

ADT MORSE C2S@Exa 10/12/2013

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HIEPACS RUNTIME INRIA Bordeaux Sud-Ouest

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MORSE prototype

Current and future work



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MORSE definition

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MORSE in a few words

For short: MORSE = Matrices Over Runtime Systems @ Exascale

Translation: design dense and sparse linear algebra methods relying on innovative runtime systems for large-scale multicore systems possibly with accelerators

- Main goal: deliver a unified set of tools able to solve very large linear algebra problems efficiently on current and future supercomputers
 - Target: 1. Inria research teams
 - 2. Inria collaborators (reseach labs, industry)
 - community-wide: developers of numerical simulation programs

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Linear Algebra

Continuous problem \rightarrow Discretization \rightarrow linear system Ax = b

- Different parameters:
 - o properties: symmetry, positive-definiteness, conditioning, ...
 - $\circ~\text{size:}~>10^6\times10^6$
 - structure: square/rectangular, dense/sparse, regular/irregular
- Involve adapted linear solvers:
 - A unsymmetric: LU factorization
 - A spd: LL^T Cholesky factorization (LDL^T)
 - A rectangular $m \times n$, with $m \ge n$: QR factorization
- Mean Square problems: $\min_{x} \|\mathbf{A}\mathbf{x} \mathbf{b}\|_{2}$
 - If rank(A) is maximal : Cholesky or **QR** factorizations
 - $\circ~$ Else Singular Value decomposition (SVD)
- Eigenvalues problems: $\mathbf{A}\mathbf{x} = \lambda \mathbf{x}$
 - Orthogonal transformations
 - $\circ~$ Schur decomposition, Hessenberg, tri-diagonal reduction, \ldots

Over Runtime Systems

runtime: intermediate layer between system and application



task-based programming model (DAG)



- task abstraction (codelet): CPU/GPU
- data management: consistency, copies, prefetching
- task scheduling: predifined, user defined

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Problematic

 \blacktriangleright Different layers \leftrightarrow Different scientific skills and research teams

• User's applications (research and industry)

- $\rightarrow~$ numerical simulation programs
- HPC solvers (HiePACS, ICL)
 - \rightarrow MAGMA, DPLASMA, PaSTIX, MaPHyS/HIPS, ScalFMM
- Runtimes
 - \rightarrow StarPU, QUARK, PaRSEC
- Kernels
 - $\rightarrow\,$ BLAS, cuBLAS, specifics
- A lot of tools
- Combine efficiently these layers



Objectives of our work in MORSE

Task 1: build and install process

- build automation software (CMake)
- portability on a wide range of UNIX systems/hardwares
- o for a wide range of users: from specialists to beginners
- \Rightarrow ease of installation, deployment and use
 - ► Task 2: interface user ↔ solver
 - a unified framework to use our softs
- \Rightarrow simplify users life, improve solvers dissemination
 - ► Task 3: interface **solver** ↔ **runtime**
 - $\circ\,$ a unified framework to call runtimes from solvers
- \Rightarrow improve solvers programming efficiency

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MORSE prototype



MORSE prototype



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What have been achieved so far

Task 1: build and install process

demonstrate the feasability: a first prototype

- validate some ideas
- features experimentation
- $\circ~$ methodology: nothing is perfect \rightarrow pros and cons

external visibility:

- o website http://icl.cs.utk.edu/morse/
- a first release MORSE 1.0, poster, ...
- ▶ work of C. Castagnède (engineer), E. Agullo, M. Faverge

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MORSE release 1.0 content



- different solvers
 - Magma (dense linear algebra)
 - Pastix (direct sparse solvers)
 - ScalFMM (FMM)
- relying on different runtime systems
 - Quark (multi-core shared-memory)
 - StarPU (multi-core/gpu shared/distributed-memory)
- build and install using CMake
 - automatic detection of dependencies (BLAS, LAPACK, MPI/CUDA, ...)
 - $\circ~$ if not detected \rightarrow installation of external libraries



Control the build with CMake



- many options:
 - solvers to compile (Magma, Pastix, ...)
 - precisions (single, double, complex, mix, ...)
 - which runtime for each (Quark, StarPU)
 - are MPI and/or CUDA activated
 - ordering (METIS, SCOTCH, ...)
- dependencies management:
 - user specific: precise paths are given
 - automatic: search within the system, install a tarball or download

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Not a simple project !





Retrospective study

- Feasability has been proven
- Is this perfect? No:
 - work done in a short time
 - o some bugs during detection, problem of portability
 - $\circ~$ generic macros with recursive calls \rightarrow difficulty to debug
 - monolithic: magma_morse, pastix_morse and scalfmm_morse cannot be taken separatly
 - o not ready to be disseminated for community-wide
- Looking for improvements:
 - $\circ \ \mathsf{make} \ \mathsf{it} \ \mathsf{simpler} \leftrightarrow \mathsf{make} \ \mathsf{it} \ \mathsf{correct}$
 - $\circ~$ separate projects $\leftrightarrow~$ more specific options
 - write generic Finds for further dissemination
 - better respect of CMake coding rules





Current and future work

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What we are doing now

Separate projects and rewrite the CMake Find macros

 $\textbf{First prototype} \rightarrow \texttt{parent CMakeLists.txt at MORSE level}$

Level 0: FindDep(morse)

 $\rightarrow\,$ magma_morse, pastix_morse, scalfmm_morse

Level 1: FindDep(magma_morse)

 $ightarrow\,$ lapacke, cblas, starpu, quark, tmg, magma

Level 2: FindDep(lapacke)

 \rightarrow lapack

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Level 3: FindDep(lapack)
```

 \rightarrow blas

- recursive calls from level 0 to find dependencies
- loop on dependencies and find/install them

⇒ Problem: FindDep macros related to 'morse' = monolithic

What we are doing now

 $\textbf{Current MORSE} \rightarrow \texttt{parent CMakeLists.txt at magma_morse level}$

Level 0: magma_morse depends on lapacke, starpu, ... options

Level 1: find_package(lapacke ...), ...

Level 2: find_package(lapack ...)

Level 3: find_package(blas ...)

- generic Finds, find_package = CMake macro widely used
- respect CMake methodology
- try to respect CMake coding rules in writting Finds:
 - how to write comments, sub-macros
 - variables naming convention
 - what variables to set (normal, cache), in which conditions
- can be reused in other projects



find_package call example

set(MAGMAMORSE_STARPU_VERSION "1.1"
CACHE STRING "oldest STARPU version desired")

Different call depending on the required components if (MAGMAMORSE_USE_MPI AND MAGMAMORSE_USE_CUDA) find_package(STARPU \${MAGMAMORSE_STARPU_VERSION} REQUIRED HWLOC MPI CUDA) elseif (MAGMAMORSE_USE_MPI) find_package(STARPU \${MAGMAMORSE_STARPU_VERSION} REQUIRED HWLOC MPI) elseif(MAGMAMORSE_USE_CUDA) find_package(STARPU \${MAGMAMORSE_STARPU_VERSION} REQUIRED HWLOC CUDA) else() find_package(STARPU \${MAGMAMORSE_STARPU_VERSION}

REQUIRED HWLOC)

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find_package output

Example of variables set in a find_package: STARPU_FOUND - True if headers and requested libraries were found STARPU_INCLUDE_DIRS - starpu include directories STARPU_LIBRARY_DIRS - Link directories for starpu libraries STARPU_SHM_LIBRARIES - starpu libraries shared memory STARPU_MPI_LIBRARIES - starpu libraries mpi STARPU_component_FOUND - True if component has been found STARPU_VERSION_STRING - The version of the package found STARPU_VERSION_MAJOR - The major version of the package STARPU_VERSION_MINOR - The minor version of the package

Hints given by the user, pkg-config can also be used: STARPU_DIR - Where to find the base directory of starpu STARPU_INCDIR - Where to find the header files STARPU_LIBDIR - Where to find the library files

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Future work: main tasks

• Task 1: build and install process ($\approx 1^{st}$ year)

- $\circ\;$ validation of generic ${\mbox{Finds}}$ in all the projects
 - \rightarrow already CMake: MAGMA, DPLASMA, PaSTIX, ScalFMM
 - $\rightarrow\,$ porting to CMake: MaPHyS, HIPS
- portable distribution: build and install
- ▶ Task 2: interface user \leftrightarrow solver ($\approx 1^{st}$ year)
 - C, Fortran, Python interfaces
 - matrices I/O management
 - MPI extension
- ⇒ interaction with J. Pedron (hybrid) and C. Piacibello (ScalFMM)
 - ▶ Task 3: interface solver \leftrightarrow runtime ($\approx 2^{nd}$ year)

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Future work: other tasks

► Task 4: continuous integration (years [1,2])

- nightly builds and tests
- o detect regression: builds and tests sequential/parallel
- performance checking: CPU time, memory consumption
- ▶ Task 5: features enrichment (years [1,2])

 $\circ \ \mathsf{MaPHYS} \to \mathsf{task-based,} \ \dots$

► Task 6: deployment (years [2,3])

• on Plafrim

 $\circ~$ on the collaborative C2S@Exa HPC platform

► Task 7, 8, 9: many other features ! (years [2, 3])

• integration in applications (Optidis, softs Bacchus)

• user support



ANY QUESTIONS ?

