \mathbf{k}:=\{1, \ldots, k\} \subset \operatorname{lnt}(X)
$$

- Let $\left(\mu_{1}, \ldots, \mu_{k}\right)$ be the following geometric basis of $\pi_{1}(X \backslash \mathbf{k} ; *):$

- Let us fix $\tau \in \mathbb{B}\left(\mathbf{k}, \mathbf{x}^{\star}\right)$.


## First datum

The Hurwitz move $\Psi_{\tau}: \pi_{1}(X \backslash \mathbf{k} ; *) \longrightarrow \pi_{1}\left(X \backslash \mathbf{x}^{\star} ; *\right)$ gives us the geometric basis $\left(\mu_{1}^{\tau}, \ldots, \mu_{k}^{\tau}\right)$ of $\pi_{1}\left(X \backslash \mathbf{x}^{\star} ; *\right)$ ．

$\Psi_{\tau}$


## First datum

The Hurwitz move $\Psi_{\tau}: \pi_{1}(X \backslash \mathbf{k} ; *) \longrightarrow \pi_{1}\left(X \backslash \mathbf{x}^{\star} ; *\right)$ gives us the geometric basis $\left(\mu_{1}^{\tau}, \ldots, \mu_{k}^{\tau}\right)$ of $\pi_{1}\left(X \backslash \mathbf{x}^{\star} ; *\right)$.

$\Psi_{\tau}$


The first datum is: $\left(m\left(\mu_{1}^{\tau}\right), \ldots, m\left(\mu_{k}^{\tau}\right)\right) \in \sum_{N}^{k}$

## Second datum

- Consider the projection map

$$
\pi:\left(\mathbb{C}^{2}, \mathfrak{D}_{f}\right) \longrightarrow \mathbb{C},(t, x) \mapsto t
$$

- The second member of the pair is a $k$-fold covering ramified on a finite set of points $\mathcal{T}$.
- The fundamental group of the base, $\pi_{1}(\mathbb{C} \backslash \mathcal{T} ; \star)$, induces the braid monodromy $\nabla_{\tau}$ of the pair $\left(\mathbb{C}^{2}, \mathfrak{D}_{f}\right)$ with respect to the projection $\pi$ :

$$
\begin{array}{ccccc}
\nabla_{\tau}: & \pi_{1}(\mathbb{C} \backslash \mathcal{T} ; \star) & \longrightarrow & \mathbb{B}\left(\mathbf{x}^{\star}, \mathbf{x}^{\star}\right) & \longrightarrow
\end{array} \mathbb{B}_{k} .
$$

$$
\text { (recall } \mathbf{x}^{\star}=\mathfrak{D}_{f} \cap\{t=\star\} \text { and } \tau \in \mathbb{B}\left(\mathbf{k}, \mathbf{x}^{\star}\right) \text { ) }
$$

## Second datum

$$
\begin{array}{ccccc}
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\end{array} \mathbb{B}_{k},
$$

－Remark：Since $f$ is good at infinity，its discriminant curve has no vertical asymptotes $\Rightarrow \mathcal{T}=f(P) \cup \pi\left(\operatorname{Sing}\left(\mathfrak{D}_{f}\right)\right)$（disjoint since（ $x, y$ ）generic）．

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\gamma & \mapsto & \left.\pi\right|_{\mathfrak{D}_{f}} ^{-1}(\gamma)=: \gamma^{\star} & \mapsto & \tau \cdot \gamma^{\star} \cdot \tau^{-1}
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The second datum is

$$
\begin{equation*}
\left(\nabla_{\tau}\left(\gamma_{1}\right), \ldots, \nabla_{\tau}\left(\gamma_{\mu(f)}\right)\right) \in \mathbb{B}_{k}^{\mu(f)} . \tag{4}
\end{equation*}
$$

## Tame polynomials: reduction to the Morse case



