

September 22

	1 6	2 4	3 5	4 16	5 3	6 8	7 11	8 T2	9 10	10 12
Morning	Grasp and task learning by imitation	Current software frameworks in cognitive robotics integrating different computational paradigms	Current State of the Art and Future Challenges in Nanorobotics	Self-Reconfigurable Robots	Visual guidance systems for small autonomous aerial vehicles.	Workshop on robot simulators: available software, scientific applications and future trends.	Robotics Challenges for Machine Learning	Tutorial on Vision for Robotics	Multi-Competence Adaptation in Robotics and A-life Amiram Moshalov Hussein Abbass	Teaching Human-Robot Interaction to Humans Jenny Burke Robin Murphy Aude Billard Tatsuya Nomura
Afternoon	Anis Sahbani Jorge Dias Paulo Menezes	Martin Huelse Manfred Hild	Constantinos Mavroidis Antoine Ferreira	Wei-Min Shen Hod Lipson Kasper Sloy Mark Yin Greg Chirikjian Behnam Salemi	Stéphane Viollet Franck Ruffier	Antonio Morales Tamin Asfour	Russ Tedrake Nicholas Roy Jan Peters Jun Morimoto	Andrew I. Comport A. Bartoli	T1 Fast Marching Method: Theoretical Underpinnings and Applications to Robotics YI LI Moslem Kazemi Kamal Gupta	T4 Modeling, Estimation, Path Planning and Control of All Terrain Mobile Robots Philippe Marinet Danwei Wang

September 26

	1 2	2 18	3 15	4 20	5 7	6 9	7 21	8 1	9 17	10 T4
Morning	Mobiligence: Adaptive Motor Function through Dynamic Interactions among the Body, Brain and Environment.	From motor to interaction learning in robots	Performance Evaluation and Benchmarking for Intelligent Robots and Systems	Robot Services in Aging Society	Workshop on Home Robotics – WHR 2008	"2nd Workshop on Planning, Perception and Navigation for Intelligent Vehicles"	Network Robot Systems: human concepts of space and activity, integration and applications	Art and Robots	3D-Mapping	Motion planning with the OOPSMP toolkit: A hands-on tutorial on using state-of-the-art Mark Moll Lydia E. Kavraki
Afternoon	Toshiyuki Kondo Koji Ito	Jan Peters Olivier Sigaud Sethu Vijayakumar	Angel P. del Pobil Raj Madhavan Fabio Bonsignorio	Yoshihiko Nakamura Martin Buss Technische Henrik Christensen	Markus Vincze Roland Siegwart	Urbano Nunes Christian Laugier	Norihiro Hagita Alberto Sanfelli Young-Jo Cho Hiroshi Ishiguro Ben Köse Zoran Zivkovic Hideki Hashimoto	Katsushi Ikeuchi Ken Goldberg Shunsuke Kudo	Patrick Pfaff Wolfram Burgard	T3 ROBOETHICS: Ethical and Societal Implications of Robotics Gianmarco VERUGGIO Fiorella OPERTO