



# Action d'envergure C2S@Exa The Traces software

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- 1. Traces historic**
- 2. Hydraulic and transport models**
- 3. Numerical methods**
- 4. Needs**



## Traces historic

Transport RéActif de Contaminant dans les Eaux Souterraines  
Transport of RadioACTIVE Elements in Subsurface

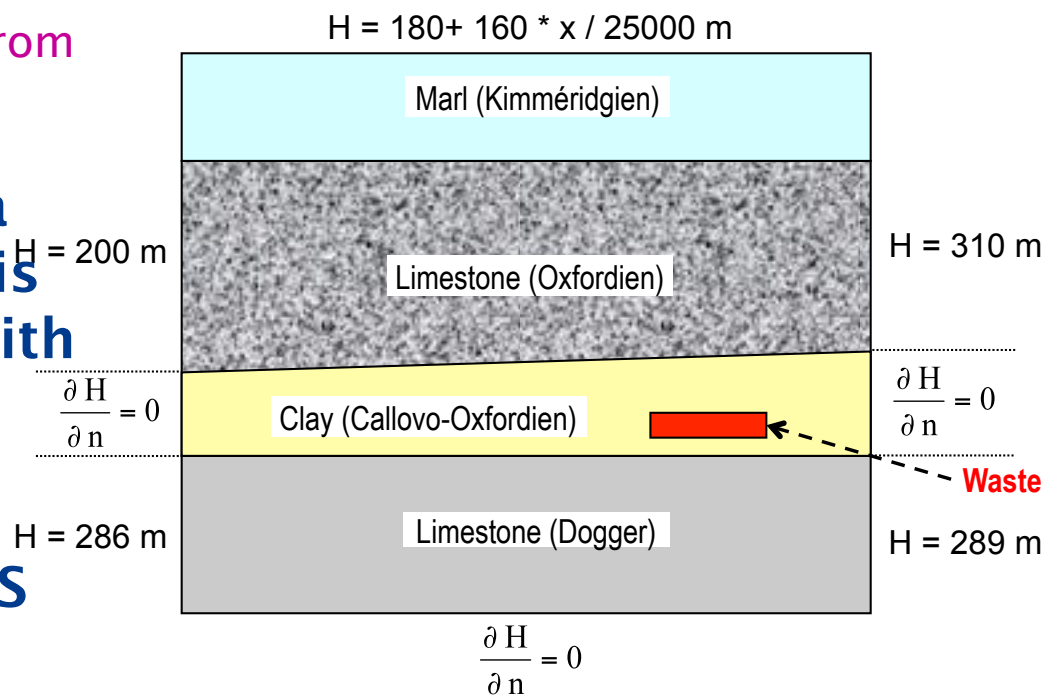
2001

## Once upon a time, the Couplex exercise

- » Compute a simplified Far Field model used in numerical waste management simulations
  - Convection diffusion type problem
  - Huge parameter variation from one layer to another

The IMFS laboratory gave a excellent numerical analysis and the obtained results with Traces code were “good”

It’s the beginning of a partnership between IMFS and Andra



## 1.2 Traces evolutions (I)

### 2002-2003

Traces code is integrated in Andra platform as numerical component for :

- Saturated Hydraulic and transport module
- Reactive transport module

**Main difficulty: the transport CPU time is too large when the problem is convective**

- Explicit time discretization (EFD)

### 2004-2005

**Development of implicit time discretization scheme for EFHM**

**Integration of new solver libraries : NSPCG, SLAP**

**Traces code is used to confirm the safety assessment results**

## 1.2 Traces evolutions (II)

**2006-2007**

**Development of the unsaturated hydraulic and transport model (Richards approximation)**

**2007-2009**

**Traces is used as transport code in a thesis about the identification of the geological layers and the associated transport parameters**

- Inverse problem by adjoint-state method
- Automatic differentiation of code Traces with Tapenade Software

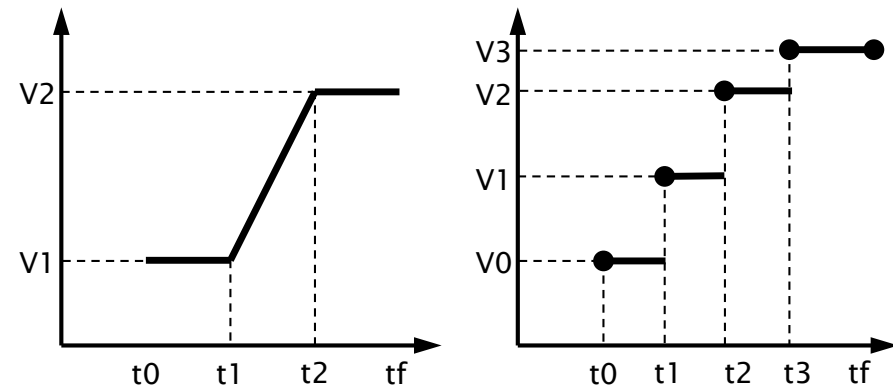
**Development of the unsaturated hydraulic and transport model (Richards approximation)**

**IMFS: thesis of M. FAHS (2007) and C.P. EL SOUEDY (2008)**

2010-2013

Parameters and boundary conditions can be defined as function of space and/or time

- » Values by cells
- » Linear or discrete interpolation



In transport calculation, flow (Darcy velocity and saturation) can be read from another calculation results

- » Linear or discrete Flow (Darcy and saturation) interpolation
- » Chaining two-phase flow and Kd-Csat transport calculation
- » Use of specific time discretization for each physical phenomena



# Hydraulic and transport models



## 2.1 Saturated porous media

### Hydraulic

- » Darcy law
- » Mass conservation

$$\vec{U} = -\bar{K} \cdot \vec{\nabla} h$$

$$\text{div}(\bar{K} \cdot \vec{\nabla} h) + s = 0$$

### Transport

- » Mass conservation

$$\frac{\partial (R \phi_e \cdot C_i)}{\partial t} = \text{div}(\underbrace{\bar{D}_i^* \cdot \vec{\nabla} C_i - C_i \vec{U}}_{\text{Diffusion-dispersion-convection}}) - \underbrace{\lambda_i \phi_e \cdot R_i \cdot C_i}_{\text{Decay, chain}} + \underbrace{\sum_{j \in I} \sigma_{ij} \lambda_j \phi_e \cdot R_j \cdot C_j}_{\text{Precipitation/dissolution}} + \underbrace{\phi_e \cdot S_i + Q_i}_{\text{Sorption}}$$

+ Sorption  
 + Diffusion-dispersion-convection  
 + Decay, chain  
 + Precipitation/dissolution

### Parameter properties

- » Anisotropy (full tensor)
- » High contrast

### Hypothesis

- » No gas phase
- » Constant viscosity and density
- » No retroaction from hydraulic on transport

### Hydraulic

» Mass conservation  $\frac{\partial(\phi_e \cdot S^l \cdot \rho)}{\partial t} + \text{div}(\rho \vec{U}) = m$

» Darcy law  $\vec{U} = -\frac{\bar{k} \cdot k_r}{\mu} (\vec{\nabla} p + \rho \cdot g \cdot \vec{\nabla} z) = -\bar{K} \cdot \vec{\nabla} h$

» Permeability and saturation laws

» Deformation of porous media

$$\bar{K} = \frac{\bar{k} \cdot k_r \cdot \rho \cdot g}{\mu} \quad k_r = k_r(\hat{S}^l) \quad \hat{S}^l = \hat{S}^l(\Psi) \quad \hat{S}^l = \frac{S^l - S_r}{1 - S_r}$$

$$\phi_e = \phi_e(p) \quad \left( \frac{\partial \phi_e}{\partial p} \right) = \alpha_s$$

### Transport

- » As in saturated porous media, but parameters depend from saturation



# Numerical methods

## 3.1 Geometry and spatial discretization

### Geometry

- » Cartesian coordinates in 2D or 3D
- » All types of elements :
  - triangle, quadrangle, tetrahedron, hexahedron, prism

### Hydraulic discretization

- » Mixed hybrid finite element method
  - + *Good Darcy velocity approximation*

### Transport discretization

- » Two possibilities:
  - Mixed hybrid finite element method
    - + *Facility to take into account the full tensors and mass balance on each element*
  - Mixed hybrid finite element method for dispersion and discontinuous Galerkin finite element method for convection
    - + *Accuracy, continuity of dispersive flow*

### Hydraulic

- » Mixed hybrid finite element
  - First order Implicit scheme

### Transport

- » Mixed hybrid finite element
  - First order implicit scheme
- » Mixed hybrid finite element and discontinuous Galerkin finite element
  - Time splitting operator
    - + *First order implicit for dispersive and reactive part*
    - + *Explicit for convective part*
      - » Second order accurate based on explicit Runge-Kutta method
      - » Stability is ensured by slope limiters
      - » Necessity to respect the CFL criteria

### Coupling with reactive process

- » Linearization using the Picard method

### First solveur

- » PCG with Eisenstat procedure

### Solvers added by Andra

- » One direct solver: Gauss decomposition
- » Solvers of NSPCG library
- » Solvers of SLAP library



## Needs

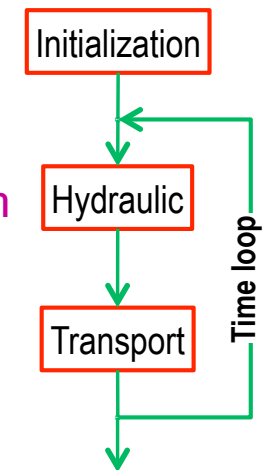
## 4.1 Discretization, coupling

### Calculation of elementary matrices

- » Using programs generated with Maple procedure
  - These routines can't be modified or corrected
  - Interpolation isn't exact for cells whose the shape isn't regular
- » It's also possible to use numerical integration

### Hydraulic and transport problem

- » Traces solves flow equations then, the transport equations
  - There is no iteration between hydraulic and transport calculation
  - Difficulties of convergence if the time step is too large
    - + *Unsaturated transport*
    - + *Reactive process*





### Mixed hybrid finite element

- » Large number of degrees of freedom
  - The solver performance is important
- » Example 1: flow calculation
  - Regular mesh with **362 304** cells, 284 375 points, 1 110 680 faces
  - Number of degrees of freedom
    - + *Porflow*: 405 840
    - + *Traces*: close to the number of faces
  - CPU Times (minutes)

	NSPCG/CONJ/CHOL	NSPCG/CONJ/NEUM	NSPCG/GMRES/NEUM
Porflow	4	86	No convergence
Traces	15 (176 avec SLAP)	36	76

## 4.2 Solver performances (II)

### » Example 2:

□ Regular mesh with 2 580 786 cells, 2644920 points, 7 806 021 faces

□ Hydraulic:

+ Matrix: 7 738 593 degrees of freedom, 46 113 243 values

+ NSPCG/GMRES/NEUMANN did not converge in 20 000 iterations

+ NSPCG/CONJ/CHOL converge in 6675 iterations, cpu time:  $\approx$ 7 hours

+ SLAP/CG/CHOL converge in 6014 iterations

□ Transport:

+ Matrix: 7 678 695 degrees of freedom

+ NSPCG/GMRES/NEUMANN:  $\approx$ 18 hours for 460 time steps

**Currently, the same solver is used for flow and transport calculation**

» Difficulty of convergence in coupled problem

### Coupled problem

- » Use different solvers for hydraulic and transport
- » Change time discretization when there are convergence difficulties (nonlinear process)

### Input optimization

- » Build the face (or edge) table in the Traces code itself
- » Reduce the number of input files
  - Even for a flow calculation, the Transport input files are required

### Outputs Optimization

- » Reduce the number of zone output files (these files can be very large)